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Πρόβλημα 1

Μαθηματικό μοντέλο:

$$m * v' = (f1 + f2) - b_x * |v| * v \quad (1)$$

$$I_z * \theta'' = \frac{d}{2}(f2 - f1) - b_\theta * |\theta'| * \theta' \Rightarrow \theta'' = \frac{\frac{d}{2}(f2 - f1) - b_\theta * |\theta'| * \theta'}{I_z} \quad (2)$$

$$v(0) = 0 \quad (3)$$

$$\theta'(0) = 0, \theta(0) = \theta_0 \quad (4)$$

Τιμες:

$$[f1, f2]^T = [4710/7000 = 0.672, 4710/7000 = 0.672]^T \text{ N}$$

$$[f1, f2]^T = [4710/7000 = 0.672, 4710/8000 = 0.589]^T \text{ N}$$

$$\theta_0 = 4710/20000 = 0.235$$

$$b_x = 3 - (4710/5000) = 3 - 0.942 = 2.058$$

$$b_\theta = 5 - (4710/5000) = 5 - 0.942 = 4.058$$

$$m = 9 \text{ kg}$$

$$d = 1 \text{ m}$$

$$I_z = 0.38 \text{ kg} \cdot \text{m}^2$$

*Εγινε στρογγυλοποιηση στα τρια δεκαδικα ψηφια .

A)

Τυποί:

Μέθοδο του Euler: ($y_{n+1} = y_n + h * y'_n$) για $[f1, f2]^T = [0.672, 0.672]^T$

$$(1) \Rightarrow V_{n+1} = V_n + h * V'_n \Rightarrow V_{n+1} = V_n + h \frac{(f1+f2)-bx*|V_n|*V_n}{m} \Rightarrow$$

$$V_{n+1} = \frac{V_n * m + h * (f1 + f2) - bx * |V_n| * V_n}{m} \Rightarrow (\text{αντικατάσταση}) \Rightarrow$$

$$V_{n+1} = \frac{V_n * 9 + h * (0.672 + 0.672) - 2.058 * |V_n| * V_n}{9} = \frac{V_n * 9 + h * 1.344 - 2.058 * |V_n| * V_n}{9}$$

$$(1), (3) \Rightarrow V_1 = \frac{V_0 * 9 + h * 1.344 - 2.058 * |V_0| * V_0}{9} = \frac{0 + h * 1.344 - 0}{9} \Rightarrow V_1 = \frac{h * 1.344}{9}$$

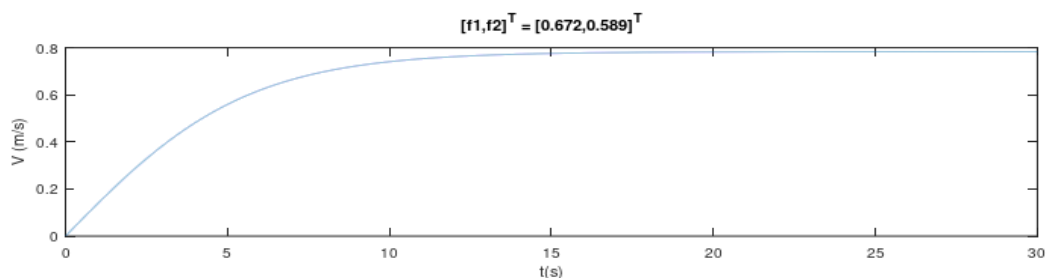
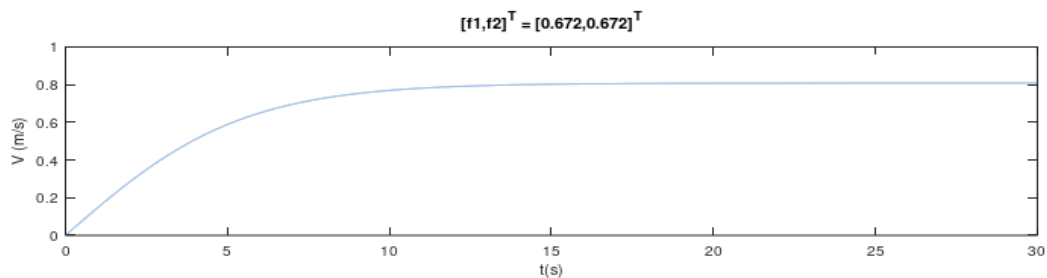
Για $[f1, f2]^T = [0.672, 0.589]^T$

$$(1) \Rightarrow V_{n+1} = V_n + h * V'_n \Rightarrow V_{n+1} = V_n + h \frac{(f1+f2)-bx*|V_n|*V_n}{m} \Rightarrow$$

$$V_{n+1} = \frac{V_n * m + h * (f1 + f2) - bx * |V_n| * V_n}{m} \Rightarrow (\text{αντικατάσταση}) \Rightarrow$$

$$V_{n+1} = \frac{V_n * 9 + h * (0.672 + 0.589) - 2.058 * |V_n| * V_n}{9} = \frac{V_n * 9 + h * 1.261 - 2.058 * |V_n| * V_n}{9}$$

$$(1), (3) \Rightarrow V_1 = \frac{V_0 * 9 + h * 1.344 - 2.058 * |V_0| * V_0}{9} = \frac{0 + h * 1.261 - 0}{9} \Rightarrow V_1 = \frac{h * 1.261}{9}$$



Για τη (2) και για $[f1, f2]^T = [0.672, 0.672]^T \Rightarrow$

Εστω $\theta'' = y'$ και $\theta' = y \Rightarrow (2) \Rightarrow y' = \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y|*y}{Iz}$, με $\theta'(0) = y(0) = 0$

$$y_{n+1} = y + h * y'_n \Rightarrow (2) \Rightarrow y_{n+1} = y_n + h * \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |y_n| * y_n}{Iz}$$

$$y_1 = y_0 + h * \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |y_0| * y_0}{Iz} \Rightarrow (\text{αντικατάσταση}) \Rightarrow$$

$$y_1 = 0 + h * \frac{\frac{1}{2}(0.672 - 0.672) - 4.058 * |0| * 0}{0.38} = 0 \Rightarrow y_1 = 0 = \theta'_1 \quad (5)$$

$$\theta'_{n+1} = \theta'_n + h * \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |\theta'_n| * \theta'_n}{Iz} \quad (6)$$

$$\theta_{n+1} = \theta_n + h * \theta'_n \xRightarrow{(6)} \theta_{n+1} = \theta_n + h * (\theta'_{n+1} - h \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |\theta'_n| * \theta'_n}{Iz}) \text{ αντικατάσταση} \Rightarrow$$

$$\theta_1 = \theta_0 + h * (\theta'_1 - h \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |\theta'_0| * \theta'_0}{Iz}) \xRightarrow{(5)}$$

$$\theta_1 = \theta_0 + h * \left(0 - h \frac{\frac{1}{2}(0) - 4.058 * |0| * 0}{0.38} \right) \Rightarrow \theta_1 = \theta_0 + 0 = \theta_0 = 0.235$$

Για τη (2) και για $[f1, f2]^T = [0.672, 0.589]^T \Rightarrow$

Εστω $\theta'' = y'$ και $\theta' = y \Rightarrow (2) \Rightarrow y' = \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y|*y}{Iz}$, με $\theta'(0) = y(0) = 0$

$$y_{n+1} = y + h * y'_n \Rightarrow (2) \Rightarrow y_{n+1} = y_n + h * \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |y_n| * y_n}{Iz}$$

$$y_1 = y_0 + h * \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |y_0| * y_0}{Iz} \Rightarrow (\text{αντικατάσταση}) \Rightarrow$$

$$y_1 = 0 + h * \frac{\frac{1}{2}(0.589 - 0.672) - 4.058 * |0| * 0}{0.38} = 0 \Rightarrow y_1 = -0.0415 * h = \theta'_1 \quad (5)$$

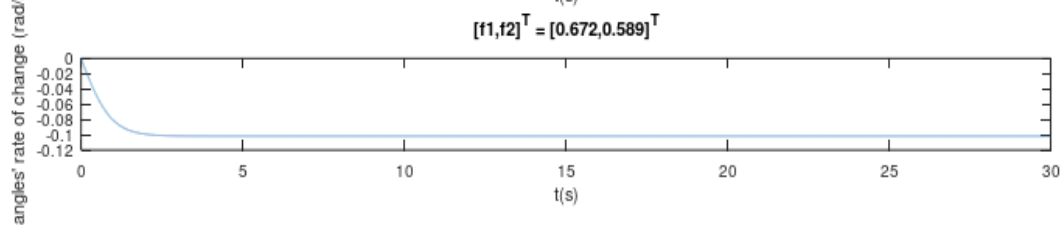
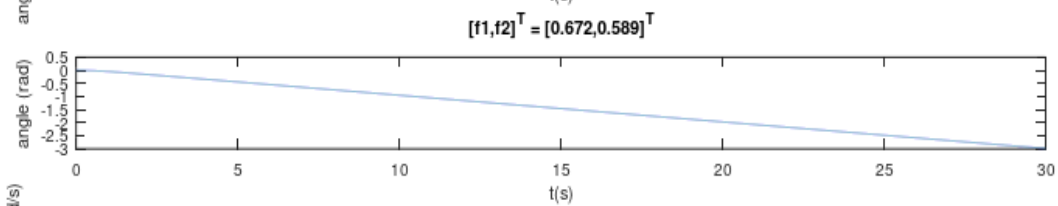
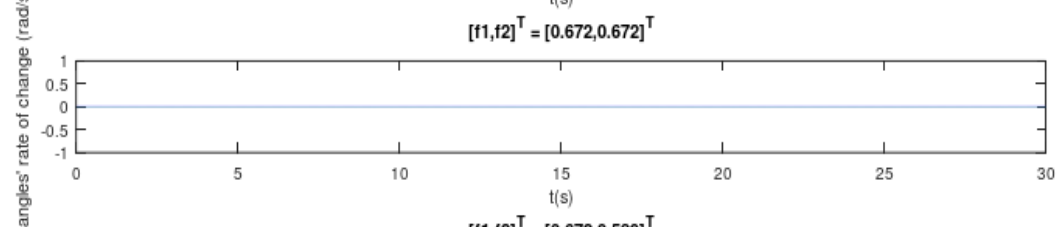
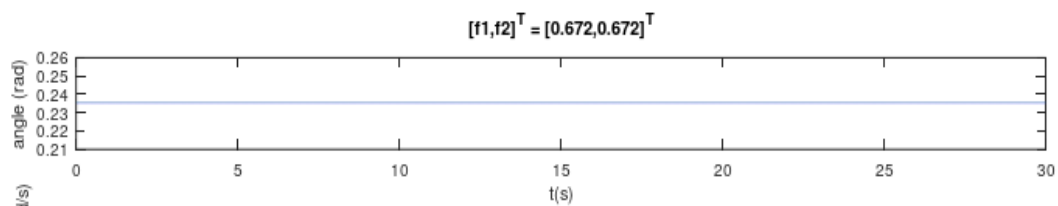
$$\theta'_{n+1} = \theta'_n + h * \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |\theta'_n| * \theta'_n}{Iz} \quad (6)$$

$$\theta_{n+1} = \theta_n + h * \theta'_n \xRightarrow{(6)} \theta_{n+1} = \theta_n + h * (\theta'_{n+1} - h \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |\theta'_n| * \theta'_n}{Iz}) \text{ αντικατάσταση} \Rightarrow$$

$$\theta_1 = \theta_0 + h * \left(\theta'_1 - h \frac{\frac{d}{2}(f2-f1) - b_{\theta} * |\theta'_0| * \theta'_0}{Iz} \right) \xRightarrow{(5)}$$

$$\theta_1 = \theta_0 + h * \left(-0.0415 * h - h \frac{\frac{1}{2}(0.589 - 0.672) - 4.058 * |0| * 0}{0.38} \right) \Rightarrow$$

$$\theta_1 = \theta_0 + h * (-0.0415 * h - 0.109 * h) = \theta_0 + h * (-0.1505 * h) \Rightarrow \theta_1 = 0.235 - 0.1505 * h^2$$



Τροποποιημένη μέθοδο του Euler $y_{n+1} = y_n + h * f(x_n + \frac{h}{2}, y_n + \frac{h}{2} f(x_n, y_n))$

Για $[f1, f2]^T = [0.672, 0.672]^T$:

$$\begin{aligned}
 (1) \Rightarrow V_{n+1} &= V_n + h * f\left(x_n + \frac{h}{2}, V_n + \frac{h}{2} f(x_n, y_n)\right) \Rightarrow \\
 \Rightarrow V_{n+1} &= V_n + h * f\left(x_n + \frac{h}{2}, V_n + \frac{h}{2} \frac{(f1 + f2) - bx * |V_n| * V_n}{m}\right) (1) \\
 \Rightarrow V_{n+1} &= V_n + h * \frac{(f1 + f2) - bx * \left(V_n + \frac{h}{2} \frac{(f1 + f2) - bx * |V_n| * V_n}{m}\right) * \left(V_n + \frac{h}{2} \frac{(f1 + f2) - bx * |V_n| * V_n}{m}\right)}{m} \Rightarrow \\
 (\text{αντικατάσταση}) \\
 \Rightarrow \\
 \Rightarrow V_{n+1} &= V_n + h * \frac{1.344 - 2.058 * \left(V_n + \frac{h}{2} \frac{1.344 - 2.058 * |V_n| * V_n}{9}\right) * \left(V_n + \frac{h}{2} \frac{1.344 - 2.058 * |V_n| * V_n}{9}\right)}{9}
 \end{aligned}$$

$$\begin{aligned}
 (1), (3) (\text{αντικατάσταση}) \\
 \Rightarrow \\
 \Rightarrow V_1 &= V_0 + h * \frac{1.344 - 2.058 * \left(V_0 + \frac{h}{2} \frac{1.344 - 2.058 * |V_0| * V_0}{9}\right) * \left(V_0 + \frac{h}{2} \frac{1.344 - 2.058 * |V_0| * V_0}{9}\right)}{9} \\
 \Rightarrow V_1 &= 0 + h * \frac{1.344 - 2.058 * \left(0 + \frac{h}{2} \frac{1.344 - 2.058 * |0| * 0}{9}\right) * \left(0 + \frac{h}{2} \frac{1.344 - 2.058 * |0| * 0}{9}\right)}{9} \\
 \Rightarrow V_1 &= h * \frac{1.344 - 2.058 * \left(\left|\frac{h}{2} \frac{1.344}{9}\right| * \left(\frac{h}{2} \frac{1.344}{9}\right)\right)}{9} \Rightarrow \\
 \Rightarrow V_1 &= h * \frac{1.344 - 2.058 * \left(|h| * \left(h * \left(\frac{1.344}{18}\right)^2\right)\right)}{9} \Rightarrow \\
 \Rightarrow V_1 &= \frac{1.344 * h - |h| * h^2 * 0.011}{9}
 \end{aligned}$$

Για $[f1, f2]^T = [0.672, 0.589]^T$:

$$\begin{aligned}
 (1) \Rightarrow V_{n+1} &= V_n + h * f\left(x_n + \frac{h}{2}, V_n + \frac{h}{2} f(x_n, y_n)\right) \Rightarrow \\
 \Rightarrow V_{n+1} &= V_n + h * f\left(x_n + \frac{h}{2}, V_n + \frac{h}{2} \frac{(f1 + f2) - bx * |V_n| * V_n}{m}\right) (1) \\
 \Rightarrow V_{n+1} &= V_n + h * \frac{(f1 + f2) - bx * \left(V_n + \frac{h}{2} \frac{(f1 + f2) - bx * |V_n| * V_n}{m}\right) * \left(V_n + \frac{h}{2} \frac{(f1 + f2) - bx * |V_n| * V_n}{m}\right)}{m} \Rightarrow
 \end{aligned}$$

(αντικατάσταση)

=>

$$\Rightarrow V_{n+1} = V_n + h * \frac{1.261 - 2.058 * \left(\left| V_n + \frac{h}{2} \frac{1.261 - 2.058 * |V_n| * V_n}{9} \right| * \left(V_n + \frac{h}{2} \frac{1.261 - 2.058 * |V_n| * V_n}{9} \right) \right)}{9}$$

(1), (3) (αντικατάσταση)

=>

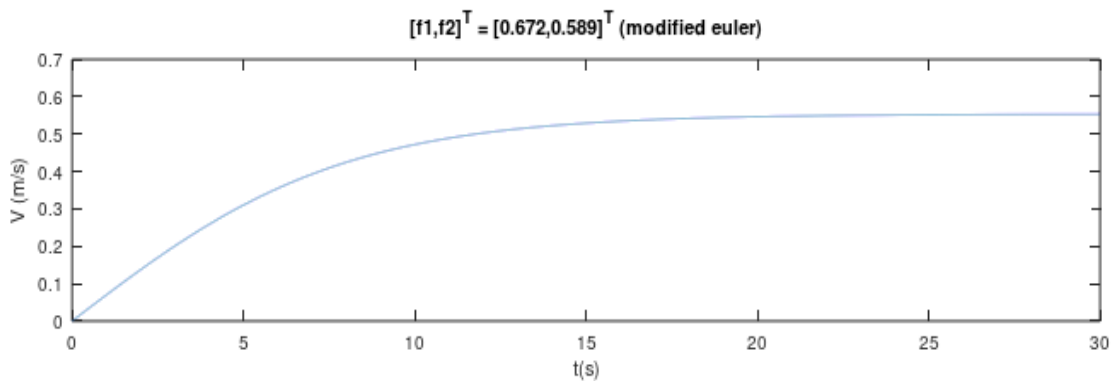
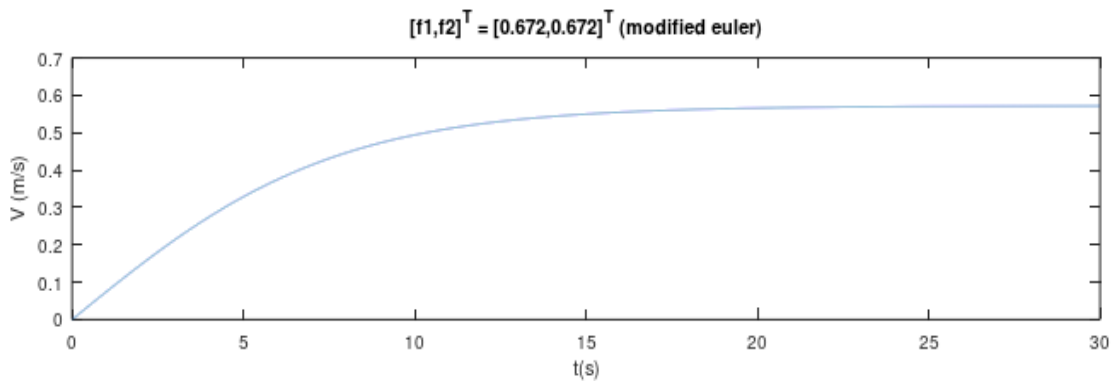
$$\Rightarrow V_1 = V_0 + h * \frac{1.261 - 2.058 * \left(\left| V_0 + \frac{h}{2} \frac{1.261 - 2.058 * |V_0| * V_0}{9} \right| * \left(V_0 + \frac{h}{2} \frac{1.261 - 2.058 * |V_0| * V_0}{9} \right) \right)}{9}$$

$$\Rightarrow V_1 = 0 + h * \frac{1.261 - 2.058 * \left(\left| 0 + \frac{h}{2} \frac{1.261 - 2.058 * |0| * 0}{9} \right| * \left(0 + \frac{h}{2} \frac{1.261 - 2.058 * |0| * 0}{9} \right) \right)}{9}$$

$$\Rightarrow V_1 = h * \frac{1.261 - 2.058 * \left(\left| \frac{h}{2} \frac{1.261}{9} \right| * \left(\frac{h}{2} \frac{1.261}{9} \right) \right)}{9} \Rightarrow$$

$$\Rightarrow V_1 = h * \frac{1.261 - 2.058 * \left(|h| * \left(h * \left(\frac{1.261}{18} \right)^2 \right) \right)}{9} \Rightarrow$$

$$\Rightarrow V_1 = \frac{1.261 * h - |h| * h^2 * 0.005}{9}$$



Τροποποιημένη μέθοδο του Euler $y_{n+1} = y_n + h * f(x_n + \frac{h}{2}, y_n + \frac{h}{2} f(x_n, y_n))$

Για $[f1, f2]^T = [0.672, 0.672]^T$:

Εστω $\theta'' = y'$ και $\theta' = y \Rightarrow (2) \Rightarrow y' = \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y|*y}{Iz}$, με $\theta'(0) = y(0) = 0$ (5)

$$(2) \Rightarrow y_{n+1} = y_n + h * f\left(x_n + \frac{h}{2}, y_n + \frac{h}{2} f(x_n, y_n)\right) \Rightarrow$$

$$\Rightarrow y_{n+1} = y_n + h * f\left(x_n + \frac{h}{2}, y_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y_n|*y_n}{Iz}\right) \Rightarrow$$

$$y_{n+1} = y_n + h * \frac{\frac{d}{2}(f2-f1)-b_{\theta}* \left| y_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y_n|*y_n}{Iz} \right| * (y_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y_n|*y_n}{Iz})}{Iz}$$

$$(αντικατασταση) \Rightarrow y_{n+1} = y_n + h * \frac{0 - 4.058 * \left| y_n + \frac{h}{2} \frac{0 - 4.058 * |y_n| * y_n}{0.38} \right| * (y_n + \frac{h}{2} \frac{0 - 4.058 * |y_n| * y_n}{0.38})}{0.38}$$

$$(αντικατασταση) \Rightarrow y_1 = y_0 + h * \frac{-4.058 * \left| y_0 + \frac{h}{2} \frac{-4.058 * |y_0| * y_0}{0.38} \right| * (y_0 + \frac{h}{2} \frac{-4.058 * |y_0| * y_0}{0.38})}{0.38}$$

$$(2), (5) \Rightarrow y_1 = 0 + h * \frac{-4.058 * |0 + 0| * (0 + 0)}{0.38} = 0 = \theta'_1 \quad (6), \text{Οποτε εχουμε:}$$

$$\theta'_{n+1} = \theta'_n + h * \frac{\frac{d}{2}(f2-f1)-b_{\theta}* \left| \theta'_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|\theta'_n|*\theta'_n}{Iz} \right| * (\theta'_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|\theta'_n|*\theta'_n}{Iz})}{Iz}$$

$$(αντικατασταση) \Rightarrow \theta'_{n+1} = \theta'_n + h * \frac{-4.058 * \left| \theta'_n + \frac{h}{2} \frac{-4.058 * |\theta'_n| * \theta'_n}{0.38} \right| * (\theta'_n + \frac{h}{2} \frac{-4.058 * |\theta'_n| * \theta'_n}{0.38})}{0.38}$$

$$\theta'_{n+1} - h * \frac{-4.058 * \left| \theta'_n + \frac{h}{2} \frac{-4.058 * |\theta'_n| * \theta'_n}{0.38} \right| * (\theta'_n + \frac{h}{2} \frac{-4.058 * |\theta'_n| * \theta'_n}{0.38})}{0.38} = \theta'_n = f(x_n, y_n)$$

$$\theta_{n+1} = \theta_n + h * f\left(x_n + \frac{h}{2}, \theta_n + \frac{h}{2} \theta'_n\right) \xRightarrow{(αντικατασταση), (\theta_0 = 0.235)} (2), (4), (6)$$

$$\theta_1 = \theta_0 + h * f\left(x_n + \frac{h}{2}, \theta_0 + \frac{h}{2} \theta'_0\right) = \theta_0 + h * f\left(x_n + \frac{h}{2}, \theta_0 + \frac{h}{2} 0\right) = \theta_0 + h * f\left(x_n + \frac{h}{2}, \theta_0\right) \Rightarrow$$

$$\theta_1 = \theta_0 + h * \theta'_1 - h * \frac{-4.058 * \left| \theta'_0 + \frac{h}{2} \frac{-4.058 * |\theta'_0| * \theta'_0}{0.38} \right| * (\theta'_0 + \frac{h}{2} \frac{-4.058 * |\theta'_0| * \theta'_0}{0.38})}{0.38}$$

$$\theta_1 = \theta_0 + h * 0 \xRightarrow{(6)} \theta_1 = 0.235$$

$$\Gamma\alpha [f1, f2]^T = [0.672, 0.589]^T$$

$$\text{Εστω } \theta'' = y' \text{ και } \theta' = y \Rightarrow (2) \Rightarrow y' = \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y|*y}{Iz}, \mu\epsilon \theta'(0) = y(0) = 0 \quad (5)$$

$$(2) \Rightarrow y_{n+1} = y_n + h * f\left(x_n + \frac{h}{2}, y_n + \frac{h}{2} f(x_n, y_n)\right) \Rightarrow$$

$$\Rightarrow y_{n+1} = y_n + h * f\left(x_n + \frac{h}{2}, y_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y_n|*y_n}{Iz}\right) \Rightarrow$$

$$y_{n+1} = y_n + h * \frac{\frac{d}{2}(f2-f1)-b_{\theta}* \left| y_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y_n|*y_n}{Iz} \right| * \left(y_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|y_n|*y_n}{Iz} \right)}{Iz}$$

(αντικατάσταση)

=>

$$y_{n+1} = y_n + h * \frac{-0.0415 - 4.058 * \left| y_n + \frac{h}{2} \frac{-0.0415 - 4.058 * |y_n| * y_n}{0.38} \right| * \left(y_n + \frac{h}{2} \frac{-0.0415 - 4.058 * |y_n| * y_n}{0.38} \right)}{0.38}$$

(αντικατάσταση)

=>

(2), (5)

$$y_1 = y_0 + h * \frac{-0.0415 - 4.058 * \left| y_0 + \frac{h}{2} \frac{-0.0415 - 4.058 * |y_0| * y_0}{0.38} \right| * \left(y_0 + \frac{h}{2} \frac{-0.0415 - 4.058 * |y_0| * y_0}{0.38} \right)}{0.38}$$

$$y_1 = h * \frac{-0.0415 - 4.058 * \left| \frac{h}{2} * \frac{-0.0415}{0.38} \right| * \left(\frac{h}{2} * \frac{-0.0415}{0.38} \right)}{0.38} =$$

$$y_1 = \frac{-0.042 * h + 0.012 * |h| * h^2}{0.38} = \theta'_1 \quad (6), \text{Οποτε εχουμε:}$$

$$\theta'_{n+1} = \theta'_n + h * \frac{\frac{d}{2}(f2-f1)-b_{\theta}* \left| \theta'_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|\theta'_n|*\theta'_n}{Iz} \right| * \left(\theta'_n + \frac{h}{2} \frac{\frac{d}{2}(f2-f1)-b_{\theta}*|\theta'_n|*\theta'_n}{Iz} \right)}{Iz}$$

(αντικατάσταση)

=>

$$\theta'_{n+1} = \theta'_n + h * \frac{-0.0415 - 4.058 * \left| \theta'_n + \frac{h}{2} \frac{-0.0415 - 4.058 * |\theta'_n| * \theta'_n}{0.38} \right| * \left(\theta'_n + \frac{h}{2} \frac{-0.0415 - 4.058 * |\theta'_n| * \theta'_n}{0.38} \right)}{0.38}$$

$$\theta'_{n+1} - h * \frac{-0.0415 - 4.058 * \left| \theta'_n + \frac{h}{2} \frac{-0.0415 - 4.058 * |\theta'_n| * \theta'_n}{0.38} \right| * \left(\theta'_n + \frac{h}{2} \frac{-0.0415 - 4.058 * |\theta'_n| * \theta'_n}{0.38} \right)}{0.38} = \theta'_n$$

$$\theta_{n+1} = \theta_n + h * f\left(x_n + \frac{h}{2}, \theta_n + \frac{h}{2} \theta'_n\right) \xRightarrow{\text{(αντικατάσταση)}, (\theta_0 = 0.235)} \text{(2), (4), (6)}$$

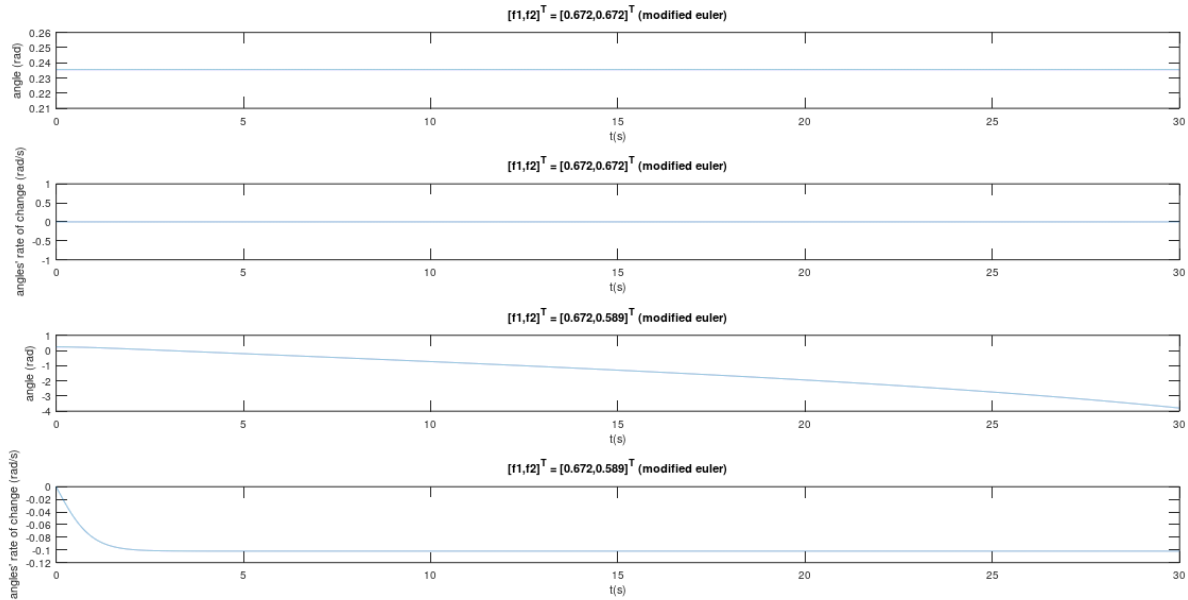
$$\theta_1 = \theta_0 + h * f\left(x_n + \frac{h}{2}, \theta_0 + \frac{h}{2} \theta'_0\right) = \theta_0 + h * f\left(x_n + \frac{h}{2}, \theta_0 + \frac{h}{2} 0\right) = \theta_0 + h * f\left(x_n + \frac{h}{2}, \theta_0\right) \Rightarrow$$

$$\theta_1 = \theta_0 + h * \frac{-0.0415 - 4.058 * \left| \theta_0 + \frac{h}{2} \frac{-0.0415 - 4.058 * |\theta_0| * \theta_0}{0.38} \right| * \left(\theta_0 + \frac{h}{2} \frac{-0.0415 - 4.058 * |\theta_0| * \theta_0}{0.38} \right)}{0.38}$$

$$\theta_1 = 0.235 + h * \frac{-0.0415 - 4.058 * \left| 0.235 + \frac{h}{2} \frac{-0.0415 - 4.058 * 0.056}{0.38} \right| * \left(0.235 + \frac{h}{2} \frac{-0.0415 - 4.058 * 0.056}{0.38} \right)}{0.38}$$

$$\theta_1 = 0.235 + \frac{-0.0415 * h + |0.235 - 0.354 * h| * (-0.954 * h + 1.436 * h^2)}{0.38} \Rightarrow$$

$$\theta_1 = 0.235 - 0.109 * h + |0.235 - 0.354 * h| * (-2.511 * h + 3.779 * h^2)$$



Γ)

Τιμές:

$$(f_2 - f_1) = K_p \theta (\theta_{des} - \theta) - K_d \theta (\theta') = 5(-0.471 - \theta) - 19.71(\theta') \quad (5)$$

$$K_p \theta = 5$$

$$K_d \theta = 15 + (4710/1000) = 19.71$$

$$\theta_0 = 0$$

$$\theta_{des} = -4710/10000 = -0.471$$

$$b_\theta = 5 - (4710/5000) = 4.058$$

$$\theta'(0) = 0, \theta(0) = \theta_0 = 0$$

Εξίσωση:

$$\begin{aligned}
 (2) \quad I_z * \theta'' &= \frac{d}{2} (f_2 - f_1) - b_\theta * |\theta'| * \theta' \quad (5) \\
 \Rightarrow \theta'' &= \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta - \frac{d}{2} * K_{d\theta} * \theta' - b_\theta * |\theta'| * \theta'}{I_z} \quad (6) \\
 \theta_0'' &= \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta_0 - \frac{d}{2} * K_{d\theta} * \theta_0' - b_\theta * |\theta_0'| * \theta_0'}{I_z} \Rightarrow \\
 \theta_0'' &= \frac{\frac{d}{2} * K_{p\theta} * \theta_{des}}{I_z} = -3.1
 \end{aligned}$$

Μέθοδο του Euler: ($y_{n+1} = y_n + h * y'_n$):

Εστω

$$\begin{aligned}
 \theta'' &= y' \text{ και } \theta' = y \text{ και } \theta = \int y dy \quad (6) \\
 y' &= \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \int y dy - \frac{d}{2} * K_{d\theta} * y - b_\theta * |y| * y}{I_z}, \text{ με } \theta'(0) = y(0) = 0 \quad (7)
 \end{aligned}$$

$$\text{και } \theta = \int y dy \text{ γινεται, } \theta(0) = \theta_0 = 0 \Rightarrow \frac{y_0^2}{2} + C = 0 \xRightarrow{(7)} C = 0 \quad (8)$$

$$\begin{aligned}
 y_{n+1} &= y_n + h * y'_n \Rightarrow y_{n+1} = y_n + h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \int y dy - \frac{d}{2} * K_{d\theta} * y - b_\theta * |y| * y}{I_z} \text{ (αντικατασταση)} \\
 y_1 &= y_0 + h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \frac{y_0^2}{2} + \frac{d}{2} * K_{p\theta} * C - \frac{d}{2} * K_{d\theta} * y_0 - b_\theta * |y_0| * y_0}{I_z} \Rightarrow
 \end{aligned}$$

$$y_1 = 0 + h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - 0 + 0 - 0 - 0}{I_z} \text{ (αντικατασταση)} \Rightarrow \quad (7), (8)$$

$$\begin{aligned}
 y_1 &= h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des}}{I_z} = h * \frac{\frac{1}{2} * 5 * (-0.471)}{0.38} = h * \frac{-1.178}{0.38} \Rightarrow \\
 \Rightarrow y_1 &= -3.1 * h = \theta'(1) \quad (9)
 \end{aligned}$$

$$\begin{aligned}
 \text{Οποτε εχουμε: } \theta'_{n+1} &= \theta'_n + h * \theta''_n \Rightarrow \\
 \Rightarrow \theta'_{n+1} &= \theta'_n + h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta_n - \frac{d}{2} * K_{d\theta} * \theta'_n - b_\theta * |\theta'_n| * \theta'_n}{I_z} \quad (10)
 \end{aligned}$$

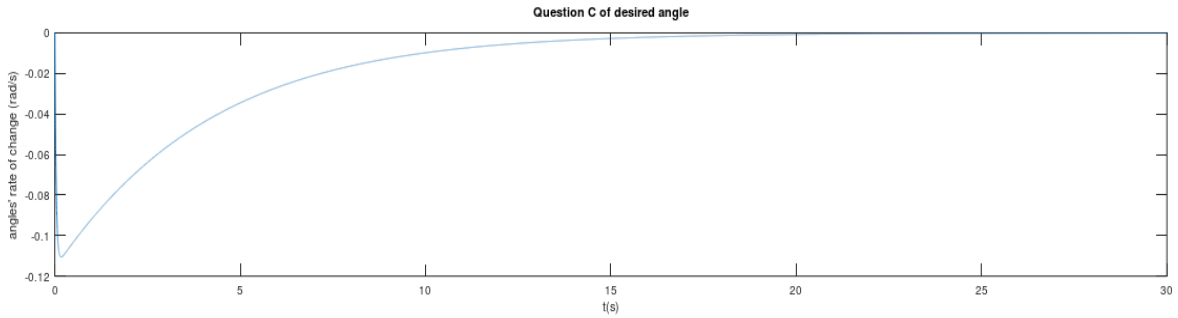
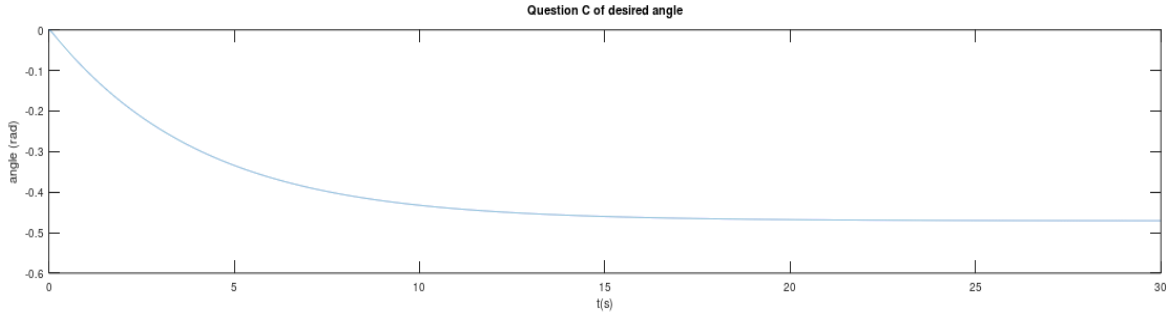
$$\begin{aligned}
 & \text{(αντικατασταση)} \\
 & \Rightarrow \theta'_1 = \theta'_0 + h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta_0 - \frac{d}{2} * K_{d\theta} * \theta'_0 - b_\theta * |\theta'_0| * \theta'_0}{Iz} = \\
 & (7), (9), (10) \\
 & >
 \end{aligned}$$

$$\begin{aligned}
 -3.1 * h &= 0 + h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta_0 - 0 - 0}{Iz} \quad (h \neq 0) \\
 \Rightarrow \\
 -3.1 &= \frac{\frac{1}{2} * 5 * -0.471 - \frac{1}{2} * 5 * \theta_0}{0.38} \Rightarrow -3.1 = \frac{-1.178 - \frac{1}{2} * 5 * \theta_0}{0.38} \Rightarrow
 \end{aligned}$$

$$\theta_0 = \frac{-1.178 + 1.178}{-\frac{1}{2} * 5} = 0$$

$$\theta_{n+1} = \theta_n + h(\theta'_n) = \theta_n + h\left(\frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta_n - Iz * \theta_n'' - b_\theta * |\theta_n'| * \theta_n'}{\frac{d}{2} * K_{d\theta}}\right) \text{(αντικατασταση)} \Rightarrow$$

$$\theta_1 = \theta_0 + h\left(\frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta_0 - Iz * \theta_0'' - b_\theta * |\theta_0'| * \theta_0'}{\frac{d}{2} * K_{d\theta}}\right) = h\left(\frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - Iz * \theta_0''}{\frac{d}{2} * K_{d\theta}}\right) = 0$$



Τροποποιημένη μέθοδο του Euler $y_{n+1} = y_n + h * f(x_n + \frac{h}{2}, y_n + \frac{h}{2} f(x_n, y_n))$

$$\theta'' = y' \text{ και } \theta' = y \text{ και } \theta = \int y dy \quad (6)$$

$$y' = \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \int y dy - \frac{d}{2} * K_{d\theta} * y - b_{\theta} * |y| * y}{I_z}, \mu\epsilon \theta'(0) = y(0) = 0 \quad (7)$$

$$\text{και } \theta = \int y dy \text{ γινεται, } \theta(0) = \theta_0 = 0 \Rightarrow \frac{y_0^2}{2} + C = 0 \stackrel{(7)}{\Rightarrow} C = 0 \quad (8)$$

$$y_{n+1} = y_n + h * f\left(x_n + \frac{h}{2}, y_n + \frac{h}{2} f(x_n, y_n)\right) \Rightarrow$$

$$y_{n+1} = y_n + h * f\left(x_n + \frac{h}{2}, y_n + \frac{h}{2} \left(\frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \int y dy - \frac{d}{2} * K_{d\theta} * y_n - b_{\theta} * |y_n| * y_n}{I_z}\right)\right) \Rightarrow$$

(αντικατάσταση)
 \Rightarrow

$$y_1 = y_0 + h * f\left(x_n + \frac{h}{2}, y_0 + \frac{h}{2} \left(\frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \int y dy - \frac{d}{2} * K_{d\theta} * y_0 - b_{\theta} * |y_0| * y_0}{I_z}\right)\right) \Rightarrow$$

(αντικατάσταση)
 \Rightarrow
(7), (8)

$$y_1 = h * f\left(x_n + \frac{h}{2}, \frac{h}{2} \left(\frac{\frac{d}{2} * K_{p\theta} * \theta_{des}}{I_z}\right)\right) \stackrel{(αντικατάσταση)}{\Rightarrow} y_1 = h * f\left(x_n + \frac{h}{2}, \frac{h}{2} \left(\frac{\frac{1}{2} * 5 * (-0.471)}{0.38}\right)\right) \Rightarrow$$

$$y_1 = h * f\left(x_n + \frac{h}{2}, \frac{-1.178 * h}{0.76}\right) \Rightarrow$$

$$y_1 = h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \int \frac{-1.178 * h}{0.76} dy - \frac{1}{2} * K_{d\theta} * \frac{-1.178 * h}{0.76} - b_{\theta} * \left|\frac{-1.178 * h}{0.76}\right| * \frac{-1.178 * h}{0.76}}{I_z}$$

$$\Rightarrow y_1 = h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \left(-\frac{31}{20} * h * y_0 + C\right) - \frac{1}{2} * K_{d\theta} * \frac{-1.178 * h}{0.76} - b_{\theta} * \left|\frac{-1.178 * h}{0.76}\right| * \frac{-1.178 * h}{0.76}}{I_z}$$

(αντικατάσταση)
 \Rightarrow
(7), (8)

$$y_1 = h * \frac{\frac{1}{2} * 5 * (-0.471) - \frac{1}{2} * 19.71 * \frac{-1.178 * h}{0.76} - 4.058 * \left|\frac{-1.178 * h}{0.76}\right| * \frac{-1.178 * h}{0.76}}{0.38}$$

$$y_1 = \frac{-1.178 * h + 15.275 * h^2 + 9.751 * |h| * h^2}{0.38} = -3.1 * h + 40.2 * h^2 + 25.66 * |h| * h^2 = \theta_1' \quad (9)$$

Ακομα:

$$\theta_0'' = \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta_0 - \frac{d}{2} * K_{d\theta} * \theta_0' - b_{\theta} * |\theta_0'| * \theta_0'}{I_z} = \frac{\frac{d}{2} * K_{p\theta} * \theta_{des}}{I_z} = -3.1$$

Και

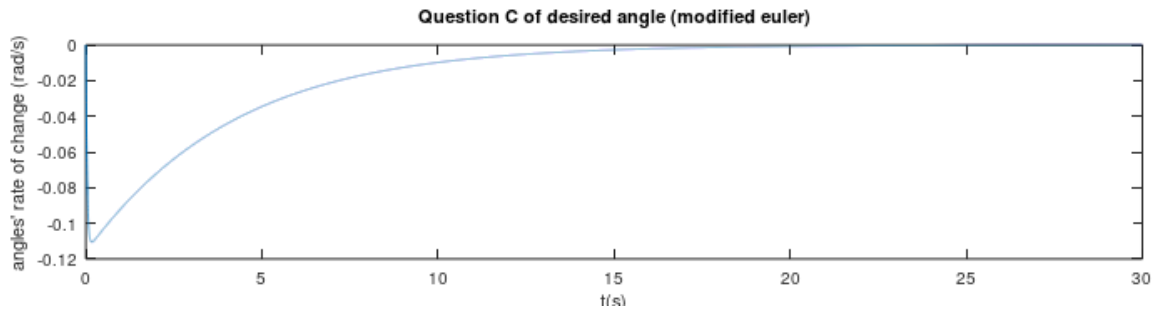
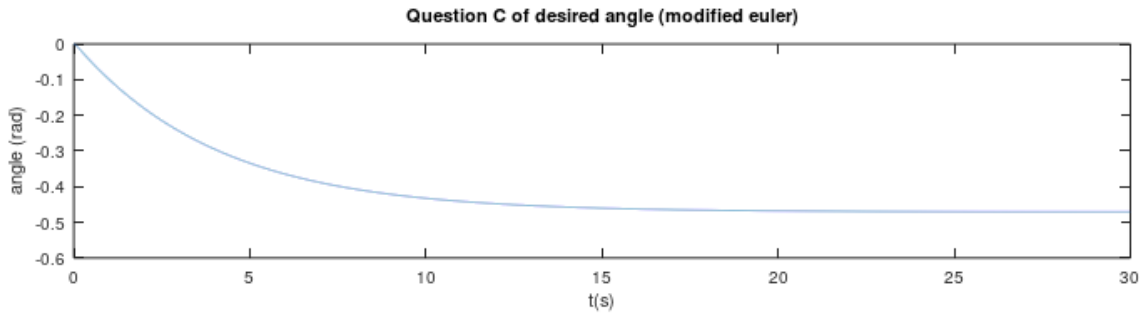
$$\theta' = \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta - I_z * \theta'' - b_{\theta} * |\theta'| * \theta'}{\frac{d}{2} * K_{d\theta}} \quad (10)$$

Κατευθειαν αντικατασταση:

$$\theta_1 = \theta_0 + h * f\left(x_n + \frac{h}{2}, \theta_0 + \frac{h}{2} \theta_0'\right) = \theta_0 + h * f\left(x_n + \frac{h}{2}, \theta_0\right) \Rightarrow (10)$$

$$\theta_1 = \theta_0 + h * \frac{\frac{d}{2} * K_{p\theta} * \theta_{des} - \frac{d}{2} * K_{p\theta} * \theta_0 - I_z * \theta_0'' - b_{\theta} * |\theta_0| * \theta_0}{\frac{d}{2} * K_{d\theta}} \text{ (αντικατασταση)} \Rightarrow$$

$$\theta_1 = h * \frac{\frac{1}{2} * 5 * -0.471 - 0.38 * (-3.1)}{\frac{1}{2} * 19.71} = h * \frac{-1.178 + 1.178}{\frac{1}{2} * 19.71} = 0$$



ΠΡΟΒΛΗΜΑ 2:

A') Από πίνακα Laplace : $U(s) = \frac{-0.471}{s}$, εφροσον $u(t)$ σταθερο

$$H(s) = \frac{Y(s)}{U(s)} = \frac{L\{y(t)\}}{L\{u(t)\}}$$

$$Iz * \theta'' + \frac{d}{2} * K_{d\theta} * \theta' + b_{\theta} * \theta' + \frac{d}{2} * K_{p\theta} * \theta = \frac{d}{2} * K_{p\theta} * \theta_{des}$$

$$(L.T) \frac{Iz * s^2}{\frac{d}{2} * K_{p\theta}} * Y(s) + \frac{K_{d\theta} * s}{K_{p\theta}} * Y(s) + \frac{b_{\theta} * s}{\frac{d}{2} * K_{p\theta}} * Y(s) + Y(s) = U(s)$$

$$Y(s) \left(\frac{Iz * s^2}{\frac{d}{2} * K_{p\theta}} + \frac{K_{d\theta} * s}{K_{p\theta}} + \frac{b_{\theta} * s}{\frac{d}{2} * K_{p\theta}} + 1 \right) = U(s) \Rightarrow$$

$$H(s) = \frac{Y(s)}{U(s)} = \frac{1}{\frac{Iz * s^2}{\frac{d}{2} * K_{p\theta}} + \frac{\frac{d}{2} * K_{d\theta} * s}{\frac{d}{2} * K_{p\theta}} + \frac{b_{\theta} * s}{\frac{d}{2} * K_{p\theta}} + \frac{\frac{d}{2} * K_{p\theta}}{\frac{d}{2} * K_{p\theta}}} = \frac{\frac{d}{2} * K_{p\theta}}{Iz * s^2 + (\frac{d}{2} * K_{d\theta} + b_{\theta}) * s + \frac{d}{2} * K_{p\theta}}$$

$$Y(s) = \frac{\frac{d}{2} * K_{p\theta}}{Iz * s^2 + (\frac{d}{2} * K_{d\theta} + b_{\theta}) * s + \frac{d}{2} * K_{p\theta}} * \frac{\theta_{des}}{s} = \frac{\theta_{des} * \frac{d}{2} * K_{p\theta}}{Iz * s^3 + (\frac{d}{2} * K_{d\theta} + b_{\theta}) * s^2 + \frac{d}{2} * K_{p\theta} * s}$$

$$Y(s) = \frac{\theta_{des} * \frac{d}{2} * K_{p\theta}}{(Iz * s^2 + (\frac{d}{2} * K_{d\theta} + b_{\theta}) * s + \frac{d}{2} * K_{p\theta}) * s} \quad (\text{διακρινουσα κλπ}) \Rightarrow$$

$$\Delta = \left(\frac{d}{2} * K_{d\theta} + b_{\theta} \right)^2 - 2 * d * Iz * K_{p\theta}$$

Μηδενικα : \nexists δεν υπαρχουν

$$\text{Πολοι : } s_1 = \frac{-\frac{d}{2} * K_{d\theta} - b_{\theta} + \sqrt{\left(\frac{d}{2} * K_{d\theta} + b_{\theta}\right)^2 - 2 * d * Iz * K_{p\theta}}}{2 * Iz}, s_2 = \frac{-\frac{d}{2} * K_{d\theta} - b_{\theta} - \sqrt{\left(\frac{d}{2} * K_{d\theta} + b_{\theta}\right)^2 - 2 * d * Iz * K_{p\theta}}}{2 * Iz}, s_3 = 0$$

$$(\text{αντικατασταση}) \Rightarrow Y(s) = \frac{-0.471 * \frac{1}{2} * 5}{0.38 * s^3 + \left(\frac{1}{2} * 15 + 3.058\right) * s^2 + \frac{1}{2} * 5 * s} = \frac{-1.178}{0.38 * s^3 + 10.558 * s^2 + 2.5 * s}$$

$$Y(s) = \frac{-1.178}{(s+27.545) * (s+0.239) * 0.38 * s}$$

$$\text{Μερικα κλασματα: } \frac{-1.178}{(s+27.545) * (s+0.239) * 0.38 * s} = \left(\frac{\alpha_1}{s+27.545} + \frac{\alpha_2}{s+0.239} + \frac{\alpha_3}{s} \right)$$

$$\alpha_1 = [(s+27.545) \frac{-1.178}{(s+27.545)*(s+0.239)*0.38*s}]_{s=-27.545} = [\frac{-1.178}{(s+0.239)*0.38*s}]_{s=-27.545} = \frac{-1.178}{285.917} = -0.0004$$

$$\alpha_2 = [(s+0.239) \frac{-1.17}{(s+27.545)*(s+0.239)*0.38*s}]_{s=-0.239} = [\frac{-1.178}{(s+27.545)*0.38*s}]_{s=-0.239} = \frac{-1.178}{-2.481} = 0.475$$

$$\alpha_3 = [s \frac{-1.178}{(s+27.545)*(s+0.239)*0.38*s}]_{s=0} = [\frac{-1.178}{0.38*(s+27.545)*(s+0.239)}]_{s=0} = \frac{-1.178}{0.38*(27.545)*(0.239)} = -0.468$$

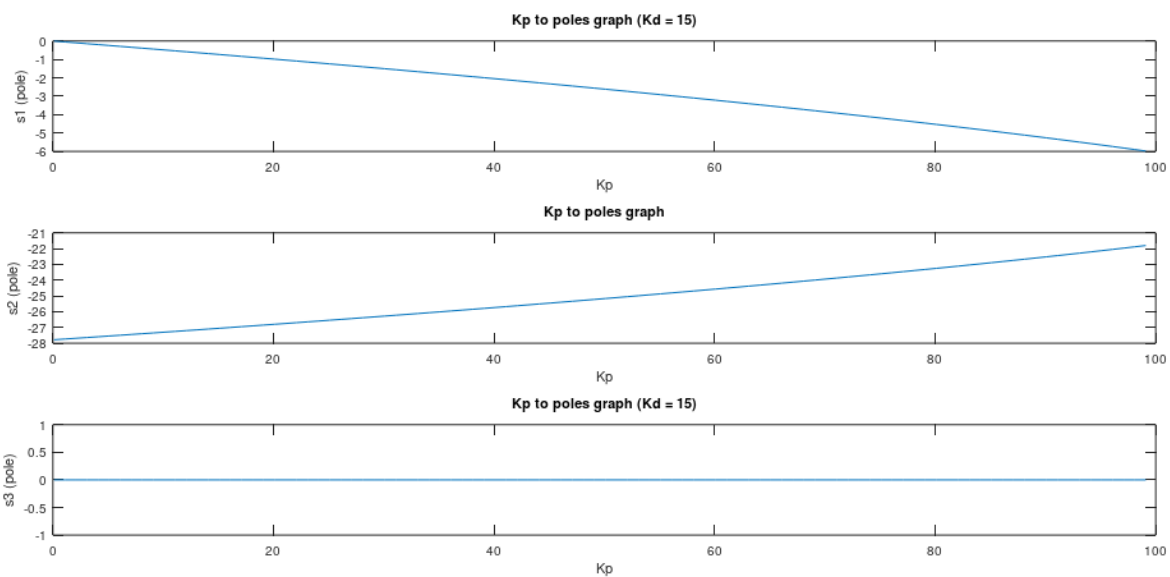
$$Y(s) = \frac{-0.0004}{s+27.545} + \frac{0.475}{s+0.239} + \frac{-0.468}{s}$$

Πολοι : $s_1 = 27.545$, $s_2 = 0.239$, $s_3 = 0$

Μηδενικά : \nexists δεν υπάρχουν

Β')

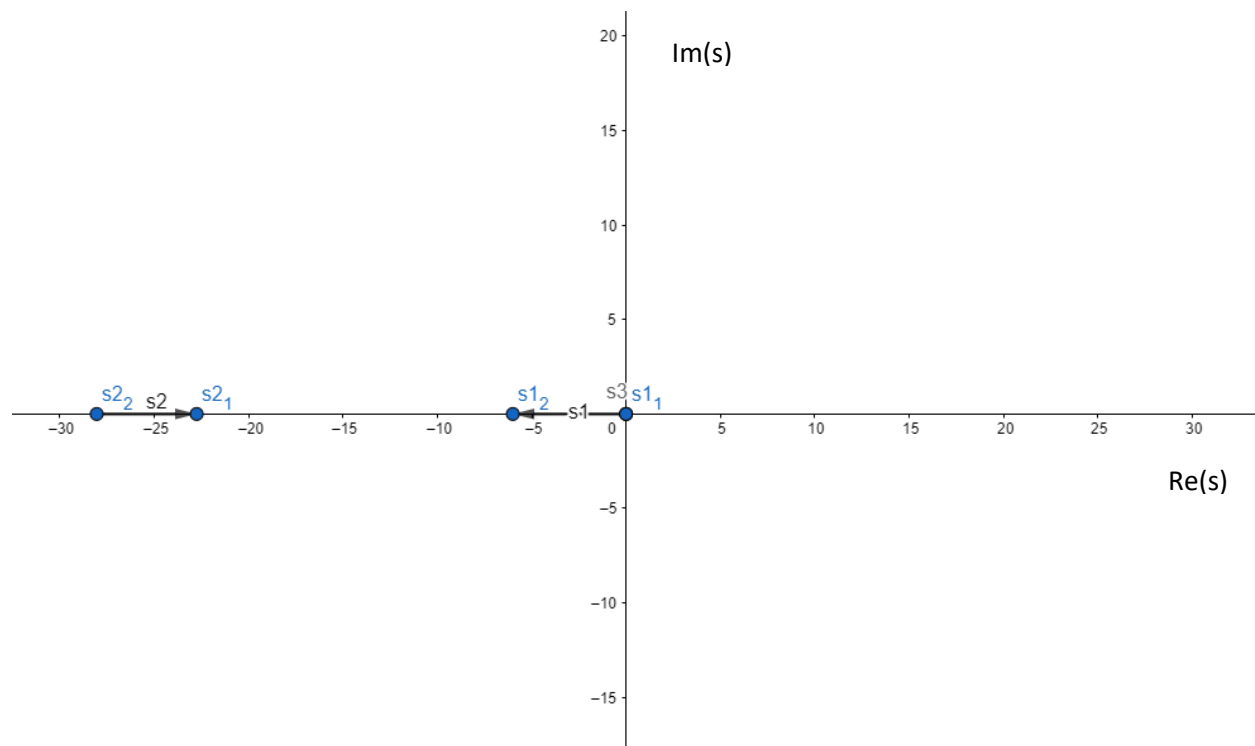
Πραγματικό επιπεδο:



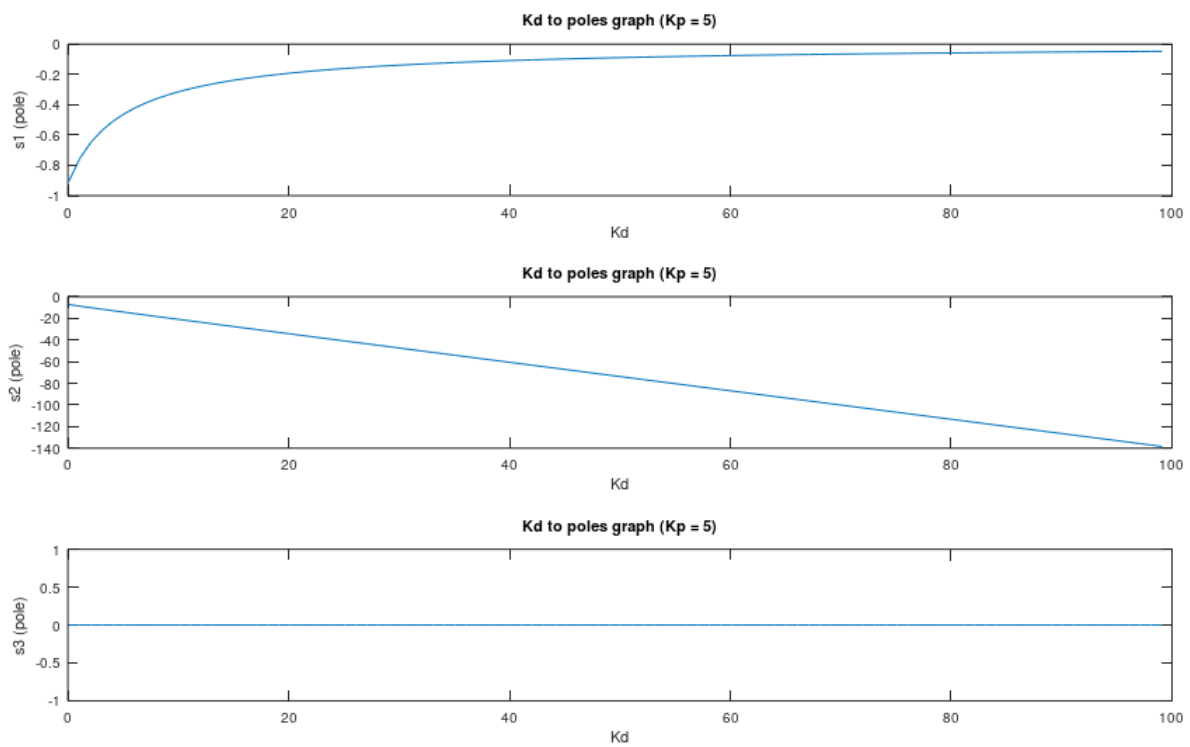
Μορφή της απόκρισης:

Και οι τρεις τιμες παραμενουν πραγματικες και μικροτερες ή ισες του μηδενος αρα εχουμε υπεραπόσβεση

Μιγαδικό επίπεδο:



Πραγματικό επίπεδο:

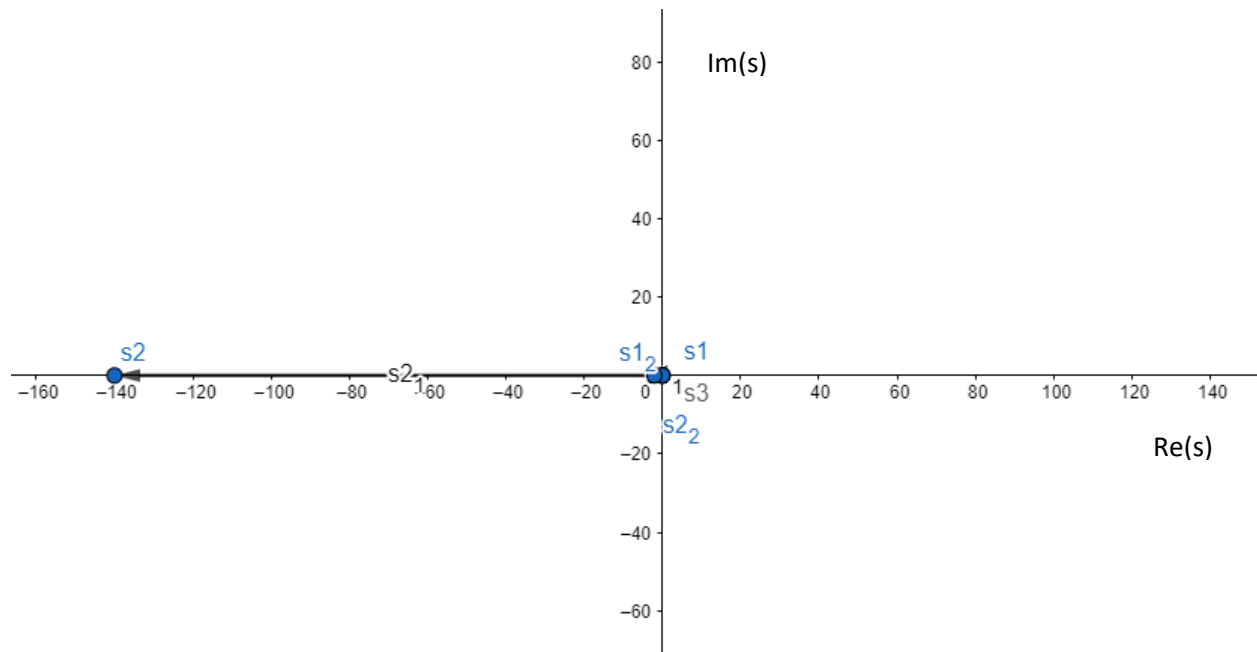


Μορφή της απόκρισης:

Και οι τρεις τιμές παραμένουν πραγματικές και μικρότερες ή ίσες του μηδενός αρα έχουμε υπεραπόσβεση

Όσον αφορά την ευσταθεια του συστήματος παρατηρούμε ότι είναι ασταθές αφού για μικρές αλλαγές στις αρχικές συνθήκες μπορούν να επιφέρουν μεγάλες αλλαγές στην λύση καθώς προσεγγίζουμε το άπειρο

Μιγαδικό επίπεδο:



Γ')

$$(f_2 - f_1) = K_{p\theta}(\theta_{des} - \theta) - K_{d\theta}(\theta') = 5(-0.471 - \theta) - 19.71(\theta') \quad (5)$$

$$K_{p\theta} = 5$$

$$K_{d\theta} = 15 + (4710/1000) = 19.71$$

$$\theta_0 = 0$$

$$\theta_{des} = -4710/10000 = -0.471$$

$$b_\theta = 5 - (4710/5000) = 4.058$$

$$\theta'(0) = 0, \theta(0) = \theta_0 = 0$$

$$\theta = \frac{-I_z \theta'' - \left(\frac{d}{2} K_{d\theta} + b_\theta\right) \theta' + \frac{d}{2} K_{p\theta} \theta_{des}}{\frac{d}{2} K_{p\theta}}$$

$$I_z \theta'' + \left(\frac{d}{2} K_{d\theta} + b_\theta\right) \theta' + \frac{d}{2} K_{p\theta} \theta = \frac{d}{2} K_{p\theta} \theta_{des} \Rightarrow$$

$$0.38\theta'' + 13.913\theta' + 2.5\theta = -1.178 \Rightarrow$$

$$\text{Αρχικά λυνουμε την ομογενη: } 0.38r^2 + 13.913r + 2.5 = 0 \Rightarrow (\Delta = 189.772) \Rightarrow$$

$$r_1 = \frac{-13.913 + \sqrt{189.772}}{0.76} = \frac{-13.913 + 13.775}{0.76} = -0.181$$

$$r_2 = \frac{-13.913 - \sqrt{189.772}}{0.76} = \frac{-13.913 - 13.775}{0.76} = -36.431$$

Υποθετουμε οτι η μερικη λυση $\theta(t) = \alpha$, αρα:

$$\theta''(t) = \theta'(t) = 0$$

Αντικατασταση:

$$0.38\theta'' + 13.913\theta' + 2.5\theta = -1.178 \Rightarrow 0 + 0 + 2.5\alpha = -1.178 \Rightarrow \alpha = \theta_{\text{des}} = -0.471$$

Αρα η Γ.Λ. είναι:

$$\theta(t) = c_1 * e^{r_1 * t} + c_2 * e^{r_2 * t} - 0.471 = c_1 * e^{-0.181 * t} + c_2 * e^{-36.431 * t} - 0.471$$

$$\theta'(t) = -0.181 * c_1 * e^{-0.181 * t} - 36.431 * c_2 * e^{-36.431 * t}$$

$$\theta(0) = 0 \Rightarrow c_1 * e^0 + c_2 * e^0 = 0.471 \Rightarrow c_1 + c_2 = 0.471 \quad (1)$$

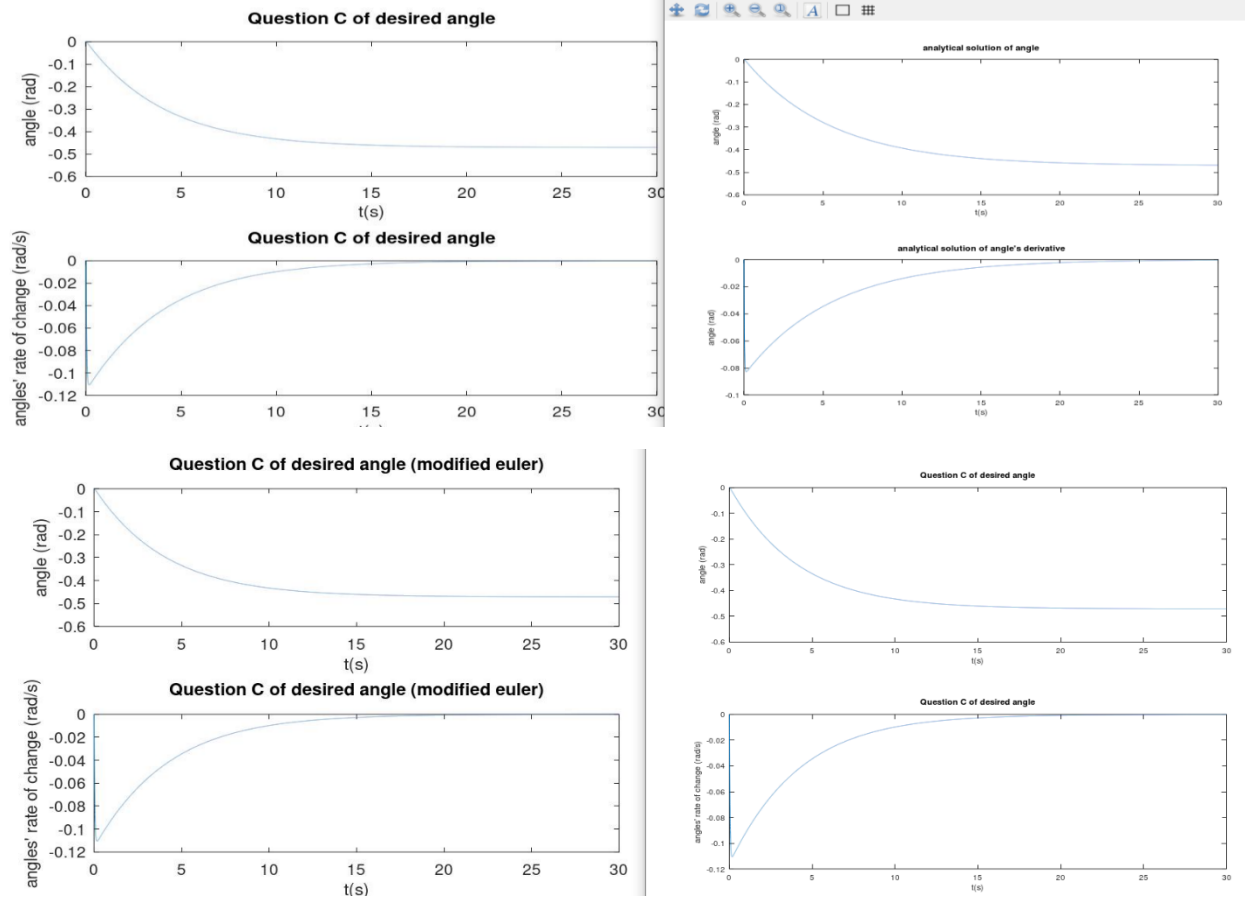
$$\theta'(0) = 0 \Rightarrow 0 = -0.181 * c_1 * e^0 - 36.431 * c_2 * e^0 \Rightarrow -0.181 * c_1 - 36.431 * c_2 = 0 \quad (2)$$

$$(1), (2) \begin{cases} c_1 + c_2 = 0.471 \\ -0.181 * c_1 - 36.431 * c_2 = 0 \end{cases} \Rightarrow \begin{cases} c_1 = -c_2 + 0.471 \\ 0.181 * c_2 - 0.085 - 36.431 * c_2 = 0 \end{cases} \Rightarrow$$

$$\begin{cases} c_1 = -c_2 + 0.471 \\ 36.25 * c_2 = -0.085 \end{cases} \Rightarrow \begin{cases} c_1 = 0.4687 \\ c_2 = -0.0023 \end{cases}$$

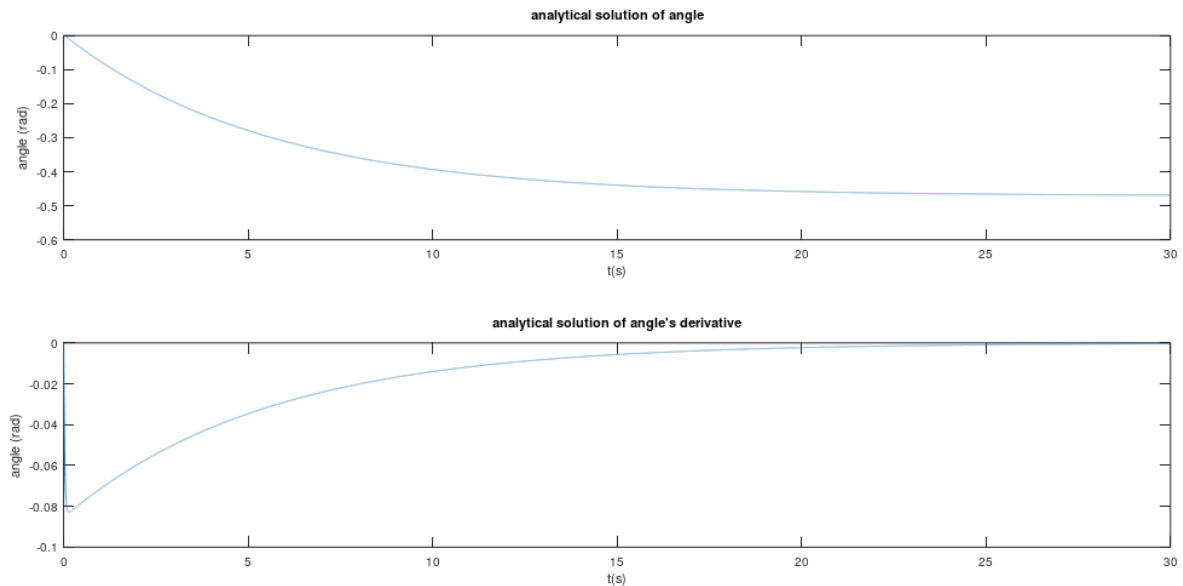
$$\text{Η γενικη λυση του ΠΑΤ είναι } \theta(t) = 0.4687 * e^{-0.181 * t} + -0.0023 * e^{-36.431 * t} - 0.471$$

Δ')



Παρατηρούμε ότι είναι παρόμοιες με την Euler να έχει τάξη ακριβείας 1 ενώ η τροποποιημένη έχει τάξη ακριβείας 2 σε σχέση με την αναλυτική λύση.

Ε')



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