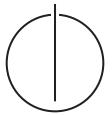


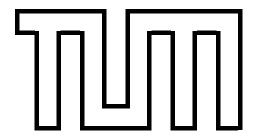
# FAKULTÄT FÜR INFORMATIK TECHNISCHE UNIVERSITÄT MÜNCHEN

Bachelor's thesis in Informatics

# Algorithms for refinement of modal process rewrite systems

Philipp Meyer





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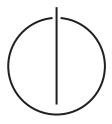
# Algorithmen zur Verfeinerung von modalen Prozessersetzungssystemen

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Munich, April 1, 2013	
	Philipp Meyer

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# 1 Introduction

## 2 Theory

## 2.1 Modal process rewrite system

Modal process rewrite systems [?] are a modal extension of process rewrite systems [?, ?]. They induce a modal transition systems [?].

#### 2.2 Basic definitions

**Definition 1** (Process term). The set of process terms over a set of constants Const is given by

$$\frac{1}{\varepsilon \in \mathcal{P}}(0) \qquad \frac{X \in Const}{X \in \mathcal{P}}(1)$$

$$\frac{p \in \mathcal{P} \quad q \in \mathcal{P}}{p \cdot q \in \mathcal{P}}(S) \qquad \frac{p \in \mathcal{P} \quad q \in \mathcal{P}}{p \| q \in \mathcal{P}}(P)$$

The processes expressions are considered modulo the usual structural congruence, i.e. the smallest congruence such that the operator  $\cdot$  is associative,  $\|$  is associative and commutative and  $\varepsilon$  is a unit for both  $\cdot$  and  $\|$ .

Processes that can be produced just with rule 0, 1 and S, i.e. contain no  $\parallel$ , are called *sequential processes* and processes that can be produced just with rule 0, 1 and P, i.e. contain no  $\cdot$ , are called *parallel processes* 

**Definition 2** (Size of a process term). The size |p| of a process term p is inductively defined by

$$\begin{aligned} |\varepsilon| &= 0 \\ |X| &= 1 \\ |p \cdot q| &= |p| + |q| \\ |p||q| &= |p| + |q| \end{aligned}$$

Process terms will be denoted by lowercase letters p, q, r, s, t, ... while single constants are denoted by uppercase letters P, Q, R, S, T, ...

**Definition 3** (Constants of a process term). The set of constants Const(p) appearing in a process term p is inductively defined by

$$\begin{split} Const(\varepsilon) &= \emptyset \\ Const(X) &= \{X\} \\ Const(p \cdot q) &= Const(p) \cup Const(q) \\ Const(p \| q) &= Const(p) \cup Const(q) \end{split}$$

## 2.3 Modal transition system

Modal transition system definition from [?]:

**Definition 4** (Modal transition system). A modal transition system (MTS) over an action alphabet Act is a triple  $(\mathcal{P}, -- \rightarrow, \longrightarrow)$  where  $\mathcal{P}$  is a set of processes and  $\longrightarrow \subseteq -- \rightarrow \subseteq \mathcal{P} \times Act \times \mathcal{P}$ . An element  $(p, a, q) \in -- \rightarrow$  is a may transition, also written as  $p \xrightarrow{a} q$ , and an element  $(p, a, q) \in \longrightarrow$  is a must transition, also written as  $p \xrightarrow{a} q$ .

## 2.4 Modal process rewrite system

**Definition 5** (Modal process rewrite system). A process rewrite system (PRS) over a set of constants Const and action alphabet Act is a finite relation.  $\Delta \subseteq \mathcal{P} \times Act \times \mathcal{P}$ , elements of which are called rewrite rules. A modal process rewrite system (mPRS) is a tuple  $(\Delta_{\text{may}}, \Delta_{\text{must}})$  where  $\Delta_{\text{may}}, \Delta_{\text{must}}$  are process rewrite systems such that  $\Delta_{\text{may}} \subseteq \Delta_{\text{must}}$ .

An mPRS  $(\Delta_{\max}, \Delta_{\text{must}})$  induces an MTS  $(\mathcal{P}, \dashrightarrow, \longrightarrow)$  as follows:

$$\frac{(p, a, p') \in \Delta_{\text{may}}}{p \xrightarrow{\frac{a}{-}} p'} (1) \quad \frac{(p, a, p') \in \Delta_{\text{must}}}{p \xrightarrow{\frac{a}{-}} p'} (2)$$

$$\frac{p \xrightarrow{\frac{a}{-}} p'}{p \cdot q \xrightarrow{\frac{a}{-}} p \cdot q} (3) \quad \frac{p \xrightarrow{\frac{a}{-}} p'}{p \cdot q \xrightarrow{\frac{a}{-}} p' \cdot q} (4) \quad \frac{p \xrightarrow{\frac{a}{-}} p'}{p \|q \xrightarrow{\frac{a}{-}} p\|q} (5) \quad \frac{p \xrightarrow{\frac{a}{-}} p'}{p \|q \xrightarrow{\frac{a}{-}} p'\|q} (6)$$

#### 2.5 Modal refinement

**Definition 6** (Refinement). Let  $(\mathcal{P}, -- \rightarrow, \longrightarrow)$  be an MTS and  $p, q \in \mathcal{P}$  be processes. We say that p refines q, written  $p \leq_m q$ , if there is a relation  $\mathcal{R} \subseteq \mathcal{P} \times \mathcal{P}$  such that  $(p,q) \in \mathcal{R}$  and for every  $(p,q) \in \mathcal{R}$  and every  $a \in Act$ :

- 1. If  $p \stackrel{a}{\dashrightarrow} p'$  then there is a transition  $q \stackrel{a}{\dashrightarrow} q'$  s.t.  $(p', q') \in \mathcal{R}$ .
- 2. If  $q \stackrel{a}{\longrightarrow} q'$  then there is a transition  $p \stackrel{a}{\longrightarrow} p'$  s.t.  $(p', q') \in \mathcal{R}$ .

#### 2.6 Attack tree

**Definition 7** (Attack transition and attack tree). Let  $(\mathcal{P}, \dashrightarrow, \longrightarrow)$  be an MTS. An *attack transition* is a tupel ((p,q),S) with  $(p,q)\in\mathcal{P}^2=\mathcal{P}\times\mathcal{P}$  and  $S\subseteq\mathcal{P}$ , also written as  $(p,q)\longrightarrow_a S$ . For  $p,q\in\mathcal{P}$ , the attack transitions are given by

$$\frac{p \xrightarrow{a} p'}{(p,q) \longrightarrow_{a} \{(p',q') \mid q \xrightarrow{a} q'\}} (1) \qquad \frac{q \xrightarrow{a} q'}{(p,q) \longrightarrow_{a} \{(p',q') \mid p \xrightarrow{a} p'\}} (2)$$

The set of attack trees labeled by  $s \in \mathcal{P}^2$  and  $S \subseteq \mathcal{P}^2$  is given by

$$\frac{(p,q) \longrightarrow_a \{s_1,...,s_n\} \quad \forall i: (s_i,T_i \text{ atree})}{((p,q),(T_1,...,T_n) \text{ atree})} \, (4)$$

For each state  $(p,q) \in \mathcal{A}$  we can construct a rooted and labeled *attack tree* by setting the root to (p,q), labeling it with  $(p,q) \longrightarrow_a S$  and setting the set of successors to the trees of states  $(p',q') \in S$ .

Intuitively, an attack transition  $(p,q)\longrightarrow_a S$  means that from the state (p,q), there is a sequence of *attack transitions*, that is a may transition from the left side or a must transition from the right side, such that S is the set of reachable states by applying appropriate *defending transition*, that is a transition of the same type and with the same action symbol from the other side.

**Theorem 1.** For an MTS  $(\mathcal{P}, \dashrightarrow, \longrightarrow)$  and processes  $p, q \in \mathcal{P}$ :

$$(p \leq_m q) \iff \neg \exists T : ((p,q), T \text{ atree})$$

*Proof.*  $\Rightarrow$ : Assume  $p \leq_m q$ . Then there is a refinement relation  $\mathcal{R}$ . Assume there is an attack tree ((p,q),T) atree). We show that any ((p,q),T) that  $(p,q) \notin R$  by induction on the attack tree:

- 1. T=(). Then there is an attack transition  $(p,q)\longrightarrow_a\emptyset$ . Contradiction.
- 2.  $T=(T_1,...,T_n)$ . Then  $(p,q)\longrightarrow_a (s_1,...,s_2)$ . By refinement there is an  $s_i\in\mathcal{R}$ . But as  $(s_i,T_i \text{ atree})$  the induction hypothesis gives  $s_i\notin\mathcal{R}$  resulting in a contradiction.

So for (p, q) there is no attack tree.

 $\Leftarrow$ : Assume  $\neg \exists T : ((p,q), T \text{ atree})$  We show that  $\mathcal{R} := \{(p,q) \mid \neg \exists T : ((p,q), T \text{ atree})\}$  is a valid refinement relation. First  $(p,q) \in \mathcal{R}$ , and for any  $(p,q) \in \mathcal{R}$ :

- 1. If  $p \stackrel{\text{a}}{\longrightarrow} p'$ , then by inference rule 1 there exists  $(p,q) \longrightarrow_a S$ . From all  $(p,q) \longrightarrow_a S$ , choose the one where S is minimal with regard to the inclusion order. There exists  $(p',q') \in S : \neg \exists T' : ((p',q'),T' \text{ atree})$ , because otherwise there would be a ((p,q),T atree). So this  $(p',q') \in S$  was created from a transition  $q \stackrel{\text{a}}{\dashrightarrow} q'$  and we have  $(p',q') \in \mathcal{R}$
- 2. If  $q \stackrel{\text{a}}{\longrightarrow} q'$ , by similar argument we get a transition  $p \stackrel{\text{a}}{\longrightarrow} p'$  for which  $(p',q') \in \mathcal{R}$ .

With this refinement relation we have  $p \leq_m q$ .

## 2.7 Visibly pushdown automaton

**Definition 8** (Visibly pushdown automaton). A PRS is a visibly pushdown automaton (vPDA) if all processes are sequential and there is a partition  $Act = Act_r \uplus Act_i \uplus Act_c$  such that each rule  $(p,a,p') \in \Delta$  has the form

$$p = P \cdot S \qquad \text{ and } \qquad p' = \begin{cases} Q & \text{ if } a \in Act_r & \text{ (return rule)} \\ Q \cdot T & \text{ if } a \in Act_i & \text{ (internal rule)} \\ Q \cdot T \cdot R & \text{ if } a \in Act_c & \text{ (call rule)} \end{cases}$$

The modal extension for a *modal visibly pushdown automaton (mvPDA)* is straightforward.

**Definition 9** (Attack rules for mvPDA). Let  $(\Delta_{\text{may}}, \Delta_{\text{must}})$  be an mvPDA. We define a attack rules  $(p, q) \longrightarrow_b S$  obtainable from the rewrite rules. For every  $p, q \in \mathcal{P}$ , we have:

$$\frac{(p,a,p')\in\Delta_{\text{may}}}{(p,q)\longrightarrow_{b}\{(p',q')\mid(q,a,q')\in\Delta_{\text{may}}\}}\,(1)$$

$$\frac{(q,a,q')\in\Delta_{\text{must}}}{(p,q)\longrightarrow_{b}\{(p',q')\mid(p,a,p')\in\Delta_{\text{must}}\}}\,(2)$$

$$\frac{(p,q)\longrightarrow_{b}\{(p'\cdot P,q'\cdot Q)\}\uplus S\quad (p',q')\longrightarrow_{b}S'\quad \forall (p'',q'')\in S':|p''|\leq 2}{(p,q)\longrightarrow_{b}S\cup\{(p''\cdot P,q''\cdot Q)\mid(p'',q'')\in S'\}}\,(3)$$

$$\frac{(p,q)\longrightarrow_{b}\{(p',q')\}\uplus S\quad (p',q')\longrightarrow_{b}S'\quad \forall (p'',q'')\in S':|p''|\leq 2}{(p,q)\longrightarrow_{b}S\cup S'}\,(4)$$

Due to the conditions on the rewrite rules of an mvPDA and the construction of the attack rules, we can see that for any element  $(p,q) \longrightarrow_b S$  it holds that |p| = |q| = 2 and for any  $(p',q') \in S$  that  $1 \le |p'| = |q'| \le 3$ .

**Lemma 1.** For an MTS generated by a mvPDA, if  $(p,q) \longrightarrow_a S$ , then  $(p \cdot s, q \cdot t) \longrightarrow_a S'$  with  $S' = \{(p' \cdot s, q' \cdot t) \mid (p', q') \in S\}$  for any  $s, t \in \mathcal{P}$ .

*Proof.* By the MTS induction rules, we have that for every  $p \stackrel{\text{a}}{\dashrightarrow} p'$  is generated from a  $(p,a,p') \in \Delta_{\text{may}}$  and for a mvPDA therefore |p|=2. Then there is only one transition from  $p \cdot s$ , nameley  $p \cdot s \stackrel{\text{a}}{\dashrightarrow} p' \cdot s$  generated by the MTS induction rule 1. Also for every  $q \stackrel{\text{a}}{\longrightarrow} q'$  there is just  $q \cdot t \stackrel{\text{a}}{\dashrightarrow} q' \cdot t$  from  $q \cdot t$ .

Then it is a single transition created from  $p \stackrel{\text{a}}{\dashrightarrow} p'$  with  $S = \{(p',q') \mid q \stackrel{\text{a}}{\dashrightarrow} q'\}$  and we get  $p \cdot s \stackrel{\text{a}}{\dashrightarrow} p' \cdot s$  and  $\{(p' \cdot s, q' \cdot t) \mid q \cdot t \stackrel{\text{a}}{\dashrightarrow} q' \cdot t\} = S'$ . If the transition was created from  $q \stackrel{\text{a}}{\longrightarrow} q'$  with  $S = \{(p',q') \mid p \stackrel{\text{a}}{\longrightarrow} p'\}$  and we get  $\{(p' \cdot s, q' \cdot t) \mid p \cdot t \stackrel{\text{a}}{\longrightarrow} p' \cdot t\} = S'$  Both cases yield  $(p \cdot s, q \cdot t) \stackrel{*}{\longrightarrow}_a^* S'$ .

**Theorem 2.** For an mvPDA  $(\Delta_{may}, \Delta_{must})$  with its induced MTS  $(\mathcal{P}, \dashrightarrow, \longrightarrow)$ , it holds that for any  $P, S, Q, T \in Const$ :

$$(P \cdot S, Q \cdot T) \longrightarrow_a^* \emptyset \iff (P \cdot S, Q \cdot T) \longrightarrow_b \emptyset$$

 $\begin{array}{l} \textit{Proof.} \implies: \text{Assume } (P \cdot S, Q \cdot T) \longrightarrow_a^* \emptyset \text{ and let } (a_1, a_2, ..., a_n) \text{ be the linear form of a derivation of the attack sequence. Always } a_1 \text{ has the form } (P \cdot S, Q \cdot T) \longrightarrow_a S \text{ and } a_n \text{ the form } (p,q) \longrightarrow_a \emptyset. \end{array}$ 

Our proposition is that if we can split up the sequence into subsequences which we can all compute seperately, we can also compute the whole sequence. More formally, we want to show that if there is a set of k+1 indices  $I=i_0,...,i_k$  where

- 1.  $0 = i_0 < i_1 < i_2 < \dots < i_{k-1} < i_k = n$ .
- 2. There is a sequence  $(b_1,...,b_k)$  where each  $b_i$  is an attack rule  $(p,q) \longrightarrow_b S$ .
- 3. For every  $i,j \in I$  with i < j the sequence  $(a_{i+1},...,a_j)$ , which generates the attack sequence  $(p,q) \longrightarrow_a^* S$ , the representing rule  $b_j$  is  $(p,q) \longrightarrow_b S$  If j < n then with  $b_i = (p',q') \longrightarrow_b S'$  we require  $(p',q') \in S'$ . and if j = n then  $S = \emptyset$ .

there is  $(P \cdot S, Q \cdot T) \longrightarrow_b \emptyset$ .

We prove this by induction on the number k:

- 1. k=1: Then the indices are 0,n and the rule sequence  $(b_1)$  represents  $(a_1,...,a_n)$  generating  $(P\cdot S,Q\cdot T)\longrightarrow_a^*\emptyset$ . Then we have  $(P\cdot S,Q\cdot T)\longrightarrow_b\emptyset$ .
- 2. k>1, and the induction hypothesis holds for any k'< k: Let  $(b_1,...,b_k)$  be the rule sequence. For the first rule  $b_1=(P\cdot S,Q\cdot T)\longrightarrow_b S$ , there is be  $(p',q')\in S$  with  $|p'|=|q'|\geq 2$  because otherwise no more rules could be applied afterwards, in contradiction to k>1. So this is a left-hand side rule. Also the last rule  $b_k=(p',q')\longrightarrow_b\emptyset$  is a right-hand side rule.

 $\Leftarrow$ : We show that for  $(p,q) \longrightarrow_b S$ , there is  $T \subseteq S$  with  $(p,q) \longrightarrow_a^* T$  by induction on the inference of  $(p,q) \longrightarrow_b S$ :

- 1. It was created by rule 1 from  $(p,a,p')\in \Delta_{\text{may}}$ . Then there is  $p\stackrel{\text{a}}{\dashrightarrow} p'$ . For every  $(q,a,q')\in \Delta_{\text{may}}$  there is  $q\stackrel{\text{a}}{\dashrightarrow} q'$  and for every  $q\stackrel{\text{a}}{\dashrightarrow} q''$  it follows that q'=q''. Then  $\{(p',q')\mid q\stackrel{\text{a}}{\dashrightarrow} q'\}=S$  and  $(p,q)\longrightarrow_a^*S$ .
- 2. It was created by rule 2 from  $(q,a,q')\in \Delta_{\mathrm{must}}$ . Then there is  $q\stackrel{\mathrm{a}}{\dashrightarrow} q'$ . For every  $(p,a,p')\in \Delta_{\mathrm{may}}$  there is  $p\stackrel{\mathrm{a}}{\dashrightarrow} p'$  and for every  $p\stackrel{\mathrm{a}}{\dashrightarrow} p''$  it follows that p'=p''. Then  $\{(p',q')\mid p\stackrel{\mathrm{a}}{\dashrightarrow} p'\}=S$  and  $(p,q)\longrightarrow_a^* S$ .
- 3. It was created by rule 3 from  $(p,q) \longrightarrow_b \{(p' \cdot P, q' \cdot Q)\} \uplus S' \text{ and } (p',q') \longrightarrow_b S''$  with  $S = S' \cup S'''$  for  $S''' = \{(p'' \cdot P, q'' \cdot Q) \mid (p'', q'') \in S''\}$  Then by induction hypothesis there is  $T' \subseteq \{(p' \cdot P, q' \cdot Q)\} \uplus S' \text{ with } (p,q) \longrightarrow_a^* T' \text{ and } T'' \subseteq S'' \text{ with } (p',q') \longrightarrow_a^* T''.$  If  $(p' \cdot P,q' \cdot Q) \notin T'$ , then we get  $T' \subseteq S' \subseteq S$ . If  $(p',q') \in T'$ , with lemma  $\ref{lem:substance}$  we have regard the  $(p' \cdot P,q' \cdot Q) \longrightarrow_a^* T'''$  with

#### 2 Theory

 $T''' \subseteq S'''$ . Then with lemma ?? we get that there is  $T \subseteq T' \setminus \{(p', q'\} \cup T''' \subseteq S' \cup S''' = S \text{ with } (p, q) \longrightarrow_a^* T$ .

4. It was created by rule 4 from  $(p,q) \longrightarrow_b \{(p',q')\} \uplus S'$  and  $(p',q') \longrightarrow_b S''$  with  $S = S' \cup S''$ . Then by induction hypothesis there is  $T' \subseteq \{(p',q')\} \uplus S'$  with  $(p,q) \longrightarrow_a^* T'$  and  $T'' \subseteq S''$  with  $(p',q') \longrightarrow_a^* T''$ . If  $(p',q') \notin T'$ , then we get  $T' \subseteq S' \subseteq S$ . If  $(p',q') \in T'$ , then with lemma  $\ref{eq:special}$ ? we get that there is  $T \subseteq T' \setminus \{(p',q'\} \cup T'' \subseteq S' \cup S'' = S \text{ with } (p,q) \longrightarrow_a^* T$ .

Then if  $(P\cdot S,Q\cdot T)\longrightarrow_b\emptyset$  we have  $(P\cdot S,Q\cdot T)\longrightarrow_a^*\emptyset$ 

# 3 Algorithms

## 3.1 Description

Figure 3.1: Algorithm for calculating the attack rules on mvPDAs

```
1: function AttackRules(mvPDA = (\Delta_{\max}, \Delta_{\max}))
        rules \leftarrow \emptyset
        for P, Q, S, T \in Const(mvPDA), a \in Act(mvPDA), type \in \{may, must\}
 3:
    do
 4:
             if type = may then
                  lhs \leftarrow (P \cdot S, Q \cdot T)
                                                     > Attack from left-hand side for may rules
 5:
             else
 6:
                 lhs \leftarrow (Q \cdot S, P \cdot Y)
                                                  > Attack from right-hand side for must rules
 7:
             end if
 8:
             for (P \cdot S, a, p') \in \Delta_{type} do
 9:
                 rhs \leftarrow \emptyset
10:
                 for (Q \cdot T, a, q') \in \Delta_{tupe} do
11:
                      if type = may then
12:
                           newRhs \leftarrow (p', q')
13:
                      else
14:
                           newRhs \leftarrow (q', p')
15:
                      end if
16:
                      rhs \leftarrow rhs \cup \{newRhs\}
17:
18:
                  rules \leftarrow rules \cup \{(lhs, rhs)\}
19:
             end for
20:
         end for
21:
        return rules
22:
23: end function
```

Figure 3.2: Algorithm for combining attack rules

```
1: function Combine(lhsRule = (lhs, lhsRhsSet), rhsRule = (rhsLhs, rhsSet))
       rules \leftarrow \emptyset
2:
       if \forall rhs \in rhsSet : size(rhs) \leq 1 then
3:
            for lhsRhs \in lhsRhsSet : lhsRhs = rhsLhs \cdot p do
4:
                newRhs \leftarrow (lhsRhsSet \setminus lhsRhs) \cup \{rhs \cdot p \mid rhs \in rhsSet\}
5:
                rules \leftarrow rules \cup \{(lhs, newRhs)\}
6:
            end for
7:
       end if
8:
9:
       return \ rules
10: end function
```

Figure 3.3: Refinement algorithm for mvPDAs

```
1: function VPDAREFINEMENT(P \cdot S, Q \cdot T, mvPDA) \triangleright P \cdot S \leq_m Q \cdot T given mvPDA

2: initial \leftarrow [P \cdot S, Q \cdot T]

3: rules \leftarrow \text{AttackRules}(mvPDA)

4: \mathbf{while} \ \exists lhsRule, rhsRule \in rules : \text{Combine}(lhsRule, rhsRule) \not\subset rules \ \mathbf{do}

5: rules \leftarrow rules \cup \text{Combine}(lhsRule, rhsRule)

6: \mathbf{end} \ \mathbf{while}

7: \mathbf{return} \ (initial, \emptyset) \in rules

8: \mathbf{end} \ \mathbf{function}
```

## 3.2 Soundness and completeness

#### 3.2.1 Soundness

#### 3.2.2 Completeness

### 3.3 Runtime

## 3.4 Optimizations

### 3.5 Performance evaluation

## 3.6 Example

Figure ?? and ?? define two mvPDA. The corresponding may transitions for the must transitions are implied. The problem is to decide whether  $p \cdot S \leq_m q \cdot S$ .

Figure 3.4: mvPDA for process  $P \cdot S$ 

Figure 3.5: mvPDA for process  $Q \cdot S$ 

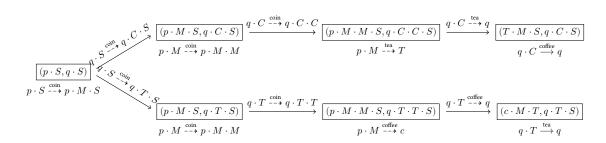


Figure 3.6: Tree for winning strategy

$$\begin{array}{c} (p \cdot M, q \cdot C) \longrightarrow \{(p \cdot M \cdot M, q \cdot C \cdot C)\} \end{array} \xrightarrow{\mathbf{call}} \begin{array}{c} (p \cdot M, q \cdot C) \longrightarrow \{(T, q)\} \end{array} \xrightarrow{\mathbf{return}} \begin{array}{c} (T \cdot M, q \cdot C) \longrightarrow \emptyset \end{array} \\ \\ (p \cdot S, q \cdot S) \longrightarrow \{(p \cdot M \cdot S, q \cdot C \cdot S), (p \cdot M \cdot S, q \cdot T \cdot S)\} \end{array} \xrightarrow{\mathbf{call}} \begin{array}{c} (p \cdot M, q \cdot T) \longrightarrow \{(c, q)\} \end{array} \xrightarrow{\mathbf{return}} \begin{array}{c} (c \cdot M, q \cdot T) \longrightarrow \emptyset \end{array}$$

Figure 3.7: Tree for winning strategy with attack rules

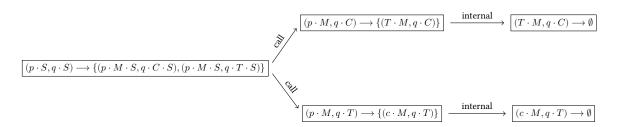


Figure 3.8: Merged tree for winning strategy with attack rules after one step

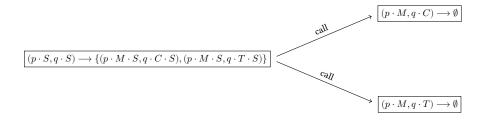


Figure 3.9: Merged tree for winning strategy with attack rules after two steps

$$(p\cdot S,q\cdot S)\longrightarrow\emptyset$$

Figure 3.10: Final merged tree for winning strategy

# 4 Conclusion

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