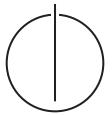


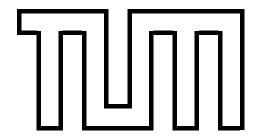
FAKULTÄT FÜR INFORMATIK TECHNISCHE UNIVERSITÄT MÜNCHEN

Bachelor's thesis in Informatics

Algorithms for refinement of modal process rewrite systems

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Algorithmen zur Verfeinerung von modalen Prozessersetzungssystemen

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Contents

1	Intr	oduction	1
2	The	ory	2
	2.1	Modal process rewrite system	2
	2.2	Basic definitions	2
	2.3	Modal transition system	3
	2.4	Modal process rewrite system	3
	2.5	Modal refinement	4
	2.6	Attack tree	4
	2.7	Visibly pushdown automaton	6
3	Alg	orithms	10
	3.1	Description	10
	3.2	Soundness and completeness	12
		3.2.1 Soundness	12
		3.2.2 Completeness	12
	3.3	Runtime	12
	3.4	Optimizations	12
	3.5	Performance evaluation	12
	3.6	Example	12
4	Con	clusion	14
Bi	bliog	raphy	15

1 Introduction

2 Theory

2.1 Modal process rewrite system

Modal process rewrite systems [BK12] are a modal extension of process rewrite systems [May00, Esp01]. They induce a modal transition systems [BKLS09].

2.2 Basic definitions

Definition 1 (Process term). The set of process terms over a set of constants Const is given by

$$\frac{1}{\varepsilon \in \mathcal{P}}(0) \qquad \frac{X \in Const}{X \in \mathcal{P}}(1)$$

$$\frac{p \in \mathcal{P} \quad q \in \mathcal{P}}{p \cdot q \in \mathcal{P}}(S) \qquad \frac{p \in \mathcal{P} \quad q \in \mathcal{P}}{p \| q \in \mathcal{P}}(P)$$

The processes expressions are considered modulo the usual structural congruence, i.e. the smallest congruence such that the operator \cdot is associative, $\|$ is associative and commutative and ε is a unit for both \cdot and $\|$.

Processes that can be produced just with rule 0, 1 and S, i.e. contain no \parallel , are called *sequential processes* and processes that can be produced just with rule 0, 1 and P, i.e. contain no \cdot , are called *parallel processes*

Definition 2 (Size of a process term). The size |p| of a process term p is inductively defined by

$$\begin{aligned} |\varepsilon| &= 0 \\ |X| &= 1 \\ |p \cdot q| &= |p| + |q| \\ |p||q| &= |p| + |q| \end{aligned}$$

Process terms will be denoted by lowercase letters p, q, r, s, t, ... while single constants are denoted by uppercase letters P, Q, R, S, T, ...

Definition 3 (Constants of a process term). The set of constants Const(p) appearing in a process term p is inductively defined by

$$\begin{split} Const(\varepsilon) &= \emptyset \\ Const(X) &= \{X\} \\ Const(p \cdot q) &= Const(p) \cup Const(q) \\ Const(p \| q) &= Const(p) \cup Const(q) \end{split}$$

2.3 Modal transition system

Modal transition system definition from [BK12]:

Definition 4 (Modal transition system). A modal transition system (MTS) over an action alphabet Act is a triple $(\mathcal{P}, -- \rightarrow, \longrightarrow)$ where \mathcal{P} is a set of processes and $\longrightarrow \subseteq -- \rightarrow \subseteq \mathcal{P} \times Act \times \mathcal{P}$. An element $(p, a, q) \in -- \rightarrow$ is a may transition, also written as $p \xrightarrow{a} q$, and an element $(p, a, q) \in \longrightarrow$ is a must transition, also written as $p \xrightarrow{a} q$.

2.4 Modal process rewrite system

Definition 5 (Modal process rewrite system). A process rewrite system (PRS) over a set of constants Const and action alphabet Act is a finite relation. $\Delta \subseteq \mathcal{P} \times Act \times \mathcal{P}$, elements of which are called rewrite rules. A modal process rewrite system (mPRS) is a tuple $(\Delta_{\text{may}}, \Delta_{\text{must}})$ where $\Delta_{\text{may}}, \Delta_{\text{must}}$ are process rewrite systems such that $\Delta_{\text{may}} \subseteq \Delta_{\text{must}}$.

An mPRS $(\Delta_{\max}, \Delta_{\max})$ induces an MTS $(\mathcal{P}, \dashrightarrow, \longrightarrow)$ as follows:

$$\frac{(p, a, p') \in \Delta_{\text{may}}}{p \xrightarrow{\frac{a}{-}} p'} (1) \quad \frac{(p, a, p') \in \Delta_{\text{must}}}{p \xrightarrow{\frac{a}{-}} p'} (2)$$

$$\frac{p \xrightarrow{\frac{a}{-}} p'}{p \cdot q \xrightarrow{\frac{a}{-}} p \cdot q} (3) \quad \frac{p \xrightarrow{\frac{a}{-}} p'}{p \cdot q \xrightarrow{\frac{a}{-}} p' \cdot q} (4) \quad \frac{p \xrightarrow{\frac{a}{-}} p'}{p \|q \xrightarrow{\frac{a}{-}} p\|q} (5) \quad \frac{p \xrightarrow{\frac{a}{-}} p'}{p \|q \xrightarrow{\frac{a}{-}} p'\|q} (6)$$

2.5 Modal refinement

Definition 6 (Refinement). Let $(\mathcal{P}, -- \rightarrow, \longrightarrow)$ be an MTS and $p, q \in \mathcal{P}$ be processes. We say that p refines q, written $p \leq_m q$, if there is a relation $\mathcal{R} \subseteq \mathcal{P} \times \mathcal{P}$ such that $(p,q) \in \mathcal{R}$ and for every $(p,q) \in \mathcal{R}$ and every $a \in Act$:

- 1. If $p \stackrel{a}{\dashrightarrow} p'$ then there is a transition $q \stackrel{a}{\dashrightarrow} q'$ s.t. $(p', q') \in \mathcal{R}$.
- 2. If $q \stackrel{a}{\longrightarrow} q'$ then there is a transition $p \stackrel{a}{\longrightarrow} p'$ s.t. $(p', q') \in \mathcal{R}$.

2.6 Attack tree

Definition 7 (Attack transition and attack tree). Let $(\mathcal{P}, \dashrightarrow, \longrightarrow)$ be an MTS. An *attack transition* is a tupel ((p,q),S) with $(p,q)\in\mathcal{P}^2=\mathcal{P}\times\mathcal{P}$ and $S\subseteq\mathcal{P}$, also written as $(p,q)\longrightarrow_a S$. For $p,q\in\mathcal{P}$, the attack transitions are given by

$$\frac{p\stackrel{\text{a}}{\dashrightarrow} p'}{(p,q)\longrightarrow_a \{(p',q')\mid q\stackrel{\text{a}}{\dashrightarrow} q'\}} (1) \qquad \frac{q\stackrel{\text{a}}{\longrightarrow} q'}{(p,q)\longrightarrow_a \{(p',q')\mid p\stackrel{\text{a}}{\longrightarrow} p'\}} (2)$$

The set of attack trees labeled by $(p,q) \in \mathcal{P}^2$ and $S \subseteq \mathcal{P}^2$ is given by

$$\frac{p,q\in\mathcal{P}\quad p\stackrel{\mathrm{a}}{\dashrightarrow} p'}{((p,q,p\stackrel{\mathrm{a}}{\dashrightarrow} p'),\{(p',q',q\stackrel{\mathrm{a}}{\dashrightarrow} q')\mid q\stackrel{\mathrm{a}}{\dashrightarrow} q'\},\emptyset)}(1)$$

$$\frac{p,q\in\mathcal{P}\qquad q\overset{\mathrm{a}}{\longrightarrow}q'}{((p,q),q\overset{\mathrm{a}}{\longrightarrow}q',\{(p',q',p\overset{\mathrm{a}}{\longrightarrow}p')\mid p\overset{\mathrm{a}}{\longrightarrow}p'\},\emptyset)}\left(2\right)$$

$$\frac{((p,q,r),O \uplus (p',q',r'),C) \text{ atree } \quad ((p',q',r'),O',C') \text{ atree } \quad (p',q',r') \in O}{((p,q,r),O,C \cup \{((p',q',r'),O',C')\}) \text{ atree}}$$

The root of an attack tree is root((p, q, r), O, C) = (p, q)

The set of open edges for an attack tree is given by $open(((p,q,r),O,C) \text{ atree}) = \{(p',q') \mid \exists r': (p',q',r') \in O\} \cup \bigcup_{T \in C} open(T).$ A tree T is a closed tree, written as closed(T), iff $open(T) = \emptyset$.

Intuitively, an attack transition $(p,q)\longrightarrow_a O$ means that from the state (p,q), there is a sequence of *attack transitions*, that is a may transition from the left side or a must transition from the right side, such that O is the set of reachable states by applying appropriate *defending transition*, that is a transition of the same type and with the same action symbol from the other side.

Lemma 1. For an attack tree ((p,q,r),O,C) atree, define the set $O \sqcup C = \{(p',q',r') \mid (p',q',r') \in O \lor \exists O',C': ((p',q',r'),O',C') \in C\}$. If $r=p \stackrel{a}{\dashrightarrow} p$, then there is $p \stackrel{a}{\dashrightarrow} p$ and $SC = \{(p',q',q \stackrel{a}{\dashrightarrow} q') \mid q \stackrel{a}{\dashrightarrow} q'\}$. If $r=q \stackrel{a}{\longrightarrow} q'$, then there is $q \stackrel{a}{\longrightarrow} q$ and $SC = \{(p',q',p \stackrel{a}{\longrightarrow} p' \mid p \stackrel{a}{\longrightarrow} p'\}$.

Proof. \Box

Lemma 2. For attack trees T = ((p,q,r), O, C) atree and T' = ((p',q',r'), O', C') atree with $(p',q',r') \in open(T)$, there exists a tree T'' = ((p,q,r),O'',C'') with $open(T'') = (open(T) \setminus \{(p',q',r')\}) \cup open(T')$.

 \square

Theorem 1. For an MTS $(\mathcal{P}, \dashrightarrow, \longrightarrow)$ and processes $p, q \in \mathcal{P}$:

$$(p \leq_m q) \iff \neg \exists T : root(T) = (p,q) \land closed(T)$$

Proof. ⇒: Assume $p \leq_m q$. Then there is a refinement relation \mathcal{R} . Let T = ((p,q,r),O,C) atree be a closed attack tree. As $open(T) = \{(p',q') \mid \exists r' : (p',q',r') \in O\} \cup \bigcup_{T' \in C} open(T') = \emptyset$, we have $O = \emptyset$. and therefore $|O \sqcup C| = |C|$. We show by induction on |C| that $(p,q) \notin R$:

- 1. |C|=0: Then there is an attacking rule r, but no defending rule, therefore $(p,q)\notin \mathcal{R}$.
- 2. $|C| \geq 0$: Then as $open(T) = \bigcup_{T' \in C} open(T') = \emptyset$, we have for every $T' = ((p',q',r'),O',C') \in C$ that $open(T') = \emptyset$ and by induction hypothesis $(p',q') \notin \mathcal{R}$. Then there is an attacking rule r, but for every defending rule r' leading to (p',q') we have $(p',q') \in \mathcal{R}$, therefore $(p,q) \notin \mathcal{R}$.

So for (p,q) there is no attack tree. \Leftarrow : Assume $\neg \exists T : root(T) = (p,q) \land closed(T)$ We show that $\mathcal{R} := \{(p,q) \mid \neg \exists T : root(T) = (p,q) \land closed(T)\}$ is a valid refinement relation. First $(p,q) \in \mathcal{R}$, and for any $(p,q) \in \mathcal{R}$:

If the attacking rule is r, then by by inference rule 1 or 2 there exists T=((p,q,r),O,C) atree. From all such T, choose the one where O is minimal with regard to the inclusion order.

There exists $(p',q',r') \in O: (p',q') \in \mathcal{R}$, because otherwise there would be a closed attack tree T' = ((p',q',r'),O',C') atree and with this tree by inference rule 3 we would get $((p,q,r),O''\setminus\{(p',q',r')\},C\cup T')$ with $O''=O\setminus\{(p',q',r')\}\subsetneq O$ in contradiction to the minimality of O. So for the attack rule r there is a defending rule r' leading to $(p',q')\in\mathcal{R}$.

With this refinement relation we have $p \leq_m q$.

2.7 Visibly pushdown automaton

Definition 8 (Visibly pushdown automaton). A PRS is a visibly pushdown automaton (vPDA) if all processes are sequential and there is a partition $Act = Act_r \uplus Act_i \uplus Act_c$ such that each rule $(p,a,p') \in \Delta$ has the form

$$p = P \cdot S \qquad \text{ and } \qquad p' = \begin{cases} Q & \text{if } a \in Act_r & \text{(return rule)} \\ Q \cdot T & \text{if } a \in Act_i & \text{(internal rule)} \\ Q \cdot T \cdot R & \text{if } a \in Act_c & \text{(call rule)} \end{cases}$$

The modal extension for a *modal visibly pushdown automaton* (*mvPDA*) is straightforward.

Definition 9 (Attack rules for mvPDA). Let $(\Delta_{\text{may}}, \Delta_{\text{must}})$ be an mvPDA. We define a attack rules $(p, q) \longrightarrow_b S$ obtainable from the rewrite rules. For every $p, q \in \mathcal{P}$, we have:

$$\frac{(p,a,p')\in\Delta_{\text{may}}}{(p,q)\longrightarrow_b\{(p',q')\mid(q,a,q')\in\Delta_{\text{may}}\}}\,(1)$$

$$\frac{(q,a,q')\in\Delta_{\text{must}}}{(p,q)\longrightarrow_b\{(p',q')\mid(p,a,p')\in\Delta_{\text{must}}\}}\,(2)$$

$$\frac{(p,q)\longrightarrow_b\{(p'\cdot P,q'\cdot Q)\}\uplus S\quad (p',q')\longrightarrow_b S'\quad \forall (p'',q'')\in S':|p''|=1}{(p,q)\longrightarrow_b S\cup\{(p''\cdot P,q''\cdot Q)\mid(p'',q'')\in S'\}}\,(3)$$

$$\frac{(p,q)\longrightarrow_b\{(p',q')\}\uplus S\quad (p',q')\longrightarrow_b S'\quad \forall (p'',q'')\in S':|p''|=1}{(p,q)\longrightarrow_b S\cup S'}\,(4)$$

Due to the conditions on the rewrite rules of an mvPDA and the construction of the attack rules, we can see that for any element $(p,q) \longrightarrow_b S$ it holds that |p| = |q| = 2 and for any $(p',q') \in S$ that $1 \le |p'| = |q'| \le 3$.

Then we see that rules 3 and 4 always combine a rule where on the left-hand side, there is (p',q') in S with |p'|=2 or |p'|=3, while on the right-hand side we require for all $(p'',q'')\in S'$ that |p''|=1. Therefore we will call an attack rule $(p,q)\longrightarrow_b S$ a right-hand side rule if $\forall (p',q')\in S: |p'|=1$ and otherwise a left-hand side rule.

Lemma 3. Given an MTS generated by a mvPDA, for an attack tree ((p,q,r),O,C) atree with open(T) = S and $any s, t \in \mathcal{P}$, there is also a tree $T' = ((p \cdot s, q \cdot t, r'), O', C')$ atree with $open(T') = \{(p' \cdot s, q' \cdot t, r'') \mid (p', q', r') \in open(T)\}$.

Proof. By the MTS induction rules, we have that for every $p \stackrel{\text{a}}{\dashrightarrow} p'$ is generated from a $(p,a,p') \in \Delta_{\text{may}}$ and for a mvPDA therefore |p|=2. Then there is only one transition from $p \cdot s$, nameley $p \cdot s \stackrel{\text{a}}{\dashrightarrow} p' \cdot s$ generated by the MTS induction rule 1. Also for every $q \stackrel{\text{a}}{\longrightarrow} q'$ there is just $q \cdot t \stackrel{\text{a}}{\longrightarrow} q' \cdot t$ from $q \cdot t$.

Then it is a single transition created from $p \stackrel{\text{a}}{\dashrightarrow} p'$ with $S = \{(p',q') \mid q \stackrel{\text{a}}{\dashrightarrow} q'\}$ and we get $p \cdot s \stackrel{\text{a}}{\dashrightarrow} p' \cdot s$ and $\{(p' \cdot s, q' \cdot t) \mid q \cdot t \stackrel{\text{a}}{\dashrightarrow} q' \cdot t\} = S'$. If the transition was created from $q \stackrel{\text{a}}{\longrightarrow} q'$ with $S = \{(p',q') \mid p \stackrel{\text{a}}{\longrightarrow} p'\}$ and we get $\{(p' \cdot s, q' \cdot t) \mid p \cdot t \stackrel{\text{a}}{\longrightarrow} p' \cdot t\} = S'$. Both cases yield $(p \cdot s, q \cdot t) \stackrel{*}{\longrightarrow}_a^* S'$.

Theorem 2. For an mvPDA $(\Delta_{may}, \Delta_{must})$ with its induced MTS $(\mathcal{P}, \dashrightarrow, \longrightarrow)$, it holds that for any $P, S, Q, R \in Const$:

$$\exists T: root(T) = (P \cdot S, Q \cdot R) \land closed(T) \iff (P \cdot S, Q \cdot T) \longrightarrow_b \emptyset$$

Proof. \Rightarrow : Assume T to be closed tree with $root(T) = (P \cdot S, Q \cdot T)$.

the linear form of a derivation of the attack sequence. Always a_1 has the form $(P \cdot S, Q \cdot R) \longrightarrow_a S$ and a_n the form $(p,q) \longrightarrow_a \emptyset$.

Our proposition is that if we can split up the sequence into subsequences which we can all compute seperately, we can also compute the whole sequence. More formally, we want to show that if there is a set of k+1 indices $I=i_0,...,i_k$ where

- 1. $0 = i_0 < i_1 < i_2 < \dots < i_{k-1} < i_k = n$.
- 2. There is a sequence $(b_1,...,b_k)$ where each b_i is an attack rule $(p,q)\longrightarrow_b S$.
- 3. For every $i,j \in I$ with i < j the sequence $(a_{i+1},...,a_j)$, which generates the attack sequence $(p,q) \longrightarrow_a^* S$, the representing rule b_j is $(p,q) \longrightarrow_b S$ If j < n then with $b_i = (p',q') \longrightarrow_b S'$ we require $(p',q') \in S'$. and if j = n then $S = \emptyset$.

there is $(P \cdot S, Q \cdot T) \longrightarrow_b \emptyset$.

We prove this by induction on the number k:

- 1. k=1: Then the indices are 0,n and the rule sequence (b_1) represents $(a_1,...,a_n)$ generating $(P\cdot S,Q\cdot T)\longrightarrow_a^*\emptyset$. Then we have $(P\cdot S,Q\cdot T)\longrightarrow_b\emptyset$.
- 2. k>1, and the induction hypothesis holds for any k'< k: Let $(b_1,...,b_k)$ be the rule sequence. For the first rule $b_1=(P\cdot S,Q\cdot T)\longrightarrow_b S$, there is be $(p',q')\in S$ with $|p'|=|q'|\geq 2$ because otherwise no more rules could be applied afterwards, in contradiction to k>1. So this is a left-hand side rule. Also the last rule $b_k=(p',q')\longrightarrow_b\emptyset$ is a right-hand side rule.

 \Leftarrow : We show that for $(p,q) \longrightarrow_b S$, there is a tree T = ((p,q,r),O,C) atree) such that open(T) = S. by induction on the inference of $(p,q) \longrightarrow_b S$:

1. If it was created by rule 1 or 2. If it was created from $(p,a,p') \in \Delta_{\text{may}}$, then there is an attacking transition $r = p \stackrel{\text{a}}{\dashrightarrow} p'$ and for every $(q,a,q') \in \Delta_{\text{may}}$ there is one induced defending transition $r' = q \stackrel{\text{a}}{\dashrightarrow} q'$. If it was created from $(q,a,q') \in \Delta_{\text{must}}$, then there is an attacking transition $r = p \stackrel{\text{a}}{\dashrightarrow} p'$ and for every $(q,a,q') \in \Delta_{\text{may}}$ there is one induced defending transition $r' = q \stackrel{\text{a}}{\dashrightarrow} q'$.

Therefore states(def(p,q,r)) = S and get the tree $T = ((p,q,r), def(p,q,r), \emptyset)$ atree with open(T) = S.

- 2. It was created by rule 3 from $(p,q) \longrightarrow_b \{(p' \cdot P, q' \cdot Q)\} \uplus S''$ and $(p',q') \longrightarrow_b S'$ with $S = S'' \cup S'''$ and $S''' = \{(p'' \cdot P, q'' \cdot Q) \mid (p'',q'') \in S'\}$. Then by induction hypothesis there is a tree $T' = ((p' \cdot P, q' \cdot Q, r'), O', C')$ atree with open(T') = S' and a tree T'' = ((p,q,r),O,C) atree with $open(T'') = S'' \uplus \{(p' \cdot P,q' \cdot Q,r')\}$. By lemma 3 there is also a tree $T''' = ((p \cdot P,q \cdot Q,r'),O'',C'')$ atree with $open(T''') = O''' \uplus \{(p' \cdot P,q' \cdot Q,r'')\}$ and $O''' = \{(p'' \cdot P,q'' \cdot Q,r''') \mid (p'',q'',r'') \in S'\} = S'''$. By lemma 2 we then get a tree T = ((p,q,r),O'''',C'''') with $open(T) = S'' \cup S''' = S$.
- 3. It was created by rule 4 from $(p,q) \longrightarrow_b \{(p',q')\} \uplus S''$ and $(p',q') \longrightarrow_b S'$ with $S = S'' \cup S'$. Then by induction hypothesis there is a tree T' = ((p',q',r'),O',C') atree with open(T') = S' and a tree T'' = ((p,q,r),O,C) atree with $open(T'') = S'' \uplus \{(p',q')\}$. By lemma 2 we then get a tree T = ((p,q,r),O'',C'') with $open(T) = S'' \cup S' = S$.

Then if $(P \cdot S, Q \cdot T) \longrightarrow_b \emptyset$ we have a tree $T = (P \cdot S, Q \cdot T, r), O, C)$ with $open(T) = \emptyset$.

3 Algorithms

3.1 Description

Figure 3.1: Algorithm for calculating the attack rules on mvPDAs

```
1: function AttackRules(mvPDA = (\Delta_{\max}, \Delta_{\max}))
        rules \leftarrow \emptyset
        for P, Q, S, T \in Const(mvPDA), a \in Act(mvPDA), type \in \{may, must\}
 3:
    do
 4:
             if type = may then
                  lhs \leftarrow (P \cdot S, Q \cdot T)
                                                     > Attack from left-hand side for may rules
 5:
             else
 6:
                 lhs \leftarrow (Q \cdot S, P \cdot Y)
                                                  > Attack from right-hand side for must rules
 7:
             end if
 8:
             for (P \cdot S, a, p') \in \Delta_{type} do
 9:
                 rhs \leftarrow \emptyset
10:
                 for (Q \cdot T, a, q') \in \Delta_{tupe} do
11:
                      if type = may then
12:
                           newRhs \leftarrow (p', q')
13:
                      else
14:
                           newRhs \leftarrow (q', p')
15:
                      end if
16:
                      rhs \leftarrow rhs \cup \{newRhs\}
17:
18:
                  rules \leftarrow rules \cup \{(lhs, rhs)\}
19:
             end for
20:
         end for
21:
        return rules
22:
23: end function
```

Figure 3.2: Algorithm for combining attack rules

```
1: function Combine(lhsRule = (lhs, lhsRhsSet), rhsRule = (rhsLhs, rhsSet))
       rules \leftarrow \emptyset
2:
       if \forall rhs \in rhsSet : size(rhs) \leq 1 then
3:
            for lhsRhs \in lhsRhsSet : lhsRhs = rhsLhs \cdot p do
4:
                newRhs \leftarrow (lhsRhsSet \setminus lhsRhs) \cup \{rhs \cdot p \mid rhs \in rhsSet\}
5:
                rules \leftarrow rules \cup \{(lhs, newRhs)\}
6:
            end for
7:
       end if
8:
9:
       return \ rules
10: end function
```

Figure 3.3: Refinement algorithm for mvPDAs

```
1: function VPDAREFINEMENT(P \cdot S, Q \cdot T, mvPDA) \triangleright P \cdot S \leq_m Q \cdot T given mvPDA

2: initial \leftarrow [P \cdot S, Q \cdot T]

3: rules \leftarrow \text{AttackRules}(mvPDA)

4: \mathbf{while} \ \exists lhsRule, rhsRule \in rules : \text{Combine}(lhsRule, rhsRule) \not\subset rules \ \mathbf{do}

5: rules \leftarrow rules \cup \text{Combine}(lhsRule, rhsRule)

6: \mathbf{end} \ \mathbf{while}

7: \mathbf{return} \ (initial, \emptyset) \in rules

8: \mathbf{end} \ \mathbf{function}
```

3.2 Soundness and completeness

3.2.1 Soundness

3.2.2 Completeness

3.3 Runtime

3.4 Optimizations

3.5 Performance evaluation

3.6 Example

Figure 3.4 and 3.5 define two mvPDA. The corresponding may transitions for the must transitions are implied. The problem is to decide whether $p \cdot S \leq_m q \cdot S$.

Figure 3.4: mvPDA for process $P \cdot S$

Figure 3.5: mvPDA for process $Q \cdot S$

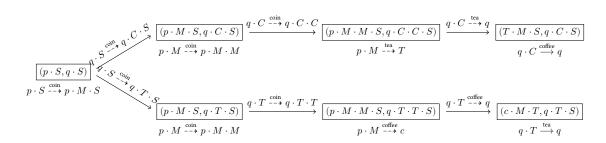


Figure 3.6: Tree for winning strategy

$$\begin{array}{c} (p \cdot M, q \cdot C) \longrightarrow \{(p \cdot M \cdot M, q \cdot C \cdot C)\} \end{array} \xrightarrow{\mathbf{call}} \begin{array}{c} (p \cdot M, q \cdot C) \longrightarrow \{(T, q)\} \end{array} \xrightarrow{\mathbf{return}} \begin{array}{c} (T \cdot M, q \cdot C) \longrightarrow \emptyset \end{array} \\ \\ (p \cdot S, q \cdot S) \longrightarrow \{(p \cdot M \cdot S, q \cdot C \cdot S), (p \cdot M \cdot S, q \cdot T \cdot S)\} \end{array} \xrightarrow{\mathbf{call}} \begin{array}{c} (p \cdot M, q \cdot T) \longrightarrow \{(c, q)\} \end{array} \xrightarrow{\mathbf{return}} \begin{array}{c} (c \cdot M, q \cdot T) \longrightarrow \emptyset \end{array}$$

Figure 3.7: Tree for winning strategy with attack rules

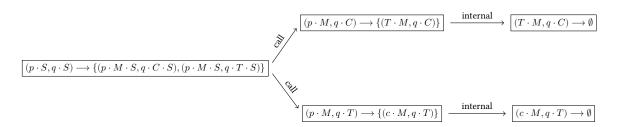


Figure 3.8: Merged tree for winning strategy with attack rules after one step

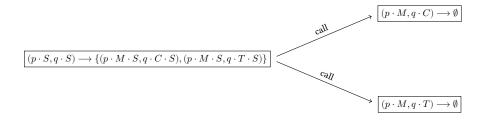


Figure 3.9: Merged tree for winning strategy with attack rules after two steps

$$(p\cdot S,q\cdot S)\longrightarrow\emptyset$$

Figure 3.10: Final merged tree for winning strategy

4 Conclusion

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