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Logistic Regression (LR)

LR for binary classification.

$$\text{I/P: } \vec{x} = \vec{x} \in \mathbb{R}^d$$

$$\text{O/P: } y \in \{0, 1\}$$

We are interested in $p(y=1 | X=x)$

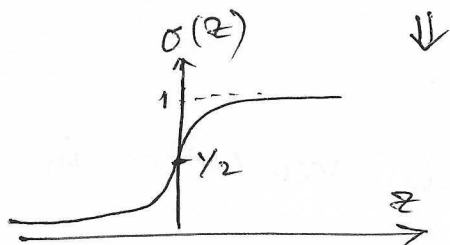
Model assumption: $y | x=x \sim \text{Bernoulli}(\theta_x)$, $\theta_x \in [0, 1]$

Can we regress from $\vec{x} \rightarrow \theta_x$? (i.e., modelling directly with a linear function)

$$\text{ie. } \hat{\theta} = \vec{w}^T \vec{x}$$

↓ problem

θ has to be true & less than 1. $\vec{w}^T \vec{x}$ will produce some value, & we want something betw. 0 & 1.



$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

$$y | x \sim \text{Bernoulli}(\sigma(\vec{w}^T \vec{x}))$$

← Logistic regression.

So the posterior probability is,

$$p(y=1 | X=x) = \frac{1}{1 + e^{-\vec{w}^T \vec{x}}}$$

← measure w directly from data.

Some facts

$$p(y=1 | X=x) = \frac{1}{1 + e^{-\vec{w}^T \vec{x}}}$$

← Complementary

$$p(y=0 | X=x) = 1 - \frac{1}{1 + e^{-\vec{w}^T \vec{x}}} = \frac{1}{1 + e^{\vec{w}^T \vec{x}}}$$

$$\hat{y}_{\text{MAP}} = \arg \max_{y \in \{0, 1\}} p(y=y | X=x)$$

So we're literally choosing betw. two numbers:

$$\left. \begin{matrix} p(y=1 | x) \\ p(y=0 | x) \end{matrix} \right\} \text{ so } \arg \max_y p(y=y | x) = 1 \text{ is same as?}$$

$$p(y=1 | x) \geq p(y=0 | x)$$

$$\text{or, } \frac{p(y=1 | x)}{p(y=0 | x)} \geq 1 \quad \left. \begin{matrix} \text{if yes then } \hat{y}=1 \\ \text{else } \hat{y}=0 \end{matrix} \right\}$$

$$\text{Also, } \log \left[\frac{P(Y=1|X=x)}{P(Y=0|X=x)} \right] \geq 0$$

$$\Rightarrow \log \left[\frac{(1/e^{-w^T x})}{e^{-w^T x}/1 + e^{-w^T x}} \right] \geq 0 \Rightarrow \log(e^{w^T x}) \geq 0$$

$$\Rightarrow \boxed{w^T x \geq 0} \leftarrow \text{linear classifier.}$$

$$\text{So if } w^T x \geq 0 \Rightarrow \hat{y} = 1$$

$$w^T x < 0 \Rightarrow \hat{y} = 0$$

Hence, $w^T x \equiv \text{score of class 1}$

$$\frac{1}{1 + e^{-w^T x}} \equiv \text{probability of class 1.}$$

Estimation of \vec{w}

MLE will be similar to the way we've seen before in coin toss / Bernoulli parameters:

Coin toss

$$Y \in \{0, 1\}$$

$$\text{Dataset: } D = \{y_1, \dots, y_N\}$$

$$Y \sim \text{Ber}(\theta)$$

$$P(Y=1) = \theta$$

$$P(Y=0) = 1 - \theta$$

Likelihood for one sample

$$L(\theta) = \theta^y (1-\theta)^{1-y}$$

Likelihood of dataset:

$$L(\theta) = \prod_{i=1}^N \theta^{y_i} (1-\theta)^{1-y_i}$$

$$\downarrow$$

$$\theta^{\sum y_i} (1-\theta)^{N - \sum y_i}$$

LR

$$Y \in \{0, 1\}$$

$$\text{Dataset: } D = \{(x_1, y_1), \dots, (x_N, y_N)\}$$

$$Y|X=x \sim \text{Ber}(\underbrace{\sigma(w^T x)}_{\theta_x})$$

$$P(Y=1|X=x) = \theta_x$$

$$P(Y=0|X=x) = 1 - \theta_x$$

Likelihood of one sample:

$$L(w) = \theta_x^y (1-\theta_x)^{1-y}$$

Likelihood of dataset:

$$L(w) = \prod_{i=1}^N \theta_{x_i}^{y_i} (1-\theta_{x_i})^{1-y_i}$$

$$= \prod_{i=1}^N [\sigma(w^T x_i)]^{y_i} [1 - \sigma(w^T x_i)]^{1-y_i}$$

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So the log likelihood for LR is,

$$\begin{aligned}
 LL(\vec{w}) &= \sum_{i=1}^N [y_i \log \sigma(\vec{w}^T \vec{x}_i) + (1-y_i) \log (1-\sigma(\vec{w}^T \vec{x}_i))] \\
 &= \sum_{i=1}^N \left[y_i \log \left(\frac{1}{1+e^{-\vec{w}^T \vec{x}_i}} \right) + (1-y_i) \log \left(\frac{1}{1+e^{\vec{w}^T \vec{x}_i}} \right) \right] \\
 &= \sum_{i=1}^N \left[y_i \log \left(\frac{e^{\vec{w}^T \vec{x}_i}}{1+e^{\vec{w}^T \vec{x}_i}} \right) + (1-y_i) \log \left(\frac{1}{1+e^{\vec{w}^T \vec{x}_i}} \right) \right] \\
 &= \sum_{i=1}^N \left[y_i \log (e^{\vec{w}^T \vec{x}_i}) - y_i \log (1+e^{\vec{w}^T \vec{x}_i}) + \log(1) - \log(1+e^{\vec{w}^T \vec{x}_i}) \right. \\
 &\quad \left. - y_i \log(1) + y_i \log(1+e^{\vec{w}^T \vec{x}_i}) \right] \\
 &= \sum_{i=1}^N [y_i \log (e^{\vec{w}^T \vec{x}_i}) - \log(1+e^{\vec{w}^T \vec{x}_i})] \\
 &= \sum_{i=1}^N [\underbrace{y_i \vec{w}^T \vec{x}_i}_{\text{linear in } \vec{w}} - \underbrace{\log(1+e^{\vec{w}^T \vec{x}_i})}_{\text{not linear in } \vec{w}}] \rightarrow \text{no closed form solution}
 \end{aligned}$$

Vanilla Gradient Descent

Initialize $w^{(0)}$ & then use the update rule:

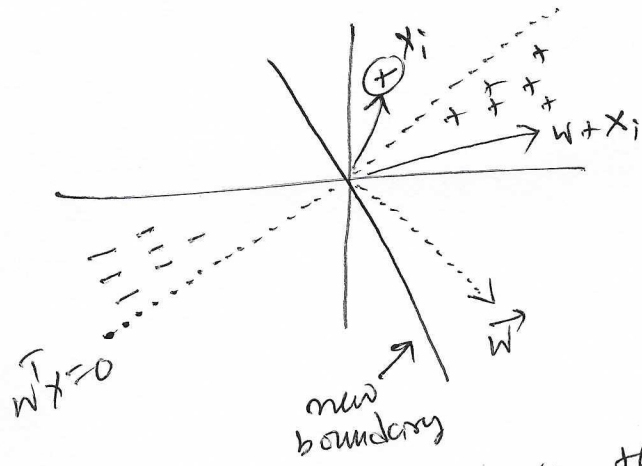
$$w^{t+1} = w^t + \eta \underbrace{\frac{\partial LL(w)}{\partial w}}_{\substack{\text{step size /} \\ \text{learning rate}}} \underbrace{\text{Gradient (direction of} \\ \text{steepest increase)}}_{\text{steepness}}$$

← Actually this is gradient ascent

$$w^{t+1} = w^t + \eta \sum_{i=1}^N \left[y_i \vec{x}_i^T - \underbrace{\frac{1}{1+e^{\vec{w}^T \vec{x}_i}} e^{\vec{w}^T \vec{x}_i}}_{p(y_i=1 | \vec{x}_i, w)} \cdot \vec{x}_i^T \right]$$

$$= w^t + \eta \sum_{i=1}^N \left[\underbrace{y_i}_{\substack{\text{truth} \\ 0, 1, 2}} - \underbrace{p(y_i=1 | \vec{x}_i, w)}_{\substack{\text{what our} \\ \text{model} \\ \text{believes}}} \right] \underbrace{\vec{x}_i^T}_{\substack{\text{feature vector /} \\ \text{data}}}$$

error



Geometric interpretation of the above equation

Batch gradient descent \Rightarrow moves the entire dataset towards the direction of the gradient

Stochastic " " \Rightarrow perform on sampled points.



GD may or may not work.

Local vs global minima



GD works always.

MAP estimation of \vec{w}

Model: $y|x \sim \text{Ber}(\sigma(\vec{w}^T x))$
 $w_i \sim \mathcal{N}(0, \tau^2)$ (i.i.d.)

$$\hat{w}_{\text{MAP}} = \arg\max_w \log P(w|D) = \arg\max_w (\log P(D|w) + \log P(w))$$

Now as usual, we'll take derivative w.r.t. w & set to 0. For the first term, we have already done it - for the second term!

$$P(\vec{w}) = \prod_{j=1}^d \frac{1}{\sqrt{2\pi}\tau^2} e^{-\frac{w_j^2}{2\tau^2}} \quad (\text{i.i.d.})$$

$$\log P(\vec{w}) = -\frac{w^2}{2\tau^2} - \frac{d}{2} \log(2\pi\tau^2)$$

$$\frac{\partial}{\partial w} [\log P(\vec{w})] = -\frac{2\vec{w}}{2\tau^2} = -\lambda \vec{w}$$

So the total expression becomes,

$$\frac{\partial}{\partial w} [\dots] = \sum_{i=1}^N \underbrace{[y_i - p(y=1|x_i)] x_i^T}_{\text{focus on mistakes}} - \lambda \vec{w}$$

\uparrow
 explain the labels
 \uparrow
 data wants to increase $\|w\|$ if it helps in classification

$\underbrace{\quad}_{\vec{w}}$
 But try to keep norm of \vec{w} small
 \uparrow
 don't get too confident unless you must.
 \uparrow
 prior resists large weights

MAP balances the two forces.