

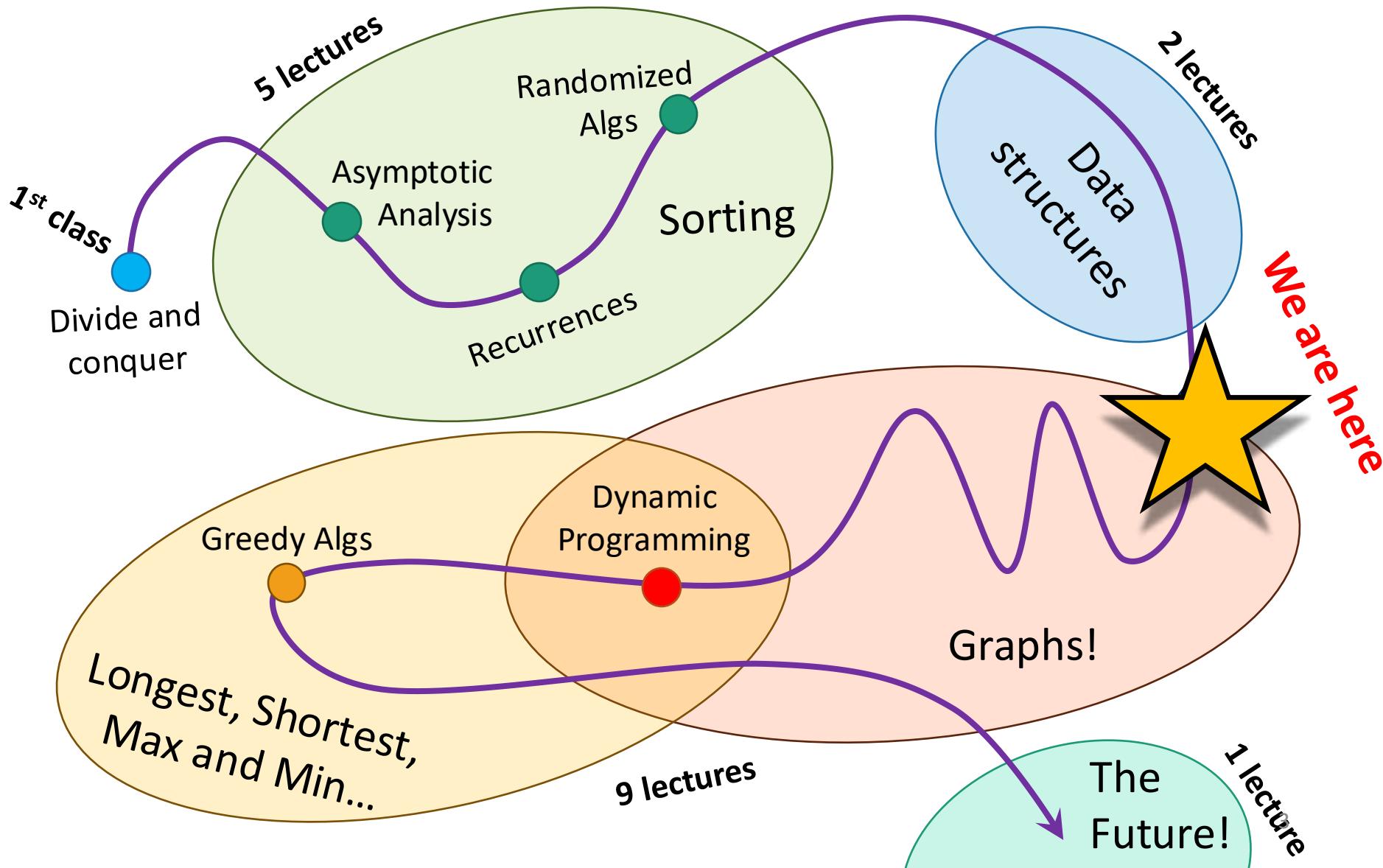
# Lecture 9

Graphs, BFS and DFS

# Announcements!

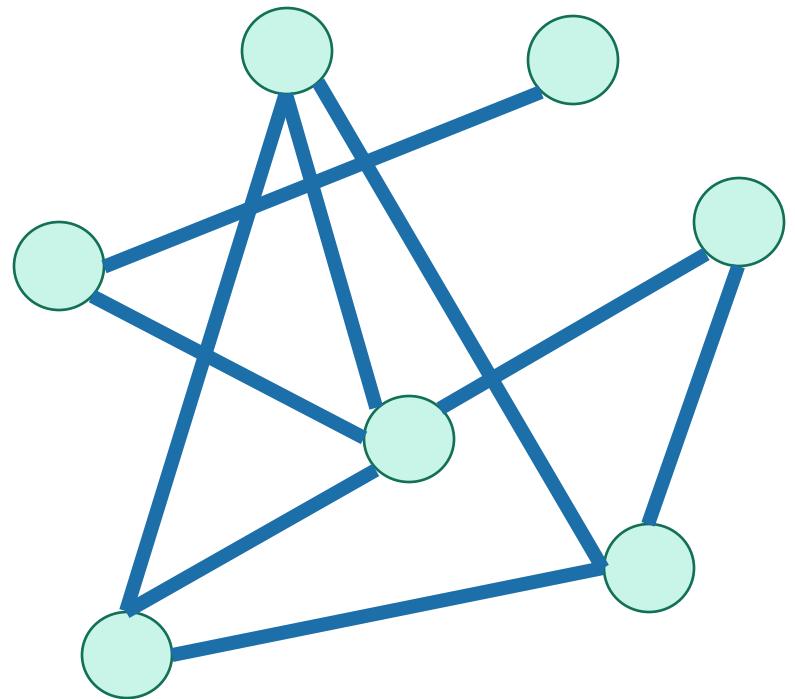
- HW3 due Friday! ☺

# Roadmap



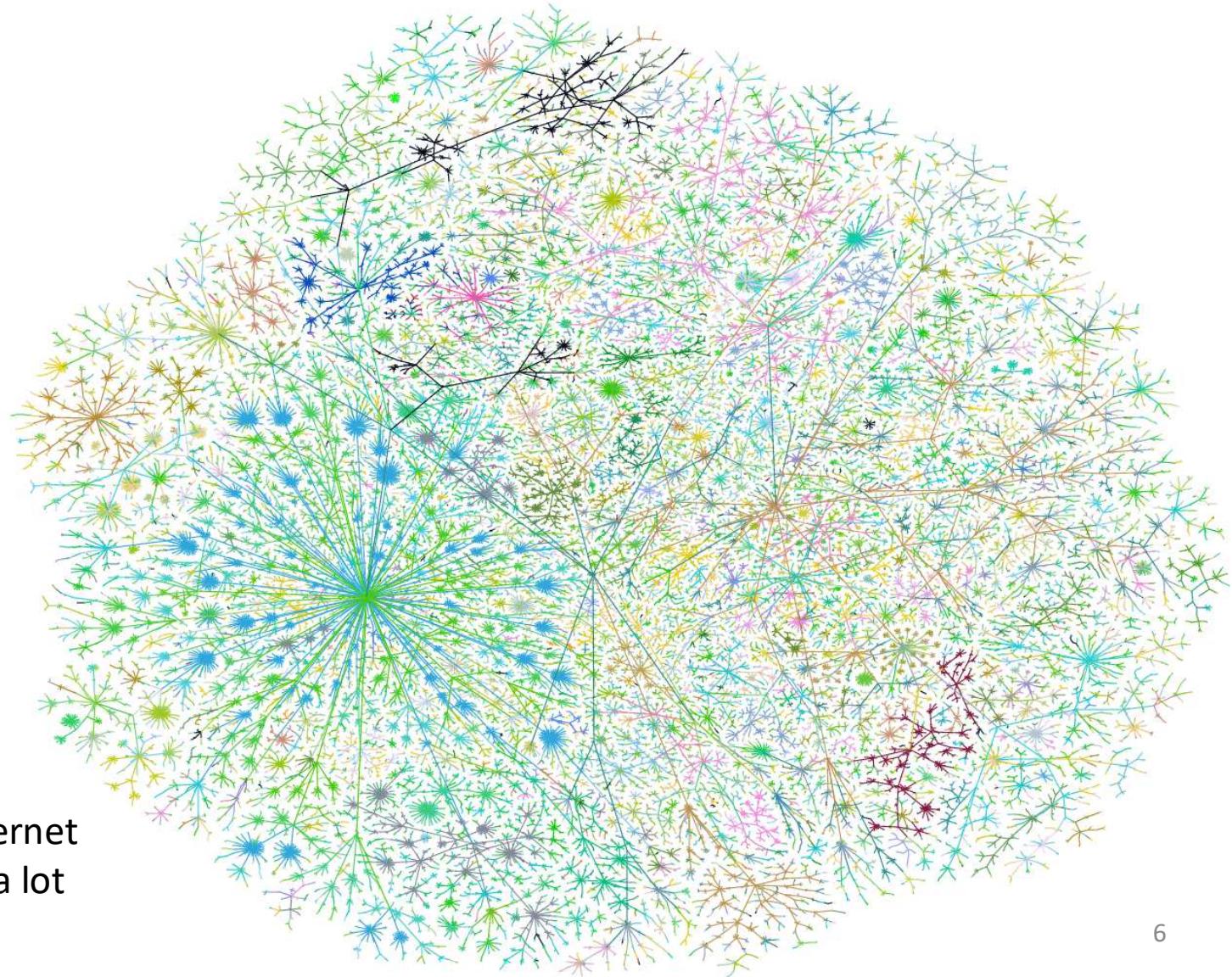
# Outline

- Part 0: Graphs and terminology
- Part 1: Depth-first search
  - Application: topological sorting
  - Application: in-order traversal of BSTs
- Part 2: Breadth-first search
  - Application: shortest paths
  - Application (if time): is a graph bipartite?



# Part 0: Graphs

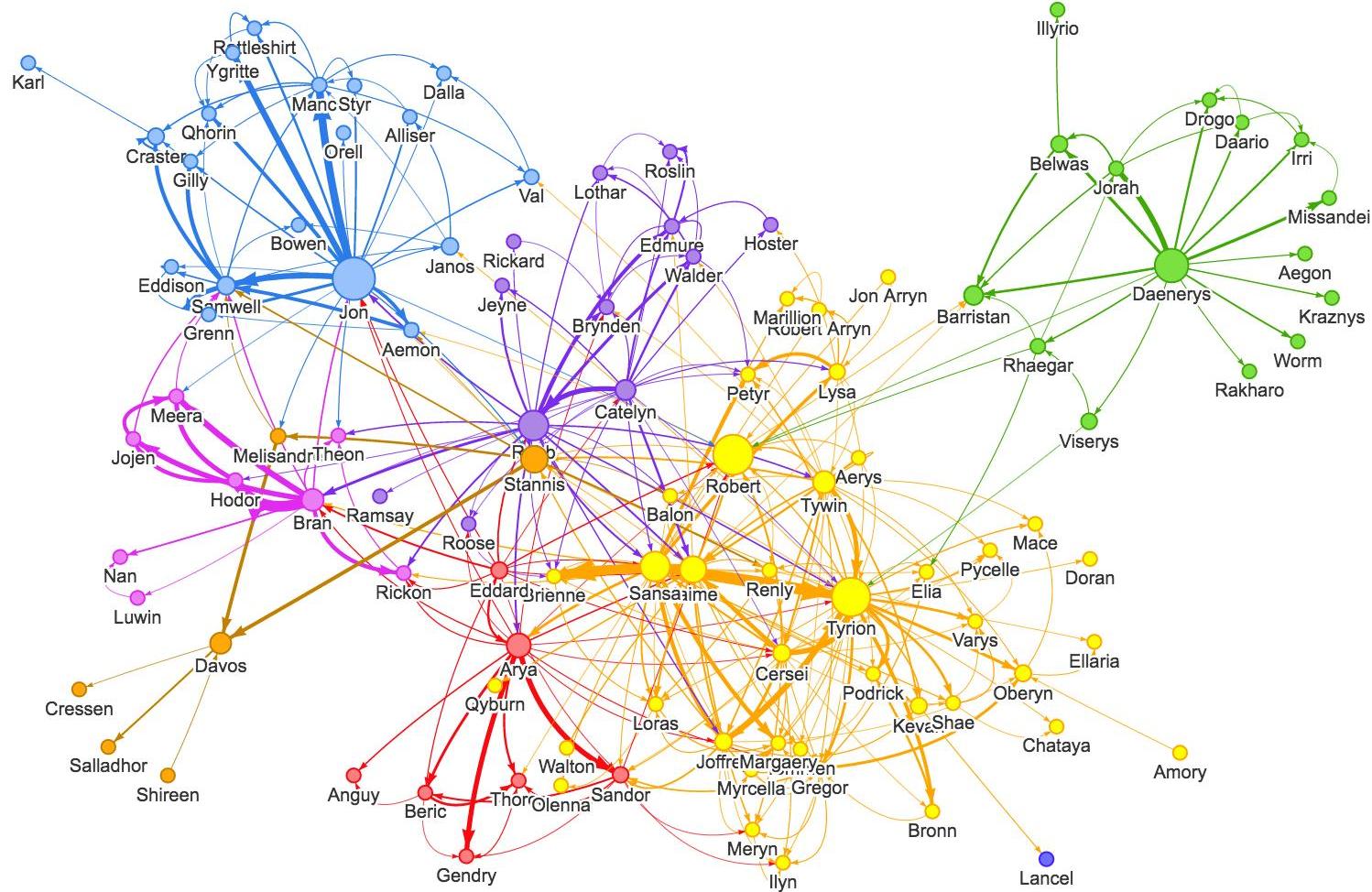
# Graphs



Graph of the internet  
(circa 1999...it's a lot  
bigger now...)

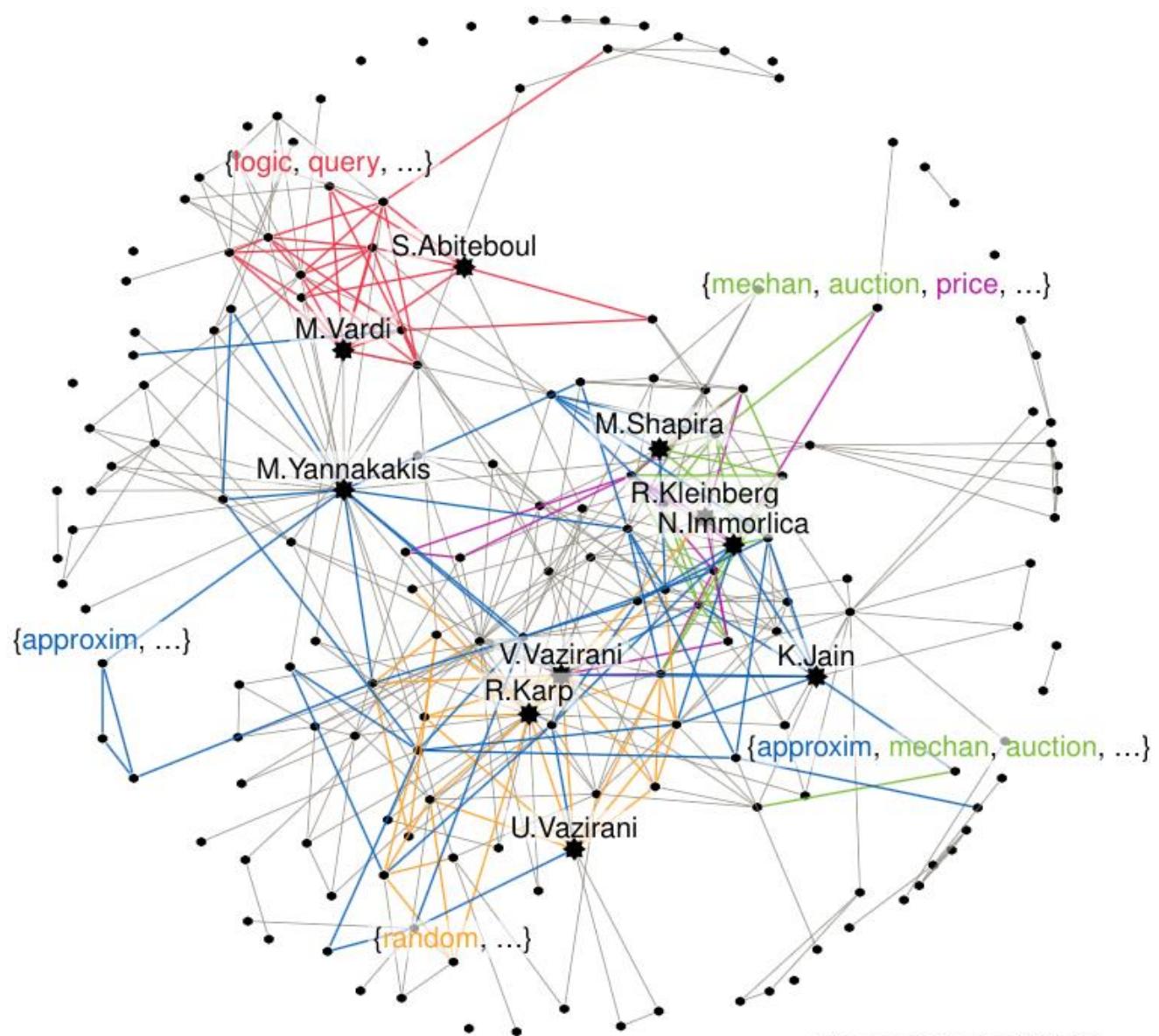
# Graphs

# Game of Thrones Character Interaction Network



# Graphs

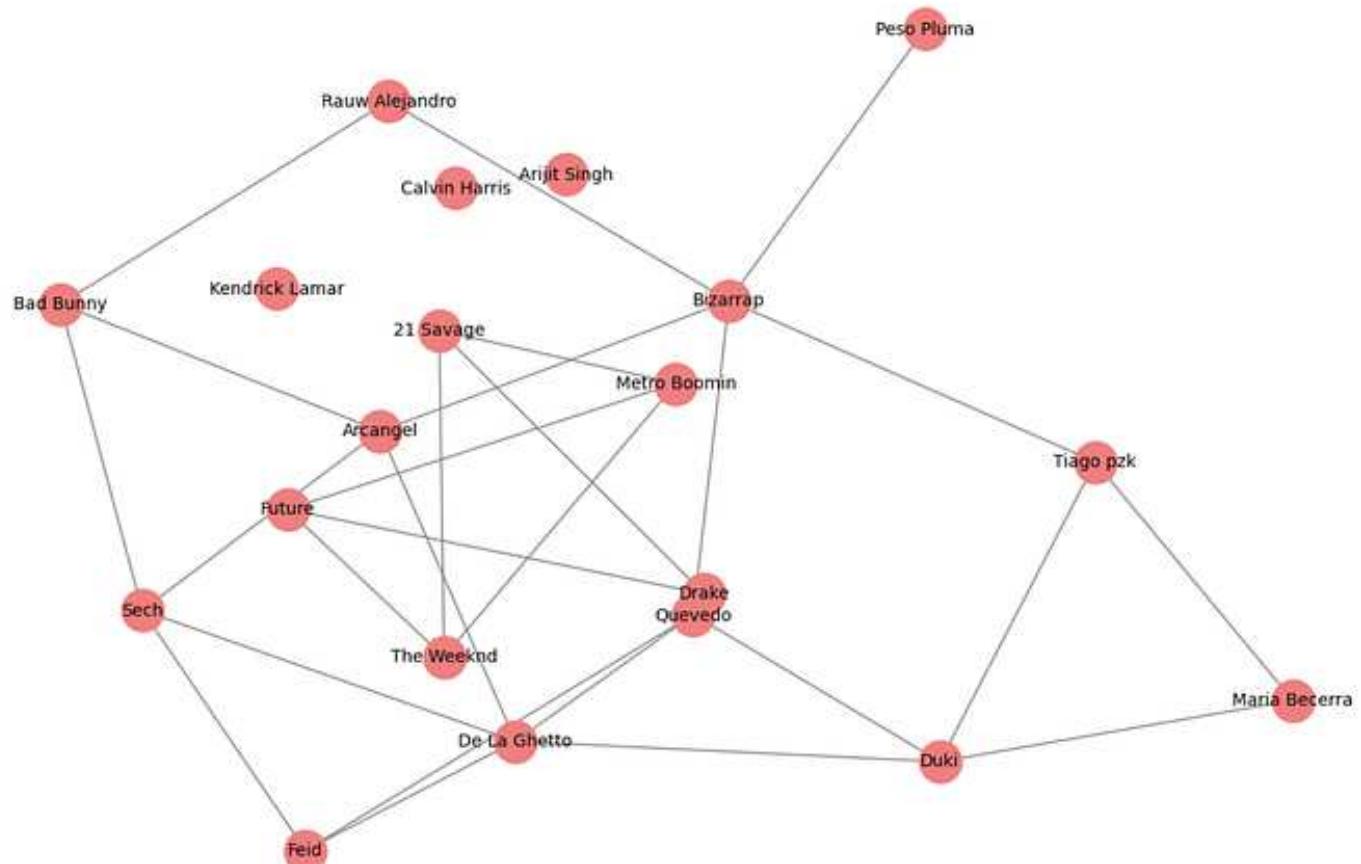
Theoretical Computer  
Science academic  
communities



*Example from DBLP:*  
Communities within the co-authors of Christos H. Papadimitriou

# Graphs

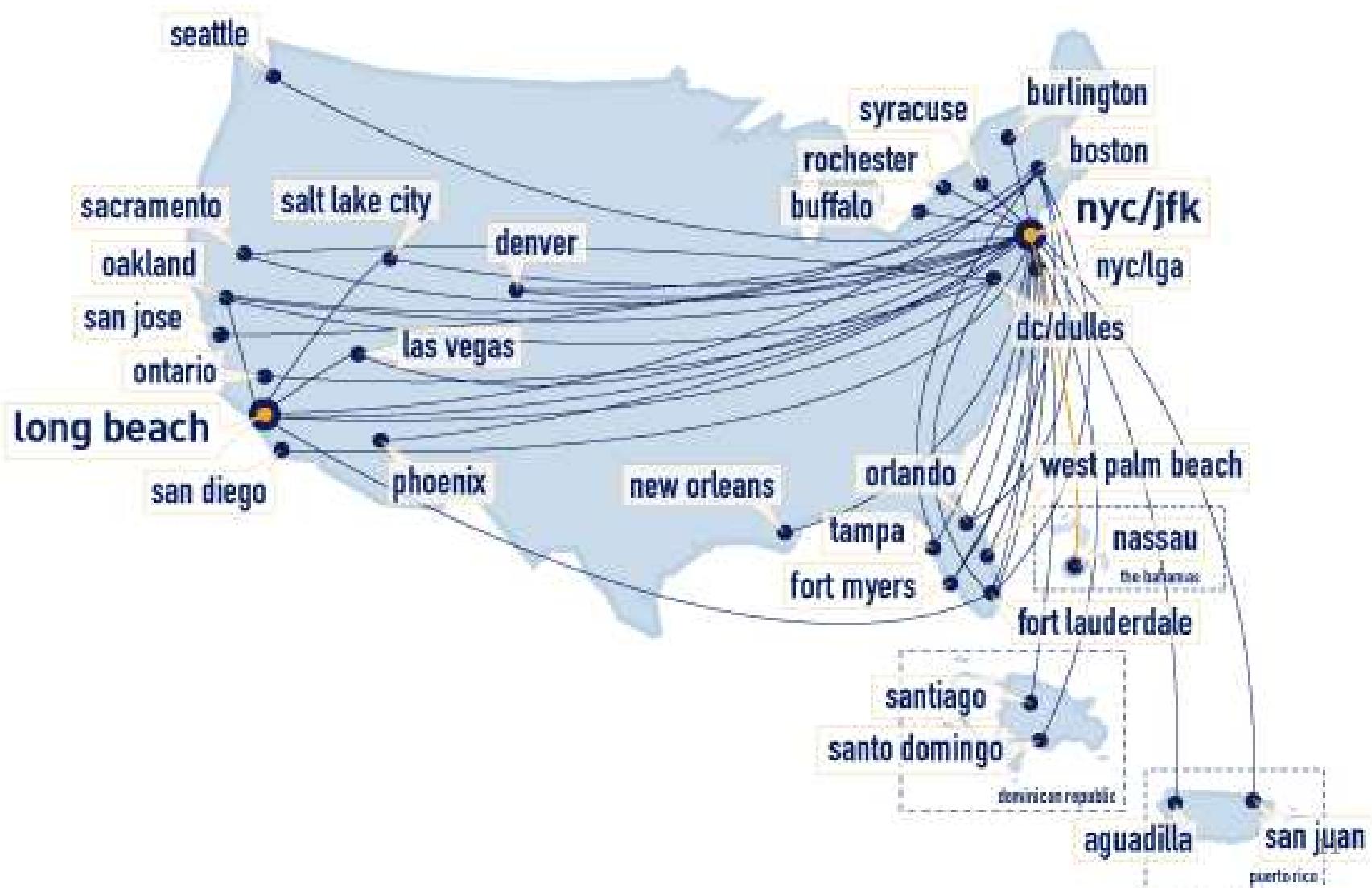
Top 20 Artists by Degree Centrality



Collaborations  
between  
musical artists

# Graphs

jetblue flights



# Graphs

# Vision of public transit in the bay area

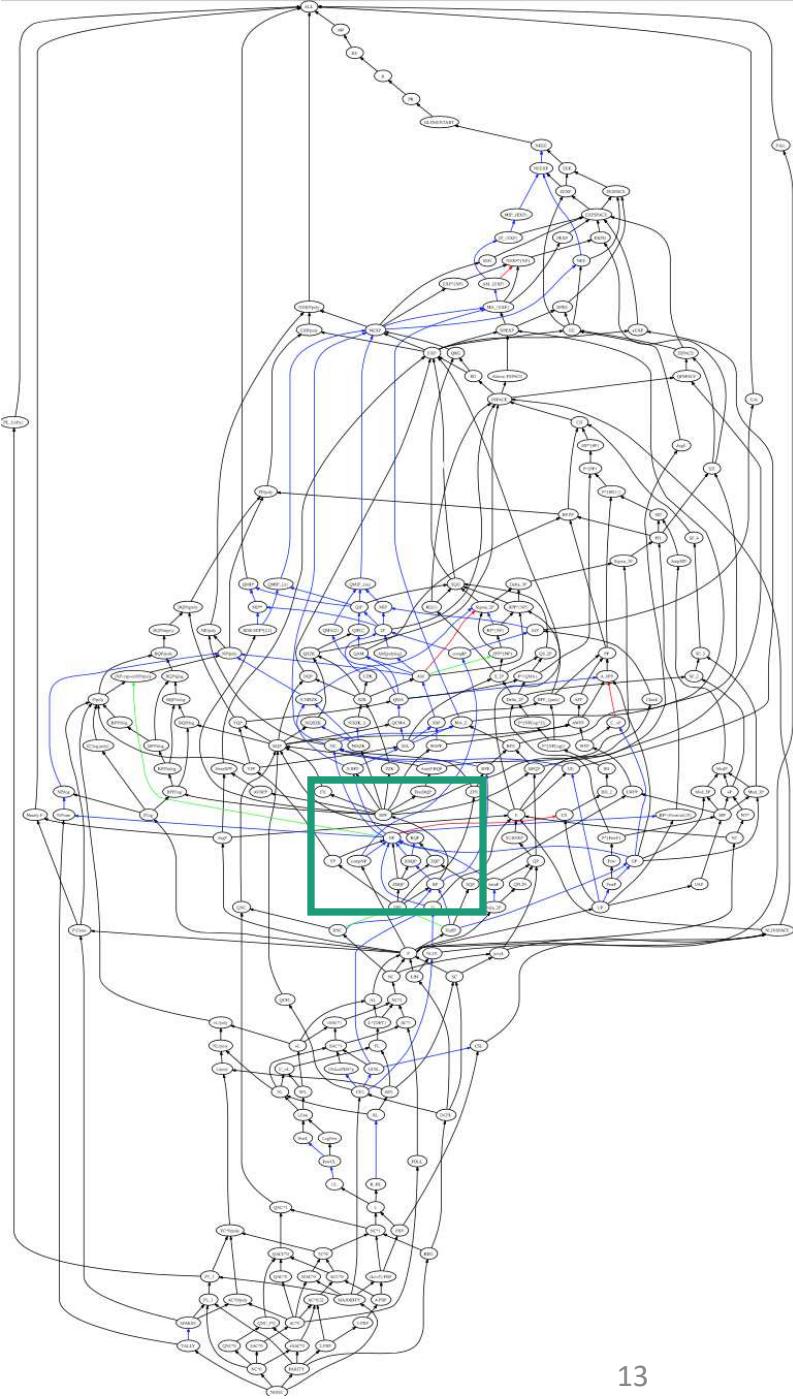
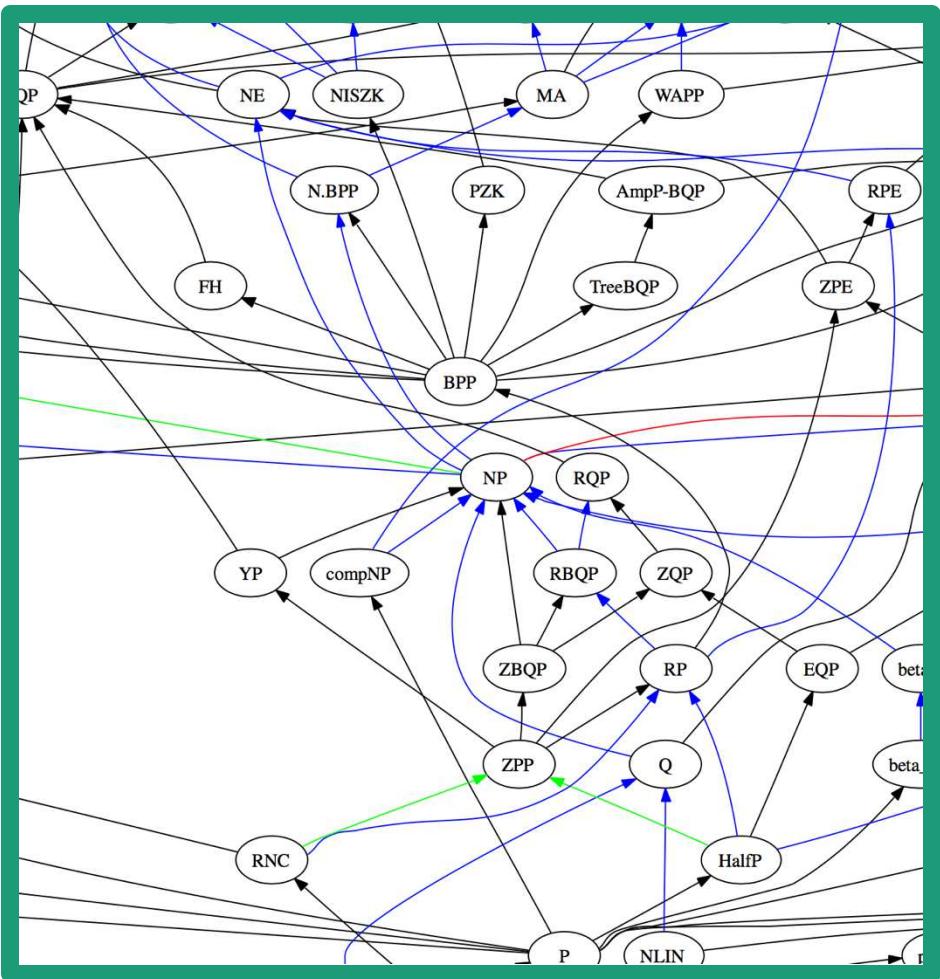
seamlessbayarea.org

(In real life it isn't so well connected 😞)



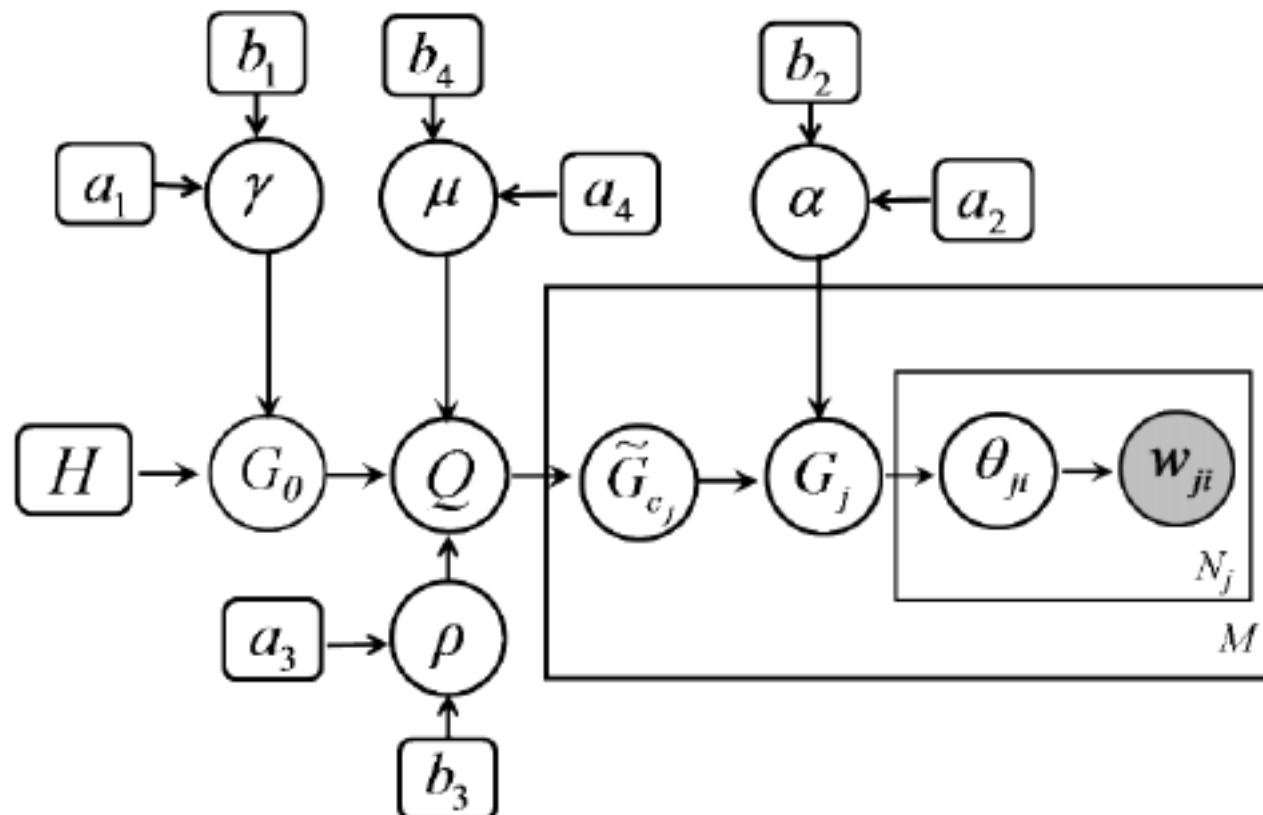
# Graphs

Complexity Zoo  
containment graph



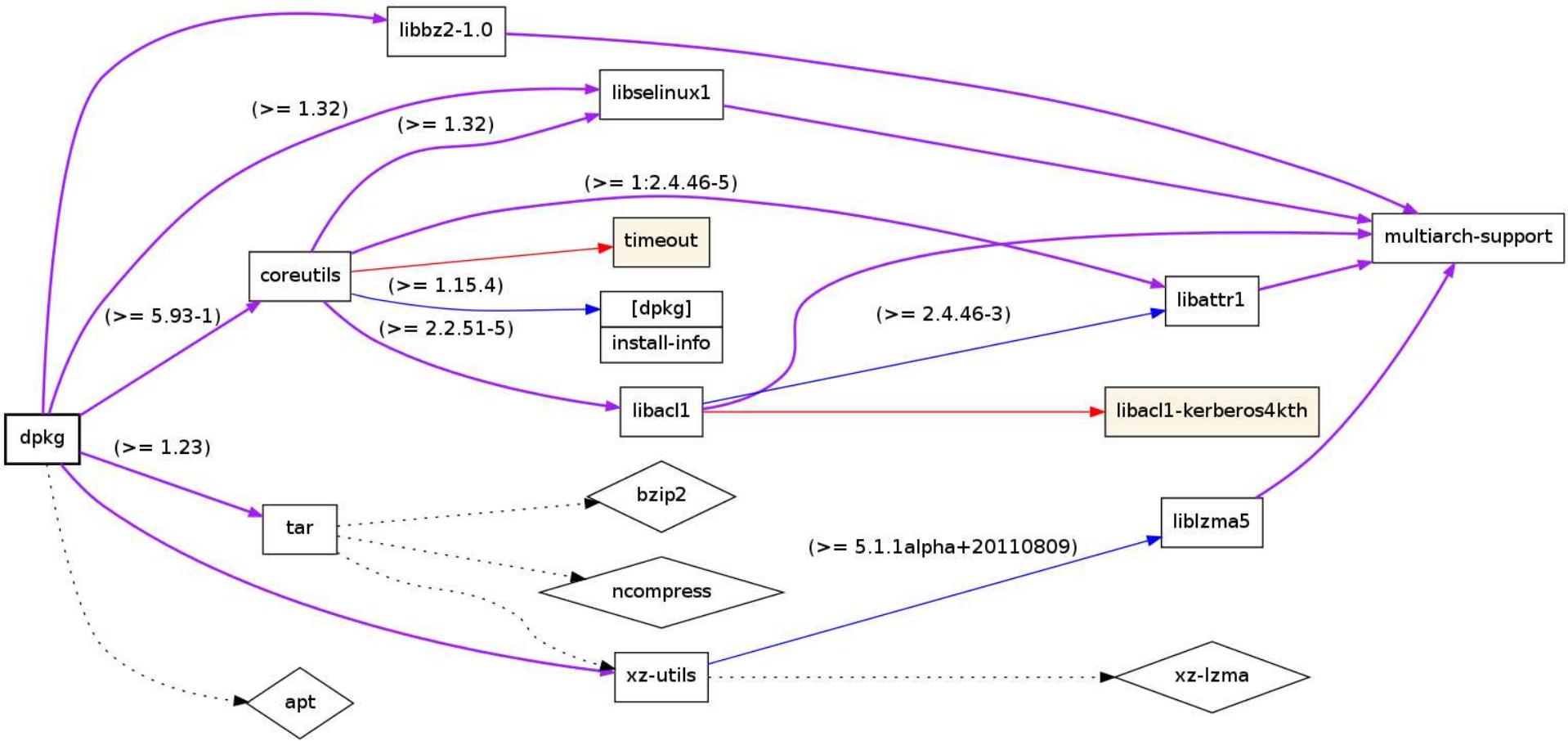
# Graphs

Graphical models



# Graphs

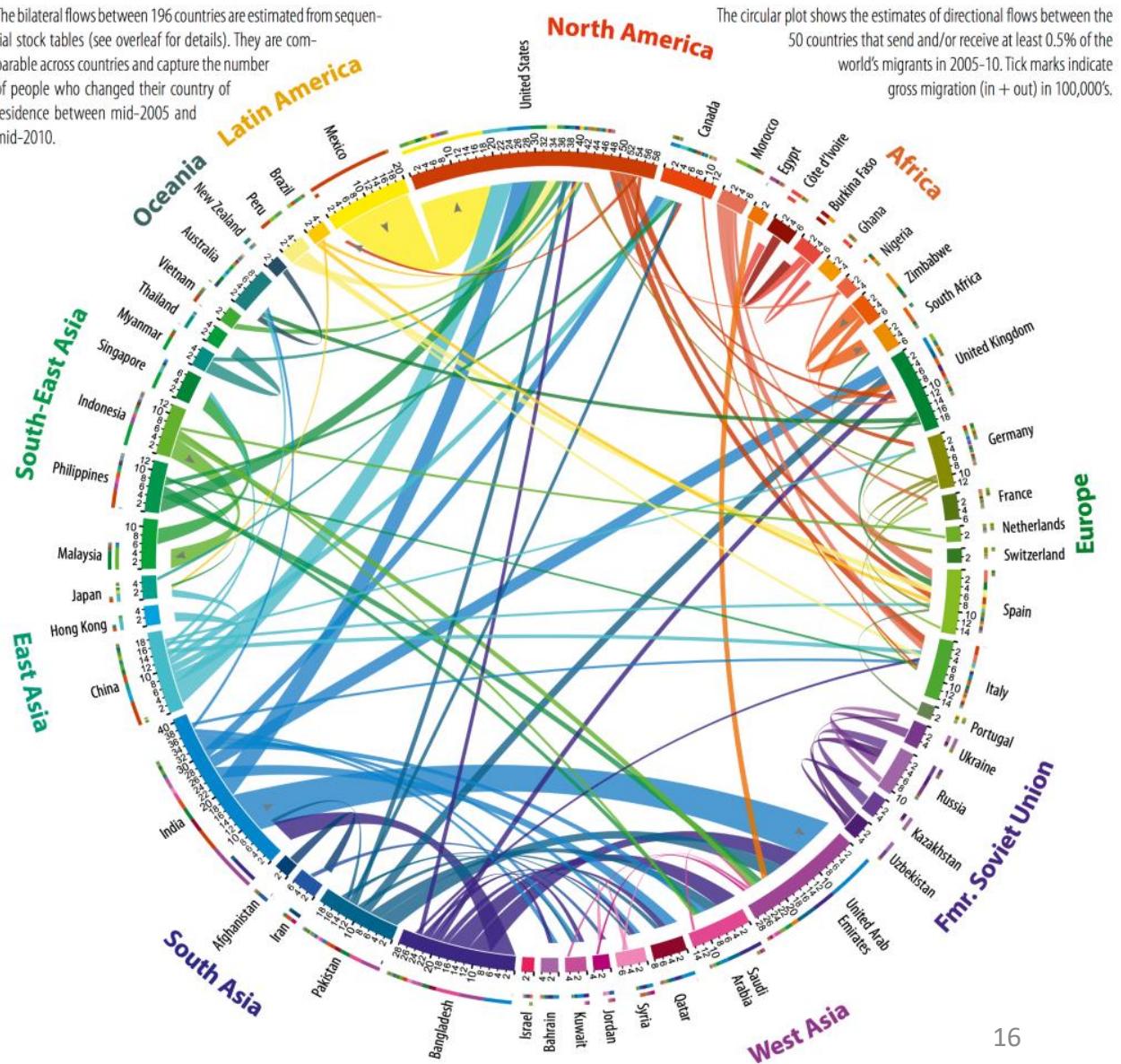
debian dependency (sub)graph



# Graphs

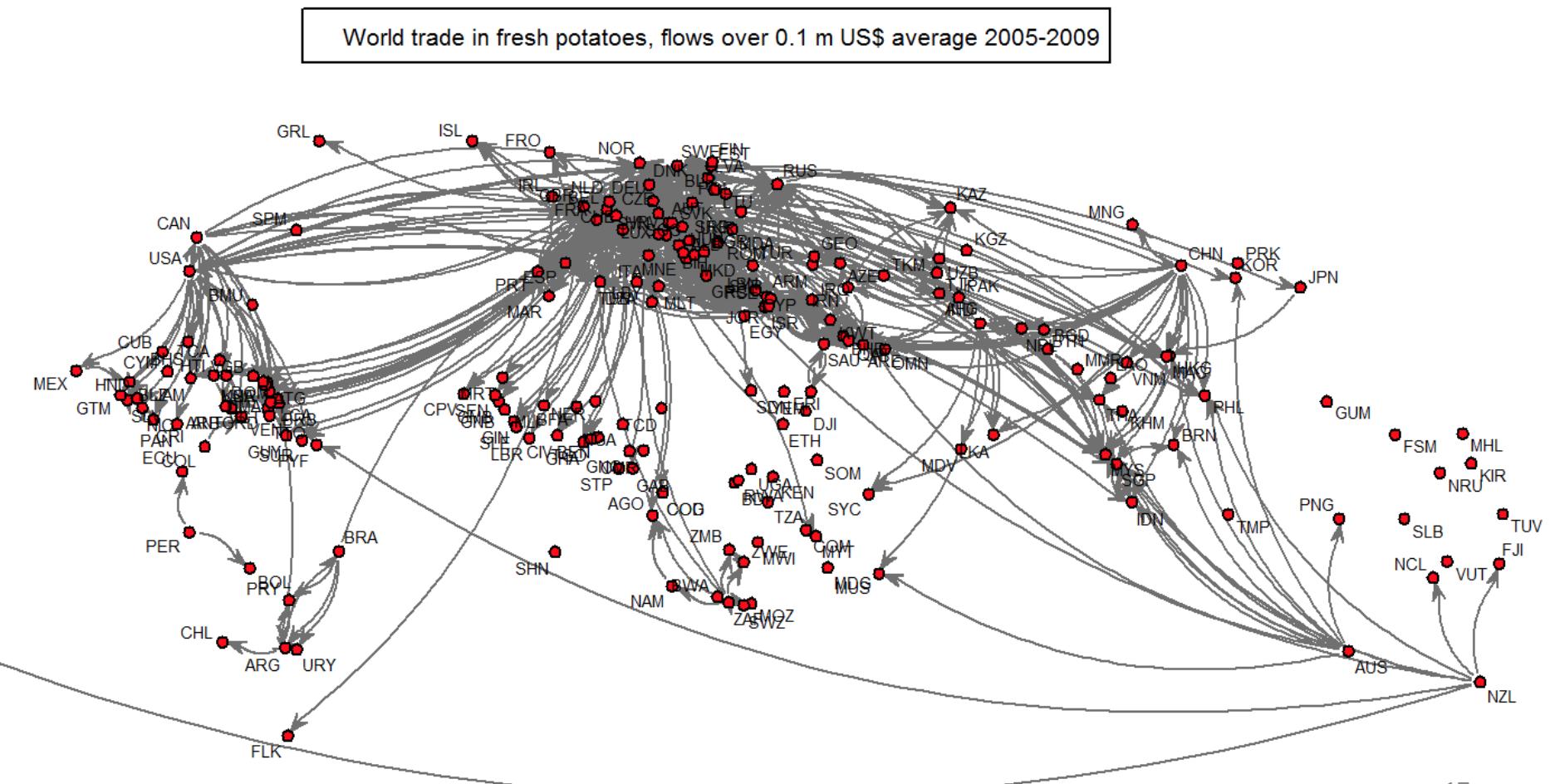
## Immigration flows

The bilateral flows between 196 countries are estimated from sequential stock tables (see overleaf for details). They are comparable across countries and capture the number of people who changed their country of residence between mid-2005 and mid-2010.



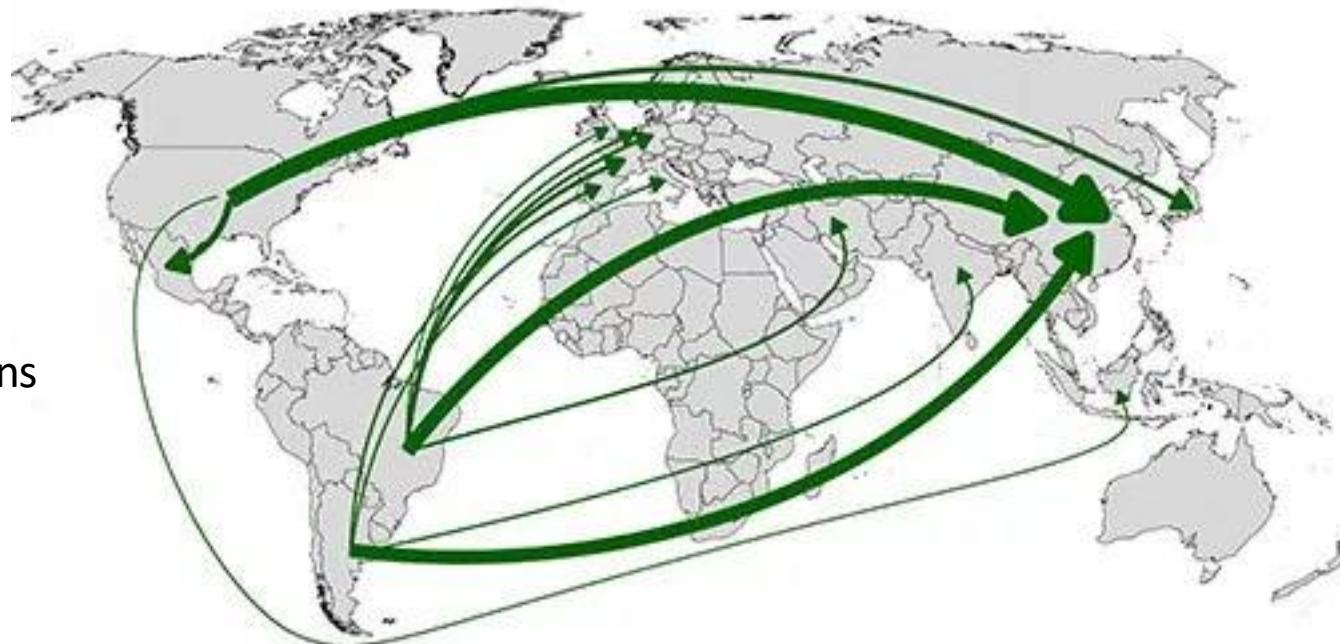
# Graphs

## Potato trade

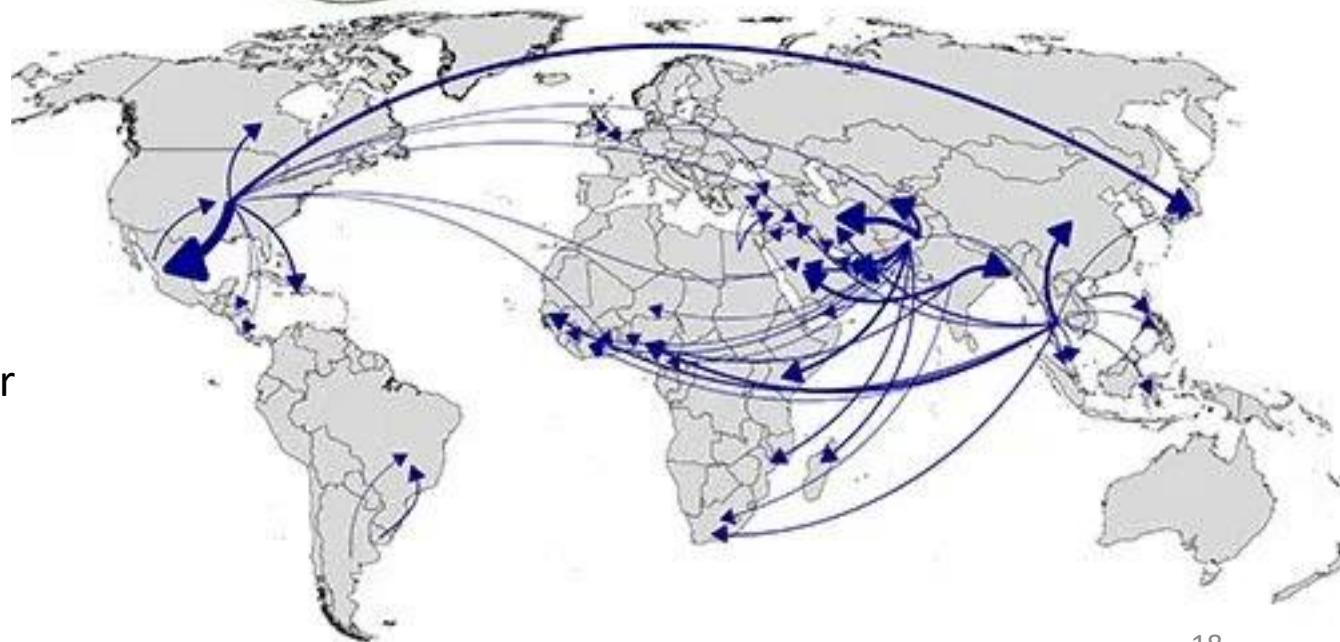


# Graphs

Soybeans

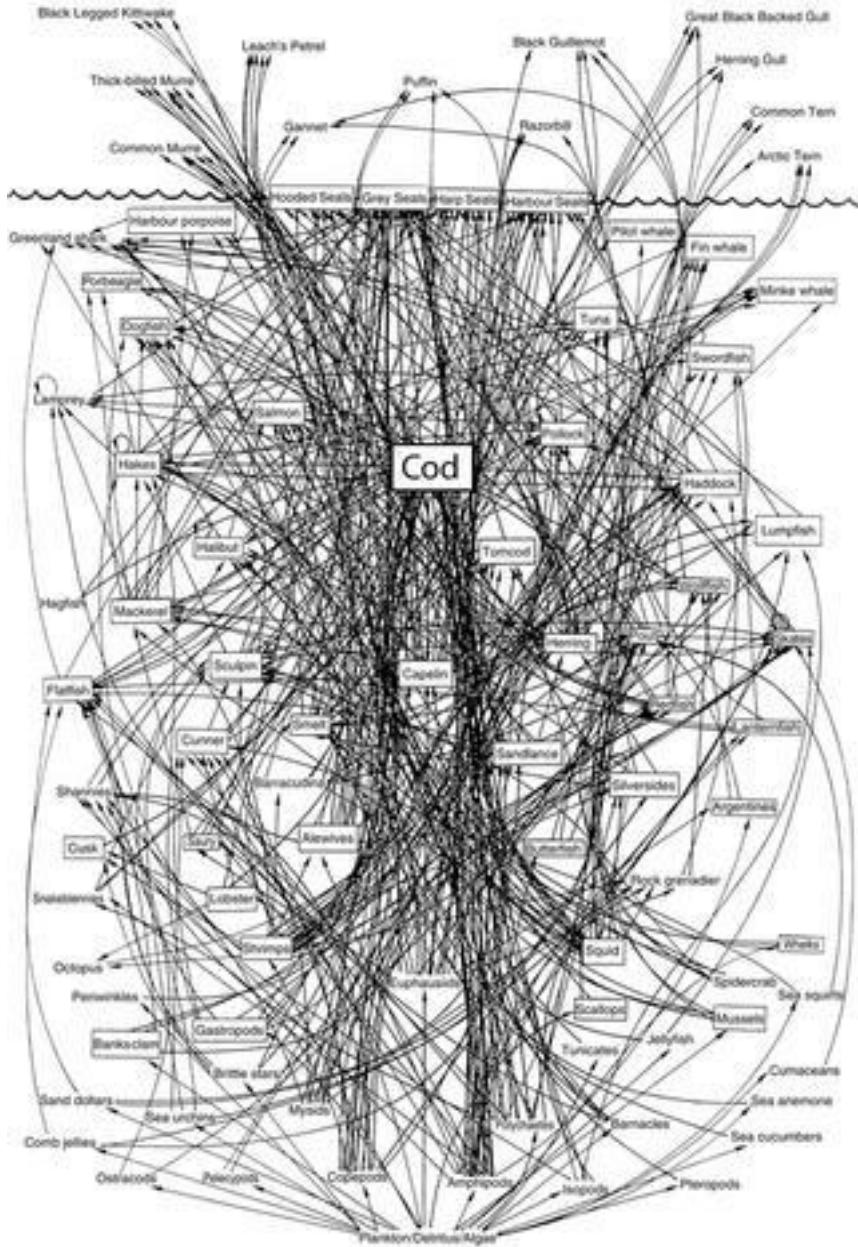


Water



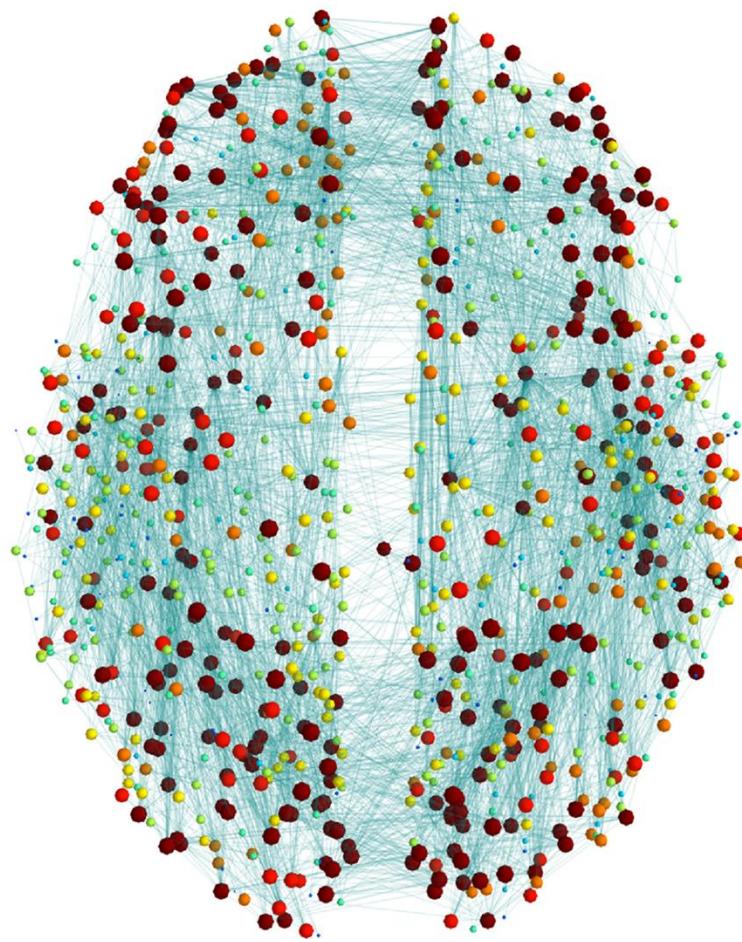
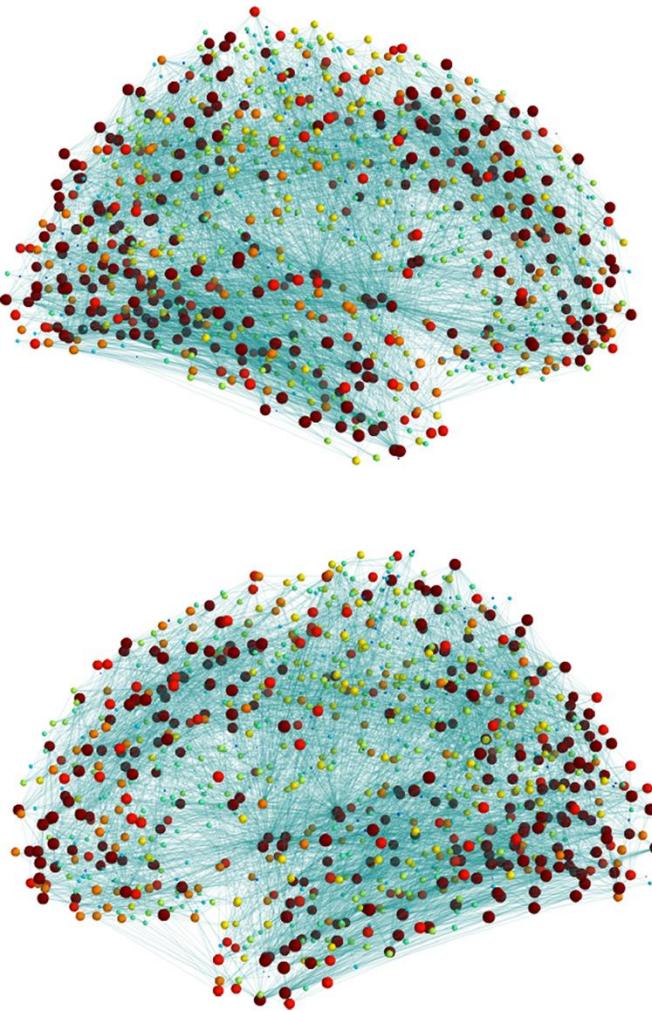
# Graphs

## What eats what in the Atlantic ocean?



# Graphs

Neural connections  
in the brain

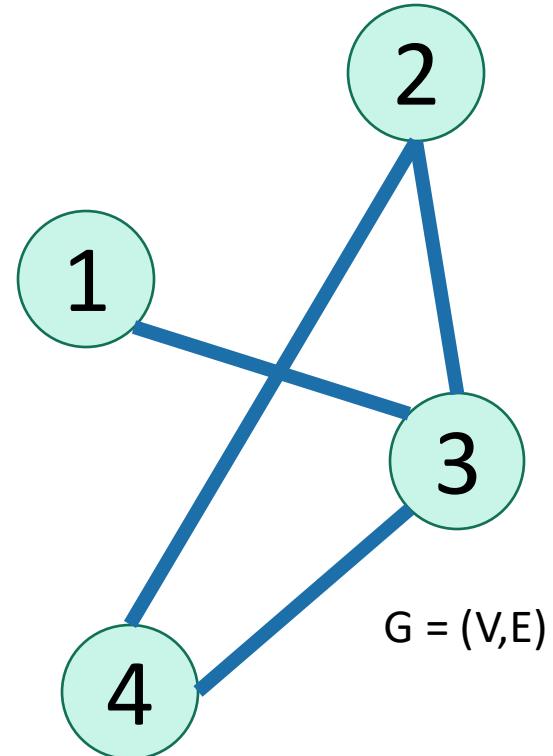


# Graphs

- **There are a lot of graphs.**
- We want to answer questions about them.
  - Community detection/clustering?
  - Efficient routing?
  - From pre-lecture exercise:
    - Computing Bacon numbers
    - Signing up for classes without violating pre-req constraints
    - How to distribute fish in tanks so that none of them will fight.
- This is what we'll do for the next several lectures.

# Undirected Graphs

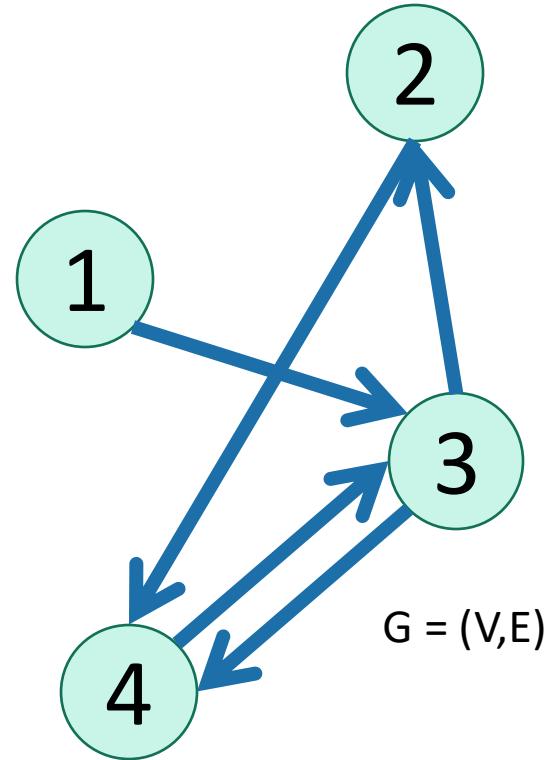
- An **undirected graph**  $G$  has:
  - A set  $V$  of vertices
  - A set  $E$  of edges
  - Formally,  $G = (V,E)$
- The **degree** of vertex is the number of edges coming out.
- The connected vertices are called **neighbors**.
- Example
  - $V = \{1,2,3,4\}$
  - $E = \{ \{1,3\}, \{2,4\}, \{3,4\}, \{2,3\} \}$



- The **degree** of vertex 4 is 2.
- Vertex 4's **neighbors** are 2 and 3

# Directed Graphs

- A directed graph  $G$  has:
  - A set  $V$  of vertices
  - A set  $E$  of **DIRECTED** edges
  - Formally,  $G = (V,E)$
- The **in-degree** of vertex is the number of edges coming in.
- The **out-degree** of vertex is the number of edges going out.
- Example
  - $V = \{1,2,3,4\}$
  - $E = \{ (1,3), (2,4), (3,4), (4,3), (3,2) \}$

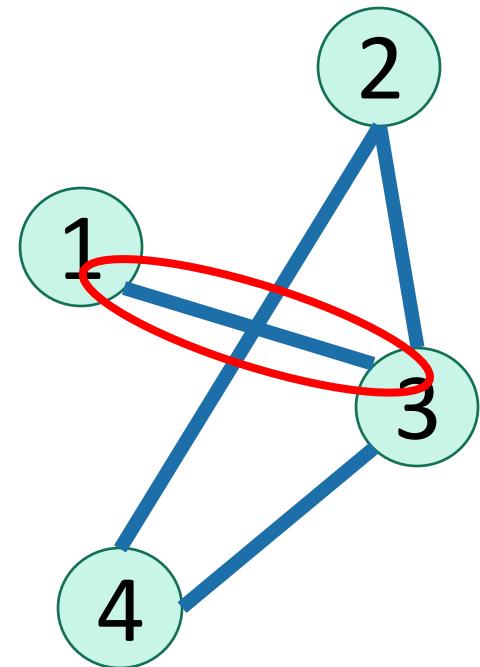


- The **in-degree** of vertex 4 is 2.
- The **out-degree** of vertex 4 is 1.
- Vertex 4's **incoming neighbors** are 2,3
- Vertex 4's **outgoing neighbor** is 3.

# How do we represent graphs?

- Option 1: adjacency matrix

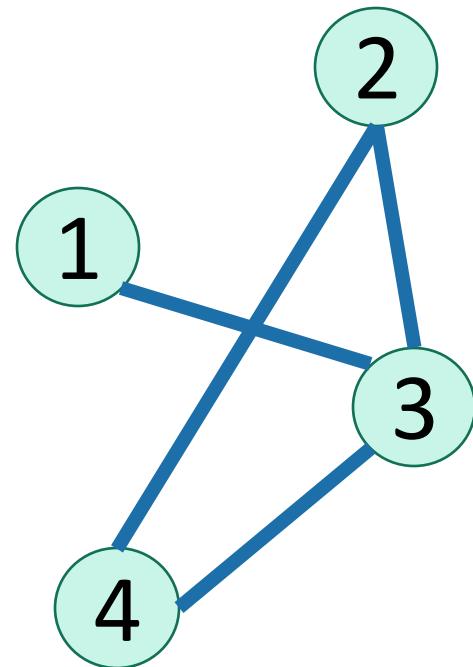
	1	2	3	4
1	0	0	1	0
2	0	0	1	1
3	1	1	0	1
4	0	1	1	0



# How do we represent graphs?

- Option 1: adjacency matrix

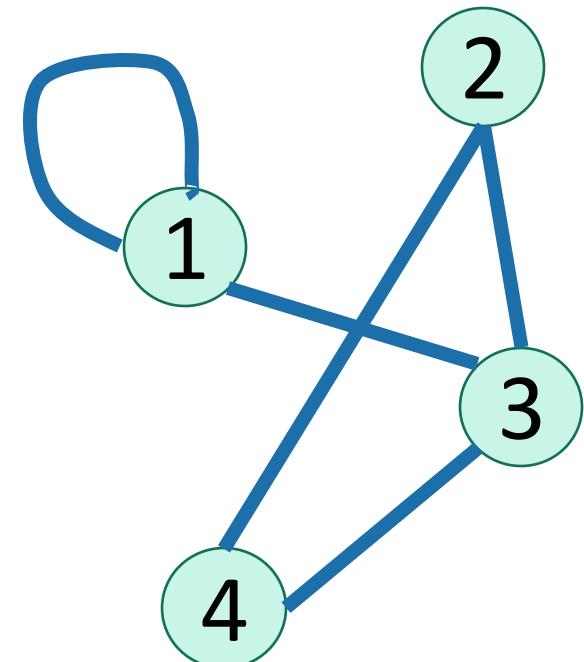
$$\begin{bmatrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix} \end{bmatrix}$$



# How do we represent graphs?

- Option 1: adjacency matrix

$$\begin{bmatrix} & \begin{matrix} 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix} \end{bmatrix}$$

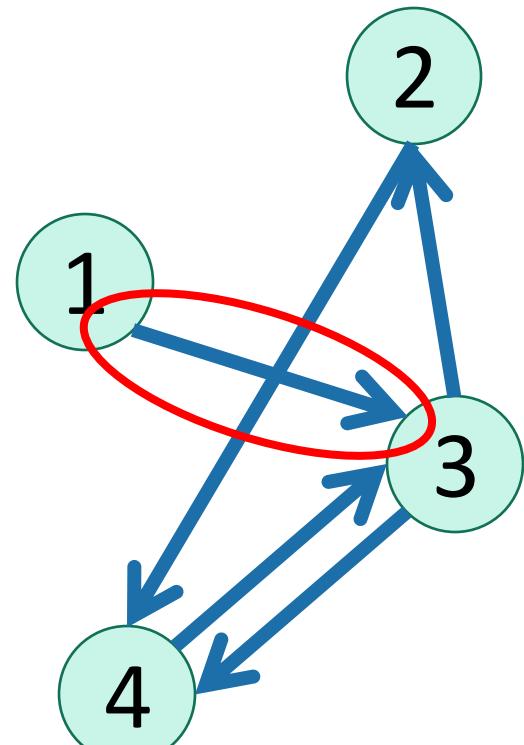


# How do we represent graphs?

directed

- Option 1: adjacency matrix

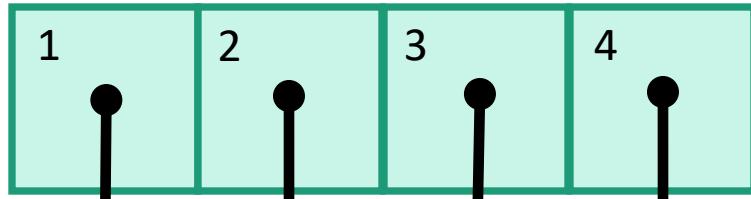
Destination					
		1	2	3	4
Source	1	0	0	1	0
	2	0	0	0	1
3	0	1	0	1	1
4	0	0	1	0	0



Note: different sources define this data structure differently. This is how Algs. Illuminated does it.

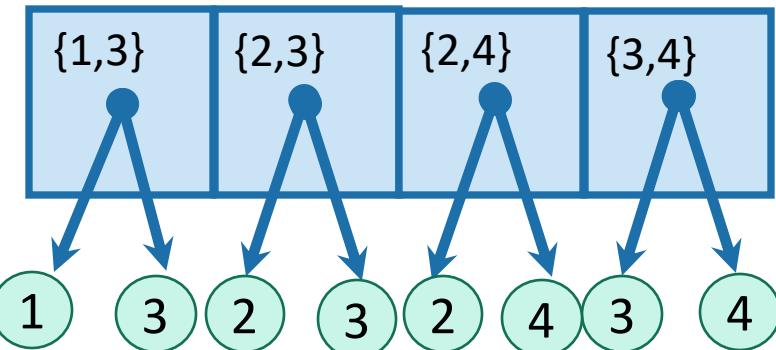
# How do we represent graphs?

- Option 2: adjacency lists.



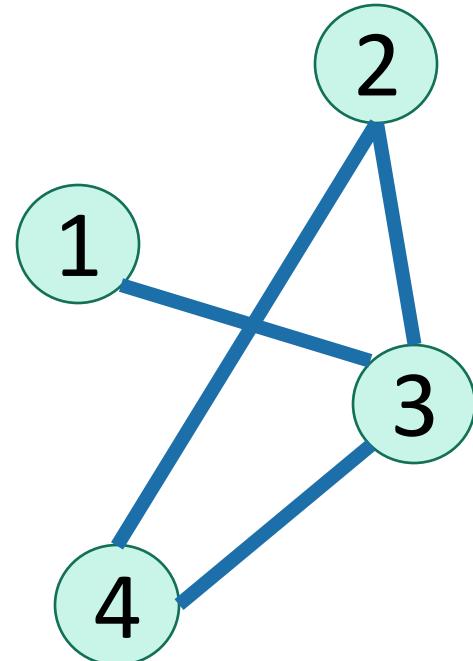
One array  
for the  
vertices

Linked lists  
of  
edges. These are  
pointers down to  
the “edges” array.



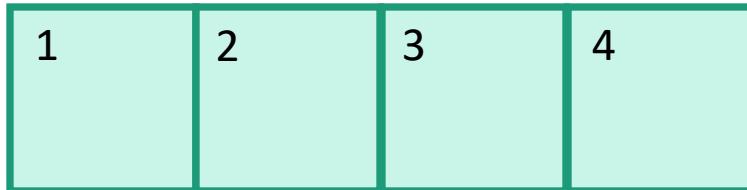
One array  
for the  
edges

These are pointers into the “vertex” array



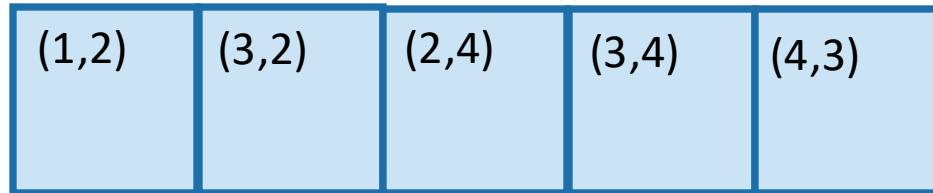
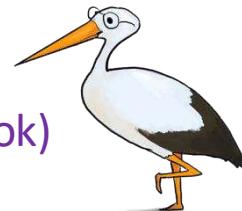
# How do we represent graphs?

- Option 2: adjacency lists.

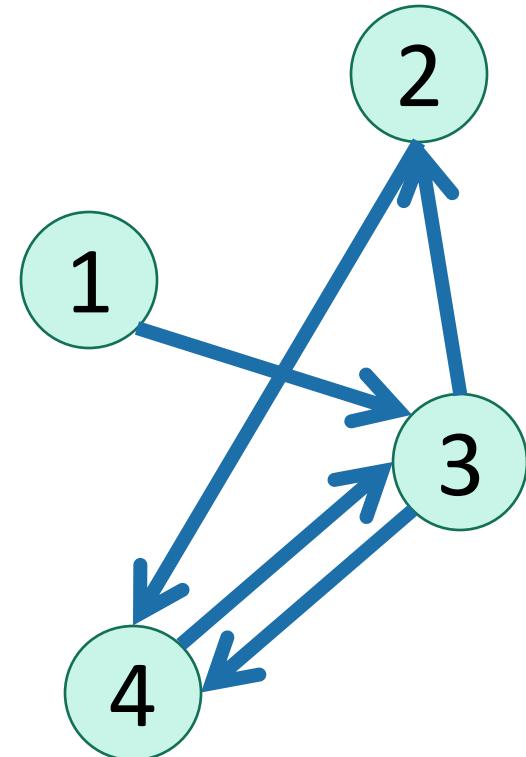


One array  
for the  
vertices

You think about it!  
(Or check the textbook)



One array  
for the  
edges

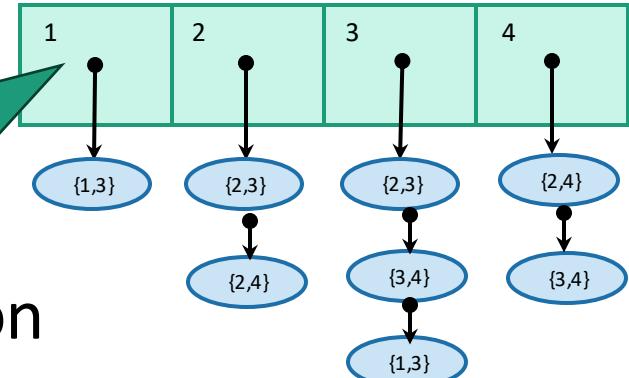


Note: different sources define this data structure differently. This is how Algs. Illuminated does it.

# In either case

## Vertex 1:

- Ptr to head of linked list for edges
- Name
- Age
- Start time
- Finish time



- Vertices can store other information
  - Attributes (name, IP address, ...)
  - helper info for algorithms that we will perform on the graph
- Basic operations:
  - **Edge Membership:** Is edge e in E?
  - **Neighbor Query:** What are the neighbors of vertex v?

# Trade-offs

Say there are  $n$  vertices  
and  $m$  edges.

$$\begin{bmatrix} 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 1 \\ 1 & 1 & 0 & 1 \\ 0 & 1 & 1 & 0 \end{bmatrix}$$

Edge membership  
Is  $e = \{v,w\}$  in  $E$ ?

$O(1)$

Neighbor query  
Give me  $v$ 's neighbors.

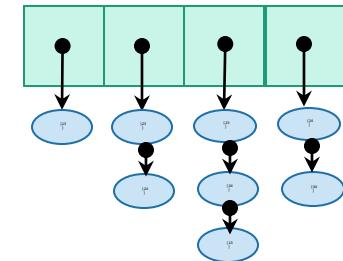
$O(n)$

Space requirements

$O(n^2)$

See Lecture 9 IPython notebook for an actual implementation!

Adjacency lists are generally better for **sparse** graphs  
(where  $m \ll n^2$ )



$O(\deg(v))$  or  
 $O(\deg(w))$

$O(\deg(v))$

$O(n + m)$

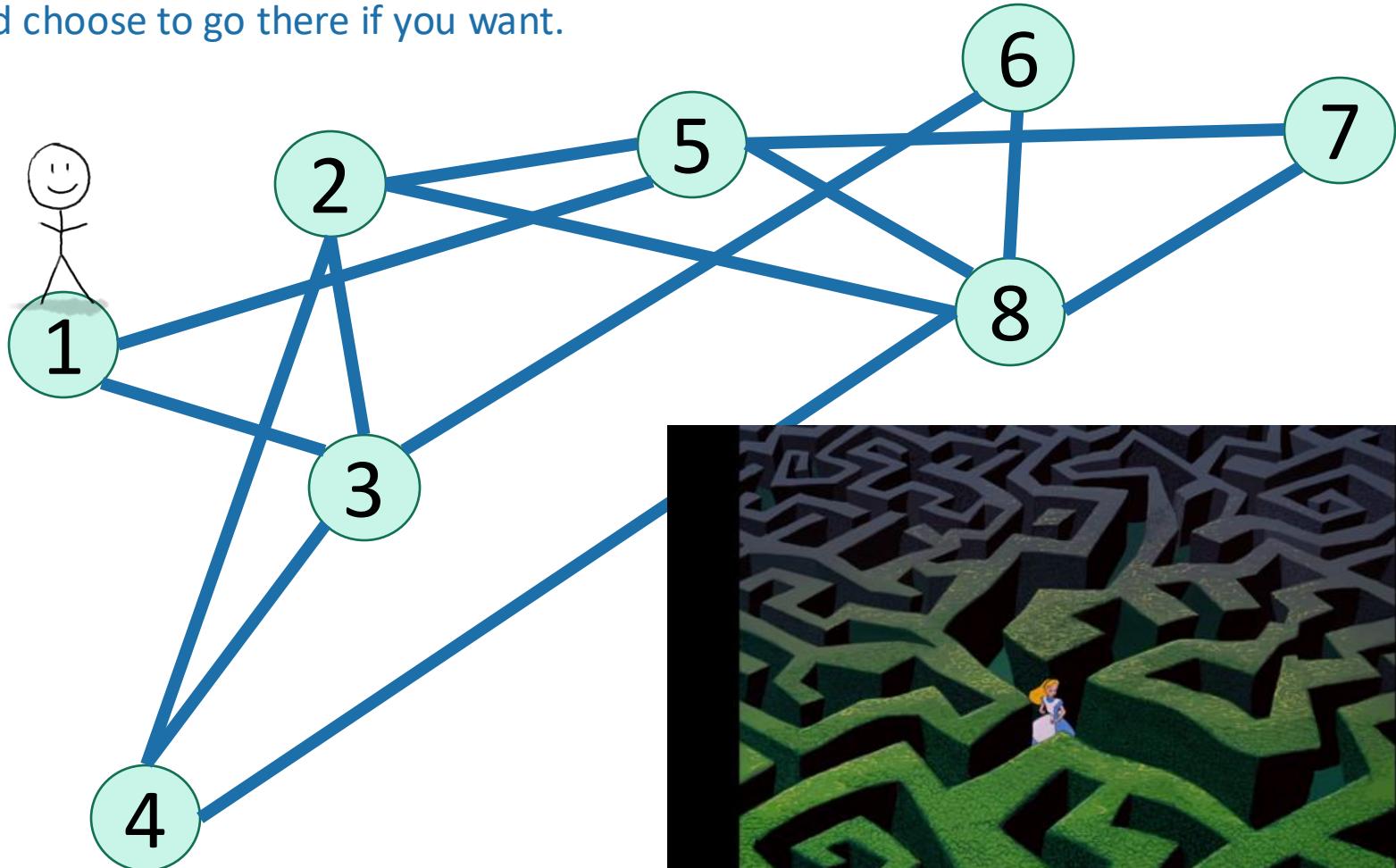
We'll assume this representation for  
the rest of the class

# Part 1: Depth-first search

labyrinth

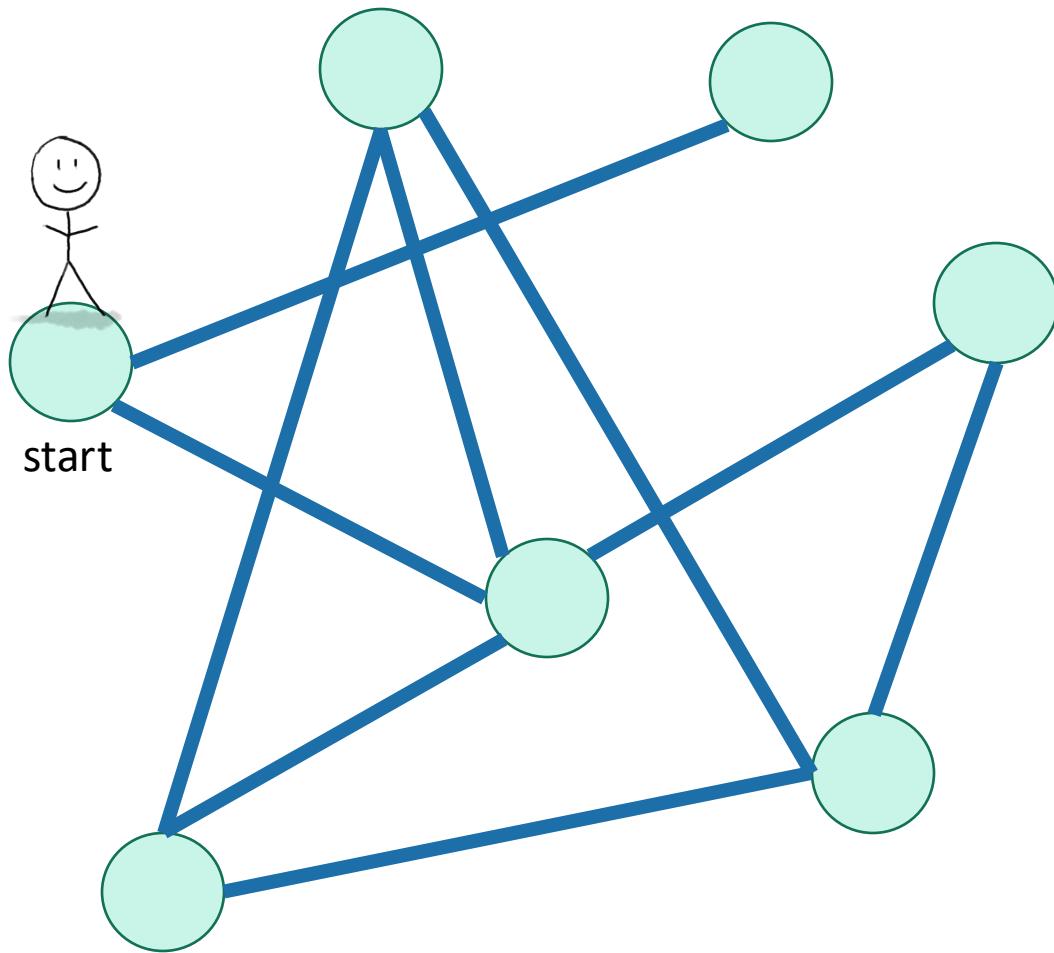
# How do we explore a graph?

At each node, you can get a list of neighbors,  
and choose to go there if you want.



# Depth First Search

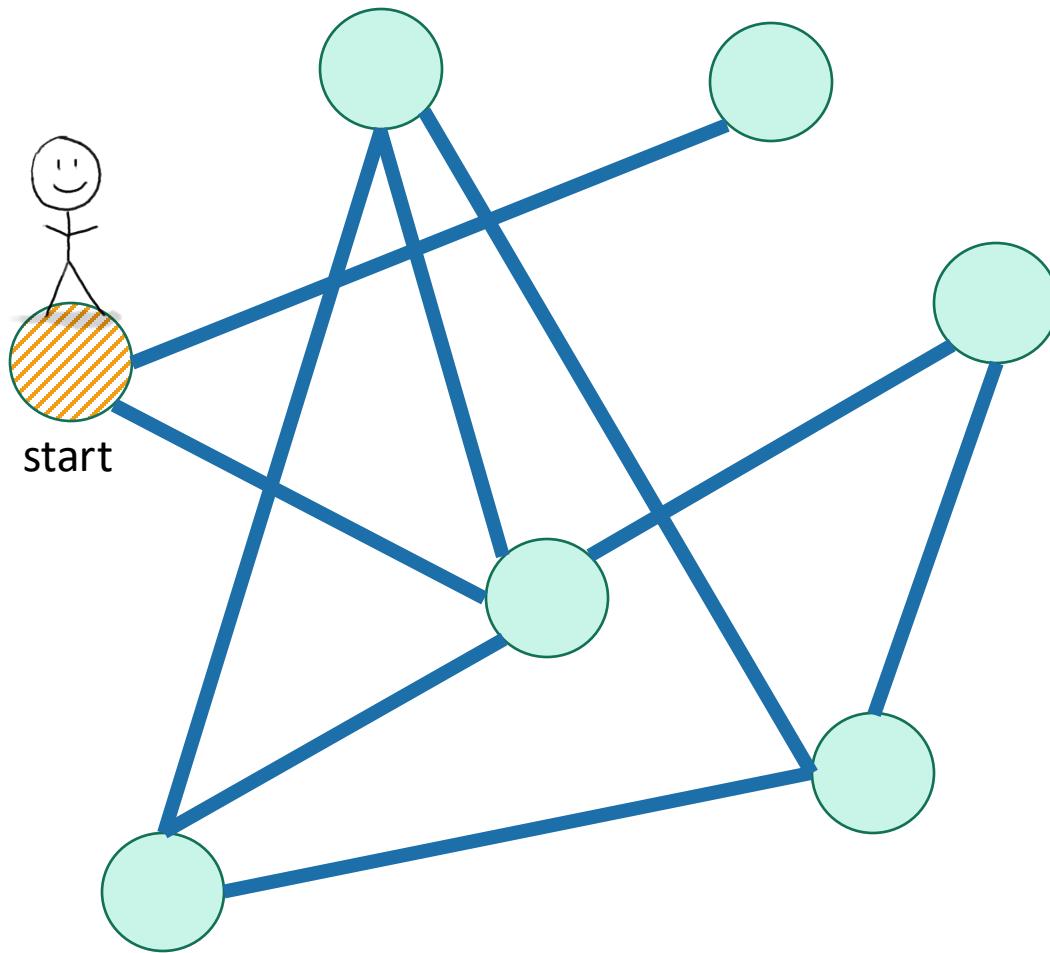
Exploring a labyrinth with chalk and a piece of string



- Not been there yet
- Been there, haven't explored all the paths out.
- Been there, have explored all the paths out.

# Depth First Search

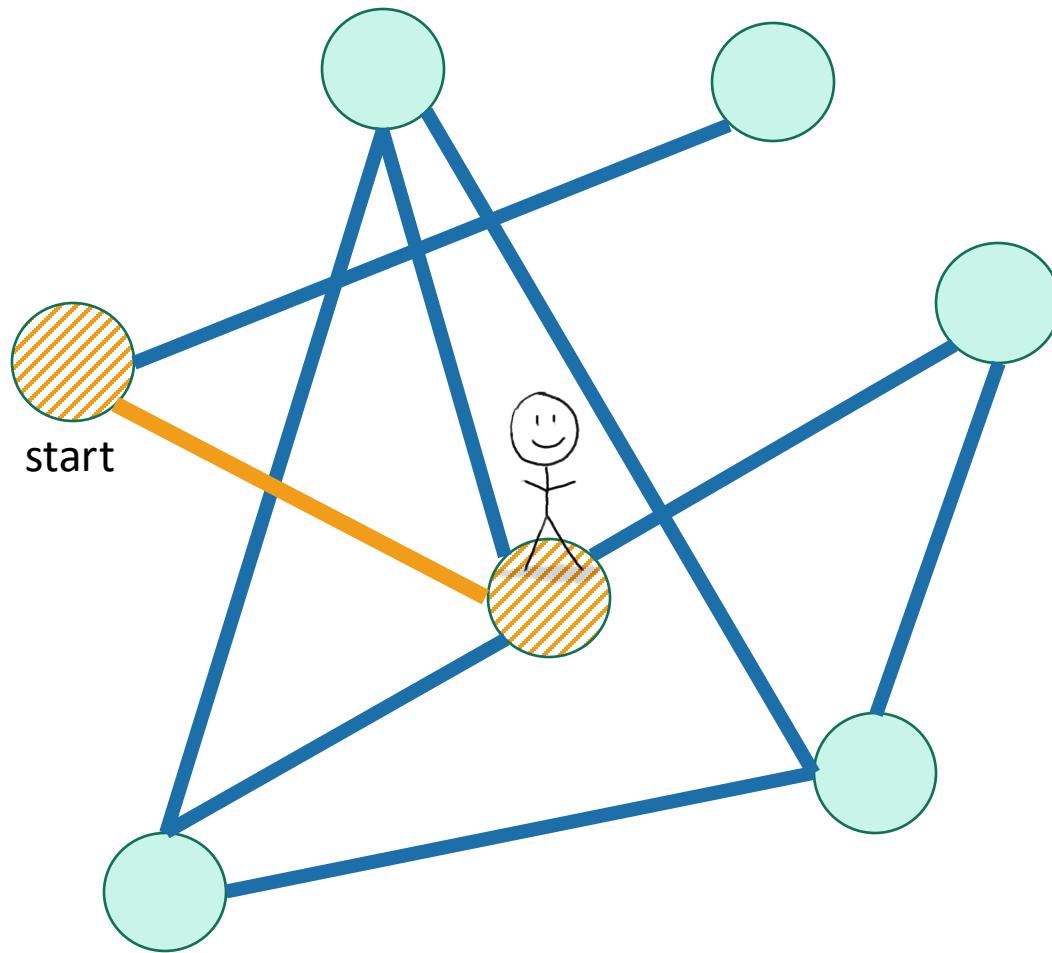
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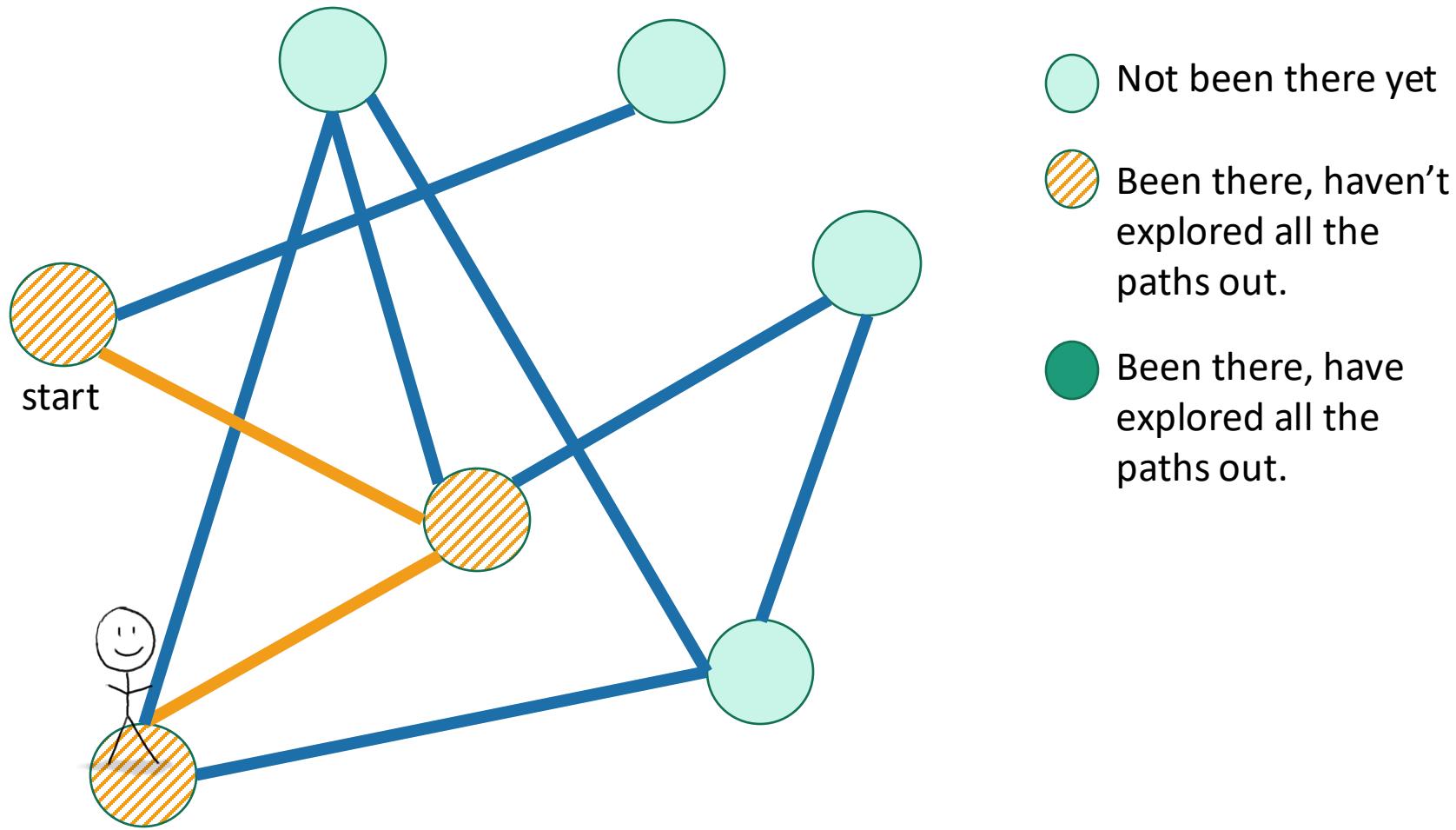
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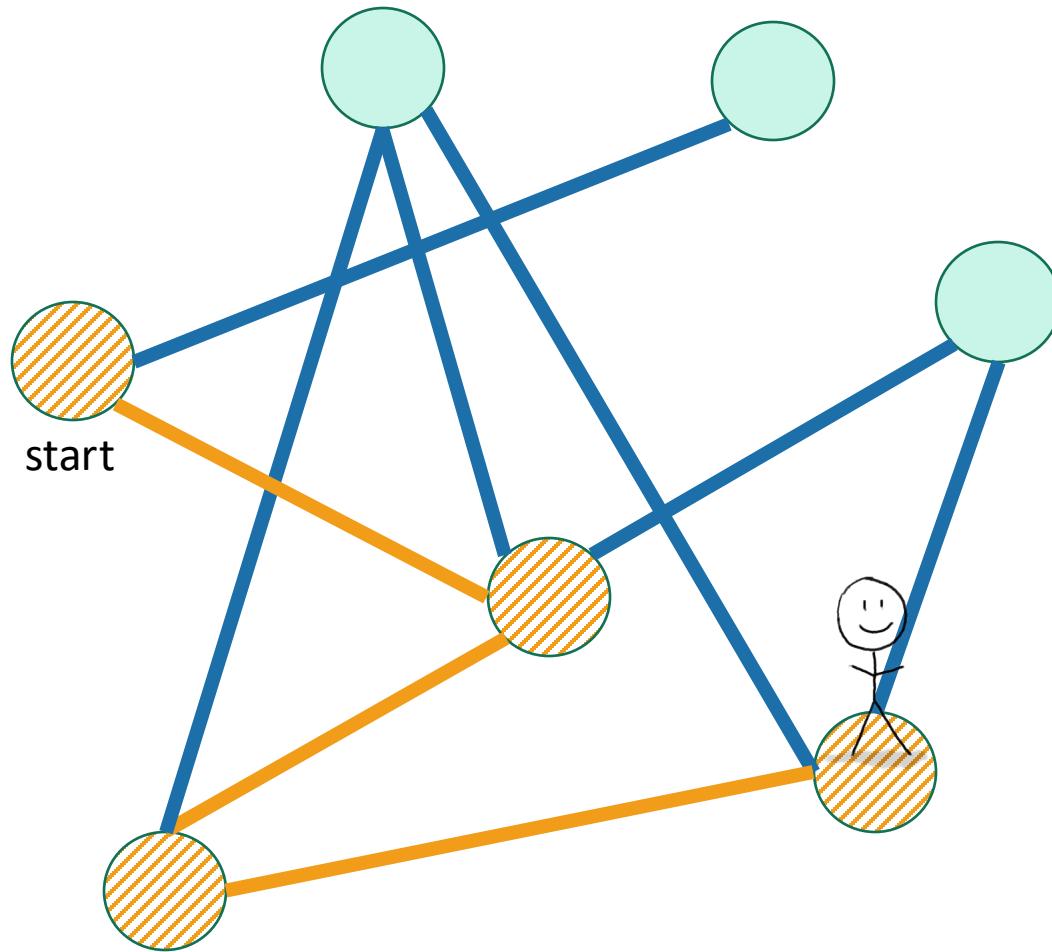
# Depth First Search

Exploring a labyrinth with chalk and a piece of string



# Depth First Search

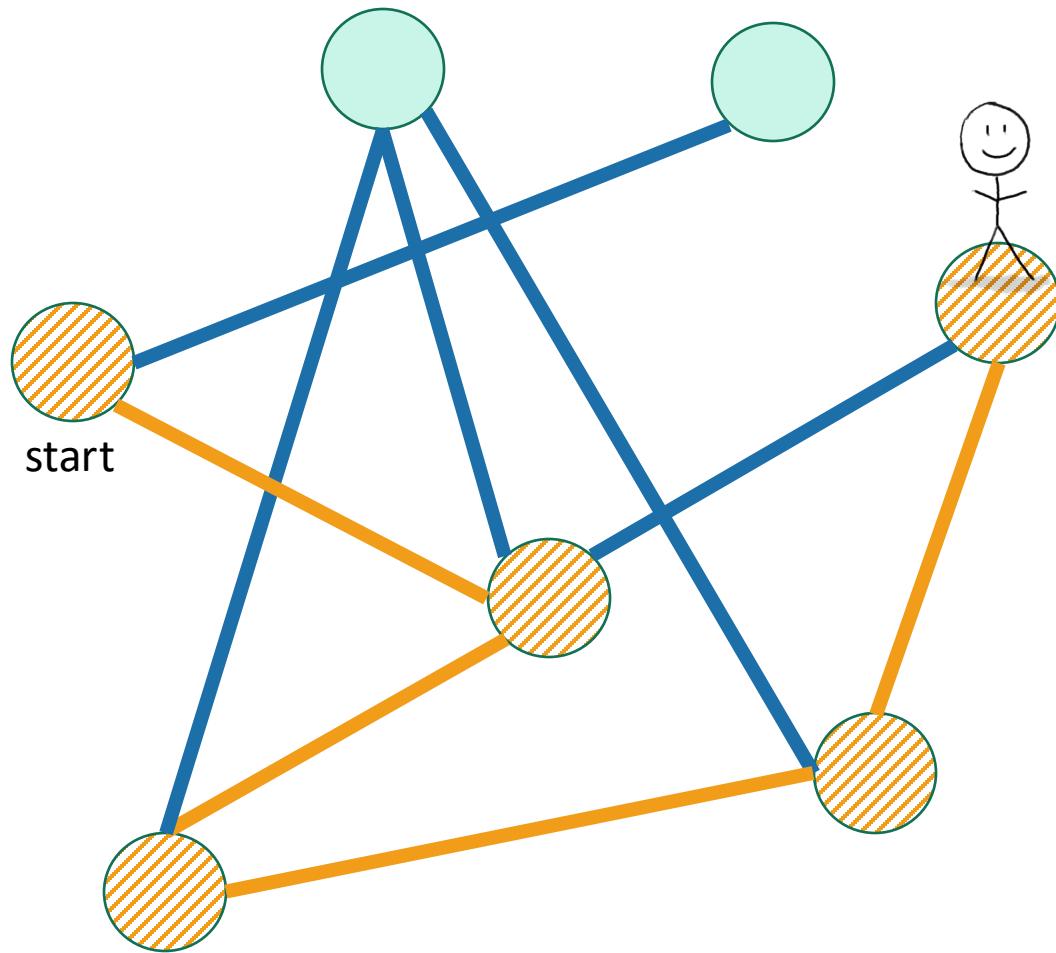
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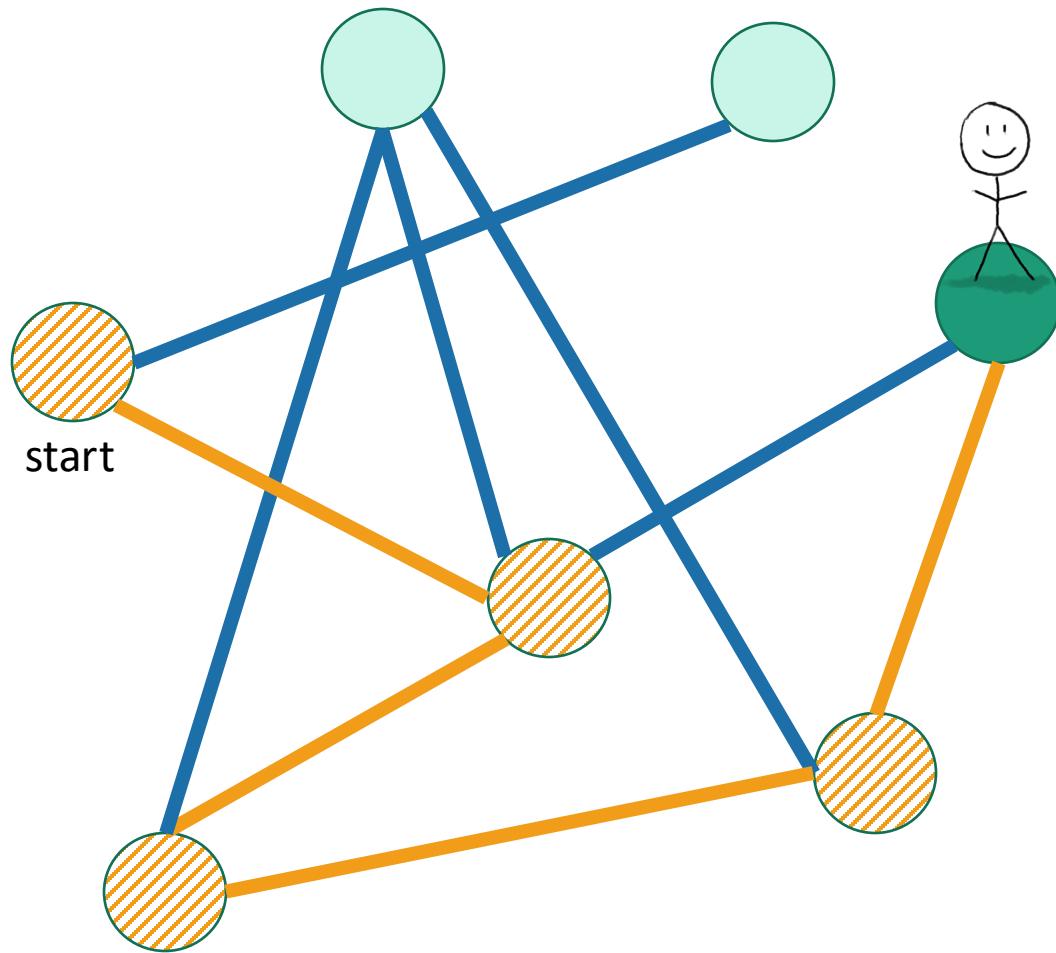
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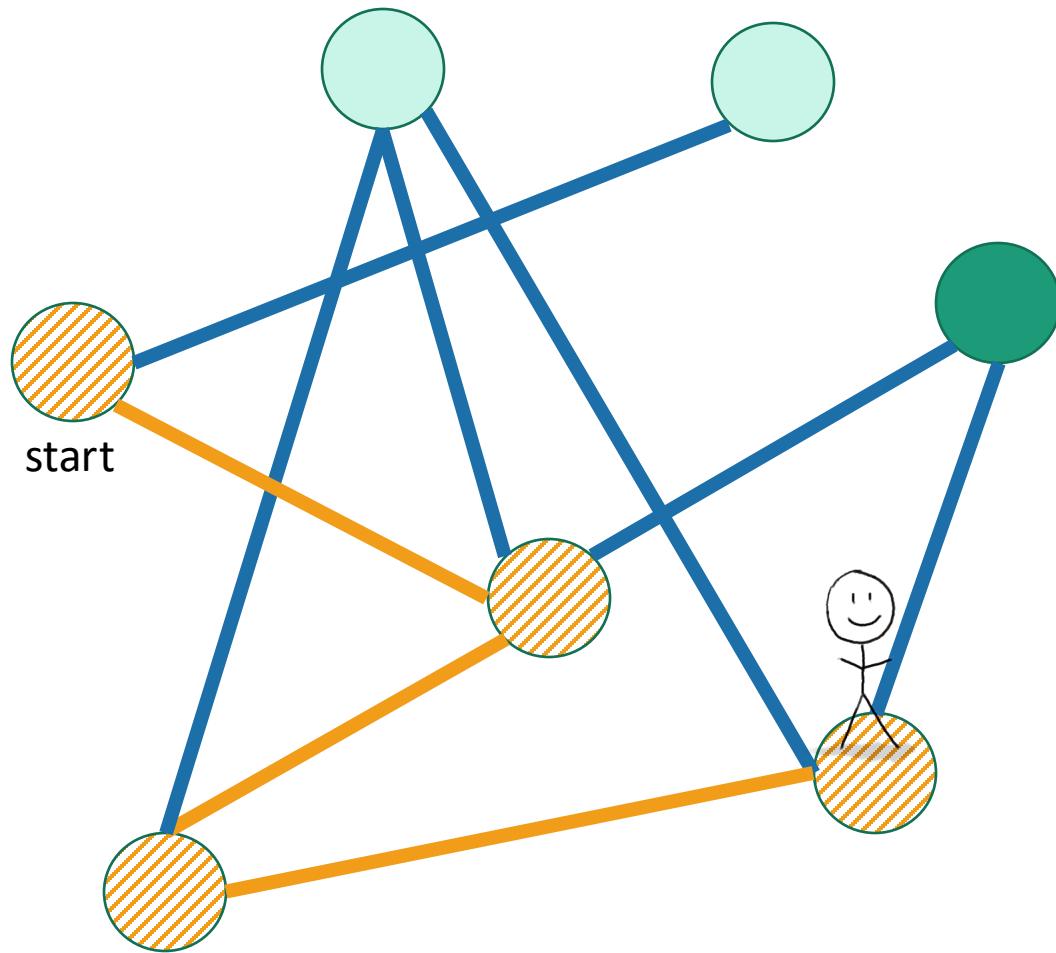
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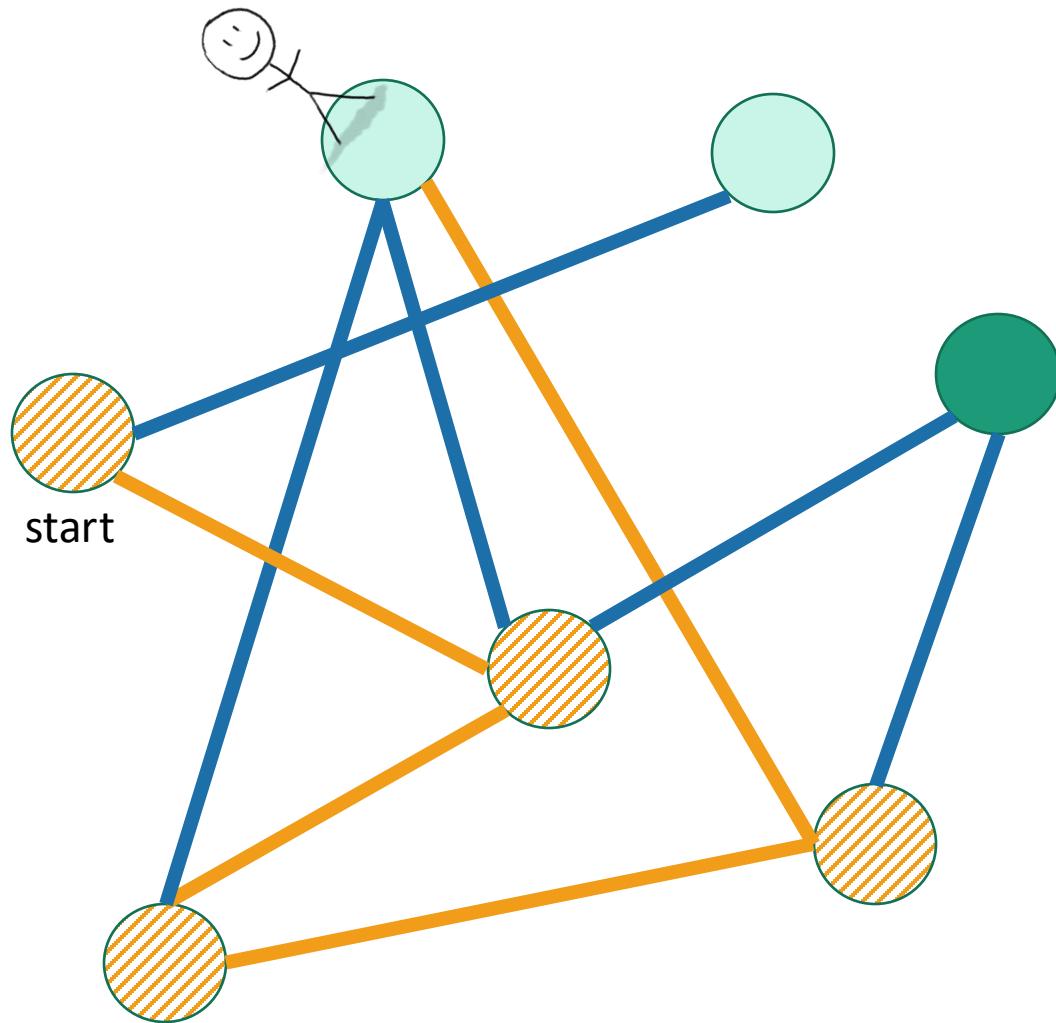
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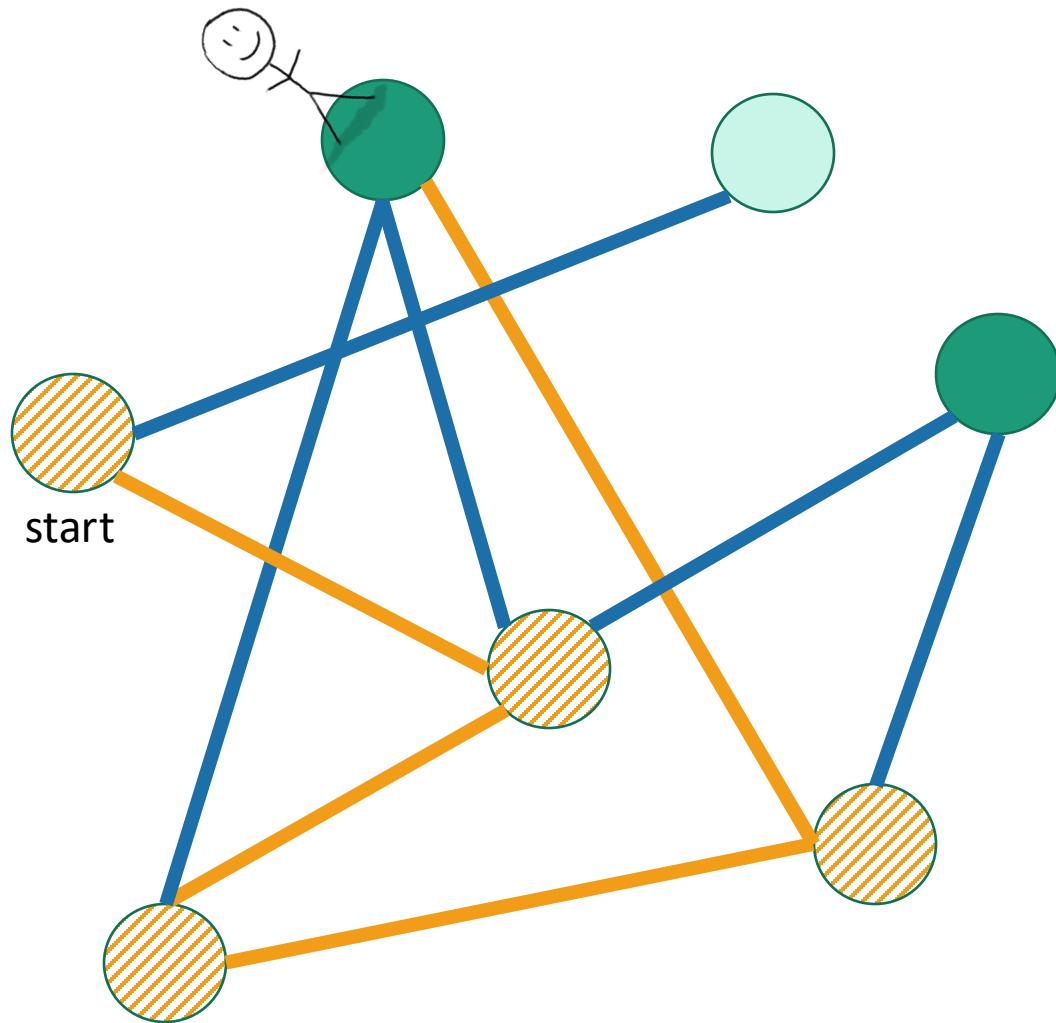
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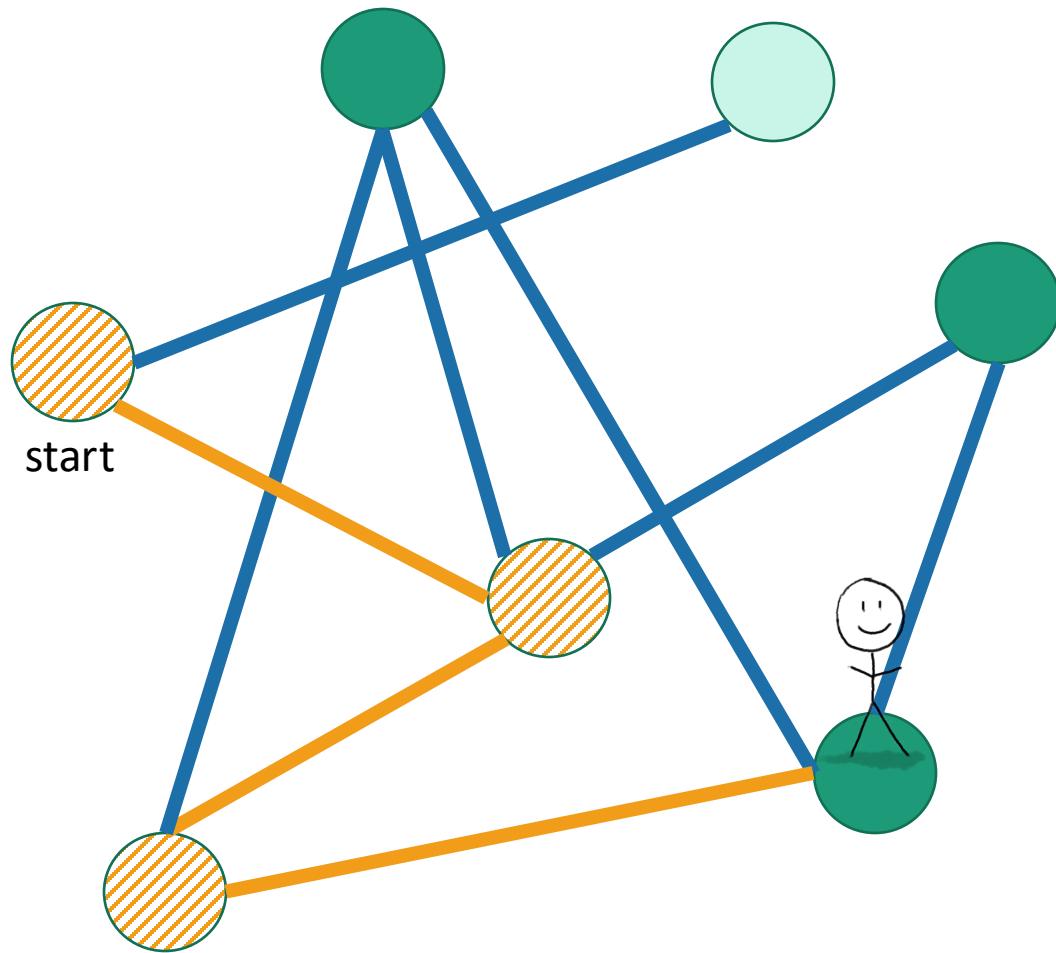
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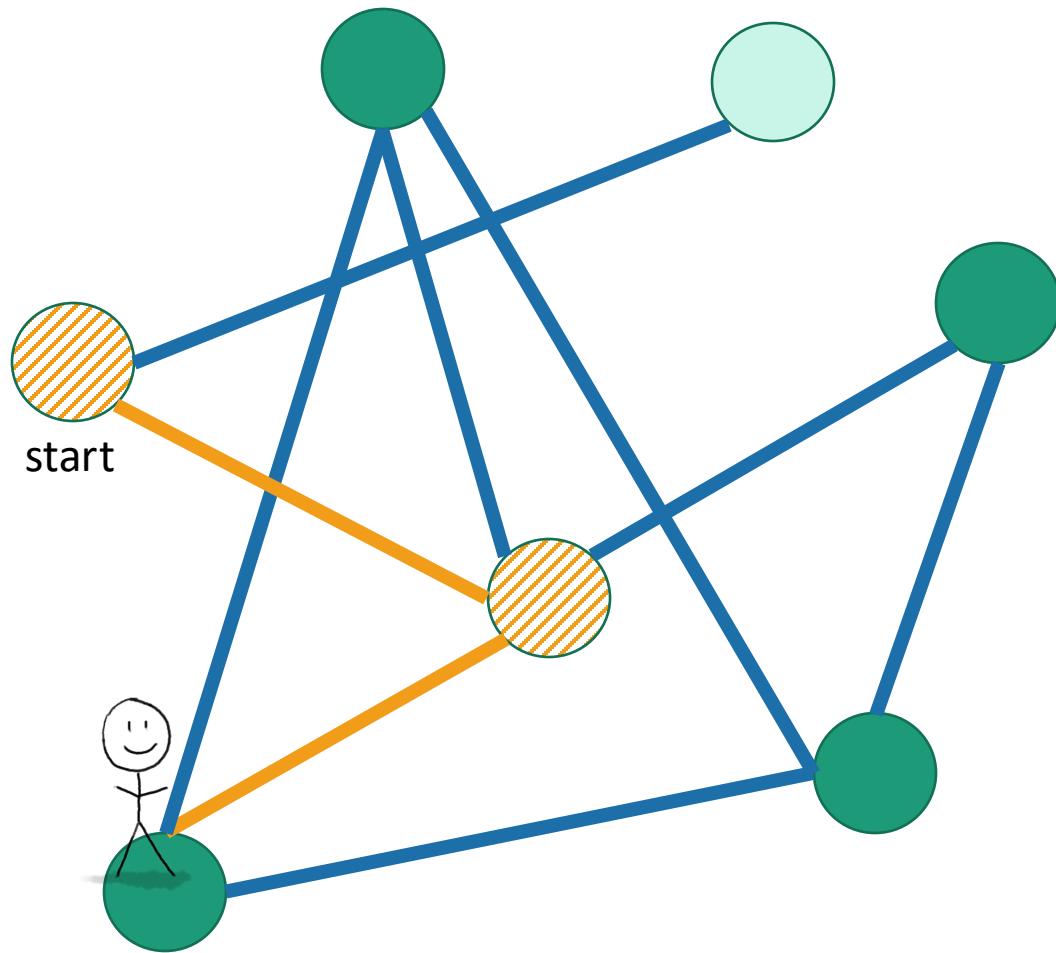
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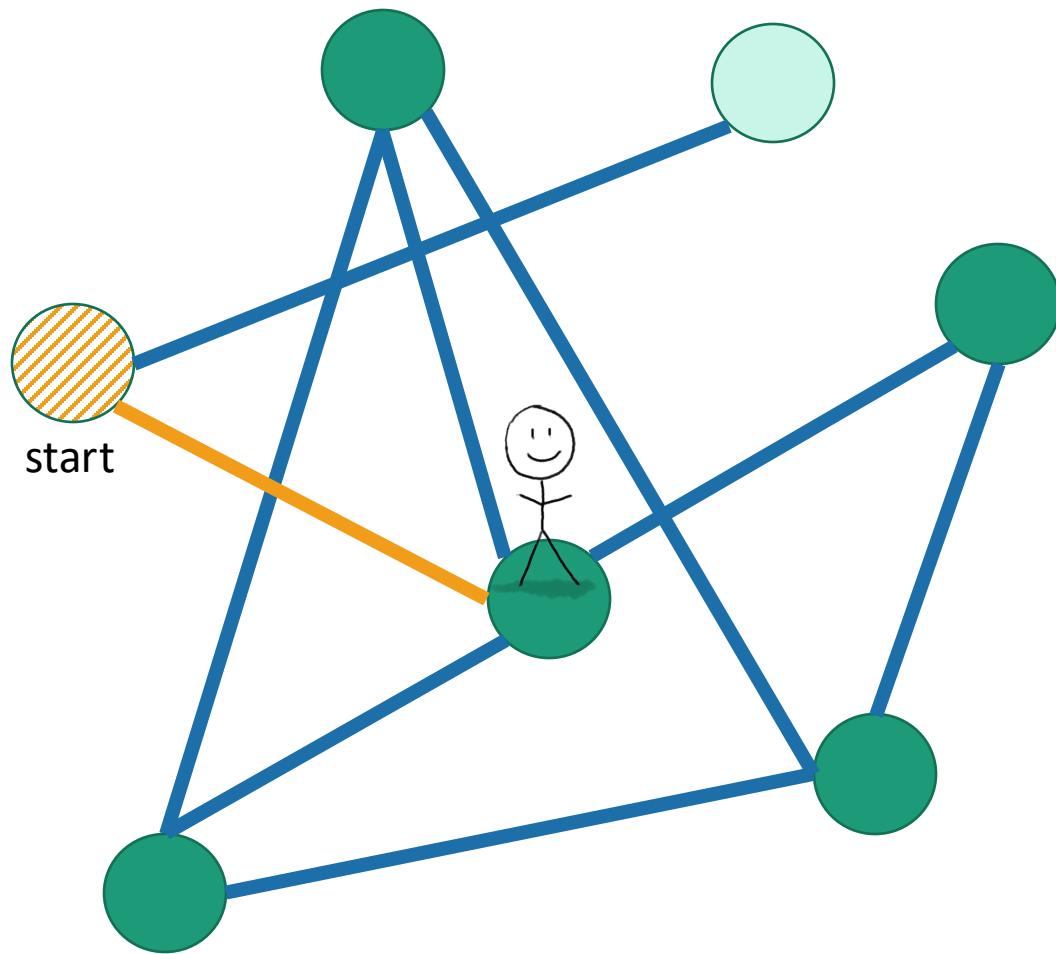
Exploring a labyrinth with chalk and a piece of string



- Not been there yet
- Been there, haven't explored all the paths out.
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# Depth First Search

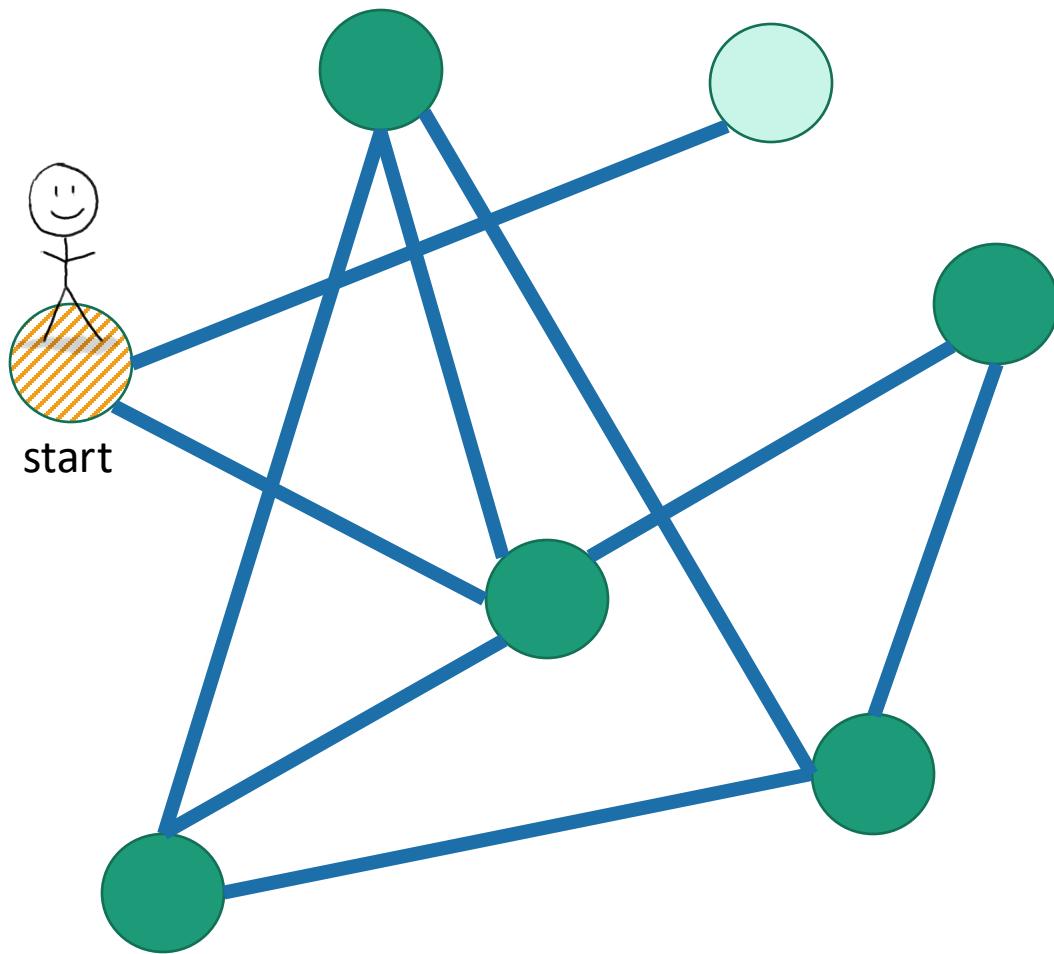
Exploring a labyrinth with chalk and a piece of string



- Light green circle: Not been there yet
- Orange striped circle: Been there, haven't explored all the paths out.
- Solid teal circle: Been there, have explored all the paths out.

# Depth First Search

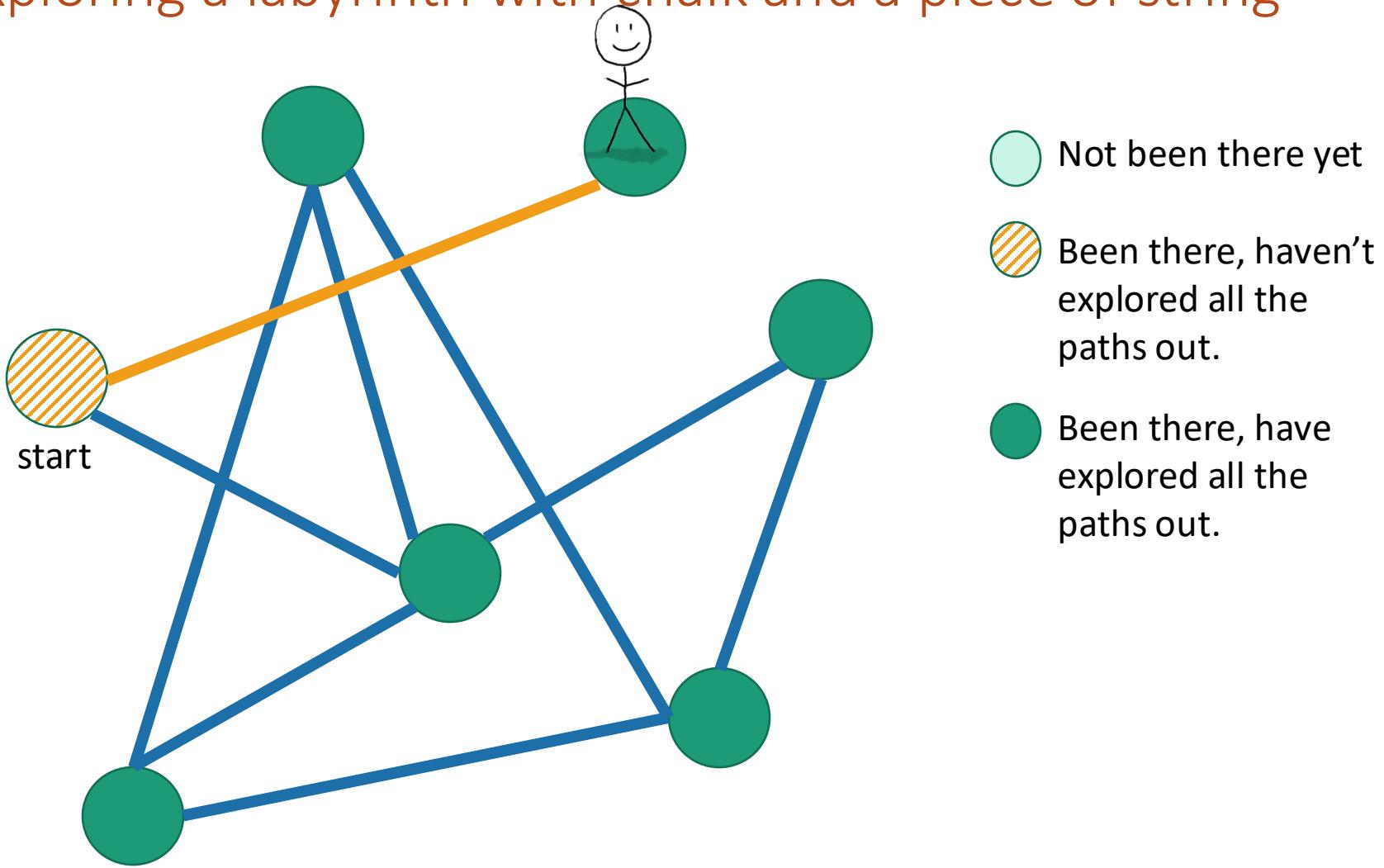
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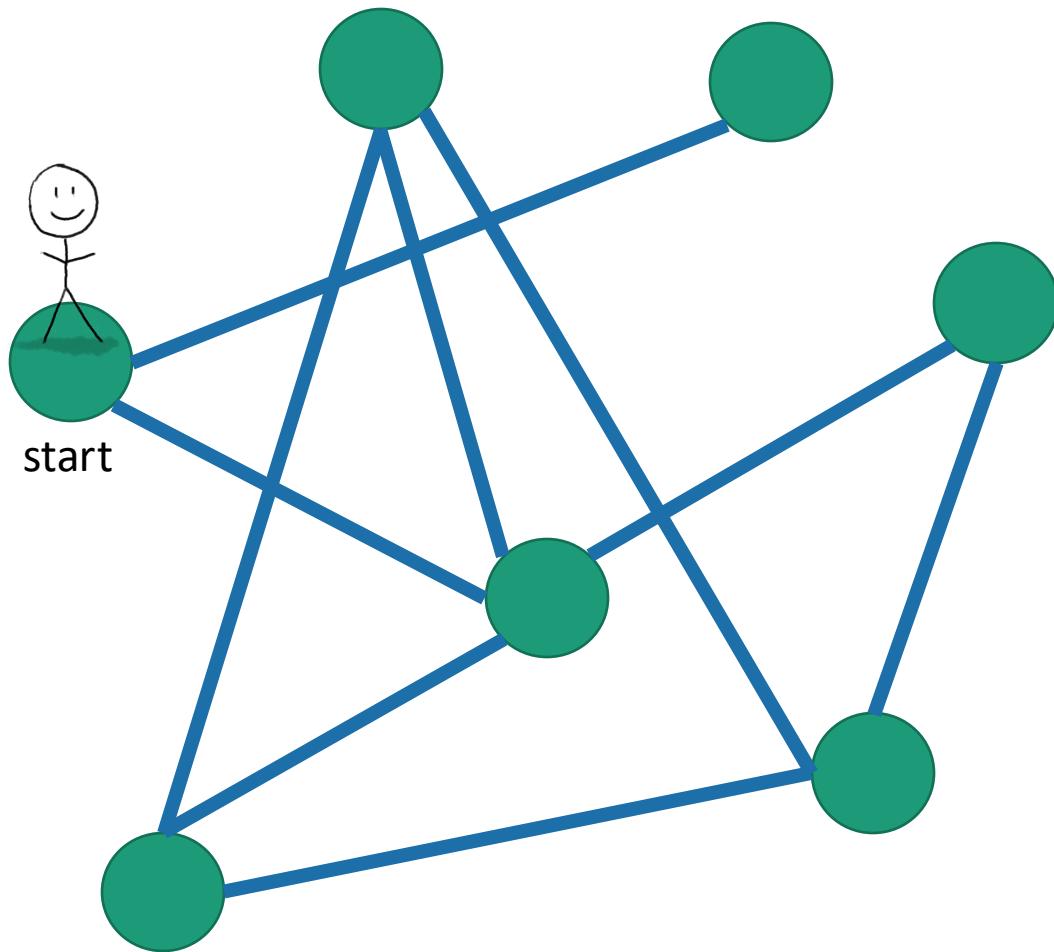
# Depth First Search

Exploring a labyrinth with chalk and a piece of string



# Depth First Search

Exploring a labyrinth with chalk and a piece of string



- Not been there yet
- Been there, haven't explored all the paths out.
- Been there, have explored all the paths out.

Labyrinth:  
explored!

# Depth First Search

## Exploring a labyrinth with pseudocode

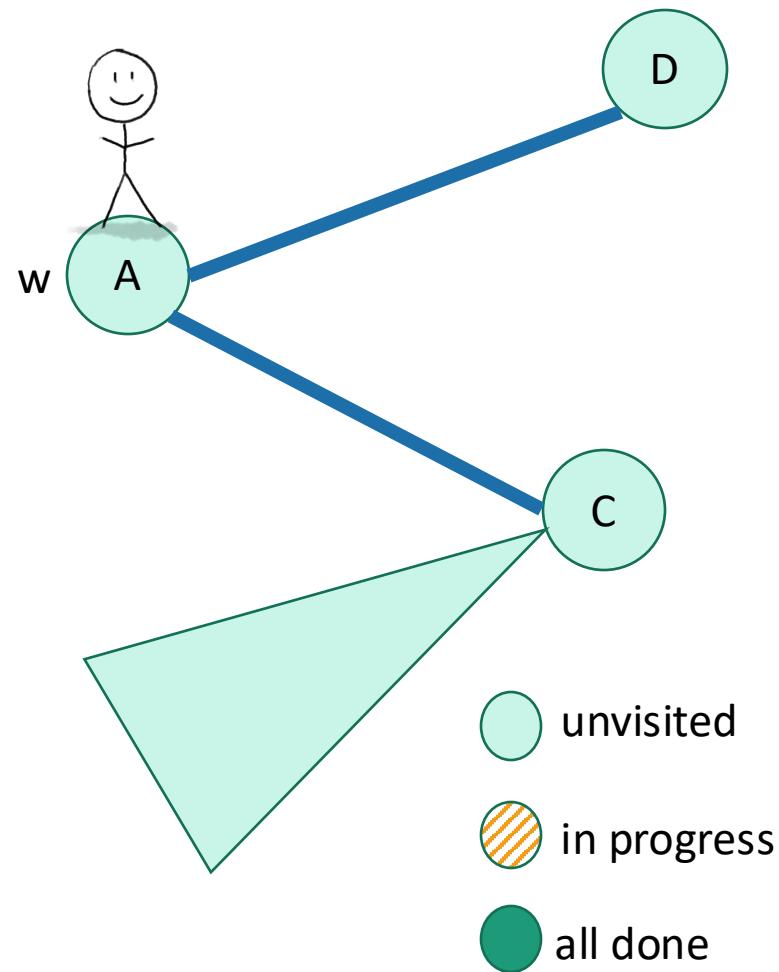
- Each vertex keeps track of whether it is:
  - Unvisited 
  - In progress 
  - All done 
- Each vertex will also keep track of:
  - The time we **first enter it**.
  - The time we finish with it and mark it **all done**.



You might have seen other ways to implement DFS than what we are about to go through. This way has more bookkeeping – the bookkeeping will be useful later!

# Depth First Search

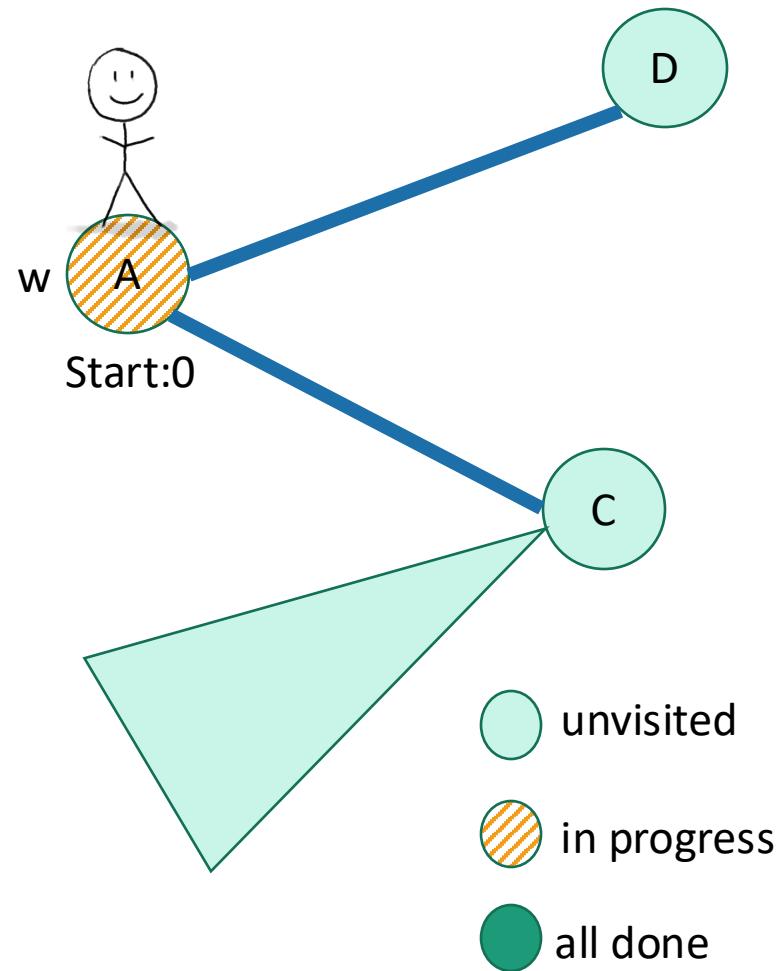
currentTime = 0



- **DFS(w, currentTime):**
  - w.startTime = currentTime
  - currentTime ++
  - Mark w as **in progress**.
  - **for v in w.neighbors:**
    - **if v is unvisited:**
      - currentTime
      - = **DFS(v, currentTime)**
      - currentTime ++
  - w.finishTime = currentTime
  - Mark w as **all done**
  - **return** currentTime

# Depth First Search

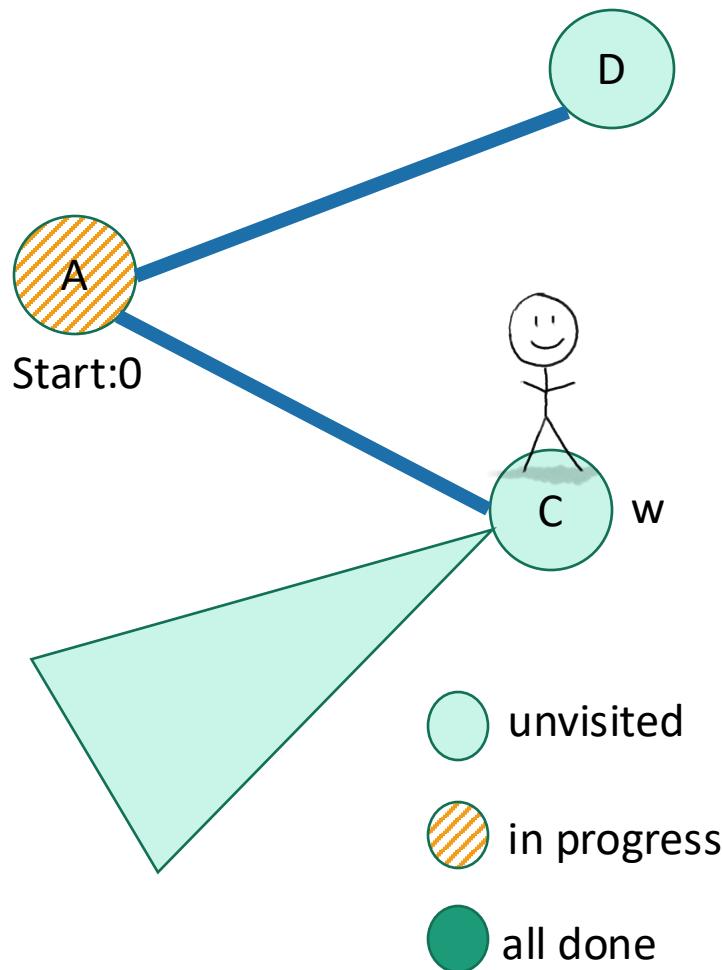
currentTime = 1



- **DFS(w, currentTime):**
  - `w.startTime = currentTime`
  - `currentTime ++`
  - Mark w as **in progress**.
  - **for v in w.neighbors:**
    - **if v is unvisited:**
      - `currentTime`  
= **DFS(v, currentTime)**
      - `currentTime ++`
  - `w.finishTime = currentTime`
  - Mark w as **all done**
  - **return currentTime**

# Depth First Search

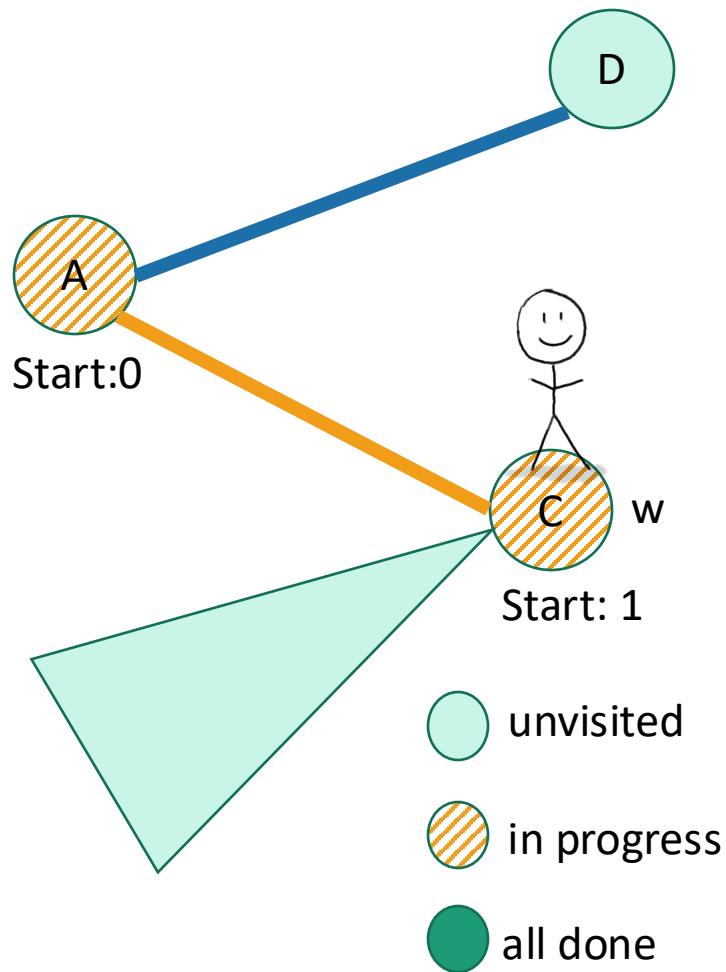
currentTime = 1



- **DFS(w, currentTime):**
  - `w.startTime = currentTime`
  - `currentTime ++`
  - Mark w as **in progress**.
  - **for v in w.neighbors:**
    - **if v is unvisited:**
      - `currentTime`  
= **DFS(v, currentTime)**
      - `currentTime ++`
  - `w.finishTime = currentTime`
  - Mark w as **all done**
  - **return currentTime**

# Depth First Search

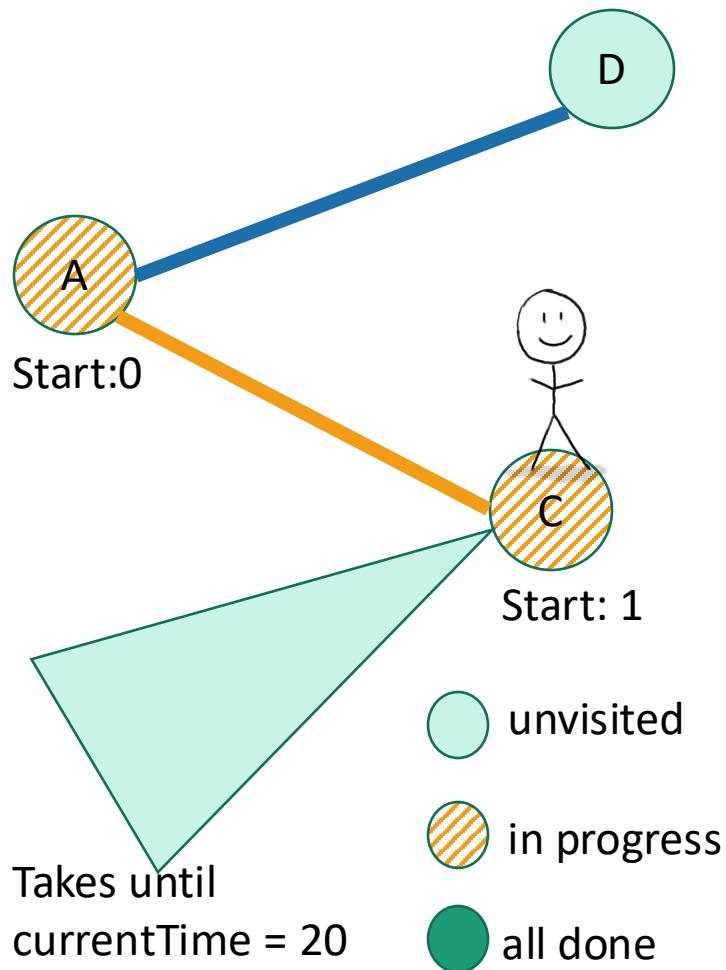
currentTime = 2



- **DFS(w, currentTime):**
  - w.startTime = currentTime
  - currentTime ++
  - Mark w as **in progress**.
  - **for v in w.neighbors:**
    - **if v is unvisited:**
      - currentTime = **DFS(v, currentTime)**
      - currentTime ++
  - w.finishTime = currentTime
  - Mark w as **all done**
  - **return** currentTime

# Depth First Search

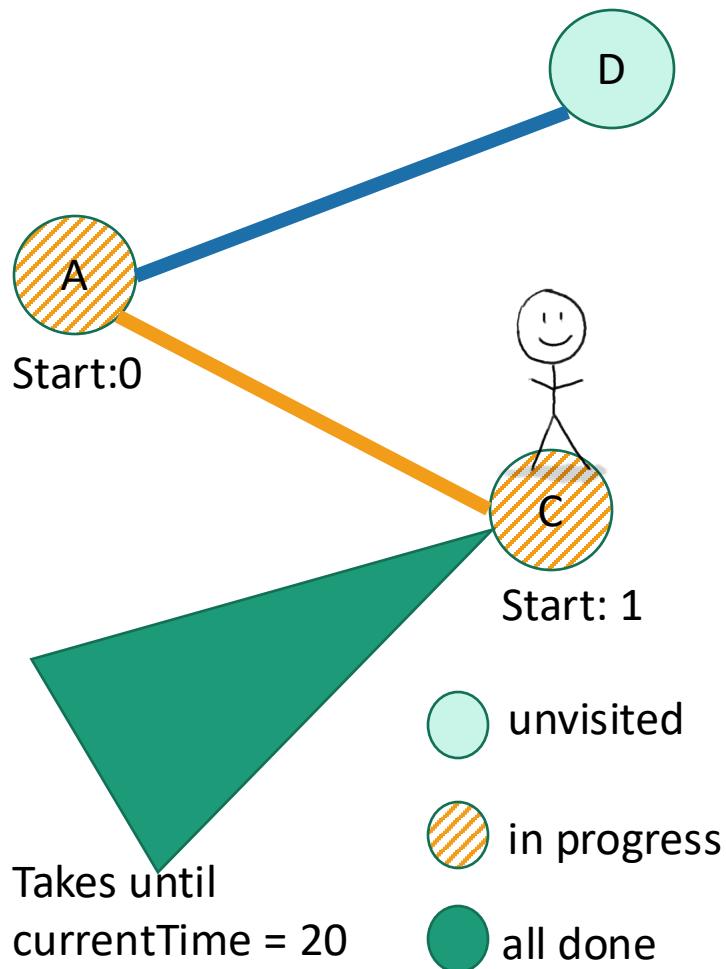
currentTime = 20



- **DFS(w, currentTime):**
  - `w.startTime = currentTime`
  - `currentTime ++`
  - Mark w as **in progress**.
  - **for v in w.neighbors:**
    - **if v is unvisited:**
      - `currentTime`  
 $= \text{DFS}(v, \text{currentTime})$
      - `currentTime ++`
  - `w.finishTime = currentTime`
  - Mark w as **all done**
  - **return currentTime**

# Depth First Search

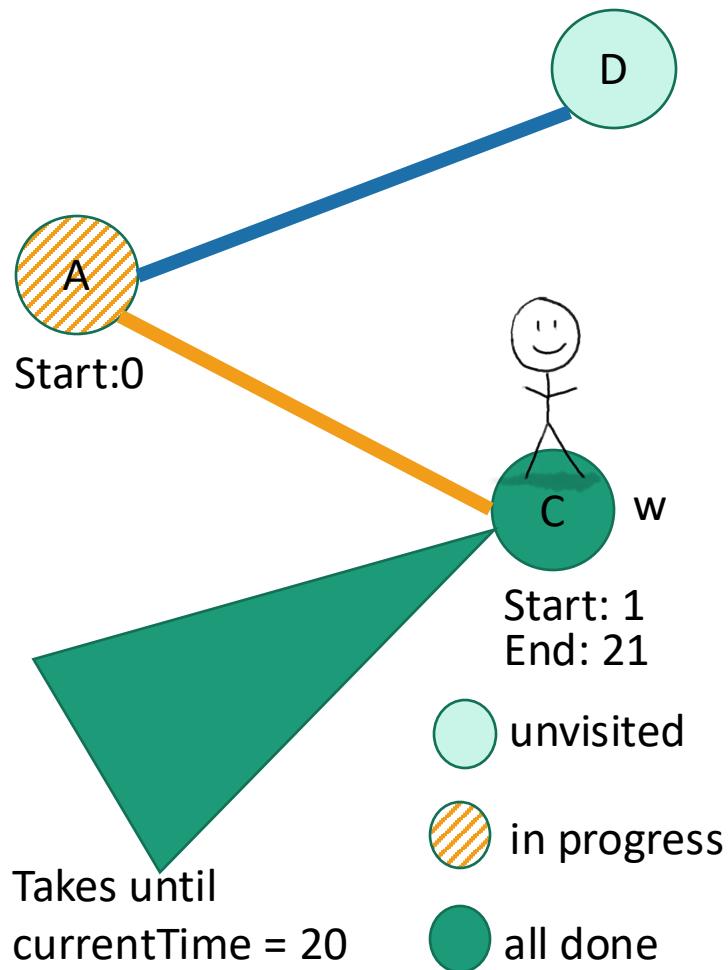
currentTime = 21



- **DFS(w, currentTime):**
  - `w.startTime = currentTime`
  - `currentTime ++`
  - Mark w as **in progress**.
  - **for v in w.neighbors:**
    - **if v is unvisited:**
      - `currentTime`  
 $= \text{DFS}(v, \text{currentTime})$
      - `currentTime ++`
  - `w.finishTime = currentTime`
  - Mark w as **all done**
  - **return currentTime**

# Depth First Search

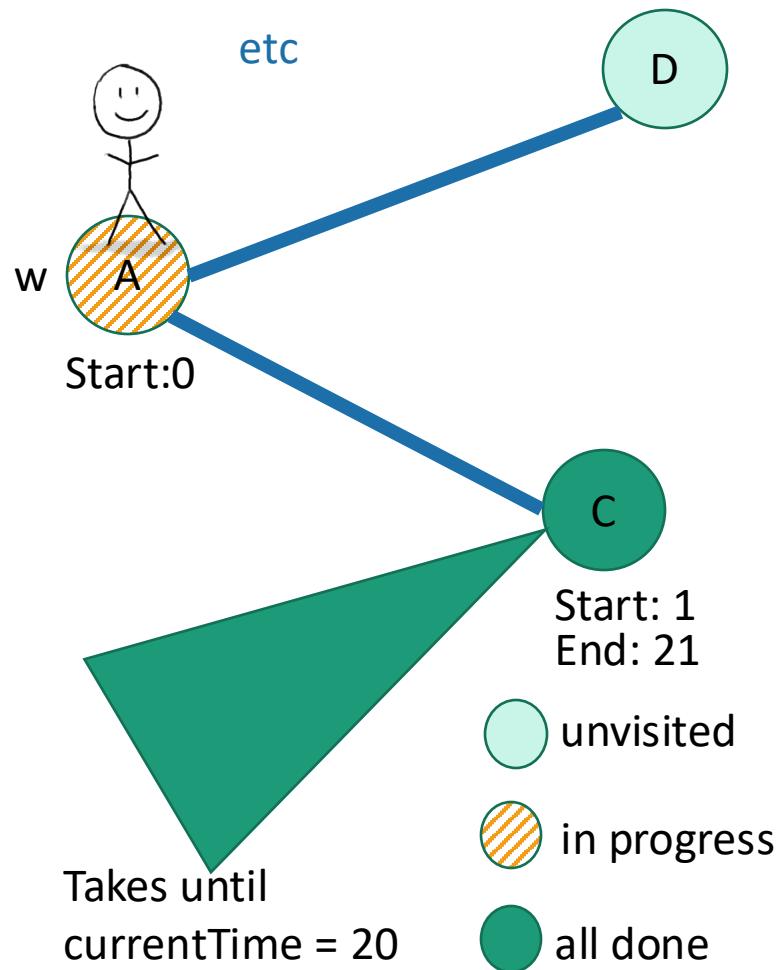
currentTime = 21



- **DFS(w, currentTime):**
  - `w.startTime = currentTime`
  - `currentTime ++`
  - Mark w as **in progress**.
  - **for v in w.neighbors:**
    - **if v is unvisited:**
      - `currentTime`  
= **DFS(v, currentTime)**
      - `currentTime ++`
  - `w.finishTime = currentTime`
  - Mark w as **all done**
  - **return currentTime**

# Depth First Search

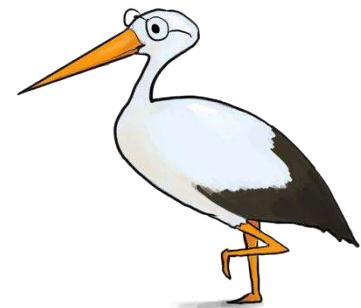
currentTime = 22



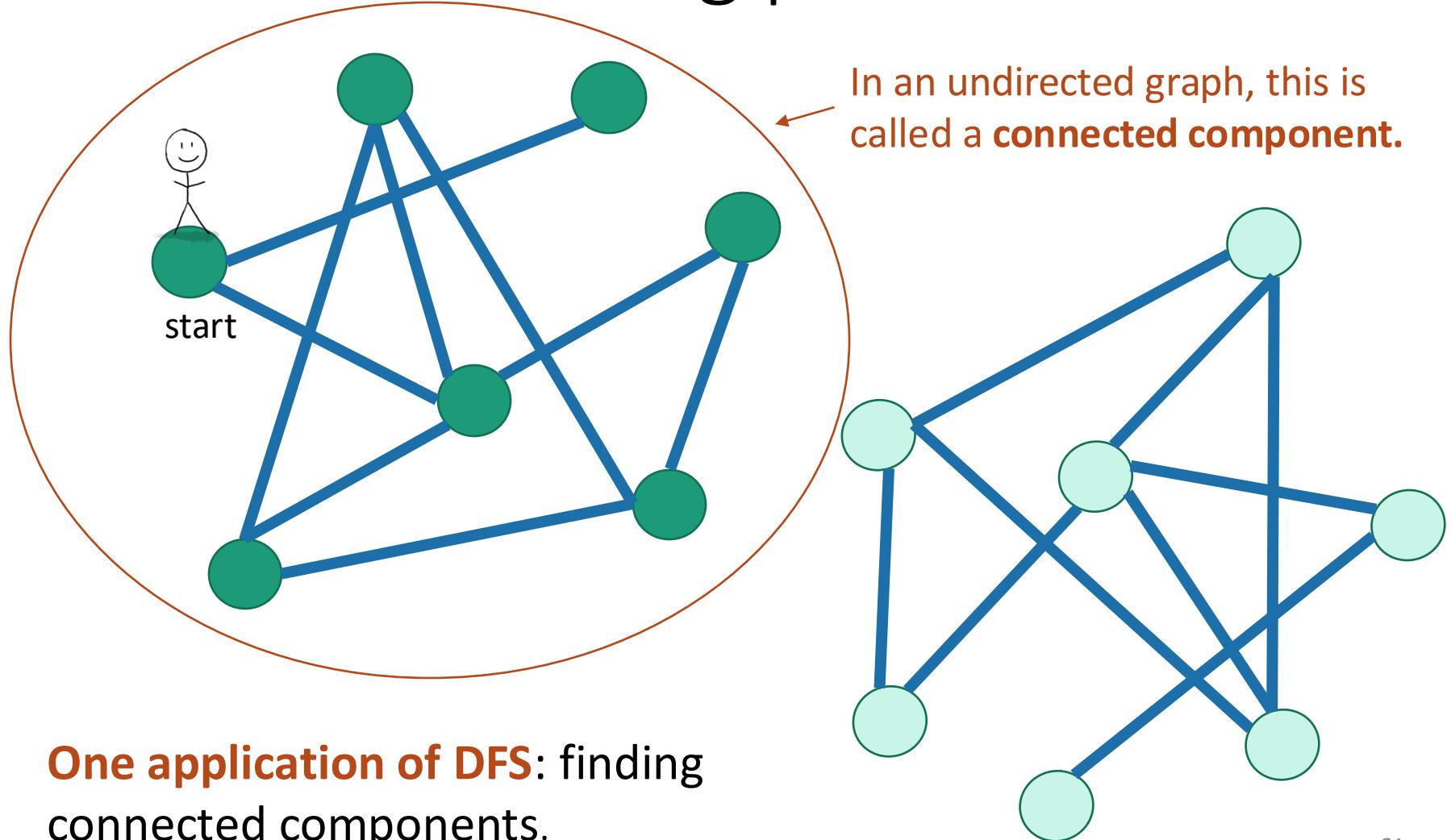
- **DFS(w, currentTime):**
  - `w.startTime = currentTime`
  - `currentTime ++`
  - Mark w as **in progress**.
  - **for v in w.neighbors:**
    - **if v is unvisited:**
      - `currentTime`  
= **DFS(v, currentTime)**
      - `currentTime ++`
  - `w.finishTime = currentTime`
  - Mark w as **all done**
  - **return currentTime**

# This is not the only way to write DFS!

- See the textbook for an iterative version.
- (And/or figure out how to do it yourself!)

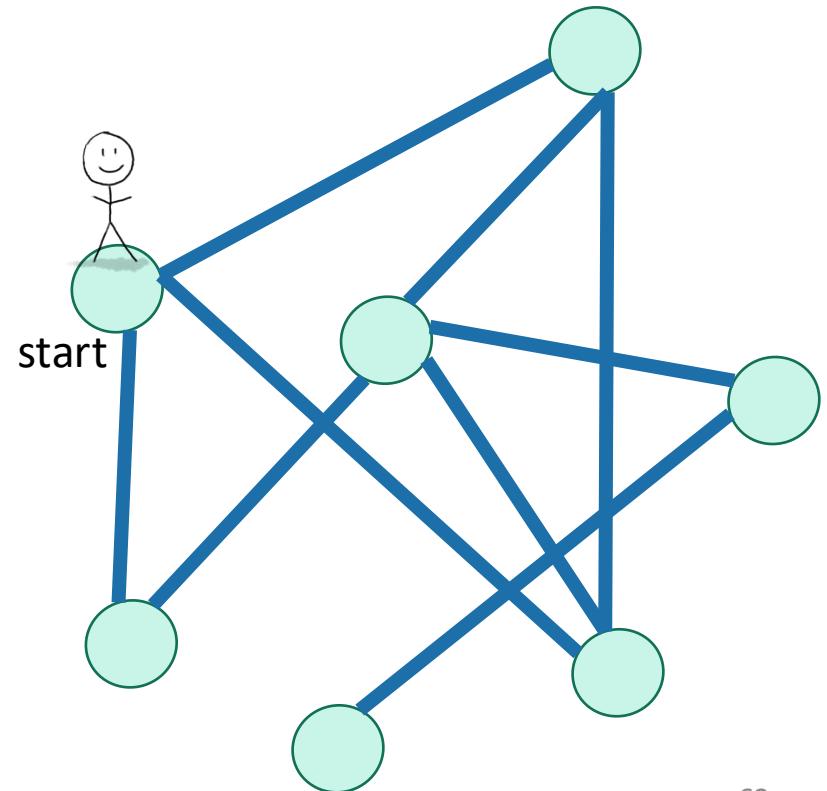
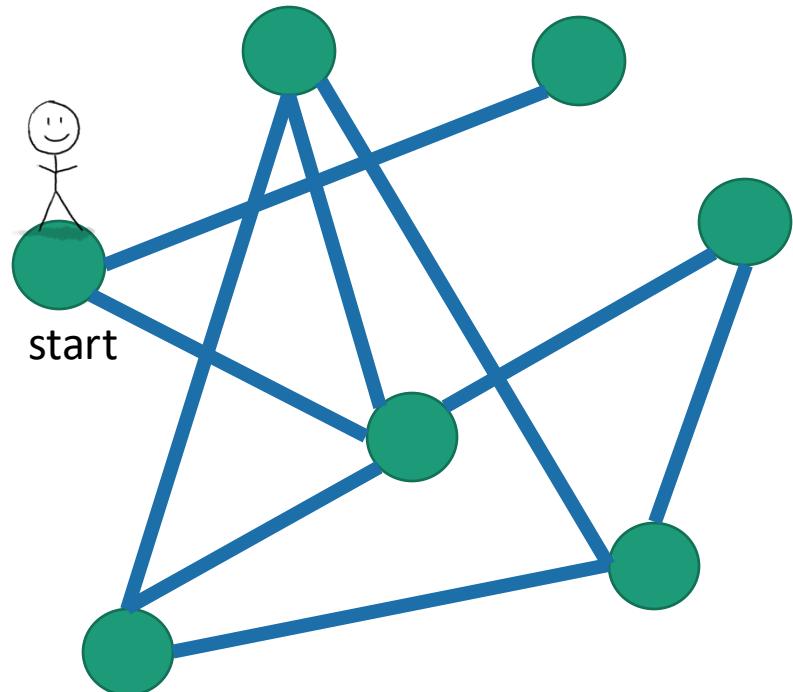


# DFS finds all the nodes reachable from the starting point



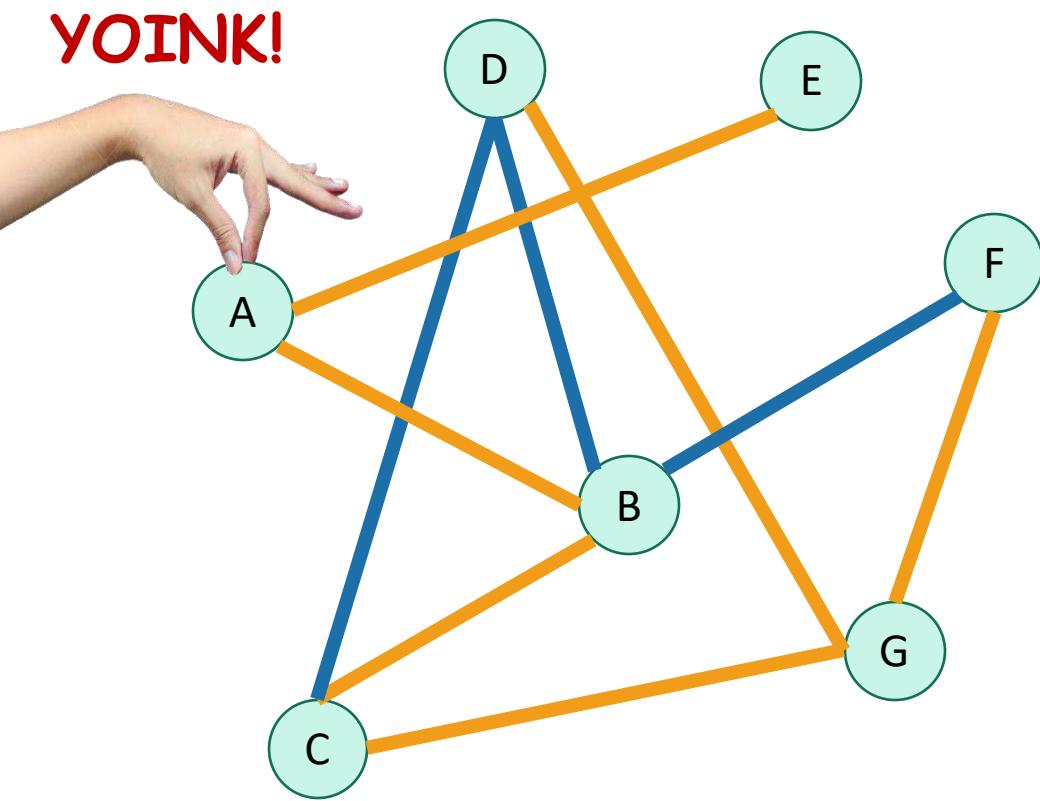
# To explore the whole graph

- Do it repeatedly!

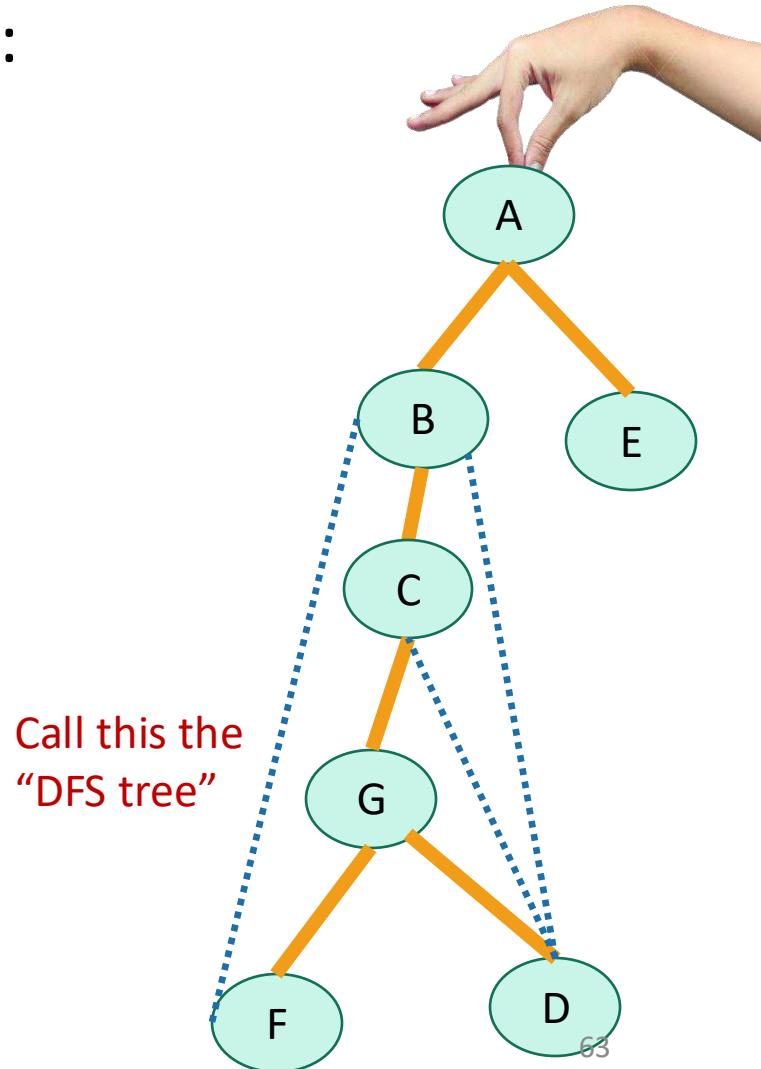


# Why is it called depth-first?

- We are implicitly building a tree:



- First, we go as deep as we can.



# Running time

- We look at each edge at most twice.
  - Once from each of its endpoints
- We visit each vertex at most once
- And basically we don't do anything else.
- So...



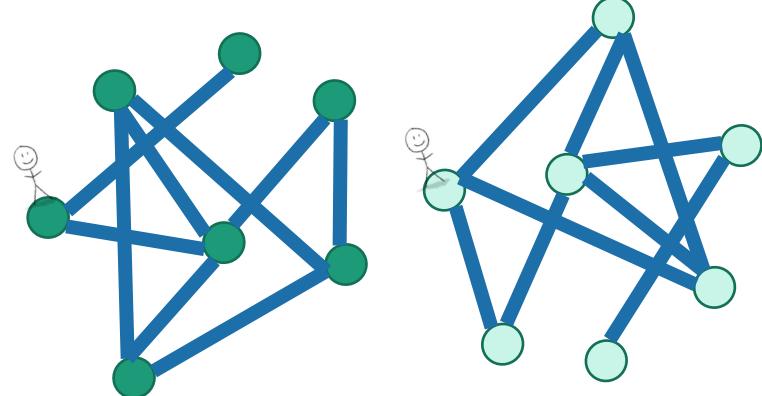
$O(m+n)$

# Running time

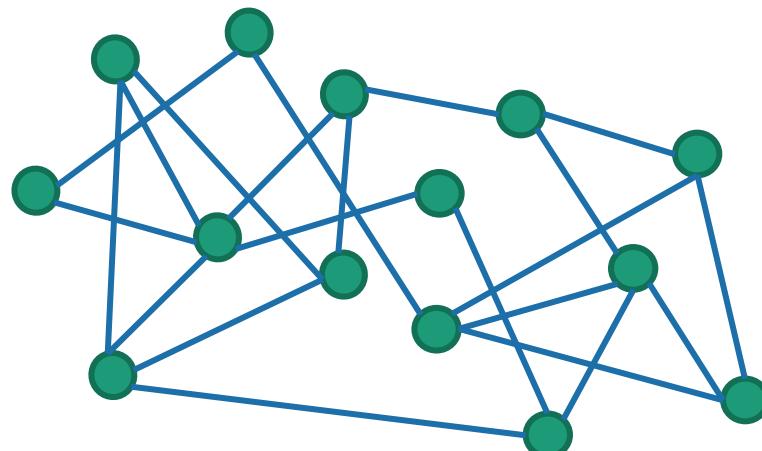
- Assume we are using the adjacency-list format for  $G=(V,E)$ .
- We visit each vertex in  $G$  exactly once.
  - Here, “visit” means “call DFS on”
- At each vertex  $w$ , we:
  - Do some book-keeping:  $O(1)$
  - Loop over  $w$ ’s neighbors and check if they are visited (and then potentially make a recursive call):  $O(1)$  per neighbor or  $O(\deg(w))$  total.
- Total time:
  - $\sum_{w \in V'} (O(\deg(w)) + O(1))$   
 $= O(|E| + |V|) = O(n + m)$



# Aside: Why not just $O(m)$ ?

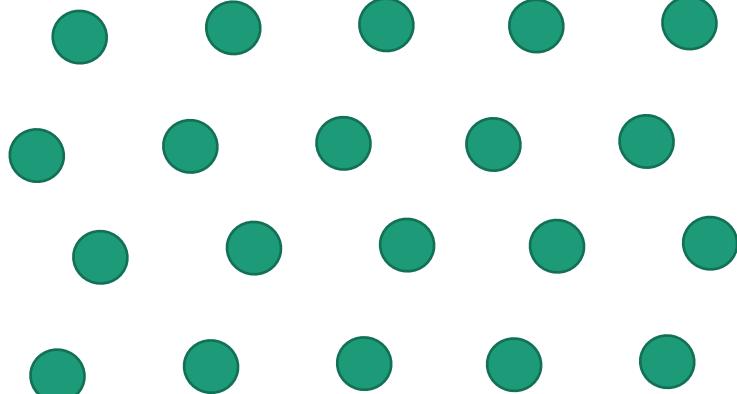


- If the graph is disconnected,  $n$  might be asymptotically larger than  $m$ :



Here the running time is  
 $O(m)$  like before

vs

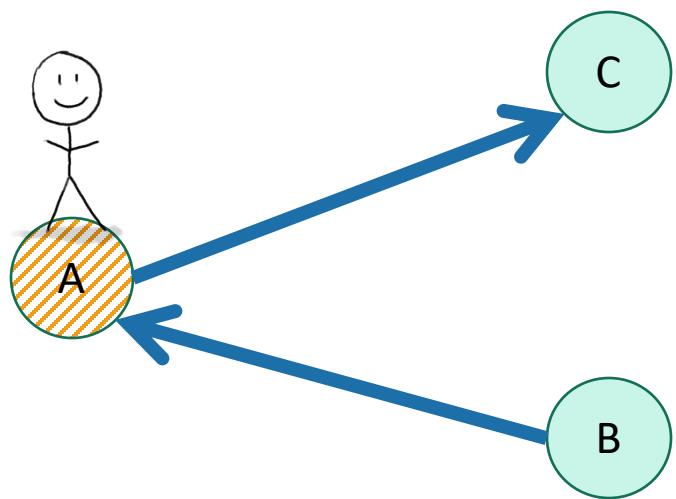


Here  $m=0$  but it still takes time  
 $O(n)$  to explore the graph.

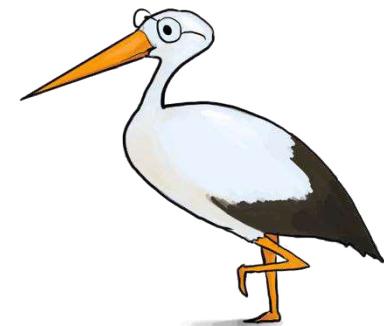
- Note: BFS can explore a *single connected component* in time  $O(m)$  (why?)

# You check:

DFS works fine on directed graphs too!



Only walk to C, not to B.



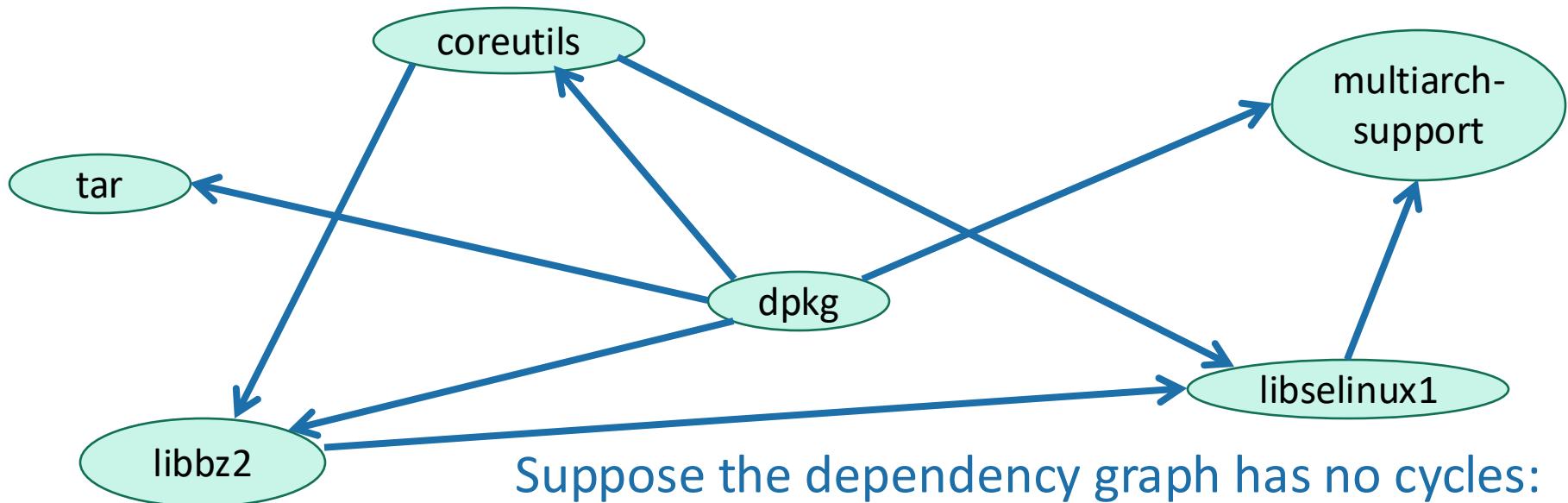
Siggi the studious stork

# Pre-lecture exercise

- How can you sign up for classes so that you never violate the pre-req requirements?
- More practically, how can you install packages without violating dependency requirements?

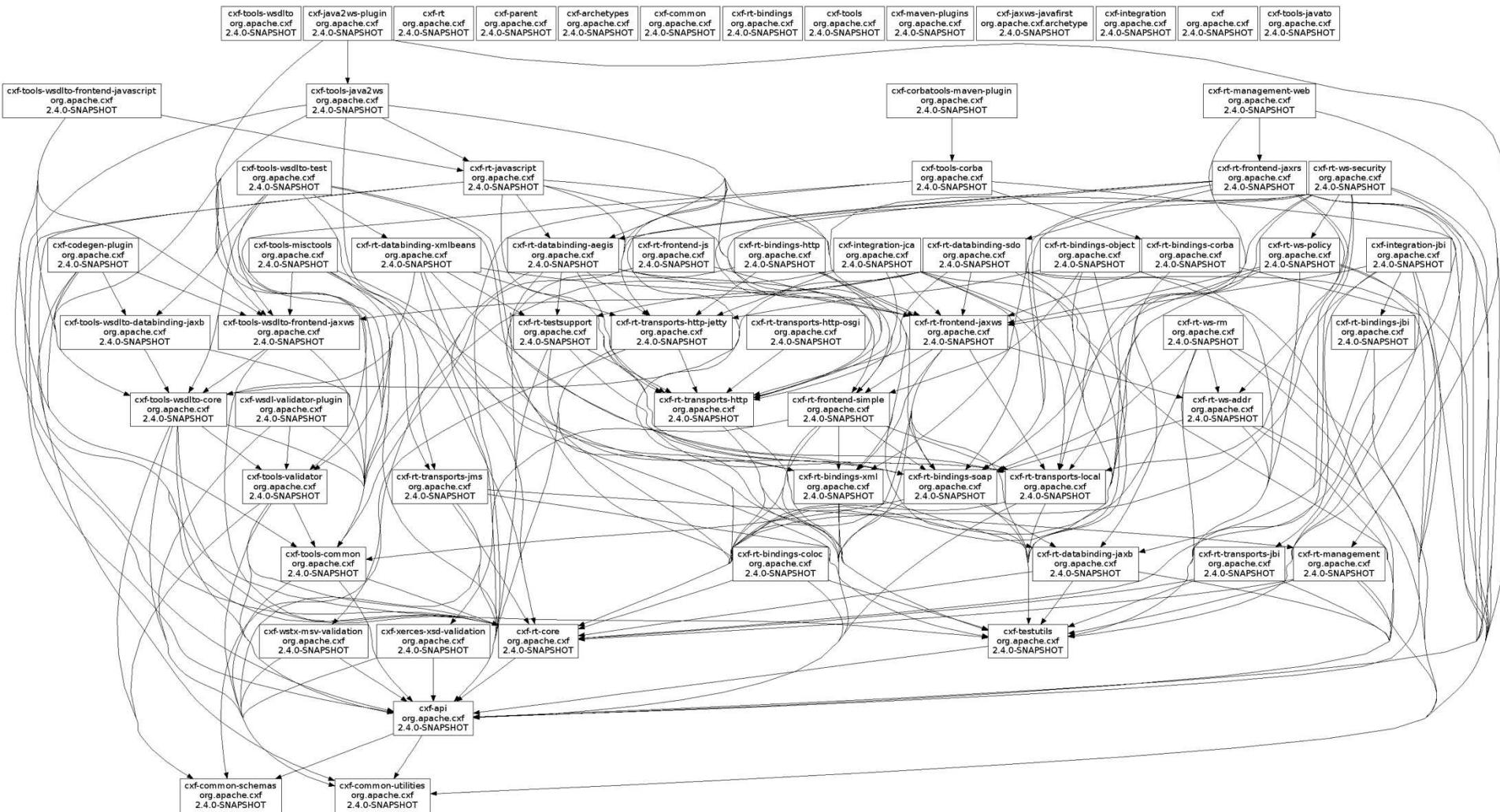
# Application of DFS: topological sorting

- Find an ordering of vertices so that all of the dependency requirements are met.
  - Aka, if  $v$  comes before  $w$  in the ordering, there is not an edge from  $w$  to  $v$ .



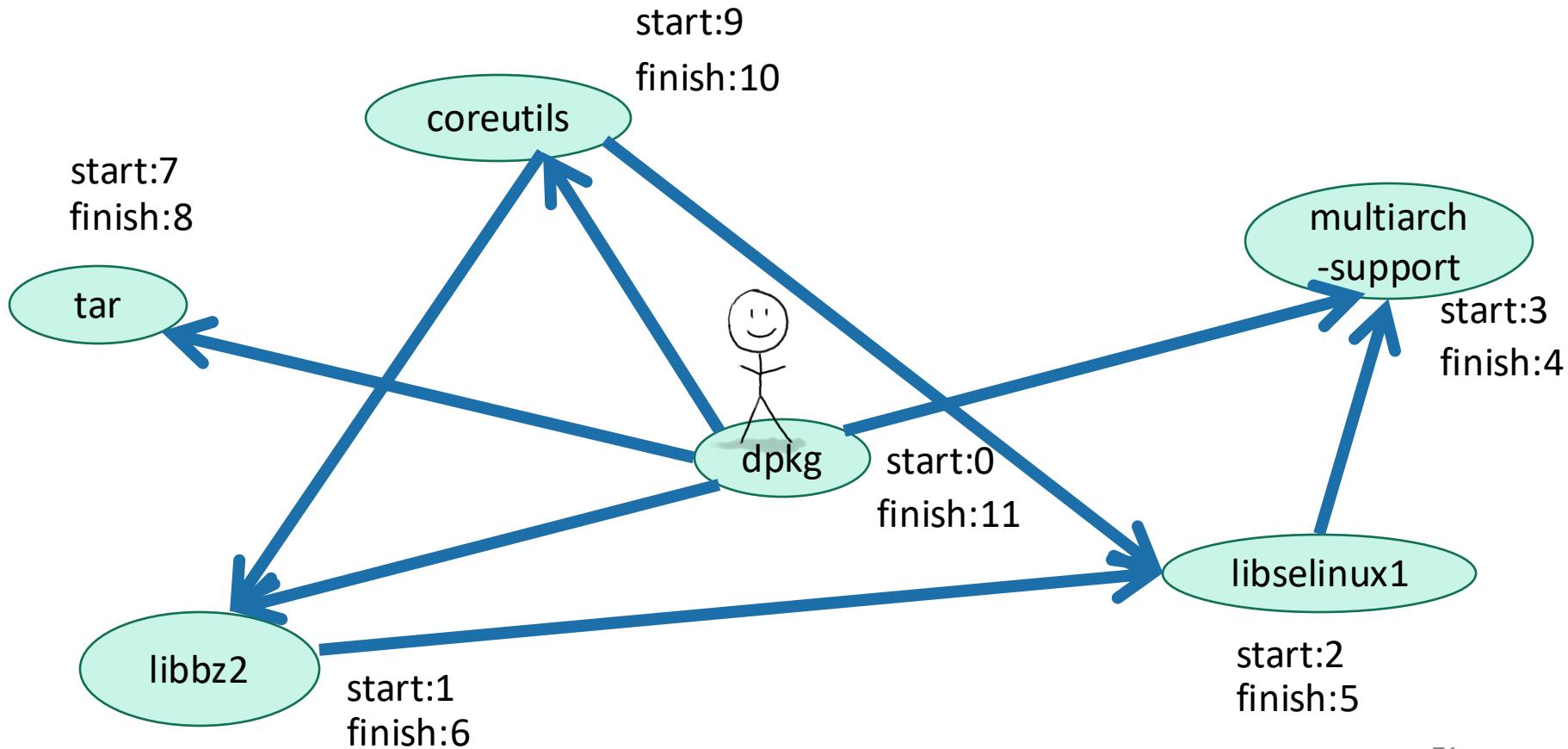
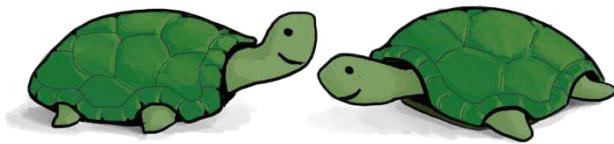
Suppose the dependency graph has no cycles:  
it is a **Directed Acyclic Graph (DAG)**

# Can't always eyeball it.



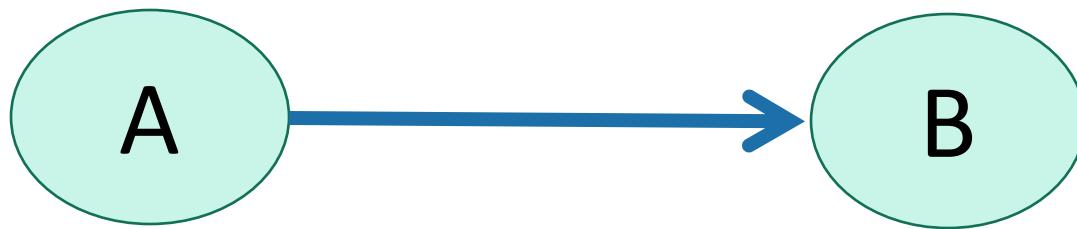
# Let's do DFS

What do you notice about the finish times? Any ideas for how we should do topological sort?



# Finish times seem useful

**Claim:** In a DAG, we always have:



finish: [larger]

finish: [smaller]

To understand why, let's go back to that DFS tree.

# A more general statement (this holds even if there are cycles)

(check this statement carefully!)



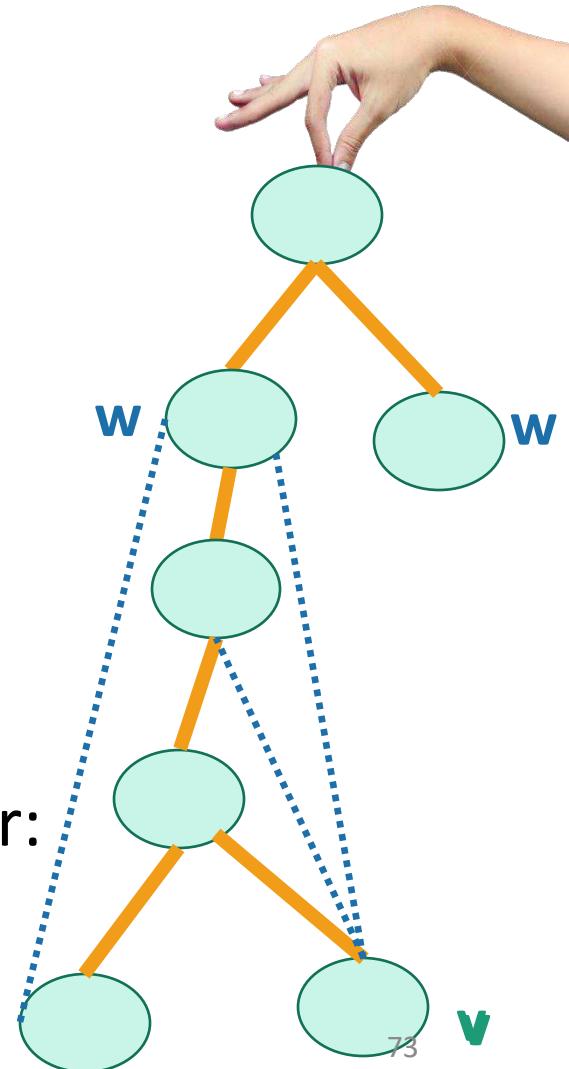
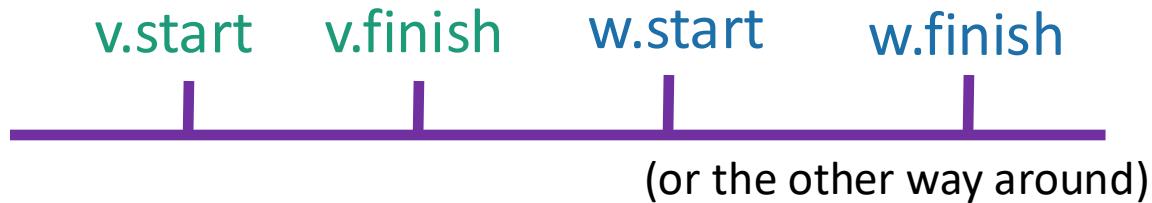
- If  $v$  is a descendant of  $w$  in this tree:



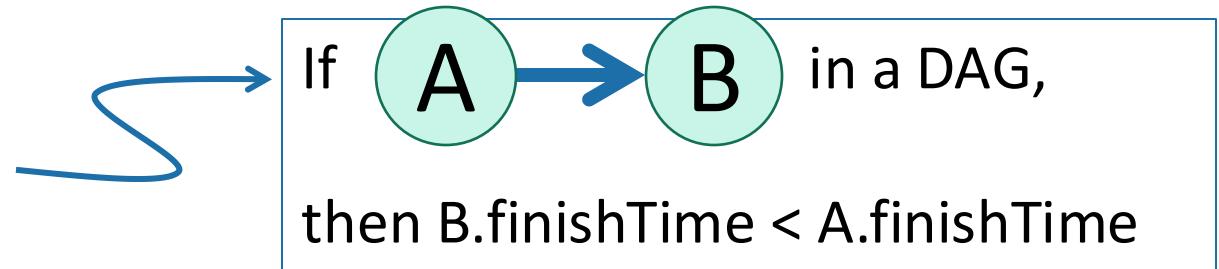
- If  $w$  is a descendant of  $v$  in this tree:



- If neither are descendants of each other:



Proof of this

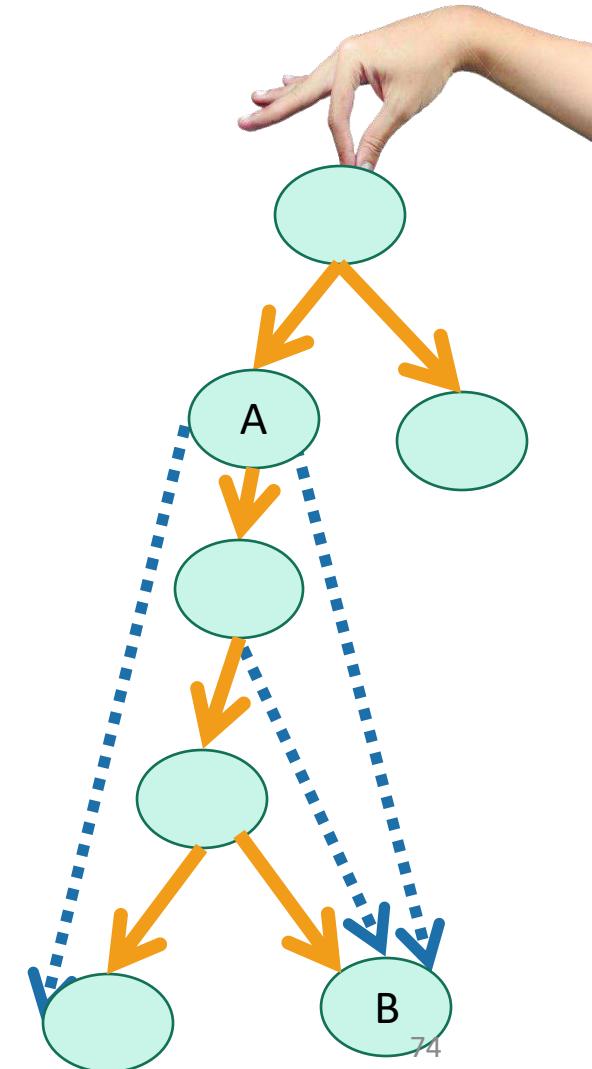


- **Case 1:** B is a descendant of A in the DFS tree.

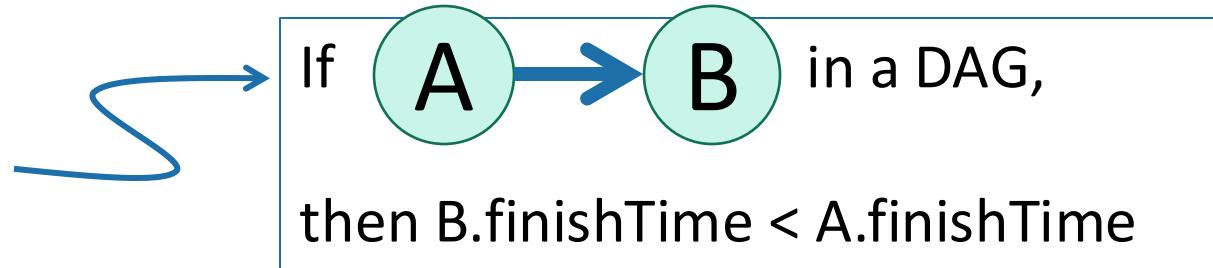
- Then



- aka,  **$B.\text{finishTime} < A.\text{finishTime}$** .



# Proof of this



- **Case 2:** B is a **NOT** descendant of A in the DFS tree.

- Notice that A can't be a descendant of B in the DFS tree or else there'd be a cycle; so it looks like this →

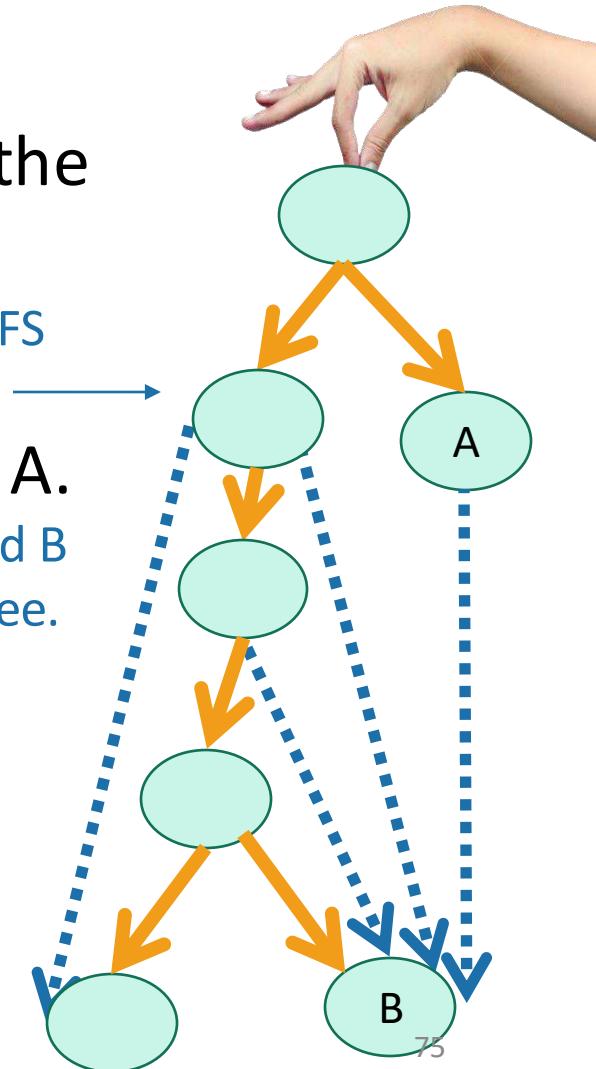
- Then we must have explored B before A.

- Otherwise we would have gotten to B from A, and B would have been a descendant of A in the DFS tree.

- Then

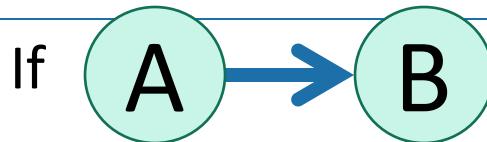


- aka,  $B.\text{finishTime} < A.\text{finishTime}$ .



# Theorem

- If we run DFS on a directed acyclic graph,



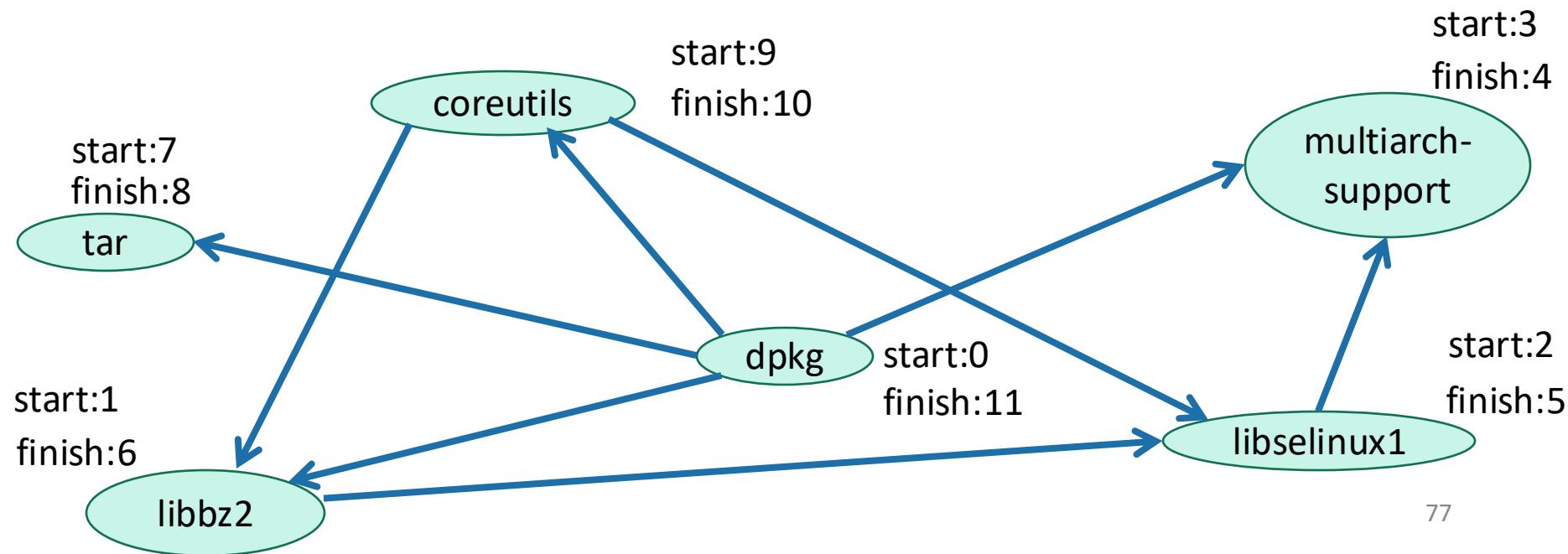
Then  $B.\text{finishTime} < A.\text{finishTime}$

# Back to topological sorting

Theorem:

If  in a DAG,  
then  $B.\text{finishTime} < A.\text{finishTime}$

- In what order should I install packages?
- In reverse order of finishing time in DFS!
  - If we do that, the **theorem** says that we'll never have a “backwards” edge.



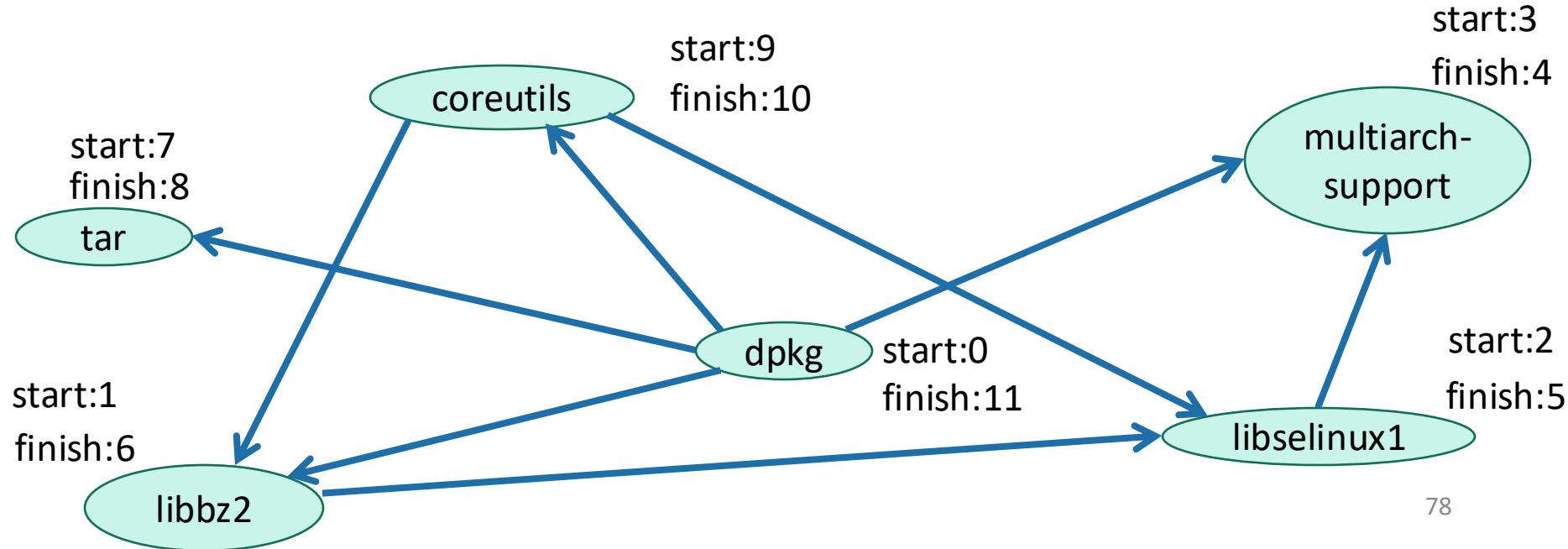
# Algorithm for Topological Sorting

(on a DAG)

- Do DFS
- When you mark a vertex as **all done**, put it at the **beginning** of the list.

Check out iPython notebook for an implementation!

- dpkg
- coreutils
- tar
- libbz2
- libselinux1
- multiarch\_support



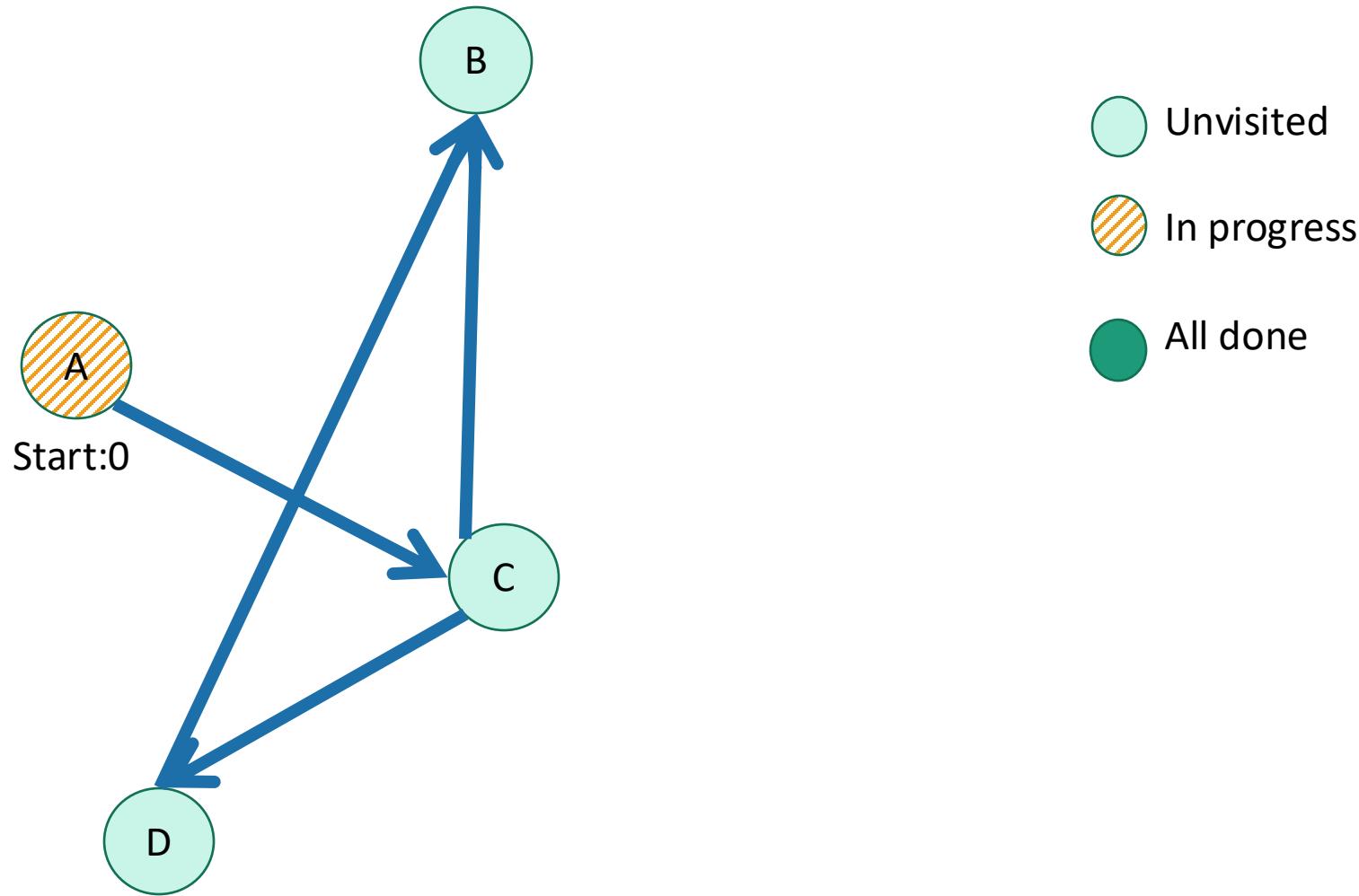
# What have we learned?

- DFS can help you solve the **topological sorting problem**
  - That's the fancy name for the problem of finding an ordering that respects all the dependencies
- Thinking about the DFS tree is helpful.

(Extra resource: There's an example of using DFS to TopoSort on some skipped slides after this).

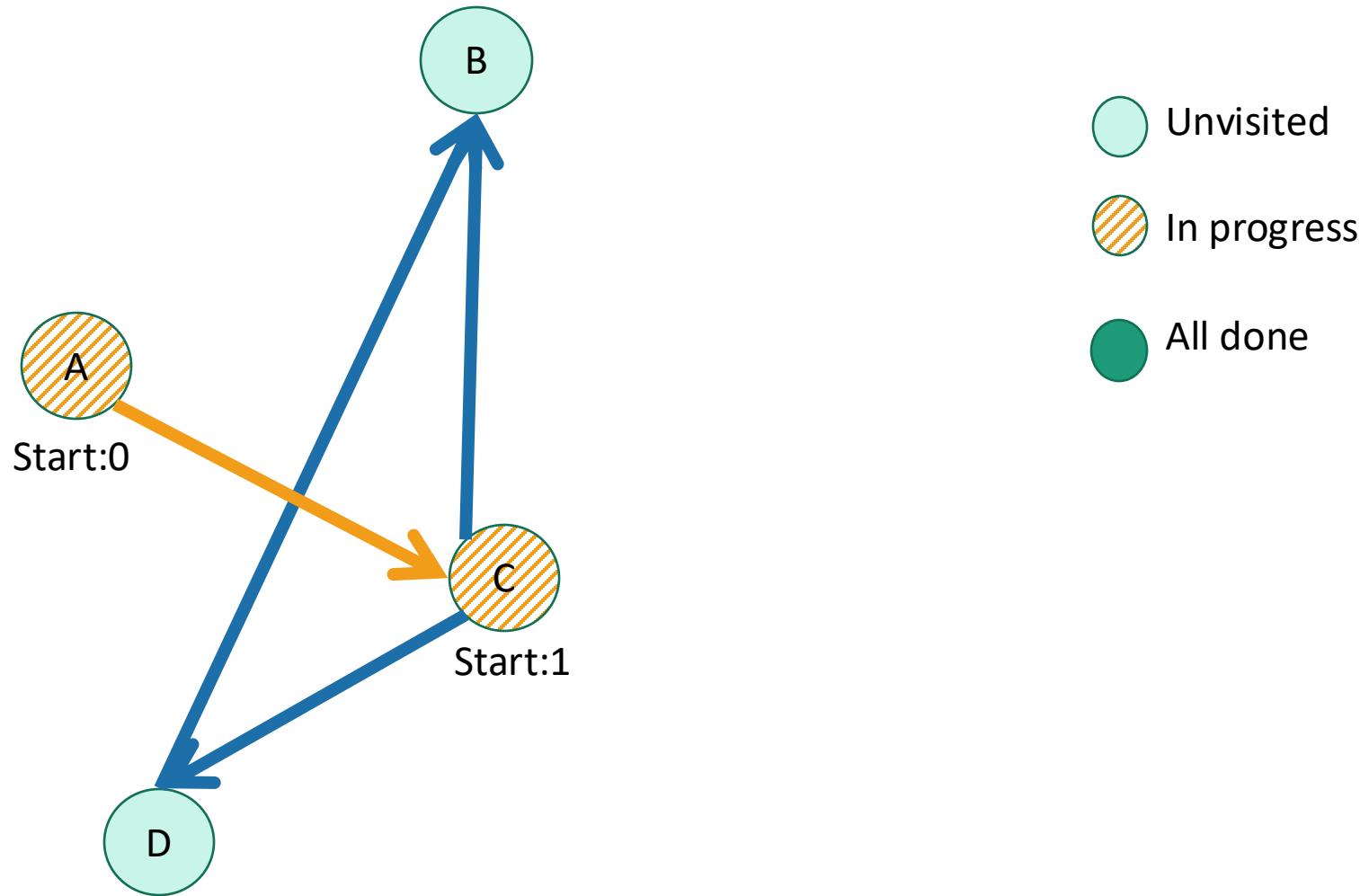
# Example:

This example skipped in class – here for reference.



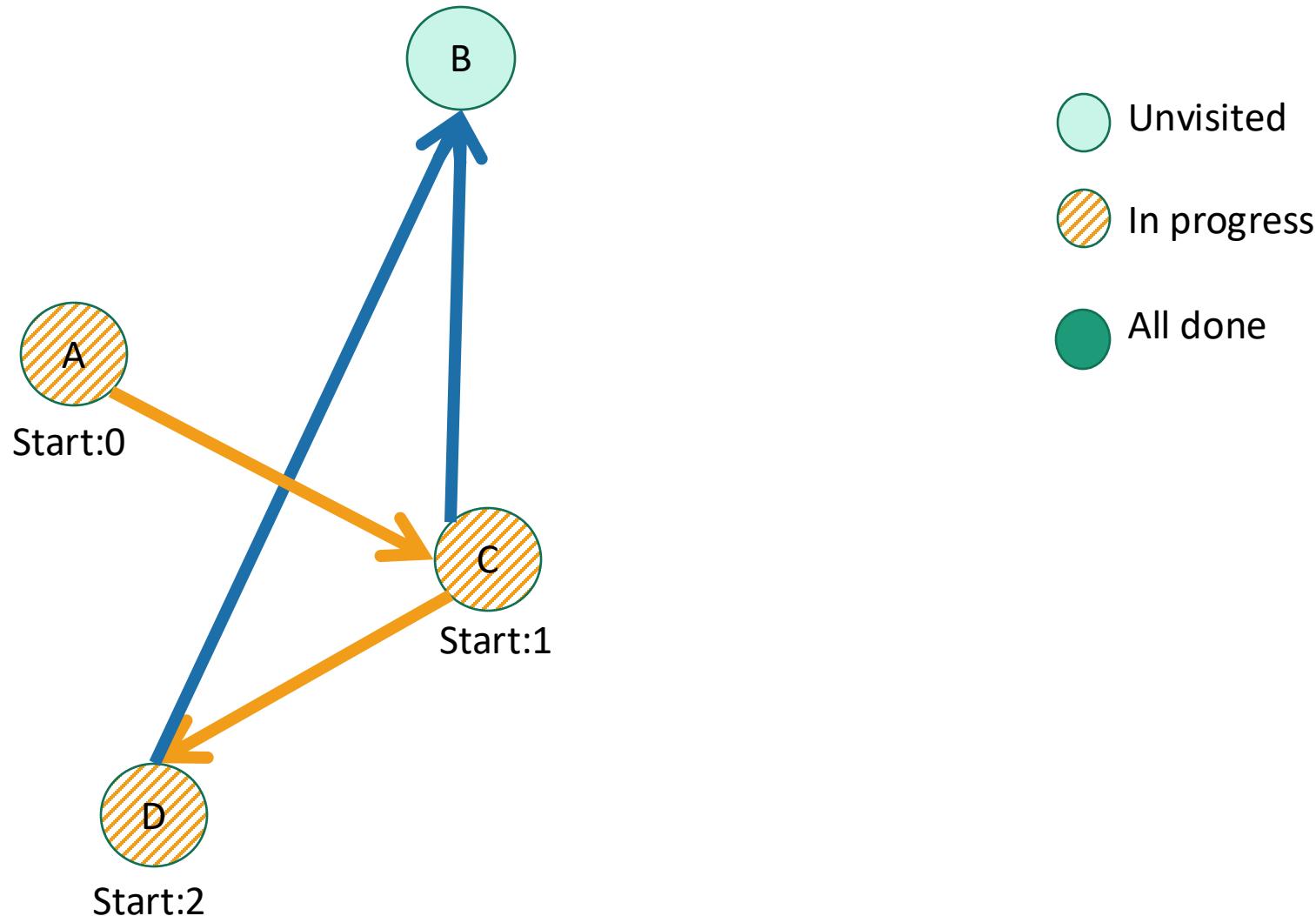
# Example

This example skipped in class – here for reference.



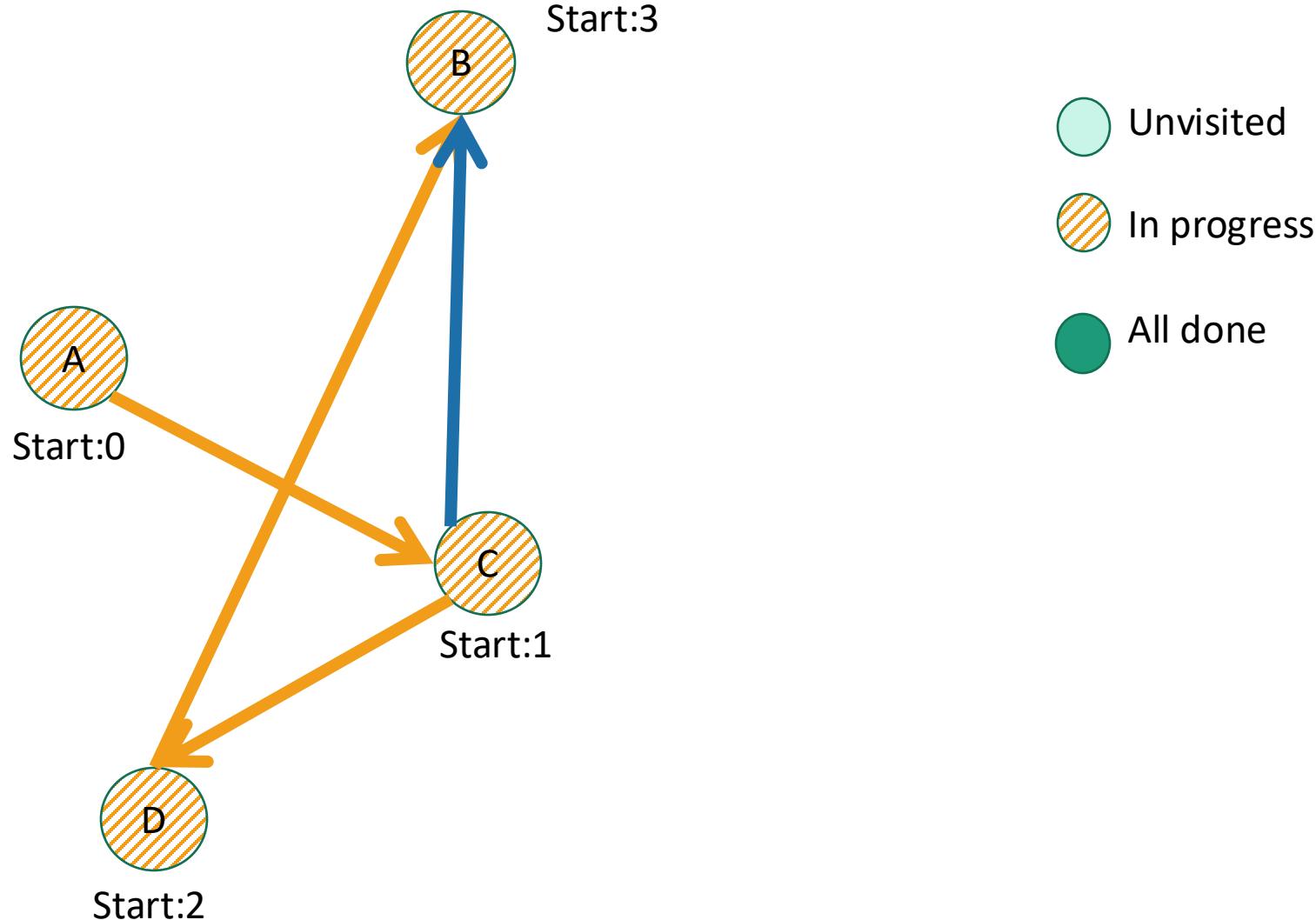
# Example

This example skipped in class – here for reference.



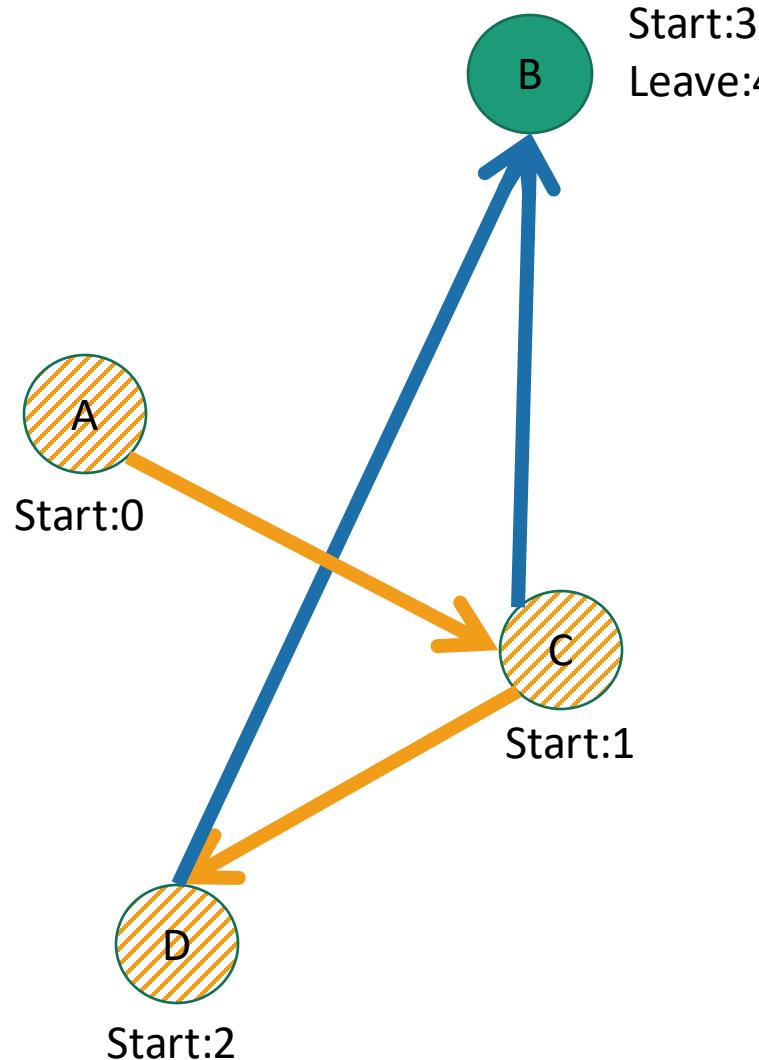
# Example

This example skipped in class – here for reference.



# Example

This example skipped in class – here for reference.

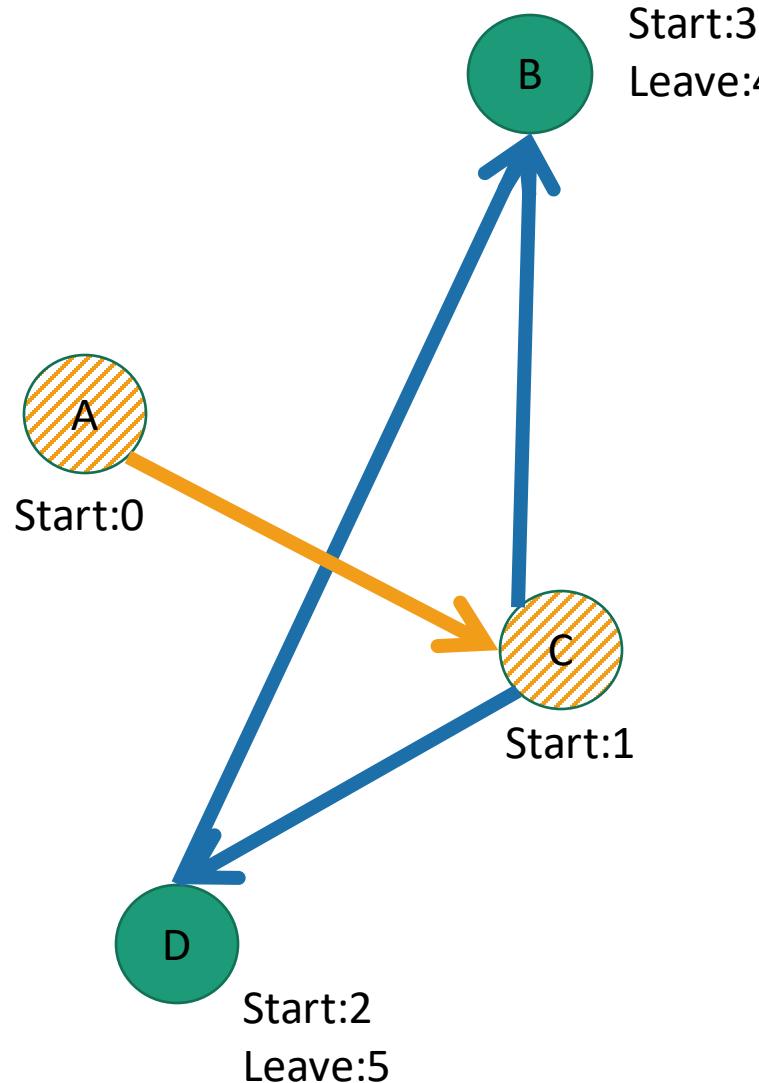


- Unvisited
- In progress
- All done



# Example

This example skipped in class – here for reference.

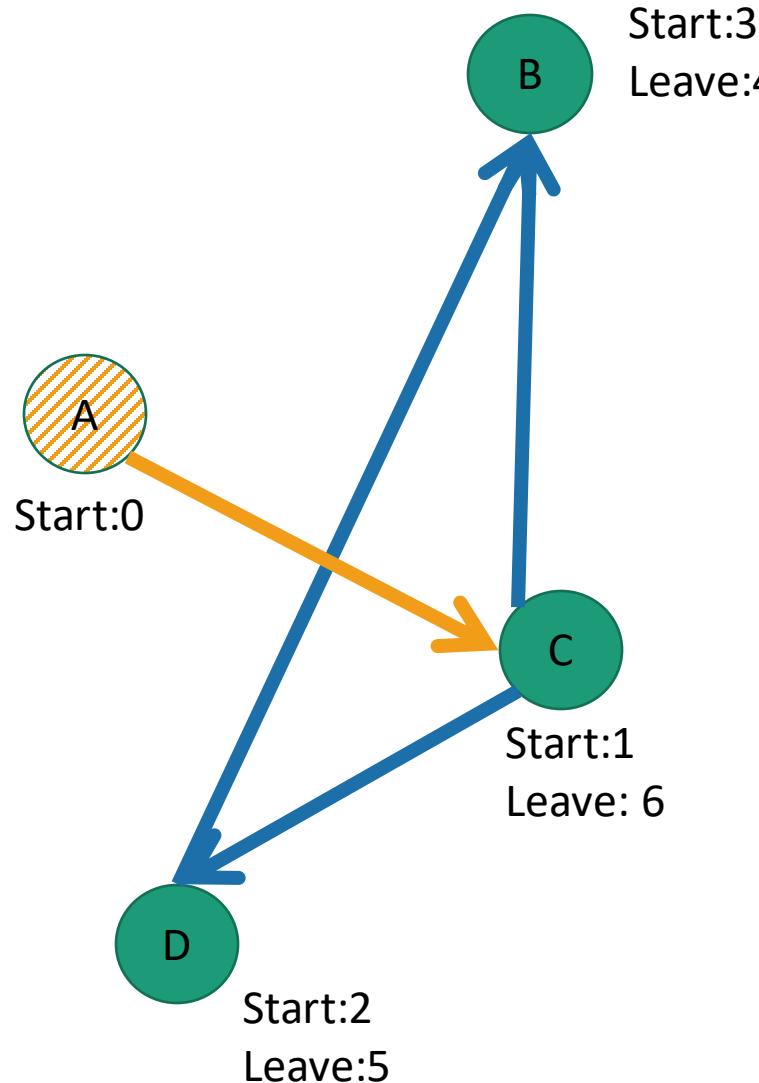


- Unvisited
- In progress
- All done



# Example

This example skipped in class – here for reference.



Unvisited

In progress

All done

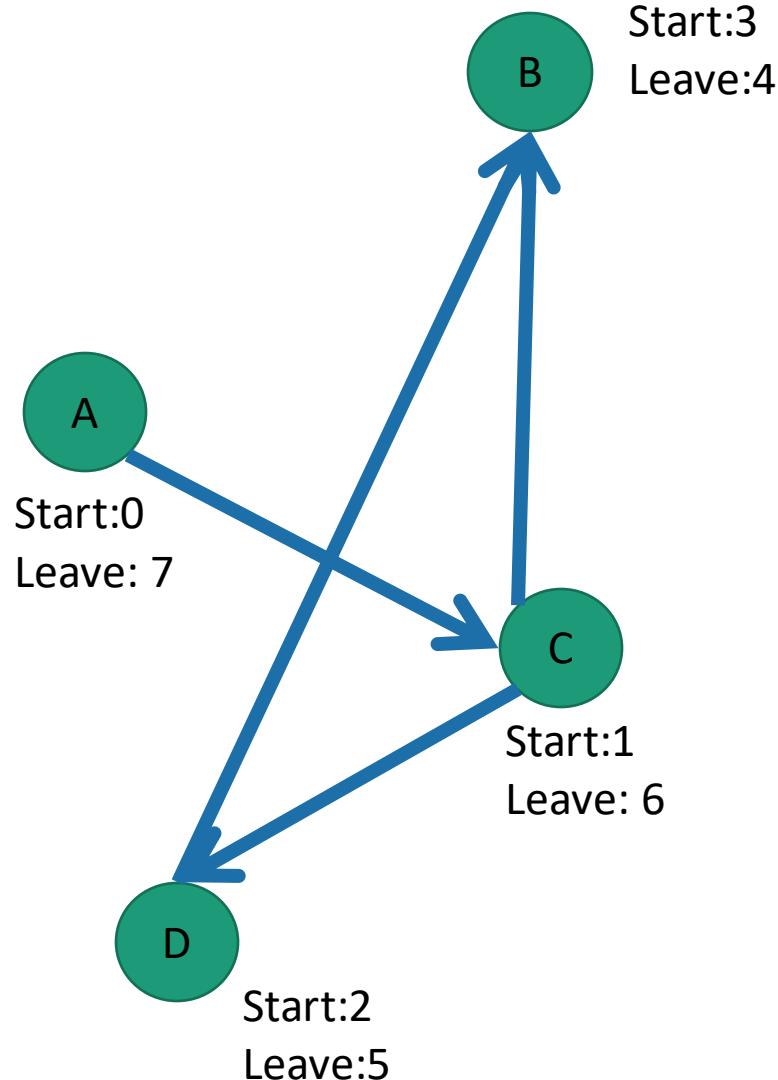
C

D

B

# Example

This example skipped in class – here for reference.



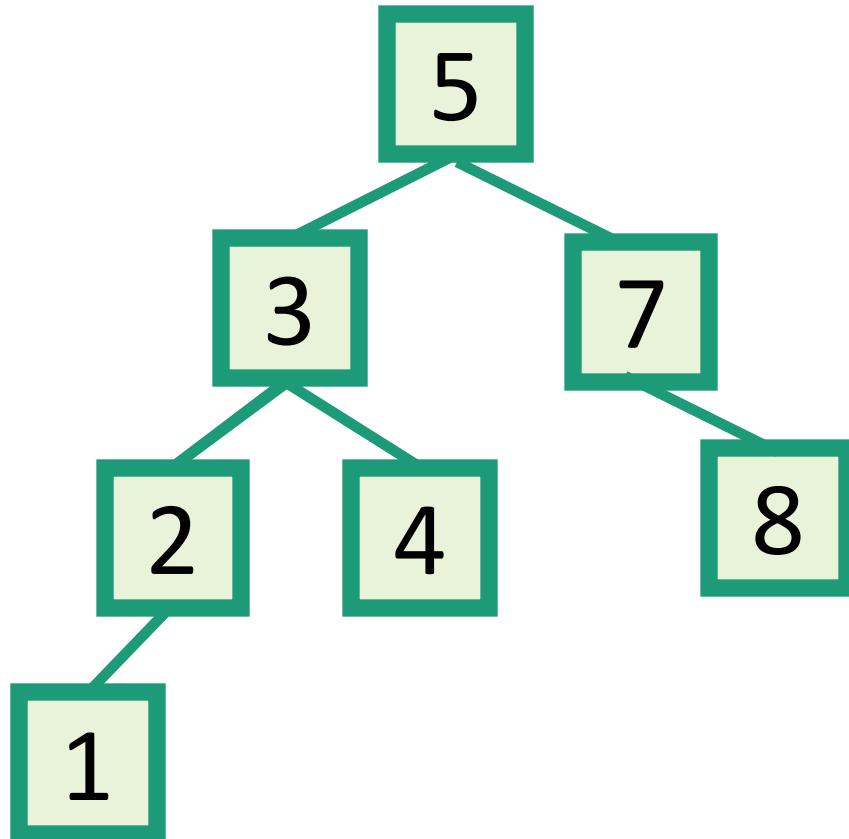
- Unvisited
- In progress
- All done

Do them in this order:



# Another use of DFS that we've already seen

- In-order enumeration of binary search trees

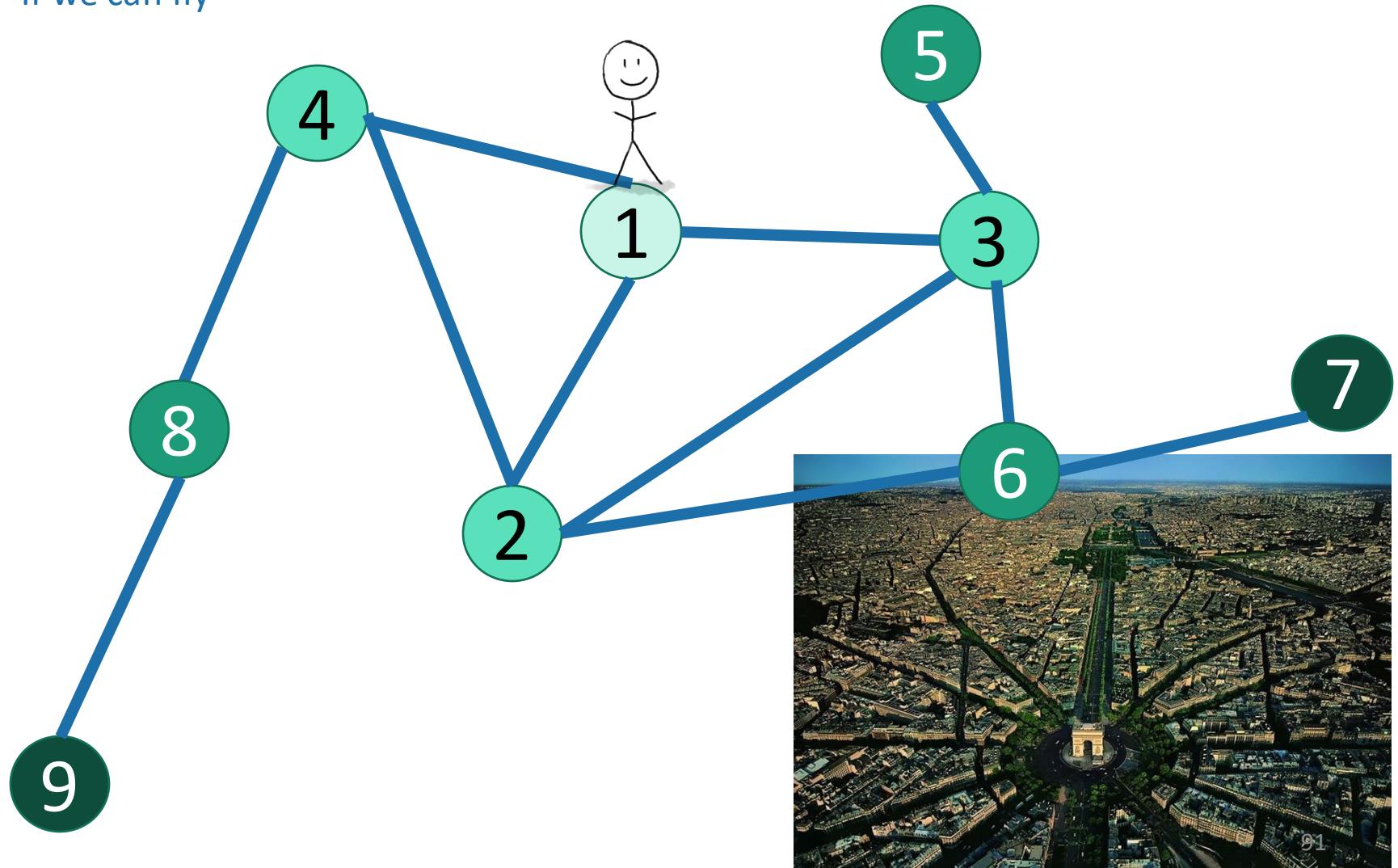


Do DFS and print a node's label when you are done with the left child and before you begin the right child.

# Part 2: breadth-first search

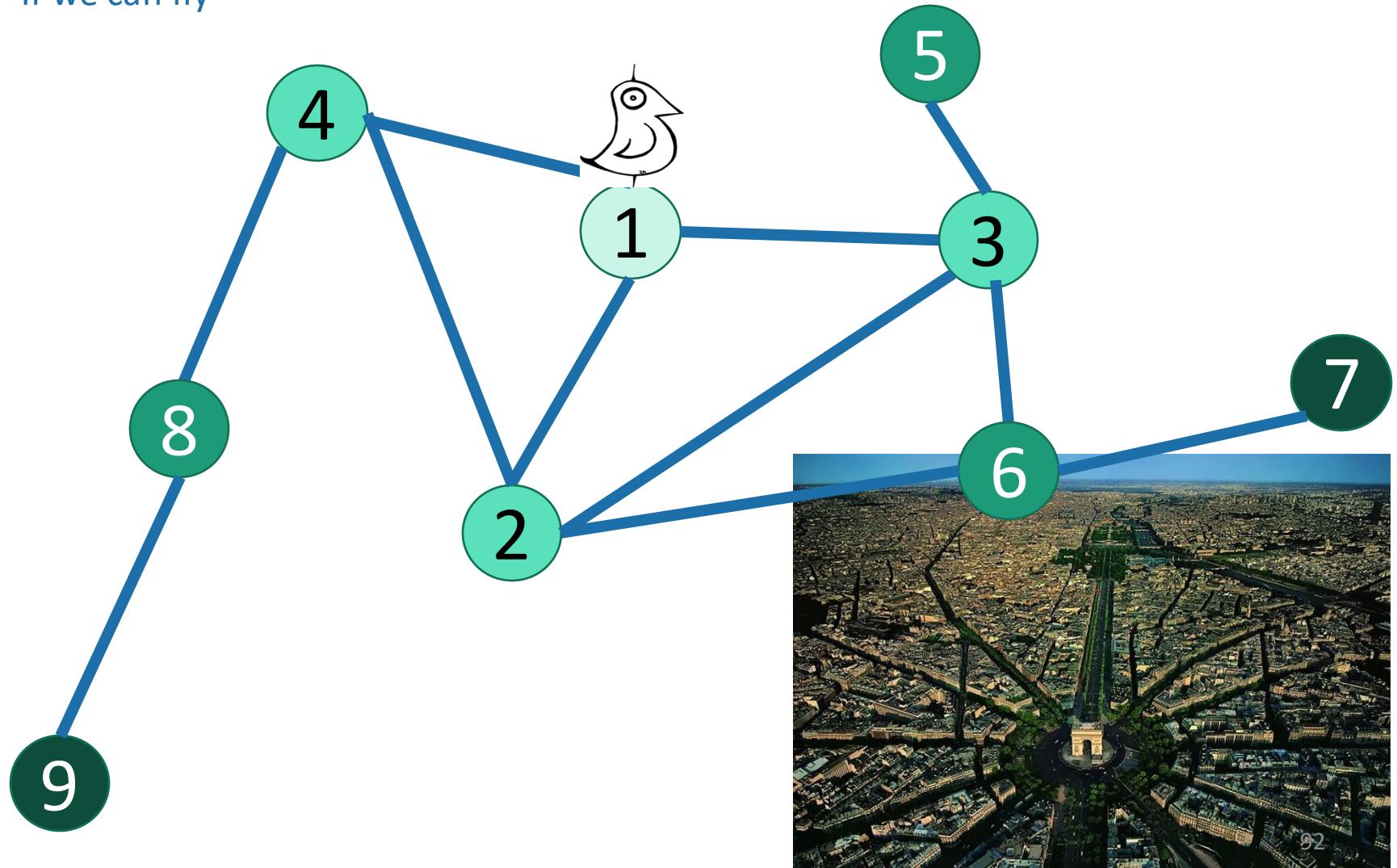
# How do we explore a graph?

If we can fly



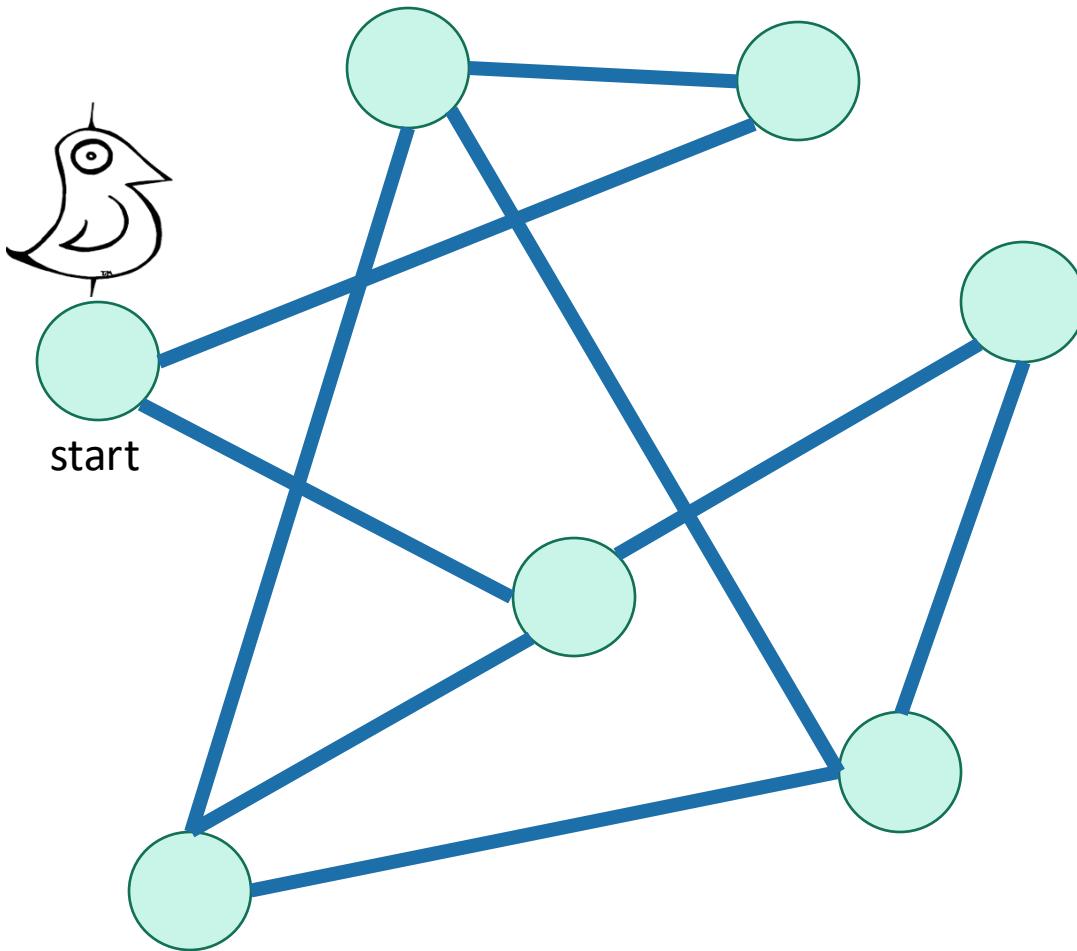
# How do we explore a graph?

If we can fly



# Breadth-First Search

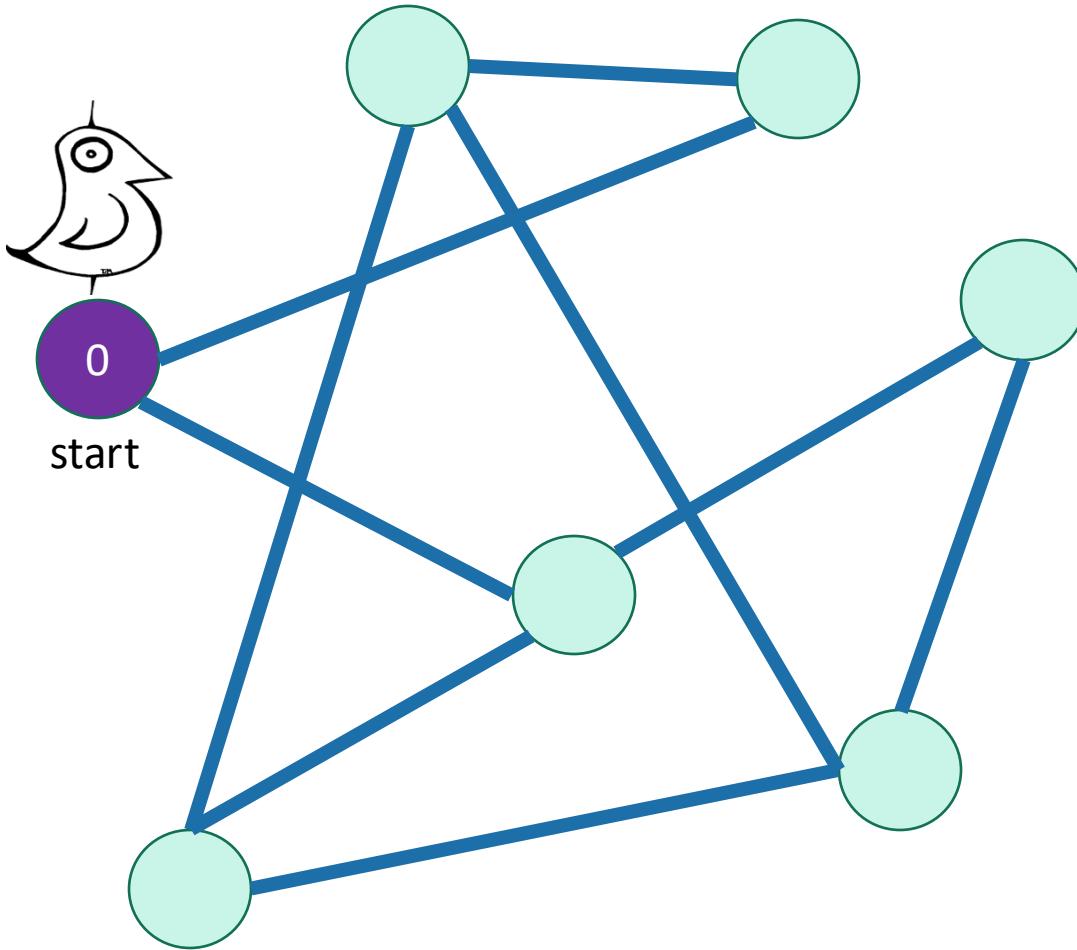
Exploring the world with a bird's-eye view



- Not been there yet
- 0 Can reach there in zero steps
- 1 Can reach there in one step
- 2 Can reach there in two steps
- 3 Can reach there in three steps

# Breadth-First Search

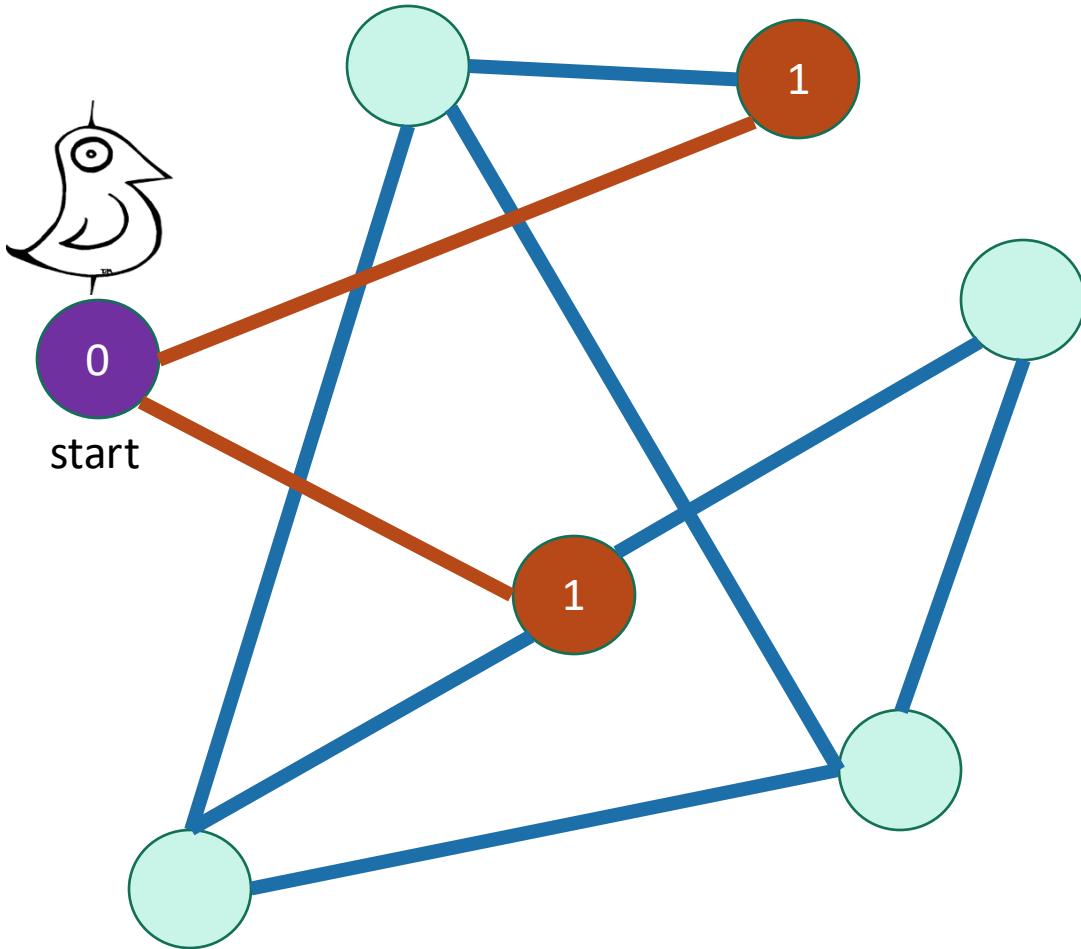
Exploring the world with a bird's-eye view



- Not been there yet
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# Breadth-First Search

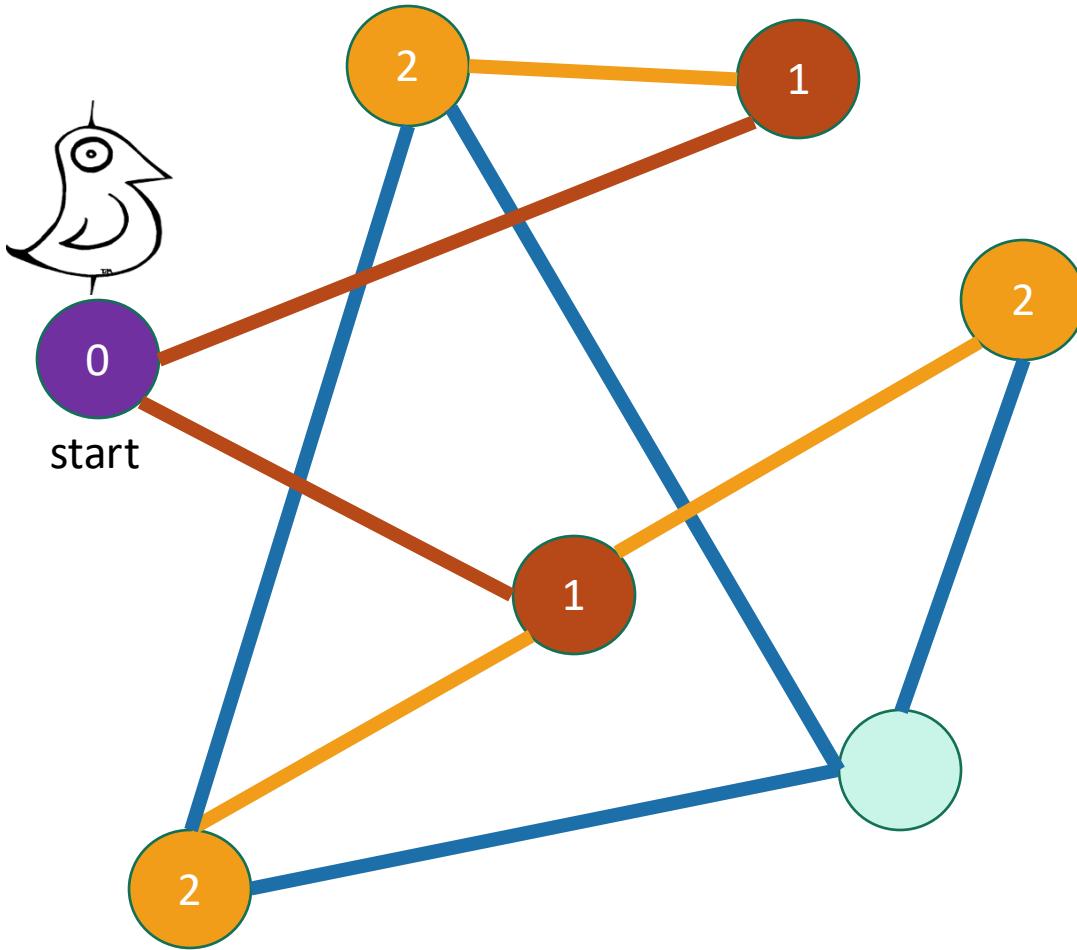
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# Breadth-First Search

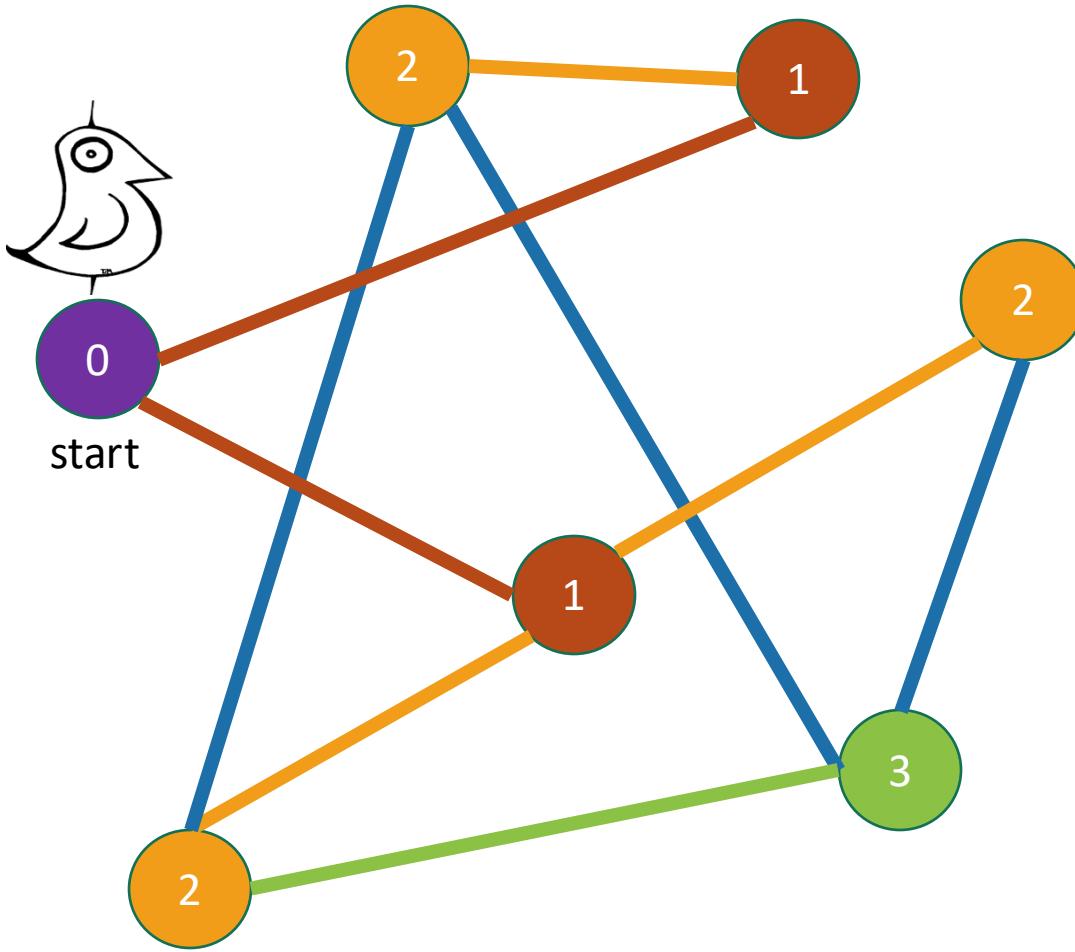
Exploring the world with a bird's-eye view



- Not been there yet
- 0 Can reach there in zero steps
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- 3 Can reach there in three steps

# Breadth-First Search

Exploring the world with a bird's-eye view



- Not been there yet
- 0 Can reach there in zero steps
- 1 Can reach there in one step
- 2 Can reach there in two steps
- 3 Can reach there in three steps

World:  
explored!

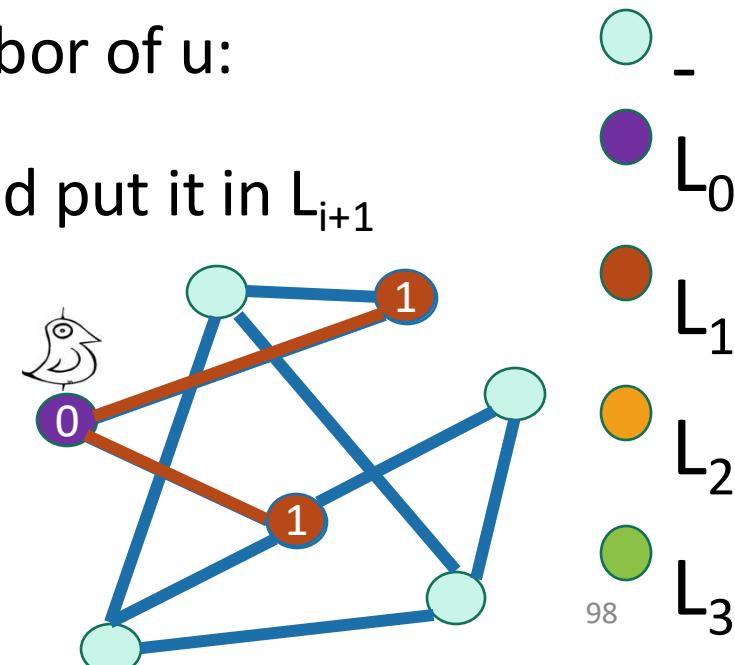
# Breadth-First Search

## Exploring the world with pseudocode

- Set  $L_i = []$  for  $i=1, \dots, n$
- $L_0 = [w]$ , where  $w$  is the start node
- Mark  $w$  as visited
- **For**  $i = 0, \dots, n-1$ :
  - **For**  $u$  in  $L_i$ :
    - **For** each  $v$  which is a neighbor of  $u$ :
    - **If**  $v$  isn't yet visited:
      - mark  $v$  as visited, and put it in  $L_{i+1}$

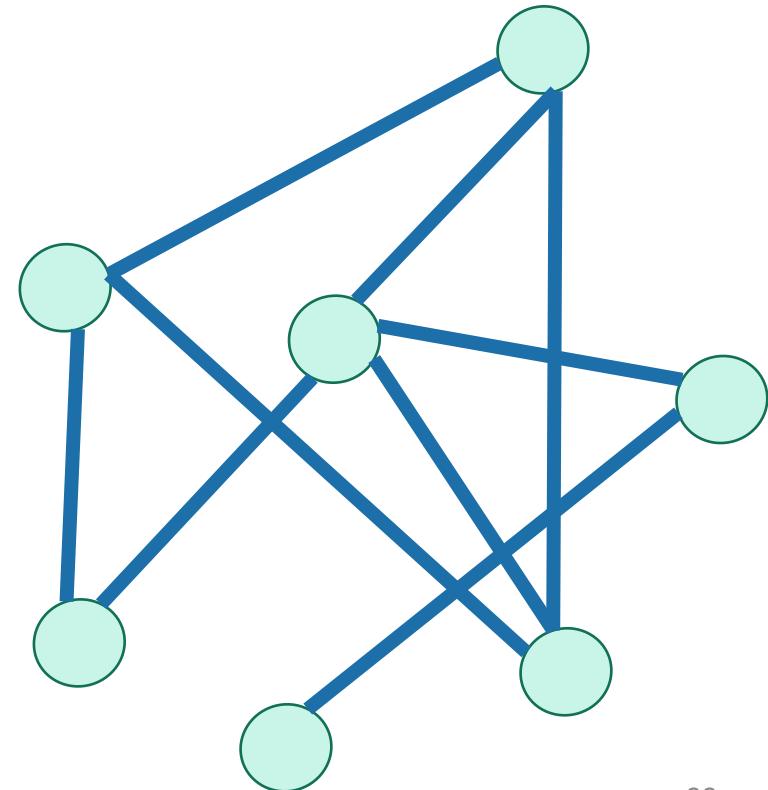
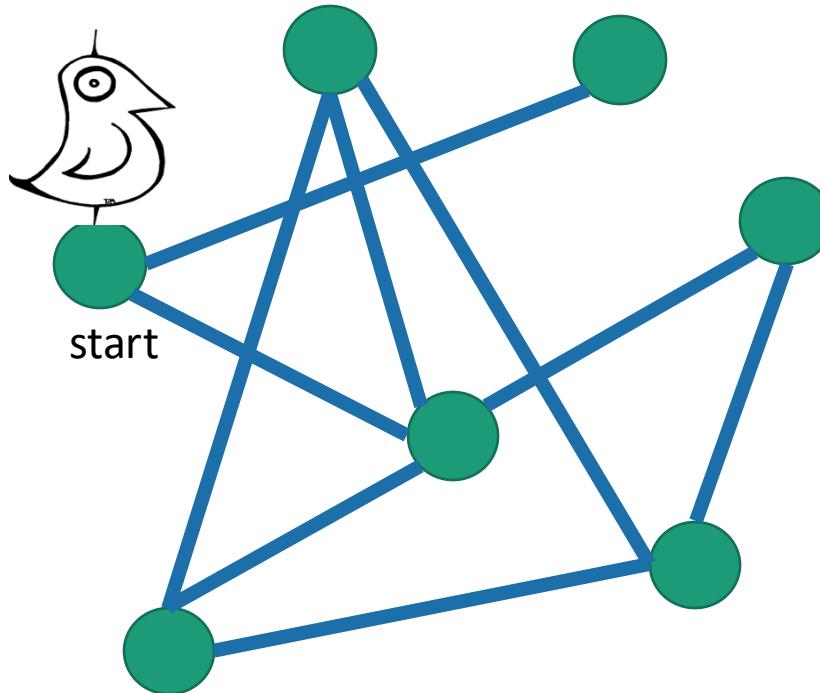
$L_i$  is the set of nodes  
we can reach in  $i$   
steps from  $w$

Go through all the nodes  
in  $L_i$  and add their  
unvisited neighbors to  $L_{i+1}$



## Just like DFS...

BFS finds all the nodes reachable from the starting point

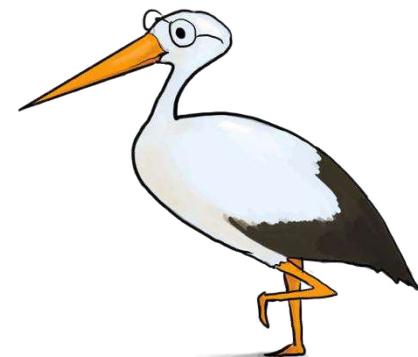


It is also a good way to find all the **connected components**.

# BFS: Running time and extension to directed graphs

- To explore the whole graph, explore the connected components one-by-one.
  - Same argument as DFS: BFS running time is  $O(n + m)$
- Like DFS, BFS also works fine on directed graphs.

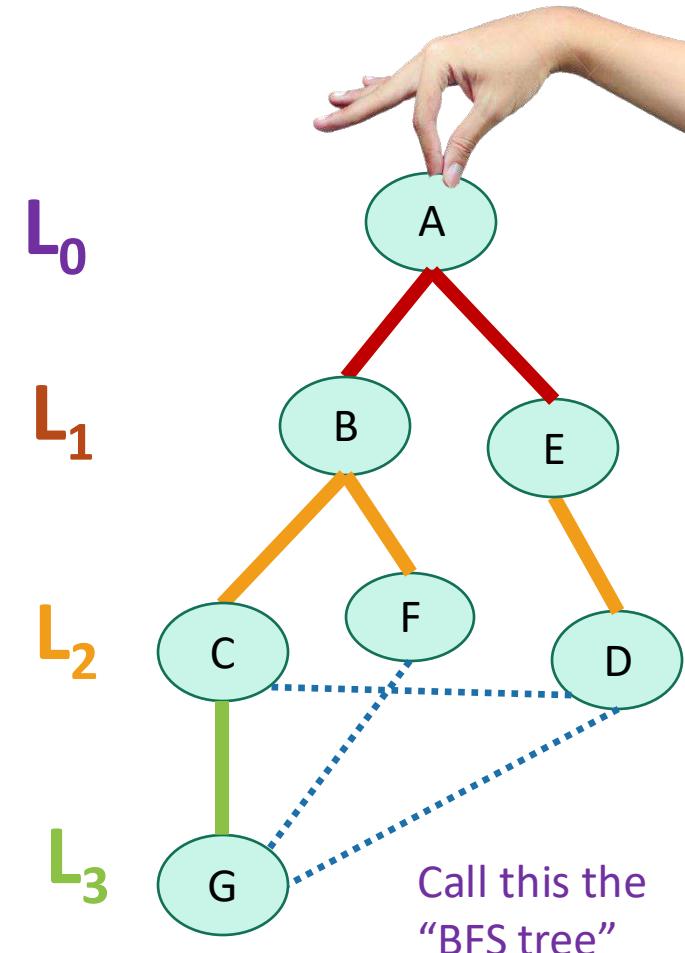
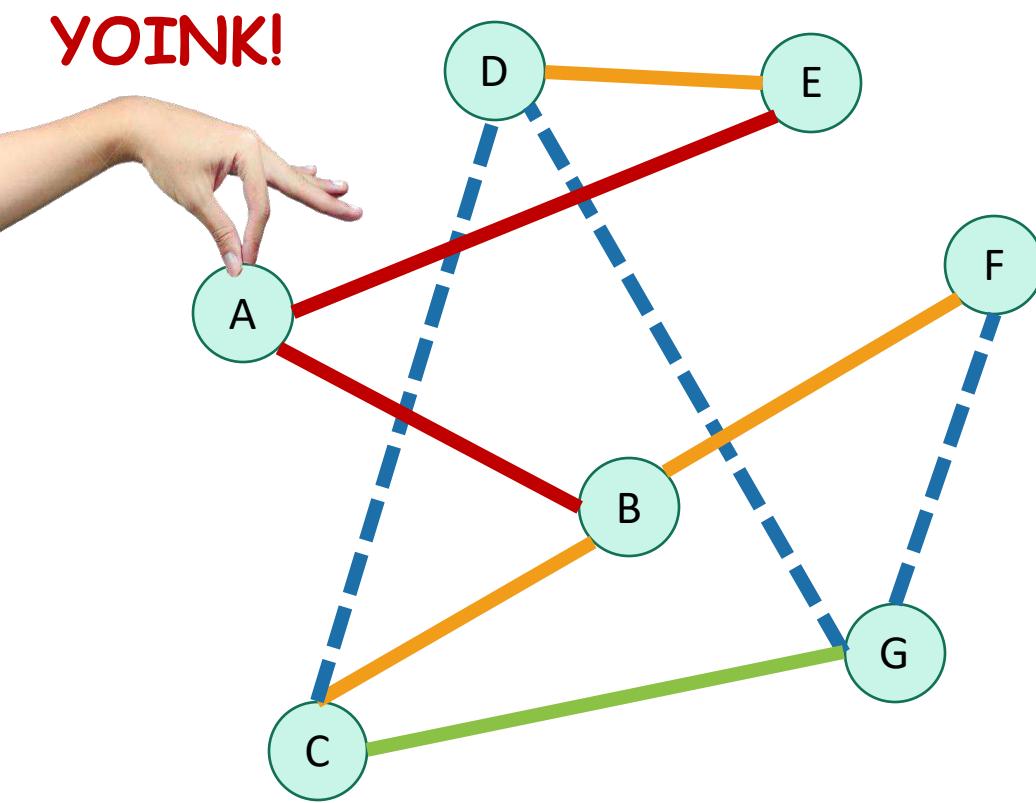
Verify these!



Siggi the Studious Stork

# Why is it called breadth-first?

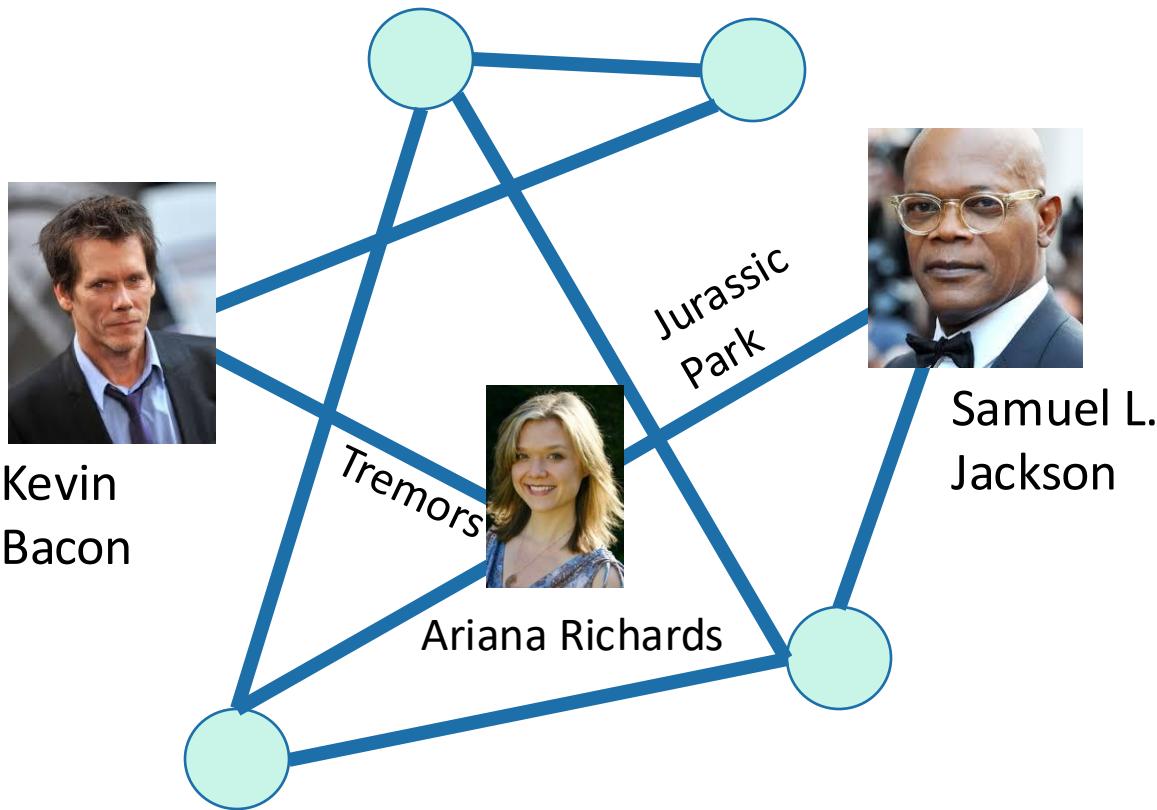
- We are implicitly building a tree:



- First we go as broadly as we can.

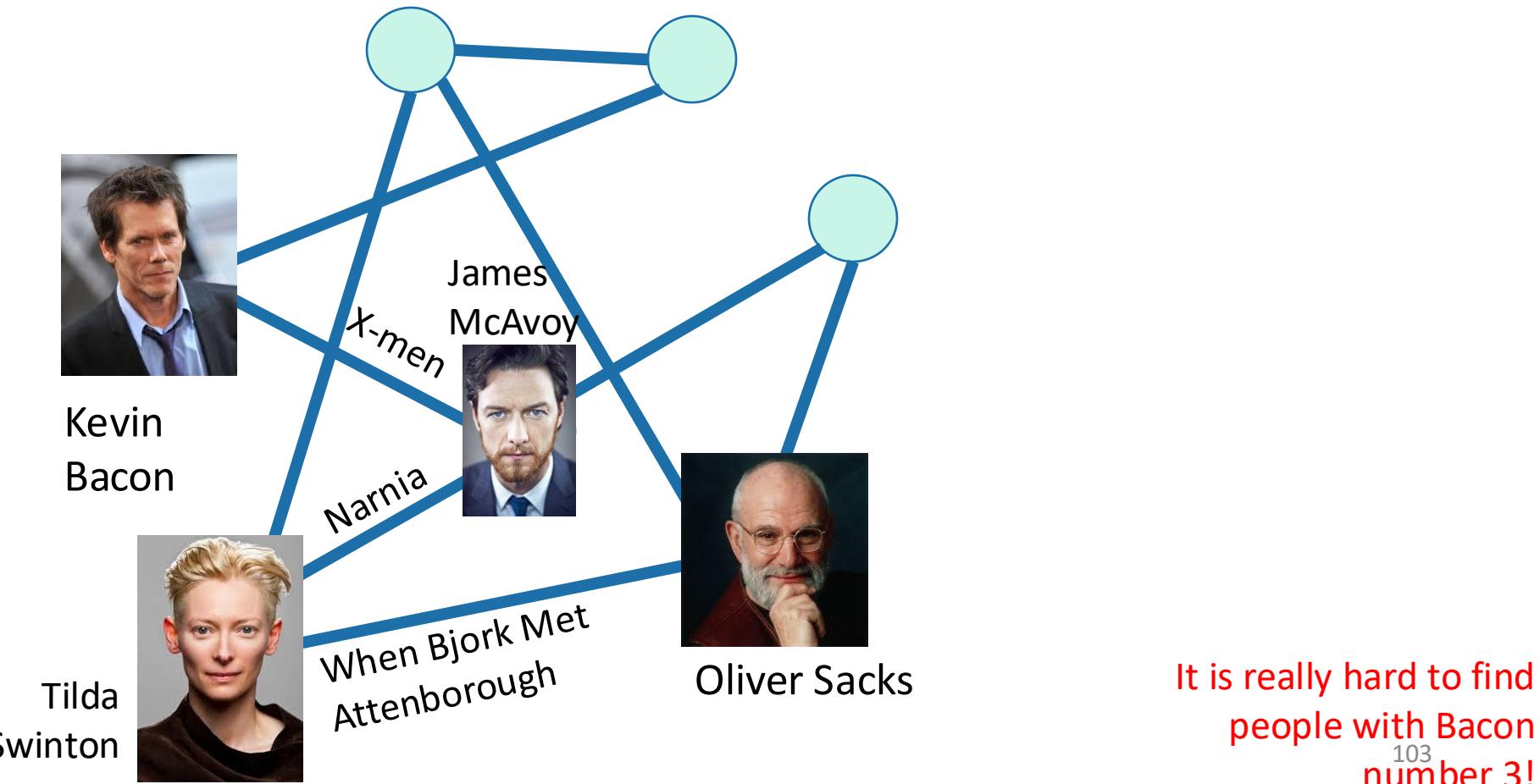
# Pre-lecture exercise

- What is Samuel L. Jackson's Bacon number?



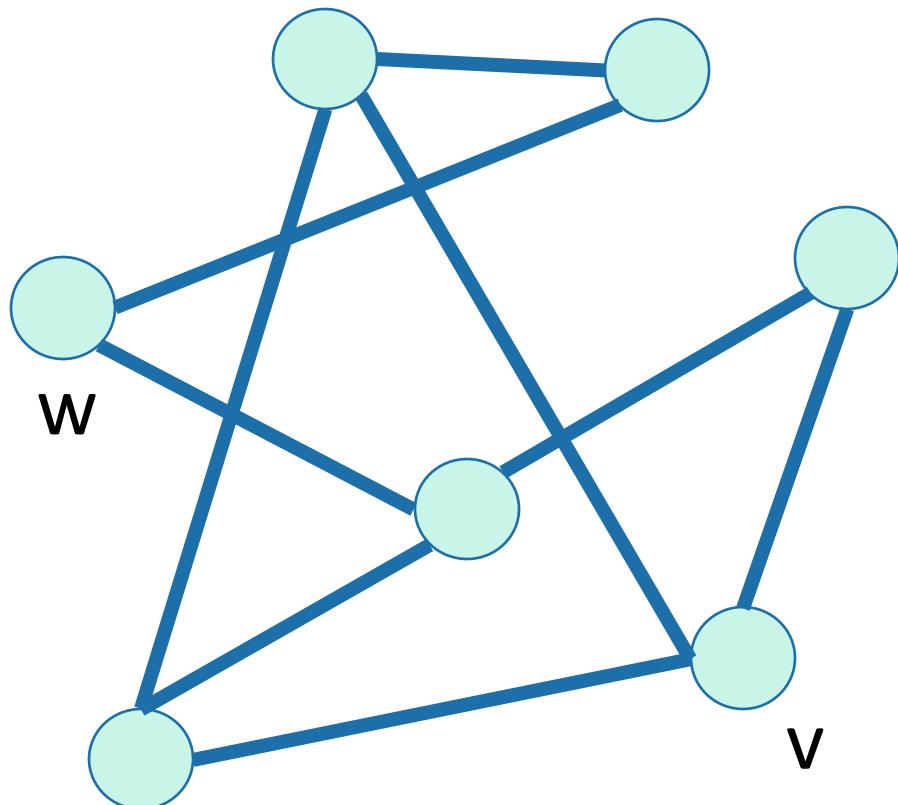
(Answer: 2)

# But for our running example I actually wanted distance 3...



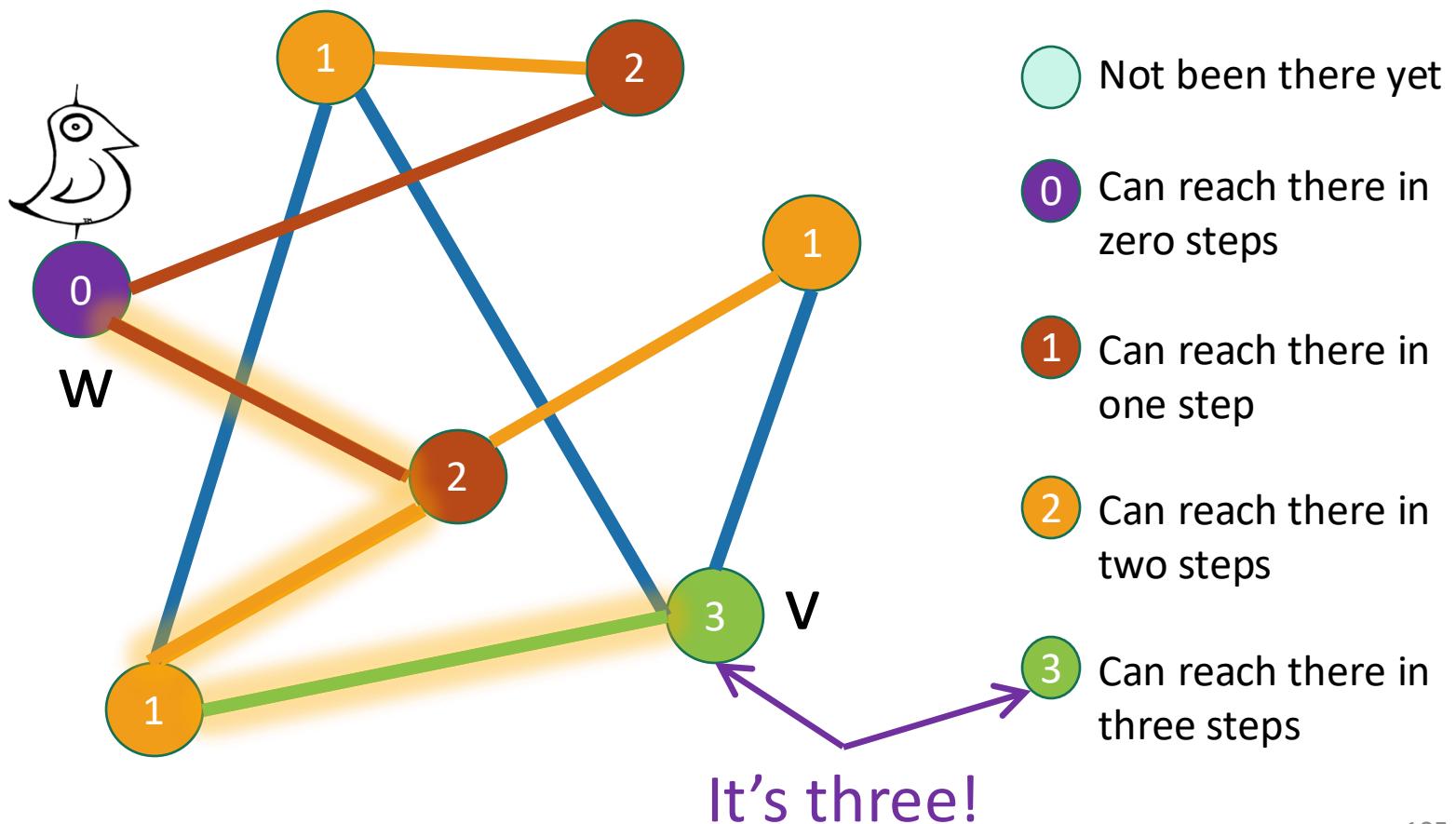
# Application of BFS: shortest path

- How long is the shortest path between w and v?



# Application of BFS: shortest path

- How long is the shortest path between w and v?



# To find the **distance** between w and all other vertices v

- Do a BFS starting at w
- For all v in  $L_i$ 
  - The shortest path between w and v has length i
  - A shortest path between w and v is given by the path in the BFS tree.
- If we never found v, the distance is infinite.

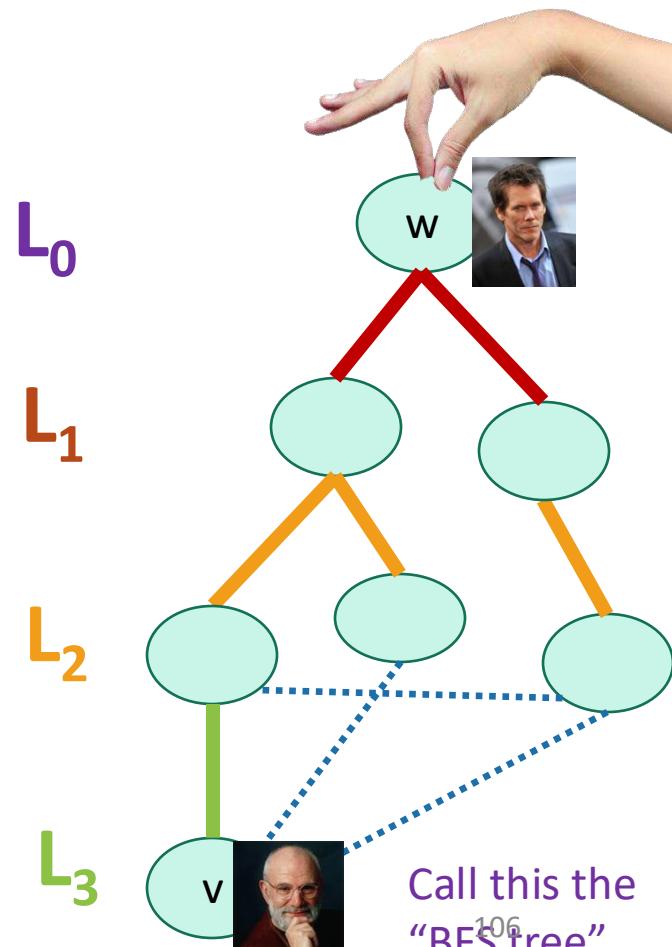
Modify the BFS pseudocode to return shortest paths!  
Prove that this indeed returns shortest paths!



Gauss has no Bacon number



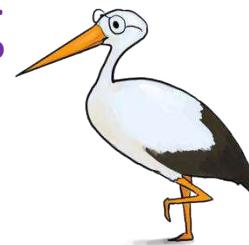
The **distance** between two vertices is the number of edges in the shortest path between them.



# What have we learned?

- The BFS tree is useful for computing distances between pairs of vertices.
- We can find the shortest path between  $u$  and  $v$  in time  $O(m)$ .

Wait... I thought the running time of BFS was  $O(n + m)$ ...  
why is it  $O(m)$  here?



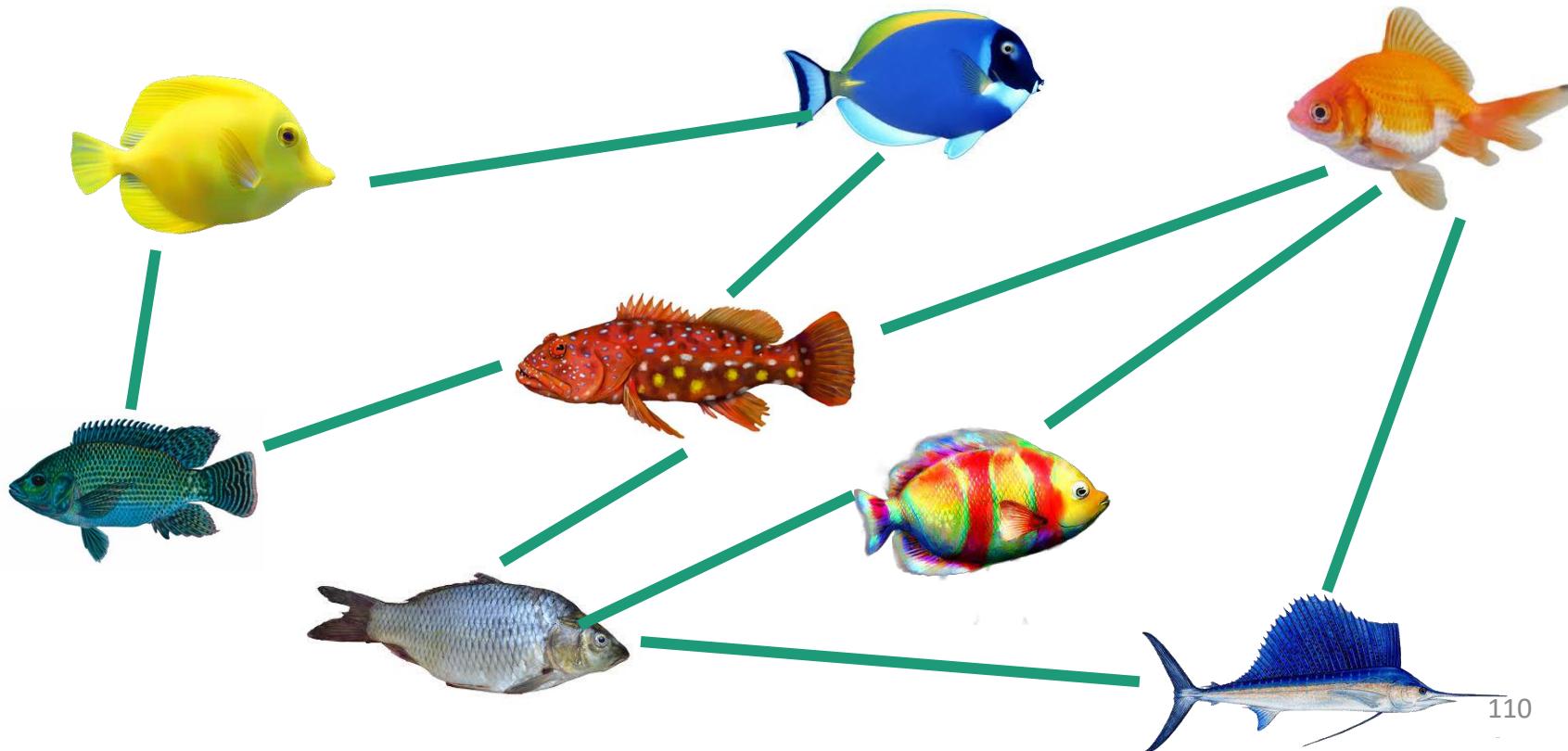
Siggi the Studious Stork

# Another application of BFS

- Testing bipartite-ness

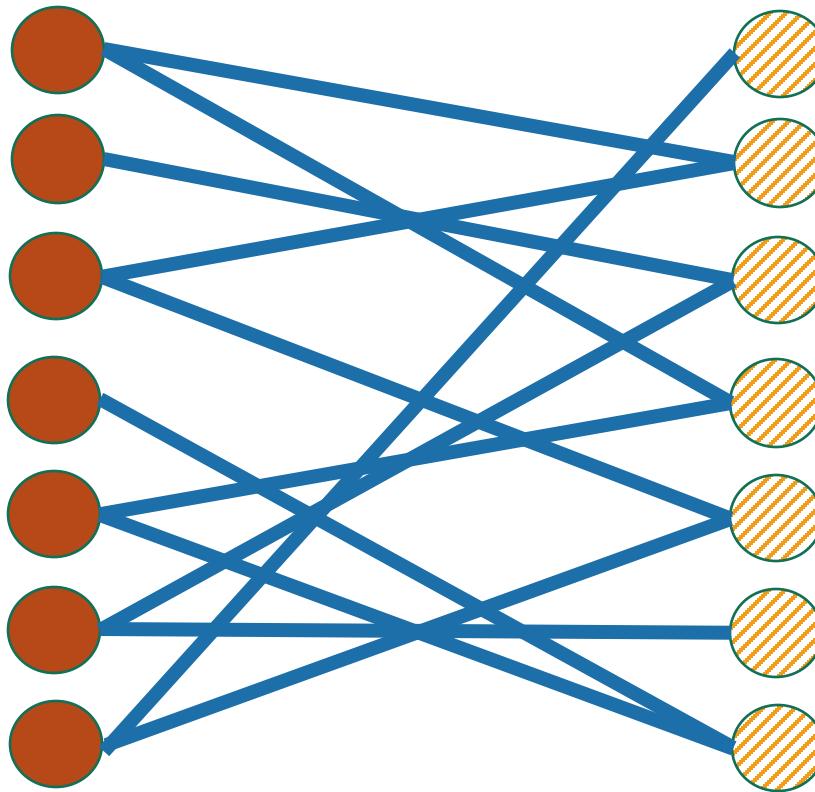
# Pre-lecture exercise: fish

- You have a bunch of fish and two fish tanks.
- Some pairs of fish will fight if put in the same tank.
  - Model this as a graph: connected fish will fight.
- Can you put the fish in the two tanks so that there is no fighting?



# Bipartite graphs

- A bipartite graph looks like this:



Can color the vertices red and orange so that there are no edges between any same-colored vertices

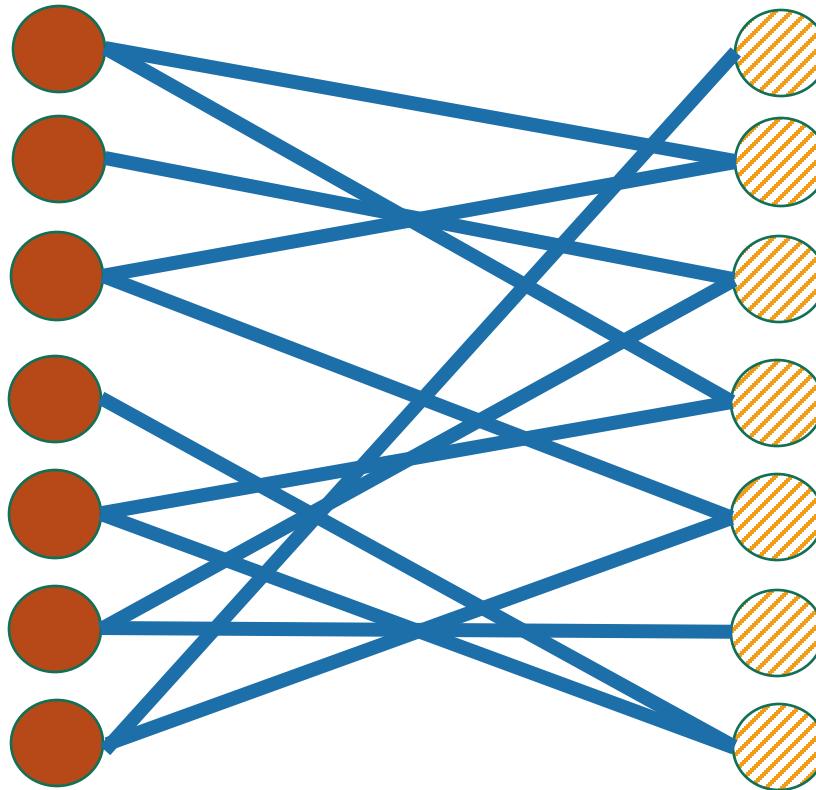
## Example:

- are in tank A
- are in tank B
- if the fish fight

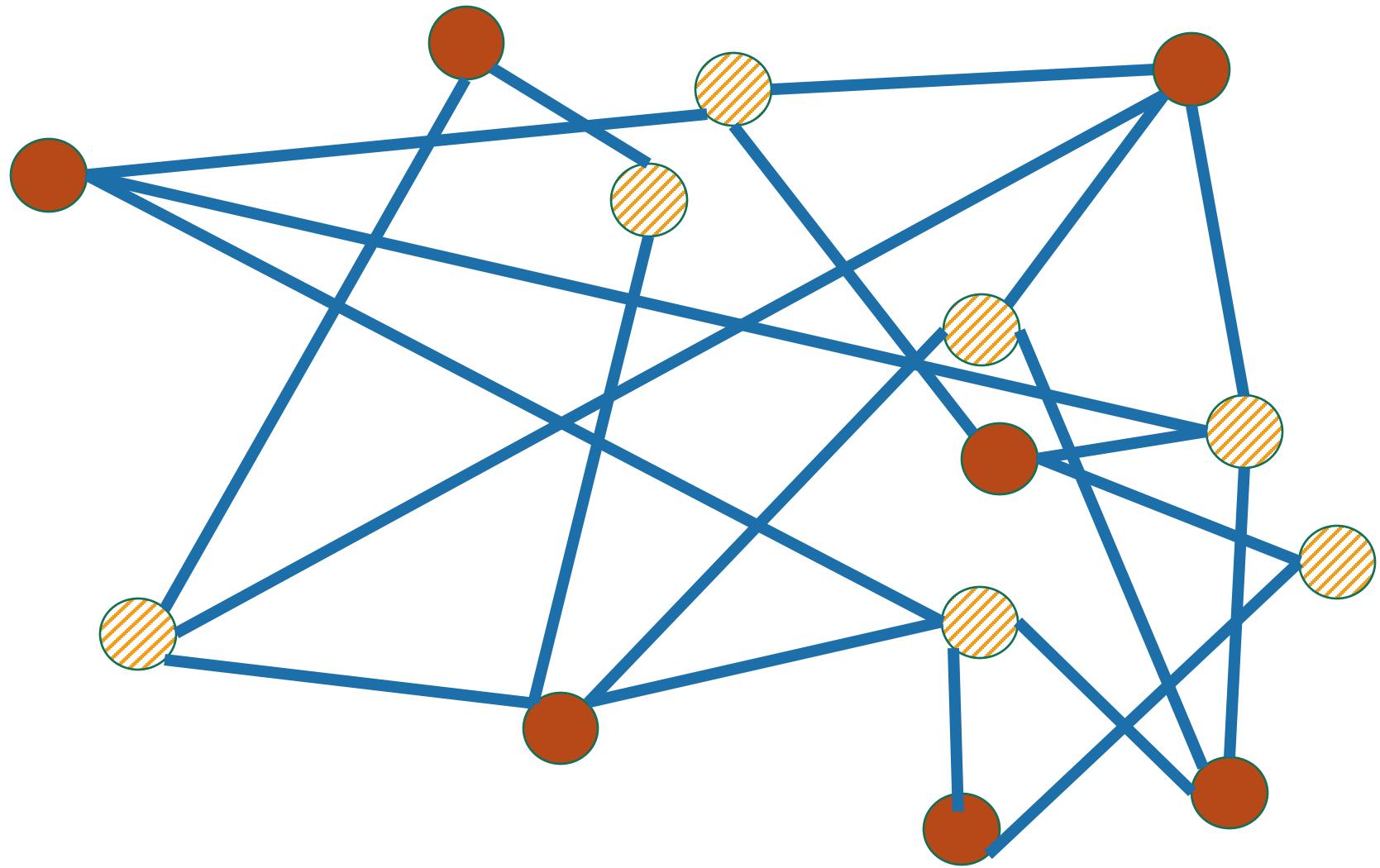
## Example:

- are students
- are classes
- if the student is enrolled in the class

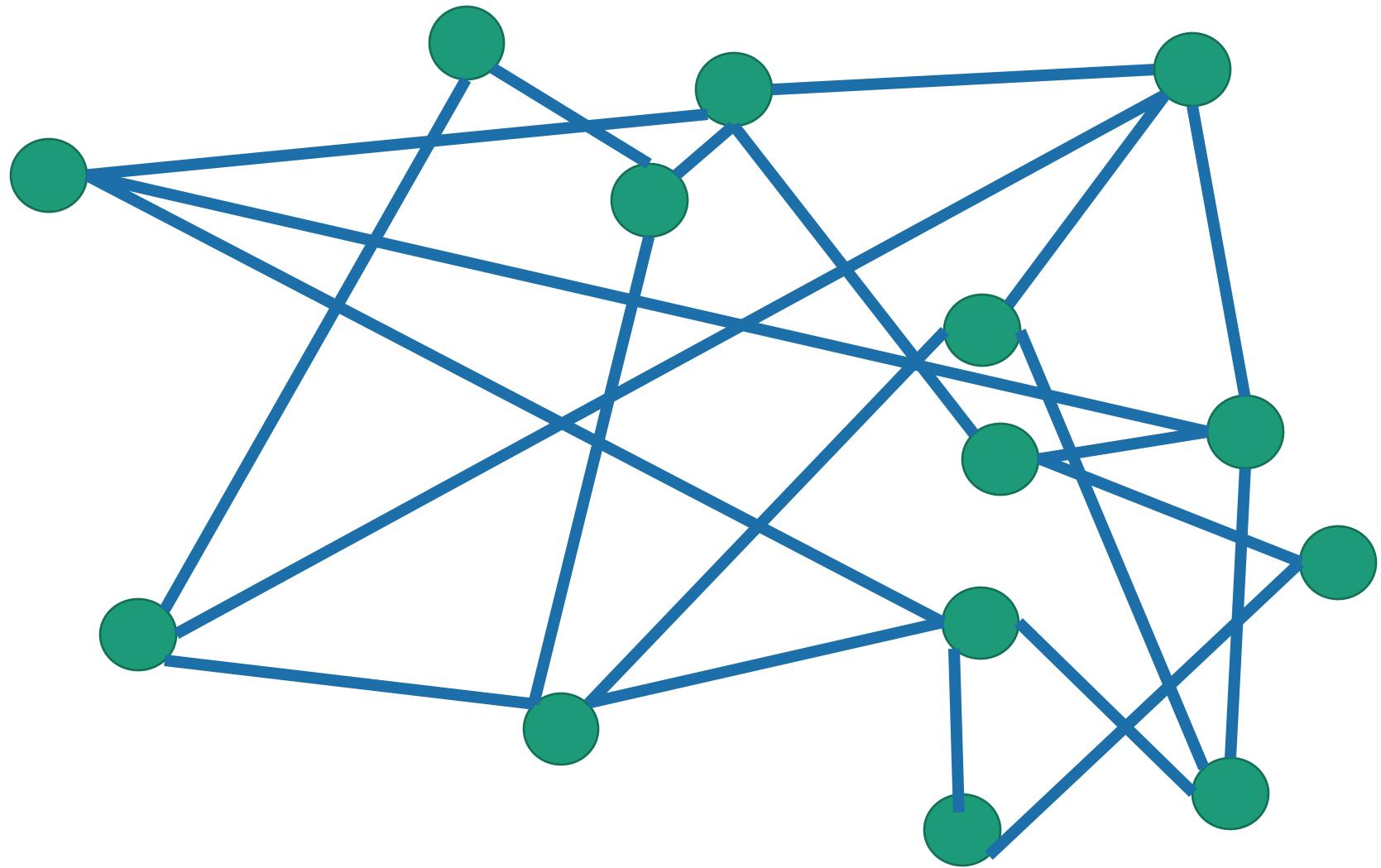
# Is this graph bipartite?



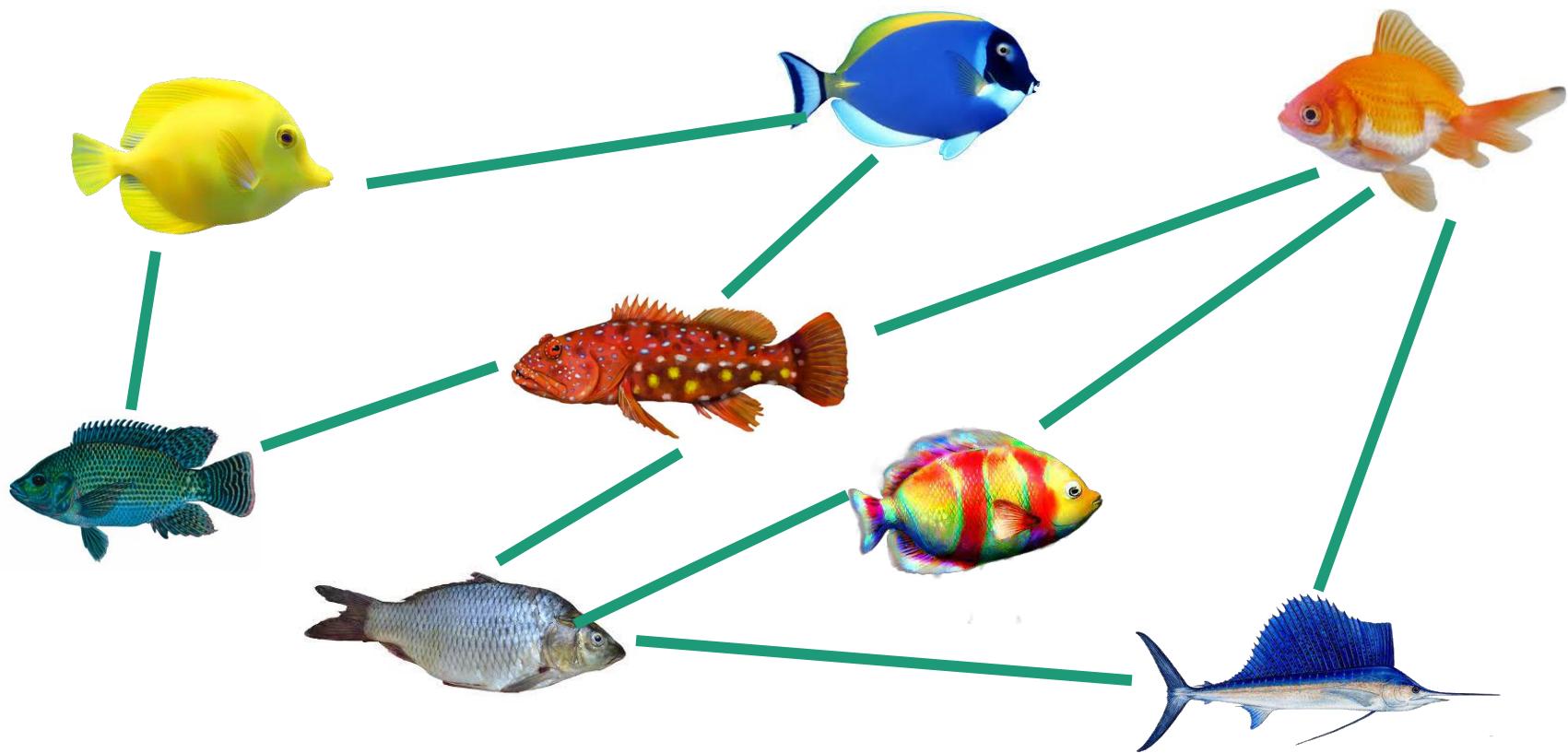
How about this one?



How about this one?

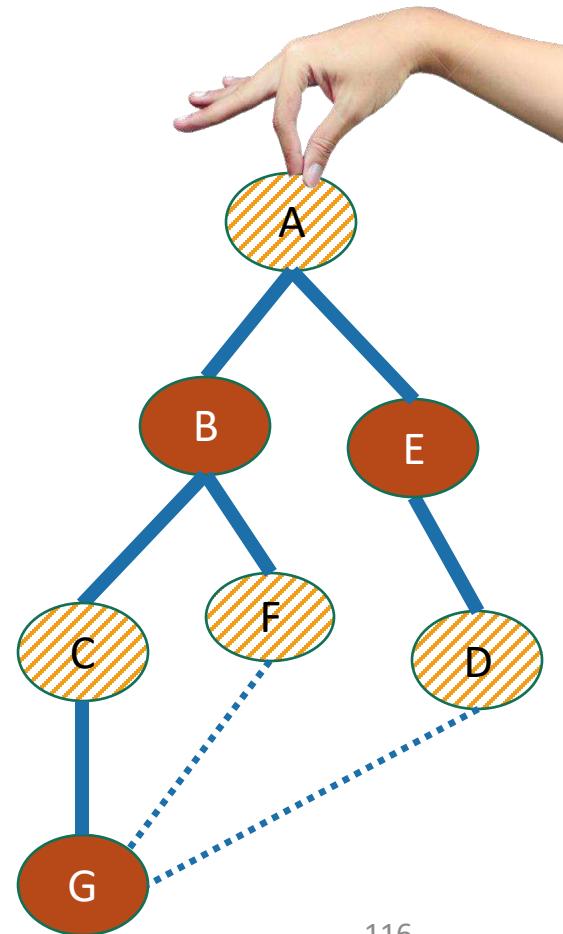


# This one?



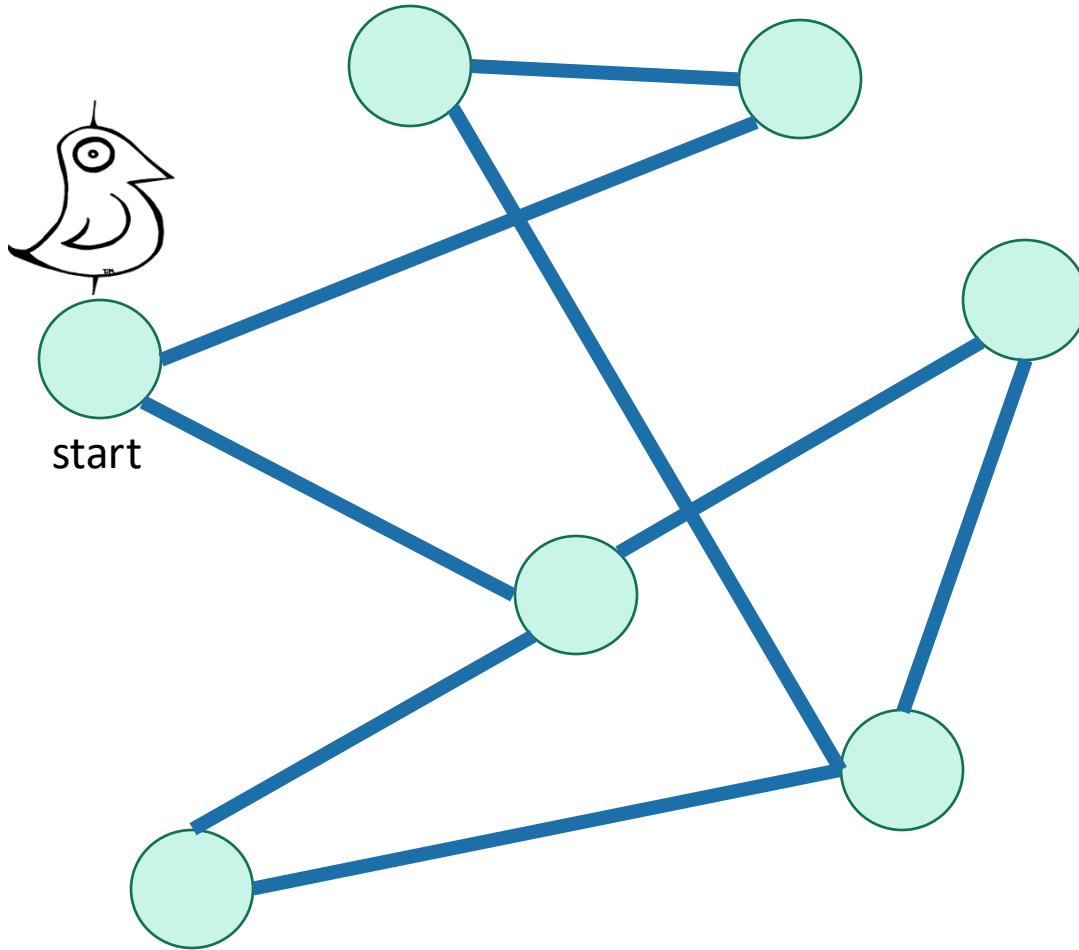
# Application of BFS: Testing Bipartiteness

- Color the levels of the BFS tree in alternating colors.
- If you never color two connected nodes the same color, then it is bipartite.
- Otherwise, it's not.



# Breadth-First Search

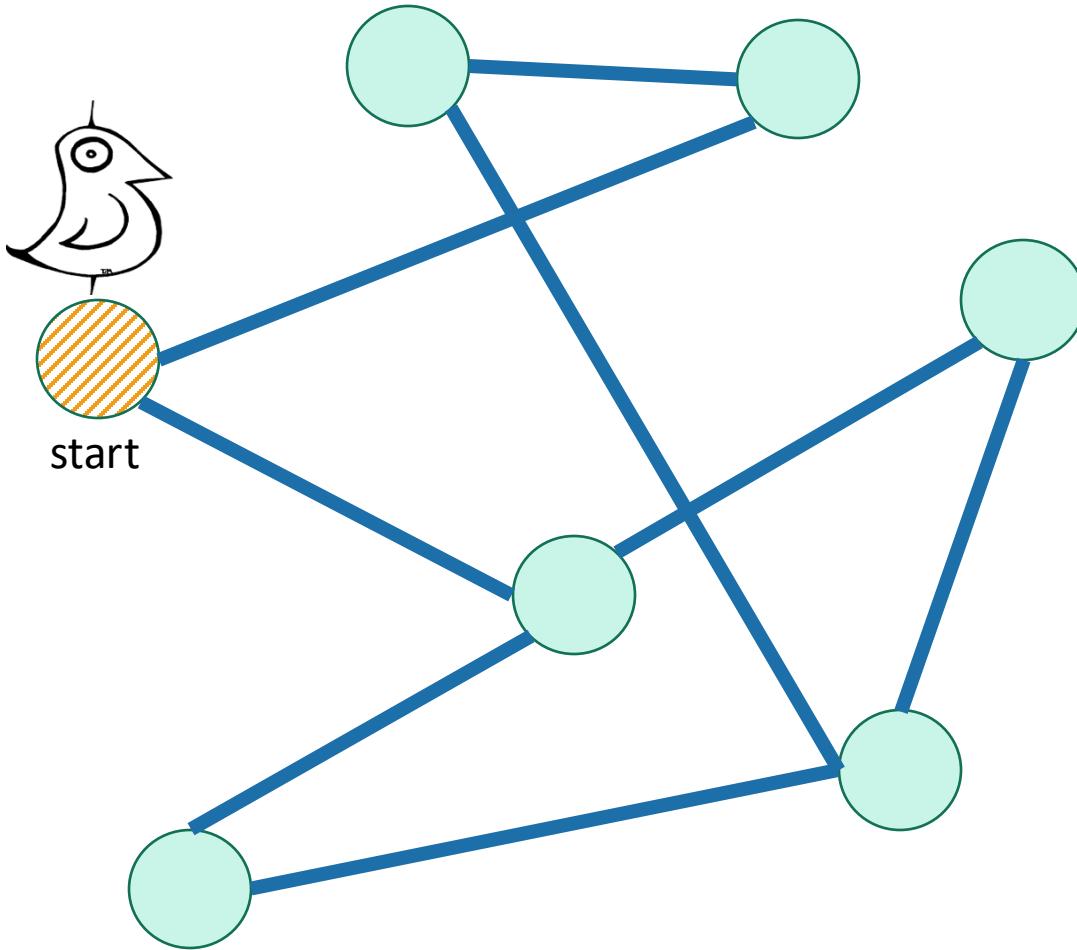
## For testing bipartite-ness



- Not been there yet
- Can reach there in zero steps
- Can reach there in one step
- Can reach there in two steps
- Can reach there in three steps

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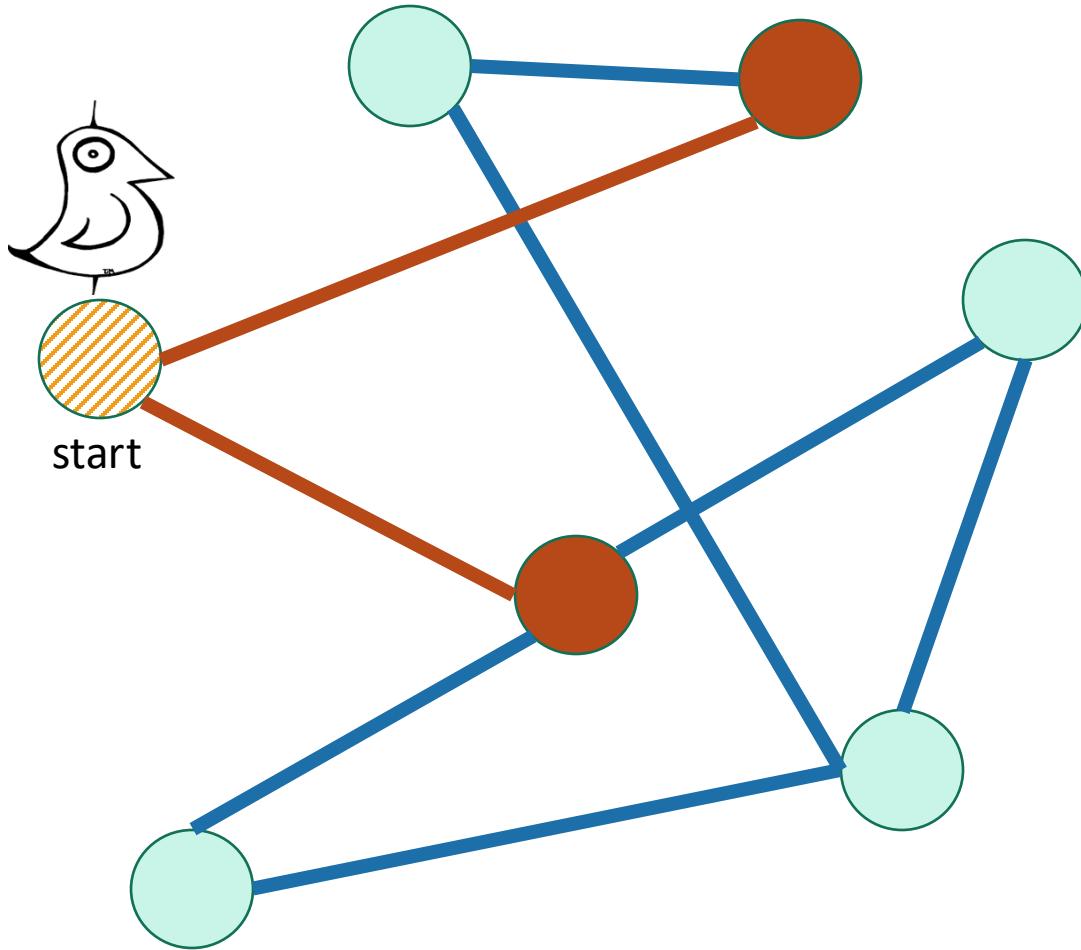
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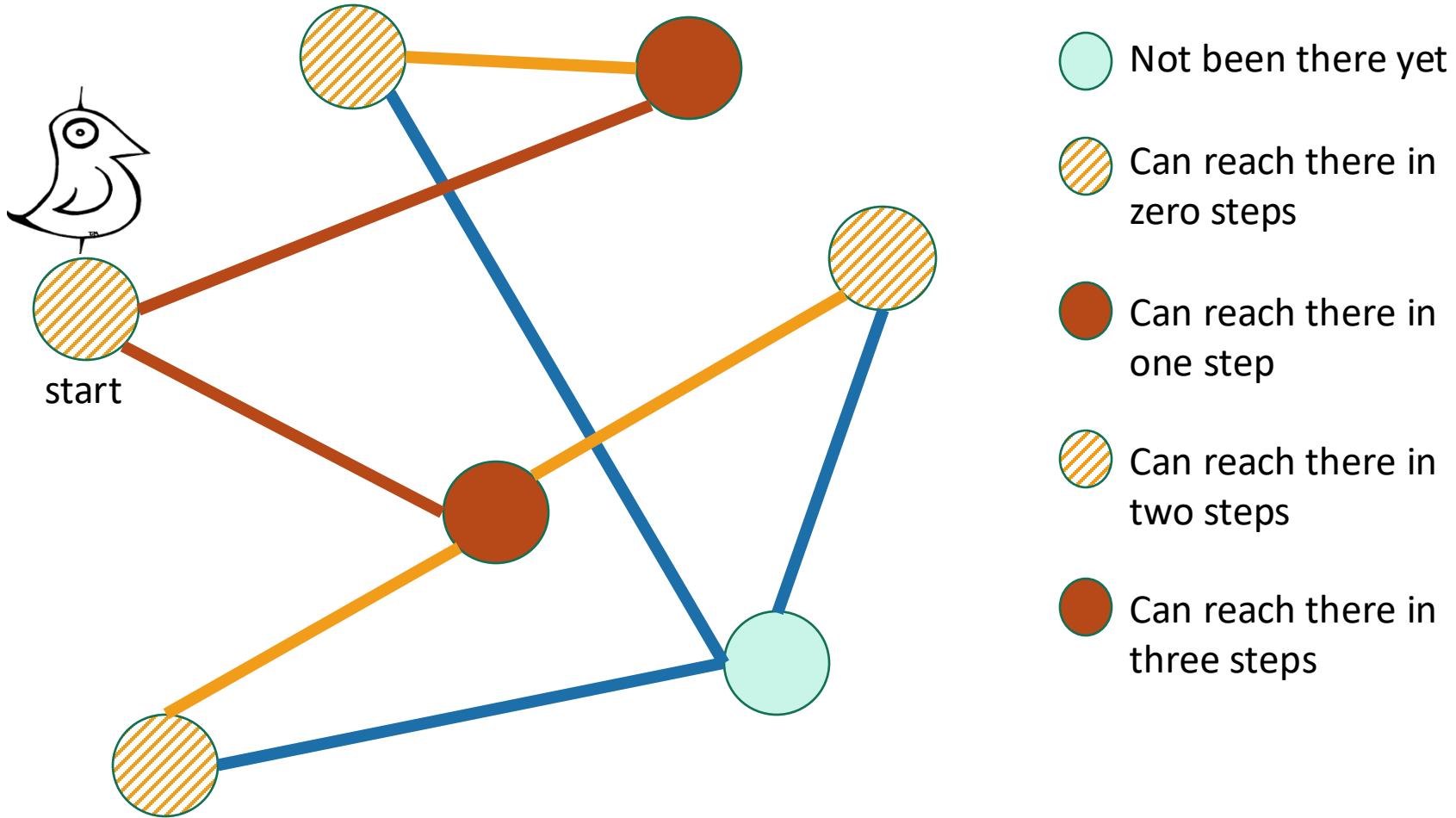
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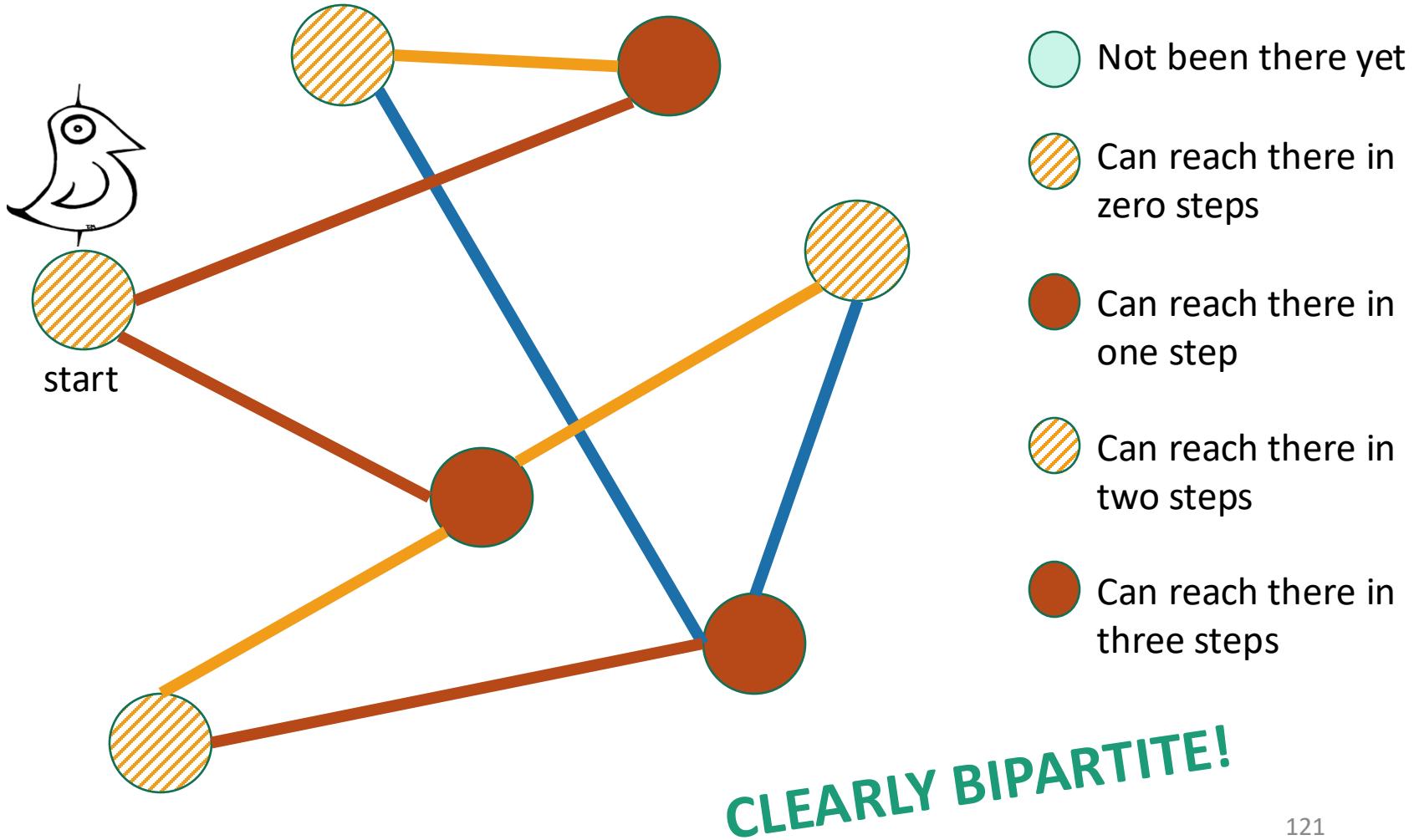
# Breadth-First Search

## For testing bipartite-ness



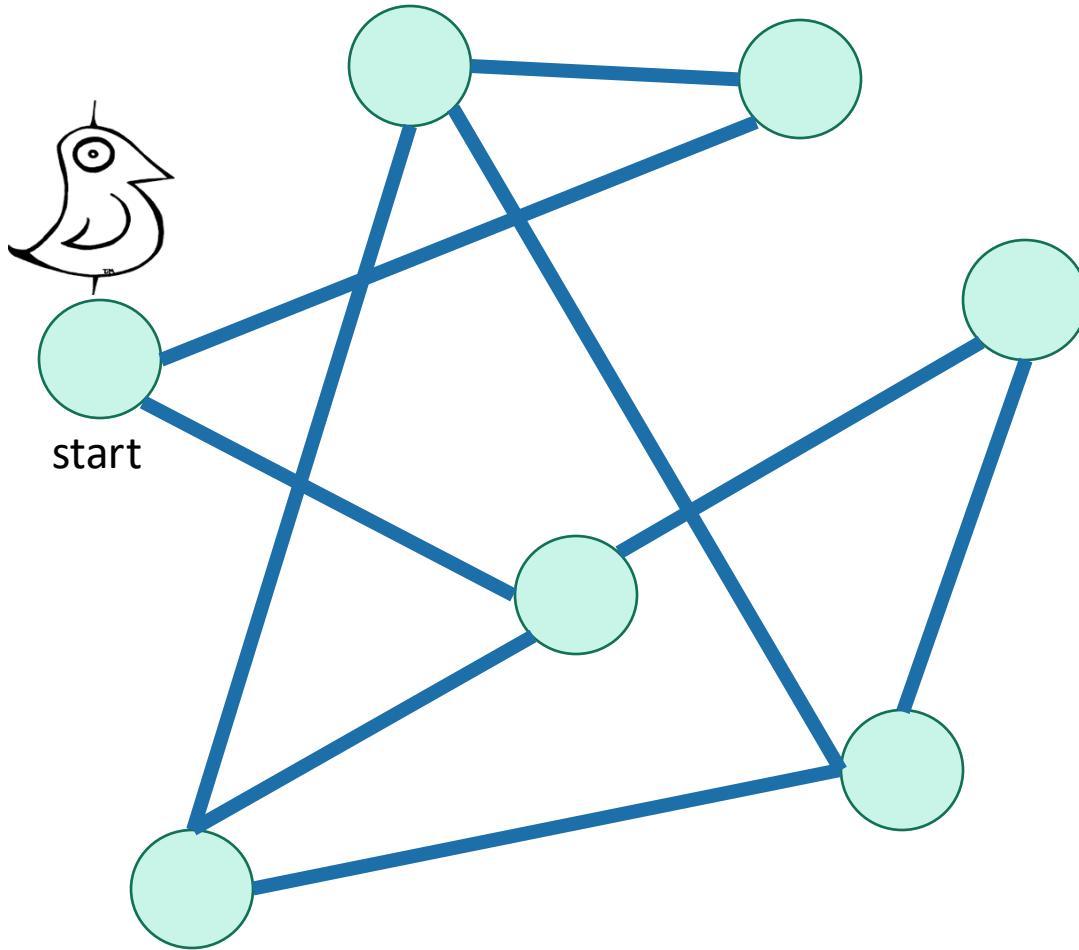
# Breadth-First Search

## For testing bipartite-ness



# Breadth-First Search

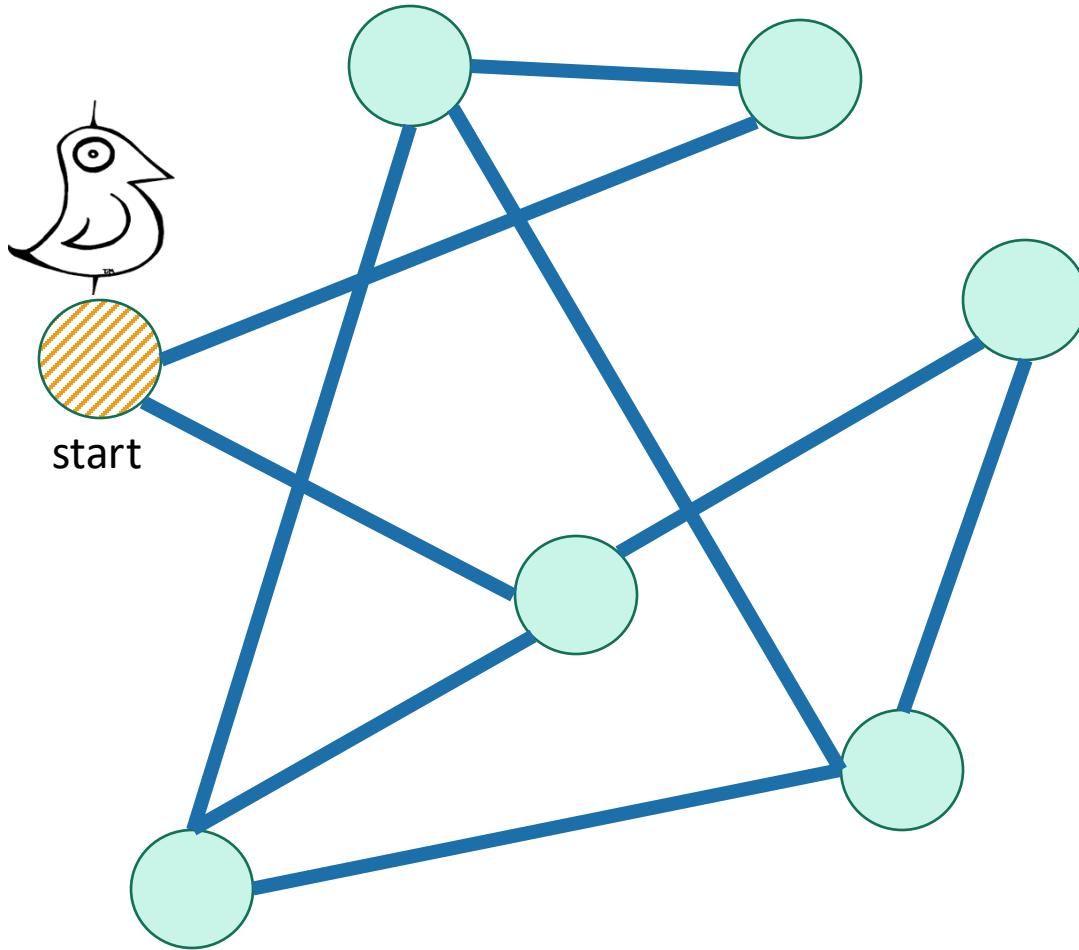
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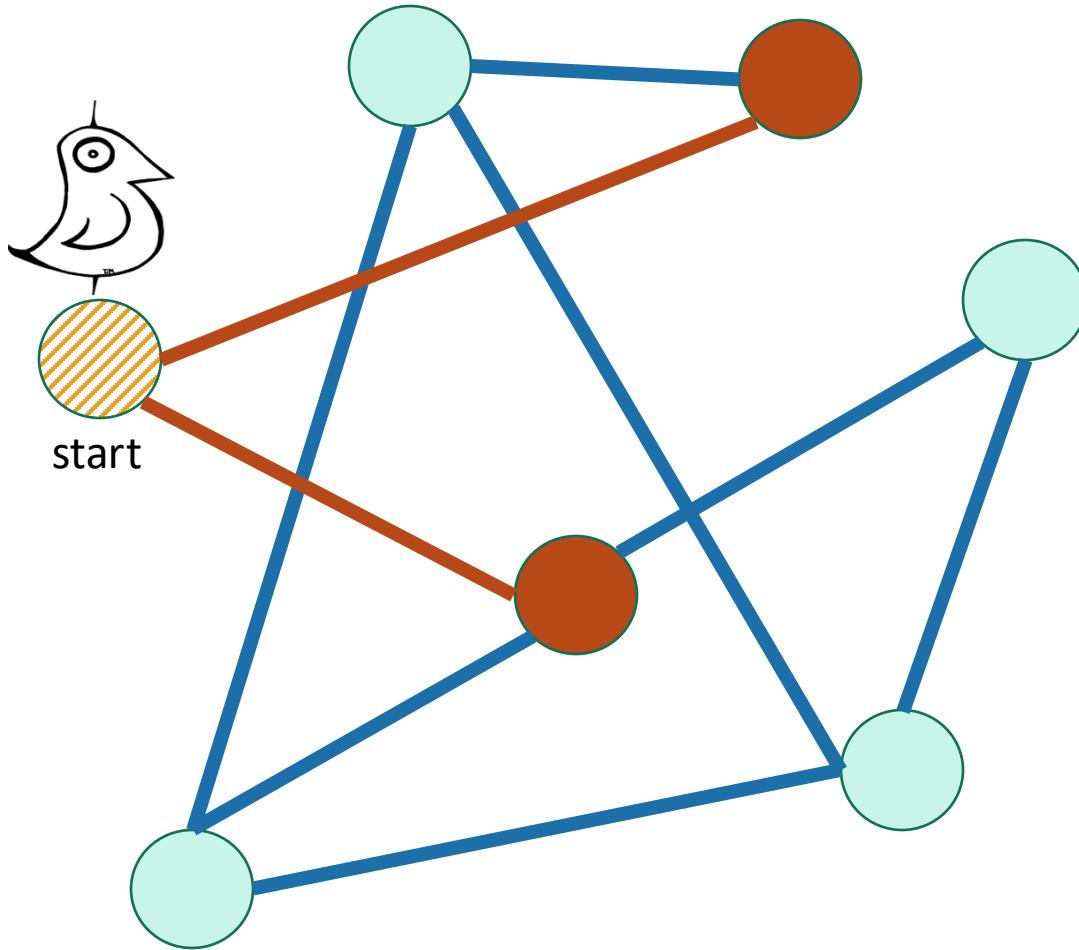
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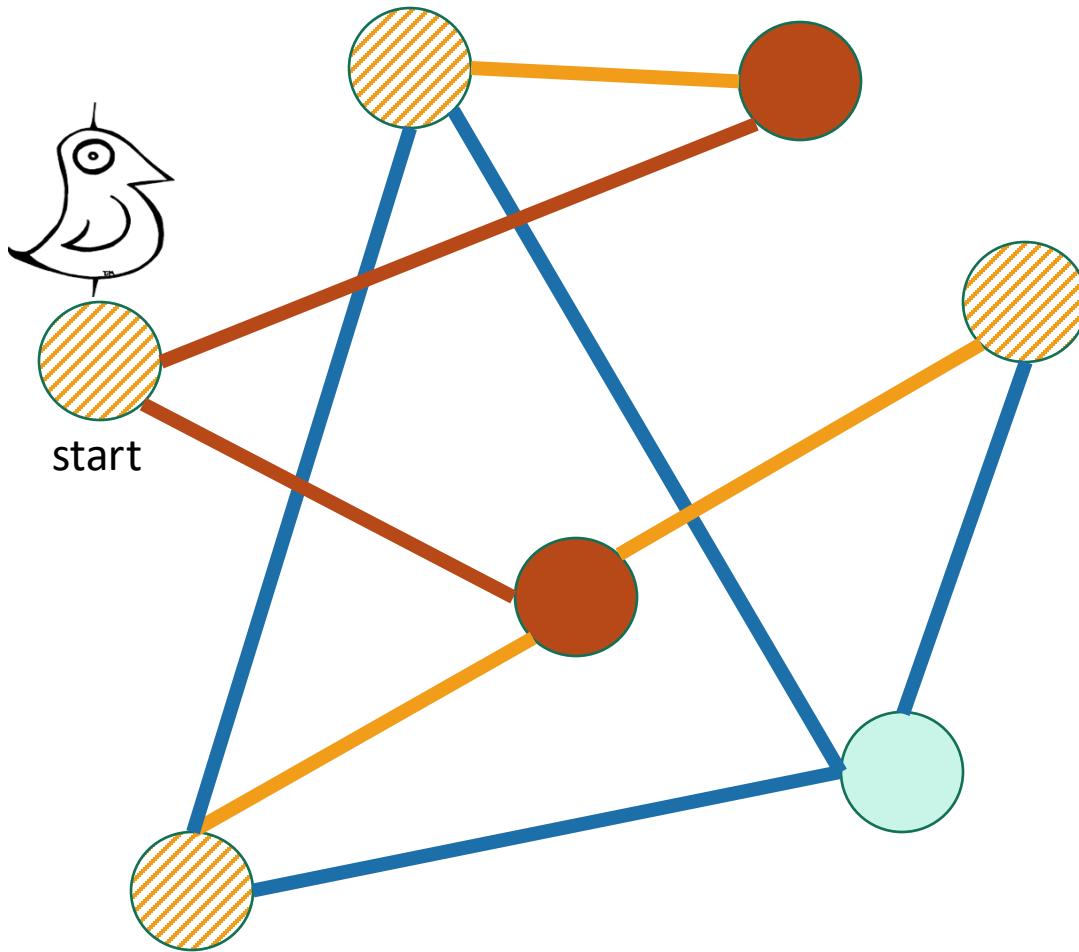
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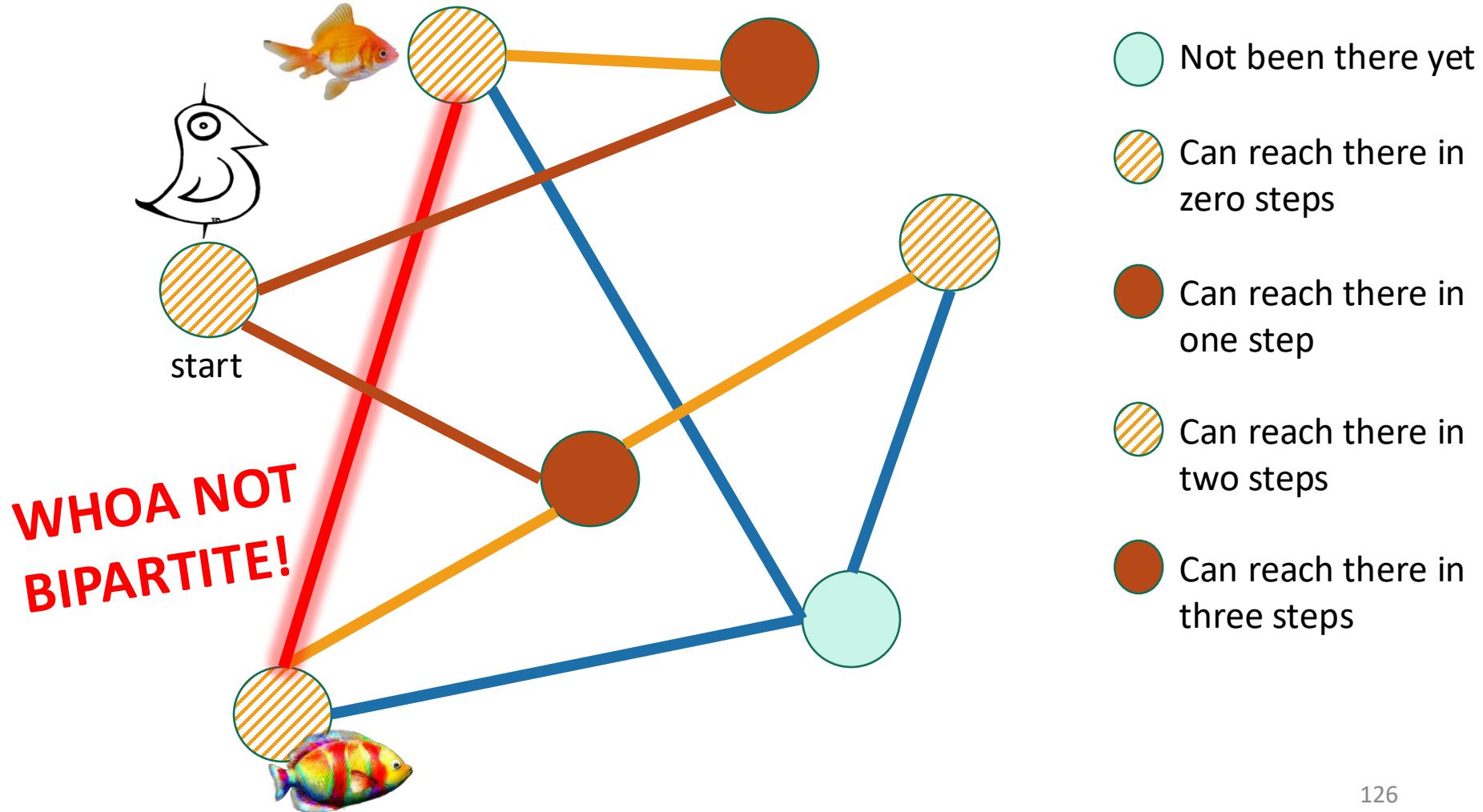
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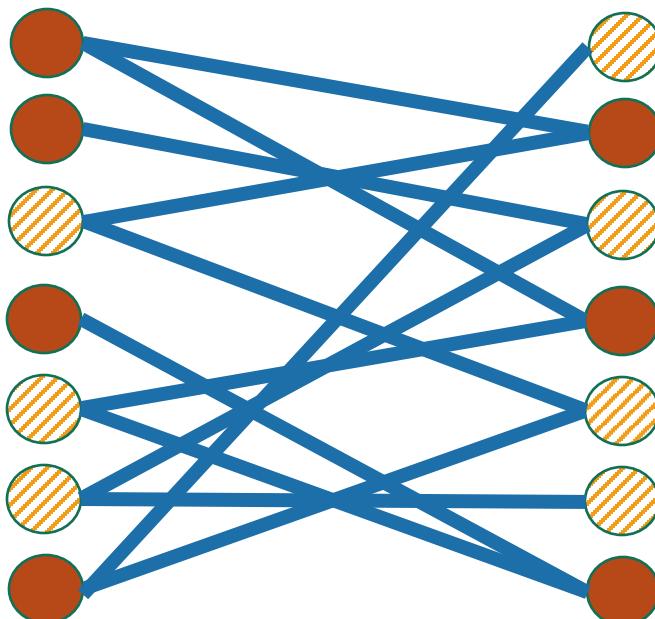
# Breadth-First Search

## For testing bipartite-ness



# Hang on now.

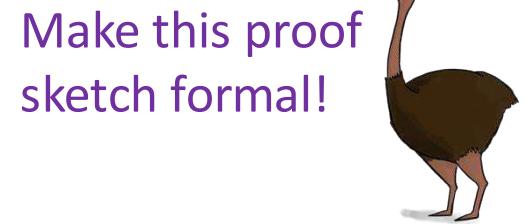
- Just because **this** coloring doesn't work, why does that mean that there is **no** coloring that works?



I can come up  
with plenty of bad  
colorings on this  
legitimately  
bipartite graph...



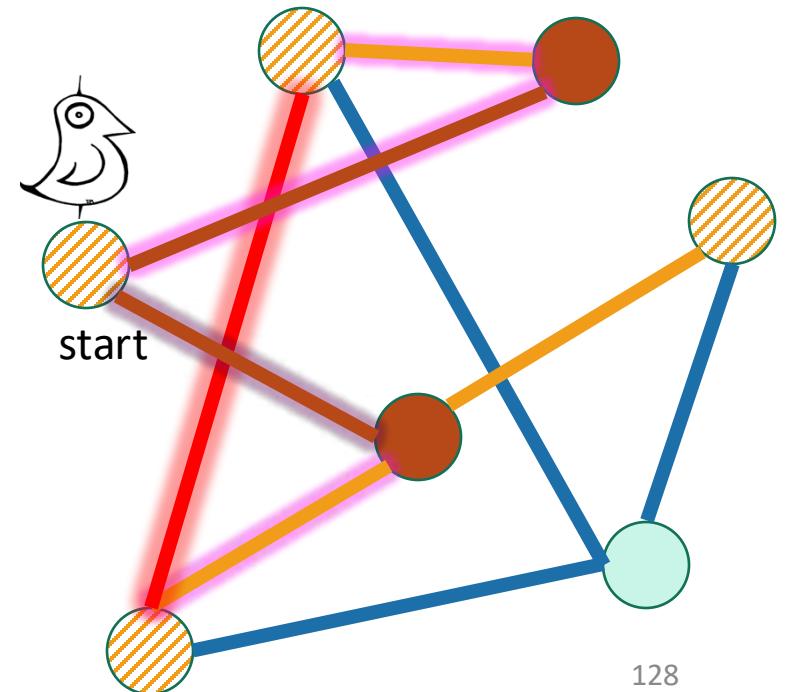
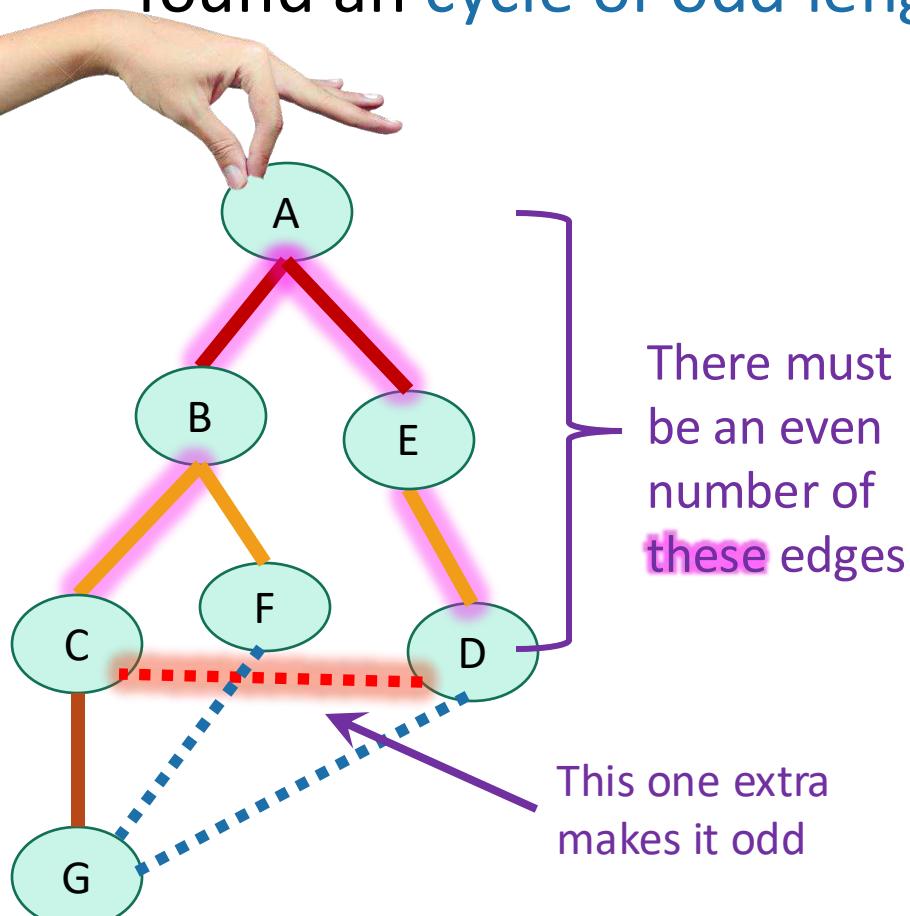
Plucky the  
pedantic penguin



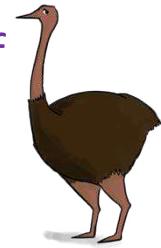
# Some proof required

Ollie the over-achieving ostrich

- If BFS colors two neighbors the same color, then it's found an **cycle of odd length** in the graph.



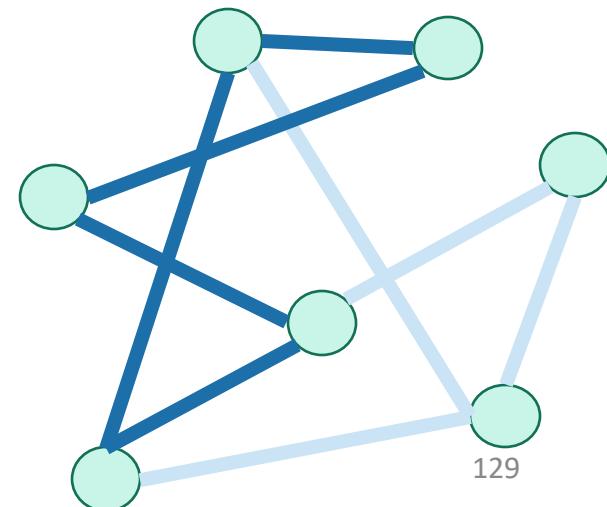
## Make this proof sketch formal!



# Some proof required

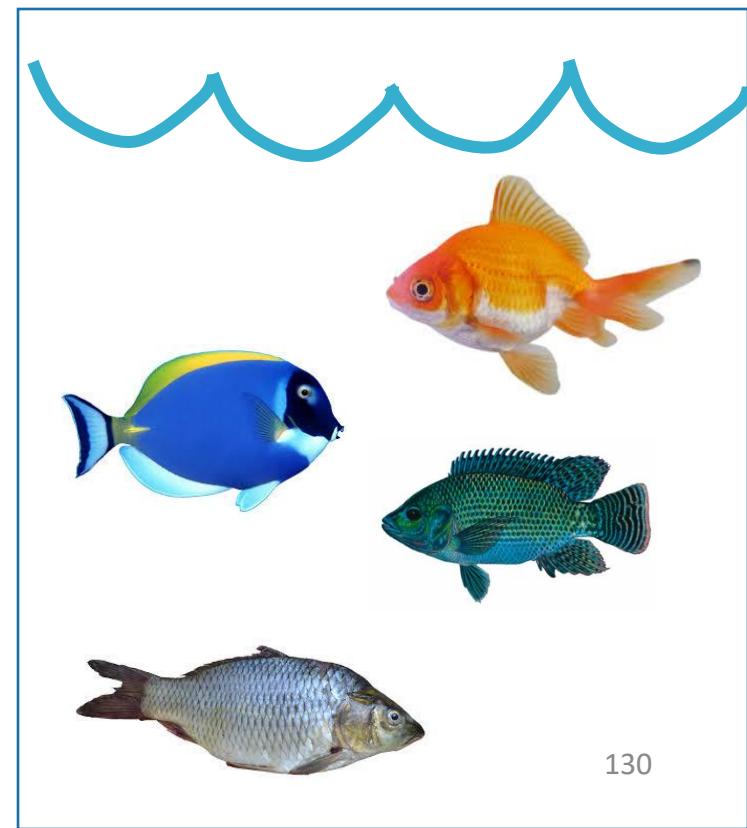
# Ollie the over-achieving ostrich

- If BFS colors two neighbors the same color, then it's found an **cycle of odd length** in the graph.
  - But you can **never** color an odd cycle with two colors so that no two neighbors have the same color.
    - [Fun exercise!]
  - So you can't legitimately color the whole graph either.
  - **Thus it's not bipartite.**



# What have we learned?

BFS can be used to detect bipartite-ness in time  $O(n + m)$ .



# Outline

- Part 0: Graphs and terminology
- Part 1: Depth-first search
  - Application: topological sorting
  - Application: in-order traversal of BSTs
- Part 2: Breadth-first search
  - Application: shortest paths
  - Application (if time): is a graph bipartite?



Recap

# Recap

- Depth-first search
  - Useful for topological sorting
  - Also in-order traversals of BSTs
- Breadth-first search
  - Useful for finding shortest paths
  - Also for testing bipartiteness
- Both DFS, BFS:
  - Useful for exploring graphs, finding connected components, etc

# Still open (next few classes)

- We can now find components in undirected graphs...
  - What if we want to find strongly connected components in directed graphs?
- How can we find shortest paths in weighted graphs?
- What is Samuel L. Jackson's Erdos number?
  - (Or, what if I want everyone's everyone-else number?)

# Next Time

- Strongly Connected Components

## Before Next Time

- Pre-lecture exercise: Strongly Connected What-Now?