

Linear Algebra

Matrices: Rectangular array of numbers in rows & columns

vectors: both size & direction



$$v = \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix}$$

Uses: To solve linear equations
Linear Transformations
Eigen values & Eigen Vectors
PCA
Neural networks
Linear Regression.

Linear Equations: Represents straight line when plotted
1st power of variable is 1

$$Ax + By = C$$

$$2x + 3y = 8$$

$$y = 5x - 1$$

$$x = 4$$

Gaussian elimination: Used to solve system of linear Equations

Example:

$$x - 2y + z = 0$$

$$2x + 2y - 3z = 5$$

$$4x - 7y + z = -1$$

$$Ax = b$$

STEP 1:

Augmented Matrix $\rightarrow \left[\begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 2 & 2 & -3 & 5 \\ 4 & -7 & 1 & -1 \end{array} \right]$

STEP 2:

1st Goal \rightarrow 0 below 1st entry in 1st column
using Row operations

$$\left[\begin{array}{ccc|c} -1 & -2 & 1 & 0 \\ 2 & 2 & -3 & 5 \\ 4 & -7 & 1 & -1 \end{array} \right] \xrightarrow{\substack{-2r_1 + r_2 \\ -4r_1 + r_3}} \left[\begin{array}{ccc|c} 1 & -2 & 1 & 0 \\ 0 & 5 & -5 & 5 \\ 0 & 1 & -3 & 1 \end{array} \right]$$

STEPS:

2nd goal: below 2nd entry in second column using row operations.

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 5 & -5 & 5 \\ 0 & 1 & -3 & -1 \end{bmatrix} \xrightarrow{r_2 \leftrightarrow r_3} \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -3 & -1 \\ 0 & 5 & -5 & 5 \end{bmatrix}$$

$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -3 & -1 \\ 0 & 5 & -5 & 5 \end{bmatrix} \xrightarrow[-r_2]{-5r_2 +} \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 1 & -3 & -1 \\ 0 & 0 & 10 & 10 \end{bmatrix}$$

echelon form

STEP 4: Use 2nd row to find the third unknown (z) & find 1st & 2nd similarly.

$$10z = 10$$

$$z = 1$$

solve for 2nd unknown (y)

$$y - 3z = -1$$

$$y = -1 + 3z$$

$$y = -1 + 3$$

$$y = 2$$

solve for 1st unknown (x)

$$x - 2y + 1 = 0$$

$$x = 2y - 1$$

$$x = 4 - 1$$

$$x = 3$$

$$(x, y, z) \rightarrow (3, 2, 1)$$

solution of system

Cases of Gaussian elimination method:

Case 1

$$\begin{bmatrix} 1 & 2 & 3 & | & 10 \\ 0 & 2 & 4 & | & 5 \\ 0 & 0 & 3 & | & 3 \end{bmatrix}$$

↑ ↑
t_{nn} c_{nn}

When t_{nn} ≠ 0

Unique solution

Consistent system

Case 2

$$\begin{bmatrix} 1 & 2 & 3 & | & 10 \\ 0 & 2 & 4 & | & 5 \\ 0 & 0 & 0 & | & 3 \end{bmatrix}$$

↑ ↑
t_{nn} c_{nn}

When t_{nn} = 0
c_{nn} ≠ 0

No solution

Inconsistent contradiction

Case 3

$$\begin{bmatrix} 1 & 2 & 3 & | & 10 \\ 0 & 2 & 4 & | & 5 \\ 0 & 0 & 0 & | & 0 \end{bmatrix}$$

↑ ↑
t_{nn} c_{nn}

When t_{nn} = 0
c_{nn} = 0

Infinitely many solutions

Consistent

REF and RREF

REF

$$\begin{bmatrix} a & b & c \\ 0 & d & e \\ 0 & 0 & f \end{bmatrix}$$

0's below pivots
all non zero rows
above all zero rows

example: $\begin{bmatrix} 0 & 1 & 3 & 2 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 3 \end{bmatrix}$

after REF in linear equation

- Gaussian elimination substitution can be done to get values.
- REF not for inverse matrix since it is not fully reduced.

RREF

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

1s at leading places (pivots)
and pivot column each has only 1 non zero value

example: $\begin{bmatrix} 1 & 7 & 0 & 2 & 0 \\ 0 & 0 & 1 & 3 & 0 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$

"fully simplified"

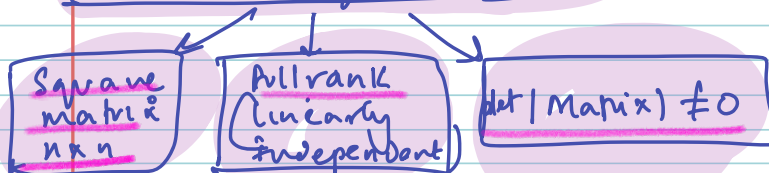
- easier to interpret results.
- "Used to find inverse of matrix"

Inverse of Matrices:

Use elementary operation to

Transform matrix into Reduced REF

Conditions for Inverse:



If A RREF = full rank
Inverse exists

If last row of AREP are all zero then it is not full rank as -1 doesn't occur.

If A is full rank then
 $A^{-1} = E_r E_{r-1} \dots E_1$
all elementary

Inverse of 2×2

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$A^{-1} = \frac{1}{ad-bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} \quad 2 \times 2$$

exists only if $ad-bc \neq 0$

Inverse for 3×3

$$A^{-1} = \frac{1}{|\det(A)|} \text{adj}(A) \quad 3 \times 3$$

exists if $\det(A) \neq 0$

- Steps: (3x3)
1. Find $\det(A)$ if $\neq 0$, continue
 2. Find cofactors of C_{ij} each and make cofactor matrix
 3. Make adjugate matrix: Transpose of cofactor matrix
 4. Divide $\text{adj}(A)$ with $\det(A)$

Rank Nullity Theorem

Rank: no. of linearly independent rows or cols vectors of matrix
#(non zero eigen values of matrix)

Nullity: how many independent solutions exist to homo. eq $Ax=0$

Example:

$A = \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$	$A = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$
$R(A)=1, N(A)=2, n=3$ $1+2=3$	$R(A)=4$ $N(A)=2$ $n=6$

For any matrix A of size $m \times n$
 $[A]_{m \times n}$

Rank Nullity Theorem states that:

$$\text{Rank}(A) + \text{Nullity}(A) = n \quad (\text{no of columns})$$