Models so far

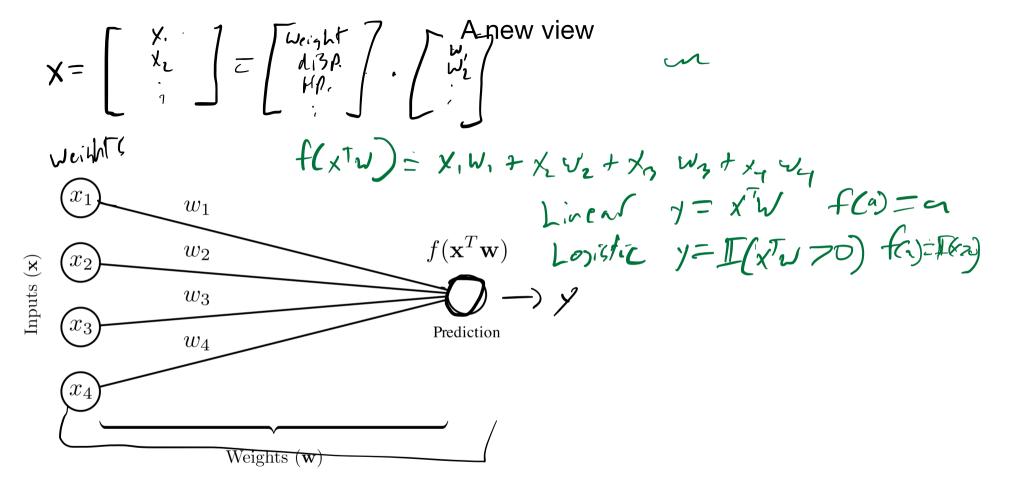
We saw that a reasonable model for continuous outputs
$$(y \in \mathbb{R})$$
 is **linear regression**. (prediction function)
$$\mathbf{Predict} \ y \in \mathbf{as} \ \begin{cases} y = \mathbf{x}^T \mathbf{w} & \text{(prediction function)} \\ p(y \mid \mathbf{x}, \mathbf{w}, \sigma^2) = \mathcal{N}(y \mid \mathbf{x}^T \mathbf{w}, \sigma^2) & \text{(probabilistic view)} \end{cases}$$

A reasonable model for binary outputs $(y \in \{0,1\})$ is **logistic regression**:

$$\mathbf{Predict}\; y \in \; \mathbf{as} \; egin{cases} y = \mathbb{I}(\mathbf{x}^T\mathbf{w} > 0) & ext{(prediction function)} \ p(y = 1 \mid \mathbf{x}, \mathbf{w}) = \sigma(\mathbf{x}^T\mathbf{w}) & ext{(probabilistic view)} \end{cases}$$

A reasonable model for *categorical* outputs $(y \in \{0,1,\ldots,C\})$ is **multinomial logistic regression**:

$$\mathbf{Predict}\; y \in \; \mathbf{as} \; egin{cases} y = rgmax \; \mathbf{x}^T \mathbf{w}_c & \mathcal{W} \ p(y = c \mid \mathbf{x}, \mathbf{w}) = \operatorname{softmax}(\mathbf{x}^T \mathbf{W})_c & (\operatorname{probabilistic view}) \end{cases}$$

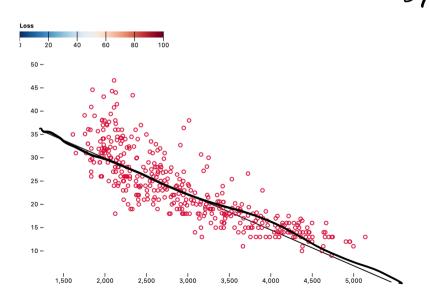


Linear Predictions

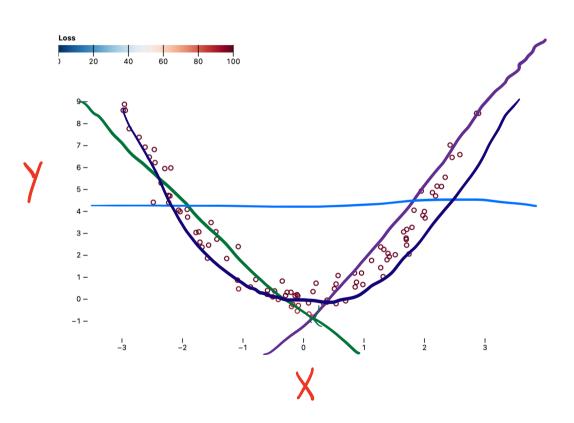
$$f(\mathbf{x}) = \mathbf{x}^T \mathbf{w} = \sum_{i=1}^n x_i w_i$$

 ${\rm Predicted}\ {\rm MPG} = f({\bf x}) =$

 $(\text{weight})w_1 + (\text{horsepower})w_2 + (\text{displacement})w_3 + (0\text{-}60\text{mph})w_4 + b$

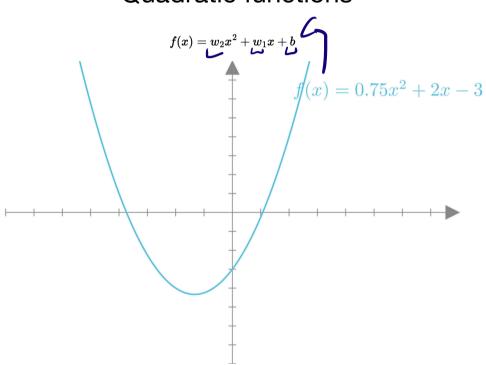


Non-Linear Data

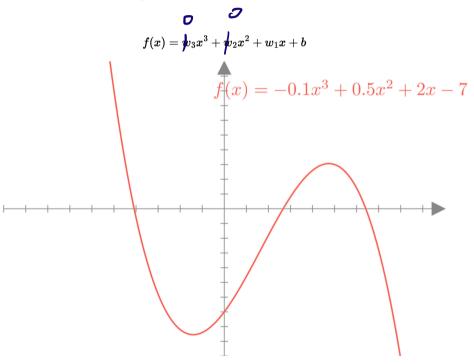


Polynomial functions

Quadratic functions



Cubic functions



The *degree* of a polynomial is the largest exponent in any term of the polynomial

Polynomial functions as vector functions

Quadratic feature transforms

Let's consider the mapping from \mathbf{x} to powers of the elements of \mathbf{x} . We'll call this mapping ϕ :

$$egin{bmatrix} x_1 \ x_2 \ x_2 \end{bmatrix} \longrightarrow egin{bmatrix} x_1 \ x_2 \ x_1 x_2 \ x_1^2 \ x_2^2 \ 1 \end{bmatrix}$$

$$\phi(\mathbf{x}) = egin{bmatrix} x_1 \ x_2 \ x_1 x_2 \ x_1^2 \ x_2^2 \ 1 \end{bmatrix} \qquad f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}$$

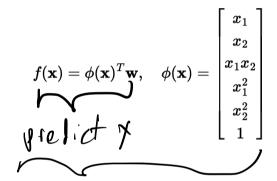
$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}$$

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w} = w_2 x_1^2 + w_1 x_1 + b, \quad \phi(\mathbf{x}) = egin{bmatrix} x_1 \ x_1^2 \ 1 \end{bmatrix}$$

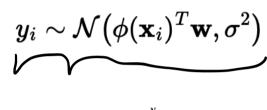
Fitting quadratic regression

Prediction function

Probabilistic model



Negative log-likelihood loss



$$abla_{\mathbf{w}}\mathbf{NLL}(\mathbf{w},\mathbf{X},\mathbf{y}) = rac{1}{2\sigma^2}\sum_{i=1}^N ig(\phi(\mathbf{x}_i)^T\mathbf{w} - y_iig)\phi(\mathbf{x}_i)$$



$$\mathbf{Loss}(\mathbf{w}) = \mathbf{NLL}(\mathbf{w}, \mathbf{X}, \mathbf{y}) = -\sum_{i=1}^{N} \log p(y_i \mid \mathbf{x}_i, \mathbf{w})$$

$$= \frac{1}{2\sigma^2} \sum_{i=1}^{N} (y_i - \phi(\mathbf{x}_i)^T \mathbf{w})^2 + N \log \sigma \sqrt{2\pi}$$

Fitting quadratic regression

Prediction function

Probabilistic model

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}, \quad \phi(\mathbf{x}) = egin{bmatrix} x_1 \ x_2 \ x_1 x_2 \ x_1^2 \ x_2^2 \ 1 \end{bmatrix} \qquad \qquad oldsymbol{y_i} \sim \mathcal{N}ig(\phi(\mathbf{x}_i)^T \mathbf{w}, \sigma^2ig)$$

$$y_i \sim \mathcal{N}ig(\phi(\mathbf{x}_i)^T\mathbf{w}, \sigma^2ig)$$

$$abla_{\mathbf{w}}\mathbf{NLL}(\mathbf{w},\mathbf{X},\mathbf{y}) = rac{1}{2\sigma^2}\sum_{i}^{N}ig(\phi(\mathbf{x}_i)^T\mathbf{w} - y_iig)\phi(\mathbf{x}_i)$$

Negative log-likelihood loss

$$\mathbf{Loss}(\mathbf{w}) = \mathbf{NLL}(\mathbf{w}, \mathbf{X}, \mathbf{y})$$

$$\mathbf{Loss}(\mathbf{w}) = \mathbf{NLL}(\mathbf{w}, \mathbf{X}, \mathbf{y})$$
 We see that the gradient doesn't change, it simply involves $\phi(\mathbf{x}_i)$ instead of \mathbf{x}_i . $\nabla_{\mathbf{w}} \mathbf{NLL}(\mathbf{w}, \mathbf{X}, \mathbf{y}) = \frac{1}{2\sigma^2} \sum_{i=1}^N \left(\phi(\mathbf{x}_i)^T \mathbf{w} - y_i \right) \phi(\mathbf{x}_i)$

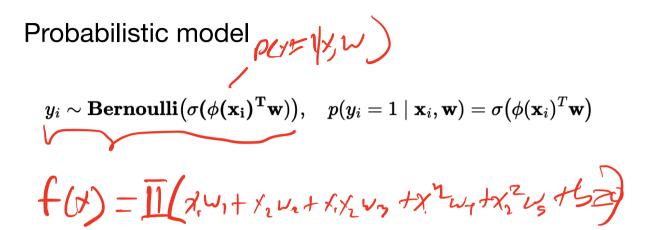
$$=rac{1}{2\sigma^2}\sum_{i}^{N}ig(y_i-\phi(\mathbf{x}_i)ig)$$

$$abla_{\mathbf{w}}\mathbf{NLL}(\mathbf{w},\mathbf{X},\mathbf{y}) = rac{1}{2\sigma^2}\sum_{i=1}^Nig(\phi(\mathbf{x}_i)^T\mathbf{w} - y_iig)\phi(\mathbf{x}_i)^T$$

Quadratic logistic regression

Prediction function

$$f(\mathbf{x}) = \mathbb{I}(\phi(\mathbf{x})^T\mathbf{w} \geq 0), \quad \phi(\mathbf{x}) = egin{bmatrix} x_1 \ x_2 \ x_1x_2 \ x_1^2 \ x_2^2 \ 1 \end{bmatrix}$$

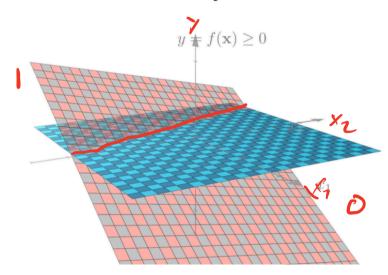


Negative log-likelihood loss

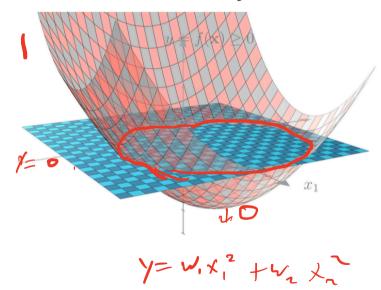
$$\mathbf{NLL}(\mathbf{w}, \mathbf{X}, \mathbf{y}) = -\sum_{i=1}^N \log \sigmaig((2y_i - 1) \overline{\phi(\mathbf{x}_i)^T} \mathbf{w}ig)$$

Quadratic decision boundary

Linear decision boundary



Quadratic decision boundary



Cubic feature transform

$$egin{pmatrix} [x_1] & \longrightarrow & egin{bmatrix} x_1^2 \ x_1^3 \ x_1 \end{bmatrix}$$

Prediction function (regression)

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w} = oldsymbol{w}_3 x_1^3 + w_2 x_1^2 + w_1 x_1 + b, \quad \phi(\mathbf{x}) = egin{bmatrix} x_1 \ x_1^3 \ x_1^3 \ 1 \end{bmatrix}$$

General feature transforms

$$\mathbf{x} = \mathbf{x} \mathbf{x}$$
 $\mathbf{x} = \mathbf{x}$
 $\mathbf{x} = \mathbf{$

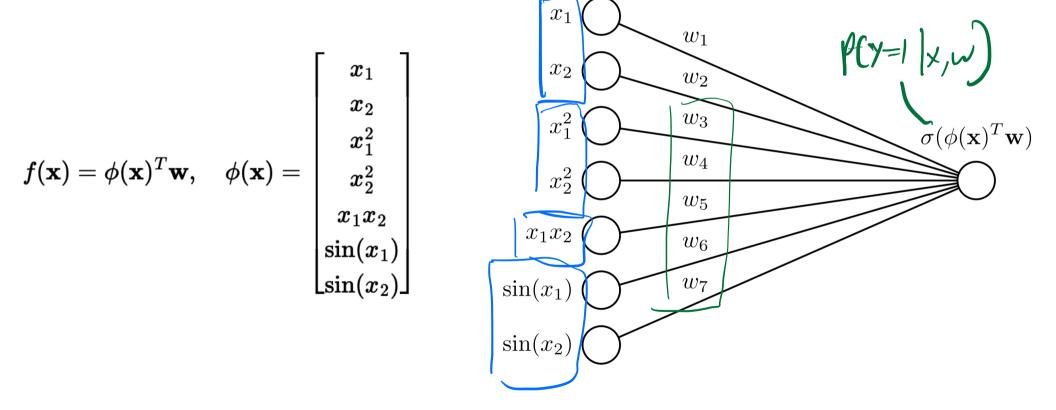
$$f(\mathbf{x}) = w_1 x_1 + w_2 x_2 + w_3 x_1^2 + w_4 x_2^2 + w_5 x_1 x_2 + w_6 \sin(x_1) + w_7 \sin(x_2)$$

General feature transforms # x^2 # x_1 * x_2 # sin(x)transformedX = np.concatenate([X, squared_X, cross_X, sin_X], axis=1) $f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}, \quad \phi(\mathbf{x}) = \mathbf{1}$ Phi $X = \begin{bmatrix} X_{11} & X_{12} \\ X_{11} & Y_{12} \end{bmatrix} \begin{bmatrix} X_{11}^2 & X_{11} \\ X_{11} & X_{12} \end{bmatrix} \begin{bmatrix} X_{11} & X_{12} \\ X_{11} & X_{12} \end{bmatrix}$ $f(\mathbf{x}) = w_1 x_1 + w_2 x_2 + w_3 x_1^2 + w_4 x_2^2 + w_5 x_1 x_2 + w_6 \sin(x_1) + w_7 \sin(x_2)$



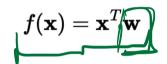
Non-linear logistic regression

$$p(y=1 \mid \mathbf{x}, \mathbf{w}) = \sigma(\phi(\mathbf{x})^T \mathbf{w})$$



Learning linear functions

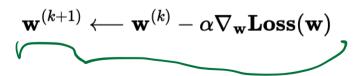
We've already seen that we can *learn* a function by defining our function in terms of a set of *parameters* \mathbf{w} :



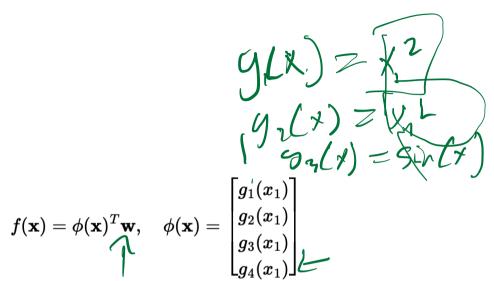
and then minimizing a loss as a function of w

$$\mathbf{w}^* = \operatorname*{argmin}_{\mathbf{w}} \mathbf{Loss}(\mathbf{w})$$

Which we can do with gradient descent:



Can we learn the functions in our feature transform?



Can we learn the functions in our feature transform?

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}, \quad \phi(\mathbf{x}) = \begin{bmatrix} g_1(x_1) \\ g_2(x_1) \\ g_3(x_1) \\ g_4(x_1) \end{bmatrix}$$

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}_0, \quad \phi(\mathbf{x}) = \begin{bmatrix} \sigma(\mathbf{x}^T \mathbf{w}_1) \\ \sigma(\mathbf{x}^T \mathbf{w}_2) \\ \sigma(\mathbf{x}^T \mathbf{w}_3) \\ \sigma(\mathbf{x}^T \mathbf{w}_4) \end{bmatrix}$$

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}_0, \quad \phi(\mathbf{x}) = \begin{bmatrix} \sigma(\mathbf{x}^T \mathbf{w}_1) \\ \sigma(\mathbf{x}^T \mathbf{w}_2) \\ \sigma(\mathbf{x}^T \mathbf{w}_3) \\ \sigma(\mathbf{x}^T \mathbf{w}_4) \end{bmatrix}$$

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}_0, \quad \phi(\mathbf{x}) = \begin{bmatrix} \sigma(\mathbf{x}^T \mathbf{w}_1) \\ \sigma(\mathbf{x}^T \mathbf{w}_2) \\ \sigma(\mathbf{x}^T \mathbf{w}_3) \\ \sigma(\mathbf{x}^T \mathbf{w}_4) \end{bmatrix}$$

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}_0, \quad \phi(\mathbf{x}) = \begin{bmatrix} \sigma(\mathbf{x}^T \mathbf{w}_1) \\ \sigma(\mathbf{x}^T \mathbf{w}_2) \\ \sigma(\mathbf{x}^T \mathbf{w}_3) \\ \sigma(\mathbf{x}^T \mathbf{w}_4) \end{bmatrix}$$

A simple learned transform

Let's look at a very simple example:

simple example:
$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}, \quad \mathbf{w}_0 = \begin{bmatrix} w_{01} \\ w_{02} \end{bmatrix}$$

$$f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}_0, \quad \phi(\mathbf{x}) = \begin{bmatrix} \sigma(\mathbf{x}^T \mathbf{w}_1) \\ \sigma(\mathbf{x}^T \mathbf{w}_2) \\ \sigma(\mathbf{x}^T \mathbf{w}_3) \end{bmatrix} = \begin{bmatrix} \sigma(x_1 w_{11} + x_2 w_{12}) \\ \sigma(x_1 w_{21} + x_2 w_{22}) \\ \sigma(x_1 w_{31} + x_2 w_{32}) \end{bmatrix}$$

In this case, we can write out our prediction function explicitly as:

$$f(x) = \phi(x)w_{o_1} + \phi(x)_2 V_{o_2} + \phi(x)_3 W_{o_3}$$

$$= \sigma(V_1 V_{11} + X_2 V_{12})W_{o_1} + \sigma(\mathbf{x}_1 W_{21} + X_2 V_{22})W_{o_2} + \sigma(X_1 V_{s_1} + K_2 W_{s_2})W_{o_3}$$

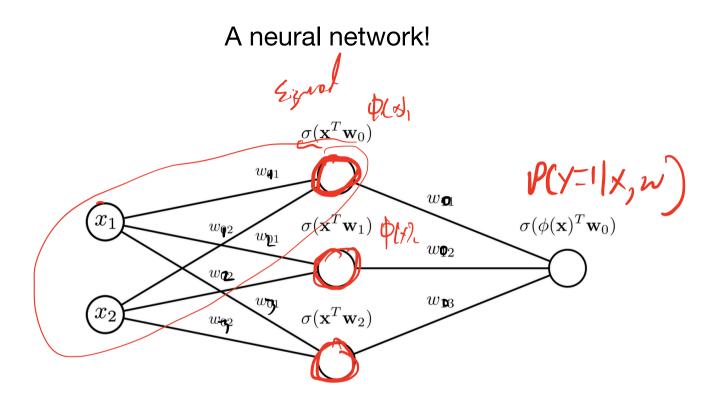
A simple learned transform

Let's look at a very simple example:

$$\mathbf{x} = egin{bmatrix} x_1 \ x_2 \end{bmatrix}, \quad \mathbf{w}_0 = egin{bmatrix} w_{01} \ w_{02} \end{bmatrix}$$
 $f(\mathbf{x}) = \phi(\mathbf{x})^T \mathbf{w}_0, \quad \phi(\mathbf{x}) = egin{bmatrix} \sigma(\mathbf{x}^T \mathbf{w}_1) \ \sigma(\mathbf{x}^T \mathbf{w}_2) \ \sigma(\mathbf{x}^T \mathbf{w}_2) \end{bmatrix} = egin{bmatrix} \sigma(x_1 w_{11} + x_2 w_{12}) \ \sigma(x_1 w_{21} + x_2 w_{22}) \ \sigma(x_1 w_{21} + x_2 w_{22}) \end{bmatrix}$

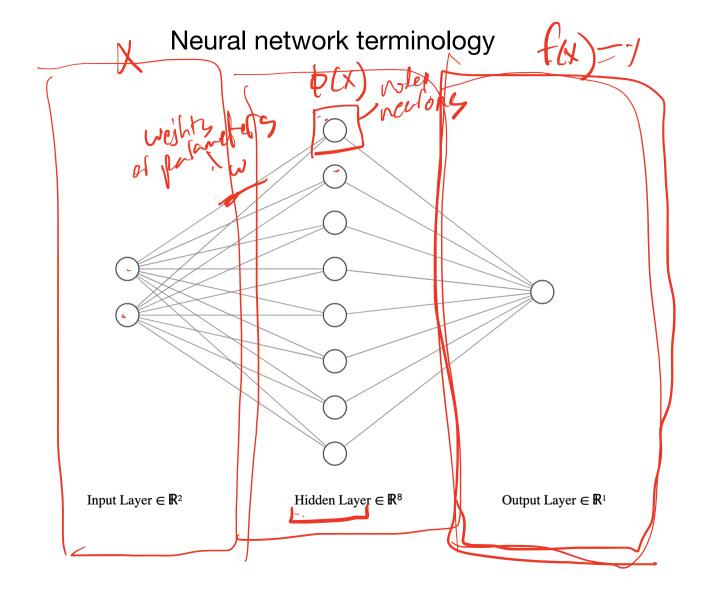
In this case, we can write out our prediction function explicitly as:

$$f(\mathbf{x}) = w_{01} \cdot \sigma(x_1w_{11} + x_2w_{12}) + w_{02} \cdot \sigma(x_1w_{21} + x_2w_{22}) + w_{03} \cdot \sigma(x_1w_{31} + x_2w_{32})$$



In this case, we can write out our prediction function explicitly as:

$$f(\mathbf{x}) = w_{01} \cdot \sigma(x_1 w_{11} + x_2 w_{12}) + w_{02} \cdot \sigma(x_1 w_{21} + x_2 w_{22}) + w_{03} \cdot \sigma(x_1 w_{31} + x_2 w_{32})$$



$$\mathbf{NLL}(\mathbf{W}, \mathbf{X}, \mathbf{y}) = -\sum_{i=1}^N \log \ \operatorname{softmax}(\mathbf{x}_i^T \mathbf{W}^T)_{y_i} = -\sum_{i=1}^N \log rac{e^{\mathbf{x}_i^T \mathbf{w}_{y_i}}}{\sum_{j=1}^C e^{\mathbf{x}_i^T \mathbf{w}_j}}$$

$$i{=}1$$
 $\sum_{j=1}e^{\mathbf{x}_i}$ " j

 $\mathbf{NLL}(\mathbf{W}, \mathbf{X}, \mathbf{y}) = -\sum_{i=1}^N \left(\mathbf{x}_i^T \mathbf{w}_{y_i} - \log \sum_{i=1}^C e^{\mathbf{x}_i^T \mathbf{w}_j}
ight)$