

```
#include <SimpleDHT.h>
```

```
#define GAS_SENSOR    A1
```

```
#define TRIG          A2
```

```
#define ECHO          A3
```

```
#define IR_SENSOR     A4
```

```
#define HT_SENSOR     A5
```

```
#define HT_LED        8
```

```
#define IR_LED        9
```

```
#define ULT_LED       10
```

```
#define BUZZER        11
```

```
#define GAS_LED       12
```

```
#define POW_LED       13
```

```
int dGas = 400;
```

```
SimpleDHT11 dht11(HT_SENSOR);
```

```
void setup() {
```

```
    Serial.begin(9600);
```

```
    pinMode(TRIG, OUTPUT);
```

```
    pinMode(ECHO, INPUT);
```

```
}
```

```
void loop() {
```

```
    digitalWrite(POW_LED,HIGH);
```

```
    ir_Readings();
```

```
    us_Readings();
```

```
    GAS_Readings();
```

```
    ht_Readings();
```

```
}
```

```

void ir_Readings() {
    int x = digitalRead(IR_SENSOR);
    Serial.print("IR=");
    Serial.print(!x);
    Serial.print("\t");

    if (x == 0) {
        digitalWrite(IR_LED, HIGH);
    }
    else {
        digitalWrite(IR_LED, LOW);
    }
}

void us_Readings() {
    long duration;
    int distance;
    duration = time_Measurement(duration);
    distance = (int)duration * (0.0343) / 2;
    if (distance > 99 || distance < 0)
        distance = 0;
    display_distance(distance);
}

void GAS_Readings() {

    int x = analogRead(GAS_SENSOR);
    Serial.print("GS=");
    Serial.print(x);
    Serial.print("\t");
    if (x >= dGas+100 && x < dGas+200){

```

```

    digitalWrite(GAS_LED, HIGH);
    //tone(BUZZER, 1000);
}
else {
    digitalWrite(GAS_LED, LOW);
    //noTone(BUZZER);
}
delay(10);
}

void ht_Readings() {

    byte temperature = 0;
    byte humidity = 0;
    dht11.read(&temperature, &humidity, NULL);
    Serial.print("HT=");
    Serial.print(temperature);
    Serial.print("*C,");
    Serial.print(humidity);
    Serial.print("%");
    Serial.println();

    if (temperature > 38 || humidity > 37)
        digitalWrite(HT_LED, HIGH);
    else
        digitalWrite(HT_LED, LOW);
    delay(500);
}

int time_Measurement(int duration)
{
    digitalWrite(TRIG, LOW);

```

```
    delayMicroseconds(2);
    digitalWrite(TRIG, HIGH);
    delayMicroseconds(10);
    digitalWrite(TRIG, LOW);
    duration = pulseIn(ECHO, HIGH);
    return duration;
}

void display_distance(int distance)
{

    Serial.print("US=");
    Serial.print(distance);
    Serial.print("cm");
    Serial.print("\t");
    if (1 <= distance && distance <= 10) {
        digitalWrite(ULT_LED, HIGH);
        tone(BUZZER, 2000);
    }
    else {
        digitalWrite(ULT_LED, LOW);
        noTone(BUZZER);
    }
    delay(10);
}
```