

Homework 4

posted on Brightspace

due next Mon (Oct 3) at 11:59pm^{*}

(pushed back so I'm not lecturing about topics for a homework due two days later)

(due late on Mon so people can ask last-minute questions that Mon after class)

Homework4.pdf (written description)

Homework4.ipynb (notebook to use for your solution)

difdata.csv

^{*} most homeworks will continue to be due at class time

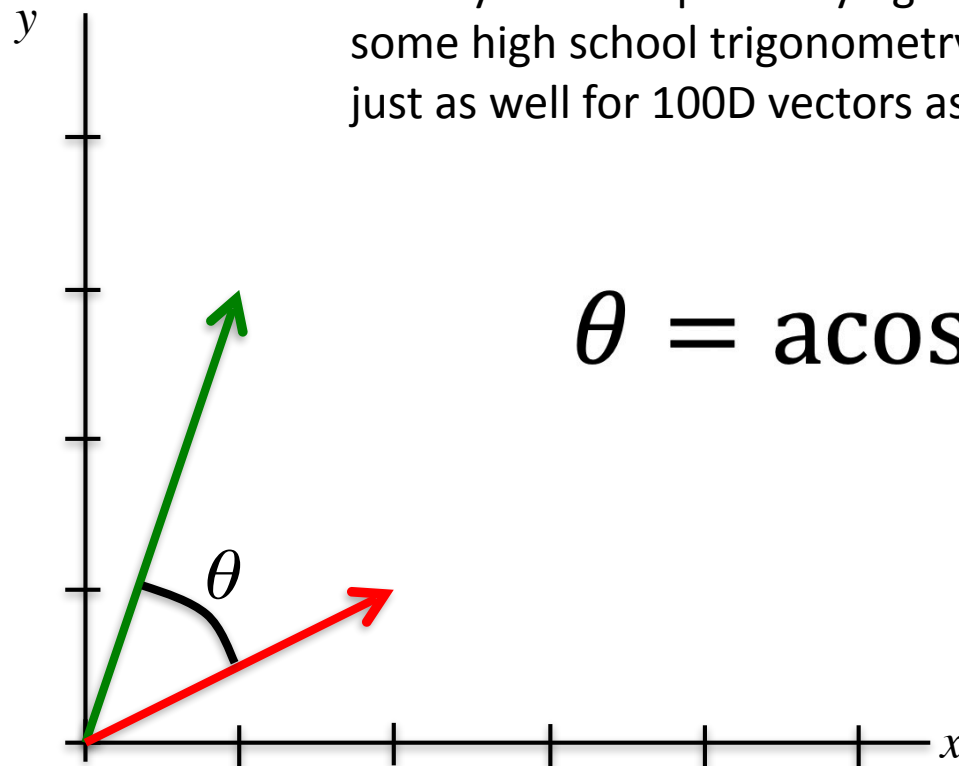
download from Brightspace

VectorsMatricesLinearAlgebra.ipynb
ControlFlow.ipynb

angle between two vectors

```
an = np.linalg.norm(a)
bn = np.linalg.norm(b)
theta = math.acos(np.dot(a,b) / (an*bn))
print(np.rad2deg(theta))
```

while you could probably figure this angle out using some high school trigonometry, this method works just as well for 100D vectors as for 2D vectors

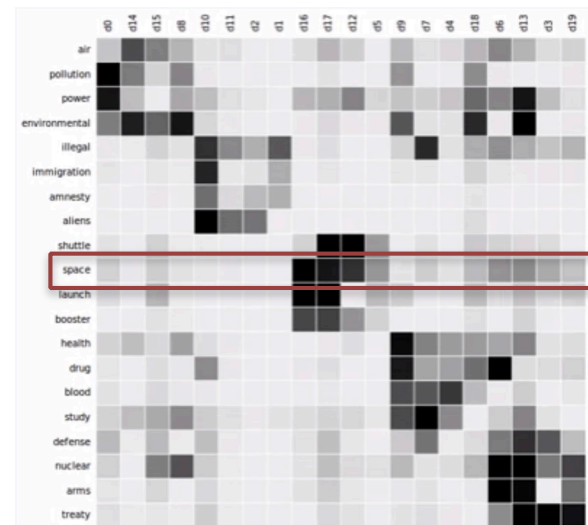
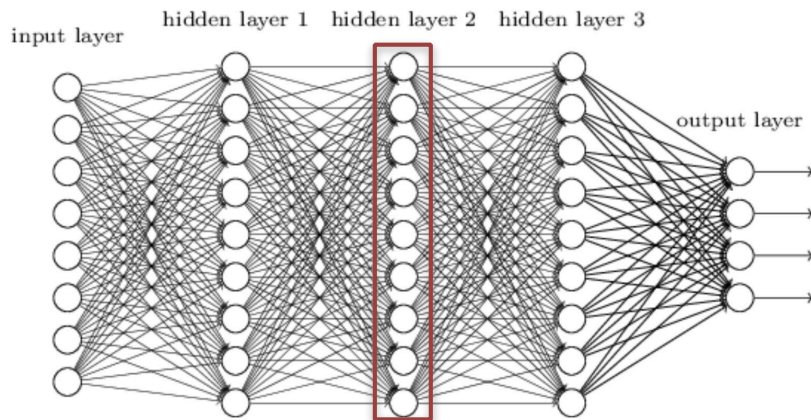


$$\theta = \text{acos} \left(\frac{\mathbf{a} \cdot \mathbf{b}}{\|\mathbf{a}\| \|\mathbf{b}\|} \right)$$

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 cosine angle is sometimes used to measure the similarity between two vector representations

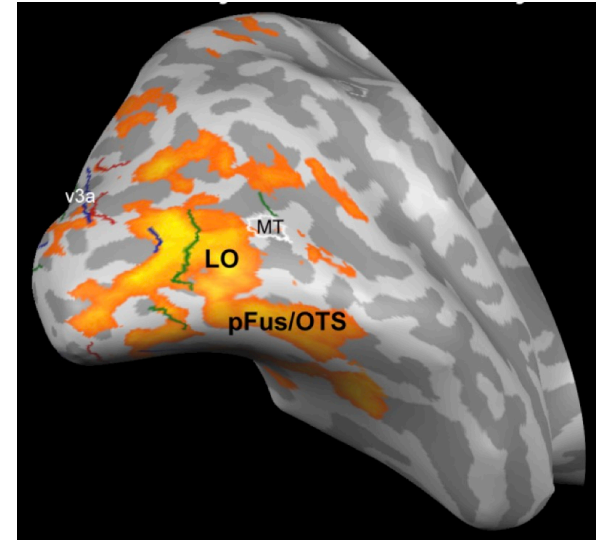
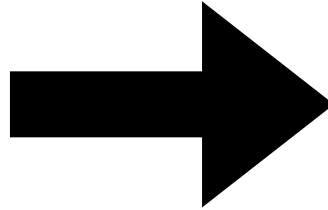


- some number of psychological measures
- or psychological, social, and demographic measures
- or some number of neural measures

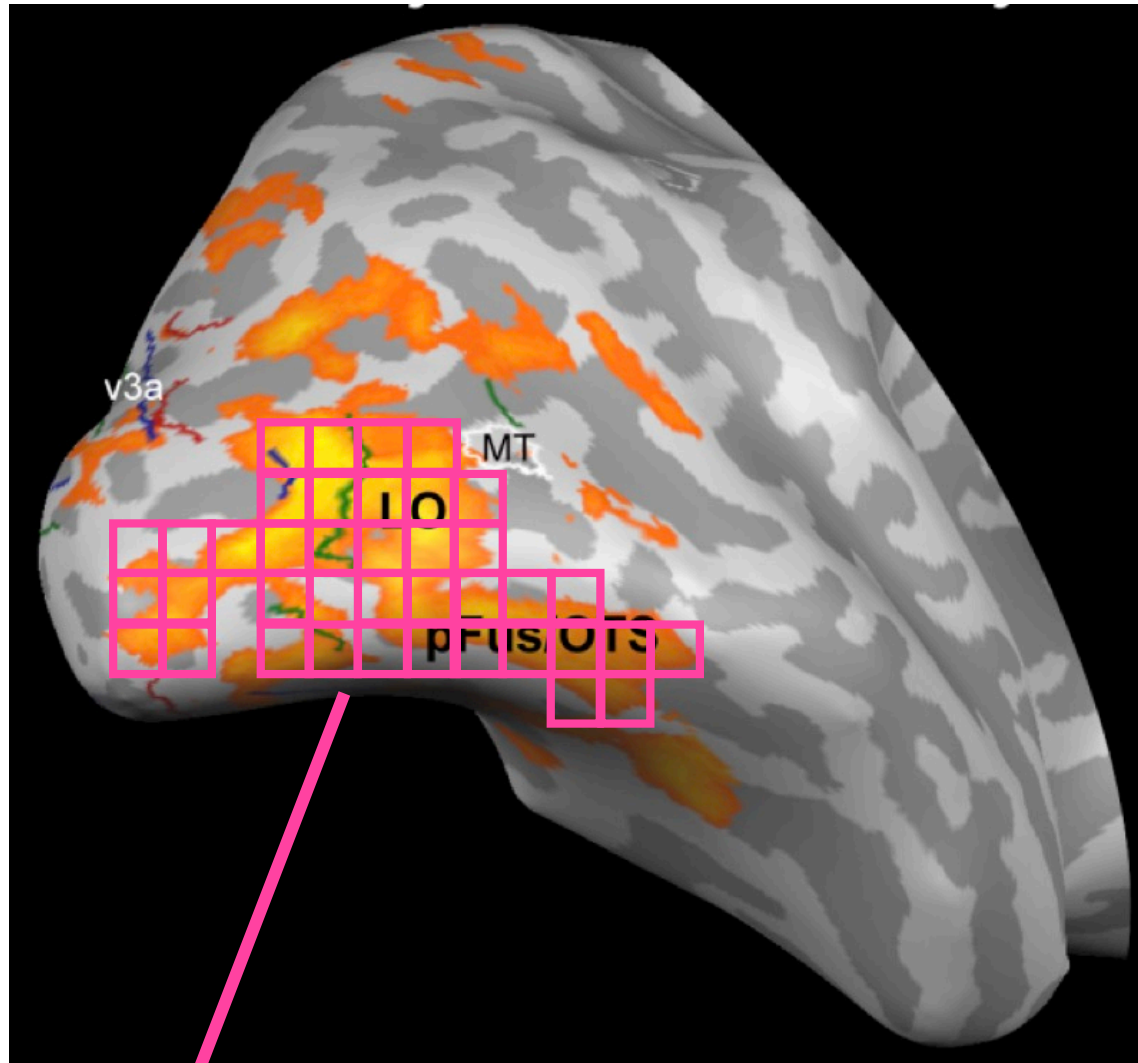


- activity of a units in a layer of a neural network model
- semantic representation of a word from latent semantic analysis

e.g., computing similarity in fMRI activation for objects



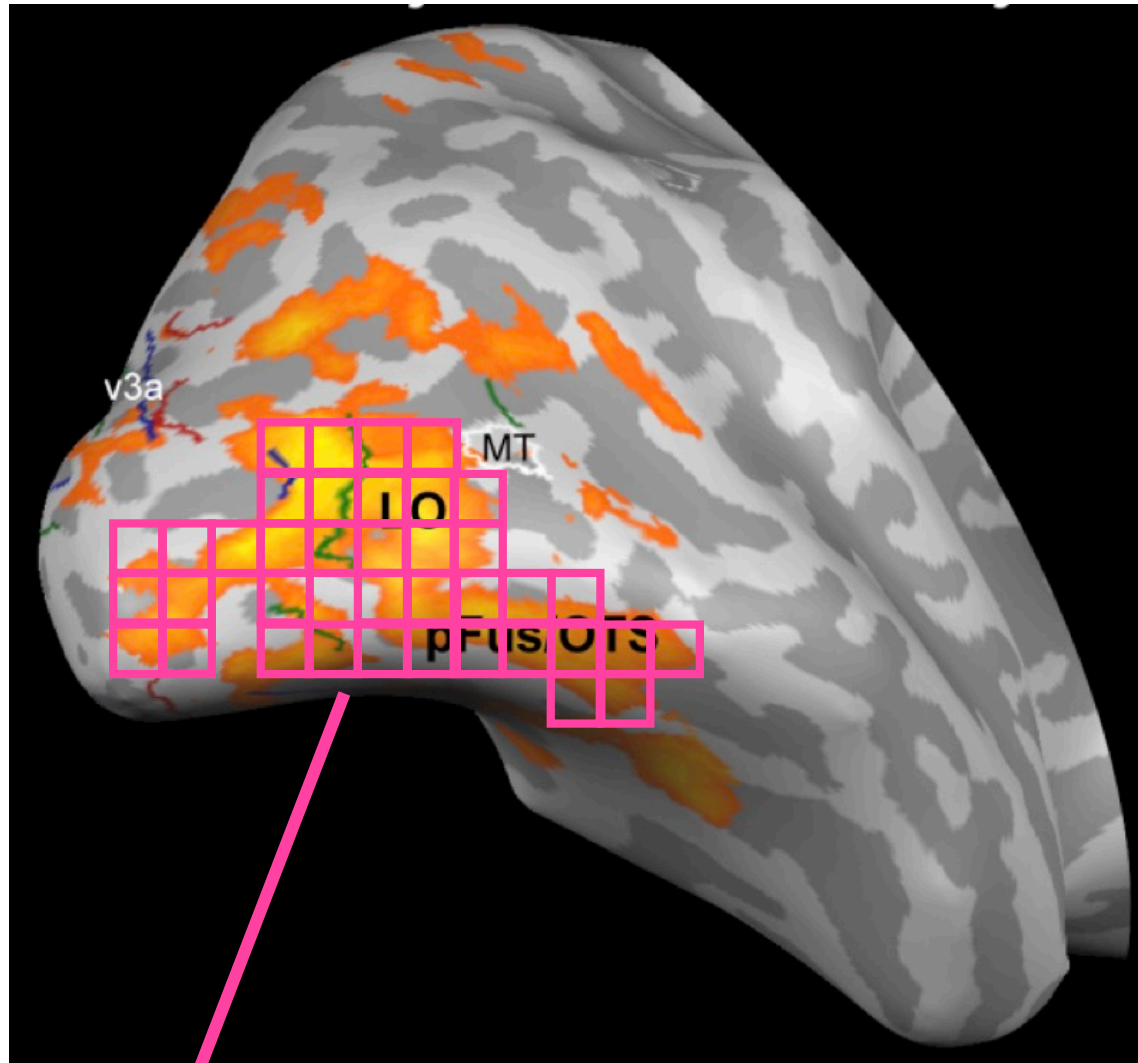
e.g., computing similarity in fMRI activation for objects



.23	.49	.12	.72	.1143	.87
.18	.39	.22	.83	.0921	.76

similarity of (voxel)
representations?

e.g., computing similarity in fMRI activation for objects



.23	.49	.12	.72	.1143	.87
.73	.23	.76	.32	.1398	.12

similarity of (voxel)
representations?



.23	.49	.12	.72	.11
-----	-----	-----	-----	-----

.49	.12	.72	.11
-----	-----	-----	-----

.12	.72	.11
-----	-----	-----

.72	.11
-----	-----

.11

...

.43	.87
-----	-----

.87



.18	.39	.22	.83	.09
-----	-----	-----	-----	-----

.39	.22	.83	.09
-----	-----	-----	-----

.22	.83	.09
-----	-----	-----

.83	.09
-----	-----

.09

...

.21	.76
-----	-----

.76



.73	.23	.76	.32	.13
-----	-----	-----	-----	-----

.23	.76	.32	.13
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.76	.32	.13
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.32	.13
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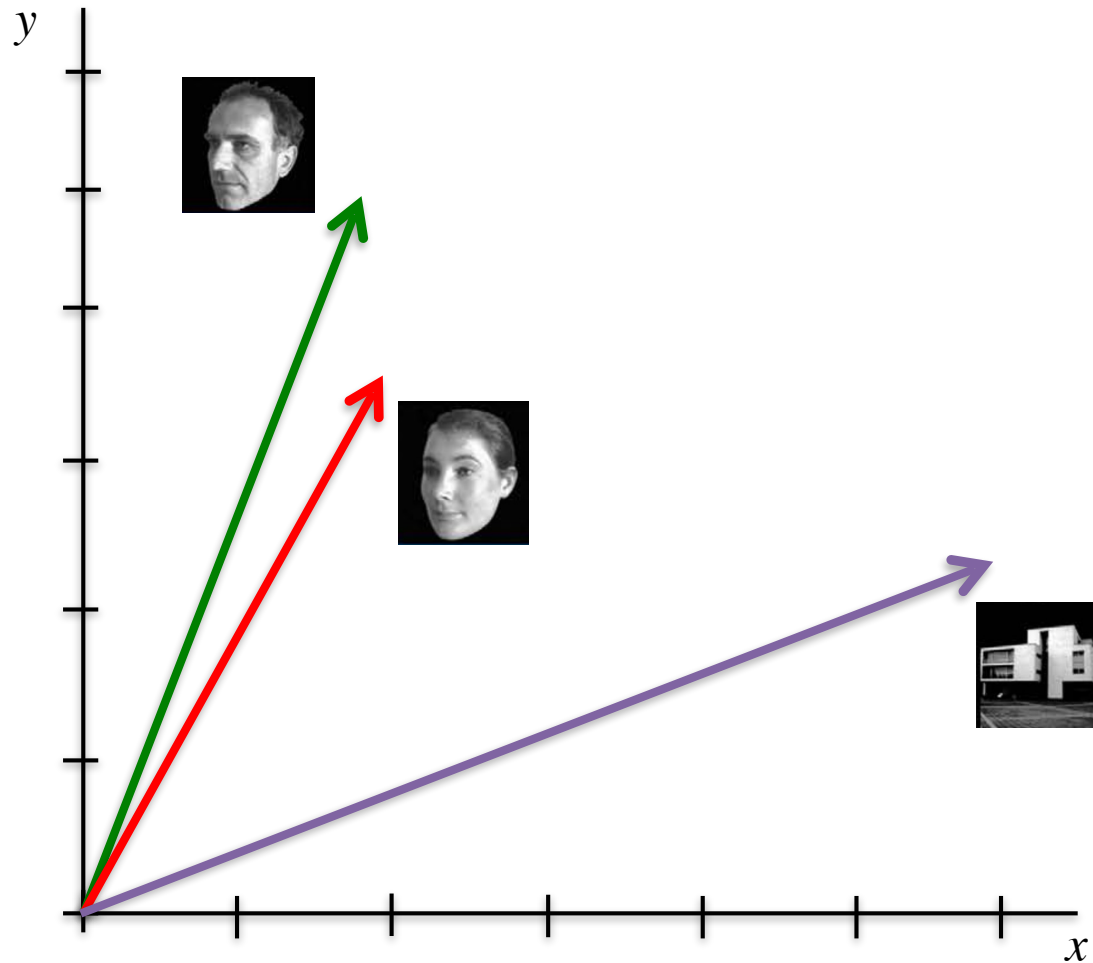
.13

...

.98	.12
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.12

similarity of (voxel)
representations?



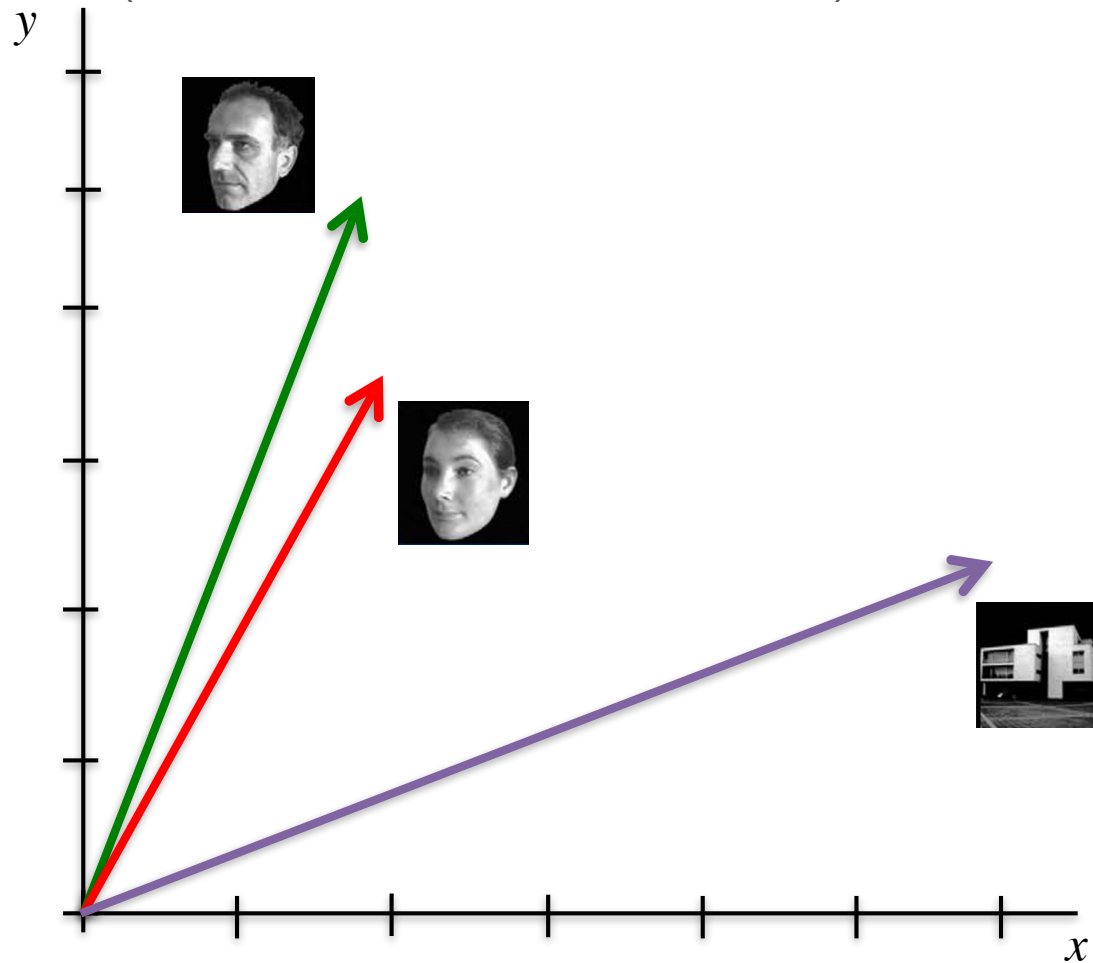
could be in a 40D space
(here only showing 2D)



.23	.49	.12	.72	.1143	.87
.18	.39	.22	.83	.0921	.76
.73	.23	.76	.32	.1398	.12

similarity of (voxel)
representations?

similarity via Pearson correlation
($\cos \theta$ of vectors mean-centered)





.23	.49	.12	.72	.11
-----	-----	-----	-----	-----

...

.43	.87
-----	-----



.18	.39	.22	.83	.09
-----	-----	-----	-----	-----

...

.21	.76
-----	-----

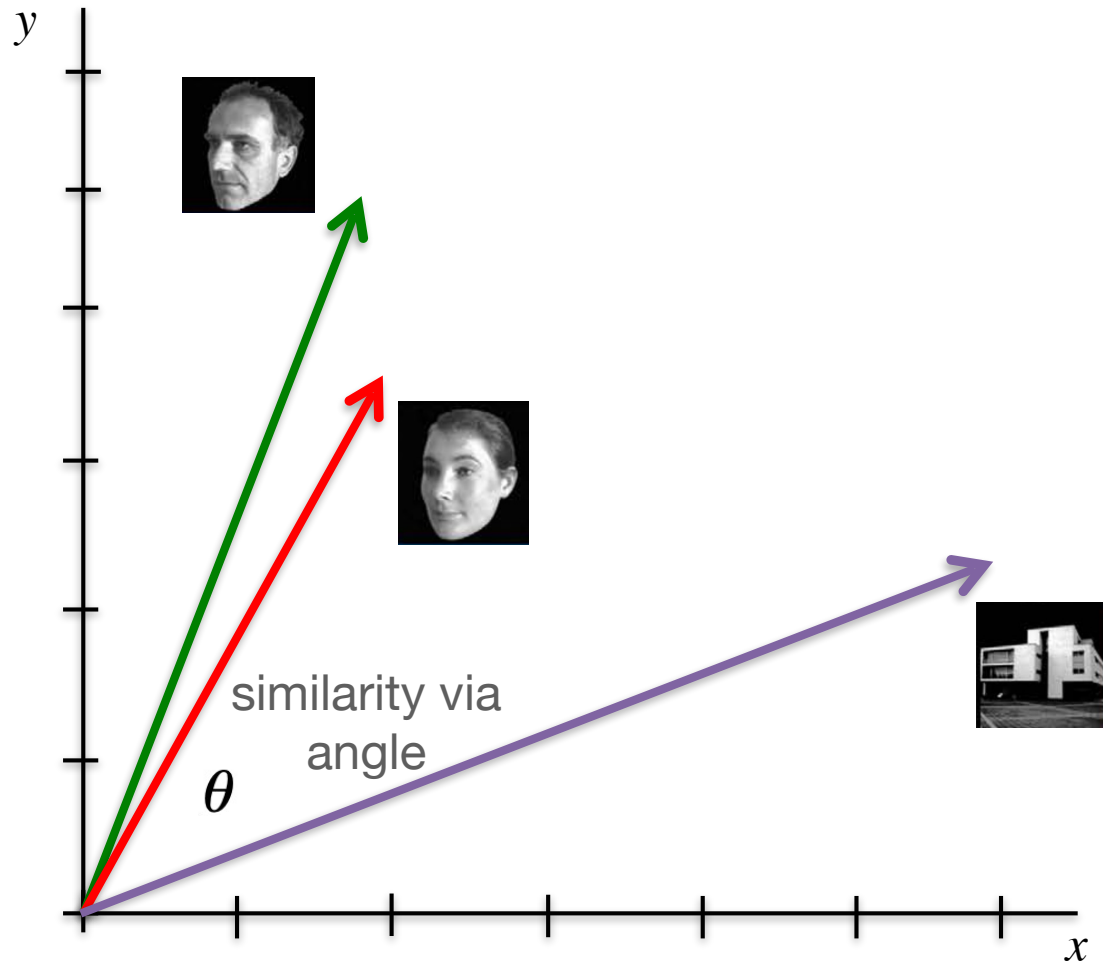


.73	.23	.76	.32	.13
-----	-----	-----	-----	-----

...

.98	.12
-----	-----

similarity of (voxel)
representations?





.23

.49

.12

.72

.11

...

.43

.87



.18

.39

.22

.83

.09

...

.21

.76



.73

.23

.76

.32

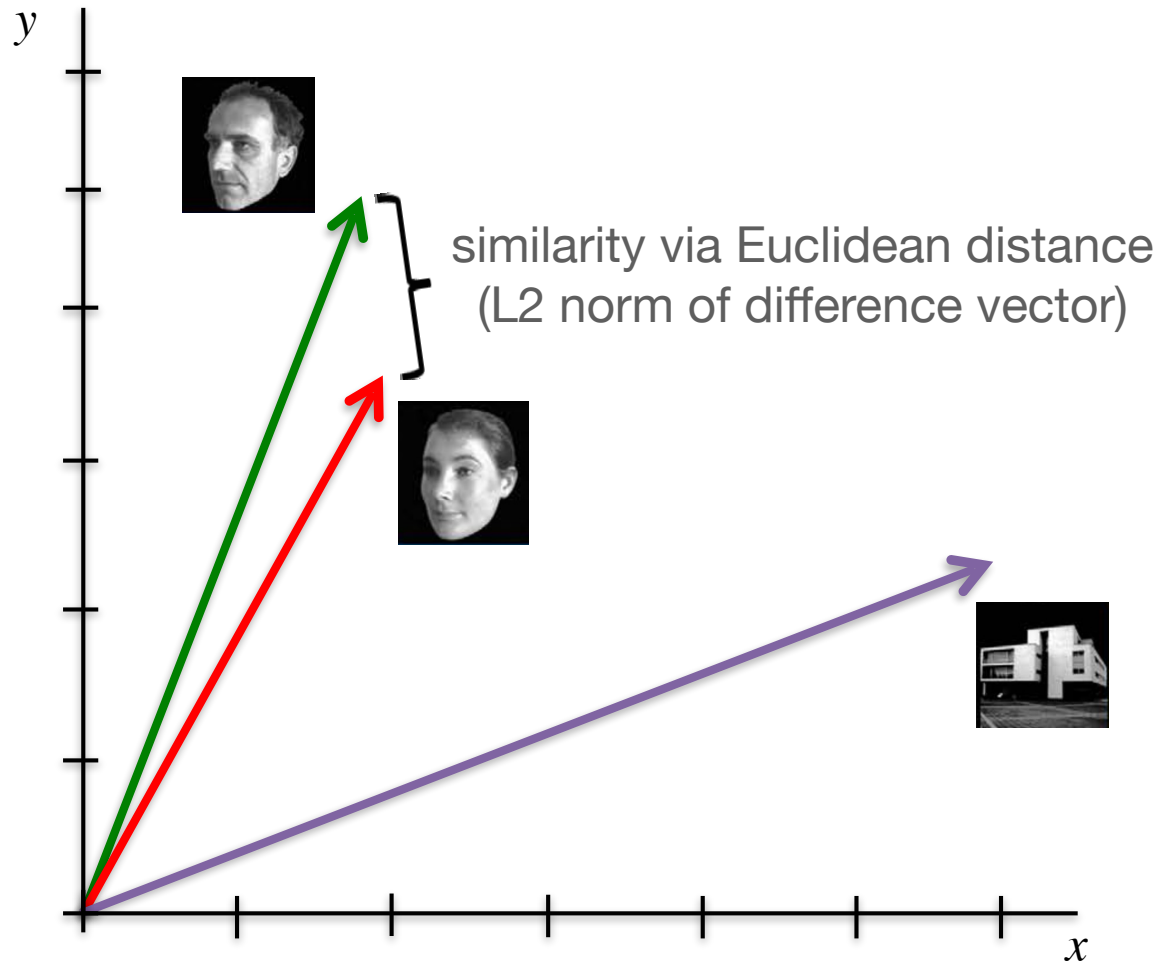
.13

...

.98

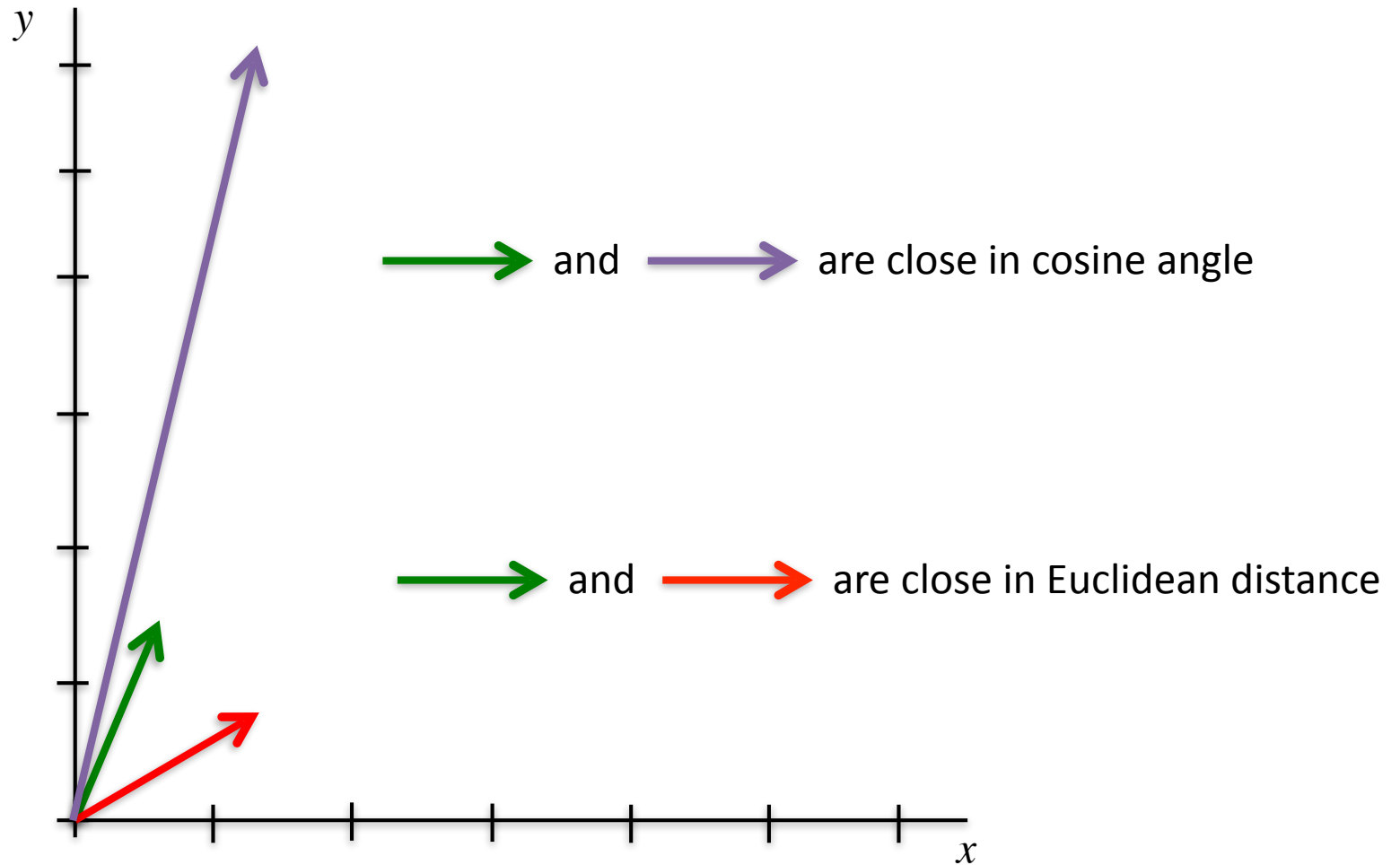
.12

similarity of (voxel)
representations?

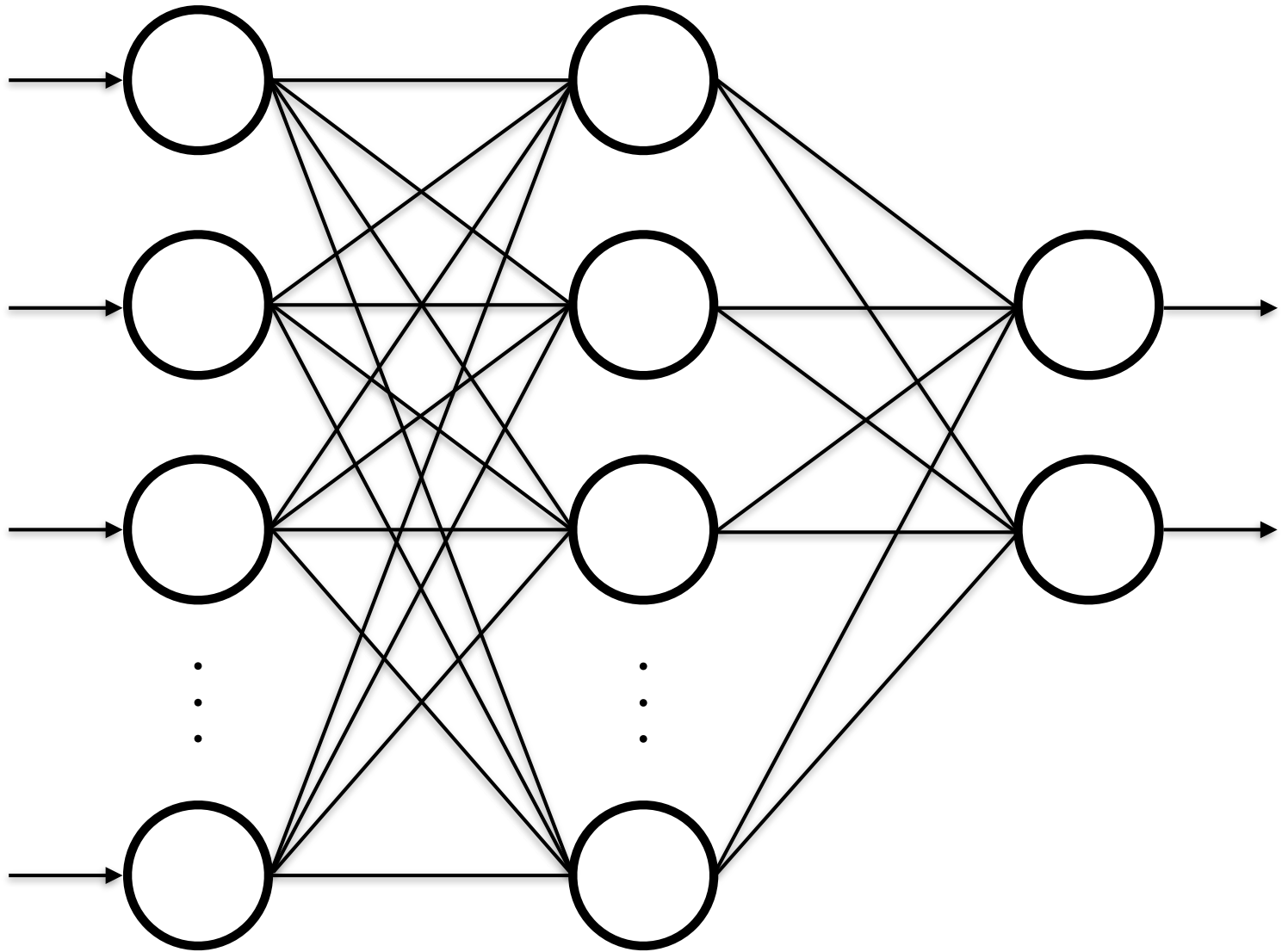


cosine angle vs. Euclidean distance

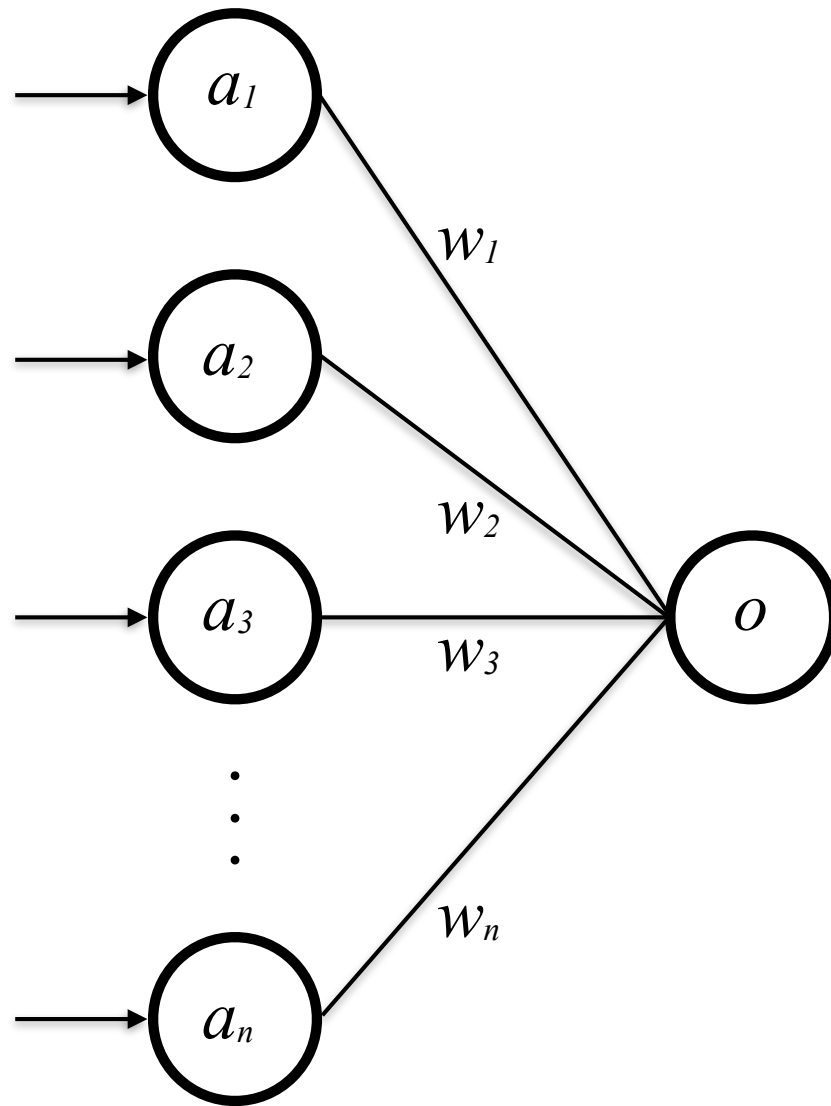
depends on what the vectors (and their distances) mean



math of a simple neural network model

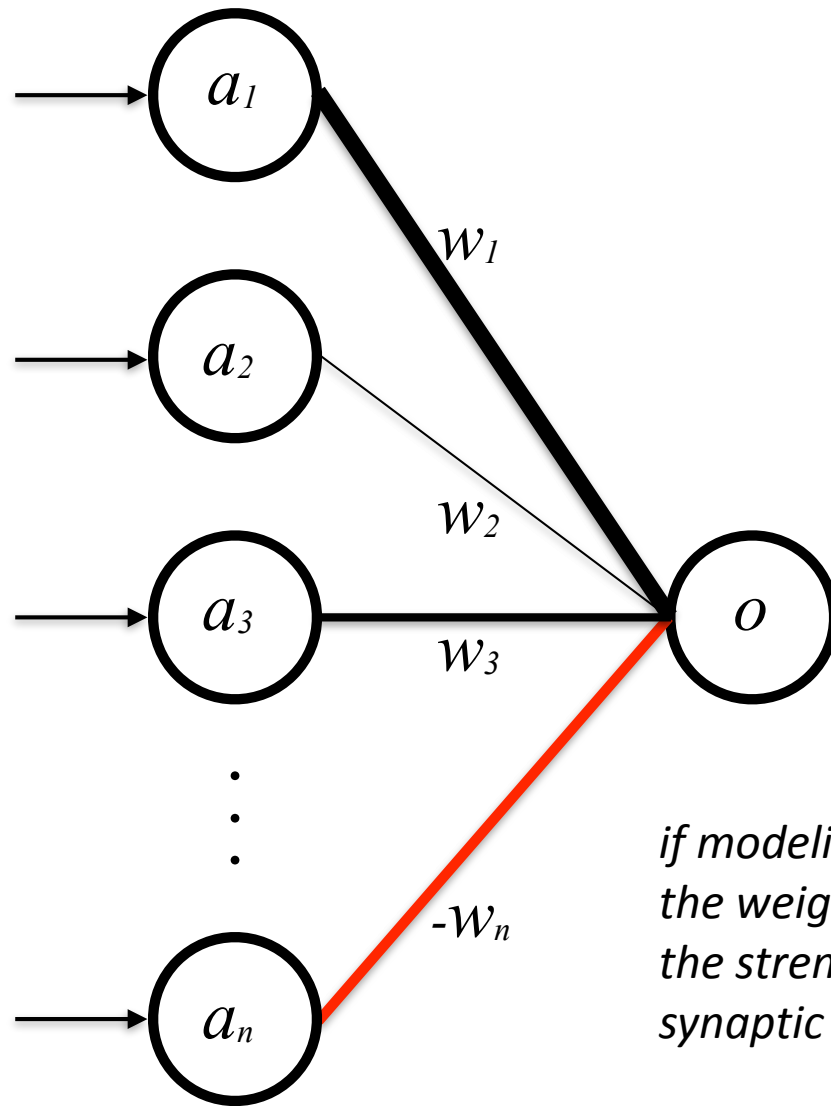


math of a simple neural network model



$$o = f \left(\sum_{i=1}^n a_i w_i \right)$$

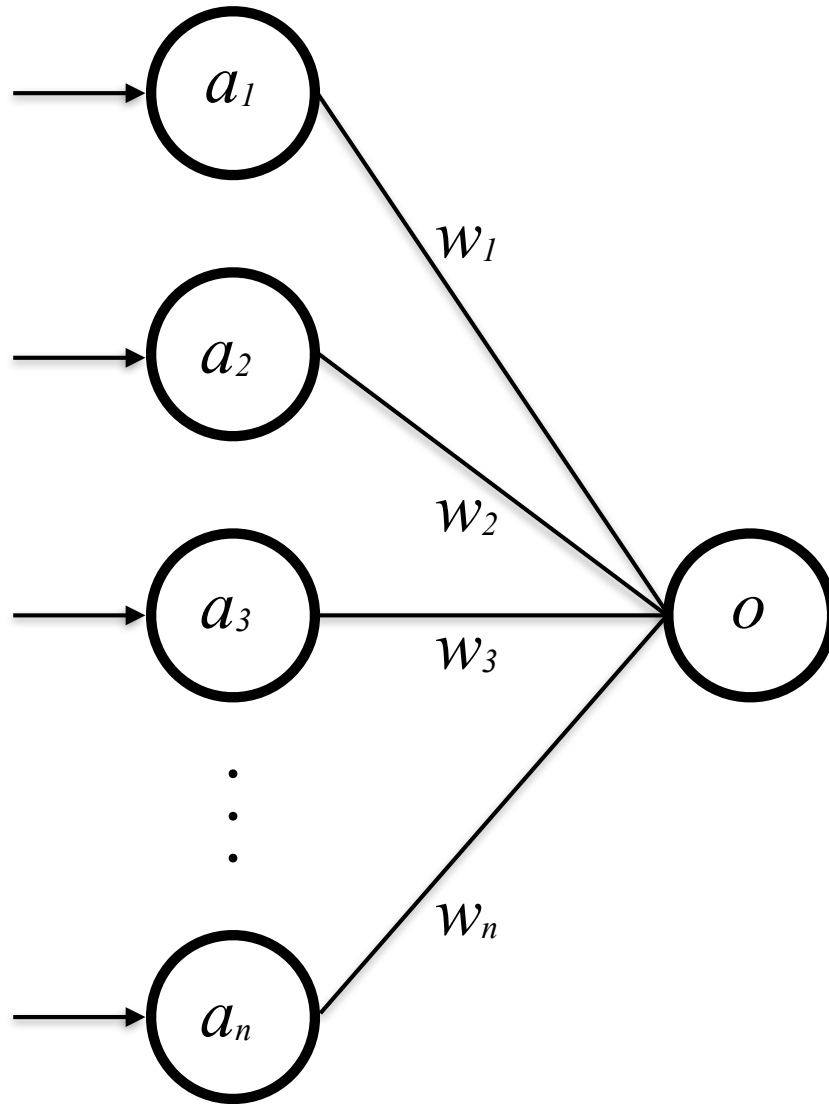
math of a simple neural network model



$$o = f \left(\sum_{i=1}^n a_i w_i \right)$$

*if modeling actual neurons,
the weights would reflect
the strength (and type) of
synaptic connections*

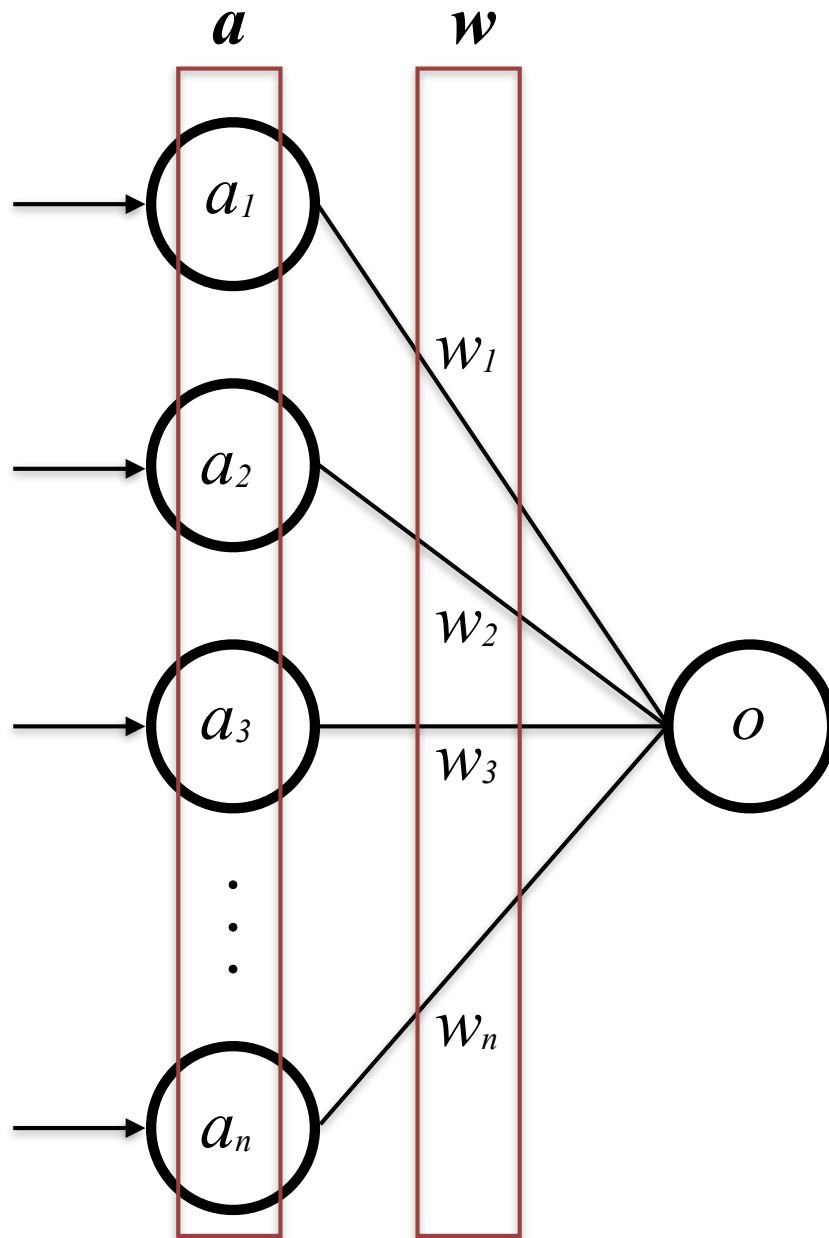
math of a simple neural network model



$$o = \sum_{i=1}^n a_i w_i$$

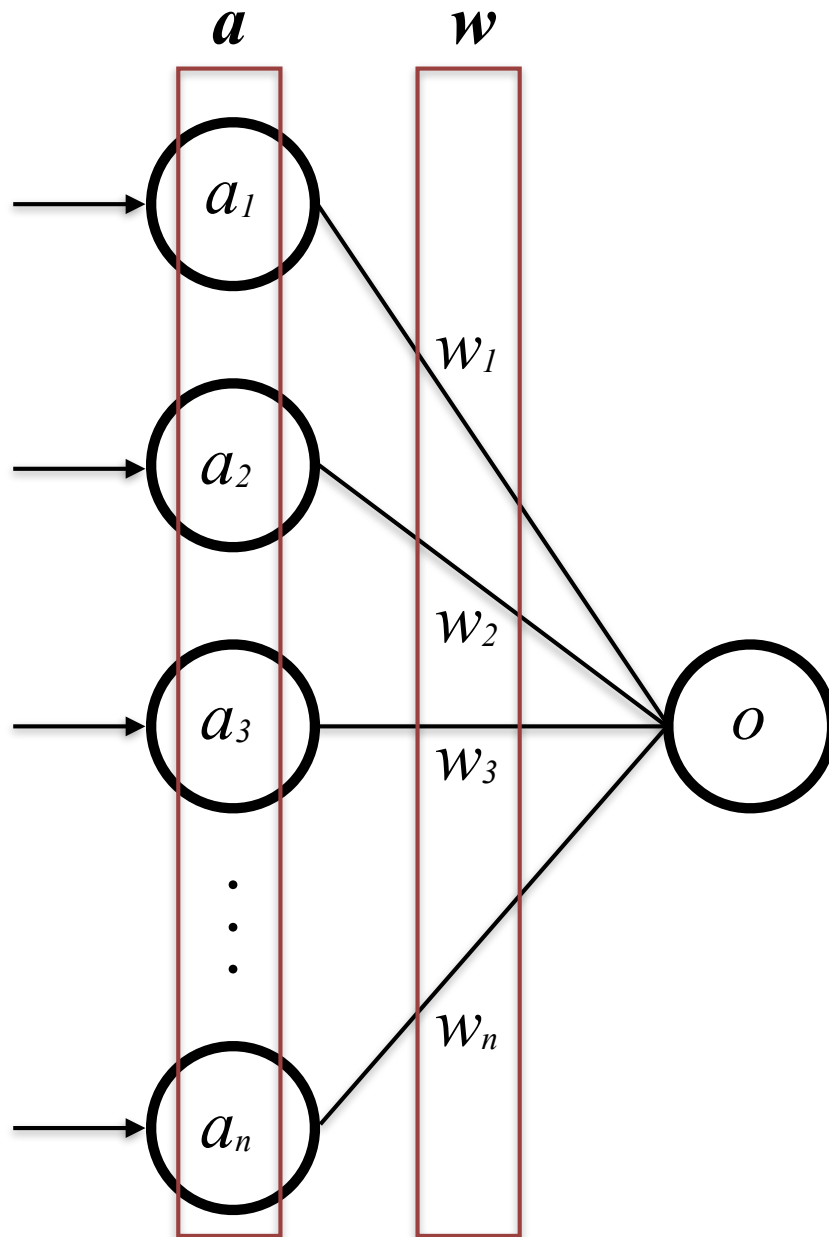
linear model (most interesting
neural networks are nonlinear)

math of a simple neural network model



$$o = \sum_{i=1}^n a_i w_i = \mathbf{a} \cdot \mathbf{w}$$

math of a simple neural network model



$$o = \sum_{i=1}^n a_i w_i = \mathbf{a} \cdot \mathbf{w}$$

if the activations and weights were normalized, o would then be the cosine angle between \mathbf{w} and \mathbf{a}

neural networks are pattern recognizers

Matrices

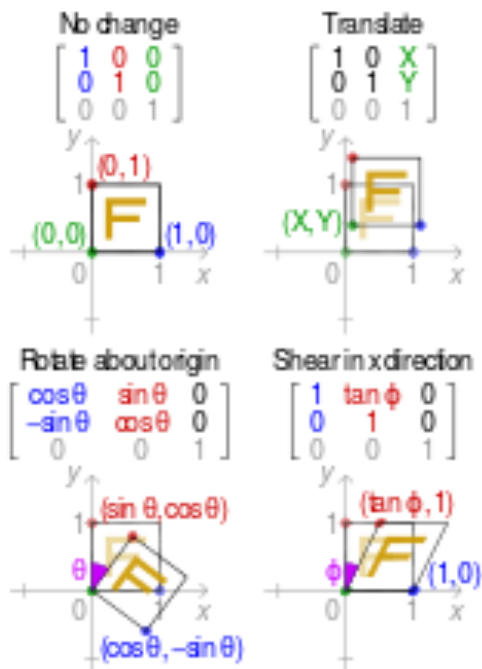
matrices



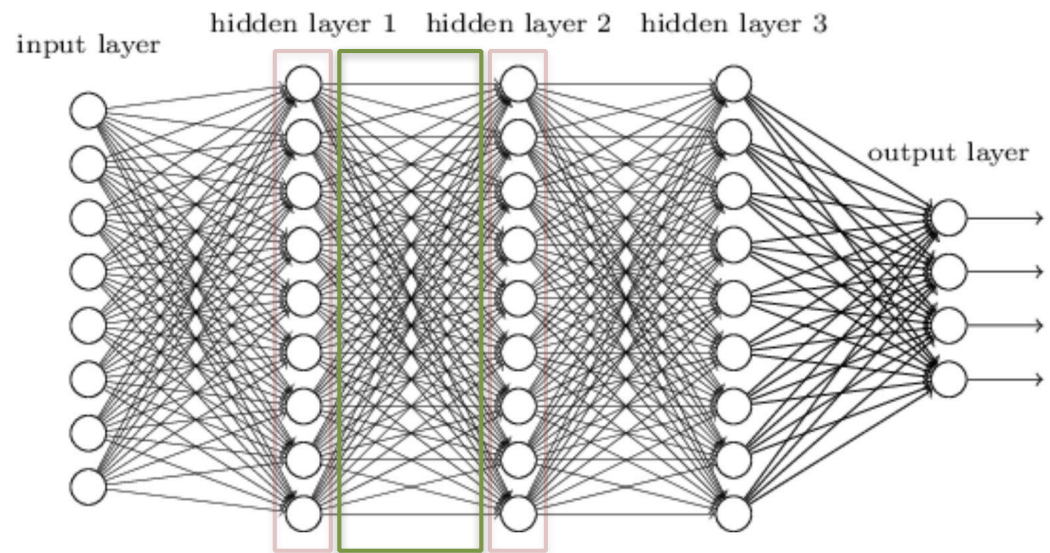
pixels of an image

$$\begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ y_4 \\ y_5 \\ y_6 \\ y_7 \end{bmatrix} = \begin{bmatrix} 1 & w_1 & x_1 \\ 1 & w_2 & x_2 \\ 1 & w_3 & x_3 \\ 1 & w_4 & x_4 \\ 1 & w_5 & x_5 \\ 1 & w_6 & x_6 \\ 1 & w_7 & x_7 \end{bmatrix} \begin{bmatrix} \beta_0 \\ \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \varepsilon_3 \\ \varepsilon_4 \\ \varepsilon_5 \\ \varepsilon_6 \\ \varepsilon_7 \end{bmatrix}$$

design of a statistical model



transformation of a vector



full set of weights between layers of a neural network model

matrix addition, subtraction, scalar multiplication

same as element-wise addition, subtraction, and
scalar multiplication with numpy arrays

mathematical operations on matrices

$$\mathbf{A} + \mathbf{B} = \mathbf{B} + \mathbf{A}$$

$$c(\mathbf{A} + \mathbf{B}) = c\mathbf{A} + c\mathbf{B}$$

Convince yourself in Python:

```
A = np.array([[2, 1], [2, 3]])
```

```
B = np.array([[1, 2], [0, 1]])
```

```
c = 2
```

```
print((A + B) - (B + A))
```

```
print(c*(A+B) - (c*A + c*B))
```

solving systems of linear equations

$$x + 2y = 2$$

$$x + y = 3$$

How would you view these equations in Python?

solving systems of linear equations

$$y = 1 - .5x$$

$$y = 3 - x$$

How would you view these equations in Python?

solving systems of linear equations

$$y = 1 - .5x$$

$$y = 3 - x$$

How would you view these equations in Python?

```
x = np.arange(-6, 6, .01)
```

```
y1 = 1 - .5*x
```

```
y2 = 3 - x
```

```
plt.plot(x, y1, x, y2)
```

What's the solution to the system of equations?

solving systems of linear equations

$$\begin{array}{rcl} x + 2y & = & 2 \\ x + y & = & 3 \end{array}$$

Rewrite in matrix notation:

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

solving systems of linear equations

$$1x + 2y = 2$$

$$1x + 1y = 3$$

Rewrite in matrix notation:

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

solving systems of linear equations

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Rewrite in matrix notation:

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$2 \times 2 \qquad \qquad 2 \times 1 \qquad \qquad 2 \times 1$

solving systems of linear equations

$$1x + 2y = 2$$

$$1x + 1y = 3$$

Rewrite in matrix notation:

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solving systems of linear equations

$$1x + 2y = 2$$

$$1x + 1y = 3$$

Rewrite in matrix notation:

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$$\begin{bmatrix} x + 2y \\ x + y \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

multiplying matrices

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{bmatrix}$$

$m \times n$ matrix $n \times p$ matrix $m \times p$ matrix

multiplying matrices

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$m \times n$ matrix

$n \times p$ matrix

$m \times p$ matrix

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

multiplying matrices

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{bmatrix}$$

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$m \times n$ matrix $n \times p$ matrix $m \times p$ matrix

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

multiplying matrices

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$m \times n$ matrix $n \times p$ matrix $m \times p$ matrix

$$c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

dot product

multiplying matrices

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{bmatrix}$$

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$m \times n$ matrix $n \times p$ matrix $m \times p$ matrix

$$c_{ij} = \underbrace{\sum_{k=1}^n a_{ik} b_{kj}}_{\mathbf{a_i} \cdot \mathbf{b_j}}$$

multiplying matrices

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multiplying matrices

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$$c_{ij} = \underbrace{\sum_{k=1}^n a_{ik} b_{kj}}_{\mathbf{a_i} \cdot \mathbf{b_j}}$$

multiplying matrices

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$$c_{ij} = \underbrace{\sum_{k=1}^n a_{ik} b_{kj}}_{\mathbf{a_i} \cdot \mathbf{b_j}}$$

multiplying matrices

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{bmatrix}$$

$m \times n$ matrix $n \times p$ matrix $m \times p$ matrix

$$c_{ij} = \underbrace{\sum_{k=1}^n a_{ik} b_{kj}}_{\mathbf{a_i} \cdot \mathbf{b_j}}$$

multiplying matrices

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{bmatrix}$$

$m \times n$ matrix $n \times p$ matrix $m \times p$ matrix

$$c_{ij} = \underbrace{\sum_{k=1}^n a_{ik} b_{kj}}_{\mathbf{a_i} \cdot \mathbf{b_j}}$$

multiplying matrices

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \times \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{bmatrix}$$

$m \times n$ matrix $n \times p$ matrix $m \times p$ matrix

$$c_{ij} = \underbrace{\sum_{k=1}^n a_{ik} b_{kj}}_{\mathbf{a_i} \cdot \mathbf{b_j}}$$

solving systems of linear equations

$$x + 2y = 2$$

$$x + y = 3$$

Rewrite in matrix notation:

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\begin{bmatrix} x + 2y \\ x + y \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

solving systems of linear equations

$$x_1 + 2x_2 = 2$$

$$x_1 + x_2 = 3$$

Rewrite :

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

A

x

=

b

matrix

vector

vector

solving systems of linear equations

$$x_1 + 2x_2 = 2$$

$$x_1 + x_2 = 3$$

Rewrite :

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

A

x

=

b

matrix

*column
vector*

*column
vector*

2x2

2x1

2x1

mathematical operations on matrices

How about this?

$$\mathbf{AB} \stackrel{?}{=} \mathbf{BA}$$

mathematical operations on matrices

How about this?

$$\mathbf{AB} \stackrel{?}{=} \mathbf{BA}$$

Homework 5

Well, you know it cannot be true in general:

$$\mathbf{A} \quad m \times n$$

Imagine \mathbf{C} is 2×3 and \mathbf{D} is 3×4 .

$$\mathbf{B} \quad n \times p$$

Then \mathbf{CD} is defined but \mathbf{DC} isn't.

\mathbf{AB} is defined

\mathbf{BA} is not (unless $m = n = p$)

mathematical operations on matrices

How about this? Try it in Python.

$$\mathbf{AB} \stackrel{?}{=} \mathbf{BA}$$

Homework 5

matrix multiplication

$$\mathbf{A@B} \text{ — } \mathbf{B@A}$$

vs.

element-wise multiplication

$$\mathbf{A*B} \text{ — } \mathbf{B*A}$$

solving systems of linear equations

$$x + 2y = 2$$

$$x + y = 3$$

Rewrite in matrix notation:

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

back to this

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\mathbf{A} \quad \mathbf{x} \quad = \quad \mathbf{b}$$

matrix

vector

vector

what do we need to do to solve for x ?

back to this

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\mathbf{A} \quad \mathbf{x} \quad = \quad \mathbf{b}$$

matrix

vector

vector



if we can move \mathbf{A} to the other side,
we will have a solution for \mathbf{x}

mathematical operations on matrices

$$Ax = b$$

*how would you solve for x if
 A , x , and b were all scalar values?*

mathematical operations on matrices

$$\mathbf{Ax} = \mathbf{b} \quad \textit{but these are vectors and matrices}$$

mathematical operations on matrices

$$\mathbf{Ax} = \mathbf{b}$$

imagine we have some matrix W such that

$$\mathbf{WAx} = \mathbf{Wb}$$

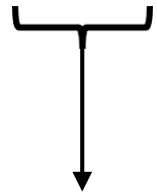
mathematical operations on matrices

$$\mathbf{Ax} = \mathbf{b}$$

imagine we have some matrix W such that

$$\mathbf{WAx} = \mathbf{Wb}$$

$$\mathbf{WAx} \neq \mathbf{bW}$$



$$\mathbf{1x} = \mathbf{Wb}$$

what is the matrix
equivalent of 1?

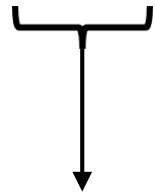
mathematical operations on matrices

$$\mathbf{Ax} = \mathbf{b}$$

imagine we have some matrix W such that

$$\mathbf{WAx} = \mathbf{Wb}$$

$$\mathbf{WAx} \neq \mathbf{bW}$$



$$\mathbf{Ix} = \mathbf{Wb}$$

identify
matrix

$$\begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{bmatrix} \times \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_N \end{bmatrix}$$

mathematical operations on matrices

W is the inverse of matrix **A**, or **A**⁻¹

$$\mathbf{W}\mathbf{A}\mathbf{x} = \mathbf{W}\mathbf{b}$$

$$\mathbf{A}^{-1}\mathbf{A}\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$$

$$\mathbf{x} = \mathbf{A}^{-1}\mathbf{b}$$

mathematical operations on matrices

\mathbf{A}^{-1} is not the same as a matrix of the
inverse of the elements ...

demonstrate they are not the same in **Homework 5**

back to this

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

$$\mathbf{A} \quad \mathbf{x} = \mathbf{b}$$

$$\mathbf{A}^{-1} \quad \mathbf{A} \quad \mathbf{x} = \mathbf{A}^{-1} \mathbf{b}$$

$$\mathbf{I} \quad \mathbf{x} = \mathbf{A}^{-1} \mathbf{b}$$

$$\mathbf{x} = \mathbf{A}^{-1} \mathbf{b}$$

back to this

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

```
A = np.array([[1, 2], [2, 1]])
```

```
b = np.array([[2], [3]])
```

```
x = np.linalg.inv(A) @ b
```


back to this

$$\begin{bmatrix} 1 & 2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

```
A = np.array([[1, 2], [2, 1]])
```

```
b = np.array([[2], [3]])
```

```
x = np.linalg.inv(A) @ b
```

this uses a better numerical method

```
x = np.linalg.solve(A, b)
```

larger systems of linear equations
(mathematically the same matrix operation)

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{bmatrix}$$

A **x** **=** **b**

solving for **x**

not all matrices are invertible

- only square matrices are invertible (but not all square matrices are invertible)
- some square matrices are singular (not invertible)

e.g., some rows or columns are linear combinations of one another (they are not linearly independent)
- matrices are singular if their determinant is zero (may be numerically close to zero on a computer)

solving systems of linear equations

$$2x - y = 2$$

$$6x - 3y = 12$$

solving systems of linear equations

$$y = -2 + 2x$$

$$y = -(12/3) + (6/3)x$$

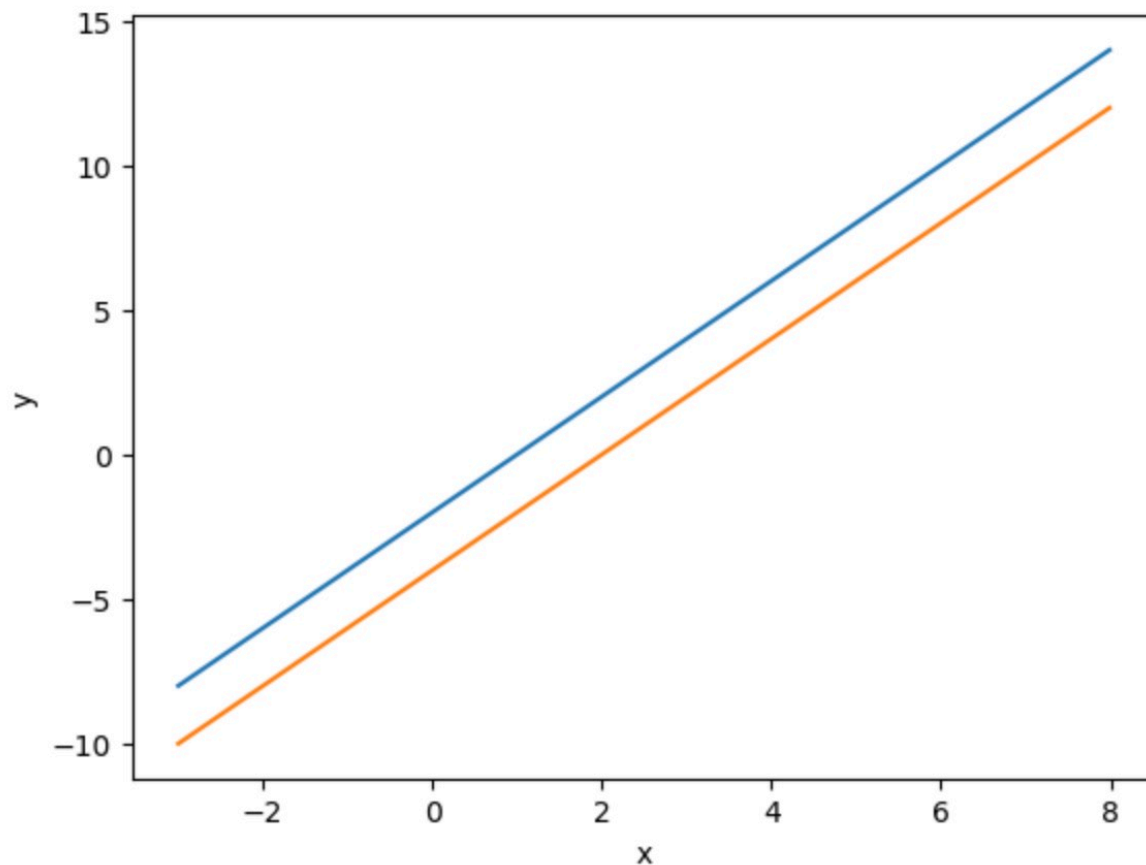
How would you view these equations in Python?

solving systems of linear equations

$$y = -2 + 2x$$

$$y = -4 + 2x$$

How would you view these equations in Python?



linear regression (multiple regression)

$$\begin{array}{ccccccc} & n \times 1 & & n \times k & & k \times 1 & n \times 1 \\ \left[\begin{array}{c} y_1 \\ y_2 \\ \vdots \\ y_n \end{array} \right] & = & \left[\begin{array}{cccc} 1 & x_{11} & \cdots & x_{1k} \\ 1 & x_{12} & \cdots & x_{2k} \\ \vdots & \vdots & & \vdots \\ 1 & x_{n2} & \cdots & x_{nk} \end{array} \right] & \left[\begin{array}{c} b_0 \\ b_1 \\ \vdots \\ b_k \end{array} \right] & + & \left[\begin{array}{c} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{array} \right] \\ \mathbf{y} & = & \mathbf{X} & & \mathbf{b} & & \end{array}$$

solving for **b**

simple linear regression

$$\begin{array}{ccccccc} & n \times 1 & & n \times 2 & & 2 \times 1 & & n \times 1 \\ \left[\begin{array}{c} y_1 \\ y_2 \\ \vdots \\ y_n \end{array} \right] & = & \left[\begin{array}{cc} 1 & x_{11} \\ 1 & x_{12} \\ 1 & \vdots \\ 1 & x_{1n} \end{array} \right] & \left[\begin{array}{c} b_\theta \\ b_1 \end{array} \right] & + & \left[\begin{array}{c} \varepsilon_1 \\ \varepsilon_2 \\ \vdots \\ \varepsilon_n \end{array} \right] \\ \mathbf{y} & = & \mathbf{X} & \mathbf{b} & & & \end{array}$$

solving for **b**

simple linear regression

$$\begin{array}{ccc} n \times 1 & & n \times 2 \qquad \qquad 2 \times 1 \\ \left[\begin{array}{c} y_1 \\ y_2 \\ \vdots \\ y_n \end{array} \right] & = & \left[\begin{array}{cc} 1 & x_{11} \\ 1 & x_{12} \\ 1 & \vdots \\ 1 & x_{1n} \end{array} \right] \left[\begin{array}{c} b_0 \\ b_1 \end{array} \right] \\ \mathbf{y} & = & \mathbf{X} \mathbf{b} \end{array}$$

can we do the same trick as before?

simple linear regression

```
X = np.array([[1, 60],  
              [1, 61],  
              [1, 62],  
              [1, 63],  
              [1, 65]])
```

```
y = np.array([[3.1],  
              [3.6],  
              [3.8],  
              [4],  
              [4.1]])
```

simple linear regression

$$\mathbf{y} = \mathbf{X} \mathbf{b}$$

Can we just do this?

$$\mathbf{X}^{-1} \mathbf{y} = \mathbf{X}^{-1} \mathbf{X} \mathbf{b}$$

Try is.

simple linear regression

$$\mathbf{y} = \mathbf{X} \mathbf{b}$$

Can we just do this?

$$\mathbf{X}^{-1} \mathbf{y} = \mathbf{X}^{-1} \mathbf{X} \mathbf{b}$$

Try is.

No. Matrix must be square.

simple linear regression

$$\mathbf{y} = \mathbf{X} \mathbf{b}$$

We can do this:

$$\mathbf{X}^T \mathbf{y} = \mathbf{X}^T \mathbf{X} \mathbf{b}$$

What will $\mathbf{X}^T \mathbf{X}$ give you? What size is it?

simple linear regression

$$\mathbf{y} = \mathbf{X} \mathbf{b}$$

We can do this:

$$\mathbf{X}^T \mathbf{y} = \mathbf{X}^T \mathbf{X} \mathbf{b}$$

What could we do now?

simple linear regression

$$\mathbf{y} = \mathbf{X} \mathbf{b}$$

We can do this:

$$\mathbf{X}^T \mathbf{y} = \mathbf{X}^T \mathbf{X} \mathbf{b}$$

What could we do now?

$$(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X} \mathbf{b}$$

What will this give you?

simple linear regression

$$\mathbf{y} = \mathbf{X} \mathbf{b}$$

We can do this:

$$\mathbf{X}^T \mathbf{y} = \mathbf{X}^T \mathbf{X} \mathbf{b}$$

What could we do now?

$$(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{X} \mathbf{b}$$

What will this give you?

$$(\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y} = \mathbf{b}$$

$$\mathbf{b} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

in practice, inverting large matrices
is computationally very expensive,
and often numerically unstable,
so different algorithms are used

simple linear regression

```
X = np.array([[1, 60], [1, 61], [1, 62], [1, 63], [1, 65]])  
y = np.array([[3.1], [3.6], [3.8], [4], [4.1]])
```

```
Xt = np.transpose(X)
```

```
b = np.linalg.inv(Xt @ X) @ Xt @ y
```

$$\mathbf{b} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

in practice, inverting large matrices
is computationally very expensive,
and often numerically unstable,
so different algorithms are used

```
yhat = b[0] + b[1] * X[:,1]
```

```
plt.plot(X[:,1], y[:,0], 'ro', X[:,1], yhat, 'g-')
```

"real" linear regression (in statistics)

```
from sklearn.linear_model import LinearRegression
```

```
model = LinearRegression()
```

uses algorithm that does not require inverting large matrices

```
Xdat = (X[:,1]).reshape((len(X[:,1]),1))
```

```
model.fit(Xdat, y)
```

```
print(model.intercept_, model.coef_)
```