Complex Eigenvalues

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Complex Numbers

The imaginary unit i is a number defined to be a number such that $i^2 = -1$. Complex numbers take the form z = a + bi.

- Addition: (a + bi) + (c + di) = (a + c) + (b + d)i
- Multiplication: $(a + bi) \cdot (c + di) = (ac bd) + (ad + bc)i$
- Conjugate: $\overline{a+bi} = a-bi$
- Magnitude: $||z|| = \sqrt{z\overline{z}} = \sqrt{a^2 + b^2}$
- Division: $\frac{1}{z} = \frac{1}{z} \frac{\bar{z}}{\bar{z}} = \frac{\bar{z}}{a^2 + b^2}$

Complex addition and multiplication are both associative and commutative. Complex numbers are useful because every non-constant complex polynomial of degree n has n (possibly repeated) root when considering complex polynomials.

$$\begin{split} r &= \sqrt{a^2 + b^2} \\ a &= r \cos(\theta) \\ b &= r \sin(\theta) \\ z &= r(\cos(\theta) + i \sin(\theta)) = re^{i\theta} \end{split}$$

Complex Numbers can also be represented as angle and magnitude in what is called polar coordinates. The angle is measured from the x-axis, counter-clockwise.

Complex Eigenvalues

 \mathbb{C}^n is a complex vector space where addition and scalar multiplication is done component-wise. For a complex $n \times n$ matrix A, we say $\lambda \in \mathbb{C}$ is a eigenvalue of A if for some non-zero $u \in \mathbb{C}^n$, $Au = \lambda u$. Linear systems, matrices, determinants, eigenvalues, and diagonalization all remain unchanged when extending from \mathbb{R}^n to \mathbb{C}^n .

General Diagonalization for Complex Matrices

A matrix A is only diagonalizable when the algebraic multiplicity equals the geometric multiplicity. Every symmetric real matrix has only real valued eigenvalues and is diagonalizable. If the matrix has n different eigenvalues, then A is diagonalizable.

General Notion of an eigenvalue

Suppose that $T: V \mapsto V$ is a linear transformation defined on a vector space V. If $T(v) = \lambda v$ for some non-zero $v \in V$, we say that λ is a eigenvalue for T and v is a eigenvector for λ .

Example 1

$$A = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$
$$det(A - \lambda I) = \lambda^2 + 1$$
$$\lambda = \pm i$$

$$\lambda = i$$

$$A - \lambda I = \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix}$$

$$rref(A - \lambda I) = \begin{bmatrix} 1 & -i \\ 0 & 0 \end{bmatrix}$$

$$z_1 - iz_2 = 0$$

$$z_1 = iz_2$$

$$z = t \begin{bmatrix} i \\ 1 \end{bmatrix}$$

$$\lambda = -i$$

$$A - \lambda I = \begin{bmatrix} i & -1 \\ 1 & i \end{bmatrix}$$

$$rref(A - \lambda I) = \begin{bmatrix} 1 & i \\ 0 & 0 \end{bmatrix}$$

$$z_1 + iz_2 = 0$$

$$z_1 = -iz_2$$

$$z = t \begin{bmatrix} -i \\ 1 \end{bmatrix}$$

$$\begin{split} P &= \begin{bmatrix} i & -i \\ 1 & 1 \end{bmatrix} \\ P^{-1} &= \frac{1}{2i} \begin{bmatrix} 1 & i \\ -1 & i \end{bmatrix} \\ D &= \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} \\ A &= \begin{bmatrix} i & -i \\ 1 & 1 \end{bmatrix} \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} \frac{1}{2i} \begin{bmatrix} 1 & i \\ -1 & i \end{bmatrix} \\ &= \frac{1}{2i} \begin{bmatrix} i & -i \\ 1 & 1 \end{bmatrix} \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix} \begin{bmatrix} 1 & i \\ -1 & i \end{bmatrix} \end{split}$$

Example 2

$$A = \begin{bmatrix} 1 & -1 & 2 \\ 0 & 2 & 1 \\ 0 & 0 & 3 \end{bmatrix}$$

$$\lambda = 1, 2, 3$$

Since there are three distinct eigenvalues and the matrix A is 3×3 , the matrix is diagonalizable.

Example 3

Suppose that there is a transformation T from infinitely differentiable function (C^{∞}) to infinitely different functions. Find the eigenvalues for T.

$$T: C^{\infty} \mapsto C^{\infty}$$

$$T(f) = \frac{df}{dx}$$

$$\frac{df}{dx} = \lambda f$$
$$f = ke^{\lambda x}$$

Every $\lambda \in \mathbb{C}$ is a eigenvalue

Example 4

Suppose that there is a linear transformation T from polynomials to polynomials. Find the eigenvalues for T.

$$T: P \mapsto P$$
$$T(p) = xp$$

$$T(p) = \lambda pp = a_0 + a_1 x + \dots + a_n x^n$$

 $T(p) = a_0 x + a_1 x^2 + \dots + a_n x^{n+1}$

If $\lambda \neq 0$, then $a_0 = 0$, and all the other coefficients are zero by induction. If $\lambda = 0$, then p = 0, thus there are no eigenvalues.