

# Orthogonal Sets

Patrick Chen

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## Orthogonal Sets

A orthogonal set is a set where every vector is orthogonal to each other. An orthonormal set is a orthogonal set where all the vectors have length 1.

## Projection

The projection of a vector  $v$  onto a vector  $u$ , written  $proj_u(v)$  is a scalar multiple of  $u$  and  $v - proj_u(v)$  is orthogonal to  $u$ . If  $W$  is a subspace, the projection of a vector  $y$  onto  $W$  is written as  $proj_W(y)$ .

$$\begin{aligned}proj_u(v) &= \frac{v \cdot u}{||u||^2} u \\u \cdot (v - proj_u(v)) &= u \cdot \left( v - \frac{v \cdot u}{||u||^2} u \right) \\&= u \cdot v - \frac{v \cdot u}{||u||^2} (u \cdot u) \\&= u \cdot v - v \cdot u \\&= \vec{0}\end{aligned}$$

Suppose that  $W$  is a subspace of  $\mathbb{R}^n$  with an orthogonal basis  $v_1, \dots, v_k$ . Then any  $y \in \mathbb{R}^n$  can be written as  $\hat{y} + z$  where  $\hat{y} \in W$  and  $z \in W^\perp$ .  $\hat{y} = proj_{v_1}(y) + \dots + proj_{v_k}(y)$  It is very important that the basis is orthogonal or else this will not work.

## Gram-Schmidt process

Every subspace of  $\mathbb{R}^n$  has an orthonormal basis. If  $v_1, \dots, v_i$  are linearly independent and  $W_i = span\{v_1, \dots, v_i\}$ . A basis  $B = \{u_1, \dots, u_k\}$  can be computed:

$$\begin{aligned}u_1 &= v_1 \\u_2 &= v_2 - proj_{W_1}(v_2) \\u_3 &= v_3 - proj_{W_2}(v_3) \\&\vdots \\u_k &= v_k - proj_{W_{(k-1)}}(v_k)\end{aligned}$$

### Example 1

Orthogonalize the basis and project  $y = [2 \ 1 \ 3]^T$  onto  $V$ .

$$B = \{u, v\} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \right\}$$

$$\text{proj}_u(v) = \frac{2}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$$

$$v - \text{proj}_u(v) = \begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \\ \frac{1}{3} \end{bmatrix}$$

$$V = \{v_1, v_2\} = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \frac{1}{3} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix} \right\}$$

$$\text{proj}_V(y) = \text{proj}_{v_1}(y) + \text{proj}_{v_2}(y)$$

$$= \frac{6}{3}v_1 + \frac{1}{\frac{6}{9}}v_2$$

$$= 2v_1 + \frac{3}{2}v_2$$

$$= 2 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \frac{3}{2} \frac{1}{3} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

$$= 2 \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + \frac{1}{2} \begin{bmatrix} 1 \\ -2 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} \frac{5}{2} \\ 1 \\ \frac{5}{2} \end{bmatrix}$$

$$z = y - \text{proj}_V(y)$$

$$= \begin{bmatrix} 2 \\ 1 \\ 3 \end{bmatrix} - \begin{bmatrix} \frac{5}{2} \\ 1 \\ \frac{5}{2} \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{2} \\ 0 \\ \frac{1}{2} \end{bmatrix}$$

$$z \cdot v_1 = 0$$

$$z \cdot v_2 = 0$$

### Example 2

Apply the Gram-Schmidt process to the following basis

$$U = \left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix} \right\}$$

$u_1$  and  $u_2$  are already orthogonal, therefore  $v_2 = u_2 - \text{proj}_{v_1}(u_2) = u_2$

$$\begin{aligned} v_3 &= u_3 - \text{proj}_{v_1}(u_3) - \text{proj}_{v_2}(u_3) \\ &= \begin{bmatrix} 2 \\ 2 \\ 3 \end{bmatrix} - \frac{7}{3} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \frac{1}{2} \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{6} \\ -\frac{1}{3} \\ \frac{1}{6} \end{bmatrix} \end{aligned}$$