

Lab 8 Documentation

Name: Crystal Low

Class: EE 104

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Professor Pham

Abstract: This lab consists of three parts, the first part is to explore the CNN code on google collaboration and achieve at least 90% accuracy and recognize 90% of the images provided. Then there is a challenge test with CNN to recognize five of the provided unrecognizable images from the test images. The last part of this lab is to make modifications to the balloon flight game.

Objective:

The objective of this lab is to make modifications to the CNN code that is provided to improve the accuracy of the recognition of the given images. The achievement can be done using any method including baseline, increasing dropout, data augmentation, batch normalization, or any method that the developer would like. In the challenge test part of this lab, the goal is to recognize at least five unrecognizable images. The lab objective is to modify the balloon flight game by either, adding more high score spots, having multiple lives, speeding up the object, adding more objects to make it harder for the user, file handling, different ways to score, having a level up, or space out the obstacles. The goal is to complete four out of eight of the provided tweaks to the game.

Instructions:

Import Packages:

CNN:

```
▼ Import TensorFlow

[ ] import tensorflow as tf
import sys
import numpy as np
# baseline model with dropout
#data augmentation on the cifar10 dataset
from keras.datasets import cifar10
from tensorflow.keras.utils import to_categorical
from keras.models import Sequential
from keras.layers import Conv2D
from keras.layers import MaxPooling2D
from keras.layers import Dense
from keras.layers import Flatten
from tensorflow.keras.optimizers import SGD
from keras.preprocessing.image import ImageDataGenerator
from keras.layers import Dropout
from keras.layers import BatchNormalization
from tensorflow.keras import datasets, layers, models
import matplotlib.pyplot as plt
```

Balloon Flight:

```
import pgzrun
from pgzero.builtins import Actor
from random import randint
```

References:

Module 8 provided by Professor Pham

<https://www.cs.toronto.edu/~kriz/cifar.html>

<https://colab.research.google.com/github/tensorflow/docs/blob/master/site/en/tutorials/images/cn>

[n.ipynb#scrollTo=WRzW5xSDDbNF](#)

<https://colab.research.google.com/github/tensorflow/docs/blob/master/site/en/tutorials/images/classification.ipynb#scrollTo=dC40sRITBSsQ>

<https://machinelearningmastery.com/how-to-develop-a-cnn-from-scratch-for-cifar-10-photo-classification/>

CNN:

In this code, the goal was to improve the accuracy of the images that were provided. The layers were fixed to accommodate the accuracy. The results will show the final accuracy that was captured. This code was running multiple times to get these results. It was tweaked and modified many times however 85% was the highest it has got.

- 1) In the layers section, the baseline model was created to help improve the accuracy.

Referenced this website:

<https://machinelearningmastery.com/how-to-develop-a-cnn-from-scratch-for-cifar-10-photo-classification/>

```
▼ Create the convolutional base

The 6 lines of code below define the convolutional base using a common pattern: a stack of Conv2D and MaxPooling2D layers.

As input, a CNN takes tensors of shape (image_height, image_width, color_channels), ignoring the batch size. If you are new to these dimensions, color_channels refers to (R,G,B). In this example, you will configure your CNN to process inputs of shape (32, 32, 3), which is the format of CIFAR images. You can do this by passing the argument input_shape to your first layer.

[ ] model = models.Sequential()

model.add(Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same', input_shape=(32, 32, 3)))
model.add(BatchNormalization())
model.add(Conv2D(32, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(MaxPooling2D((2, 2)))
model.add(Dropout(0.2))

model.add(Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(Conv2D(64, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(MaxPooling2D((2, 2)))
model.add(Dropout(0.3))

model.add(Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(Conv2D(128, (3, 3), activation='relu', kernel_initializer='he_uniform', padding='same'))
model.add(BatchNormalization())
model.add(MaxPooling2D((2, 2)))
model.add(Dropout(0.4))

model.add(Flatten())
model.add(Dense(128, activation='relu', kernel_initializer='he_uniform'))
model.add(BatchNormalization())
model.add(Dropout(0.8))
model.add(Dense(10, activation='softmax'))
```

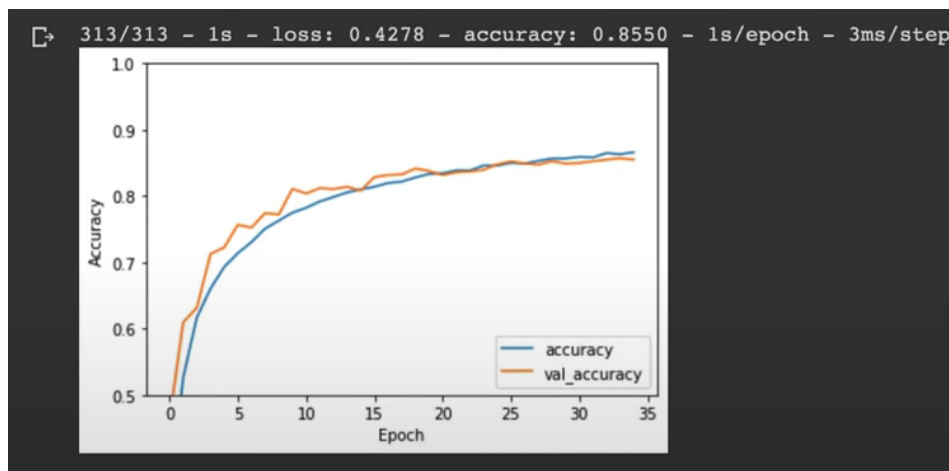
- 2) Added more epochs to obtain a better range of accuracy

```
▼ Compile and train the model

model.compile(optimizer='adam',
               loss=tf.keras.losses.SparseCategoricalCrossentropy(from_logits=True),
               metrics=['accuracy'])

history = model.fit(train_images, train_labels, epochs=35,
                    validation_data=(test_images, test_labels))
```

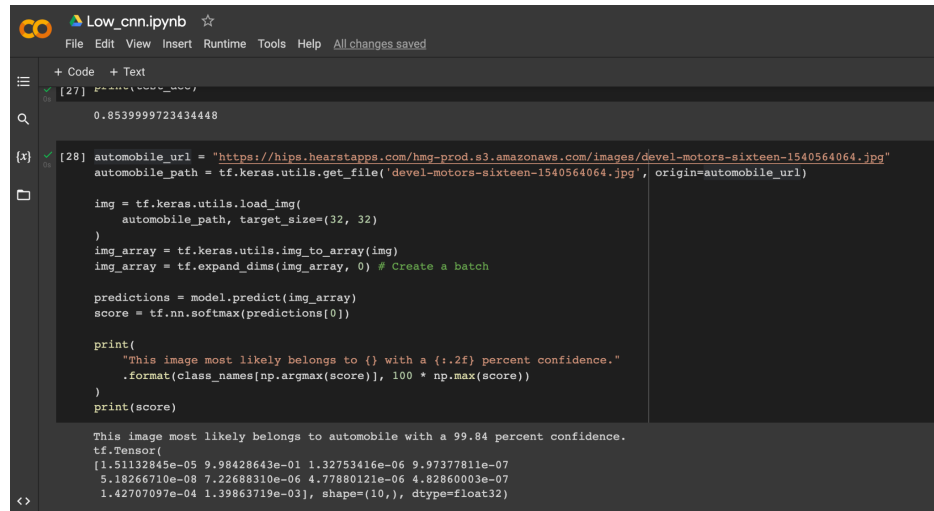
- 3) The results with the accuracy



CNN Challenge Test

The goal of this lab is to recognize the unrecognizable images from the test images section provided in the lab instructions.

- 1) Added a cell to recognize the automobile, figured the frame size that will cater to the image put in the link of the image, and classify under an automobile.



```
Low_cnn.ipynb
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+ Code + Text

[27] print('score:',
0.8539999723434448

[28] automobile_url = "https://hips.hearstapps.com/hmg-prod.s3.amazonaws.com/images/devel-motors-sixteen-1540564064.jpg"
    automobile_path = tf.keras.utils.get_file('devel-motors-sixteen-1540564064.jpg', origin=automobile_url)

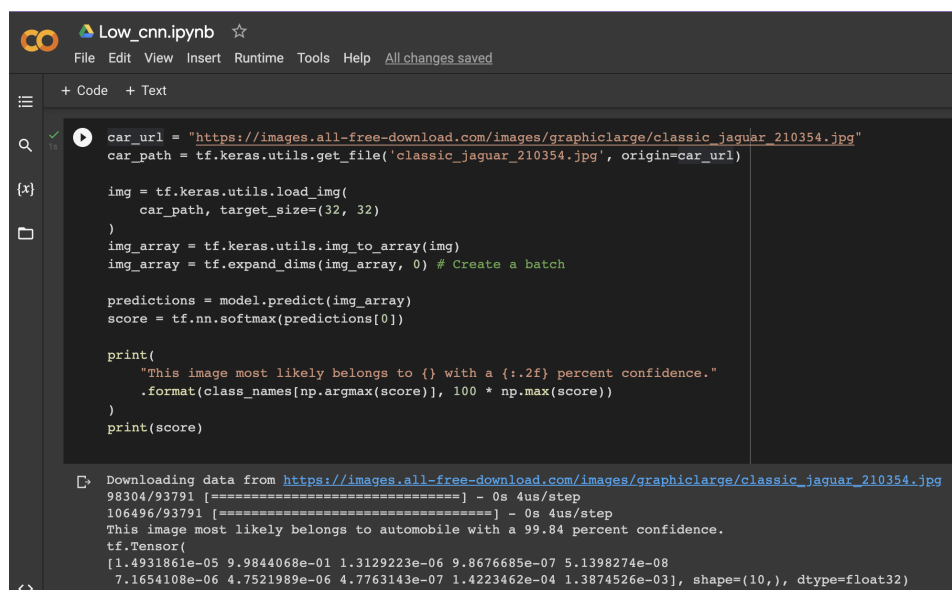
    img = tf.keras.utils.load_img(
        automobile_path, target_size=(32, 32)
    )
    img_array = tf.keras.utils.img_to_array(img)
    img_array = tf.expand_dims(img_array, 0) # Create a batch

    predictions = model.predict(img_array)
    score = tf.nn.softmax(predictions[0])

    print(
        "This image most likely belongs to {} with a {:.2f} percent confidence."
        .format(class_names[np.argmax(score)], 100 * np.max(score))
    )
    print(score)

This image most likely belongs to automobile with a 99.84 percent confidence.
tf.Tensor(
[1.51132845e-05 9.98428643e-01 1.32753416e-06 9.97377811e-07
 5.18266710e-08 7.22688310e-06 4.77880121e-06 4.82860003e-07
 1.42707097e-04 1.39863719e-03], shape=(10,), dtype=float32)
```

- 2) Second image is classified as an automobile as it is an automobile



```
Low_cnn.ipynb
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+ Code + Text

[29] car_url = "https://images.all-free-download.com/images/graphiclarge/classic_jaguar_210354.jpg"
    car_path = tf.keras.utils.get_file('classic_jaguar_210354.jpg', origin=car_url)

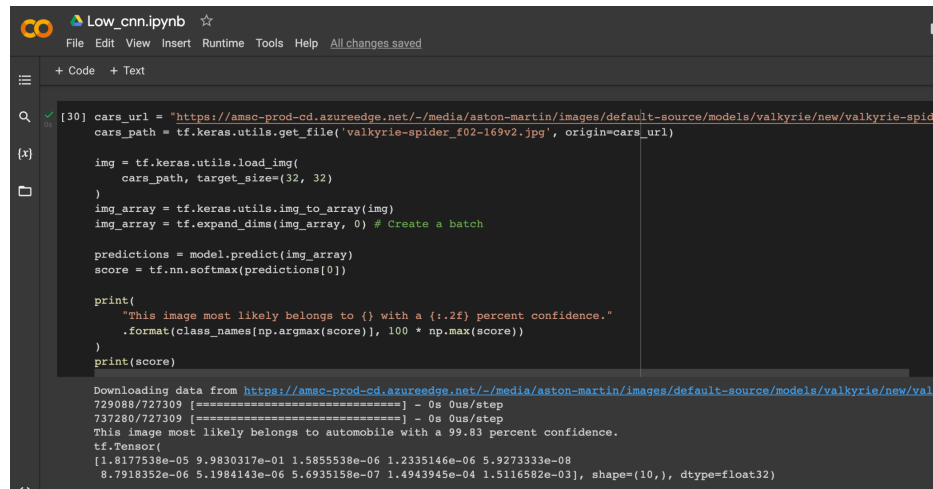
    img = tf.keras.utils.load_img(
        car_path, target_size=(32, 32)
    )
    img_array = tf.keras.utils.img_to_array(img)
    img_array = tf.expand_dims(img_array, 0) # Create a batch

    predictions = model.predict(img_array)
    score = tf.nn.softmax(predictions[0])

    print(
        "This image most likely belongs to {} with a {:.2f} percent confidence."
        .format(class_names[np.argmax(score)], 100 * np.max(score))
    )
    print(score)

[30] Downloading data from https://images.all-free-download.com/images/graphiclarge/classic_jaguar_210354.jpg
98304/93791 [=====] - 0s 4us/step
106496/93791 [=====] - 0s 4us/step
This image most likely belongs to automobile with a 99.84 percent confidence.
tf.Tensor(
[1.4931861e-05 9.9844068e-01 1.3129223e-06 9.8676685e-07 5.1398274e-08
 7.1654108e-06 4.7521989e-06 4.7763143e-07 1.4223462e-04 1.3874526e-03], shape=(10,), dtype=float32)
```

3) Third image classified as an automobile as it is an automobile



A Jupyter Notebook interface titled 'Low_cnn.ipynb'. The code cell contains the following Python code:

```
[30] cars_url = "https://amsc-prod-cd.azureedge.net/-/media/aston-martin/images/default-source/models/valkyrie/new/valkyrie-spider_f02-169v2.jpg"
cars_path = tf.keras.utils.get_file('valkyrie-spider_f02-169v2.jpg', origin=cars_url)

img = tf.keras.utils.load_img(
    cars_path, target_size=(32, 32)
)
img_array = tf.keras.utils.img_to_array(img)
img_array = tf.expand_dims(img_array, 0) # Create a batch

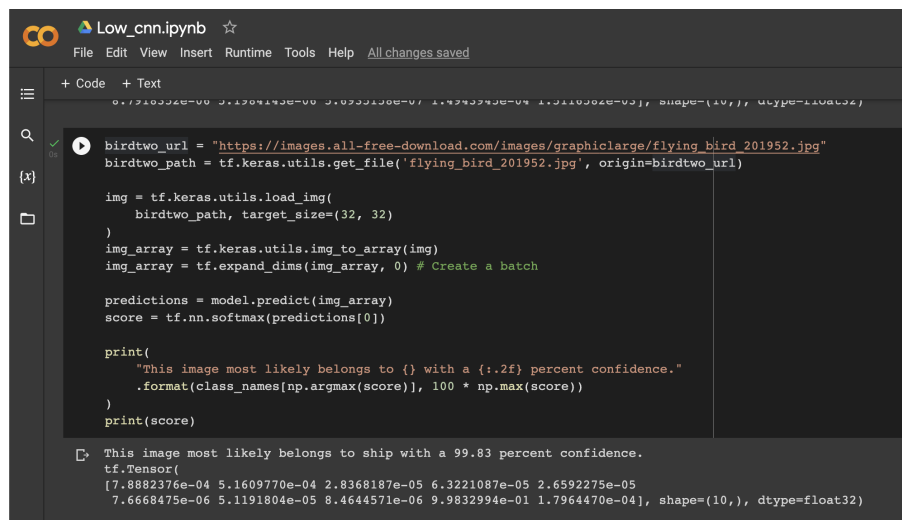
predictions = model.predict(img_array)
score = tf.nn.softmax(predictions[0])

print(
    "This image most likely belongs to {} with a {:.2f} percent confidence."
    .format(class_names[np.argmax(score)], 100 * np.max(score))
)
print(score)
```

The output shows the download progress of the image and the classification result:

```
Downloading data from https://amsc-prod-cd.azureedge.net/-/media/aston-martin/images/default-source/models/valkyrie/new/valkyrie-spider_f02-169v2.jpg
729088/727309 [=====] - 0s 0us/step
737280/727309 [=====] - 0s 0us/step
This image most likely belongs to automobile with a 99.83 percent confidence.
tf.Tensor(
[1.8177538e-05 9.9830317e-01 1.5855538e-06 1.2335146e-06 5.9273333e-08
 8.7918352e-06 5.1984143e-06 5.6935158e-07 1.4943945e-04 1.5116582e-03], shape=(10,), dtype=float32)
```

4) The fourth image was classified as a ship when it was a bird



A Jupyter Notebook interface titled 'Low_cnn.ipynb'. The code cell contains the following Python code:

```
birdtwo_url = "https://images.all-free-download.com/images/graphiclarge/flying_bird_201952.jpg"
birdtwo_path = tf.keras.utils.get_file('flying_bird_201952.jpg', origin=birdtwo_url)

img = tf.keras.utils.load_img(
    birdtwo_path, target_size=(32, 32)
)
img_array = tf.keras.utils.img_to_array(img)
img_array = tf.expand_dims(img_array, 0) # Create a batch

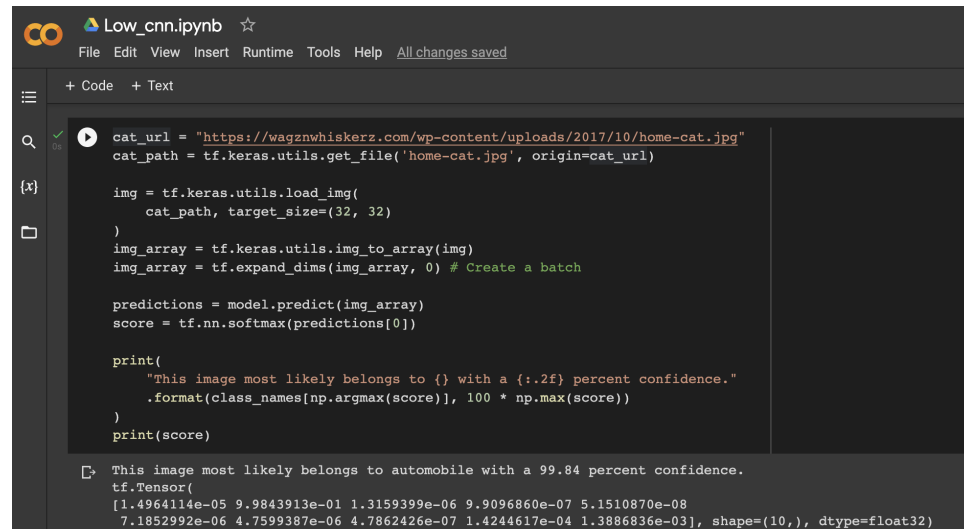
predictions = model.predict(img_array)
score = tf.nn.softmax(predictions[0])

print(
    "This image most likely belongs to {} with a {:.2f} percent confidence."
    .format(class_names[np.argmax(score)], 100 * np.max(score))
)
print(score)
```

The output shows the classification result:

```
This image most likely belongs to ship with a 99.83 percent confidence.
tf.Tensor(
[7.8882376e-04 5.1609770e-04 2.8368187e-05 6.3221087e-05 2.6592275e-05
 7.6668475e-06 5.1191804e-05 8.4644571e-06 9.9832994e-01 1.7964470e-04], shape=(10,), dtype=float32)
```

5) The fifth image was classified as an automobile but it was a cat image



```
cat_url = "https://wagznwhiskerz.com/wp-content/uploads/2017/10/home-cat.jpg"
cat_path = tf.keras.utils.get_file('home-cat.jpg', origin=cat_url)

img = tf.keras.utils.load_img(
    cat_path, target_size=(32, 32)
)
img_array = tf.keras.utils.img_to_array(img)
img_array = tf.expand_dims(img_array, 0) # Create a batch

predictions = model.predict(img_array)
score = tf.nn.softmax(predictions[0])


print(
    "This image most likely belongs to {} with a {:.2f} percent confidence."
    .format(class_names[np.argmax(score)], 100 * np.max(score))
)
print(score)

This image most likely belongs to automobile with a 99.84 percent confidence.
tf.Tensor(
[1.4964114e-05 9.9843913e-01 1.3159399e-06 9.9096860e-07 5.1510870e-08
 7.1852992e-06 4.7599387e-06 4.7862426e-07 1.4244617e-04 1.3886836e-03], shape=(10,), dtype=float32)
```

Balloon Flight

The goal of this lab is to incorporate four minor tweaks of the developer's choice. The first tweak that was made was adding more lines for the high score. The second tweak that was made was to speed up the bird to fly faster across the screen. The third modification made was to add another actor to the game to make it harder for the user to score. The fourth adjustment that was made was to create a different way to score so that when the hot air balloon passes an object then the score will change accordingly.

- 1) Changing the high score to prompt more slots was completed by adding more to the text file created for the high score to prompt.

 *highscore - Notepad

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0 0 0 0 0 |

- 2) To make the bird fly across the screen faster, the number has to increase at Line in the def update structure.

```
109 def update():
110     global game_over, score, number_of_updates, subtract_life
111     if not game_over:
112         if not up:
113             balloon.y += GRAVITY_STRENGTH # gravity
114         if bird.x > 0:
115             bird.x -= 10 #made the bird fly faster
116             if number_of_updates == 20: #changed correlated to the speed of the bird
117                 flap()
118                 number_of_updates = 0
119             else:
120                 number_of_updates += 1
121         else:
122             bird.x = randint(800, 1600)
123             bird.y = randint(10, 200)
124             score += 1
125             number_of_updates = 0
126
```

- 3) Add new actors for the tree, house and the bird so they can be called throughout the code

```
10 balloon = Actor('balloon')
11 balloon.pos = 400, 300
12
13 bird = Actor('bird-up')
14 bird.pos = randint(800, 1600), randint(10, 200)
15
16 # add another bird actor
17 birdtwo = Actor('bird-up')
18 birdtwo.pos = randint(800, 1600), randint(10, 200)
19
20 house = Actor('house')
21 house.pos = randint(800, 1600), 460
22
23 housetwo = Actor('house')
24 housetwo.pos = randint(800, 1600), 460
25
26 tree = Actor('tree')
27 tree.pos = randint(800, 1600), 450
28
29 treetwo = Actor('tree')
30 treetwo.pos = randint(800, 1600), 450
31
```

- 4) Make sure the set the bird up to be true for bird two so it can be called later on


```

26     bird_up = True
27     bird_uptwo = True #set bird up to be true for bird two
28     up = False
29     game_over = False
30     score = 0
31     number_of_updates = 0

```

- 5) Make sure to draw the duplicated characters so it can be seen in the screen

```

73     def draw():
74         screen.blit('background', (0,0))
75         if not game_over:
76             balloon.draw()
77             bird.draw()
78             birdtwo.draw() #draw another bird
79             house.draw()
80             housetwo.draw()#draw another house
81             tree.draw()
82             treetwo.draw()
83             screen.draw.text('Score: ' + str(score), (700, 5), color='black')
84         else:
85             display_high_scores()

```

- 6) The def flap includes the second bird so that it can flap

```

91     def flap():
92         global bird_up, bird_uptwo
93         if bird_up:
94             bird.image = 'bird-down'
95             bird_up = False
96         else:
97             bird.image = 'bird-up'
98             bird_up = True
99
100         #add another bird to flap
101         if bird_uptwo:
102             birdtwo.image = 'bird-down'
103             bird_uptwo = False
104         else:
105             birdtwo.image = 'bird-up'
106             bird_uptwo = True
107

```

7) Make sure there are constraints for the other obstacles with how they score.

```
135         #add another bird and the constraints
136         if birdtwo.x > 0:
137             birdtwo.x -= 6 #made the bird fly faster
138             if number_of_updates == 12:
139                 flap()
140                 number_of_updates = 0
141             else:
142                 number_of_updates += 1
143         else:
144             birdtwo.x = randint(400, 1200)
145             birdtwo.y = randint(5, 100)
146             score += 1
147             number_of_updates = 0
148
149         if house.right > 0:
150             house.x -= 2
151             score_up()
152         else:
153             house.x = randint(800, 1600) #800
154
155
156         if tree.right > 0:
157             tree.x -= 2
158             score_up()
159         else:
160             tree.x = randint(800, 1600) #800
161         #add new house and tree constraints
162         if housetwo.right > 0:
163             housetwo.x -= 3
164             score_up()
165         else:
166             housetwo.x = randint(800, 1600) #800
167
168         if treetwo.right > 0:
169             treetwo.x -= 3
170             score_up()
171         else:
172             treetwo.x = randint(800, 1600) #800
173
```

8) Add new collide points for the new obstacles added

```
179
180         if (balloon.collidepoint(bird.x, bird.y) or
181             balloon.collidepoint(house.x, house.y) or
182             balloon.collidepoint(tree.x, tree.y) or
183             balloon.collidepoint(birdtwo.x, birdtwo.y) or
184             balloon.collidepoint(housetwo.x, housetwo.y) or
185             balloon.collidepoint(treetwo.x, treetwo.y)):
186             # subtract_life()
187             game_over = True
188             update_high_scores()
```

9) Adding a new def structure for score_up for every time the balloon passes the tree and house the points will add to the score instead of when the objects move out of the screen.

```
190 def score_up():
191     global score
192     if tree.right == 400 or tree.right == 399:
193         score = score + 1
194     if house.right == 400 or house.right == 399:
195         score = score + 1
196     if treetwo.right == 400 or treetwo.right == 399:
197         score = score + 1
198     if housetwo.right == 400 or housetwo.right == 399:
199         score = score + 1
200
```

10) Results after the modifications

