

Homework 8

due Wed Nov 9 at start of class

Homework8.pdf

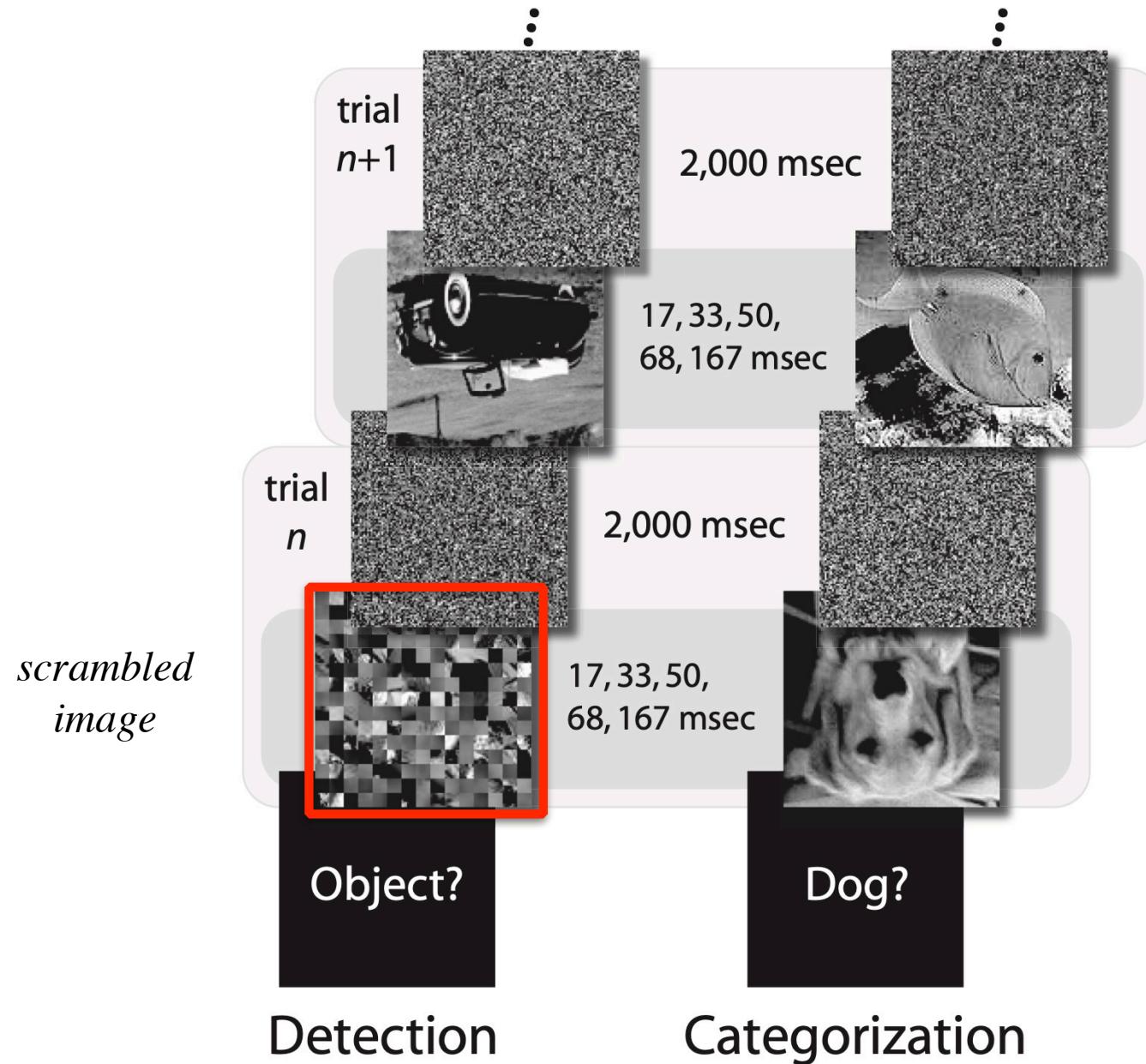
nashville.jpg

Homework 8

- **Q1a** create a b/w version from a color version (using vectorized operations in numpy, not `for` loops)



Homework 8



Homework 8

- **Q1b** scramble an (b/w) image



8x8 scramble grid



Homework 8

- **Q1b** scramble an (b/w) image



8x8 scramble grid



Homework 8

- **Q1b** scramble an (b/w) image



2x2 scramble grid



Homework 8

- **Q1b** scramble an (b/w) image



16x16 scramble grid



Homework 8

- lots of ways of doing this - I will give you a hint to one approach to try (you can do it another way)

Homework 8

what are we trying to do?

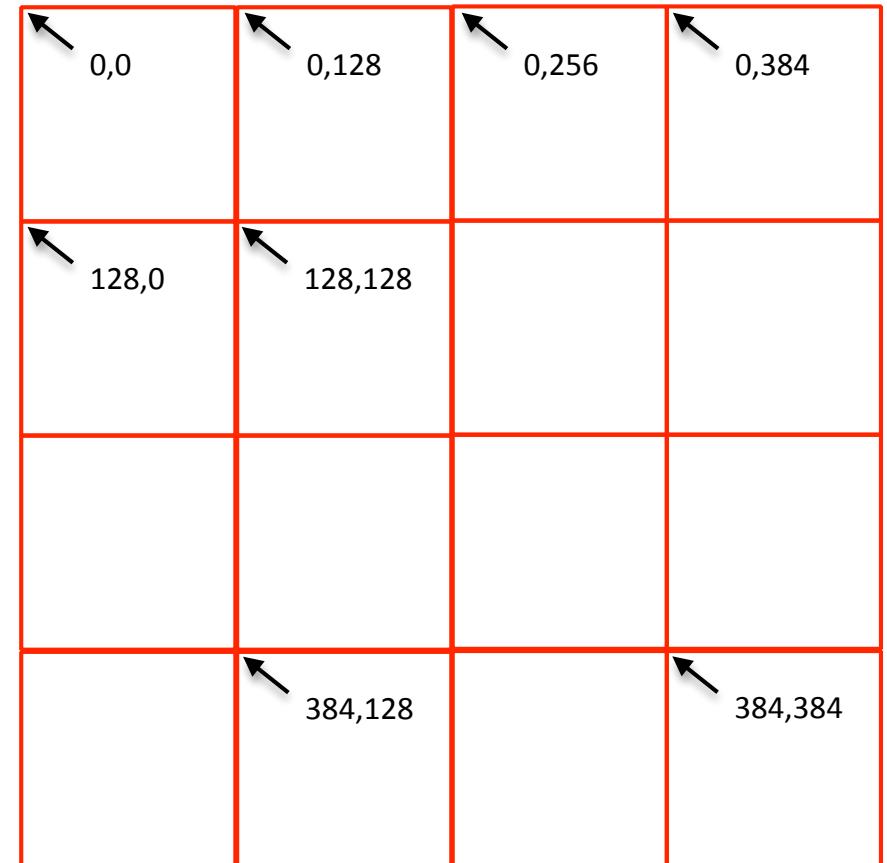
512x512 image



use a 4x4 grid as an example

Homework 8

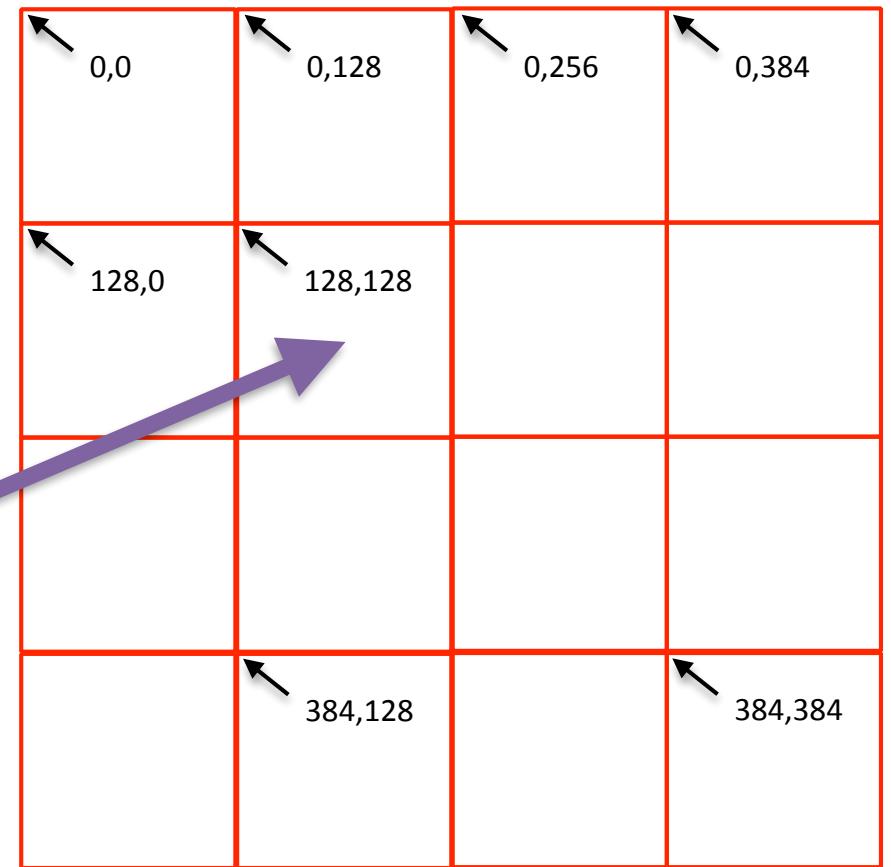
512x512 image



use a 4x4 grid as an example

Homework 8

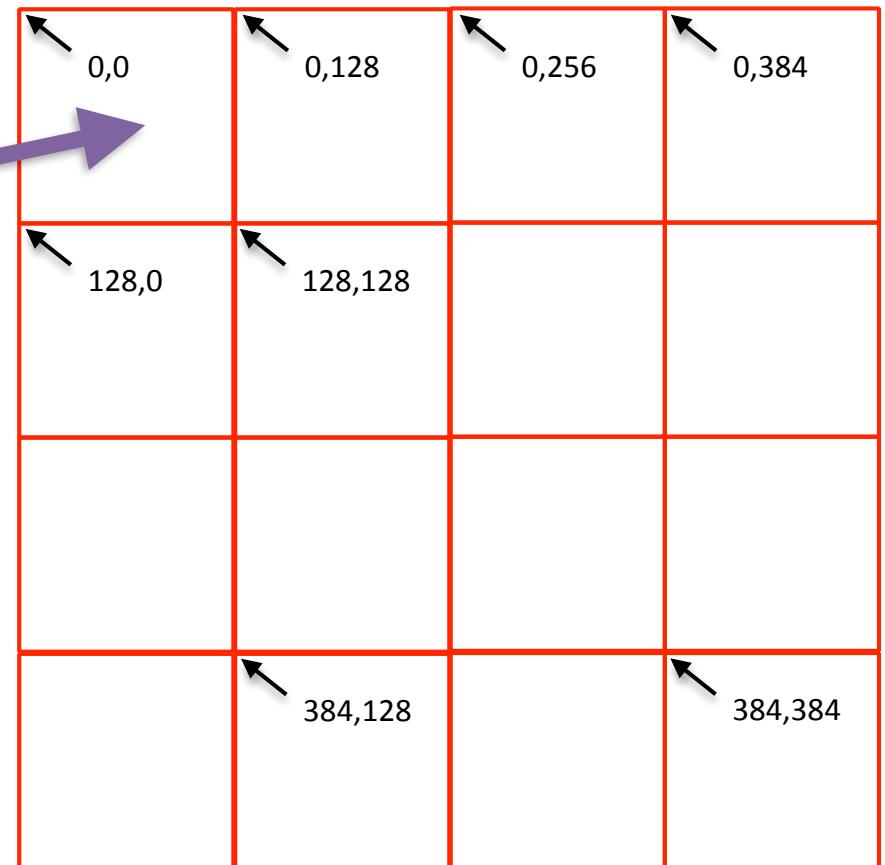
512x512 image



use a 4x4 grid as an example

Homework 8

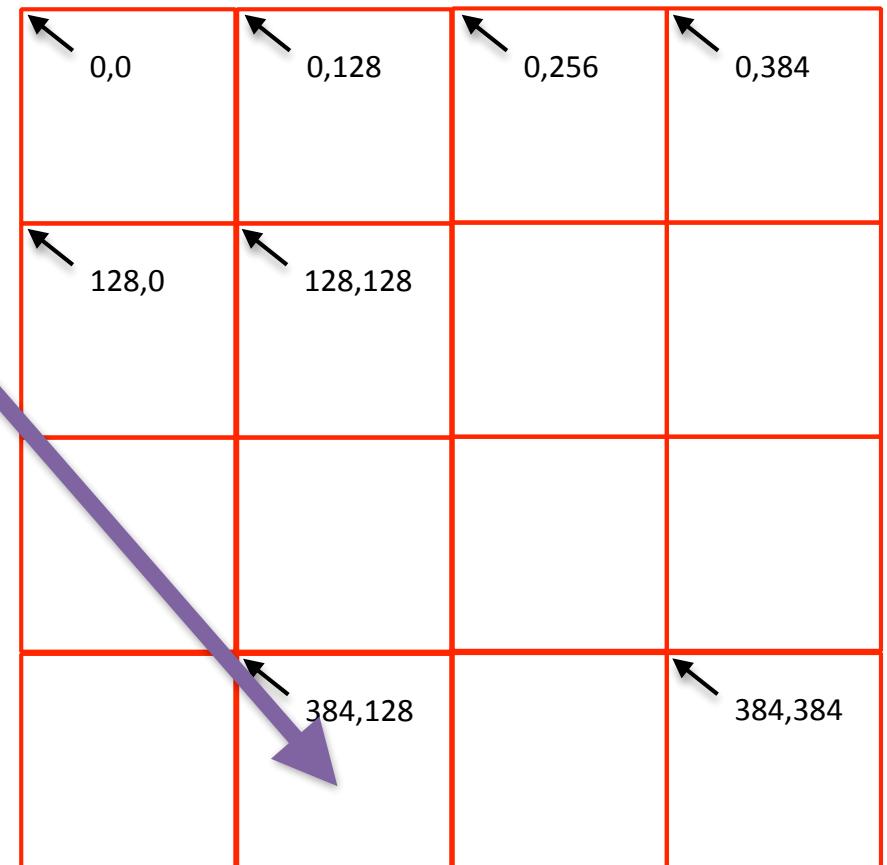
512x512 image



use a 4x4 grid as an example

Homework 8

512x512 image



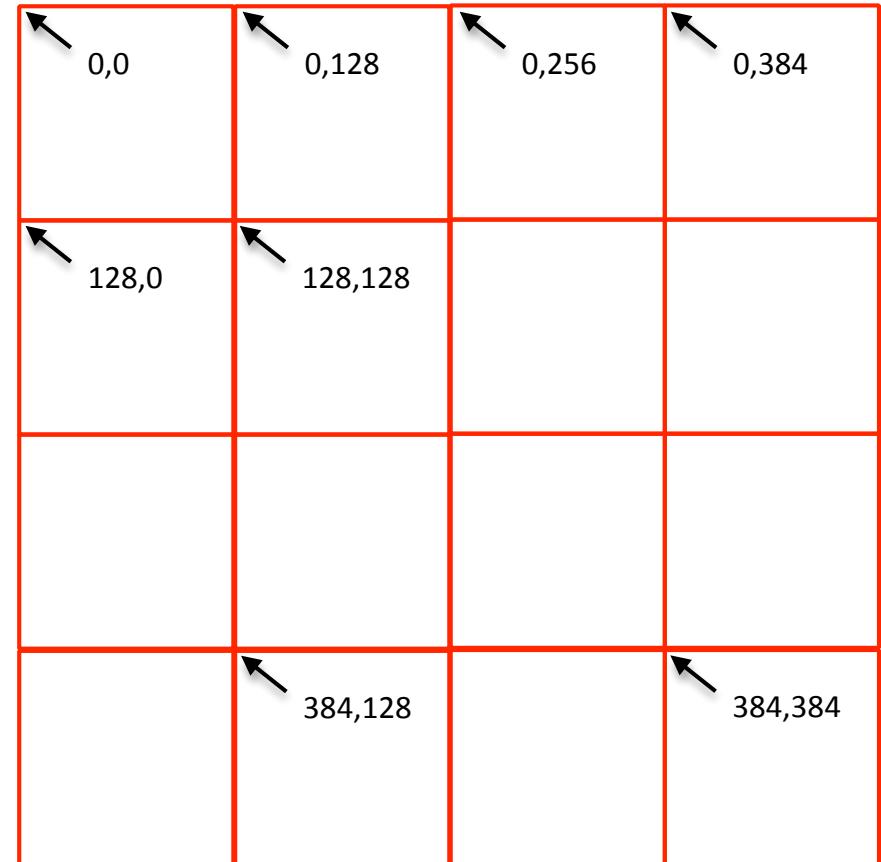
use a 4x4 grid as an example

Homework 8

*scramble (permute) the
coordinates of the 16 squares*

*fill in a blank (scrambled)
numpy array*

512x512 image



use a 4x4 grid as an example

Homework 8

*scramble (permute) the
coordinates of the 16 square*

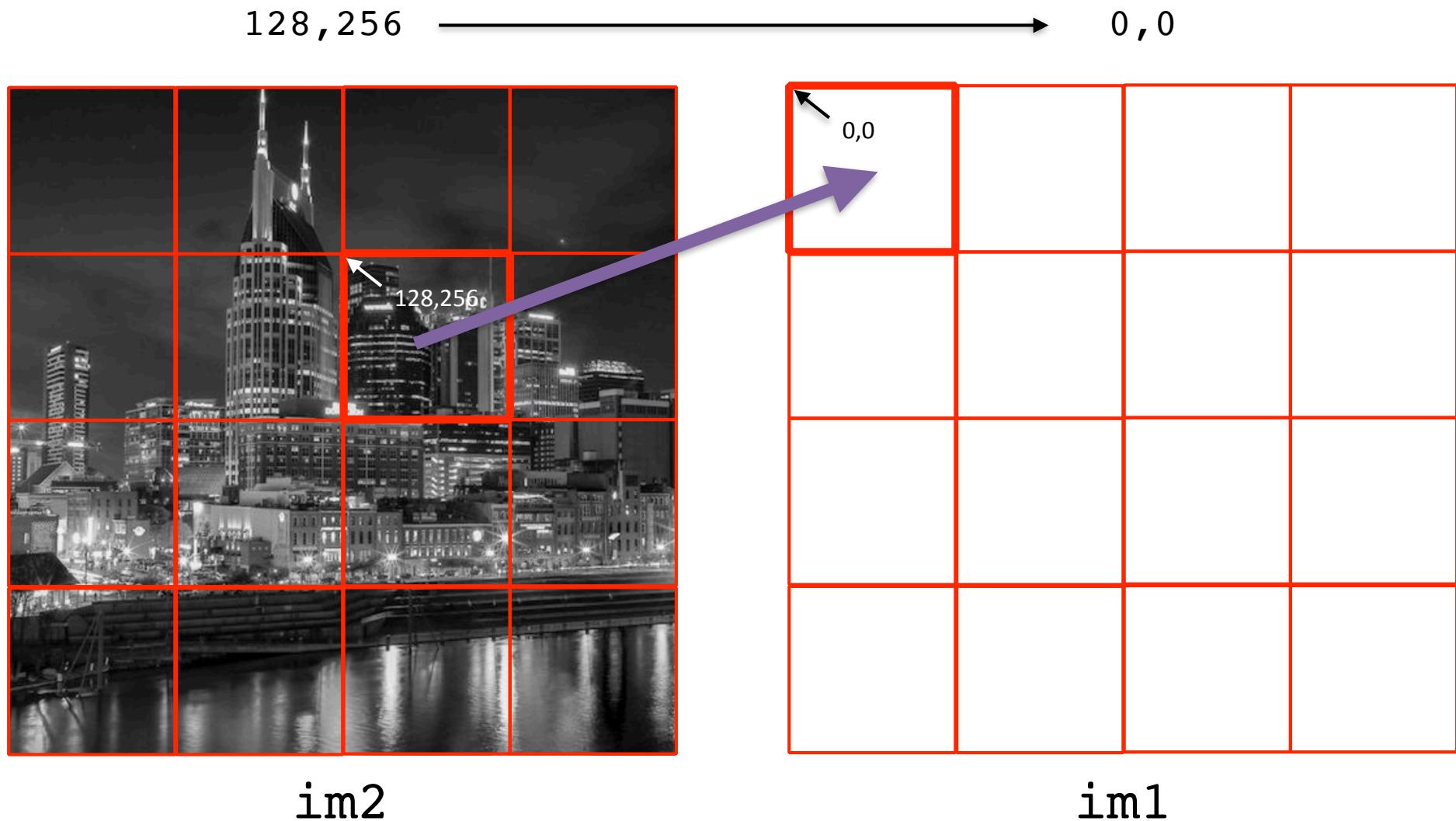
*fill in a blank (scrambled)
numpy array*

128,256	→	0,0
256,384	→	0,128
384,0	→	0,256
384,385	→	0,384
0,0	→	128,0
384,256	→	128,128
0,256	→	128,256
128,128	→	128,384
384,128	→	256,0
0,128	→	256,128
256,256	→	256,256
0,384	→	256,384
128,0	→	384,0
256,0	→	384,128
256,128	→	384,256
128,384	→	384,385
	→	

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`im1[0:128, 0:128] = im2[128:256, 256:384]`

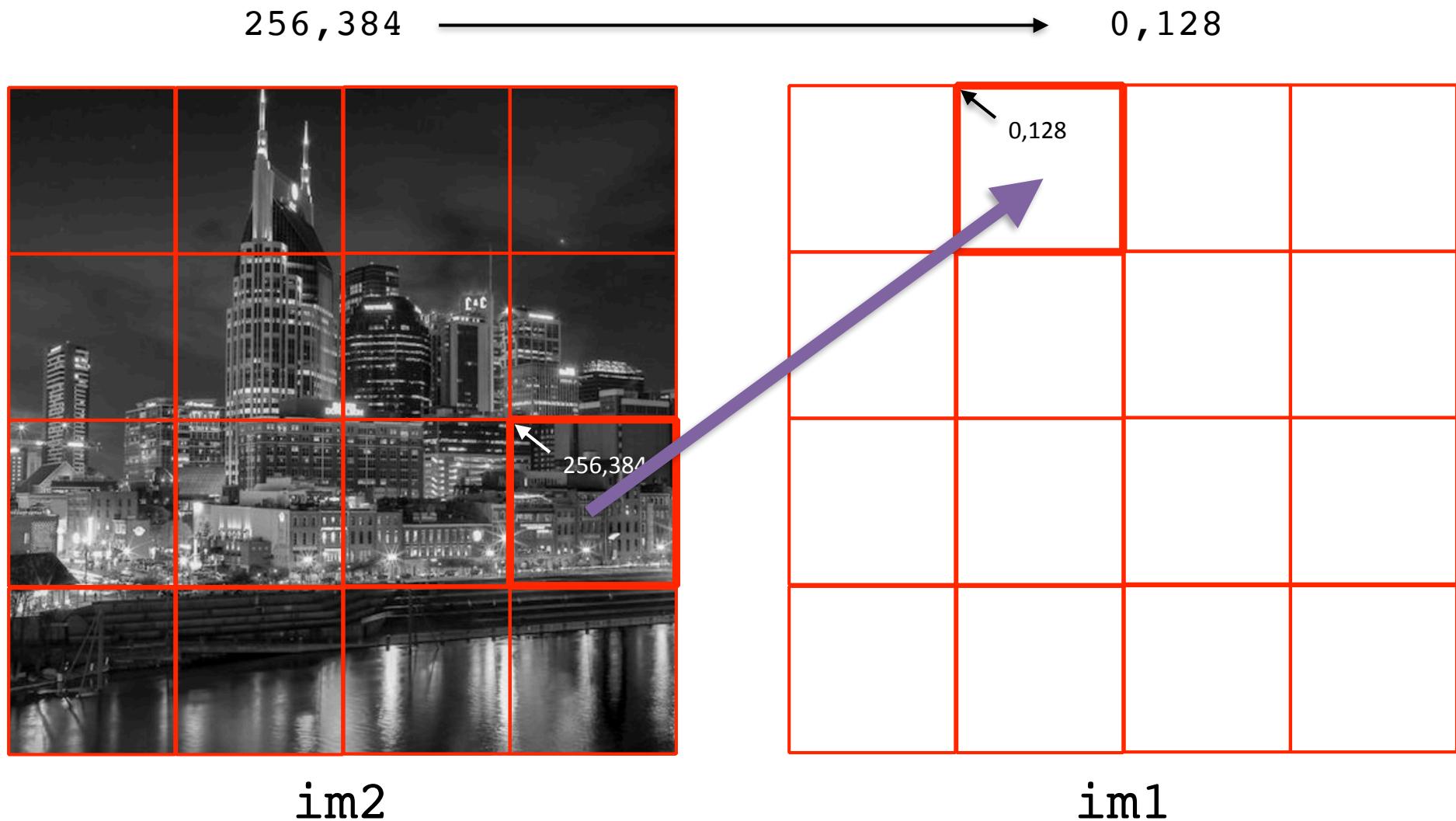
obviously, you can't hard code this



Homework 8

`im1[0:128, 128:256] = im2[256:384, 384:512]`

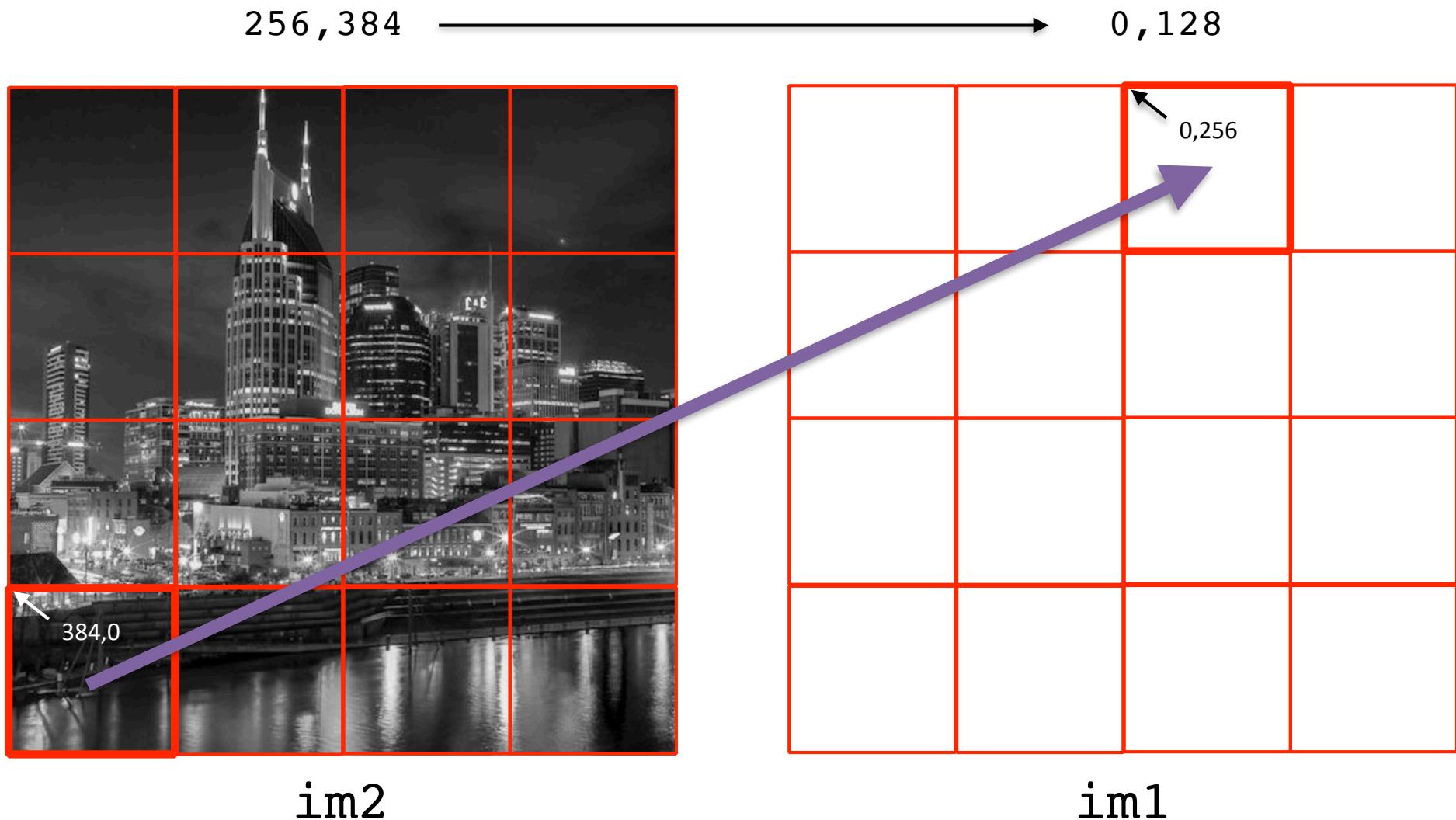
obviously, you can't hard code this



Homework 8

`im1[0:128, 256:384] = im2[384:512, 0:128]`

obviously, you can't hard code this



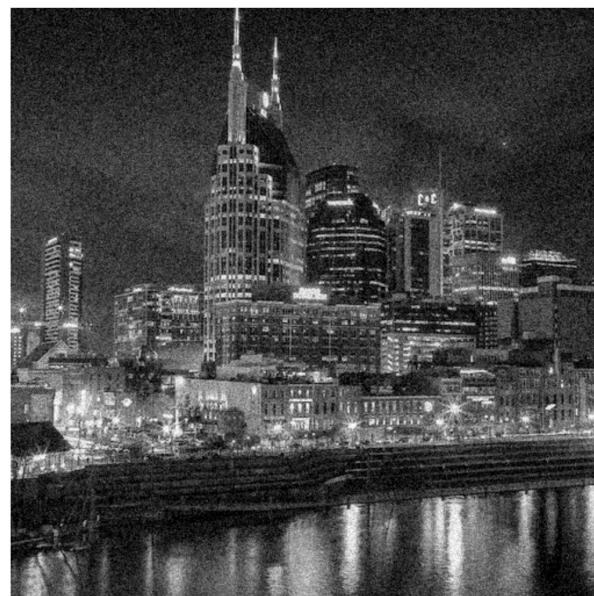
Homework 8

- **Q1c** add "salt and pepper" (normally-distributed) noise to the intensity of each image pixel

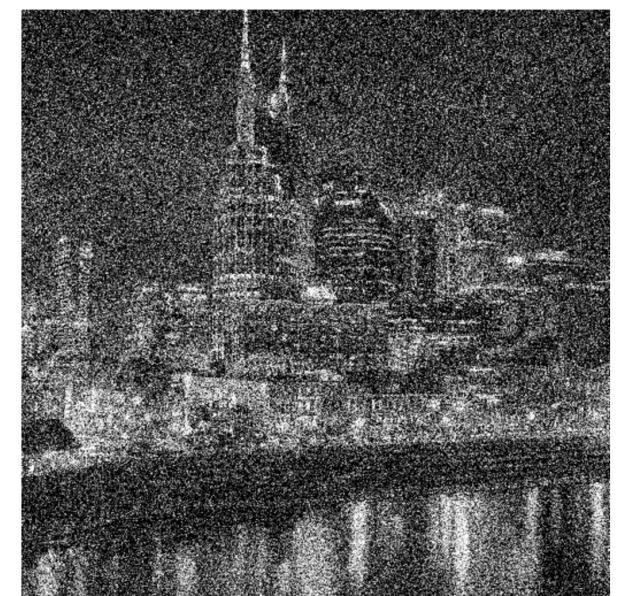
original



low noise



high noise



do this two ways: (1) where you cap out at 0 and 255,
(2) where you allow the numbers to "roll over"

("vectorized" for full credit)

download from Brightspace

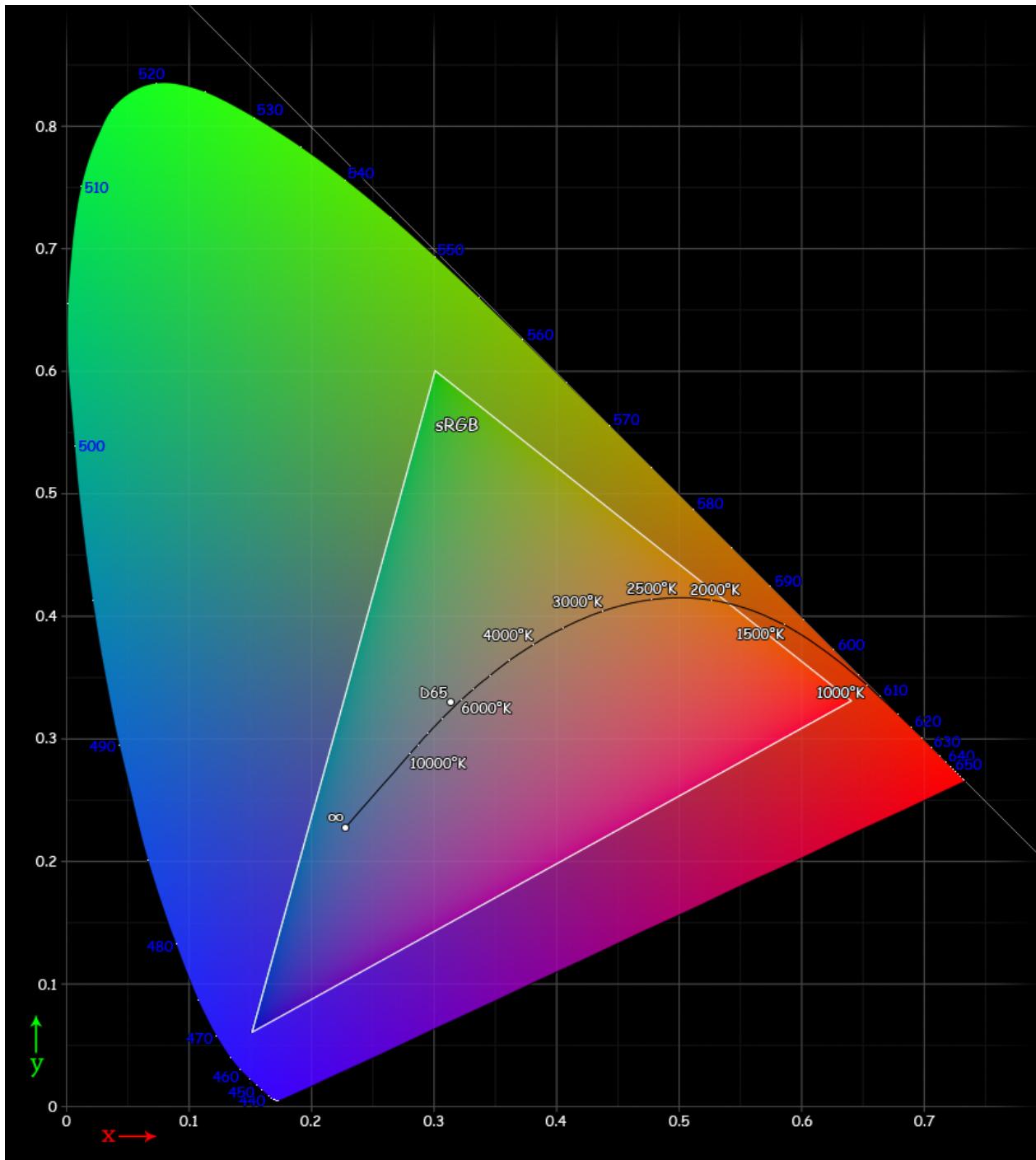
Signals.zip

More on Images and Signals

bit depth (monitors)

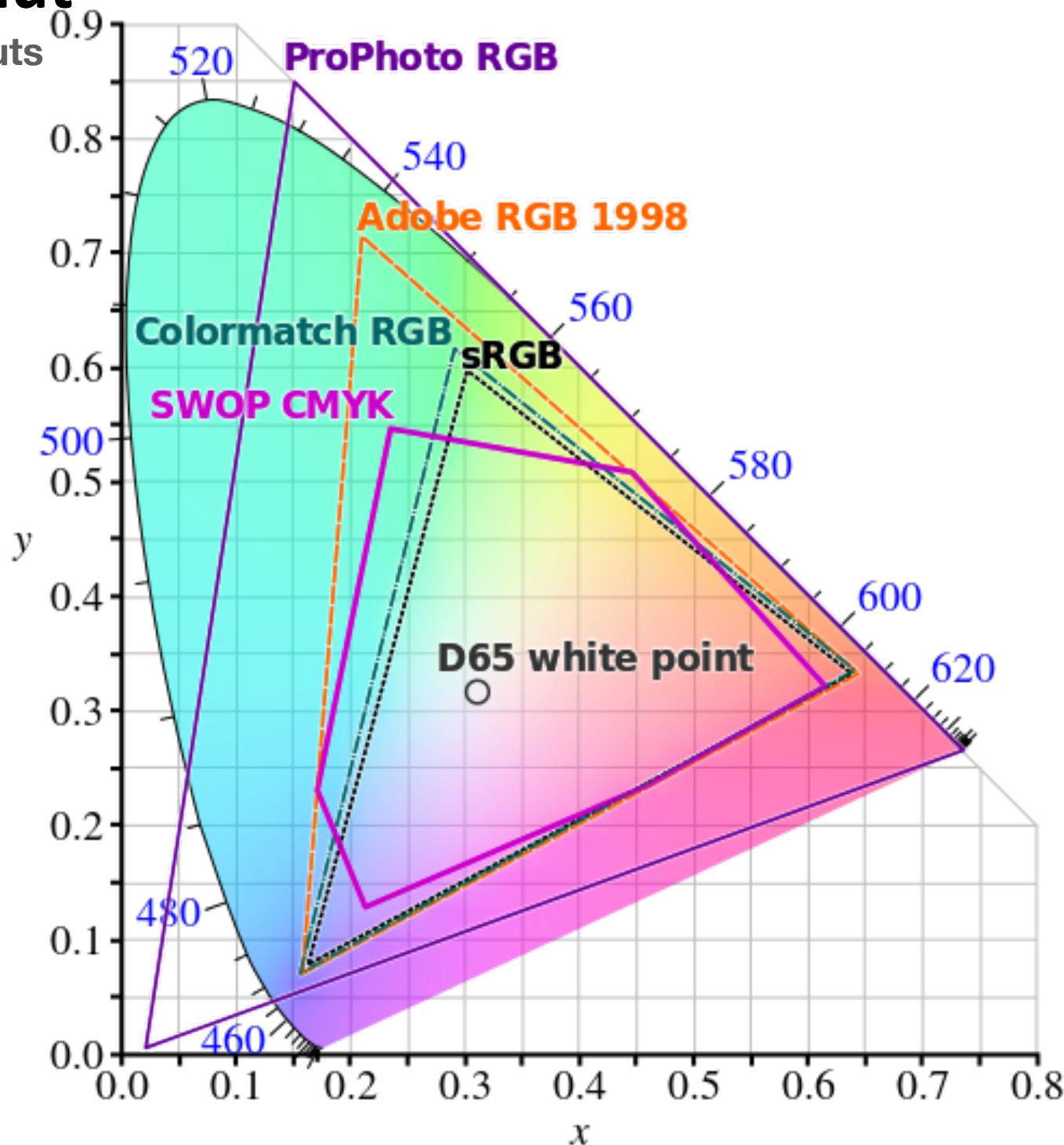
1st computers	1 bit (white/black, green/black)
early NeXT	2 bits
Atari, Commodore 64	4 bits
early VGA	8 bits (total for color) used color maps
most current monitor	24 bits (R, G, B)
HDR monitors	30/36/48 bits (R, G, B)
more than 3 primaries	R, G, B, C, Y, M

color gamut



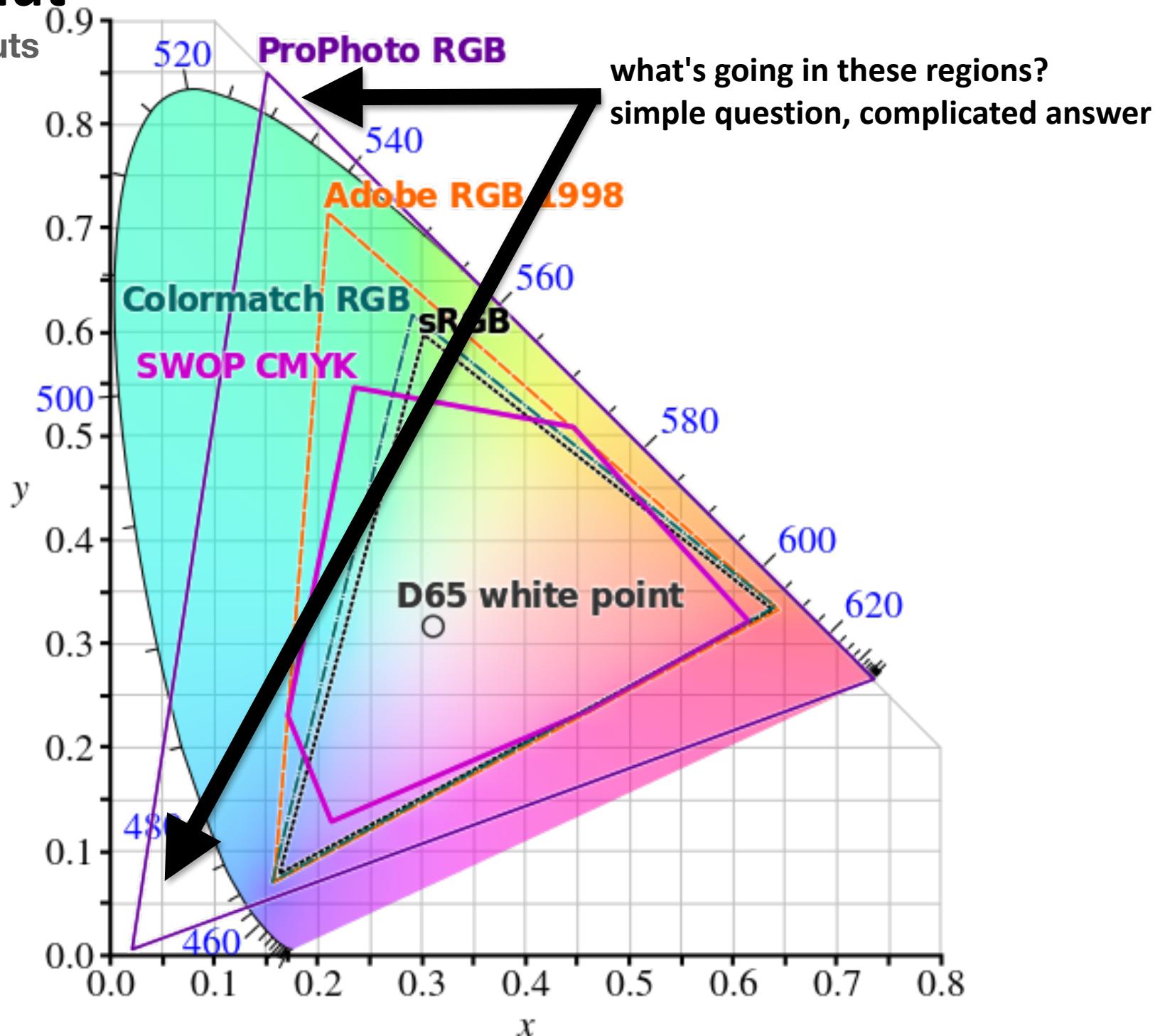
color gamut

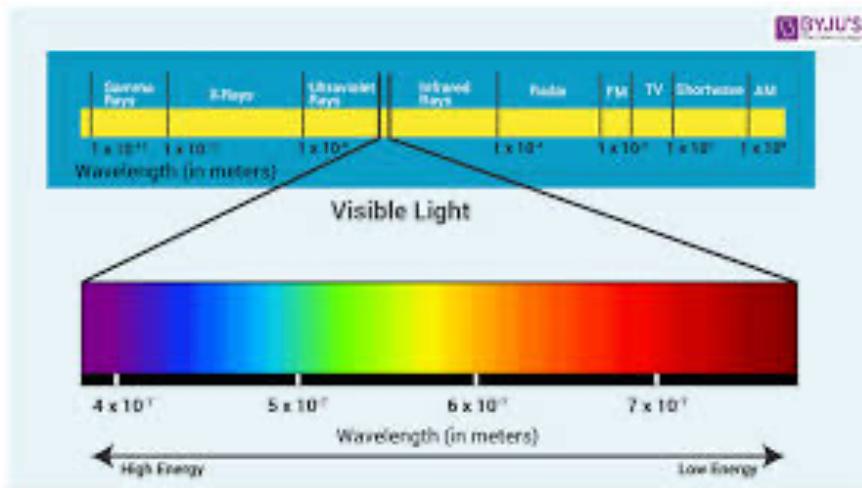
printing gamuts



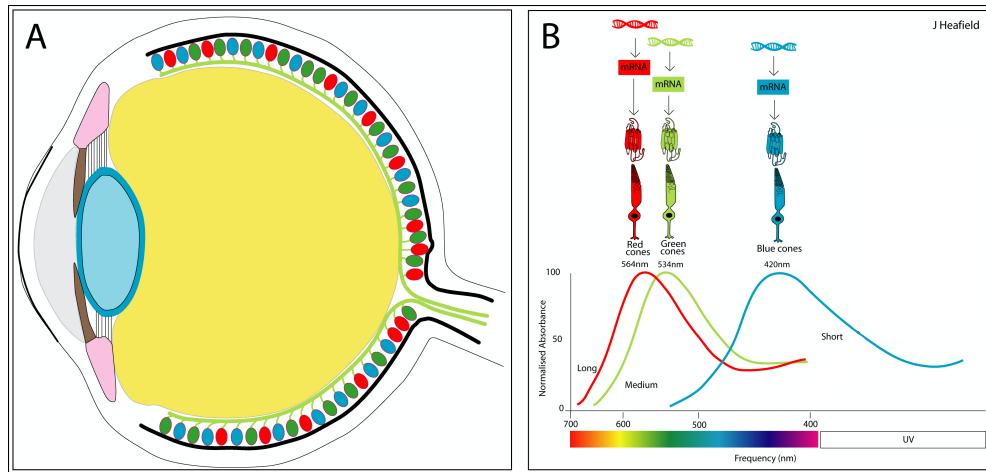
color gamut

printing gamuts

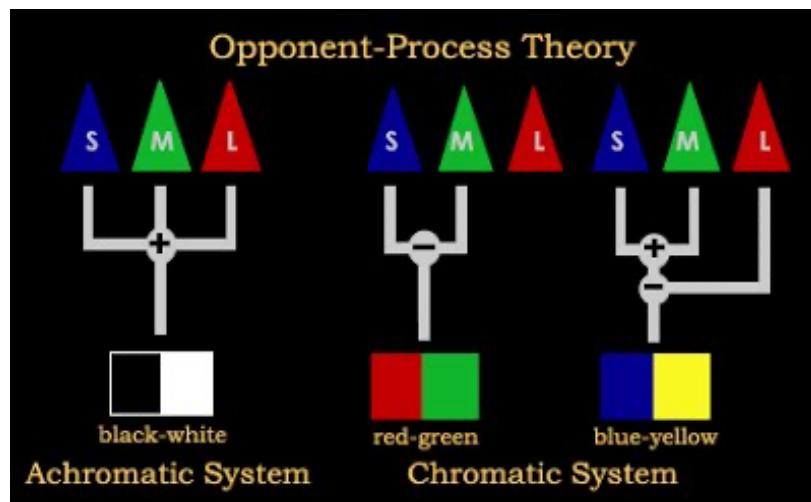




not all colors we can perceive correspond to a single wavelength of light (e.g., grays, pinks, browns, magentas)



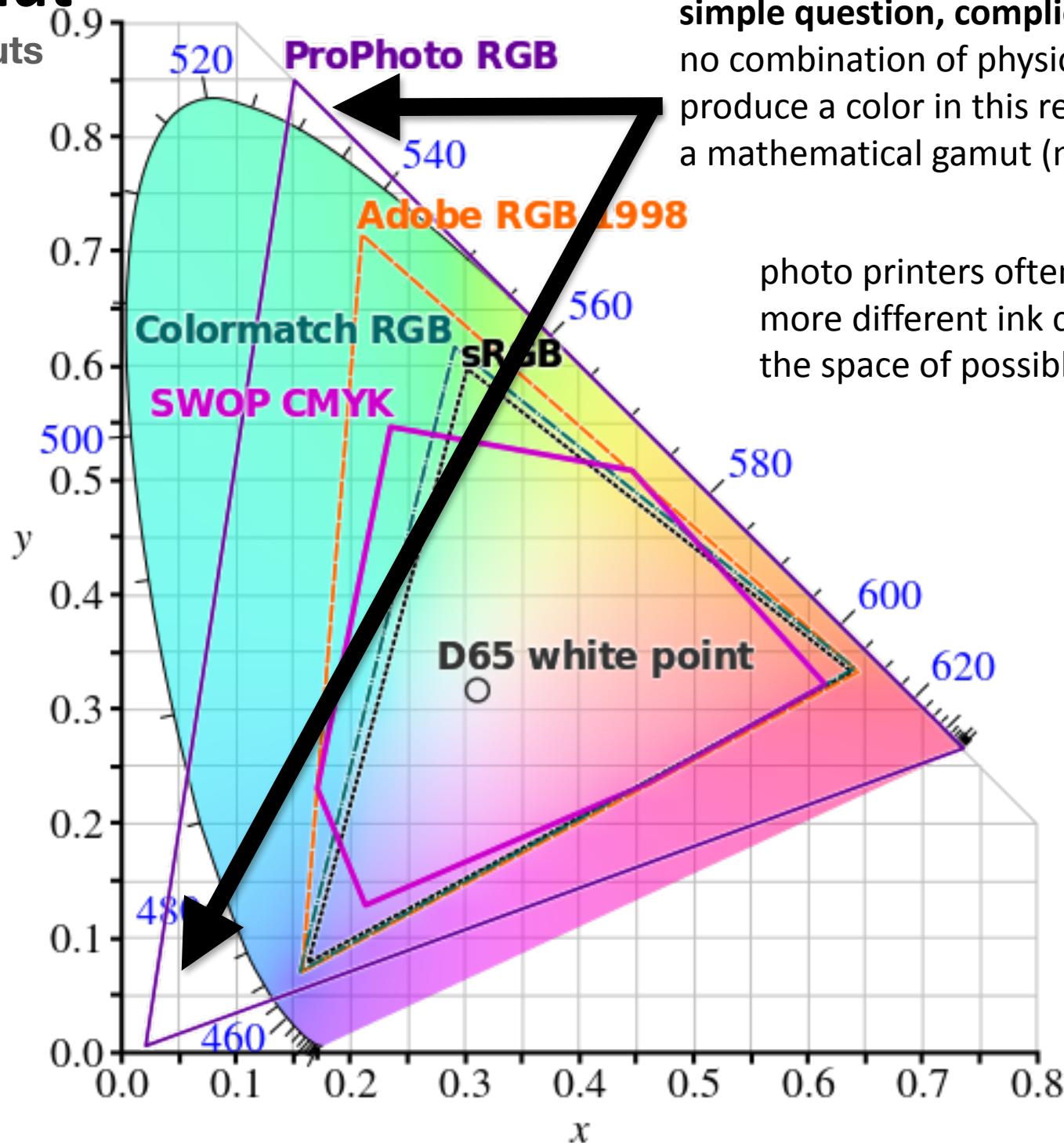
rods (low light) and cones (red, green, blue) photoreceptors in the retina



opponent-processes in higher-level color representation (black-white, red-green, blue-yellow)

color gamut

printing gamuts



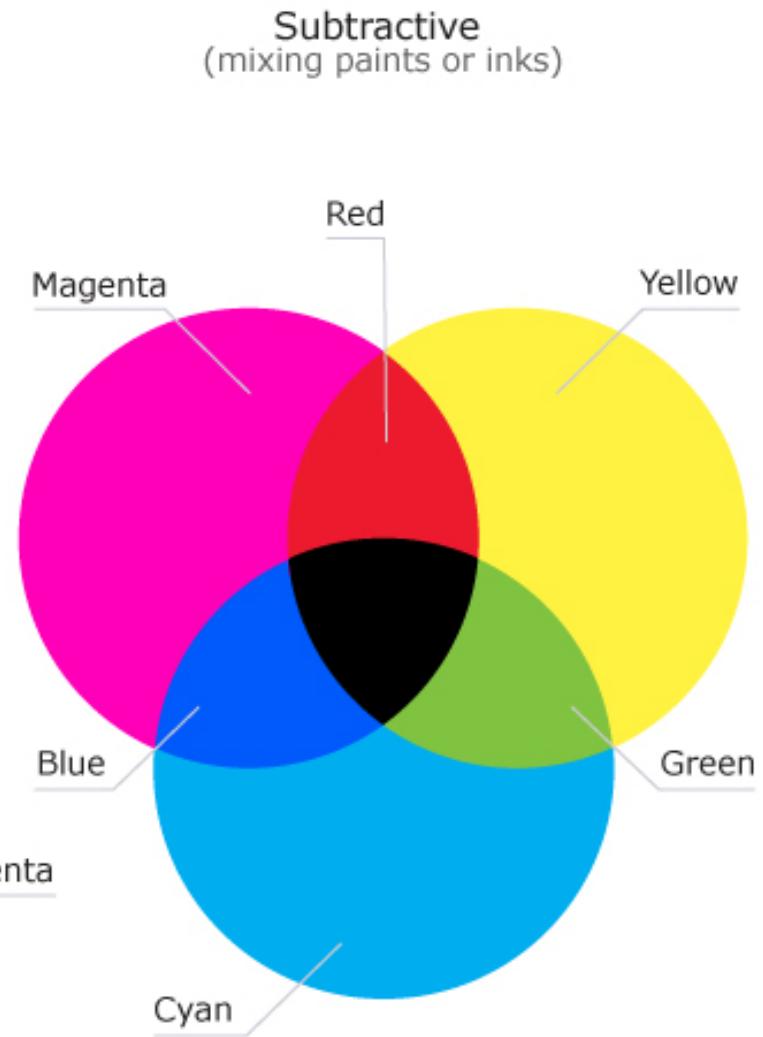
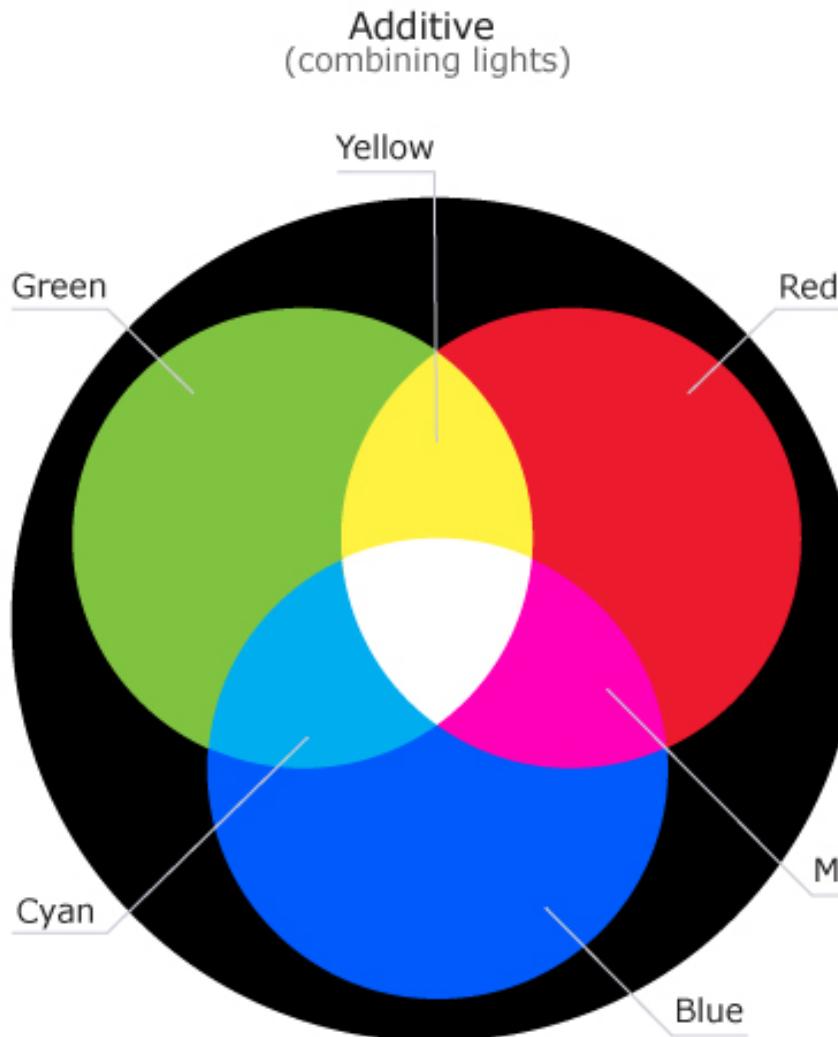
simple question, complicated answer
no combination of physical light can produce a color in this region - this is a mathematical gamut (not a real one)

photo printers often use 9 or more different ink colors to cover the space of possible colors

light mixing vs. paint mixing

light mixing is additive (base on projection)

paint mixing is subtractive (based on reflectance)



how resolution and bit depth affect size

how resolution and bit depth affect size

assuming no compression

lower resolution and bit depth audio recording

10sec audio x 44.1kHz x 2 bytes/sample

10sec audio x 44.1ksamples/sec x 2 bytes/sample

882,000 bytes

how resolution and bit depth affect size

assuming no compression

lower resolution and bit depth audio recording

10sec audio x 44.1kHz x 2 bytes/sample

10sec audio x 44.1ksamples/sec x 2 bytes/sample

882,000 bytes

high resolution and bit depth audio recording

10sec audio x 192kHz x 3 bytes/sample

10sec audio x 192ksamples/sec x 3 bytes/sample

5,760,000 bytes

how resolution and bit depth affect size

assuming no compression

lower resolution and bit depth image

320x240 image x 8 bit color

76,800 bytes

high resolution and bit depth audio recording

7360x4912 image x 42 bit color (raw)

189,799,680 bytes

how resolution and bit depth affect size

size not only affects storage needs (computer memory and disk drive space) but time to copy/transfer files

how resolution and bit depth affect size

1000 lower resolution and bit depth images

76,800,000 bytes

256Kb/sec = 5min

10Mb/sec = <8sec

Comcast/Xfinity upload speeds capped at 20Mb/sec

10Gb/sec = <.008sec

1000 high resolution and bit depth images

189,799,680,000 bytes

256Kb/sec = >8 days

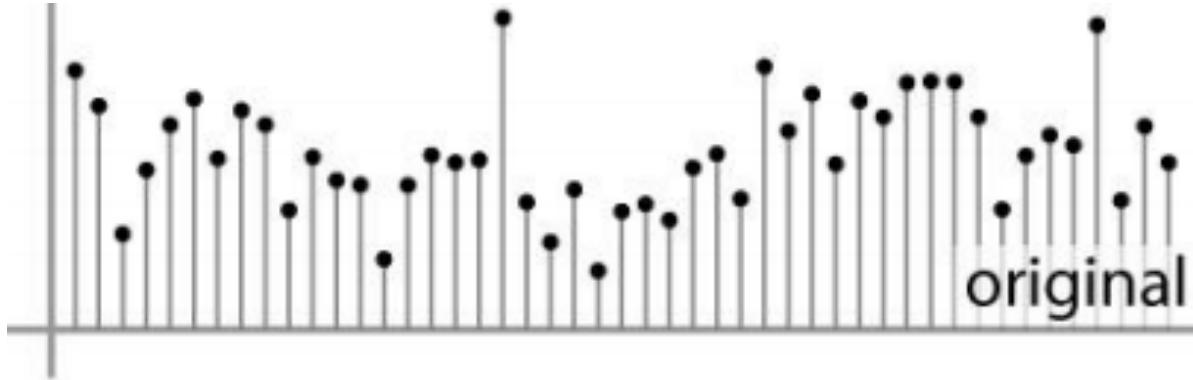
10Mb/sec = <6hours

10Gb/sec = <19sec

size not only affects storage needs (computer memory and disk drive space) but time to copy/transfer files

Filtering

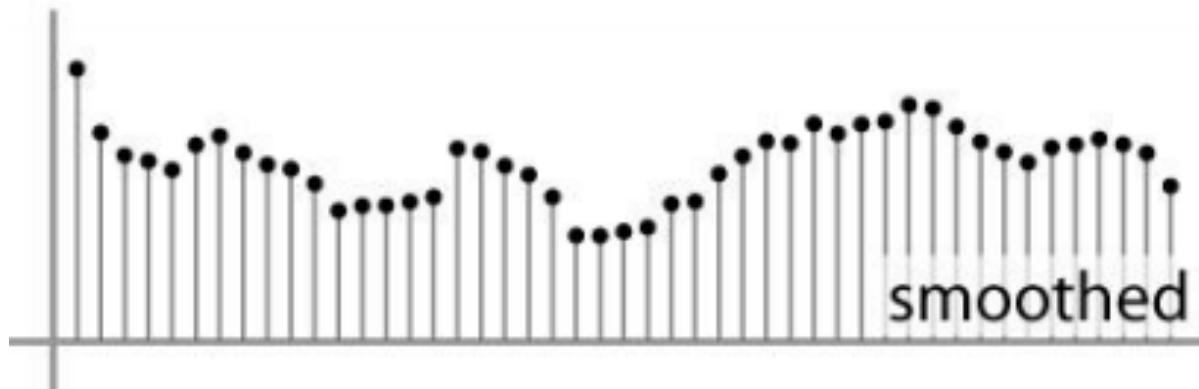
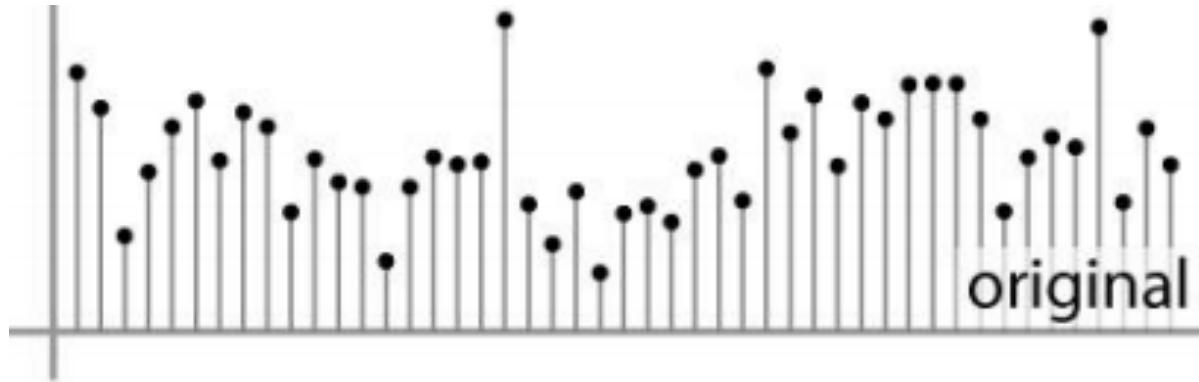
1D signal



x axis could be time or space
y axis is intensity at each time point or spatial position

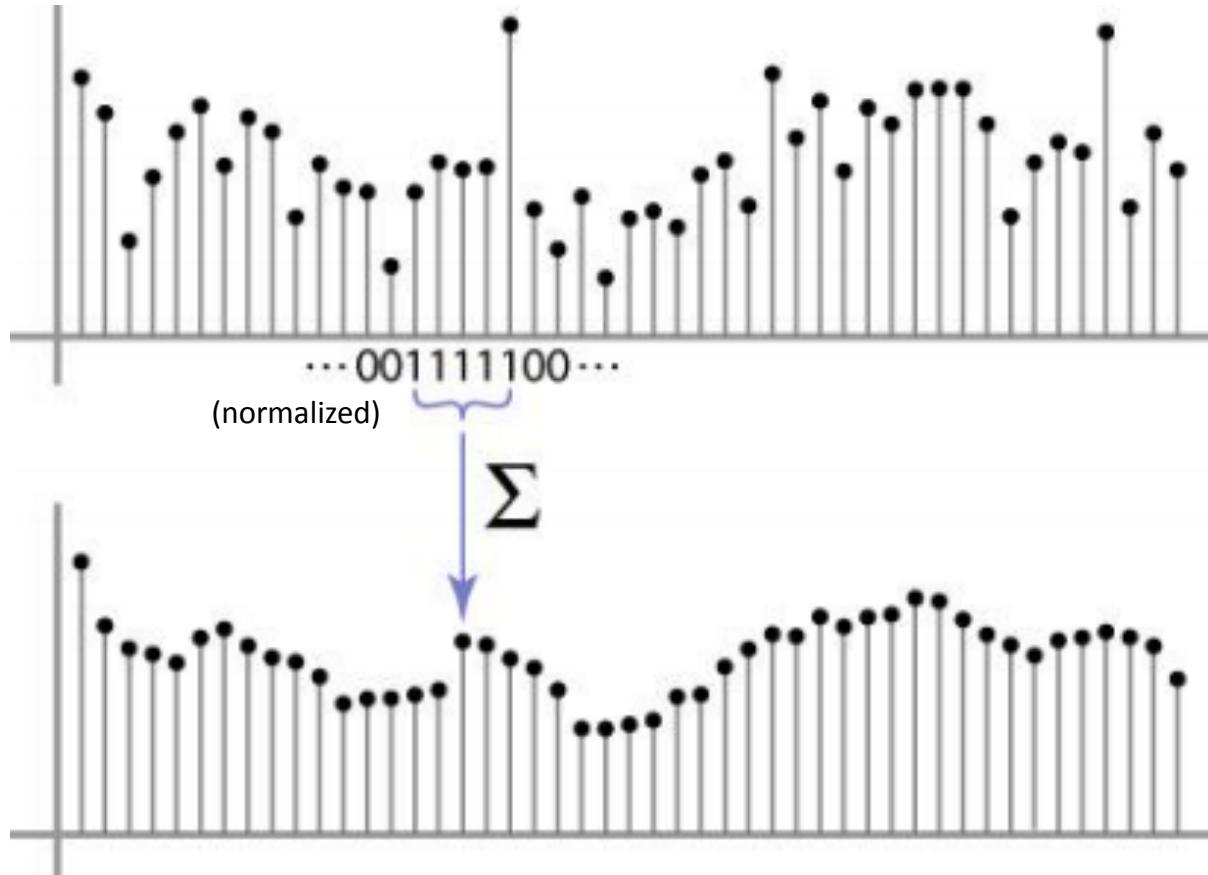
For example:
pixel intensity of 1D image
amplitude of a sound wave over time
electrical potential at one electrode over time
MR measurement in one brain voxel

e.g., a moving average filter (blur)



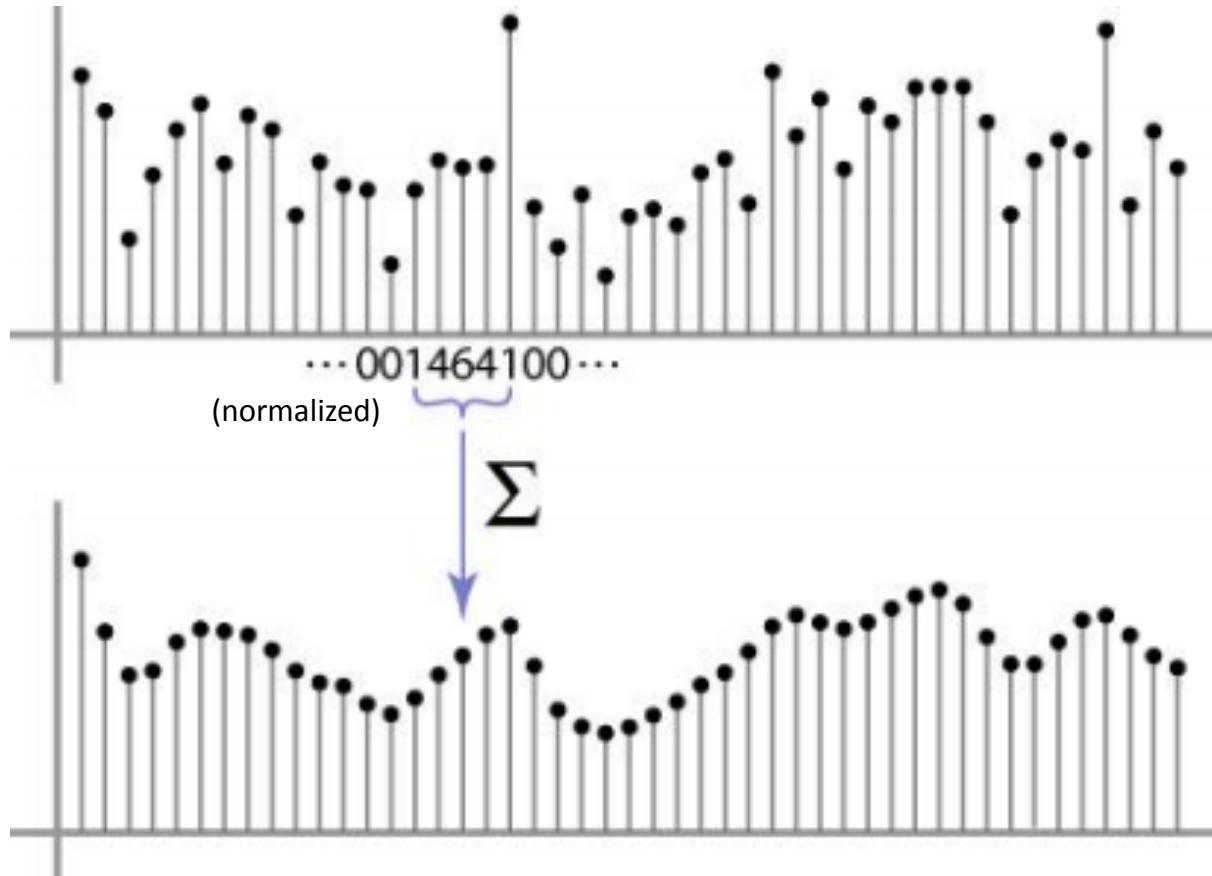
e.g., a moving average filter

```
weights = np.array([ 0, 0, 0, 0, 1, 1, 1, 1, 1, 0, 0, 0, 0, ]) / 5
```



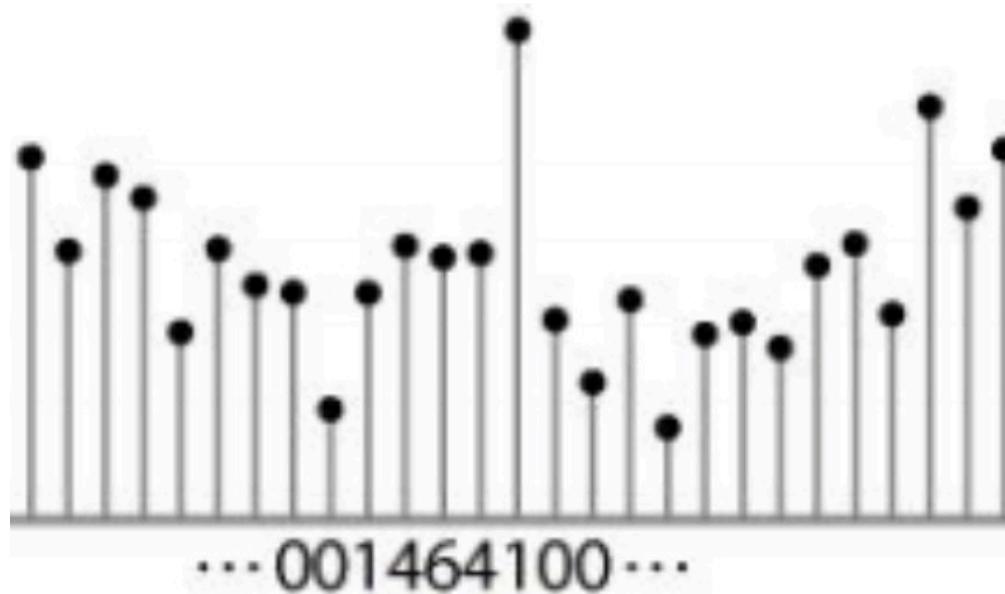
e.g., a moving average filter

```
weights = np.array([ 0, 0, 0, 0, 1, 4, 6, 4, 1, 0, 0, 0, 0, 0, ]) / 16
```

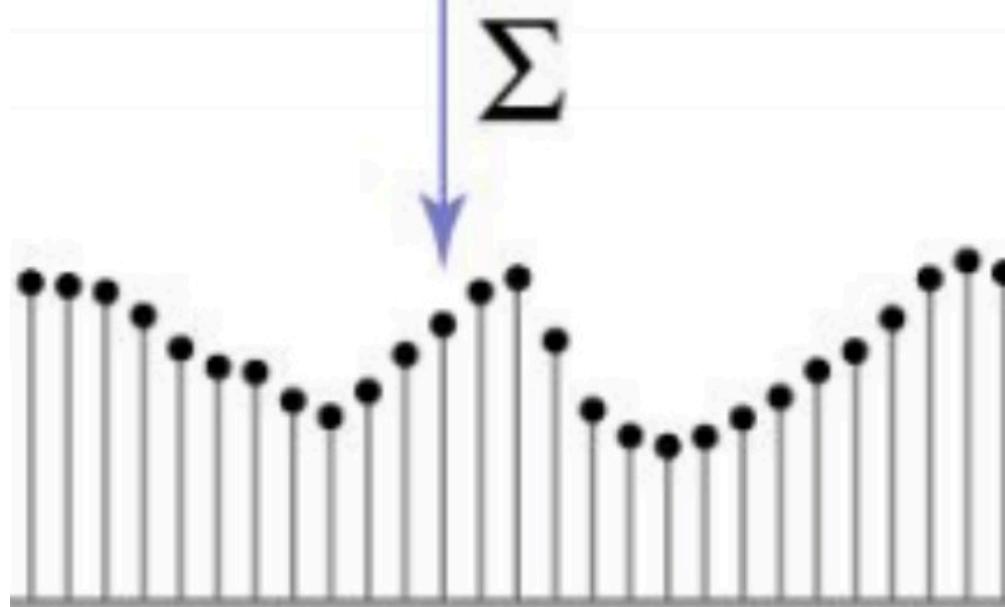


e.g., a moving average filter

```
weights = np.array([ 0, 0, 0, 0, 1, 4, 6, 4, 1, 0, 0, 0, 0, 0, ]) / 16
```

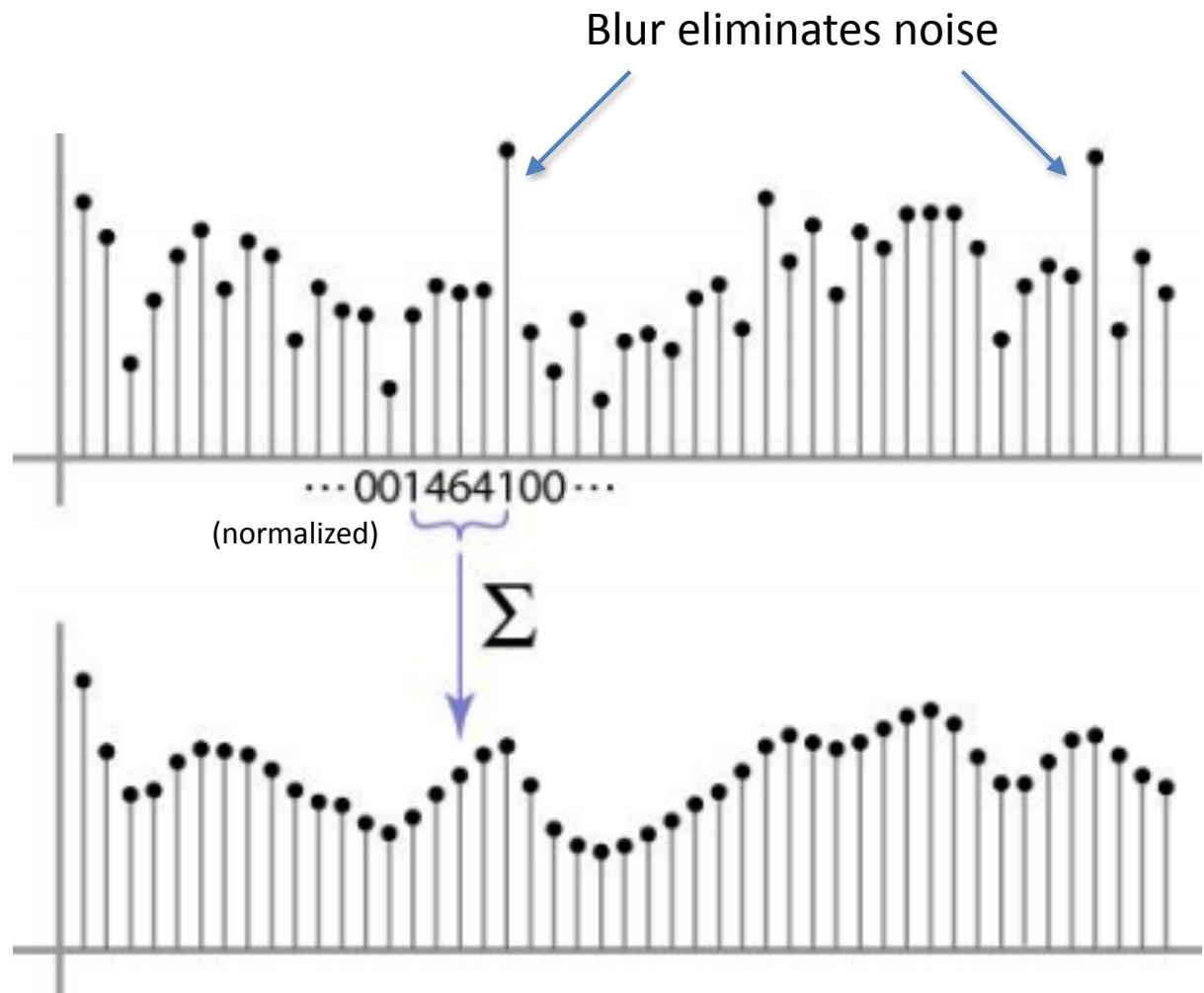


weights sum to 1

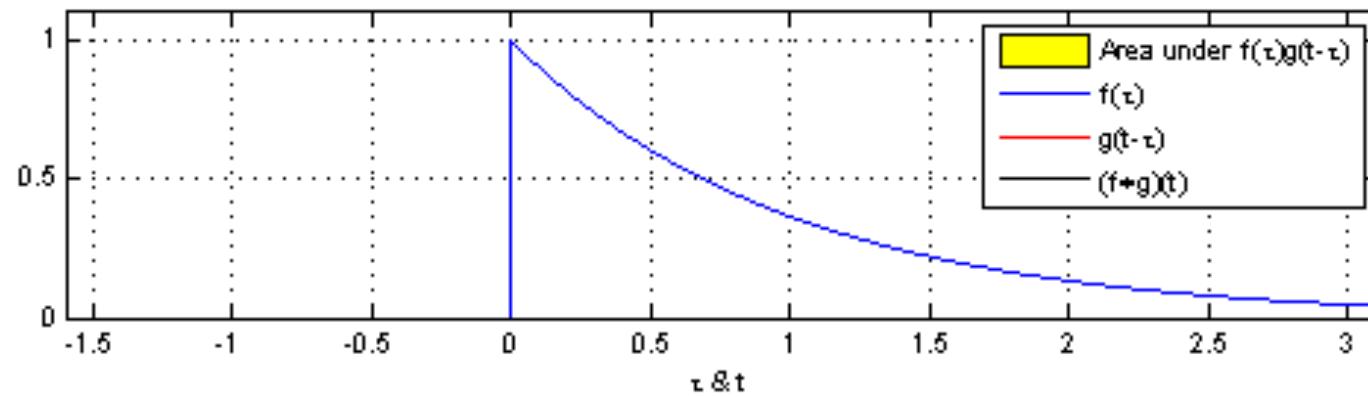
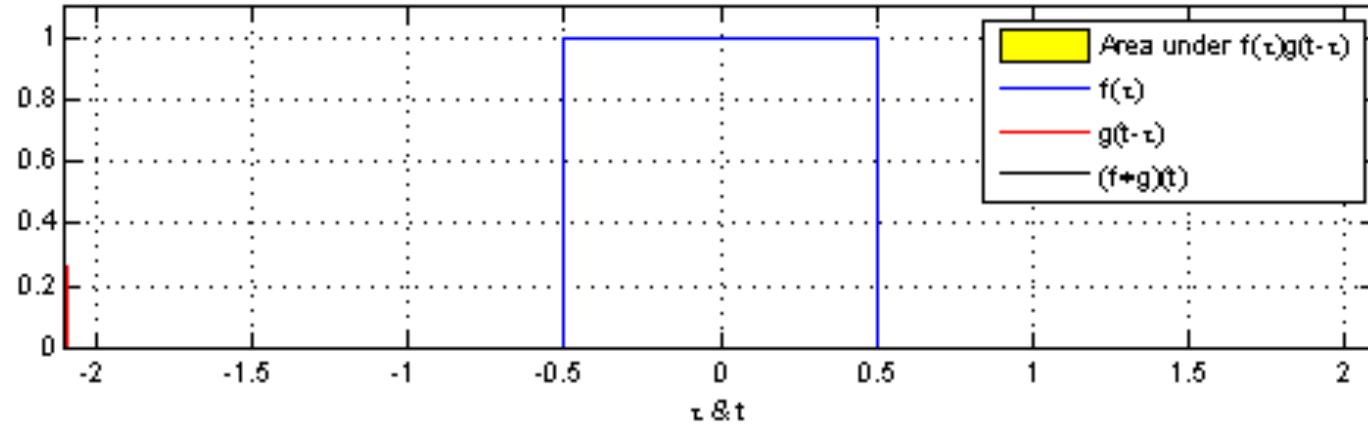


e.g., a **moving** average filter

```
weights = np.array([ 0, 0, 0, 0, 1, 4, 6, 4, 1, 0, 0, 0, 0, 0, ]) / 16
```



Illustration



0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	90	0	90	90	90	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0

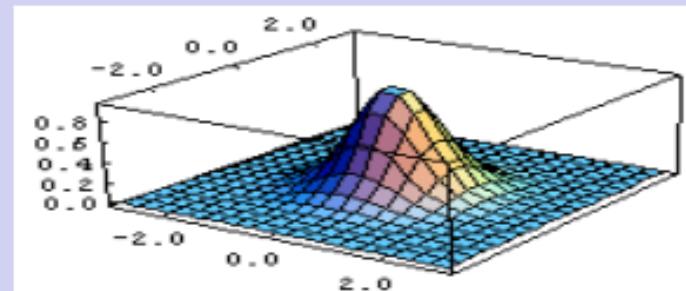
$I [i, j]$

(normalized)

$$\frac{1}{16}$$

1	2	1
2	4	2
1	2	1

$F [u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	90	0	90	90	90	0	0
0	0	0	90	90	90	90	90	0	0
0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0

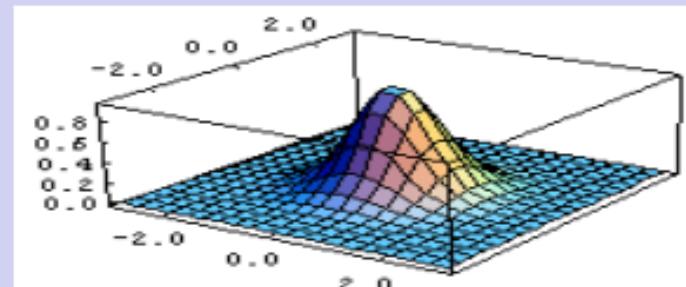
$I[i, j]$

Blur eliminates noise

(normalized)

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

$F[u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

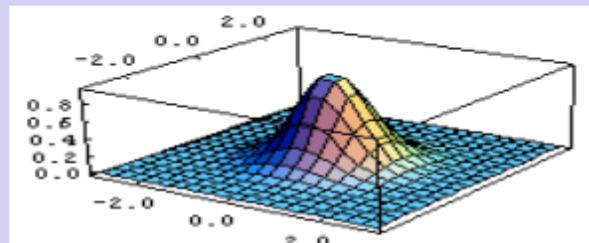
“weighted sum”

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

$F[u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

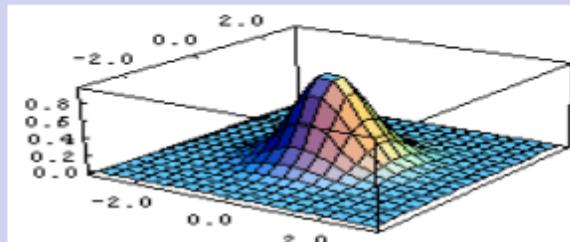
filtered image
pixel (i, j)

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

$F[u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

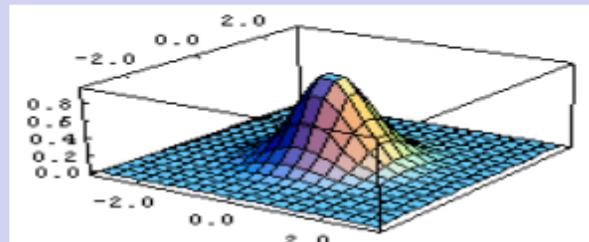
filtered image *pixel (i, j)* *pixels from input image*

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

$F[u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

*also called
a kernel*

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

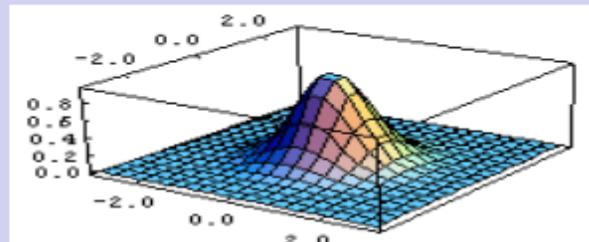
filtered image pixel (i, j) *$u = -k$ $v = -k$ pixels from filter* *I_{in} pixels from input image*

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

$F[u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

(kernel size)
filter size *also called*
 k k *a kernel*

$$I_{out}(i, j) = \sum_{u=-k} \sum_{v=-k} F(u, v) I_{in}(i - u, j - v)$$

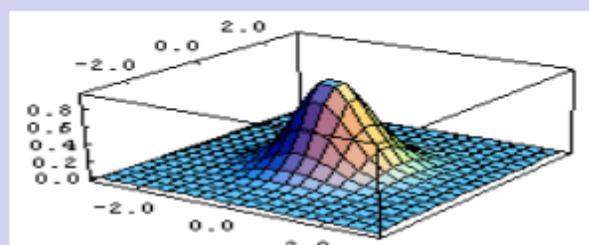
filtered image *$u = -k$* *$v = -k$* *$pixels from$* *$pixels from$*
 $pixel (i, j)$ *filter* *input image*

$I[i, j]$

$$\begin{array}{r} \boxed{1} \\ \hline \boxed{16} \end{array}$$

1	2	1
2	4	2
1	2	1

$$F[u, v]$$

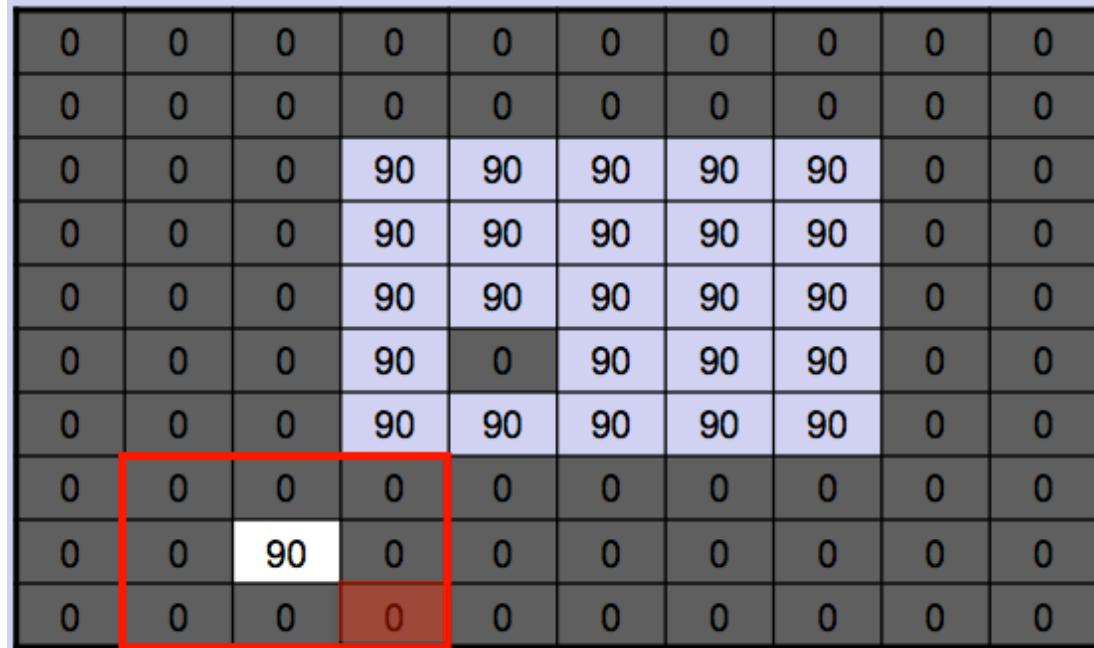


$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

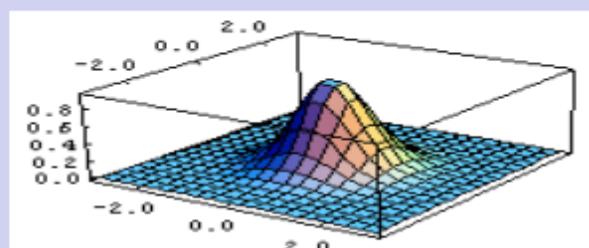
$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

“weighted sum”



$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

$$F [u, v]$$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

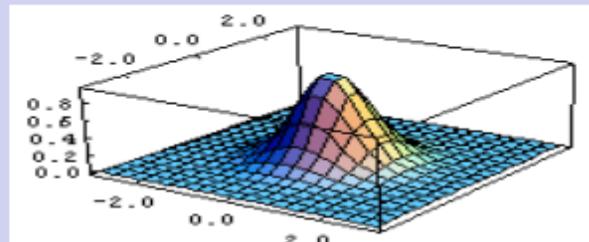
“weighted sum”

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

$F[u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

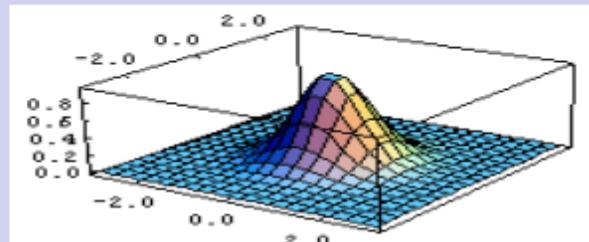
“weighted sum”

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

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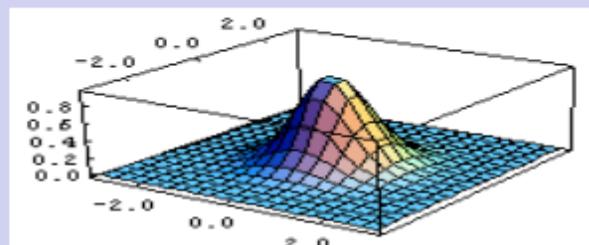
“weighted sum”

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{matrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{matrix}$$

$F[u, v]$

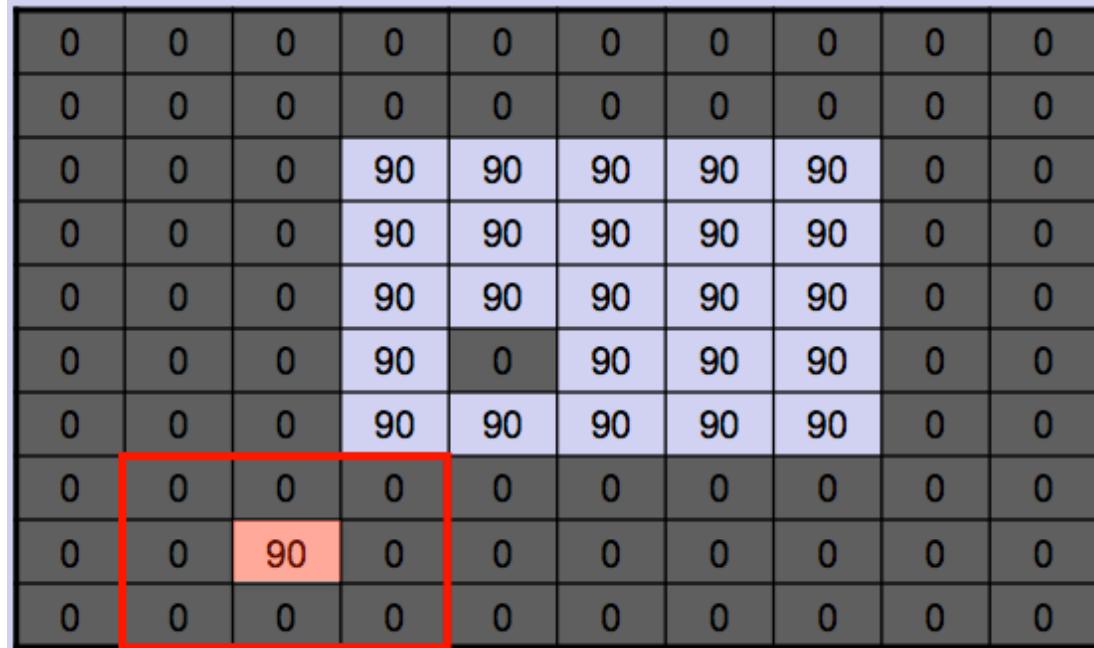


$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

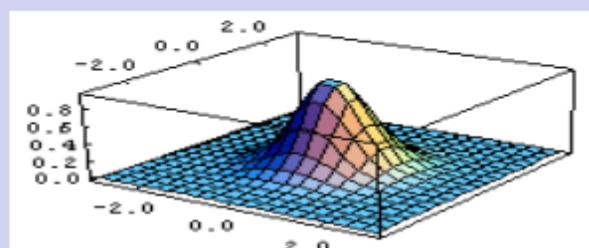
$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

“weighted sum”



$$\frac{1}{16} \begin{matrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{matrix}$$

$$F[u, v]$$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

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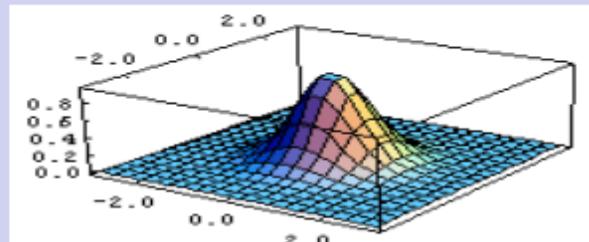
“weighted sum”

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{bmatrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{bmatrix}$$

$F[u, v]$

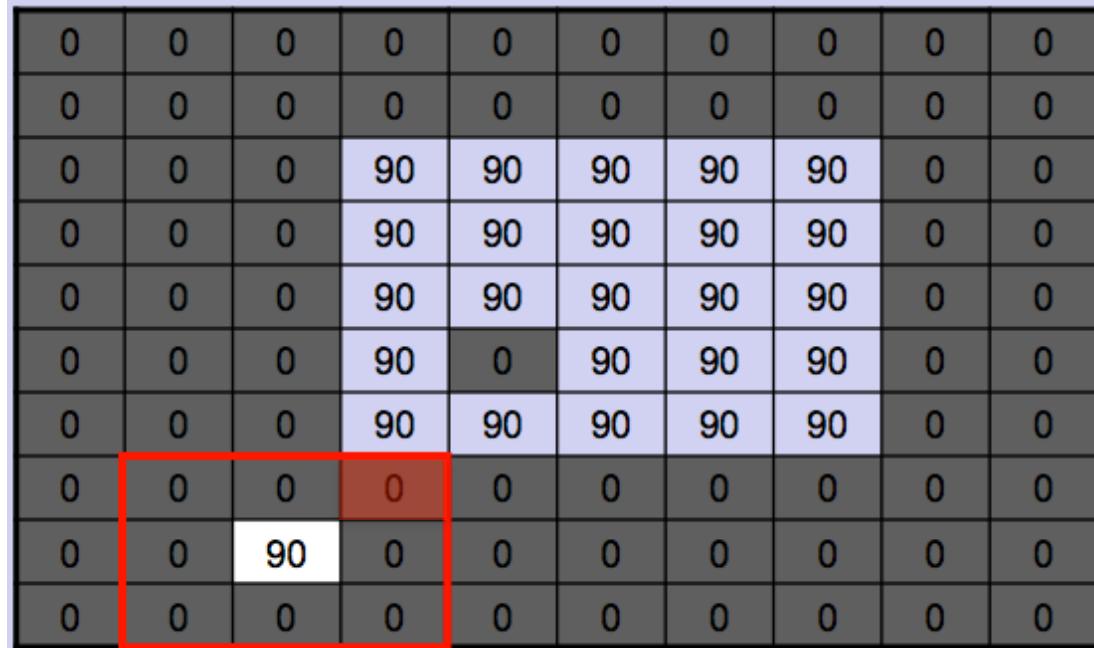


$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

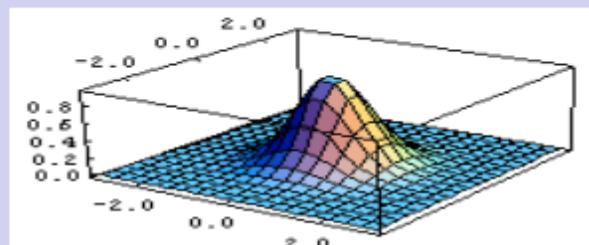
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“weighted sum”



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$$F[u, v]$$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

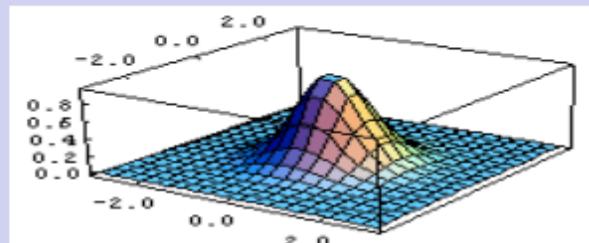
“weighted sum”

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{matrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{matrix}$$

$F[u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

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$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

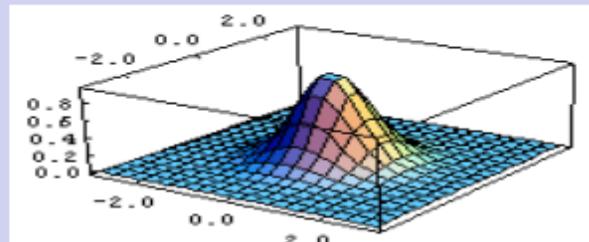
“weighted sum”

0	0	0	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	90	0	90	90	90	0	0	0
0	0	0	90	90	90	90	90	0	0	0
0	0	0	0	0	0	0	0	0	0	0
0	0	90	0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0	0	0	0

$I[i, j]$

$$\frac{1}{16} \begin{matrix} 1 & 2 & 1 \\ 2 & 4 & 2 \\ 1 & 2 & 1 \end{matrix}$$

$F[u, v]$



$$f(u, v) = \frac{1}{2\pi\sigma^2} e^{-\frac{u^2+v^2}{\sigma^2}}$$

Convolution

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

discrete version

in Python, you can't define a numpy array with negative indices like this, so you'd need to adjust accordingly

Convolution

$$I_{out}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

discrete version

$$I_{out}(x, y) = \iint F(u, v) I_{in}(x - u, y - v) du dv$$

continuous version

Convolution

$$I_{out}(i, j) = F(i, j) * I_{in}(i, j) = \sum_{u=-k}^k \sum_{v=-k}^k F(u, v) I_{in}(i - u, j - v)$$

discrete version

symbolically in mathematics, $$ is convolution (never multiplication)*

$$I_{out}(x, y) = F(x, y) * I_{in}(x, y) = \iint F(u, v) I_{in}(x - u, y - v) du dv$$

continuous version

Convolution

$$I_{out}(t) = F(t) * I_{in}(t) = \sum_{\tau=-k}^k F(\tau) I_{in}(t - \tau)$$

discrete version

1D (e.g., sound)

$$I_{out}(t) = F(t) * I_{in}(t) = \int F(\tau) I_{in}(t - \tau) d\tau$$

continuous version

Convolution Operations

commutative

$$f(t) * g(t) = g(t) * f(t)$$

associative

$$f(t) * (g(t) * h(t)) = (f(t) * g(t)) * h(t)$$

distributive

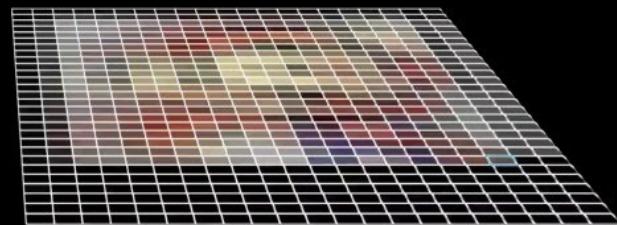
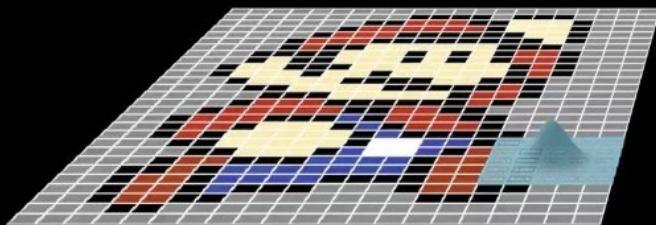
$$f(t) * (g(t) + h(t)) = f(t) * g(t) + f(t) * h(t)$$

linear

$$\alpha(f(t) * g(t)) = (\alpha f(t)) * g(t) = f(t) * (\alpha g(t))$$

what's the "signal" and what's the "filter" is arbitrary

Convolutions



in image processing

<https://www.youtube.com/watch?v=8rrHTtUzyZA>

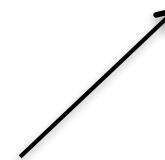
watch from 1:00 to 7:30
(rest is implementation in Julia)

(Grant Sanderson, creator of 3blue1brown)

convolutions in Python

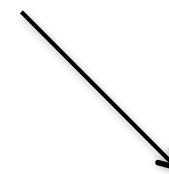
```
from scipy import signal
```

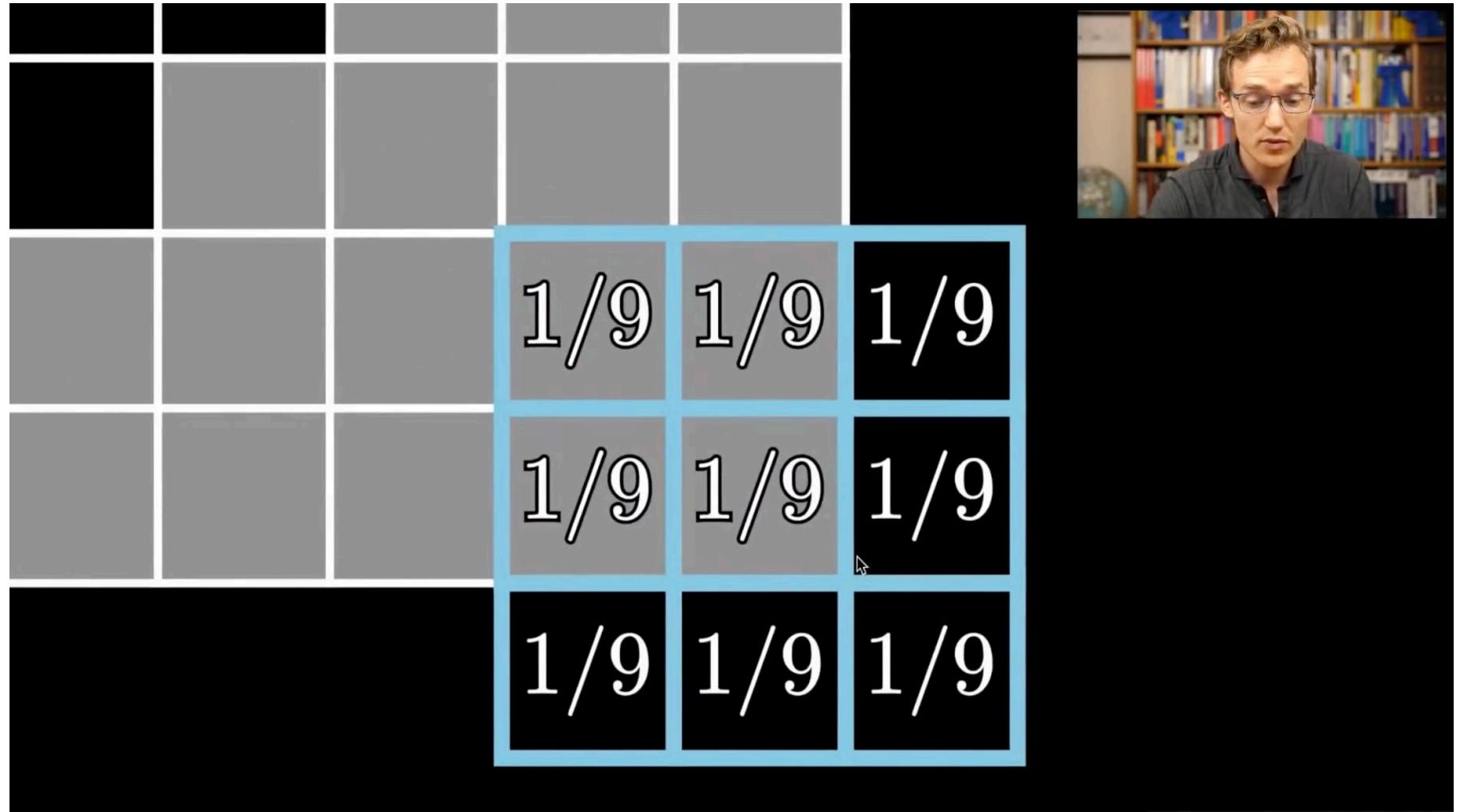
```
filtered = signal.convolve(sig, fil, mode='same' )
```



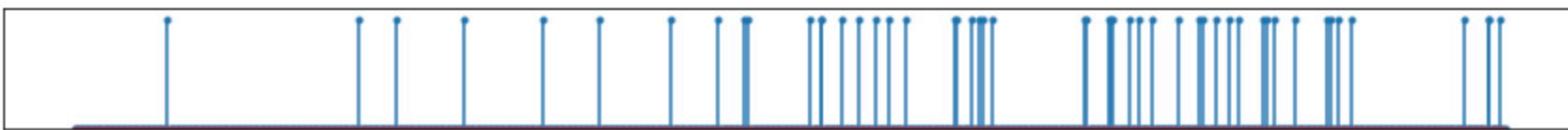
' same ' means that the output is *not* padded ...
the output is the *same* length as the signal

```
filtered = signal.convolve2(sig, fil, mode='same' )
```

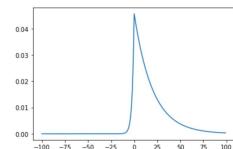




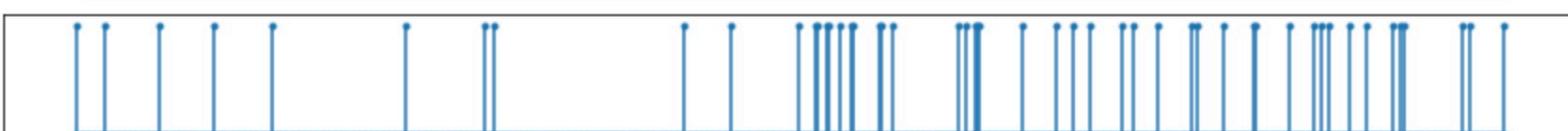
neural spiking example



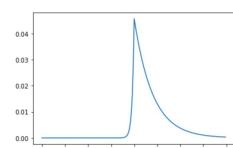
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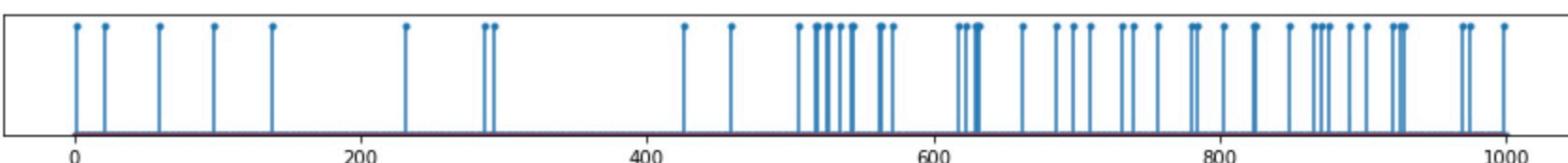
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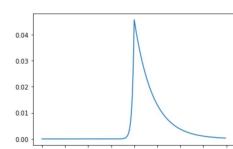
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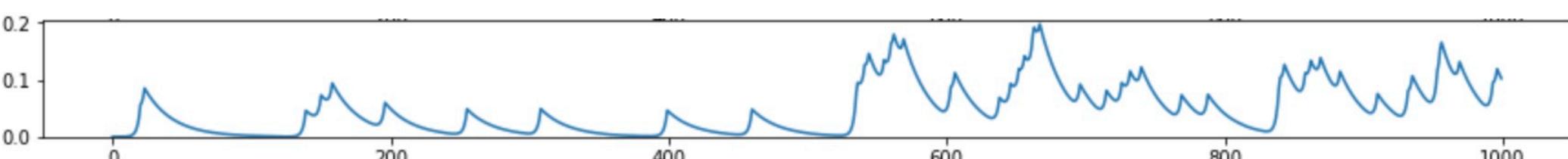
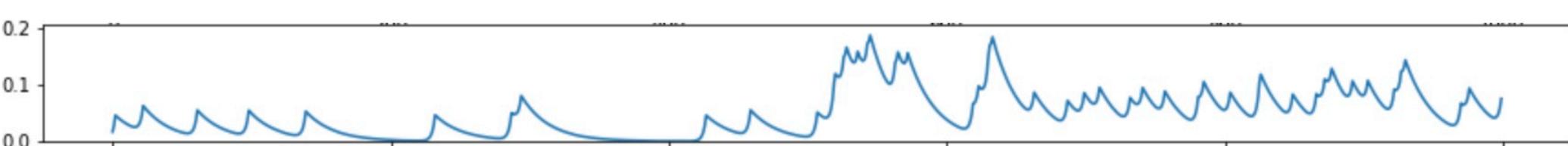
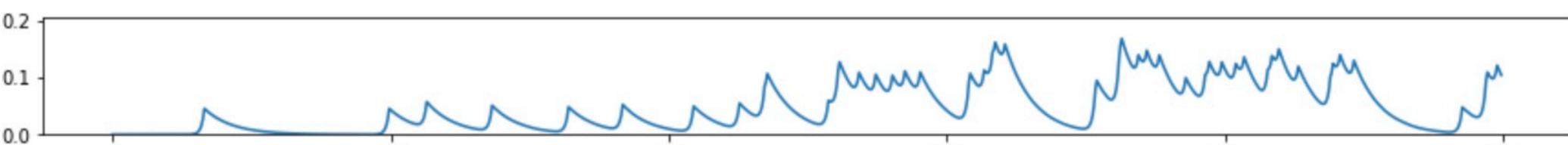
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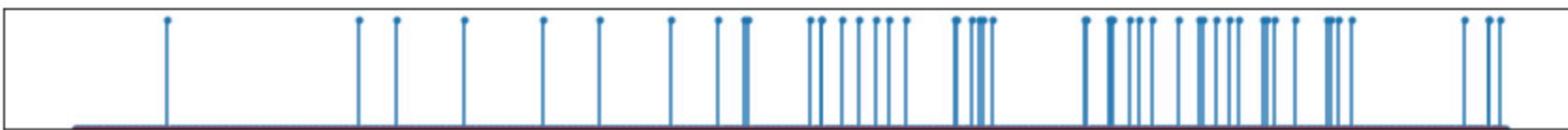
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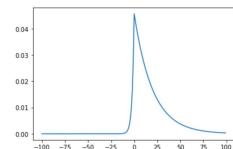
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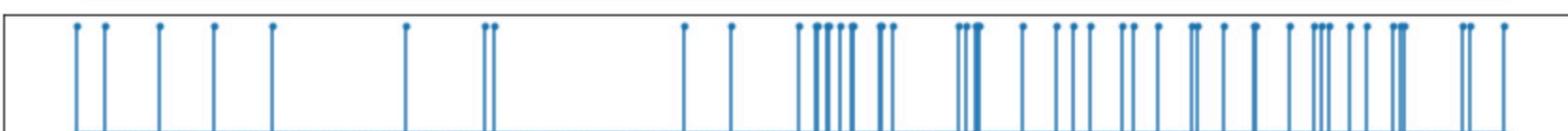
neural spiking example



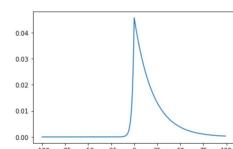
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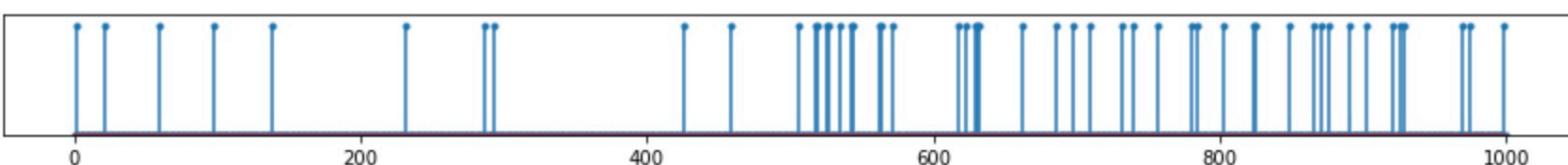
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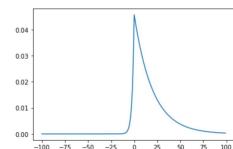
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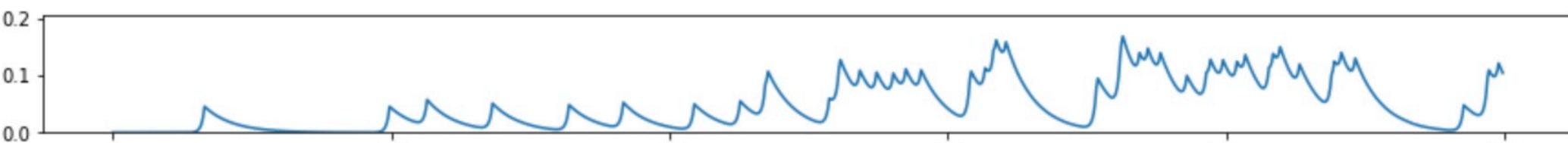
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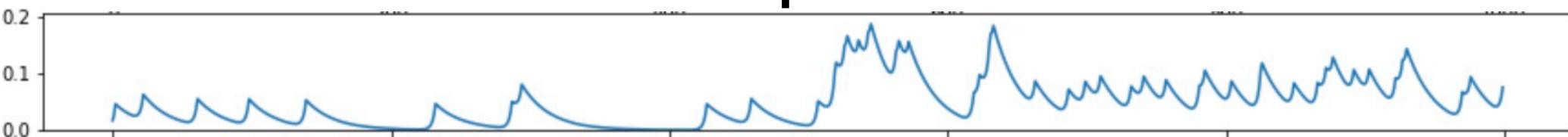
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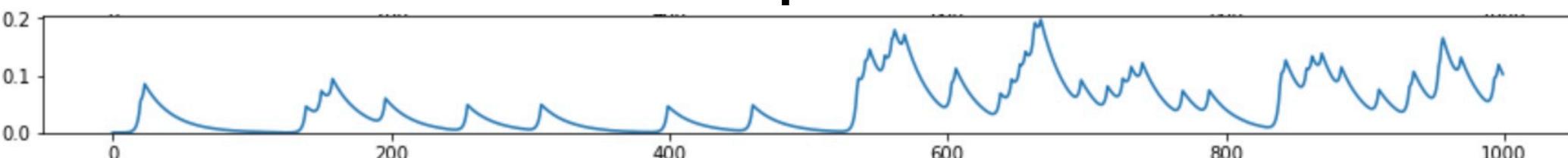
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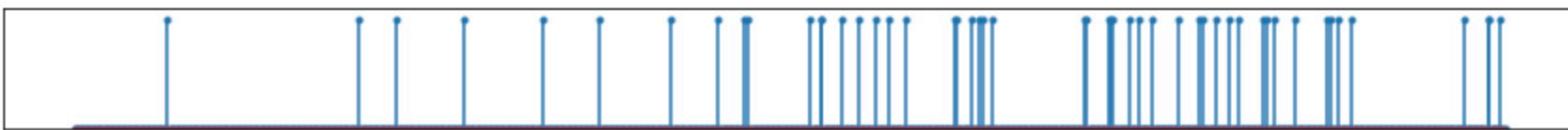
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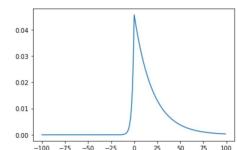
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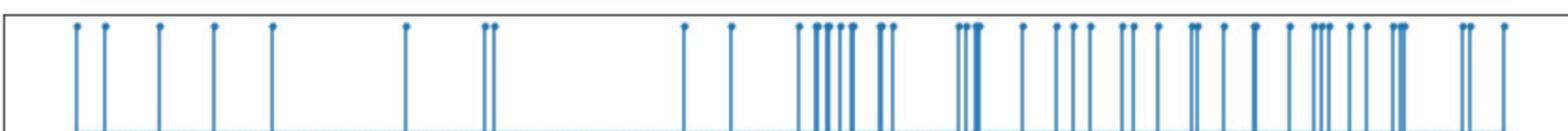
neural spiking example



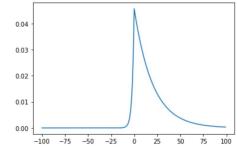
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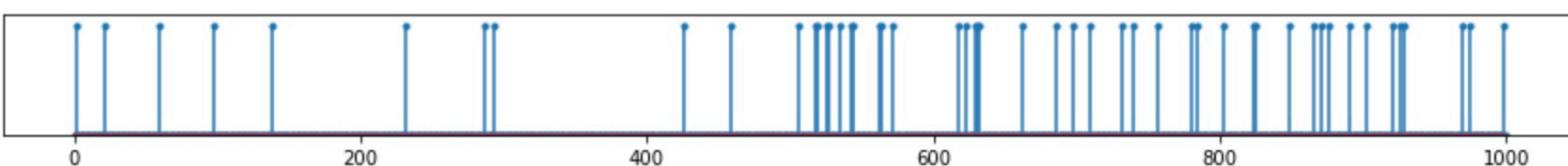
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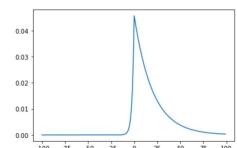
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