

# Kinematics in 1D

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## Dimensional Analysis

A dimension (unit) is an inherent property of a quantity. Most physical quantities can be expressed in terms of these fundamental dimensions: Mass, Length, Time. We can use dimensions to understand and solve problems.

### Rules

1. addition and subtraction must have same dimensions.
2. log and exponential functions only apply to dimensionless quantities
3. trig functions only apply to dimensionless quantities

### Example

In the equation  $E = mc^2$ , what is the unit of  $E$ ?

$$\begin{aligned} E &= mc^2 \\ &= \text{mass speed}^2 \\ &= \text{mass} \left( \frac{\text{length}}{\text{time}} \right)^2 \\ &= \text{mass length}^2 \text{ time}^{-2} \\ &= \text{energy} \end{aligned}$$

Consider the following equation

$$x(=? )x_0 + v_0 t^2 + at$$

The first term has unit of *length* and the second term has units of *length time*. These two terms are different units and cannot be added therefore this equation is invalid.

$$\begin{aligned} x &= x_0 + v_0 t^2 + at \\ &= \text{length} + \text{length/time time}^2 + \text{length/time}^2 \text{ time} \\ &= \text{length} + \frac{\text{length}}{\text{time}} \text{ time}^2 + \frac{\text{length}}{\text{time}^2} \text{ time} \\ &= \text{length} + \text{length time} + \frac{\text{length}}{\text{time}} \end{aligned}$$

The correct formula is

$$x = x_0 + v_0 t + \frac{1}{2} a t^2$$

## Kinematics

Kinematics is the description of motion. These three important quantities can describe 1D motion as a function of time:

- Position:  $\vec{r}(t)$  (displacement from the origin)
- Velocity:  $\vec{v}(t)$  (rate of change of position)
- Acceleration  $\vec{a}(t)$  (rate of change of velocity)

In 1D direction can be expressed as sign. The relations between these quantities can be found using calculus.

## Vector vs Scalar

Physical quantities can be classified as scalars, vectors, etc.

Scalars are described as real numbers with units (examples: speed, temperature, mass, time, energy)

Vectors describe both a scalar (magnitude) and a direction in space (examples: velocity displacement, electric field, force)

## Notation

- scalars: ordinary or italic font ( $i$ ,  $i$ )
- vector: boldface, arrow notation, underline ( $\mathbf{i}$ ,  $\vec{i}$ ,  $\underline{i}$ )
- unit vector: hat ( $\hat{i}$  or  $\hat{x}$  for x,  $\hat{j}$  or  $\hat{y}$  for y,  $\hat{k}$  or  $\hat{z}$  for z)

Unit vectors are vectors with a magnitude of 1. It is basically a direction.

## Position, distance, displacement

- Position: gives a location, need to define an origin
- Distance: a scalar that expressed the change in position, depending on the path
- Displacement: a vector that expressed the straight line distance without depending on the path

Displacement:

$$\Delta \vec{x} \equiv \vec{x}_f - \vec{x}_i$$

## Vector arithmetic

- magnitude: scalar, length of vector
- scalar \* vector: multiply the magnitude of vector
- vector \* vector: either dot or cross product
- vector + vector: add vectors tip to tail
- vector - vector: add the negation of the subtracted vector

## Velocity

Velocity is the time rate of change of position. Average velocity:

$$\vec{v}_{avg} = \frac{\Delta \vec{x}}{\Delta t}$$

The instantaneous velocity is the slope of a line tangent to curve. Thus, velocity is the time derivative of position.

$$\vec{v} = \frac{d\vec{x}}{dt}$$

## Acceleration

Acceleration is the time rate of change of velocity. Average acceleration:

$$\vec{a}_{avg} = \frac{\Delta \vec{v}}{\Delta t}$$

The instantaneous acceleration is the slope of a line tangent to curve.

$$\vec{a} = \frac{d\vec{v}}{dt}$$