# **Performance Analysis**

 $\sigma(n) \rightarrow \text{inherently sequential computations}$ 

 $\rho(n) \rightarrow potentially parallel computations$ 

 $\kappa(n, p) \rightarrow communication operations$ 

#### **SPEEDUP**

$$speedup = \frac{sequential\ executio\ time}{parallel\ execution\ time}$$

$$\psi(n,p) = \frac{\sigma(n) + \varphi(n)}{\sigma(n) + \frac{\varphi(n)}{p} + \varkappa(n,p)}$$

#### **EFFICIENCY**

$$speedup = \frac{\sigma(n)}{p \cdot \varphi(n)}$$
$$speedup = \frac{speedup}{processors}$$

**AMDAHL'S LAW** 
$$f = \frac{\sigma(n)}{\sigma(n) + \varphi(n)} = share \ of \ parallel \ code$$
 
$$\psi \leq \frac{1}{f + \frac{1-f}{p}}$$

Example: 95% of the code can be executed in parallel  $\psi \leq \frac{1}{0.05 - \frac{1 - 0.05}{8}}$ 

$$\psi \le \frac{1}{0.05 - \frac{1 - 0.05}{8}}$$

Amdahl's law ignores the time needed for communication and thus themes to overestimate the speedup.

#### **ISOEFFICIENCY METRIC**

compute total amount of overhead 
$$T_0(n,p) = (p-1) \cdot \sigma(n) + p \cdot \varkappa(n,p)$$

Substitute into speedup formula

$$\psi(n,p) \le \frac{p \cdot (\sigma(n) + \phi(n))}{\sigma(n) + \phi(n) + T_0(n,p)}$$

assume efficiency stays constant

$$T(n,1) = \sigma(n) + \phi(n)$$

determine relation between sequential execution time and overhead

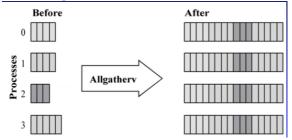
$$T(n,1) \ge C \cdot T_0(n,p)$$

This is the isoefficency relation

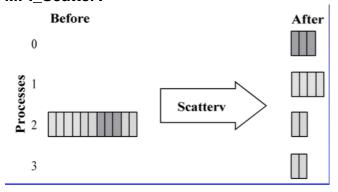
# **MPI**

A communicator in MPI is a process group.

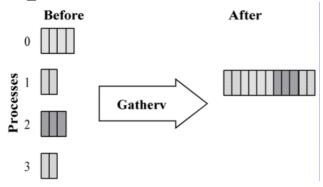
# MPI\_Allgatherv



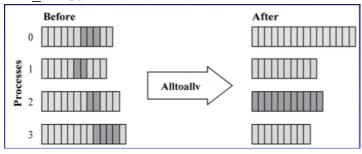
# MPI\_Scatterv



## **MPI\_Gatherv**



## MPI\_Alltoallv



# MPI\_Abort

Aborts the execution and terminates all MPI processes

#### **MPI** Irec

Non-blocking receive. Using MPI\_Request structure pointer to store the received data

### MPI\_Recv

Blocking receive

### MPI\_Wait

Waits until a message is received and stored in the given MPI\_Request structure

#### MPI\_Isend

Non-blocking send

### MPI\_Send

Blocking send

#### **MPI Probe**

Blocks until a message is available to be received

# Floyd's Algorithm

Finds the shortest paths for all pairs in a given matrix:

	Α	В	C	D	E
A	0	6		6	4
В	4	0		10	8
C	12	6	0		1
D	7		10	0	11
Ε	9	5	12	2	0

## Algorithm:

```
for k \leftarrow 0 to n-1
for i \leftarrow 0 to n-1
for j \leftarrow 0 to n-1
a[i,j] \leftarrow \min(a[i,j], a[i,k] + a[k,j])
endfor
endfor
endfor
```

Parallel execution possible by limiting n and setting the start values to something greater than 0. Floyd's algorithm has a poor scalability because the memory needed increases with each process.

# Manager/Worker MPI Program

Manager/Worker MPI programs have an early control flow split.

Workers are coordinated by manager, manager dispatches tasks to workers and collects results. A separate worker comunicator can be created using MPI\_Comm\_split with the split\_key MPI\_UNDEFINED (global communicator is split, new communicator includes all processes but manager). Allows manager to send messages to all processes but to exclude himself.

Allows dynamic number of tasks to be assigned to a number of worker processes. No communication between workers. Variable task lengths.