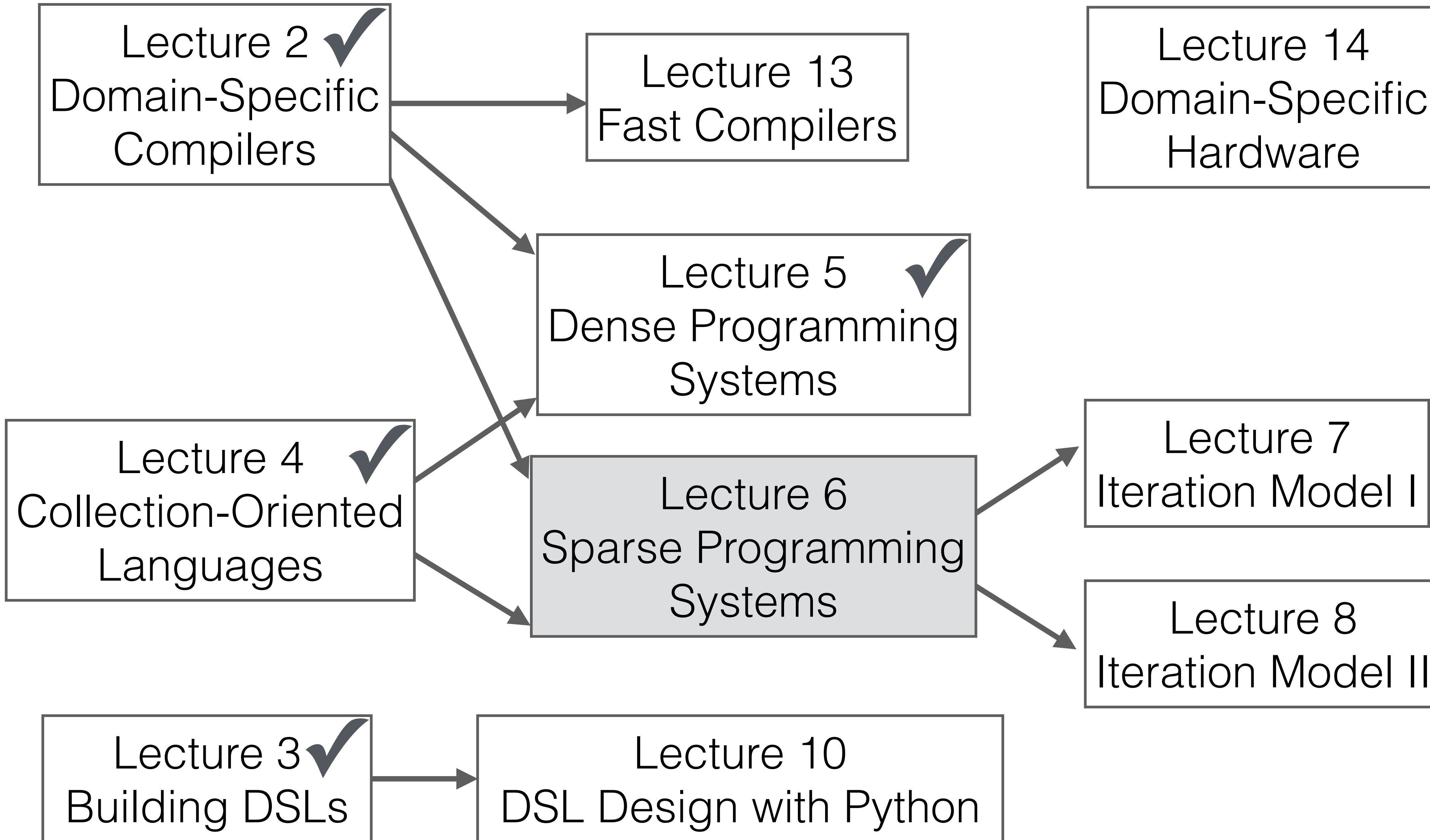


# Lecture 6 - Sparse Programming Systems

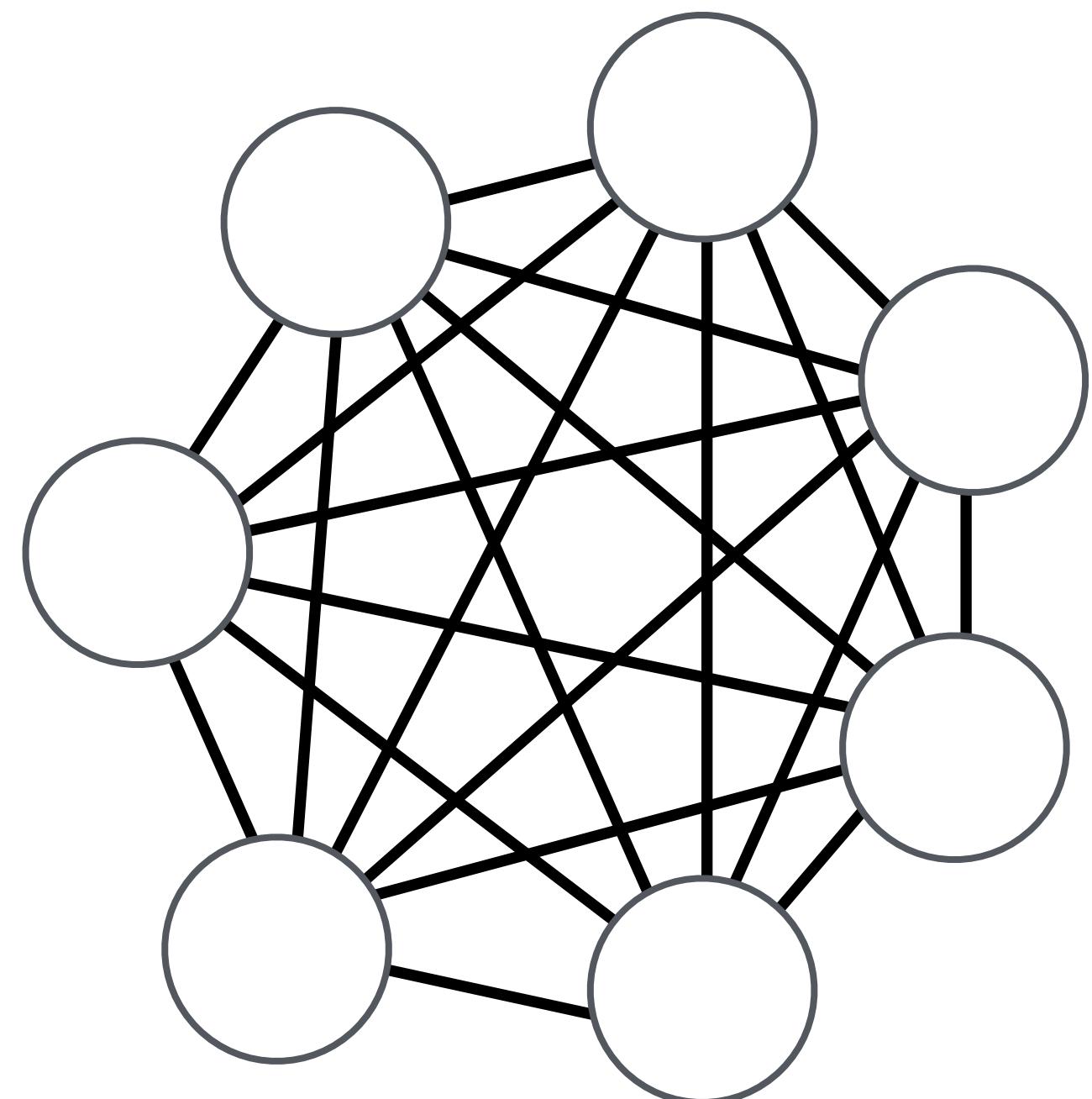
Stanford CS343D (Fall 2021)  
Fred Kjolstad

# Lecture Overview

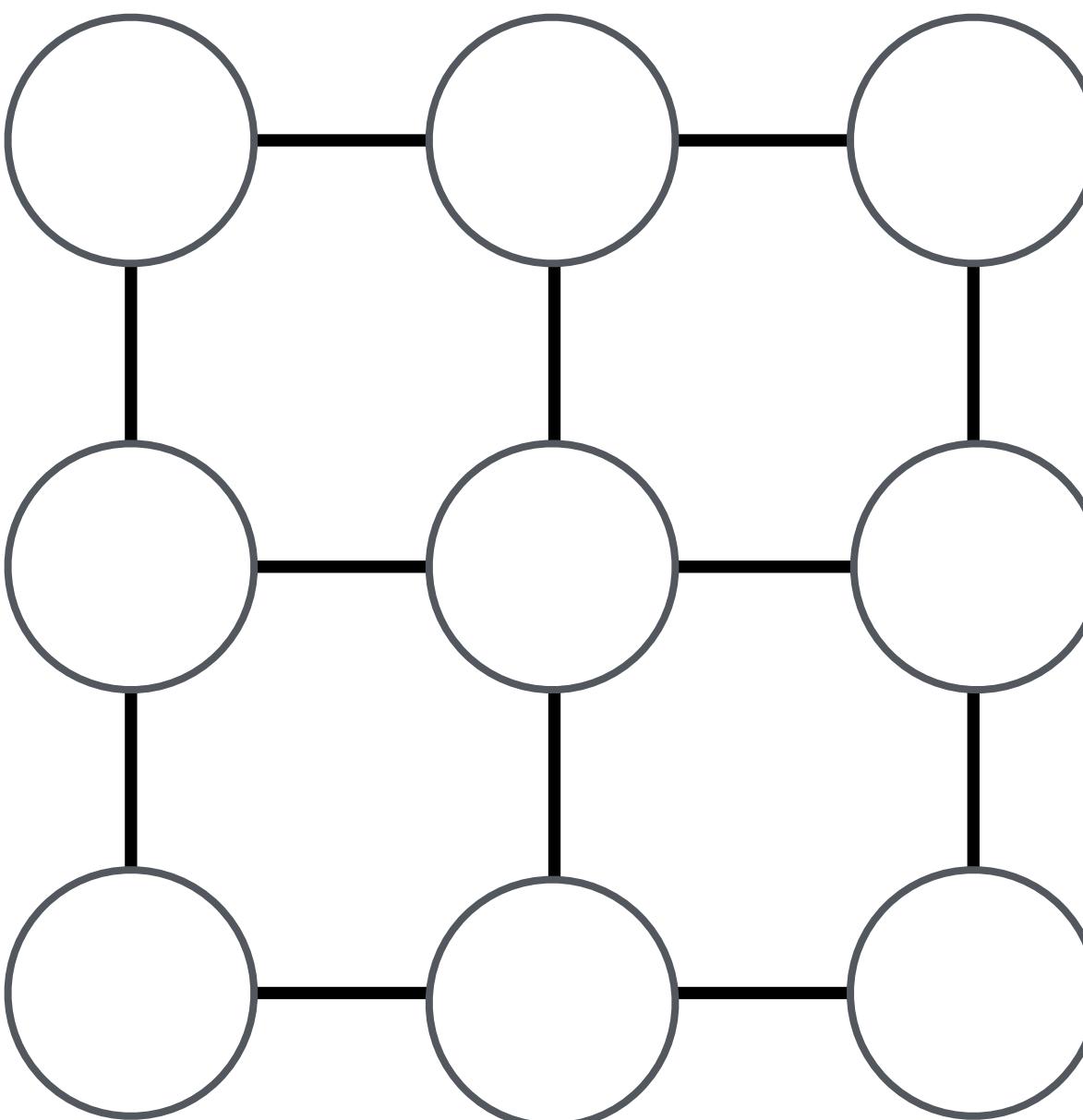


# Terminology: Regular and Irregular

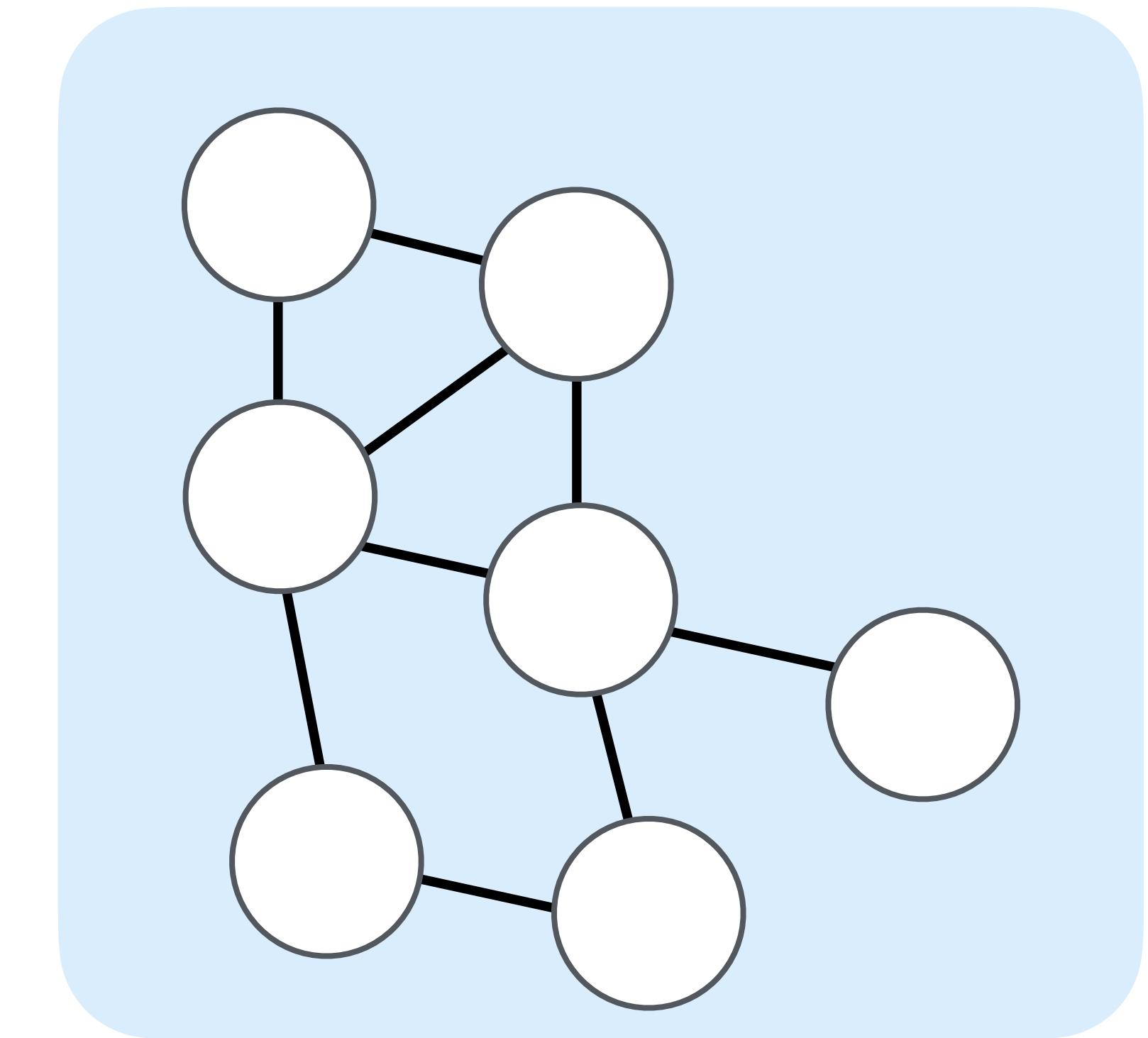
Fully Connected System



Regular System

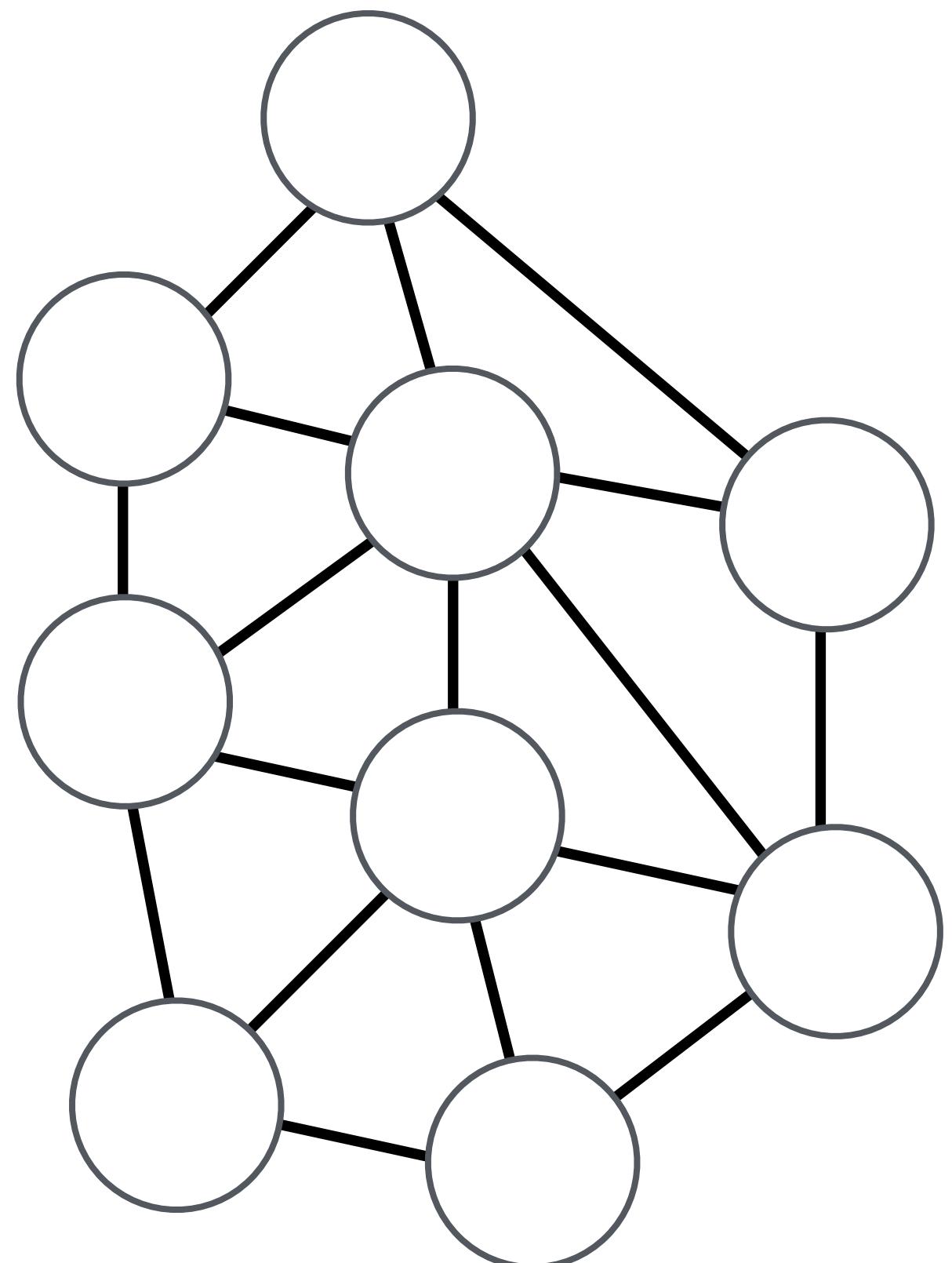


Irregular System

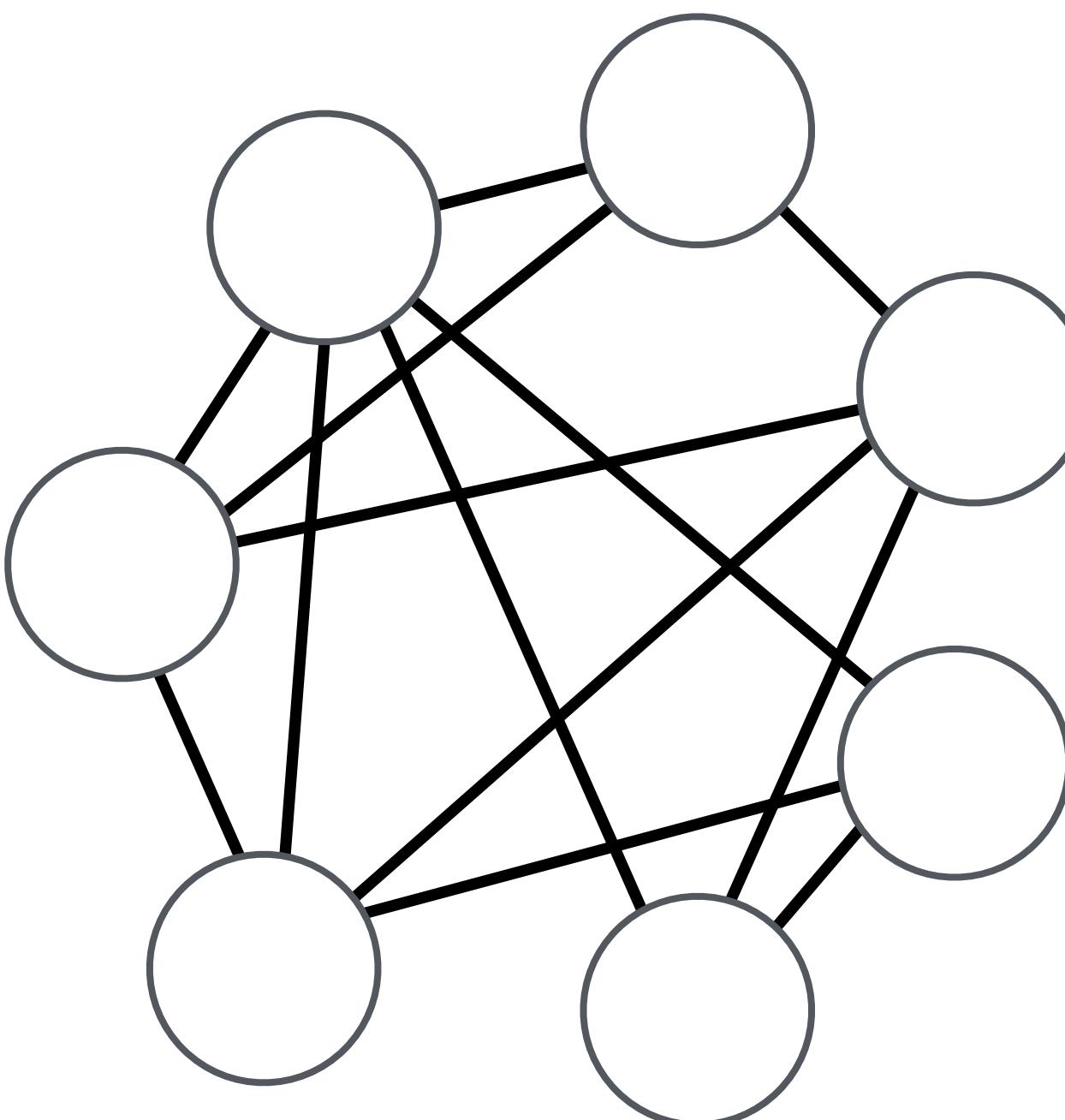


# Three main classes of irregular systems

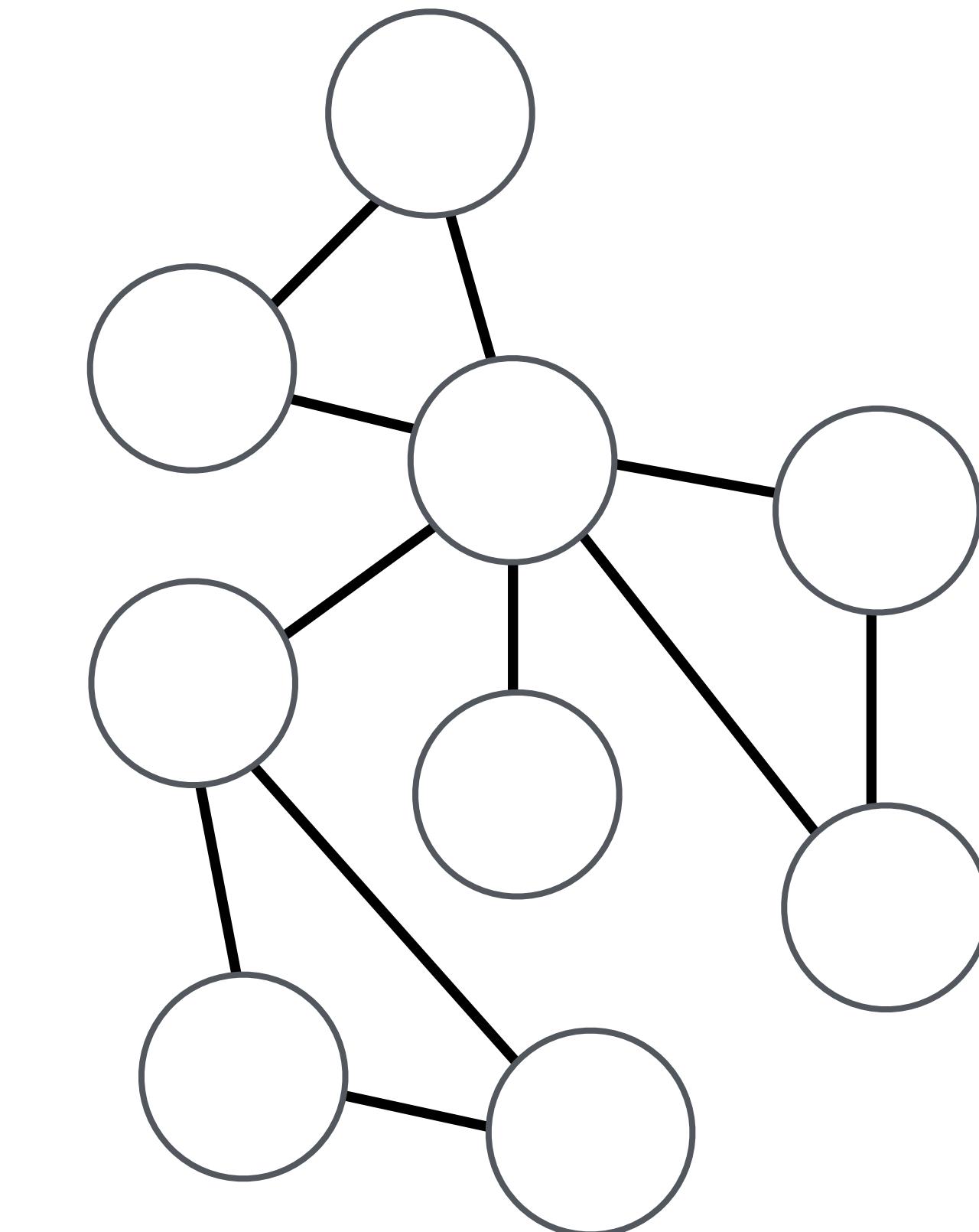
Road Networks



Fractional Sparsity

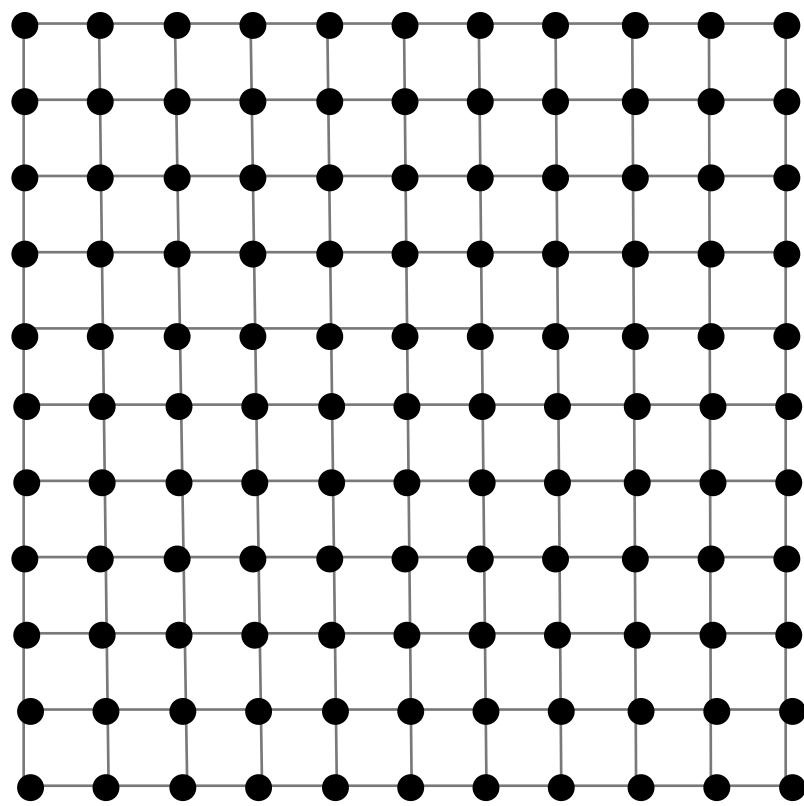


Power Law Graphs



# Terminology: Dense and Sparse

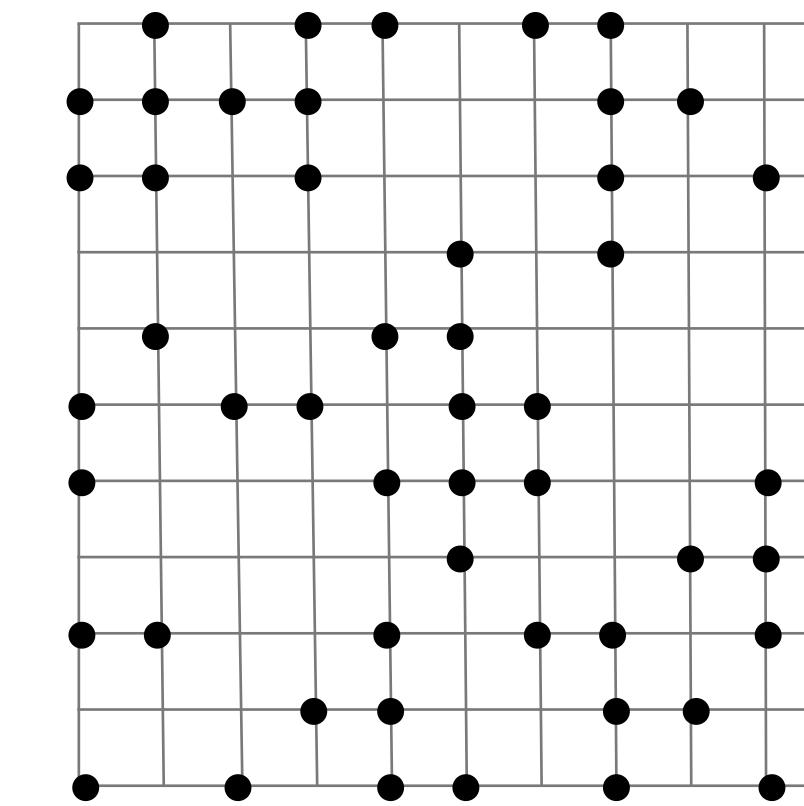
Dense loop iteration space



```
for (int i = 0; i < m; i++) {  
    for (int j = 0; j < n; j++) {  
        y[i] += A[i*n+j] * x[j];  
    }  
}
```

$$y = Ax$$

Sparse loop iteration space

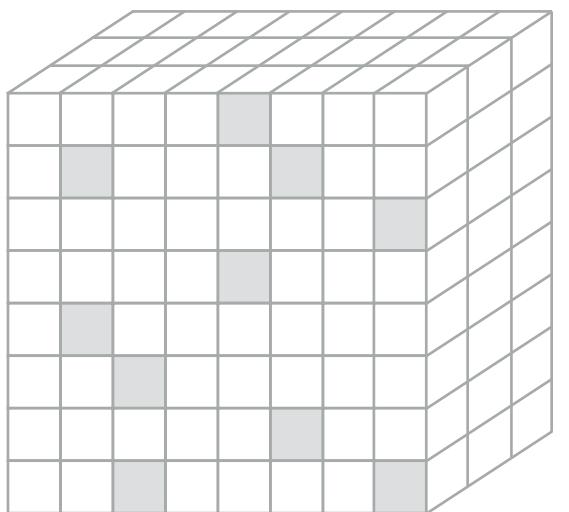


```
for (int i = 0; i < m; i++) {  
    for (int pA = A2_pos[i]; pA < A_pos[i+1]; pA++) {  
        int j = A_crd[pA];  
        y[i] += A[pA] * x[j];  
    }  
}
```

$$y = Ax$$

# Three sparse applications areas

Tensors



Nonzeros are a subset of the cartesian combination of sets



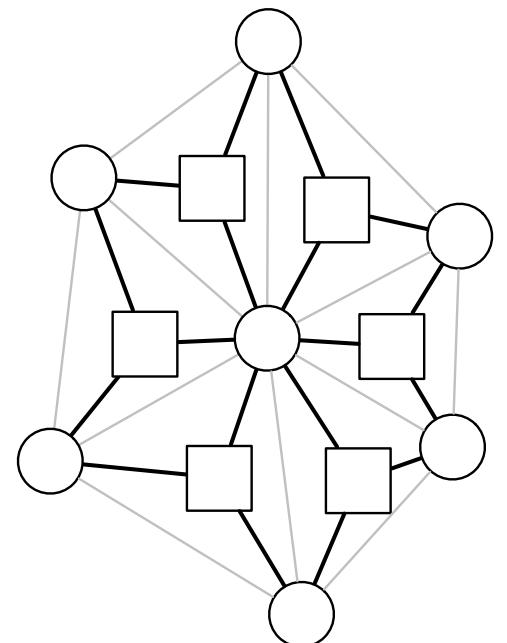
Relations

Names	City	Age
Peter	Boston	54
Mary	San Fransisco	35
Paul	New York	23
Adam	Seattle	84
Hilde	Boston	19
Bob	Chicago	76
Sam	Portland	32
Angela	Los Angeles	62

A relation is a subset of the cartesian combination of sets



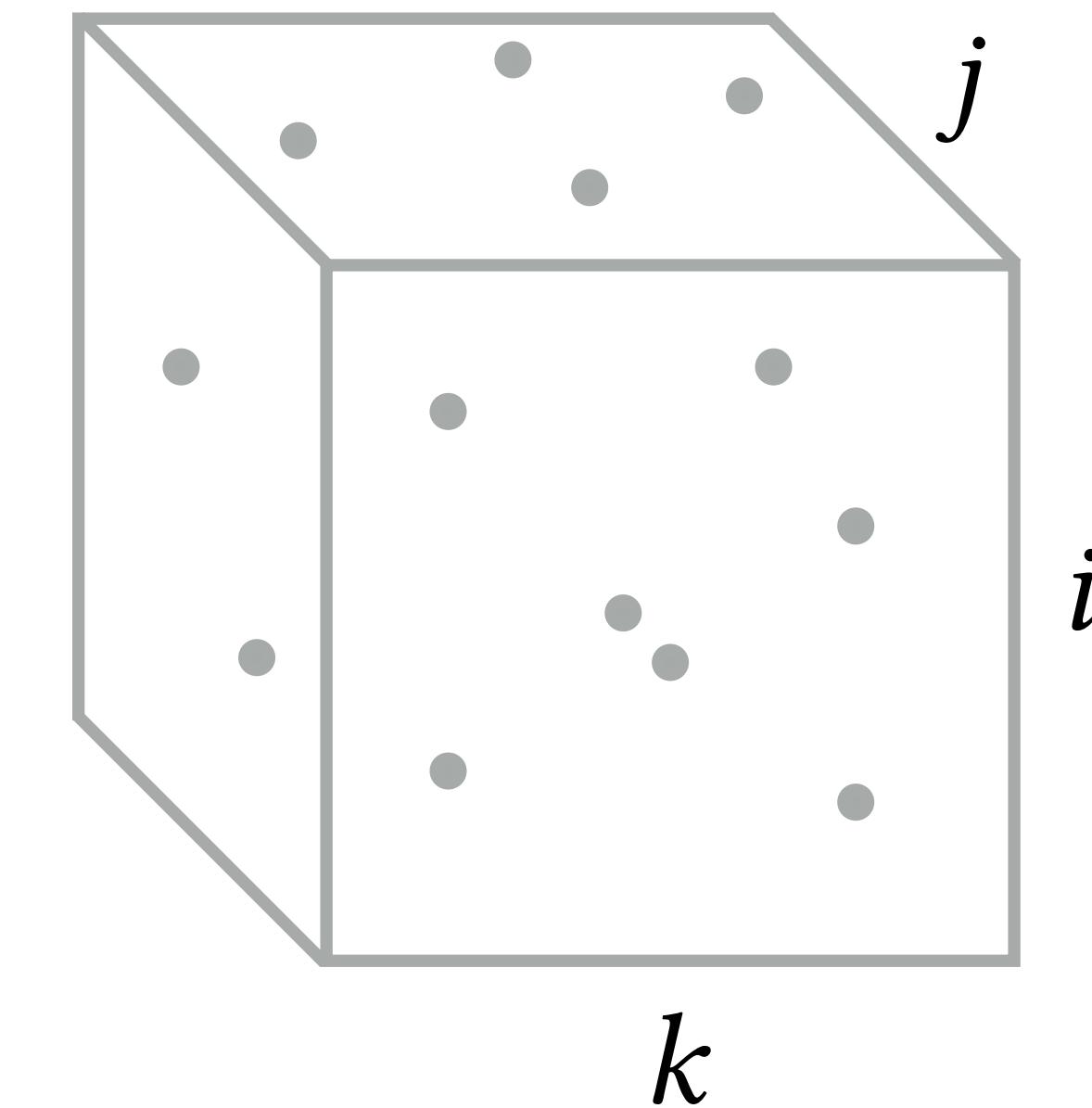
Graphs



Graph edges are a subset of the cartesian combination of sets



Sparse Iteration Spaces



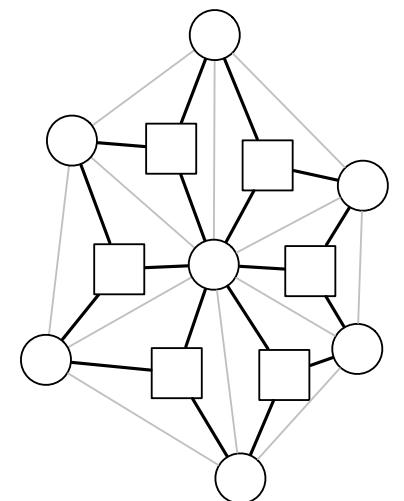
# Relations, graphs, and tensors share a lot of structure but are specialized for different purposes

Relations

Names	City	Age
Peter	Boston	54
Mary	San Fransisco	35
Paul	New York	23
Adam	Seattle	84
Hilde	Boston	19
Bob	Chicago	76
Sam	Portland	32
Angela	Los Angeles	62

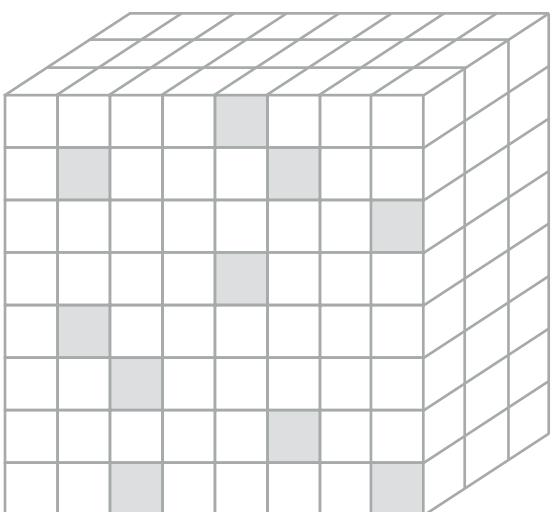
Combine data to form systems

Graphs



Local operations on systems

Tensors



Global operations on systems

Relations

Filters

Solves

Pagerank  
Triangle Counting

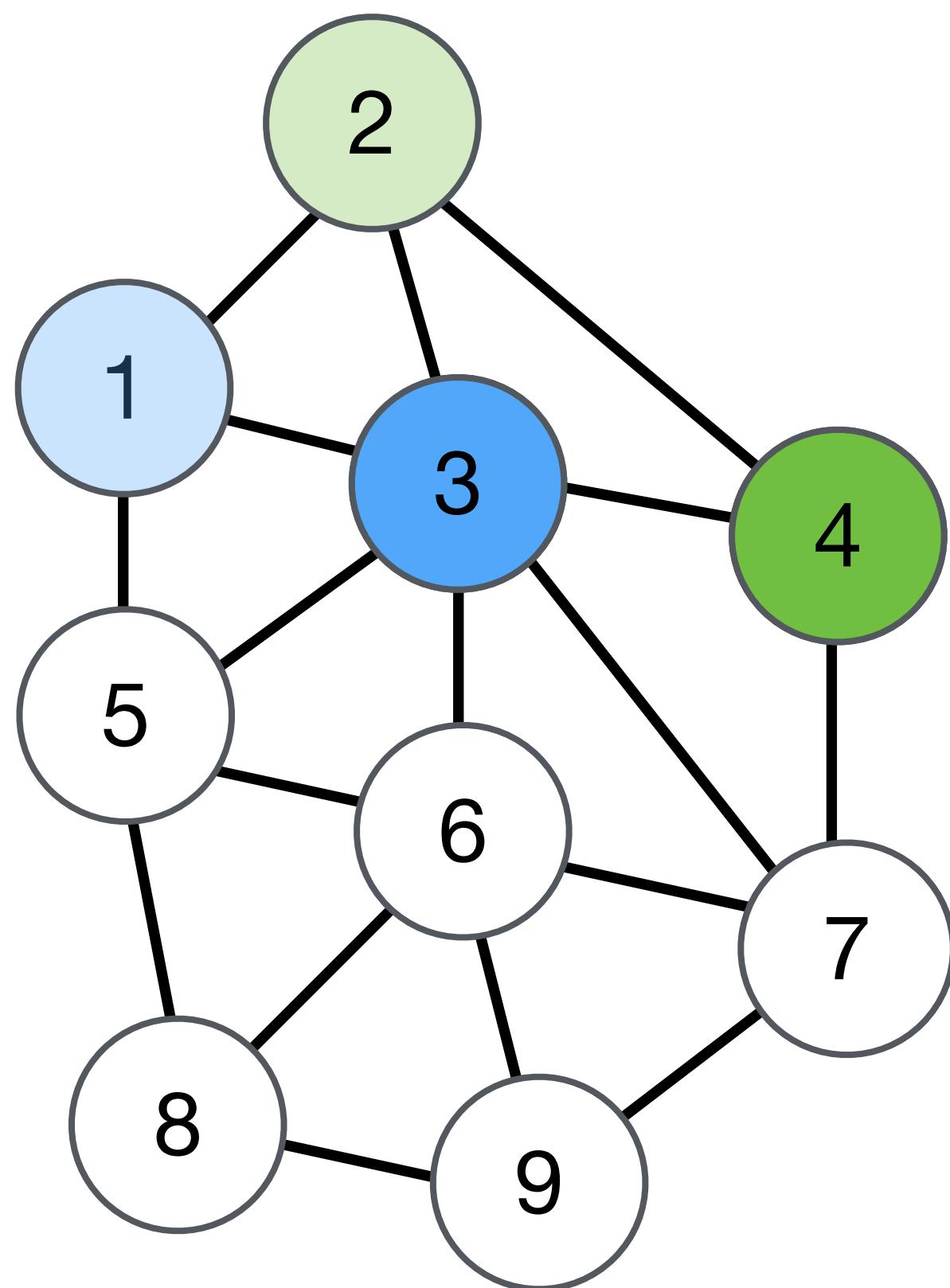
Tensor

Graphs

Dijkstra's Algorithm

# Triangle counting on graphs, relations, and tensors

On graphs



On relations

$$Q_{\Delta} = R(A, B) \bowtie S(B, C) \bowtie T(A, C)$$

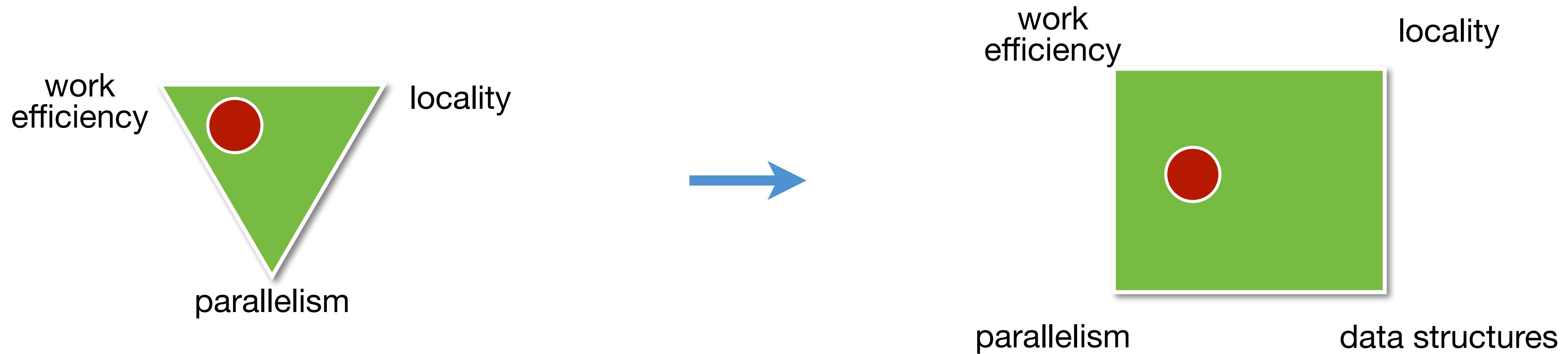
On tensors

$$\frac{1}{6}\text{trace}(A^3).$$

# Some important developments in compilers and programming languages for sparse compilers

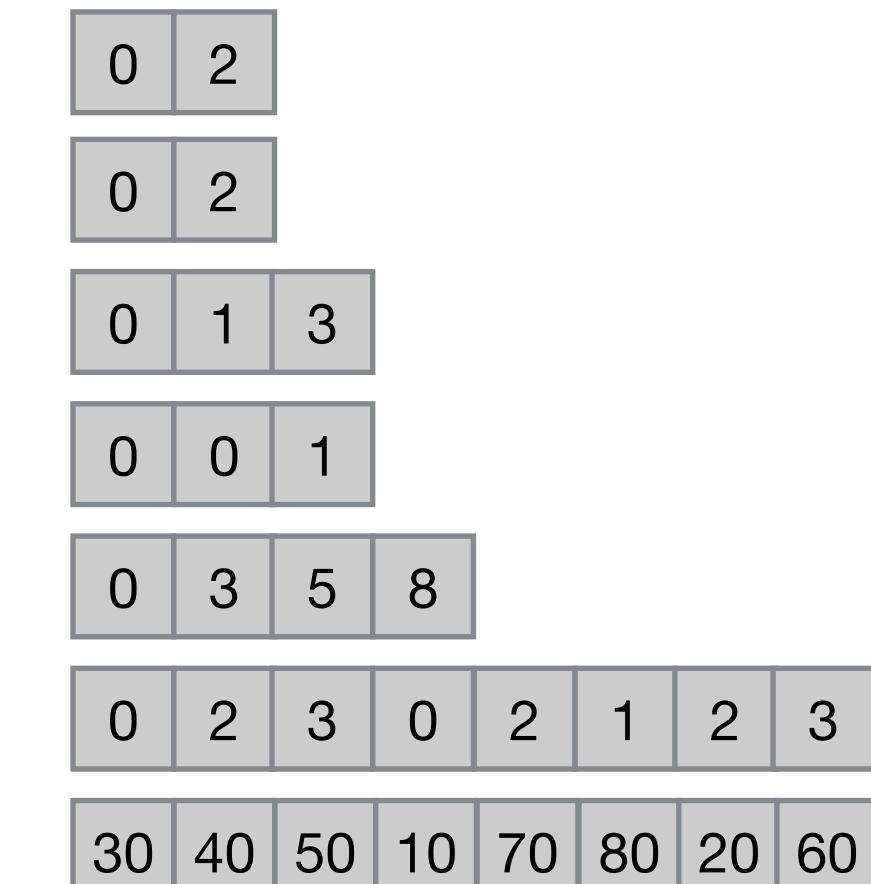
- 1960s: Development of libraries for sparse linear algebra
- 1970s: Relational algebra and the first relational database management systems: System R and INGRES
- 1980s: SQL is developed and has commercial success
- 1990s: Matlab gets sparse matrices and some dense to sparse linear algebra compilers are developed
- 2000s: Sparse linear algebra libraries for supercomputers and GPUs
- 2010s: Graph processing libraries become popular, compilers for databases, and compilers for tensor algebra

# Parallelism, locality, work efficiency still matters, but the key is choosing efficient data structures



Harry	CS
Sally	EE
George	CS
Mary	ME
Rita	CS

Harry	Sally	George	Mary	Rita
CS	EE	CS	ME	CS

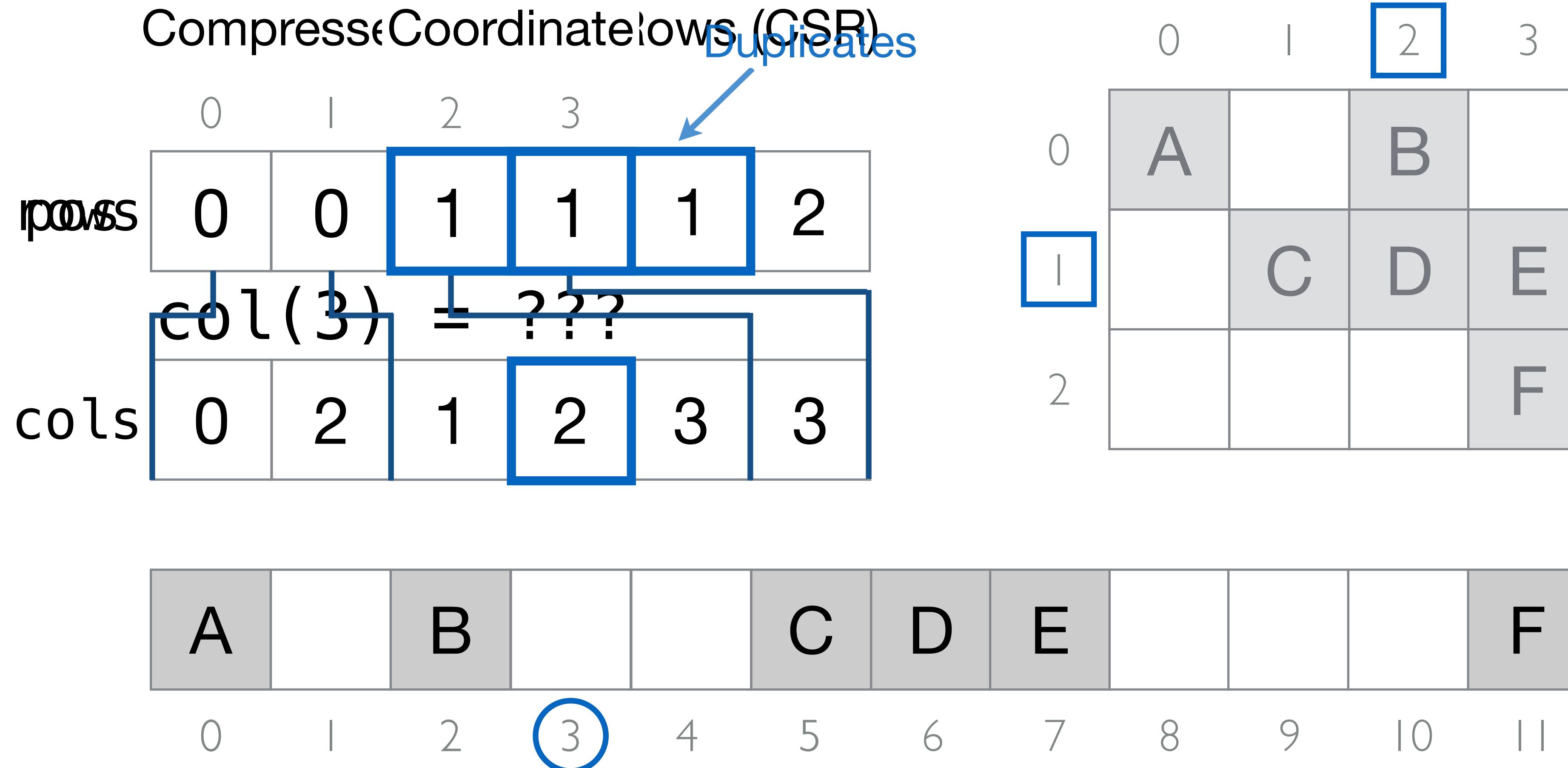


# Sparse data structures in graphs, tensors, and relations encode coordinates in a sparse iteration space

Tensor (nonzeros)		Relation (rows)	Graph (edges)
	(0,1)	(Harry,CS)	(v <sub>1</sub> ,v <sub>5</sub> )
(2,3)	(0,5)	(Sally,EE)	(v <sub>4</sub> ,v <sub>3</sub> )
(5,5)	(7,5)	(George,CS)	(v <sub>5</sub> ,v <sub>3</sub> )
		(Rita,CS)	(v <sub>3</sub> ,v <sub>5</sub> )
		(Mary,ME)	(v <sub>3</sub> ,v <sub>1</sub> )

Values may be attached to these coordinates: e.g., nonzero values, edge attributes

Hierarchically compressed data structures (tries)  
reduce the number of values that need to be stored

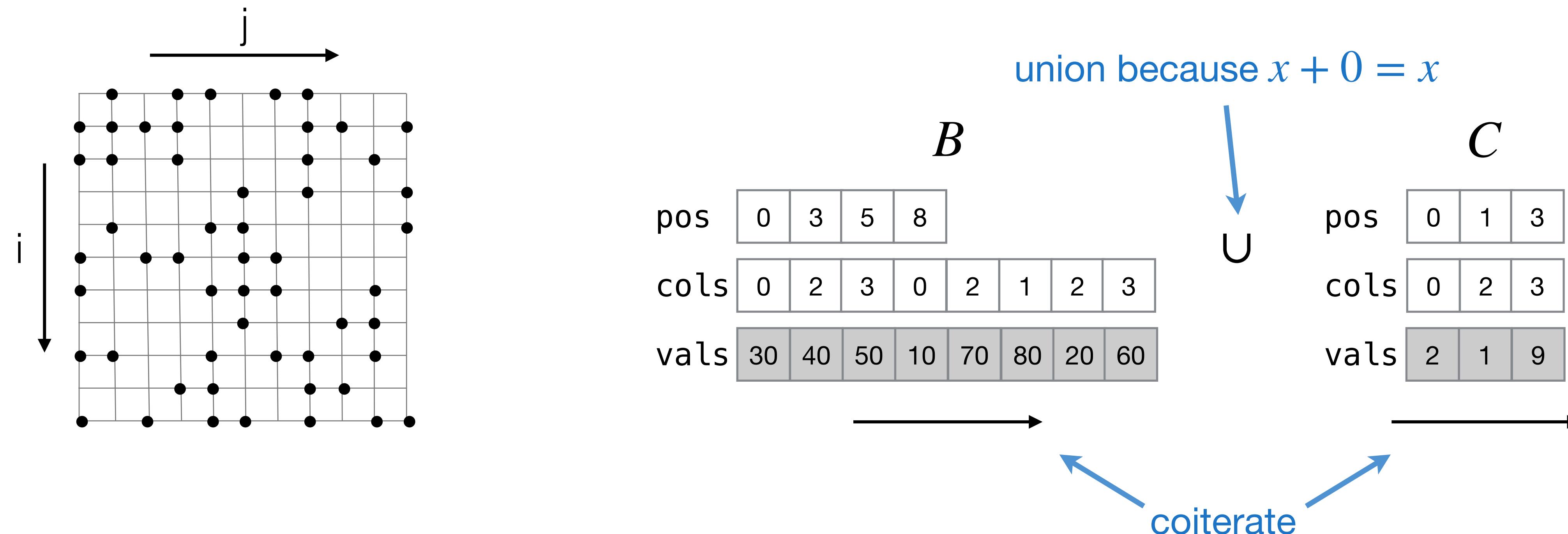


# Iteration over sparse iteration spaces imply coiteration over sparse data structures

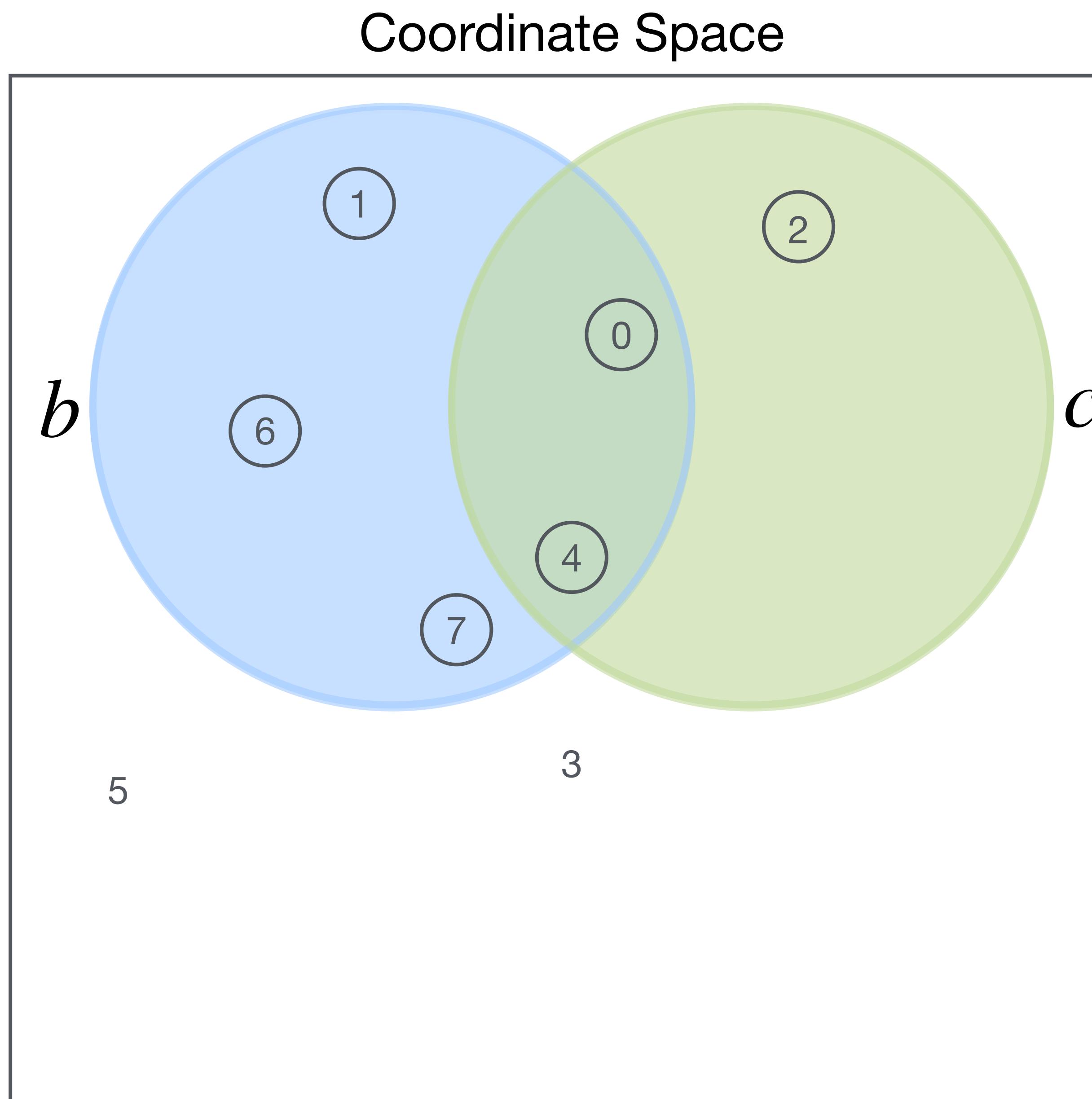
Linear Algebra:  $A = B + C$

Tensor Index Notation:  $A_{ij} = B_{ij} + C_{ij}$

Iteration Space:  $B_{ij} \cup C_{ij}$



# Merged coiteration



$$a_i = b_i \oplus c_i$$

$$\begin{matrix} a \\ \hline 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 \end{matrix} = \begin{matrix} b \\ \hline 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 \end{matrix} \times \begin{matrix} c \\ \hline 0 & 1 & 2 & 3 & 4 & 5 & 6 & 7 \end{matrix}$$

$x \cdot 0 = 0$

$a$

$\times$

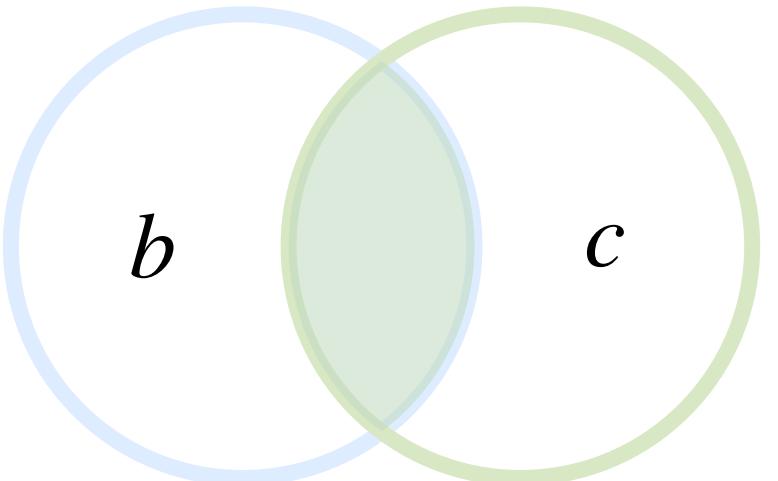
$b$

$c$

# Merged coiteration code

Intersection  $b \cap c$

```
int pb = b_pos[0];
int pc = c_pos[0];
while (pb < b_pos[1] && pc < c_pos[1]) {
    int ib = b_crd[pb];
    int ic = c_crd[pc];
    int i = min(ib, ic);
    if (ib == i && ic == i) {
        a[i] = b[pb] * c[pc];
    }
    if (ib == i) pb++;
    if (ic == i) pc++;
}
```

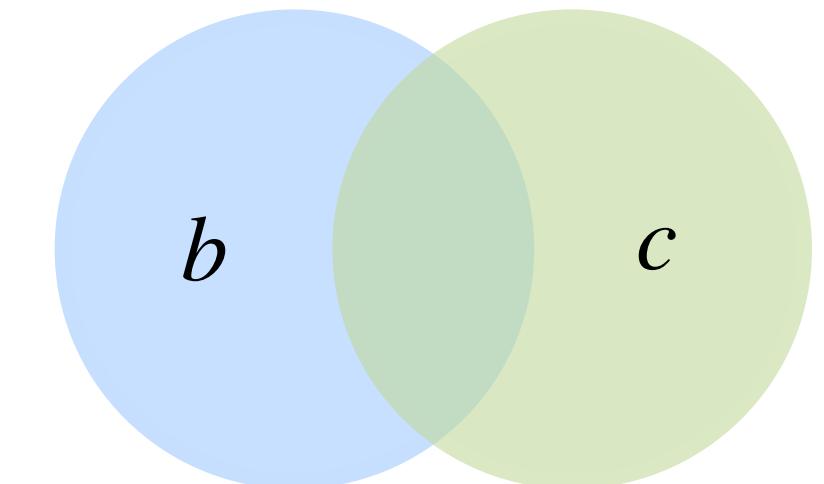


Union  $b \cup c$

```
int pb = b_pos[0];
int pc = c_pos[0];
while (pb < b_pos[1] && pc < c_pos[1]) {
    int ib = b_crd[pb];
    int ic = c_crd[pc];
    int i = min(ib, ic);
    if (ib == i && ic == i) {
        a[i] = b[pb] + c[pc];
    }
    else if (ib == i) {
        a[i] = b[pb];
    }
    else {
        a[i] = c[pc];
    }
    if (ib == i) pb++;
    if (ic == i) pc++;
}

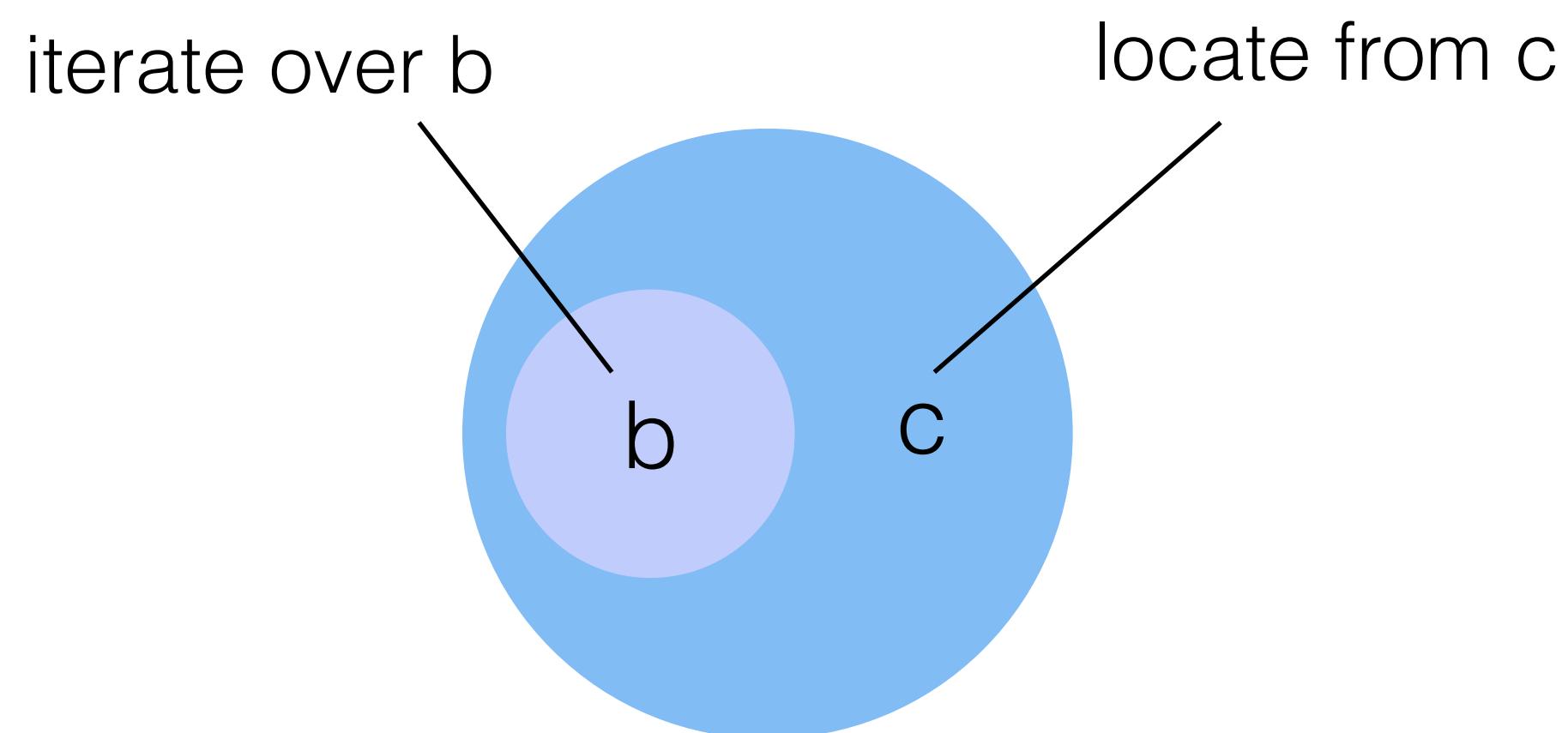
while (pb < b_pos[1]) {
    int i = b_crd[pb];
    a[i] = b[pb++];
}

while (pc < c_pos[1]) {
    int i = c_crd[pc];
    a[i] = c[pc++];
}
```



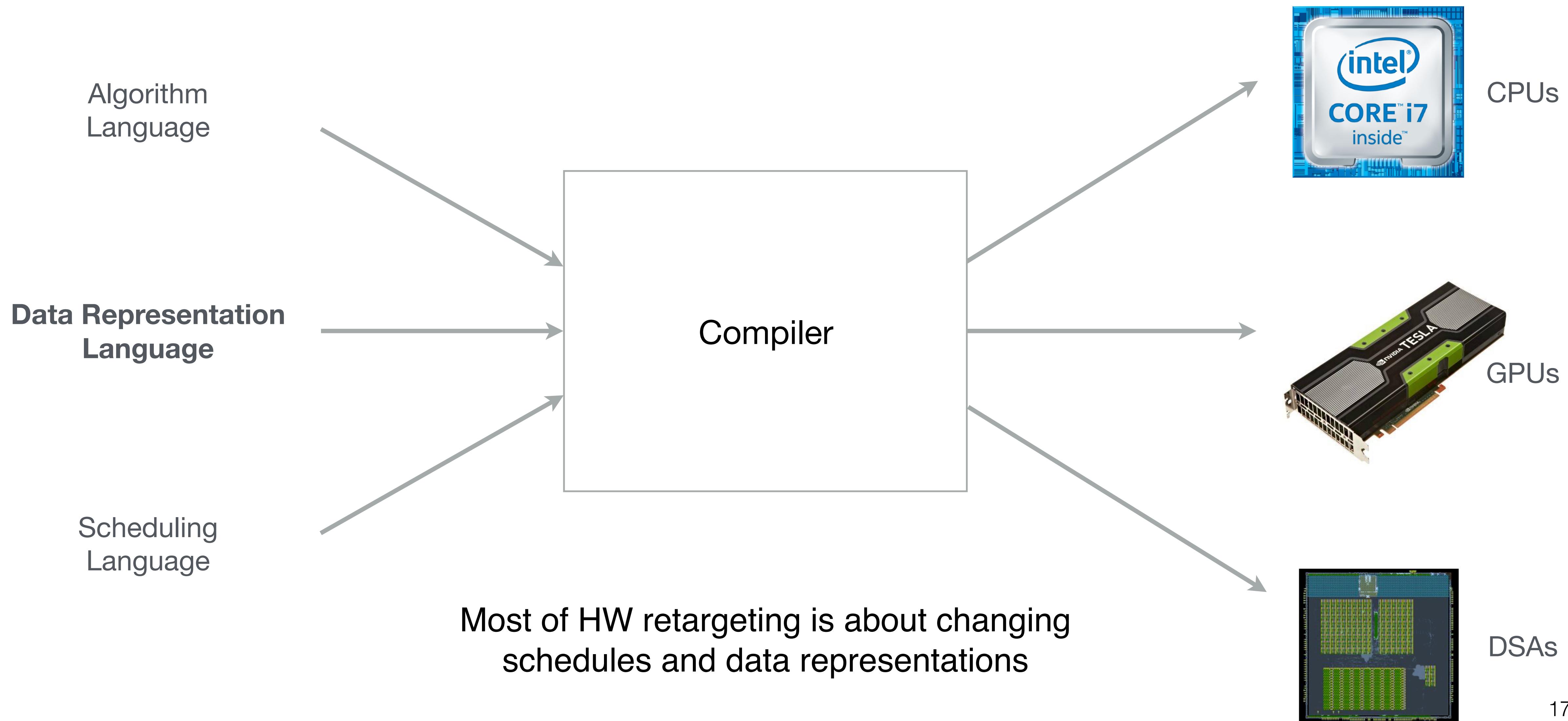
# Iterate-and-locate examples (intersection)

$$a = \sum_i b_i c_i$$



```
for (int pb = b_pos[0]; pb < b_pos[1]; pb++) {  
    int i = b_crd[pb];  
    a += b[pb] * c[i];  
}
```

# Separation of Algorithm, Data Representation, and Schedule

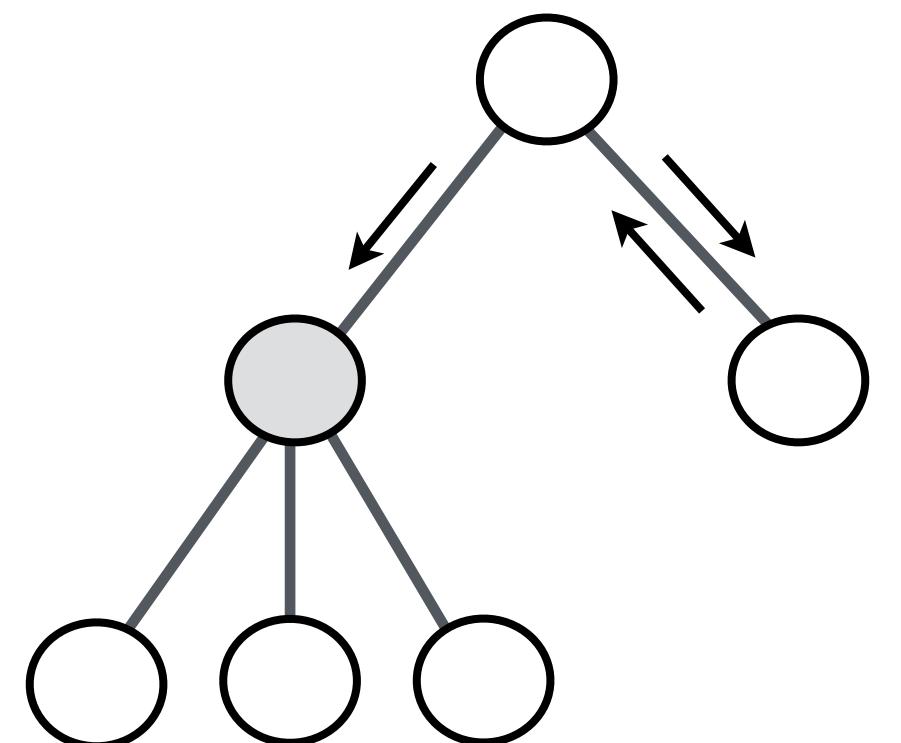


# Data independence separates algorithm from data layout and order of computation

- You want a logical (abstract) representation that exposes only characteristics of the data – not how the data is stored
- Tree models and network models require programmers to write programs to traverse indices
- If the indices change, the programs must change
- A flat abstract view—as coordinates—allows the system to change data representation without users changing their programs
- Underneath the hood, the system can impose hierarchies and networks

# Tree models, to network models, to the relational model

Tree model (1960s)  
(e.g., IMS)

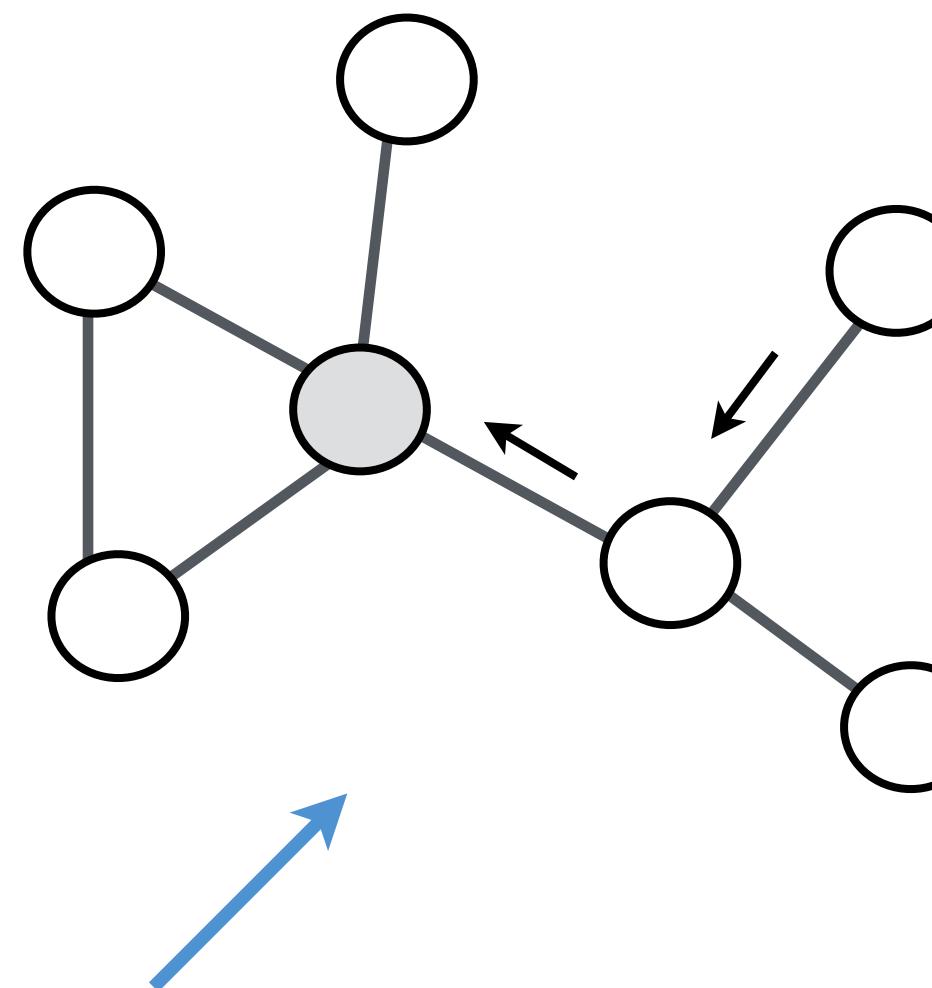


Programmer as navigator

A Relational Model of Data for Large Shared Data Banks. Codd (1970)

The Programmer as Navigator.  
Bachman (1974)

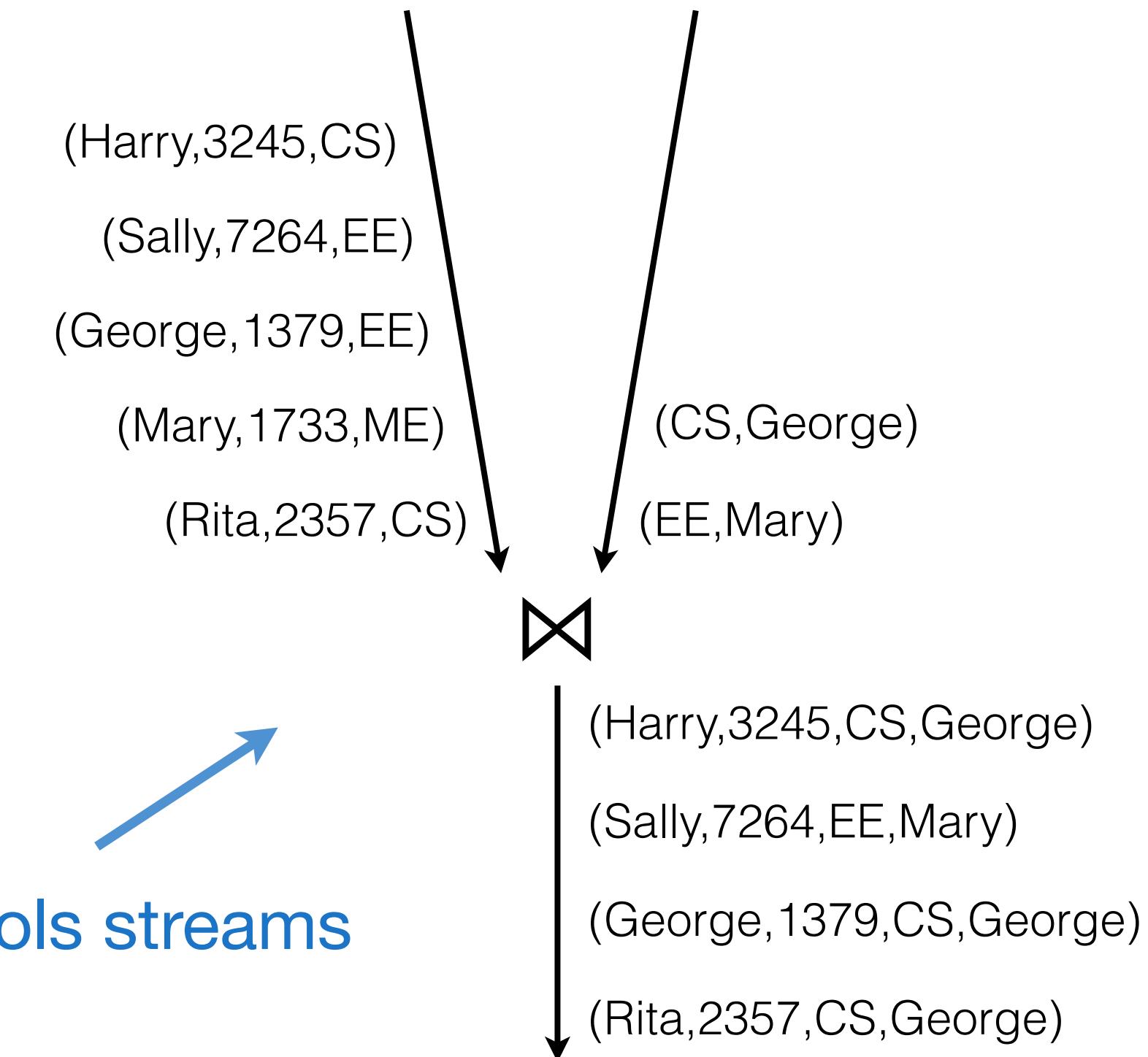
Network model (1970s)  
(e.g., CODASYL)



Programmer controls streams

What Goes Around Comes Around.  
Stonebraker and Hellerstein (2005)

Relational model



# Data structures in relational database management systems

- **Row stores** for efficient insertion
- **Column stores** for spatial locality during scans
- **B-trees** to efficiently support sorted data
- **Hash maps** for random access
- **Tries** for compression
- **Spatial data structures** for geo-spatial queries

But database management systems are still rewritten for each new major data structure