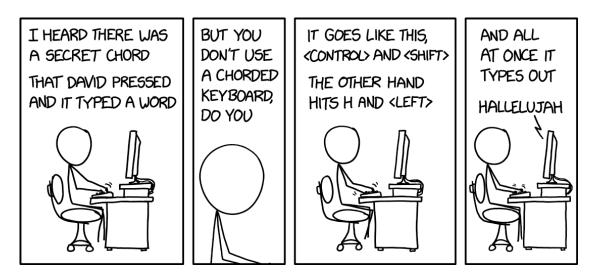
Admin

Lab 5

Bring in code for show & tell



https://xkcd.com/2583/

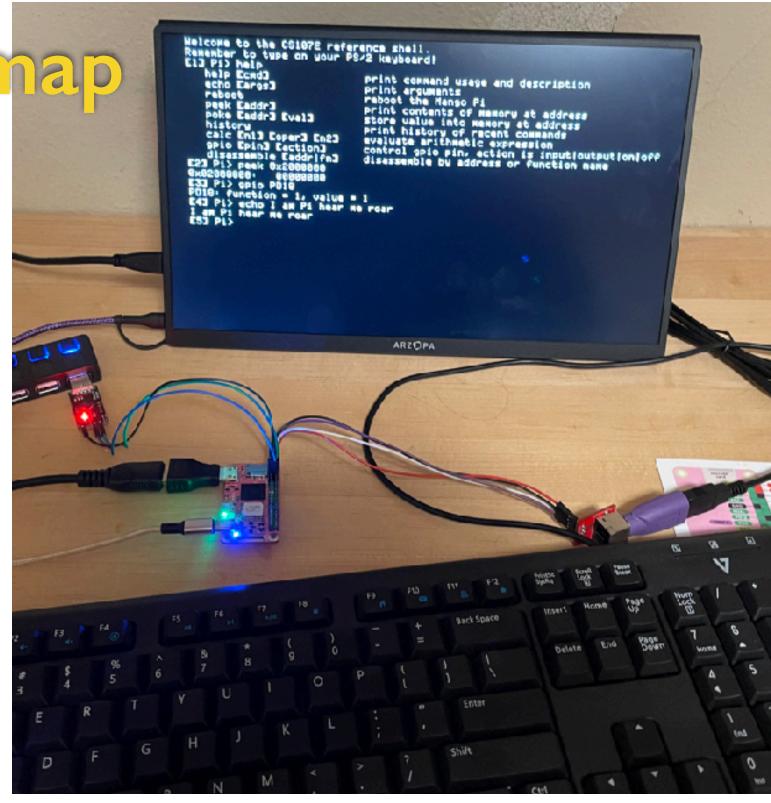
Today: PS/2 protocol

Reunite with our first and oldest friend, gpio module! 1987 called and asked for its keyboard back



Road map

gpio timer uart strings printf backtrace symtab malloc keyboard shell fb console



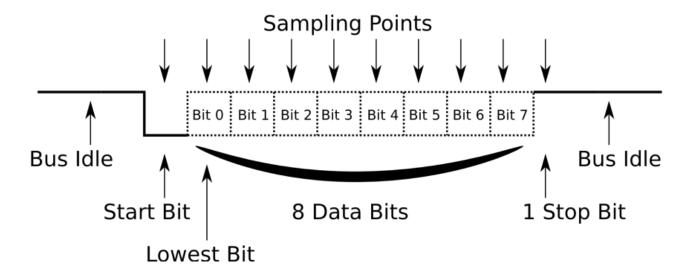
UART

Bi-directional communicate laptop <-> Pi (uart_putchar/getchar)

8N1: start bit, 8 data bits, no parity bit, I stop bit

Asynchronous: no clock, need precise timing both ends

What can happen if drift/inaccuracy between sender/receiver clocks?



PS/2 interface

PS/2 is the original serial protocol for keyboards and mouse (since replaced by USB)

Computer PS/2 ports

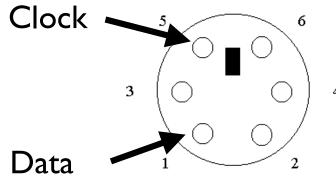




http://www.computerhope.com



PS/2 Keyboard and Mouse Cable



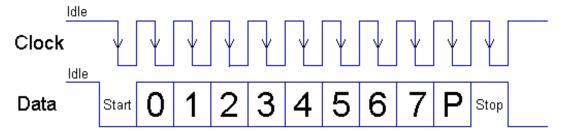
Cable (male) pinout

Pin Name

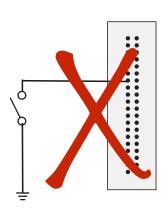
- 1 +Keyboard Data
- 2 Unused
- 3 Ground
- 4 +5 Volts
- 5 Clock
- 6 Unused

PS/2 Protocol

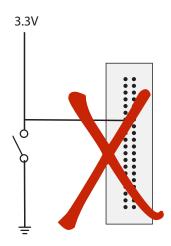
- 8-Odd-I
 - Start, 8 data bits, odd parity, stop (11 total bits)
- Synchronous, clocked by sender
 - Two lines: clock and data
 - Pulse clock to indicate when to read data line
 - Read happens after falling edge of clock
- Open-collector (both clock and data)
 - Circuit is high when idle
 - Pull low (connect to ground) to start signal



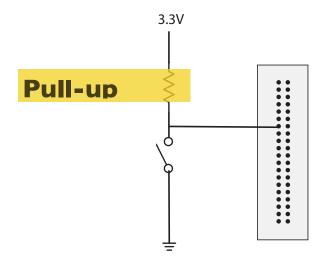
Switch

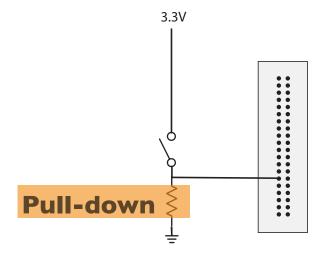


Wired as above, what does switch read when open?



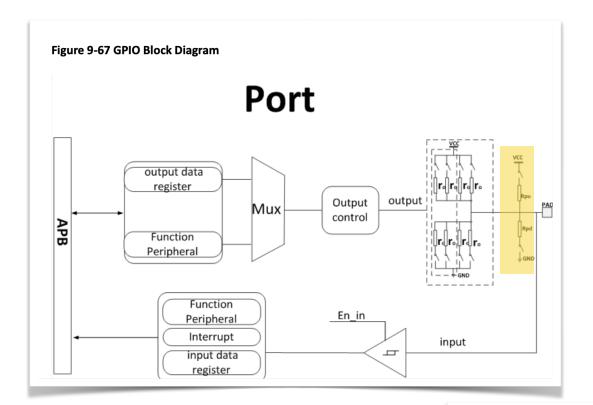
Wired as above, what happens when switch is closed?





How does adding pull-up or pull-down fix the problems from above?

Software-controlled pull state



9.7.4 Register List

Module Name	Base Address
GPIO	0x02000000

Register Name	Offset	Description		
PB_CFG0	0x0030	PB Configure Register 0		
PB_CFG1	0x0034	PB Configure Register 1		
PB_DAT	0x0040	PB Data Register		
PB_DRV0	0x0044	PB Multi_Driving Register 0		
PB_DRV1	0x0048	PB Multi_Driving Register 1		
PB_PULLO	0x0054	PB Pull Register 0		
PC_CFG0	0x0060	PC Configure Register 0		

See our gpio_extra.h

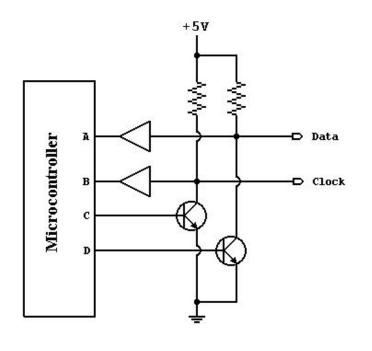
High-impedance, the output is float state, all buffer is off, the level is decided by external high/low level. When high-impedance, the software configures the switch on Rpu and Rpd as off, and the multiplexing function of IO is set as IO disable or input by software.

Pull-up, an uncertain signal is pulled high by resistance, the resistance has a current-limiting function. When pulling up, the switch on Rpu is conducted by software configuration, the IO is pulled up to VCC by Rpu.

Pull-down, an uncertain signal is pulled low by a resistance. When pulling down, the switch on Rpd is conducted by software configuration, the IO is pulled down to GND by Rpd.

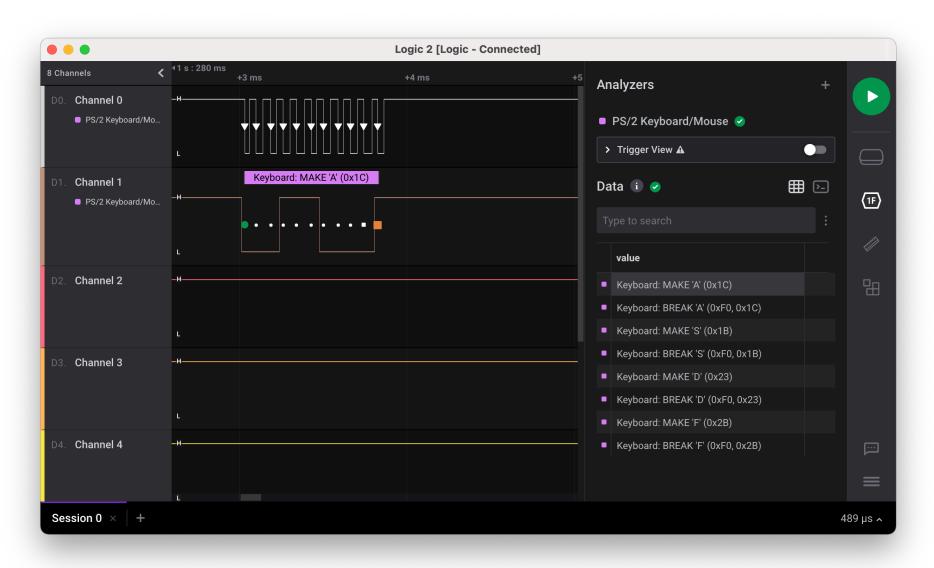
Ref: DI-H User Manual p.1093

Open collector



- Clock and Data lines are pulled up to 5V in idle state
- Switching on transistor sets line to 0V
- Communication bi-directional (keyboard or Pi can pull line low to take control)

PS/2 logic analyzer demo



Code to read scancode bits

code/ps2/

PS/2 Scancodes

http://www.computer-engineering.org/ps2keyboard/

$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
$ \begin{array}{c} \sim \\ 1! \\ 0E \\ 16 \\ \end{array} \begin{array}{c} 3\# \\ 26 \\ \end{array} \begin{array}{c} 4\$ \\ 25 \\ 2E \\ \end{array} \begin{array}{c} 5\% \\ 36 \\ \end{array} \begin{array}{c} 6^{\wedge} \\ 3D \\ \end{array} \begin{array}{c} 7\& \\ 3E \\ \end{array} \begin{array}{c} 9 \\ 45 \\ 45 \\ \end{array} \begin{array}{c} 0 \\ 45 \\ 4E \\ \end{array} \begin{array}{c} -1 \\ 55 \\ 5D \\ 66 \\ \end{array} $
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$
58 1C 1B 23 2B 34 33 3B 42 4B 4C 52 4
Ctrl Alt SPACE Alt Ctrl 14 11 29 E0 11 E0 14

0xF0 is "Break" scancode

Key	Action	Scancode		
A	Make (press)	0x1C		
Α	Break (release)	0xF0 0x1C		
Shift (left)	Make (press)	0x12		
Shift (left)	Break (release)	0xF0 0x12		

Keyboard read scancode

code/scancode/

Parity bit

Even parity: XOR 9 bits (8 data, I parity), result even (count of on bits is even)

Odd parity: XOR 9 bits (8 data, I parity), result odd (count of on bits is odd) PS2 protocol is odd parity

even

bbo

data	parity							
		0		0			0	
data	parity							
		0		0			0	0

Error recovery

When reading PS/2 scancode, check for errors:

- Start bit != 0
- Parity not odd
- Stop bit != I
- Time between bits is too long

When detect error, discard partial bits and restart read

tekkieneet says:

March 11, 2021 at 1:01 pm

While simple logic to decode the PS/2 protocol, it is unlikely it can recover gracefully glitches/ESD/accidental connector removal/reconnection. When clock bits are missed without a resynchronization, all the data collected from that point are garbled. This was one of the things why the early PC don't handle reconnect well and requires a reboot if someone tripped on the keyboard cable.

To recover, you would need a timeout on last clock pulse and try to resynchrize the start bit. I have implement that on my PS/2 code and it always recovers.

Key (scancode) ≠ character

- Scancode identifies key, not ASCII value
 - e.g A key sends scancode 0x1c, ascii 'A' is 0x41
 - Typically keyboard has 104 keys, 127 ASCII character codes
- Extra keys
 - Special keys handled by code in keyboard driver/application
 - Function keys, arrows, delete, escape, ...
 - Modifiers (shift, control, alt, command)
 - Multiple keys with same function
 - · Left and right shift
 - Numbers on keypad vs. keyboard

Keyboard Viewer



Modifier keys



None



[CapsLock]



[Shift]



[CapsLock][Shift]

Layered abstractions

https://cs107e.github.io/header#keyboard

uint8_t keyboard_read_scancode(void)

Read single well-formed scancode (8-bit unsigned int)

key_action_t keyboard_read_sequence(void)

Read sequence of scancodes corresponding to single key press or release

key_event_t keyboard_read_event(void)

Return key event including modifier state

char keyboard_read_next(void)

Return typed ASCII character