CS187 Lab 4-4: Sequence-to-sequence models

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```
[]: # Please do not change this cell because some hidden tests might depend on it.
     import os
     # Otter grader does not handle ! commands well, so we define and use our
     # own function to execute shell commands.
     def shell(commands, warn=True):
         """Executes the string `commands` as a sequence of shell commands.
            Prints the result to stdout and returns the exit status.
            Provides a printed warning on non-zero exit status unless `warn`
           flag is unset.
         file = os.popen(commands)
         print (file.read().rstrip('\n'))
         exit_status = file.close()
         if warn and exit_status != None:
             print(f"Completed with errors. Exit status: {exit_status}\n")
         return exit_status
     shell("""
     ls requirements.txt >/dev/null 2>&1
     if [ ! $? = 0 ]; then
     rm -rf .tmp
     git clone https://github.com/cs187-2021/lab4-4.git .tmp
     mv .tmp/tests ./
     mv .tmp/requirements.txt ./
     rm -rf .tmp
     fi
     pip install -q -r requirements.txt
```

```
[]: # Initialize Otter
import otter
grader = otter.Notebook()
```

In lab 4-2, you used a syntactic-semantic grammar for semantic parsing to convert natural language to meaning representations in SQL. In this lab, we consider an alternative approach, sequence-to-sequence models, which can solve this task by directly learning the mapping from a sequence of inputs to a sequence of outputs. Since sequence-to-sequence models make few assumptions about the data, they can be applied to a variety of tasks, including machine translation, document summarization, and speech recognition.

In this lab, you will implement a sequence-to-sequence model in its most basic form (as in this seminal paper), and apply it to the task of converting English number phrases to numbers, as exemplified in the table below.

Input	Output
seven thousand nine hundred and twenty nine	7929
eight hundred and forty two thousand two hundred and fifty nine	842259
five hundred and eight thousand two hundred and seventeen	508217

For this simple task, it is possible to write a rule-based program to do the conversion. However, here we take a learning-based approach and learn the mapping from demonstrations, with the benefit that the system we implement here can be applied to other sequence-to-sequence tasks as well (including the ATIS-to-SQL problem in project segment 4).

New bits of Pytorch used in this lab, and which you may find useful include:

- torch.transpose: Swaps two dimensions of a tensor.
- torch.reshape: Redistributes the elements of a tensor to form a tensor of a different shape, e.g., from 3 x 4 to 6 x 2.
- torch.nn.utils.rnn.pack_padded_sequence (imported as pack): Handles paddings. A more detailed explanation can be found here.

Preparation - Loading data

```
import copy
import csv
import math
import os
import torch
import torch.nn as nn

from datasets import load_dataset

from tokenizers import Tokenizer
from tokenizers.pre_tokenizers import WhitespaceSplit
from tokenizers.processors import TemplateProcessing
from tokenizers import normalizers
from tokenizers.models import WordLevel
from tokenizers.trainers import WordLevelTrainer
```

```
from tqdm import tqdm

from torch.nn.utils.rnn import pack_padded_sequence as pack
```

```
[]: # GPU check, make sure to use GPU where available
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
print (device)
```

```
[]: # Download data
     def download_if_needed(source, dest, filename):
         os.makedirs(dest, exist_ok=True) # ensure destination
         os.path.exists(f"./{dest}{filename}") or wget.download(source + filename,_
      out=dest)
     local_dir = "data/"
     remote_dir = "https://github.com/nlp-course/data/raw/master/Words2Num/"
     os.makedirs(local_dir, exist_ok=True)
     for filename in [
        "train.src",
         "train.tgt",
         "dev.src",
         "dev.tgt",
         "test.src",
         "test.tgt",
     ]:
         download_if_needed(remote_dir, local_dir, filename)
```

Next, we process the dataset by extracting the sequences and their corresponding labels and save it in CSV format.

Let's take a look at what each data file looks like.

```
[]: shell('head "data/train.csv"')
```

1 The dataset

Let's take a first look at a few lines of the dataset of English number phrases and their translations into digit-sequence form.

```
[]: with open(local_dir + "dev.csv") as f:
    for line, _ in zip(f, range(3)):
        src, tgt = line.split(',')
        print (f'{src.strip():70s} {tgt.strip():>12s}')
```

As before, we use HuggingFace's datasets to load data. We use two fields: SRC for processing the source side (the English number phrases) and TGT for processing the target side (the digit sequences).

```
[]: train_data = dataset['train']
val_data = dataset['val']
test_data = dataset['test']
```

```
[]: unk_token = '[UNK]'
     pad_token = '[PAD]'
     bos_token = '<bos>'
     eos_token = '<eos>'
     src_tokenizer = Tokenizer(WordLevel(unk_token=unk_token))
     src_tokenizer.pre_tokenizer = WhitespaceSplit()
     src_trainer = WordLevelTrainer(special_tokens=[pad_token, unk_token])
     src_tokenizer.train_from_iterator(train_data['src'], trainer=src_trainer)
     tgt_tokenizer = Tokenizer(WordLevel(unk_token=unk_token))
     tgt_tokenizer.pre_tokenizer = WhitespaceSplit()
     tgt_trainer = WordLevelTrainer(special_tokens=[pad_token, unk_token, bos_token, __
      ⇔eos_token])
     tgt_tokenizer.train_from_iterator(train_data['tgt'], trainer=tgt_trainer)
     tgt_tokenizer.post_processor = \
       TemplateProcessing(single=f"{bos_token} $A {eos_token}",
                          special_tokens=[(bos_token,
                                           tgt_tokenizer.token_to_id(bos_token)),
```

```
(eos_token,
   tgt_tokenizer.token_to_id(eos_token))])
```

Note that we prepended <bos> and appended <eos> to target sentences. The purpose for introducing them will become clear in later parts of this lab.

We use datasets.Dataset.map to convert text into word ids. As shown in lab 1-5, first we need to wrap tokenizer with the transformers.PreTrainedTokenizerFast class to be compatible with the datasets library.

```
[]: def encode(example):
    example['src_ids'] = hf_src_tokenizer(example['src']).input_ids
    example['tgt_ids'] = hf_tgt_tokenizer(example['tgt']).input_ids
    return example

train_data = train_data.map(encode)
val_data = val_data.map(encode)
test_data = test_data.map(encode)
```

```
[]: # Compute size of vocabularies
src_vocab = hf_src_tokenizer.get_vocab()
tgt_vocab = hf_tgt_tokenizer.get_vocab()

print(f"Size of src vocab: {len(src_vocab)}")
print(f"Size of tgt vocab: {len(tgt_vocab)}")
print(f"Index for src padding: {src_vocab[pad_token]}")
print(f"Index for tgt padding: {tgt_vocab[pad_token]}")
print(f"Index for start of sequence token: {tgt_vocab[bos_token]}")
print(f"Index for end of sequence token: {tgt_vocab[eos_token]}")
```

To load data in batched tensors, we use torch.utils.data.DataLoader for data splits, which enables us to iterate over the dataset under a given BATCH_SIZE. For the test set, we use a batch size of 1, to make the decoding implementation easier.

```
[]: BATCH_SIZE = 32  # batch size for training and validation

TEST_BATCH_SIZE = 1  # batch size for test; we use 1 to make implementation

easier

# Defines how to batch a list of examples together
```

```
def collate_fn(examples):
    batch = {}
    bsz = len(examples)
    src_ids, tgt_ids = [], []
    for example in examples:
        src_ids.append(example['src_ids'])
        tgt_ids.append(example['tgt_ids'])
    src_len = torch.LongTensor([len(word_ids) for word_ids in src_ids]).
 →to(device)
    src_max_length = max(src_len)
    tgt_max_length = max([len(word_ids) for word_ids in tgt_ids])
    src_batch = torch.zeros(bsz, src_max_length).long().

¬fill_(src_vocab[pad_token]).to(device)

    tgt_batch = torch.zeros(bsz, tgt_max_length).long().
 →fill_(tgt_vocab[pad_token]).to(device)
    for b in range(bsz):
        src_batch[b][:len(src_ids[b])] = torch.LongTensor(src_ids[b]).to(device)
        tgt_batch[b][:len(tgt_ids[b])] = torch.LongTensor(tgt_ids[b]).to(device)
    batch['src_lengths'] = src_len
    batch['src ids'] = src batch
    batch['tgt_ids'] = tgt_batch
    return batch
train_iter = torch.utils.data.DataLoader(train_data,
                                         batch_size=BATCH_SIZE,
                                         shuffle=True,
                                         collate_fn=collate_fn)
val_iter = torch.utils.data.DataLoader(val_data,
                                       batch_size=BATCH_SIZE,
                                       shuffle=False,
                                       collate_fn=collate_fn)
test_iter = torch.utils.data.DataLoader(test_data,
                                        batch_size=TEST_BATCH_SIZE,
                                        shuffle=False,
                                        collate fn=collate fn)
```

Let's take a look at a batch from these iterators.

```
[]: batch = next(iter(train_iter))
    src_ids = batch['src_ids']
    src_example = src_ids[2]
    print (f"Size of src batch: {src_ids.size()}")
    print (f"Third src sentence in batch: {src_example}")
    print (f"Length of the third src sentence in batch: {len(src_example)}")
```

```
print (f"Converted back to string: {hf_src_tokenizer.decode(src_example)}")

tgt_ids = batch['tgt_ids']

tgt_example = tgt_ids[2]

print (f"Size of tgt batch: {tgt_ids.size()}")

print (f"Third tgt sentence in batch: {tgt_example}")

print (f"Converted back to string: {hf_tgt_tokenizer.decode(tgt_example)}")
```

2 Neural Encoder-Decoder Models

Sequence-to-sequence models are sometimes called neural encoder-decoder models, as they consist of an encoder, which maps a sequence of source tokens into some vector representations, and a decoder, which generates a sequence of output words from those encoded vectors.

Formally, given a sequence of source tokens $\mathbf{x} = x_1, \dots, x_S$, the goal is to map it to a sequence of target tokens $\mathbf{y} = y_1, \dots, y_T$.

In practice, we prepend a special beginning-of-sequence symbol $y_0 = \langle bos \rangle$ to the target sequence. Further, in order to provide a way of knowing when to stop generating \mathbf{y} , we append a special end-of-sequence symbol $y_{T+1} = \langle eos \rangle$ to the target sequence, such that when it is produced by the model, the generation process stops.

The generation process is structured as a generative model:

$$\Pr(y_0,\dots,y_{T+1}\mid x_1,\dots,x_S) = \prod_{t=1}^{T+1} \Pr(y_t\mid y_{< t},x_1,\dots,x_S),$$

where $y_{< t}$ denotes the tokens before y_t (that is, y_0, \dots, y_{t-1}).

We use a recurrent neural network with parameters θ to parameterize $\Pr(y_t \mid y_{\leq t}, x_1, \dots, x_S)$:

$$\Pr(y_t \mid y_{< t}, x_1, \dots, x_S) \approx \Pr_{\theta}(y_t \mid y_{< t}, x_1, \dots, x_S),$$

or equivalently,

$$\mathrm{Pr}_{\theta}(y_1, \dots, y_T \mid x_1, \dots, x_S) = \prod_{t=1}^{T+1} \mathrm{Pr}_{\theta}(y_t \mid y_{< t}, x_1, \dots, x_S)$$

In neural encoder-decoder models, we first use an encoder to encode \mathbf{x} into some vectors (either of fixed length as we'll see in this lab, or of varying length as we'll see in the next lab). Based on the encoded vectors, we use a decoder to generate \mathbf{y} :

$$\mathrm{Pr}_{\theta}(y_t \mid y_{< t}, x_1, \dots, x_S) = \mathrm{decode}(\mathrm{encode}(x_1, \dots, x_S), y_{< t})$$

2.0.1 RNN Encoder-Decoders

We can use any recurrent neural networks such as LSTMs as encoders and decoders. In this lab, we will use a bidirectional LSTM as the encoder, and a unidirectional LSTM as the decoder, as shown in the illustration below.

In the above illustration, S=4, T=3, and there are two encoder/decoder layers. Since we are using a bidirectional encoder, for each layer there are two final states, one for the cell running from left to right (such as $h_{0,4}$), and the other for the cell running from right to left (such as $h'_{0,4}$). We concatenate these two states and use the result to initialize the corresponding layer of the decoder. (In the example, we concatenate $h_{0,4}$ and $h'_{0,4}$ to initialize layer 0, and we concatenate $h_{1,4}$ and $h'_{1,4}$ to initialize layer 1.) Therefore, to make the sizes match, we set the hidden state size of the encoder to be half of that of the decoder.

Note that in PyTorch's LSTM implementation, the final hidden state is represented as a tuple (h, c) (documentation here), so we want to apply the same operations to c to initialize the decoder.

You'll implement forward_encoder and forward_decoder in the code below. The forward_encoder function will be reminiscent of a sequence model from labs 2-* and project segment 2. It operates on a batch of source examples and proceeds as follows:

- 1. Map the input words to some word embeddings. You'll notice that the embedding size is an argument to the model.
- 2. Optionally "pack" the sequences to save some computation using torch.nn.utils.rnn.pack_padded_sequence, imported above as pack.
- 3. Run the encoder RNN (a bidirectional LSTM) over the batch, generating a batch of output states.
- 4. Reshape the final state information (which will have h and c components each of half the size needed to initialize the decoder) so that it is appropriate to initialize the decoder with.

The forward_decoder function takes the reshaped encoder final state information and the ground truth target sequences and returns logits (unnormalized log probs) for each target word. (These are ready to be converted to probability distributions via a softmax.)

The steps in decoding are:

- 1. Map the target words to word embeddings.
- 2. Run the decoder RNN (a unidirectional LSTM) over the batch, initializing the hidden units from the encoder final states, generating a batch of output states.
- 3. Map the RNN outputs to vectors of vocabulary size (so that they could be softmaxed into a distribution over the vocabulary).

The components that you'll be plugging together to do all this are already established in the __init__ method.

The major exception is the reshaping of the encoder output h and c to form the decoder input h and c. This is the trickiest part. As usual, your best strategy is to keep careful track of the shapes of each input and output of a layer or operation. We recommend that you try out just the reshaping code on small sample data to test it out before running any encodings or decodings.

Hint #1: We've provided an auxiliary notebook, called lab4-4-reshaping.ipynb, that discusses the reshaping issue in some detail. You'll want to look it over.

Hint #2: The total number of for loops in our solution code for the parts you are to write is...zero.

Hint #3: According to the documentation of torch.nn.LSTM, its outputs are: outputs, (h, c). outputs contains all the intermediate states, which you don't need in this lab. You will need h and c, both of them have the shape: (num layers * num directions, batch size, hidden size).

```
[]: # TODO - finish implementing the `forward encoder` and `forward decoder` methods
     class EncoderDecoder(nn.Module):
         def __init__(self, hf_src_tokenizer, hf_tgt_tokenizer, embedding_size=64,_
      ⇔hidden_size=64, layers=3):
             .....
             Initializer. Creates network modules and loss function.
             Arguments:
                 hf_src_tokenizer: src field information
                 hf_tgt_tokenizer: tgt field information
                 embedding size: word embedding size
                 hidden_size: hidden layer size of both encoder and decoder
                 layers: number of layers of both encoder and decoder
             super(EncoderDecoder, self).__init__()
             self.hf_src_tokenizer = hf_src_tokenizer
             self.hf_tgt_tokenizer = hf_tgt_tokenizer
             # Keep the vocabulary sizes available
             self.V_src = len(hf_src_tokenizer)
             self.V_tgt = len(hf_tgt_tokenizer)
             # Get special word ids or tokens
             self.padding_id_src = self.hf_src_tokenizer.pad_token_id
             self.padding_id_tgt = self.hf_tgt_tokenizer.pad_token_id
             self.bos_id = self.hf_tgt_tokenizer.bos_token_id
             self.eos_id = self.hf_tgt_tokenizer.eos_token_id
             # Keep hyper-parameters available
             self.embedding_size = embedding_size
             self.hidden_size = hidden_size
             self.layers = layers
             # Create essential modules
             self.word_embeddings_src = nn.Embedding(self.V_src, embedding_size)
             self.word_embeddings_tgt = nn.Embedding(self.V_tgt, embedding_size)
             # RNN cells
             self.encoder_rnn = nn.LSTM(
                 input_size=embedding_size,
```

```
hidden_size=hidden_size // 2, # to match decoder hidden size
           batch_first=True,
           num_layers=layers,
           bidirectional=True,
                                           # bidirectional encoder
      self.decoder_rnn = nn.LSTM(
           input_size=embedding_size,
           hidden_size=hidden_size,
           batch first=True,
           num_layers=layers,
           bidirectional=False, # unidirectional decoder
      )
       # Final projection layer
      self.hidden2output = nn.Linear(hidden_size, self.V_tgt)
       # Create loss function
      self.loss_function = nn.CrossEntropyLoss(
           reduction="sum", ignore_index=self.padding_id_tgt
  def forward_encoder(self, src, src_lengths):
      Encodes source words `src`.
      Arguments:
           src: src batch of size (batch_size, max_src_len)
           src_lengths: src lengths of size (batch_size)
      Returns:
           a tuple (h, c) where h/c is of size (layers, bsz, hidden_size)
       # TODO - implement this function
       # Optional: use `pack` to deal with paddings (https://discuss.pytorch.
\hookrightarrow org/t/
\hookrightarrow simple-working-example-how-to-use-packing-for-variable-length-sequence-inputs-for-rnn/
⇒2120)
       # Note that the batch size is the first dimension, and the sequences_
⇒are not sorted.
  def forward_decoder(self, encoder_final_state, tgt_in):
      Decodes based on encoder final state and ground truth target words.
      Arguments:
           encoder_final_state: a tuple (h, c) where h/c is of size
                                 (bsz, layers, hidden_size)
           tgt_in: a tensor of size (tgt_len, bsz)
```

```
Returns:
           Logits of size (tqt len, bsz, V tqt) (before the softmax operation)
       # TODO - implement this function
  def forward(self, src, src_lengths, tgt_in):
       Performs forward computation, returns logits.
       Arguments:
           src: src batch of size (batch_size, max_src_len)
           src_lengths: src lengths of size (batch_size)
           tgt_in: a tensor of size (batch_size, tgt_len)
       # Forward encoder
       encoder_final_state = self.forward_encoder(src, src_lengths) # tuple_
\hookrightarrow (h, c)
       # Forward decoder
       logits = self.forward_decoder(encoder_final_state, tgt_in)
                                                                        \# bsz_{,||}
\hookrightarrow tgt_len, V_tgt
       return logits
  def forward_decoder_incrementally(self, decoder_state, tgt_in_token):
       Forward the decoder at `decoder state` for a single step with token |
→ 'tqt in token'.
       This function will only be used in the beam search section.
       Arguments:
           decoder state: a tuple (h, c) where h/c is of size (layers, 1, \square
\hookrightarrow hidden_size)
           tgt_in_token: a tensor of size (1), a single token
       Returns:
           `logits`: Log probabilities for `tgt_in_token` of size (V_tgt)
           'decoder state': updated decoder state, ready for next incremental,
\hookrightarrow update
       11 11 11
       bsz = decoder_state[0].size(1)
       assert bsz == 1, "forward_decoder_incrementally only supports batch_
⇔size 1!"
       # Compute word embeddings
       tgt_embeddings = self.word_embeddings_tgt(
           tgt in token.view(1, 1)
       ) # bsz, tgt_len, hidden
       # Forward decoder RNN and return all hidden states
```

```
decoder_outs, decoder_state = self.decoder_rnn(tgt_embeddings,_
→decoder state)
       # Project to get logits
       logits = self.hidden2output(decoder_outs) # bsz, tgt_len, V_tgt
       # Get log probabilities
      logits = torch.log softmax(logits, -1)
       return logits.view(-1), decoder_state
  def evaluate_ppl(self, iterator):
       """Returns the model's perplexity on a given dataset `iterator`."""
       # Switch to eval mode
      self.eval()
      total loss = 0
      total_words = 0
       for batch in iterator:
           # Input and target
           src = batch['src ids']
                                                # bsz, max src len
           src_lengths = batch['src_lengths'] # bsz
           tgt_in = batch['tgt_ids'][:, :-1].contiguous() # remove <eos> for_
\rightarrow decoder input (y_0=<bos>, y_1, y_2)
           tgt_out = batch['tgt_ids'][:, 1:].contiguous() # remove <bos> as_
⇔decoder output
                   (y_1, y_2, y_3 = \langle eos \rangle)
           # Forward to get logits
           logits = self.forward(src, src_lengths, tgt_in) # bsz, tgt_len,__
\hookrightarrow V_tgt
           # Compute cross entropy loss
           loss = self.loss_function(logits.view(-1, self.V_tgt), tgt_out.
\rightarrowview(-1))
           total_loss += loss.item()
           total_words += tgt_out.ne(self.padding_id_tgt).float().sum().item()
       return math.exp(total_loss / total_words)
  def train_all(self, train_iter, val_iter, epochs=10, learning_rate=0.001):
       """Train the model."""
       # Switch the module to training mode
      self.train()
       # Use Adam to optimize the parameters
       optim = torch.optim.Adam(self.parameters(), lr=learning_rate)
      best_validation_ppl = float("inf")
      best_model = None
       # Run the optimization for multiple epochs
       for epoch in range(epochs):
           total_words = 0
           total loss = 0.0
           for batch in tqdm(train_iter):
               # Zero the parameter gradients
               self.zero_grad()
```

```
tgt = batch['tgt_ids']
                                                            # bsz, max_tqt_len
                      src = batch['src_ids']
                                                            # bsz, max_src_len
                      src_lengths = batch['src_lengths'] # bsz
                      tgt_in = tgt[:, :-1]
                                                             # Remove <eos> for decoder_
      \rightarrow input (y_0 = < bos>, y_1, y_2)
                      tgt_out = tgt[:, 1:]
                                                             # Remove <bos> as decoder
      \rightarrow output (y_1, y_2, y_3 = \langle eos \rangle)
                      batch_size = src.size(0)
                      # Run forward pass and compute loss along the way.
                      logits = self.forward(src, src_lengths, tgt_in) # bsz, tgt_len,__
      \hookrightarrow V_tgt
                      loss = self.loss_function(logits.reshape(-1, self.V_tgt),__
      →tgt_out.reshape(-1))
                      # Training stats
                      num_tgt_words = tgt_out.ne(self.padding_id_tgt).float().sum().
      →item()
                      total_words += num_tgt_words
                      total_loss += loss.item()
                      # Perform backpropagation
                      loss.div(batch_size).backward()
                      optim.step()
                  # Evaluate and track improvements on the validation dataset
                  validation_ppl = self.evaluate_ppl(val_iter)
                  self.train()
                  if validation_ppl < best_validation_ppl:</pre>
                      best_validation_ppl = validation_ppl
                      self.best_model = copy.deepcopy(self.state_dict())
                  epoch_loss = total_loss / total_words
                  print(f"Epoch: {epoch} Training Perplexity: {math.exp(epoch_loss):.
      94f} "
                        f"Validation Perplexity: {validation_ppl:.4f}")
[]: EPOCHS = 2 # epochs, we highly recommend starting with a smaller number like 1
     LEARNING_RATE = 2e-3 # learning rate
     # Instantiate and train classifier
     model = EncoderDecoder(
         hf_src_tokenizer,
         hf_tgt_tokenizer,
         embedding_size=64,
         hidden_size=64,
         layers=3,
     ).to(device)
```

Input and target

Since the task we consider here is very simple, we should expect a perplexity very close to 1.

```
[]: # Evaluate model performance
print (f'Test perplexity: {model.evaluate_ppl(test_iter):.3f}')
```

```
[]: grader.check("encoder_decoder_ppl")
```

3 Beam search decoding

Now that we have a well-trained model, we need to consider how to use it to do the actual conversion. At decoding time, given a source sequence x_1, \dots, x_S , we want to find the target sequence $y_1^*, \dots, y_T^*, y_{T+1}^*$ (recall that $y_{T+1} = \langle \cos \rangle$) such that the conditional likelihood is maximized:

$$\begin{split} y_1^*, \dots, y_T^*, y_{T+1}^* &= \underset{y_1, \dots, y_T, y_{T+1}}{\operatorname{argmax}} \operatorname{Pr}_{\theta}(y_1, \dots, y_T \mid x_1, \dots, x_S) \\ &= \underset{y_1, \dots, y_T, y_{T+1}}{\operatorname{argmax}} \prod_{t=1}^{T+1} \operatorname{Pr}_{\theta}(y_t \mid y_{< t}, x_1, \dots, x_S) \end{split}$$

In previous labs and project segments, we used $greedy\ decoding$, i.e., taking $\hat{y}_1 = \underset{y_1}{\operatorname{argmaxPr}} \operatorname{Pr}_{\theta}(y_1 \mid y_0, x_1, \dots, x_S), \quad \hat{y}_2 = \underset{y_2}{\operatorname{argmaxPr}} \operatorname{Pr}_{\theta}(y_2 \mid y_0, \hat{y}_1, x_1, \dots, x_S), \quad \dots, \quad \hat{y}_{T+1} = \underset{y_{T+1}}{\operatorname{argmaxPr}} \operatorname{Pr}_{\theta}(y_{T+1} \mid y_0, \hat{y}_1, \dots, \hat{y}_T, x_1, \dots, x_S), \quad \text{until} \ \hat{y}_{T+1} = \langle \cos \rangle.$

Question: Does greedy decoding guarantee finding the optimal sequence (the sequence with the highest conditional likelihood)? Why or why not?

Type your answer here, replacing this text.

3.1 Beam search decoding

Beam search decoding is the most commonly used decoding method in sequence-to-sequence approaches. Like greedy decoding, it uses a left-to-right search process. But instead of only keeping the single argmax at each position, beam search maintains the K best partial hypotheses $H_t = \{(y_1^{(k)}, \dots, y_t^{(k)}) : k \in \{1, \dots, K\}\}$ at every step t. To proceed to t+1, we compute the scores of sequences $y_1^{(k)}, \dots, y_t^{(k)}, y_{t+1}$ for every possible extension $y_{t+1} \in \mathcal{V}$ and every possible prefix $(y_1^{(k)}, \dots, y_t^{(k)}) \in H_t$, where \mathcal{V} is the vocabulary. Among these $K \times |\mathcal{V}|$ sequences, we only keep the top K sequences with the best partial scores, and that becomes $H_{t+1} = \{(y_1^{(k)}, \dots, y_{t+1}^{(k)}) : k \in \{1, \dots, K\}\}$. To start at t=1, $H_1 = \{(y) : y \in K\text{-argmax}_{y_1 \in \mathcal{V}} \log P(y_1|y_0 = bos)\}$. Here K is called the beam size.

To summarize,

$$\begin{split} H_1 &= \{(y): y \in \text{K-argmax} \log P(y_1|y_0 = bos)\} \\ H_{t+1} &= \underset{\{(y_1, y_2, \dots, y_{t+1}) \in \mathcal{V}^{t+1}: (y_1, \dots, y_t) \in H_t\}}{\text{K-argmax}} \log P(y_1, \dots, y_{t+1}|x) \end{split}$$

until we reach a pre-specified maximum search length, and we collect the completed hypotheses along the way. (By completed we mean ending with <eos>.) The finished hypothesis with the best score will then be returned.

Question: Is beam search better than greedy search when K = 1? Is it better when K > 1? Why? How big a K value do we need to get a guarantee that we can find the globally best sequence (assuming a maximum sequence length T and vocabulary size $|\mathcal{V}|$).

Type your answer here, replacing this text.

Under the probabilistic formulation of sequence-to-sequence models, the partial scores are decomposable over time steps: $\log \Pr_{\theta}(y_1, \dots, y_T \mid x) = \sum_{t=1}^T \log \Pr_{\theta}(y_t \mid y_{< t}, x)$. Therefore, we can save computation in the above process by maintaining the partial sums $\sum_{t'=1}^t \log \Pr_{\theta}(y_{t'}^{(k)} \mid y_{< t'}^{(k)}, x)$, such that we only need to compute $\log \Pr_{\theta}(y_{t+1} \mid y_{< t+1}^{(k)})$ when we want to go from t to t+1.

Here is pseudo-code for the beam search algorithm to decode a single example x of maximum length max_T using a beam size of K.

```
def beam_search(x, K, max_T):
2.
        finished = []
                              # for storing completed hypotheses
        # Initialize the beam
        beams = [Beam(hyp=(bos), score=0)] # initial hypothesis: bos, initial score: 0
3.
4.
        for t in [1..max_T] # main body of search over time steps
5.
            hypotheses = []
            # Expand each beam by all possible tokens y_{t+1}
6.
            for beam in beams:
7.
                y_{1:t}, score = beam.hyp, beam.score
8.
                for y_{t+1} in V:
                    y_{1:t+1} = y_{1:t} + [y_{t+1}]
9.
                    new_score = score + log P(y_{t+1} | y_{1:t}, x)
10.
                    hypotheses.append(Beam(hyp=y_{1:t+1}, score=new_score))
11.
            # Find K best next beams
            beams = sorted(hypotheses, key=lambda beam: -beam.score)[:K]
12.
            # Set aside finished beams (those that end in <eos>)
            for beam in beams:
13.
14.
                y_{t+1} = beam.hyp[-1]
15.
                if y_{t+1} == eos:
                    finished.append(beam)
16.
17.
                    beams.remove(beam)
```

```
# Break the loop if everything is finished

18.     if len(beams) == 0:

19.          break

20.     return sorted(finished, key=lambda beam: -beam.score)[0] # return the best finished has been the second of the second of
```

beams.

Implement function beam_search in the below code. Note that there are some differences from the pseudo-code: first, we maintained a decoder_state in addition to $y_{1:t}$ and score such that we can compute $P(y_{t+1} \mid y_{< t+1}, x)$ efficiently; second, instead of creating a list of actual hypotheses as in lines 8-11, we use tensors to get pointers to the beam id and y_{t+1} that are among the best K next

```
[ ]: MAX T = 15
                  # max target length
    class Beam():
      ⇔state."""
      def __init__(self, decoder_state, tokens, score):
        self.decoder_state = decoder_state
        self.tokens = tokens
        self.score = score
    class BeamSearcher():
      """Main class for beam search."""
      def __init__(self, model):
        self.model = model
        self.bos_id = model.bos_id
        self.eos_id = model.eos_id
        self.V = model.V_tgt
      def beam_search(self, src, src_lengths, K, max_T=MAX_T):
        """Performs beam search decoding.
        Arguments:
            src: src batch of size (1, max_src_len)
            src_lengths: src lengths of size (1)
            K: beam size
            max_T: max possible target length considered
        Returns:
            a list of token ids
        finished = []
        # Initialize the beam
        self.model.eval()
        #TODO - fill in encoder_final_state and init_beam below
        encoder_final_state = ...
        init_beam = ...
```

```
beams = [init_beam]
  for t in range(max_T): # main body of search over time steps
       # Expand each beam by all possible tokens y_{t+1}
      all_total_scores = []
      for beam in beams:
           y_1_to_t, score, decoder_state = beam.tokens, beam.score, beam.
→decoder state
           y_t = y_1_{to_t[-1]}
           #TODO - finish the code below
           # Hint: you might want to use `model.forward_decoder_incrementally`
           decoder_state = ...
           total_scores = ...
           all_total_scores.append(total_scores)
           beam.decoder_state = decoder_state # update decoder state in the_
→beam
      all_total_scores = torch.stack(all_total_scores) # (K, V) when t>0, (1, )
\hookrightarrow V) when t=0
       # Find K best next beams
       # The below code has the same functionality as line 6-12, but is more
      all_scores_flattened = all_total_scores.view(-1) # K*V when t>0, 1*V_{\sqcup}
\rightarrowwhen t=0
      topk_scores, topk_ids = all_scores_flattened.topk(K, 0)
      beam_ids = topk_ids.div(self.V, rounding_mode='floor')
      next_tokens = topk_ids - beam_ids * self.V
      new_beams = []
      for k in range(K):
           beam_id = beam_ids[k]
                                        # which beam it comes from
           y_t_plus_1 = next_tokens[k] # which y_{t+1}
           score = topk_scores[k]
           beam = beams[beam_id]
           decoder_state = beam.decoder_state
           y_1_to_t = beam.tokens
           #TODO
          new_beam = ...
           new_beams.append(new_beam)
      beams = new_beams
       # Set aside completed beams
       # TODO - move completed beams to `finished` (and remove them from
→ `beams`)
```

```
# Break the loop if everything is completed
if len(beams) == 0:
    break

# Return the best hypothesis
if len(finished) > 0:
    finished = sorted(finished, key=lambda beam: -beam.score)
    return [token.item() for token in finished[0].tokens]
else: # when nothing is finished, return an unfinished hypothesis
    return [token.item() for token in beams[0].tokens]
```

```
[]: grader.check("beam_search")
```

Now we can use beam search decoding to predict the outputs for the test set inputs using the trained model.

```
[]: DEBUG_FIRST = 10  # set to 0 to disable printing predictions
     K = 5
                      # beam size 5
     correct = 0
     total = 0
     # create beam searcher
     beam_searcher = BeamSearcher(model)
     for index, batch in enumerate(test_iter, start=1):
       # Input and output
       src = batch['src ids']
      src_lengths = batch['src_lengths']
       # Predict
      prediction = beam_searcher.beam_search(src, src_lengths, K)
       # Convert to string
      prediction = hf_tgt_tokenizer.decode(prediction,
                                            skip_special_tokens=True)
       ground_truth = hf_tgt_tokenizer.decode(batch['tgt_ids'][0],
                                              skip_special_tokens=True)
       # Print out the first few examples
       if DEBUG FIRST >= index :
         src = hf_src_tokenizer.decode(src[0], skip_special_tokens=True)
         print (f'Source:
                               \{index\}. \{src\}\n'
                f'Prediction: {prediction}\n'
                f'Ground truth: {ground_truth}\n')
       if ground_truth == prediction:
         correct += 1
       total += 1
```

```
print (f'Accuracy: {correct/total:.2f}')
```

You might have noticed that using a larger K might lead to very similar performance as using K=1 (greedy decoding). This is largely due to the fact that there are no dependencies among target tokens in our dataset (e.g., knowing that y_1 is 1 does not affect our prediction on y_2 conditioned on the source). In real world applications, people usually find using a fixed value of K>1 (such as K=5) performs better than greedy decoding.

Question: Can we use beam search decoding to decode an HMM? For state space Q, sequence length T, what is the complexity of beam search with beam size K? What is the complexity of Viterbi decoding? What are their pros and cons?

Type your answer here, replacing this text.

4 Lab debrief

Question: We're interested in any thoughts you have about this lab so that we can improve this lab for later years, and to inform later labs for this year. Please list any issues that arose or comments you have to improve the lab. Useful things to comment on might include the following, but you're not restricted to these:

- Was the lab too long or too short?
- Were the readings appropriate for the lab?
- Was it clear (at least after you completed the lab) what the points of the exercises were?
- Are there additions or changes you think would make the lab better?

Type your answer here, replacing this text.

End of Lab 4-4

To double-check your work, the cell below will rerun all of the autograder tests.

[]: grader.check_all()