# Multivariate Derivatives

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# Partial Derivative

In two dimensions, the partial derivative a of function f(x, y) with respect to a variable is the one dimensional derivative with the other variable fixed.

$$\frac{\partial}{\partial x} f(x,y) = \lim_{h \to 0} \frac{f(x+h,y) - f(x,y)}{h}$$
$$\frac{\partial}{\partial y} f(x,y) = \lim_{h \to 0} \frac{f(x,y+h) - f(x,y)}{h}$$

In general, the partial derivative of a multivariate function  $f(x_1, x_2, ..., x_n)$  with respect to  $x_i$  is the one dimensional derivative with all other independent variables fixed.

$$\frac{\partial f}{\partial x_i} = \lim_{h \to 0} \frac{f(\dots, x_{i-1}, x_i + h, x_{i+1}, \dots) - f(x_1, x_2, \dots, x_n)}{h}$$

Partial derivatives are sometimes written using subscript notation.

$$\frac{\partial f}{\partial x} = f_x(x, y, \dots)$$

#### **Higher Partial Derivatives**

Higher partial derivatives of a function is calculated the same way that regular higher derivatives are calculated.

$$\frac{\partial^2 f}{\partial x^2} = \frac{\partial}{\partial x} \frac{\partial f}{\partial x}$$

When differentiating with respect to two different variables, it is written as follows. Note that the subscript notation and the Leibniz have reversed order.

$$f_{yx}(x,y) = \frac{\partial}{\partial x} \frac{\partial}{\partial y} f(x,y) = \frac{\partial^2 f}{\partial x \partial y}$$

Clairaut's Theorem: If the both mixed partial derivatives of a function is locally continuous, then the partial derivatives commute.

$$\frac{\partial}{\partial x}\frac{\partial f}{\partial y} = \frac{\partial}{\partial y}\frac{\partial f}{\partial x} = \frac{\partial^2 f}{\partial x \partial y}$$

$$g(x,y) = xe^{x-y}$$

$$\frac{\partial g}{\partial x} = e^{x-y} + xe^{x-y}$$

$$= e^{x-y}(1+x)$$

$$\frac{\partial g}{\partial y} = xe^{x-y}(-1)$$

$$= -xe^{x-y}$$

# Example 2

$$f(x,y,z) = \frac{z \arctan(xy)}{y}$$

$$\frac{\partial f}{\partial x} = \frac{z}{y} \cdot \frac{1}{1 + (xy)^2} \cdot y$$

$$= \frac{z}{1 + x^2 y^2}$$

$$\frac{\partial f}{\partial y} = z \cdot \frac{\left(\frac{\partial}{\partial y} \arctan(xy)\right) y - \arctan(xy)}{y^2}$$

$$= \frac{z}{y^2} \left(\frac{xy}{1 + x^2 y^2} - \arctan(xy)\right)$$

$$\frac{\partial f}{\partial z} = \frac{\arctan(xy)}{y}$$

# **Tangent Planes**

A tangent line to y = f(x) at a is a line passing through (a, f(a)) that is parallel to the graph of f(x) at a.

$$y = \frac{df}{dx}x + b$$

A tangent plane to a function z = f(x, y) passing through a point  $(x_0, y_0)$  is a plane such that is passing the point (a, b, f(a, b)).

$$z = f_x(a,b)x + f_y(a,b)y + z_0$$

Thus

$$z = f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) + f(x_0, y_0)$$

The tangent plane is also called the linearization of a function at a point. The first degree Taylor polynomial  $T_1(x, y)$  is a tangent plane.

Find the tangent plane to  $z = 4x^2 + y^2$  at (x,y)=(1,2)

$$f(1,2) = 8$$

$$f_x(x,y) = 8x$$

$$f_x(1,2) = 8$$

$$f_y(x,y) = 2y$$

$$f_y(1,2) = 4$$

$$z = 8x + 4y + z_0$$

$$8 = 8(1) + 4(2) + z_0$$

$$z_0 = -8$$

$$z = 8x + 4y - 8$$

## Differential

For low changes in x and y, the difference in z can be approximated with differentials.

$$\Delta z \approx f_x(x, y)\Delta x + f_y(x, y)\Delta y$$
$$dz = f_x(x, y)dx + f_y(x, y)dy$$

## Example

Given the function  $u = \frac{t^4}{s^3}$ , use the total differential to find the change in u if s decreases by 0.2 and t increases by 0.1 when (s,t) = (2,1).

$$\Delta u \approx f_s(s, y)\Delta s + f_t(s, t)\Delta t$$

$$f_s(s, t) = -\frac{3t^4}{s^4}$$

$$f_t(s, t) = \frac{4t^3}{s^3}$$

$$\Delta u \approx -\frac{3t^4}{s^4}\Delta s + \frac{4t^3}{s^3}\Delta t$$

$$\Delta u \approx -\frac{3(1)^4}{(2)^4}(-0.2) + \frac{4(1)^3}{(2)^3}(0.1)$$

$$\Delta u \approx \frac{7}{80}$$

The volume of a cylinder is  $V = \pi r^2 h$ . What is the absolute error of the volume of a cylinder if the cylinder is measured to have a height of  $14m \pm 0.2$  and a radius of  $3m \pm 0.2$ 

$$dV = \frac{\partial V}{\partial r} dr + \frac{\partial V}{\partial h} dh$$

$$= 2\pi r h \ dr + \pi r^2 \ dh$$

$$= 2\pi (3)(14) \ dt + \pi (3)^2 \ dh$$

$$= 84\pi \ dr + 9\pi \ dh$$

$$\Delta V \approx 84\pi (0.2) + 9\pi (0.2)$$

$$\approx 18.6\pi$$

$$V = \pi r^2 h \pm \text{err}$$

$$V = \pi 3^2 \cdot 14 \pm \text{err}$$

$$V = 126\pi \ \text{m}^3 \pm 18.6\pi \ \text{m}^3$$

#### Multivariate Chain Rule

For 2 variables

$$z = f(x, y)$$
$$x = g(t)$$
$$y = h(t)$$

$$\frac{dz}{dt} = \frac{\partial z}{\partial x}\frac{dx}{dt} + \frac{\partial z}{\partial y}\frac{dy}{dt}$$

For n variables

$$f: \mathbb{R} \mapsto \mathbb{R}^n$$
$$g: \mathbb{R}^n \mapsto \mathbb{R}$$
$$\mathbf{y} = f(x)$$
$$z = g(\mathbf{y})$$

$$\frac{\partial x}{\partial z} = \sum_{i}^{n} \frac{\partial x}{\partial y_{i}} \frac{\partial y_{i}}{\partial z}$$

When evaluating derivatives of multivariate function, it may be advantages to draw tree diagrams showing the dependencies of the functions.

# Implicit Differentiation

In single variable

$$y = \frac{d}{dx}f(x) \Rightarrow \frac{d}{dx}g(y) = g'(y)\frac{dy}{dx}$$

Given a function F(x, y) = k where F is differentiable and k is a constant. We can assume that y can be locally represented as a function of x.

$$w = F(x, y)$$

$$y = f(x)$$

$$\frac{dw}{dx} = \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y} \frac{dy}{dx}$$

$$0 = \frac{\partial F}{\partial x} + \frac{\partial F}{\partial y} \frac{dy}{dx}$$

$$\frac{\partial F}{\partial y} \frac{dy}{dx} = -\frac{\partial F}{\partial x}$$

$$\frac{dy}{dx} = -\frac{\frac{\partial F}{\partial x}}{\frac{\partial F}{\partial y}}$$

$$\frac{dy}{dx} = -\frac{F_x}{F_y}$$

For multiple variables  $F(x_1, \ldots, x_n) = k$ :

$$\frac{\partial x_i}{\partial x_j} = -\frac{F_{x_j}}{F_{x_i}}$$

All relations can be made to be in that form by subtracting one side form the other.

$$(f(x_1, x_2, \dots) = g(x_1, x_2, \dots)) \Rightarrow (f(x_1, x_2, \dots) - g(x_1, x_2, \dots) = 0)$$

#### Example

Find 
$$\frac{dy}{dx}$$
 for  $e^{xy^2} = x - 3y$ 

$$e^{xy^{2}} = x - 3y$$

$$F(x,y) = x - 3y - e^{xy^{2}} = 0$$

$$F_{x}(x,y) = 1 - y^{2}e^{xy^{2}}$$

$$F_{y}(x,y) = -3 - 2xye^{xy^{2}}$$

$$\frac{dy}{dx} = -\frac{1 - y^{2}e^{xy^{2}}}{-3 - 2xye^{xy^{2}}}$$

$$= \frac{1 - y^{2}e^{xy^{2}}}{3 + 2xye^{xy^{2}}}$$

Find  $\frac{\partial z}{\partial y}$  for  $\cos(z^2 + xy) = \ln(x - z)$ .

$$F(x,y) = \ln(x-z) - \cos(z^2 + xy)$$

$$F_y = x \sin(z^2 + xy)$$

$$F_z = -\frac{1}{x-z} + 2z \sin(z^2 + xy)$$

$$\frac{\partial z}{\partial y} = -\frac{x \sin(z^2 + xy)}{-\frac{1}{x-z} + 2z \sin(z^2 + xy)}$$

$$= \frac{x \sin(z^2 + xy)}{\frac{1}{x-z} - 2z \sin(z^2 + xy)}$$

# Gradient

The gradient if function  $f: \mathbb{R}^n \to \mathbb{R}$  is a vector in  $\mathbb{R}^n$  such that the components of the vector are the derivative of f with respect to the component. Geometrically, the gradient vector points in the direction f increases in. Vectors orthogonal to the gradient are directions where the value of f doesn't change.

$$\nabla f(x_1, \dots, x_n) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix}$$

#### **Directional Derivatives**

The directional derivative  $D_{\hat{\mathbf{u}}}$  of a function f(x,y) in the direction of a unit vector  $\hat{u}$  is the dot product between  $\hat{u}$  and the gradient of the function.

$$D_{\hat{\mathbf{u}}}f(x,y) = \lim_{h \to 0} \frac{f(\mathbf{x} + h\hat{\mathbf{u}}) - f(\mathbf{x})}{h} = \nabla f \cdot \hat{\mathbf{u}}$$

For two variables:

$$\begin{split} D_{\mathbf{\hat{u}}}f(x,y) &= \lim_{h \to 0} \frac{f(x_1 + hu_1, x_2 + hu_2) - f(x_1, x_2)}{h} \\ &= \lim_{h \to 0} \frac{f(x_1 + hu_1, x_2 + hu_2) - f(x_1, x_2 + hu_2) + f(x_1, x_2 + hu_2) - f(x_1, x_2)}{h} \\ &= \frac{f(x_1 + hu_1, x_2 + hu_2) - f(x_1, x_2 + hu_2)}{h} + \frac{f(x_1, x_2 + hu_2) - f(x_1, x_2)}{h} \\ &= u_1 \frac{f(x_1 + hu_1, x_2 + hu_2) - f(x_1, x_2 + hu_2)}{hu_1} + u_2 \frac{f(x_1, x_2 + hu_2) - f(x_1, x_2)}{hu_2} \\ &= u_1 \frac{\partial f}{\partial x_1} + u_2 \frac{\partial f}{\partial x_2} \\ &= u \cdot \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix} \\ &= u \cdot \nabla f \end{split}$$

In general, this works for any number of variables.

$$D_{\hat{\mathbf{u}}}f = u \cdot \nabla f$$