

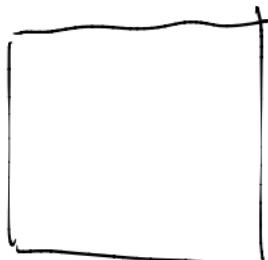
21 – Polygonal Modeling (Data structures, Triangle Meshes, Subdivision Surfaces)

Regular Polygons ~ convex, congruent sides & angles

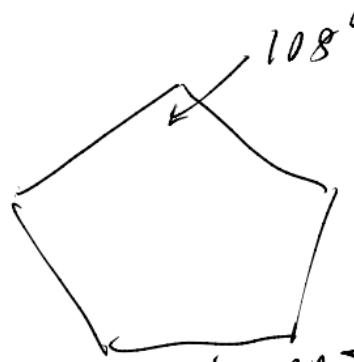
Regular Polygons



equilateral triangle



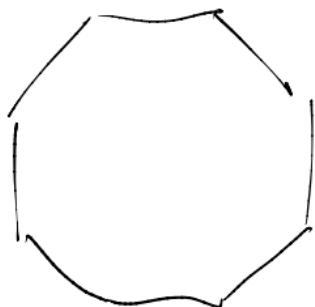
squares



pentagons

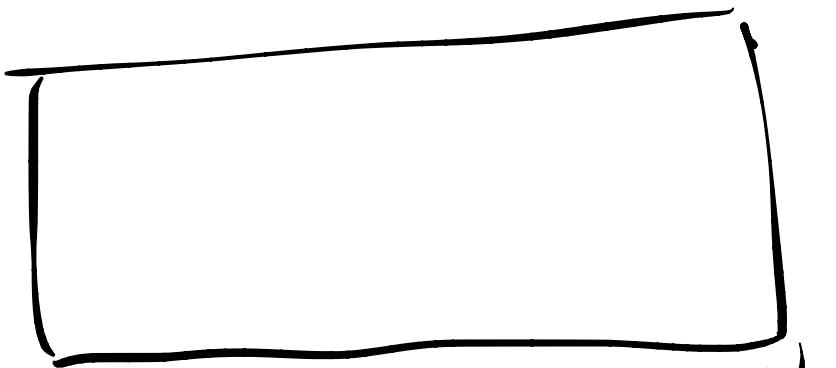


hexagons

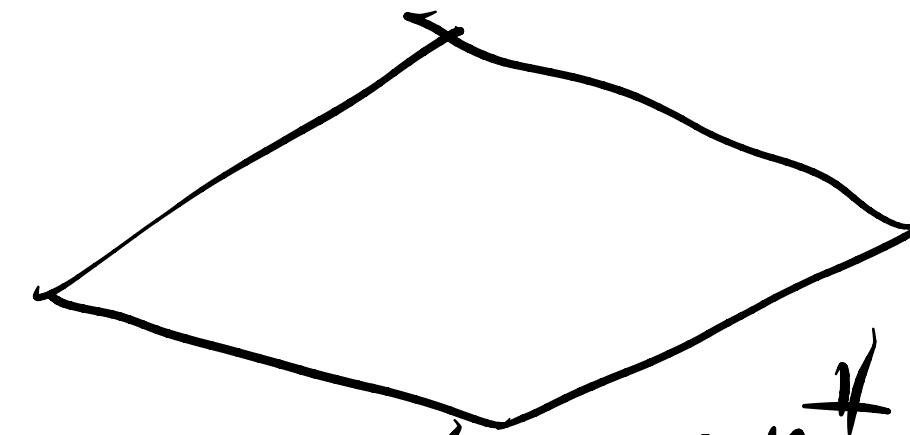


heptagons
160°

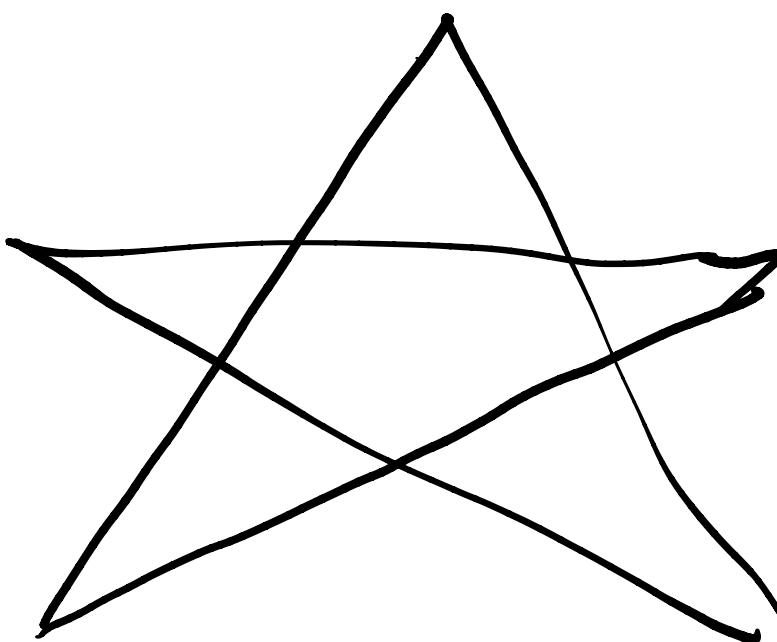
not regular



sides aren't
congruent



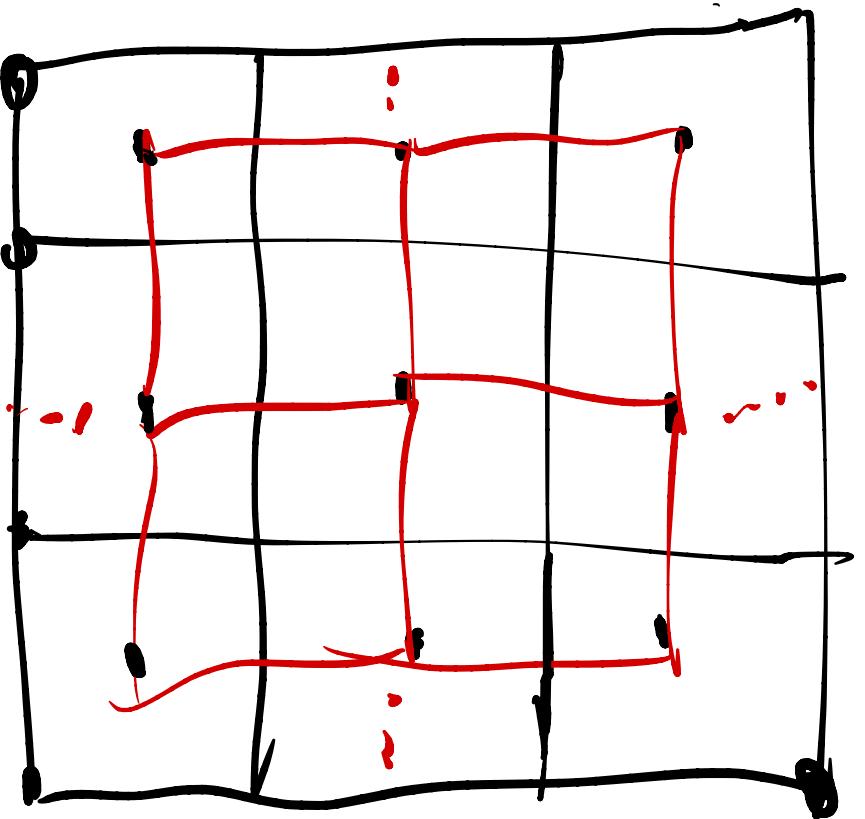
angles aren't congruent



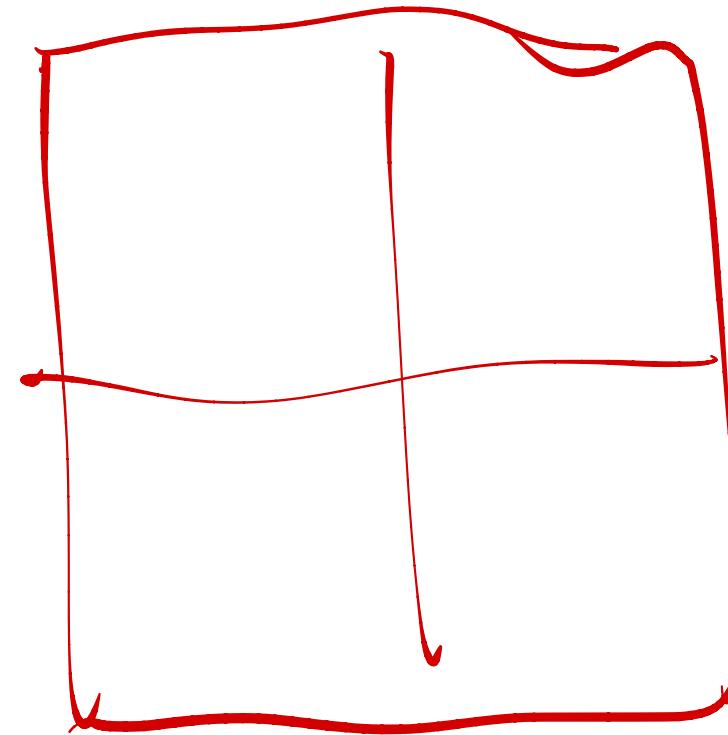
not convex

Regular Planar Tilings \rightarrow fill plane with reg poly's
 \hookrightarrow no gaps, no overlaps

valence = number of faces surrounding a vertex



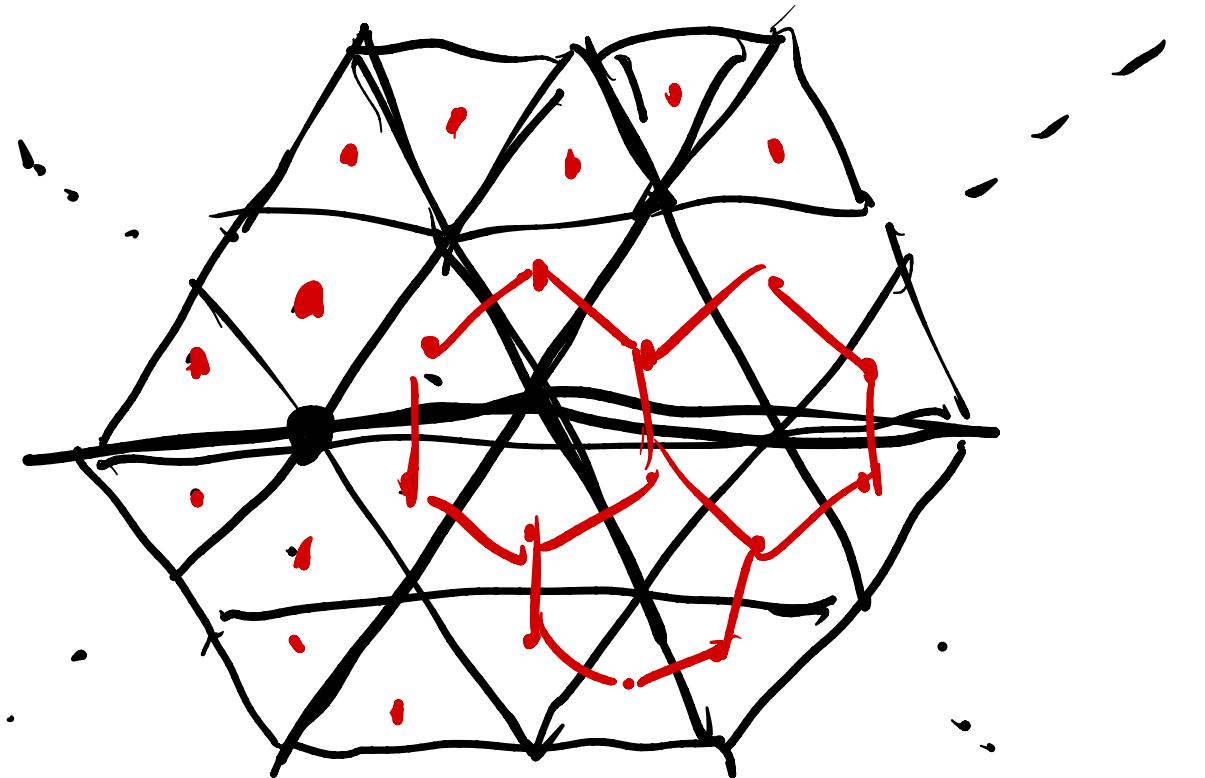
duat



:

• valence of 4
of sides is 4

swap # of
sides & valence
of vertices



Triangles.

3 sides per triangle

valence is 6

Represents any
regular polygon?

1 number
to specify sides

1 number for
scale

Hexagons

6 sides per face
valence of 3

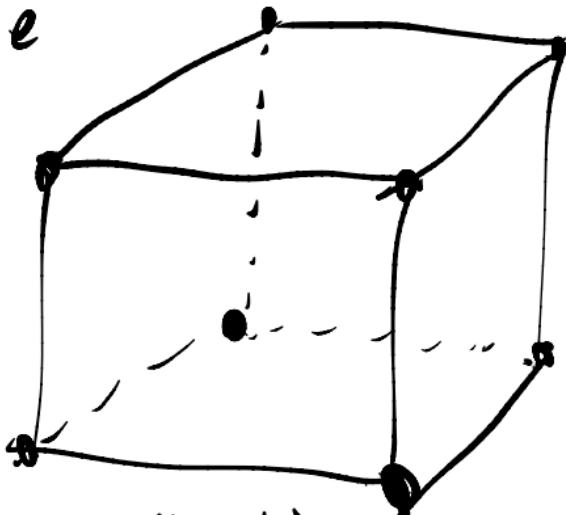
Regular Planar Tilings

Platonic Solids \rightarrow 3D!

regular & convex
& congruent sides
& angles

Cube

fill
space



tiling in
3D
cube

Vertices
8

Faces
6

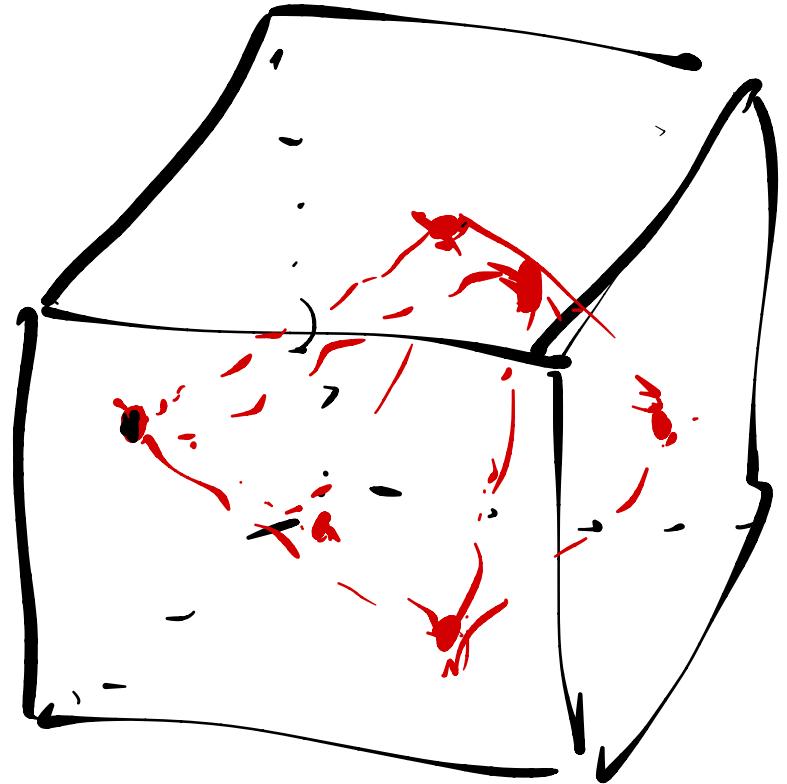
Edges
12

$$(1, 1, 1)$$

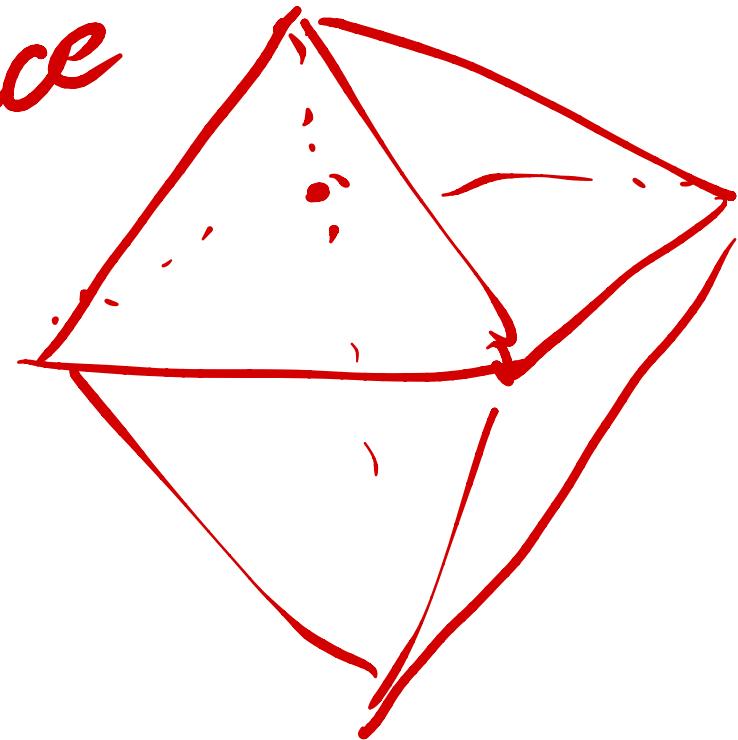
$$(-1, -1, -1)$$

$$(1, -1, -1)$$

⋮



Not fill
space



Octahedron.

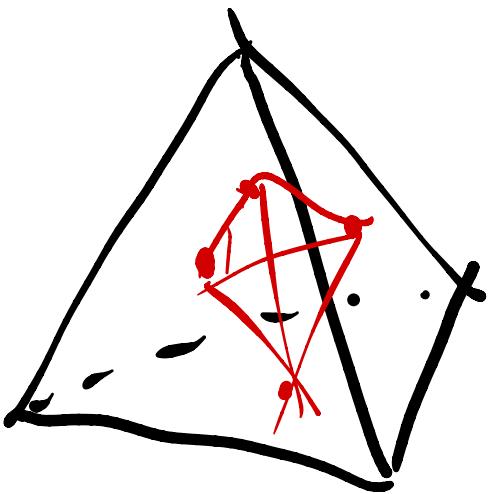
$$\begin{aligned} & (1, 0, 0) \\ & (-1, 0, 0) \end{aligned}$$

↓

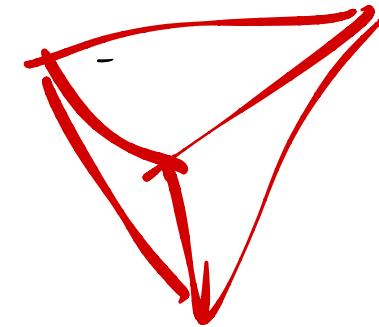
dual ↗
cube
octahedron

✓ F
~~8~~ 6
~~6~~ 8
Edges
12 5
12

Tetrahedron



dual



can't fill
space

tetrahedrons
+
octahedrons
fill space

Name

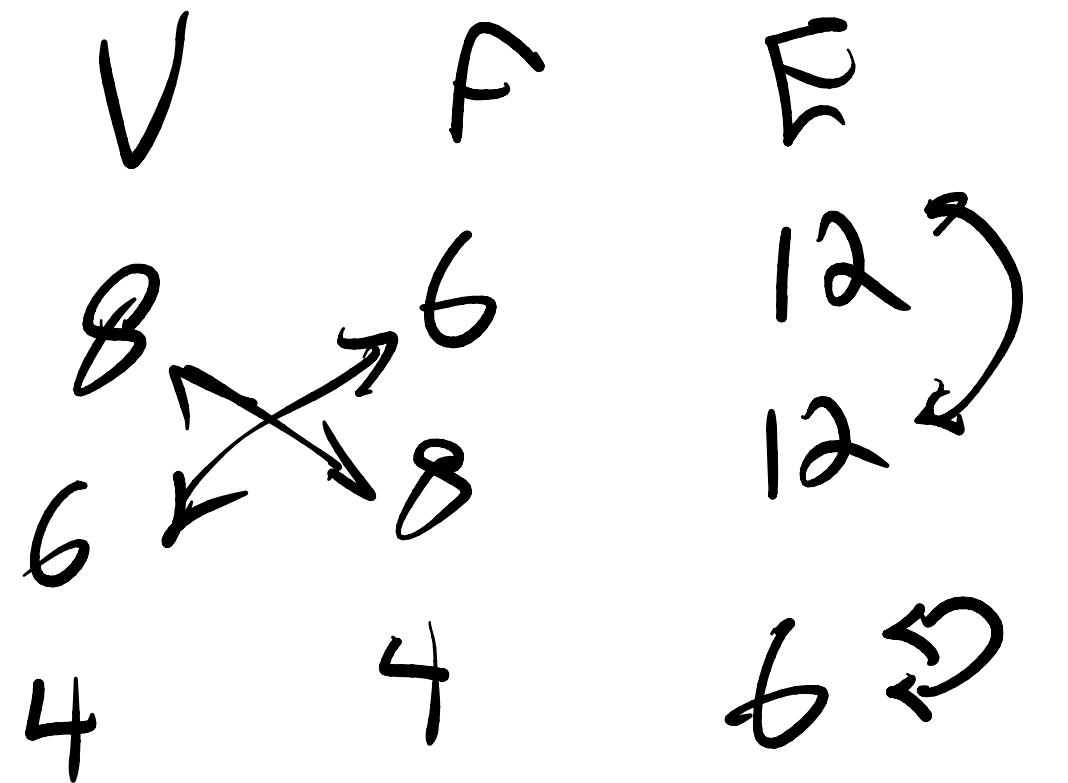
→ cubes

→ octahedrons

→ tetrahedrons

→ icosahedrons

→ dodecahedrons



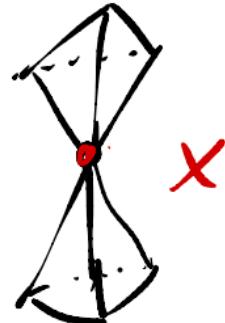
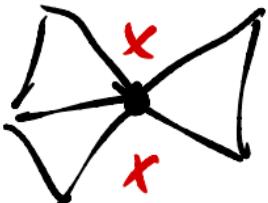
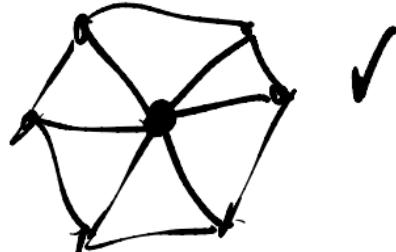
Platonic Solids

Polyhedrons :

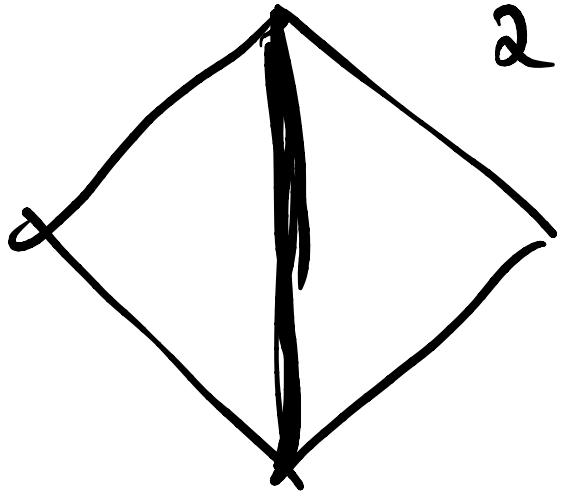
- surfaces composed of polygons
- polygons made of vertices & faces
- solids
- approximate smooth surfaces
 - ↳ rendering lets us smooth appearance

Manifold ↳ vertices
objects

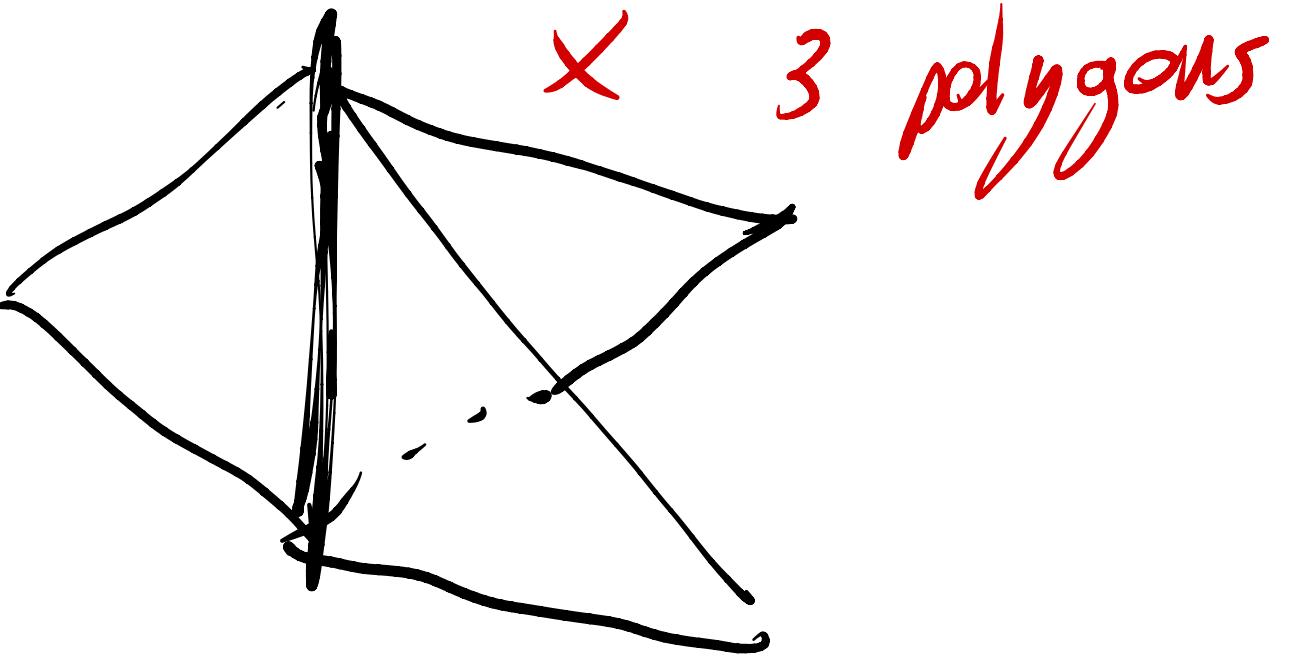
Manifold vertex: surface arounds it looks like a plate.
(possibly bent)



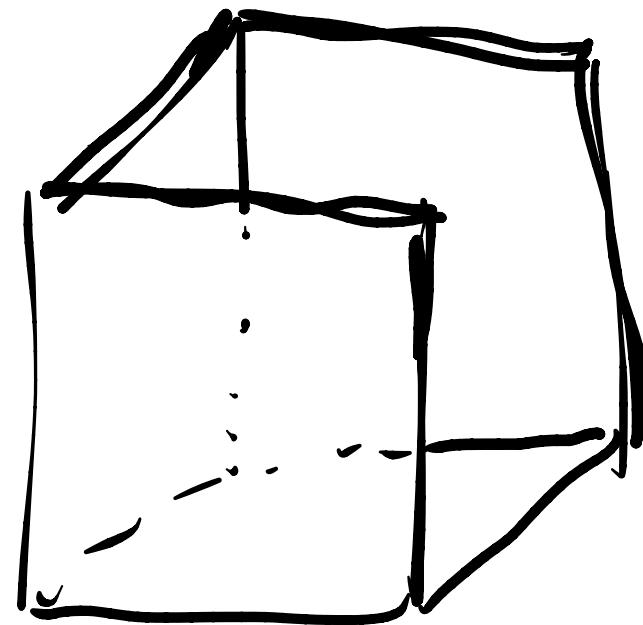
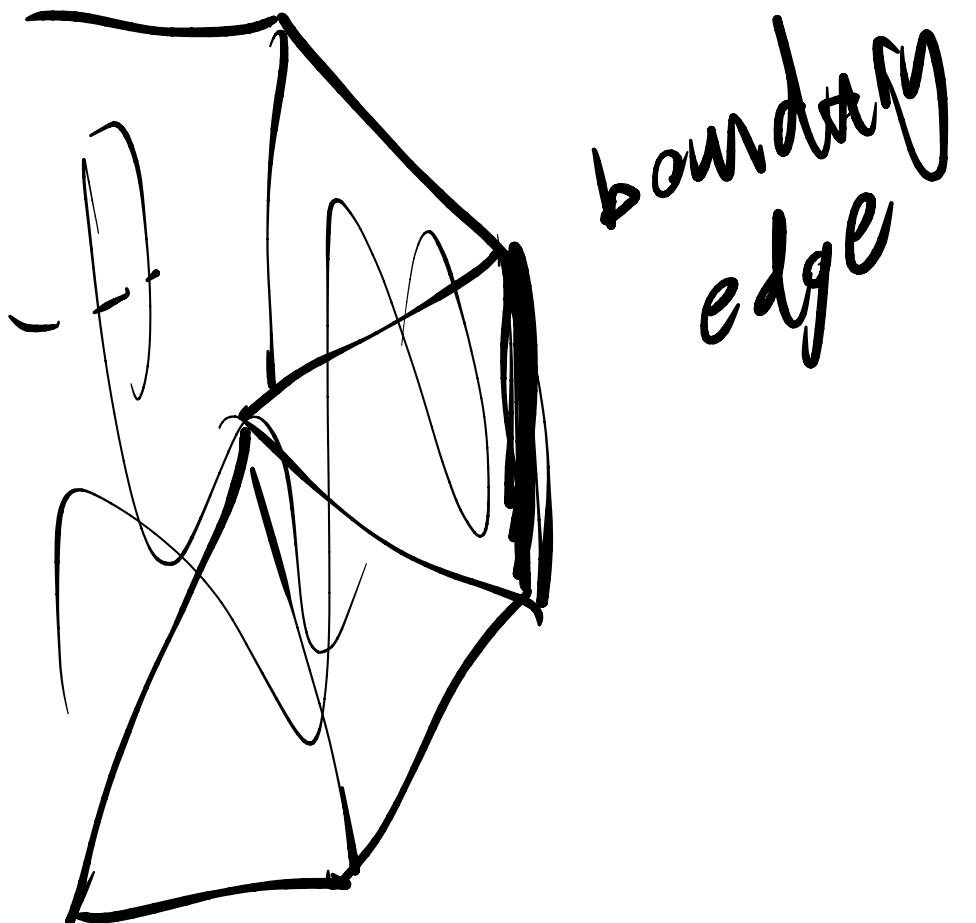
Manifold Edges



2 polygons
connected
by the
edge



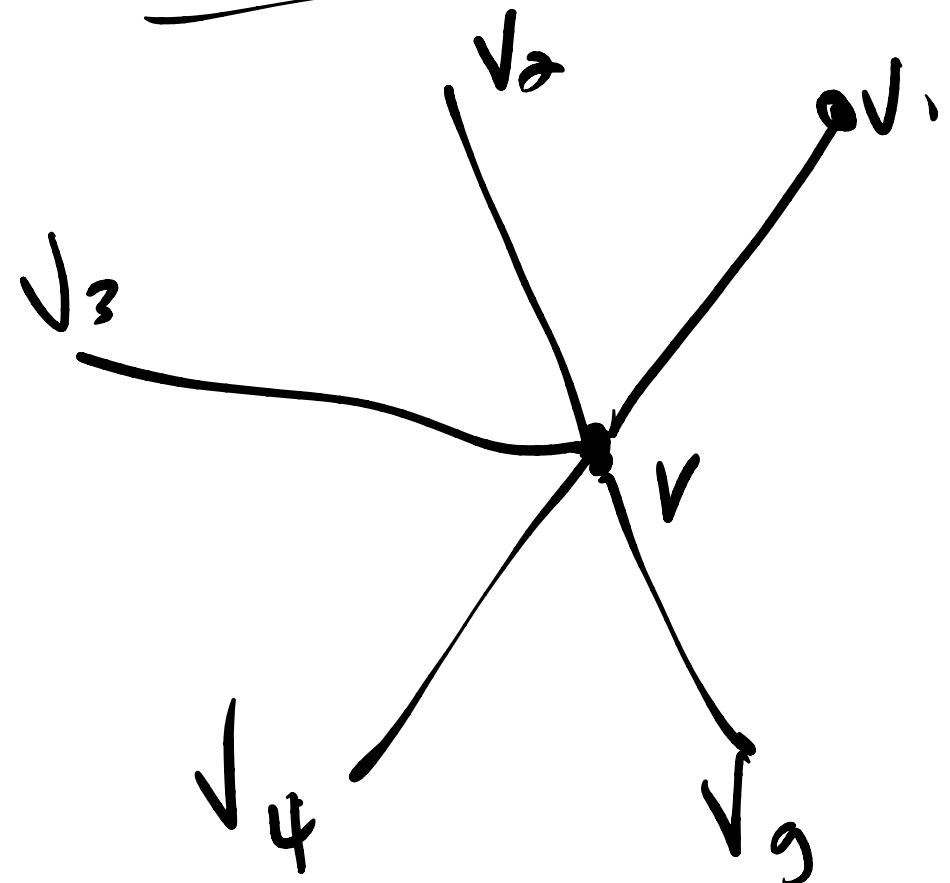
3 polygons



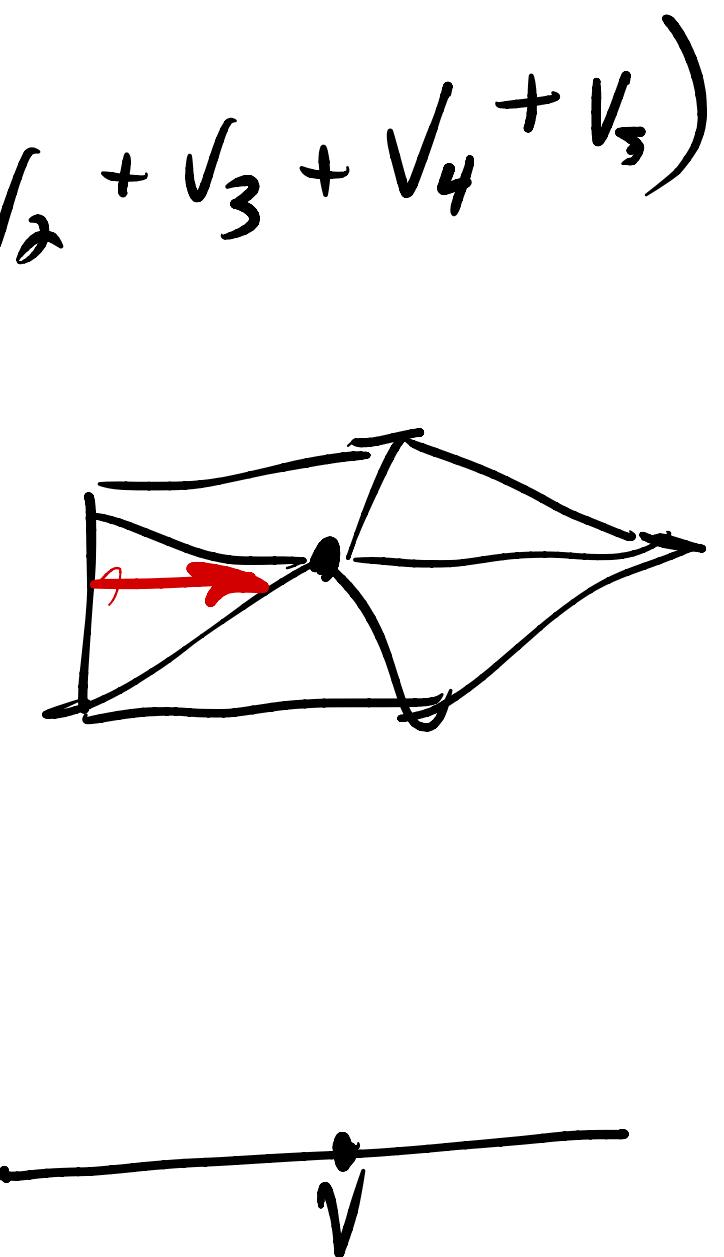
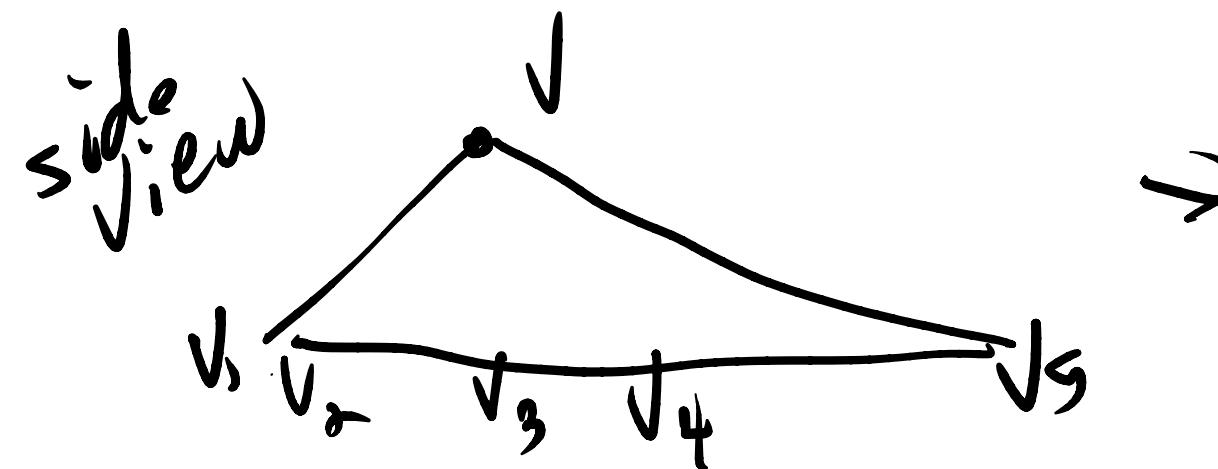
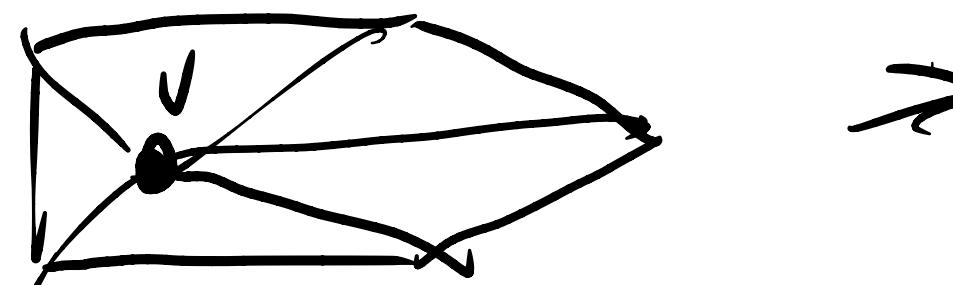
Some operations on polyhedra:

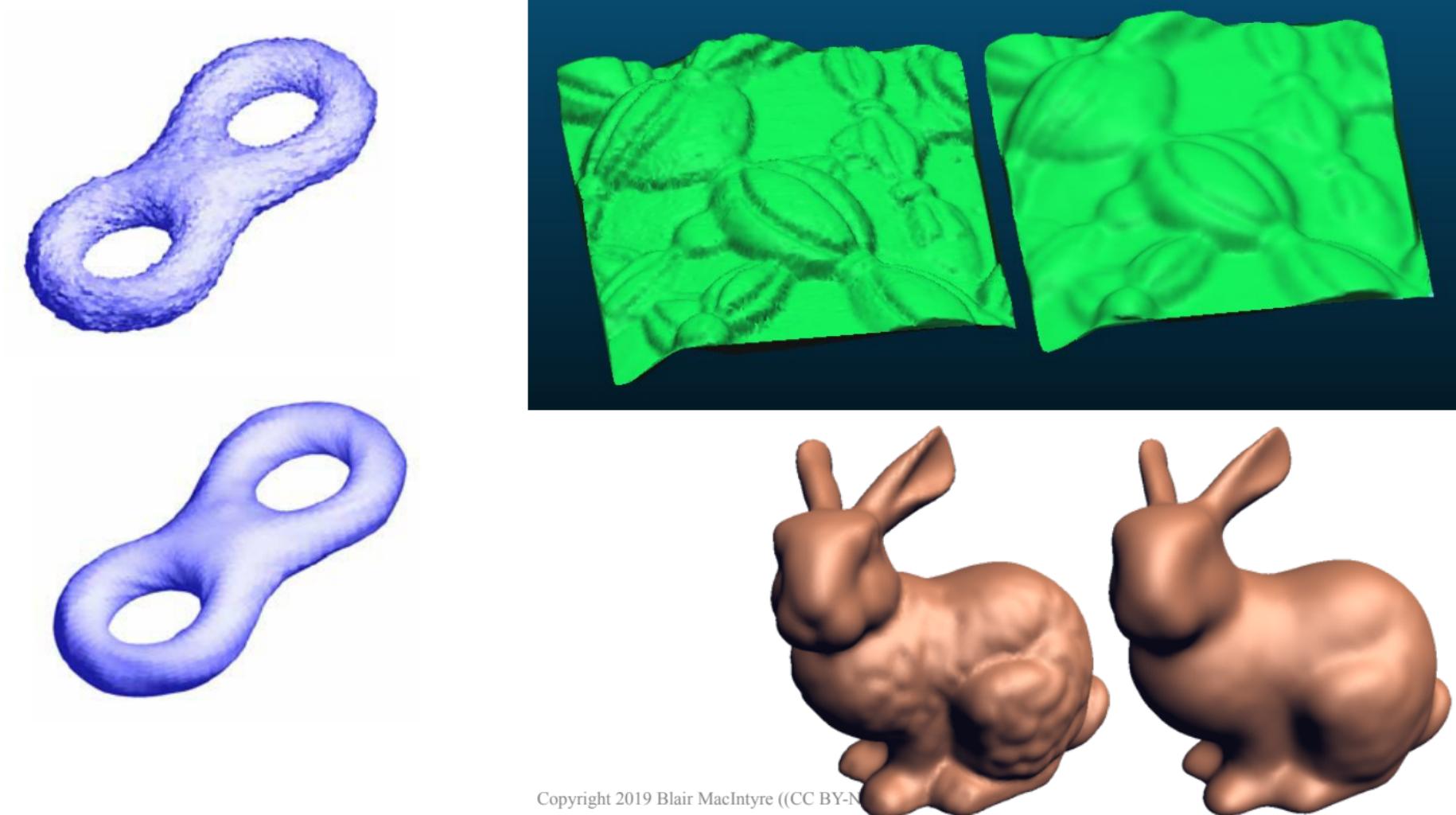
- Laplacian smoothing
- Face subdivision
- Triangulation

Laplacian Smoothing



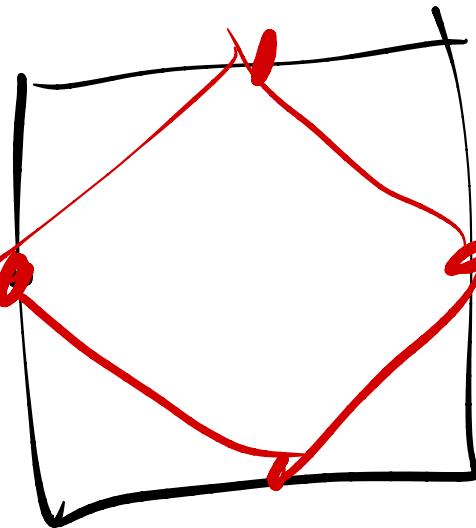
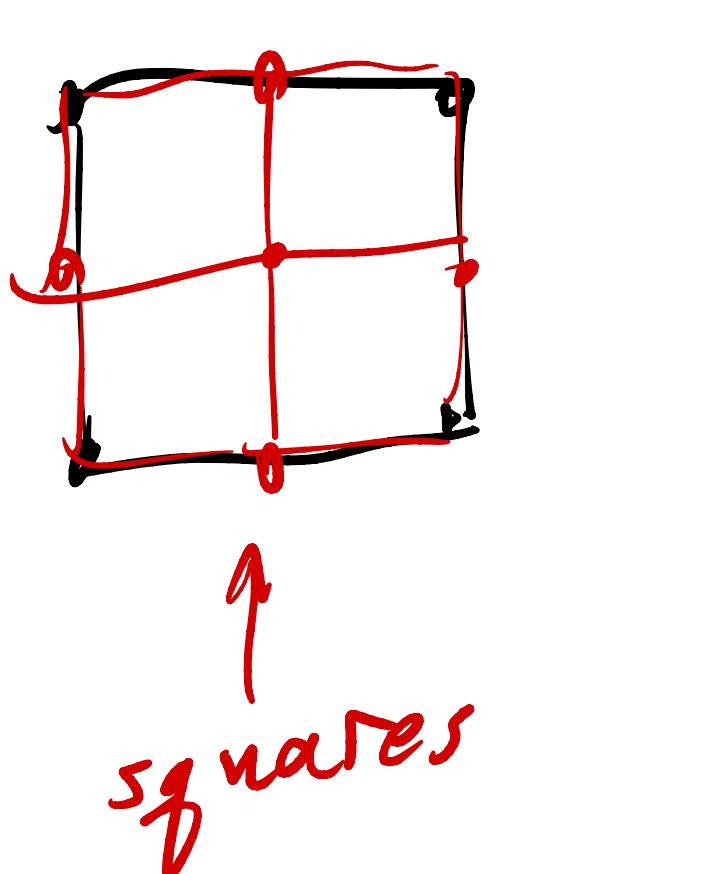
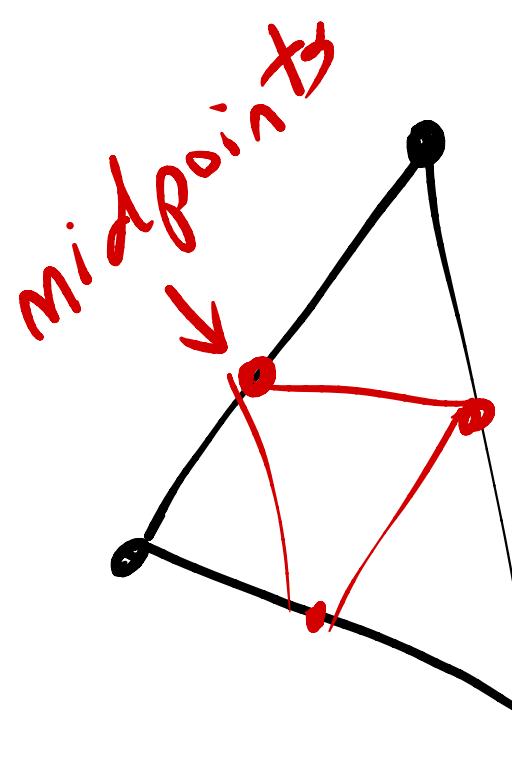
$$\text{new } V = \frac{1}{5} (V_1 + V_2 + V_3 + V_4 + V_5)$$





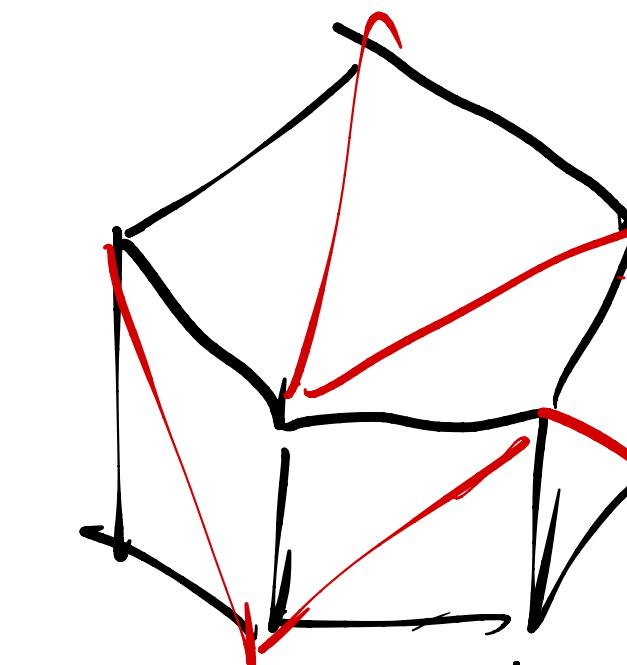
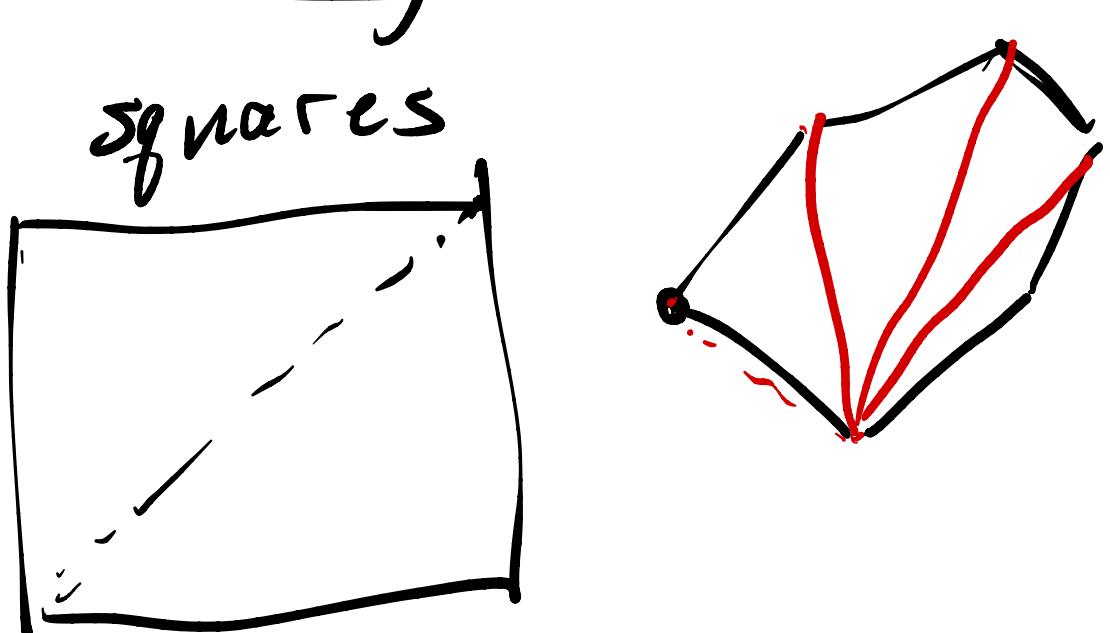
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Face subdivision

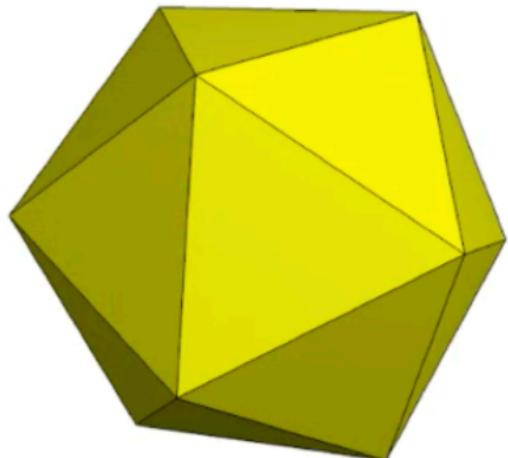


square + triangles

Triangulation

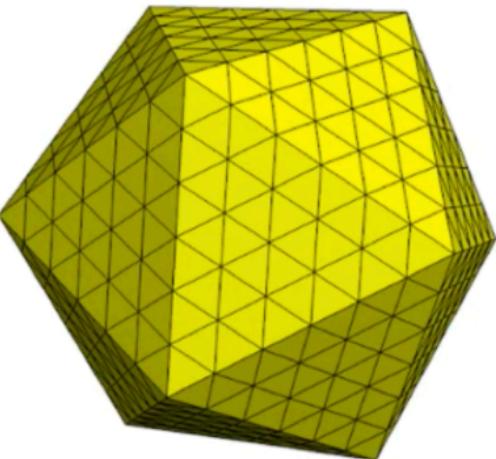


pentagonal
prism



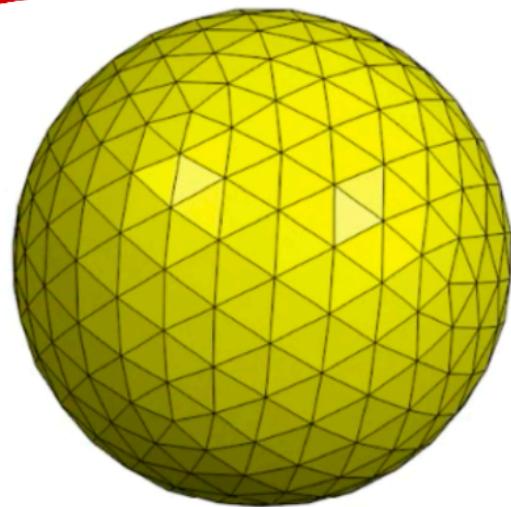
Icosahedron

+

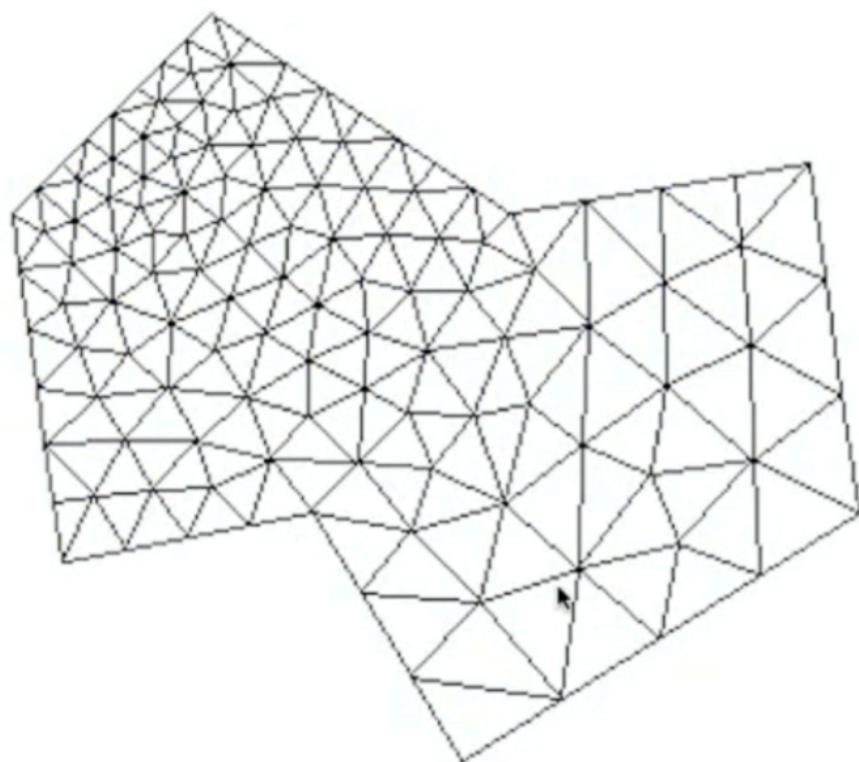
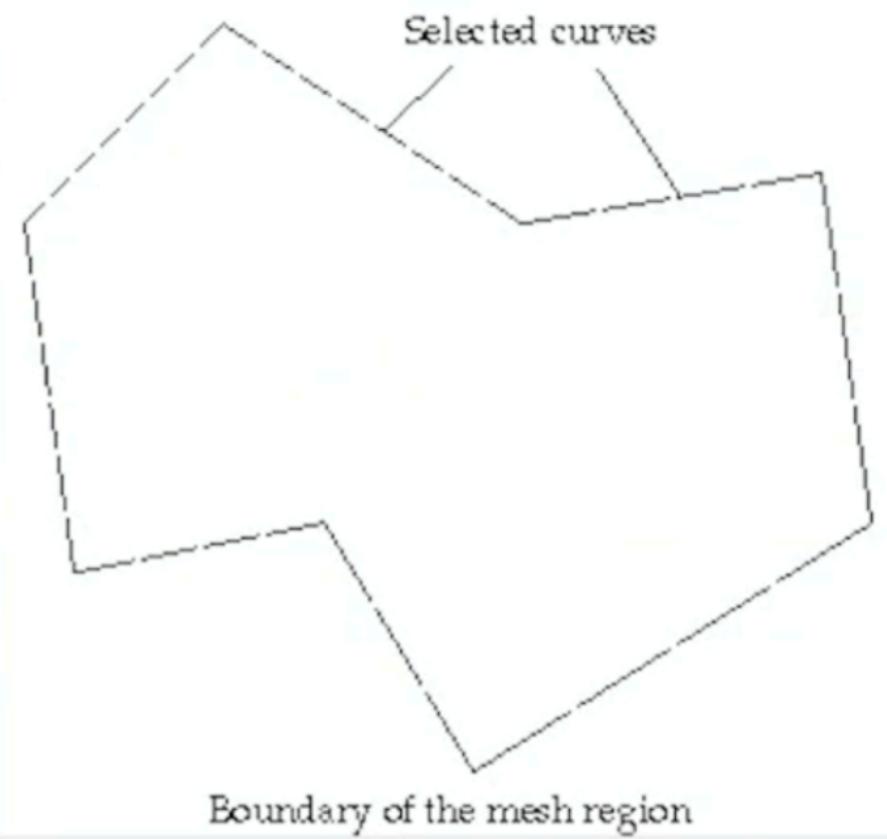


6-frequency
subdivision

Normalize new vertices
(assuming unit sphere)



Vertices projected
onto sphere



Representing Polyhedra (Meshes)

Polygon Soup

class Face {

float $x_1, y_1, z_1;$

float $x_2, y_2, z_2;$

float $x_3, y_3, z_3;$

each polygon is represented by itself

class polyhedra {

face[] : faces

}

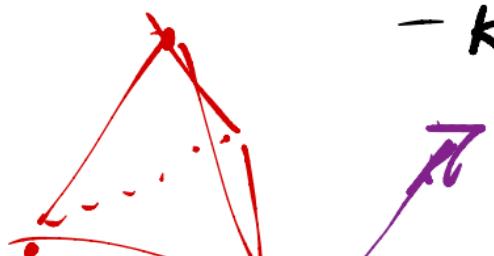
files
- .stl

³ polyhedra is a list of faces

Shared Vertices / Indexed face set
→ hardware supports soup or indexed set

• obj \leftarrow implicit indices

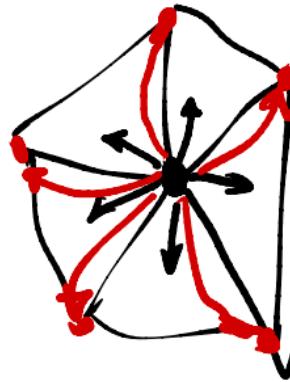
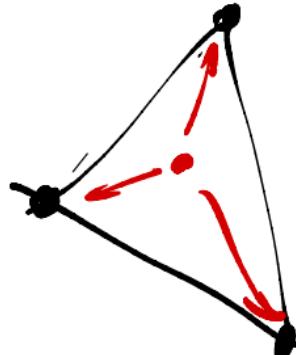
| v | -1 | -1 | -1 |
|---|----|----|----|
| v | 1 | 1 | -1 |
| v | 1 | -1 | 1 |
| v | -1 | 1 | 1 |
| f | 0 | 1 | 2 |
| f | 0 | 2 | 3 |
| f | 0 | 1 | 3 |
| f | 1 | 2 | 3 |



- More compact
- know about shared vertices
- ↳ structure

Vertices, faces, References

.face



```
class Vertex {  
    float x, y, z;  
    float nx, ny, nz;  
    vertex[] vertices;  
    face[] faces;
```

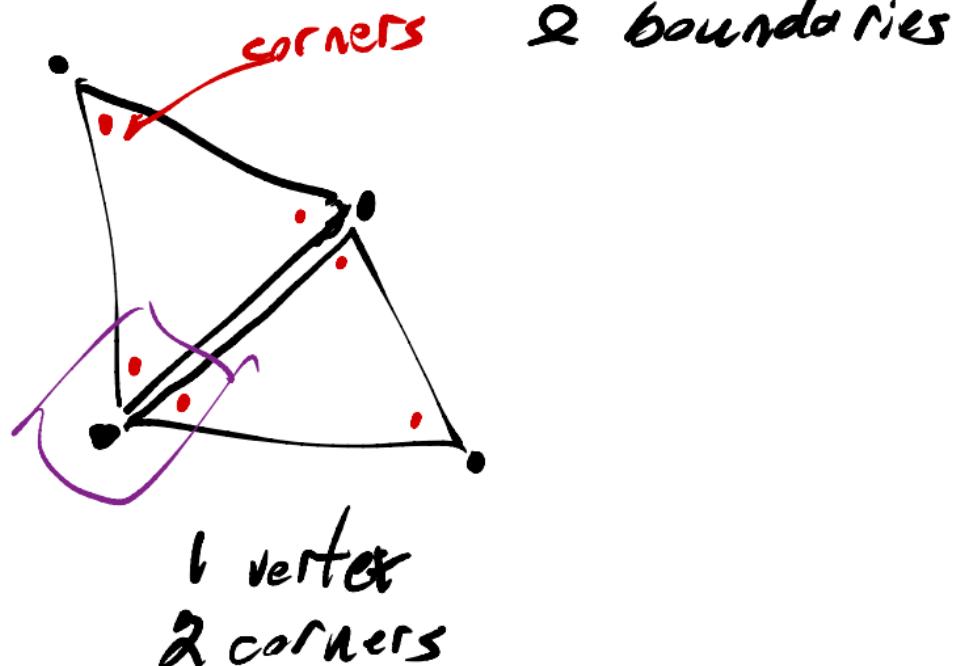
lots of repetition
of data

corner representation — Jarek Rossignac

- only works for triangles
- assumes manifold surface → but it can handle holes & boundaries

Geometry Table

| | x | y | z |
|----|---|---|---|
| V0 | . | . | . |
| V1 | . | . | . |
| V2 | . | . | . |
| ⋮ | | | |

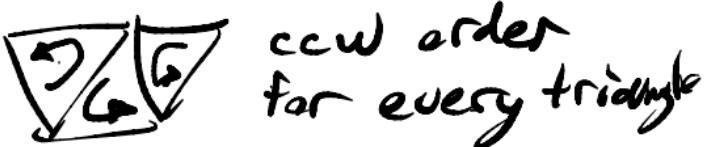


(c)

Vertex Table

Corners are implied indices into geometry

| | | |
|---|---|------------|
| 0 | 0 | triangle 0 |
| 1 | 1 | |
| 2 | 2 | triangle 1 |
| 3 | 1 | |
| 4 | 0 | triangle 1 |
| 5 | 3 | |
| 6 | : | triangle 1 |
| i | ; | |



- triangle num

$$c.t = \underbrace{< \text{div } 3}_{\text{int}}$$

- next corner

$$c.n = 3 * c.t + (c+1) \% 3$$

- previous corner

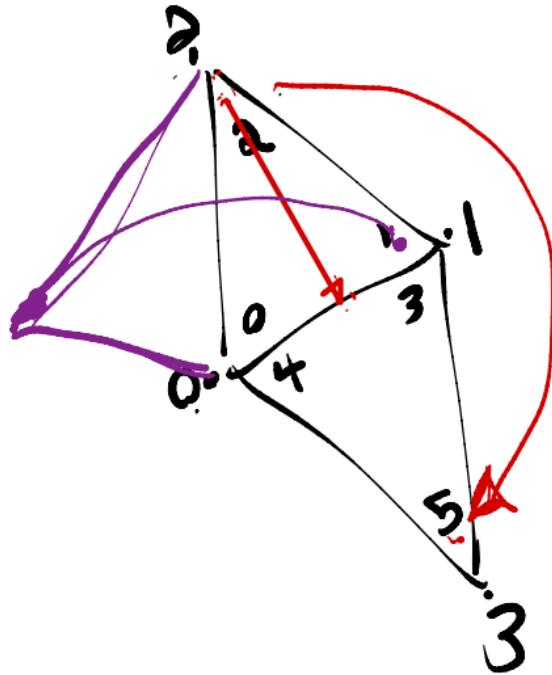
$$c.p = c.n - 1$$

Adjacency using Opposite Table.

$\Delta 0$

| V | Q |
|---|---|
| 0 | 7 |
| 1 | 8 |
| 2 | 5 |
| 1 | 9 |
| 0 | 6 |
| 3 | 2 |
| : | |

$\Delta 1$



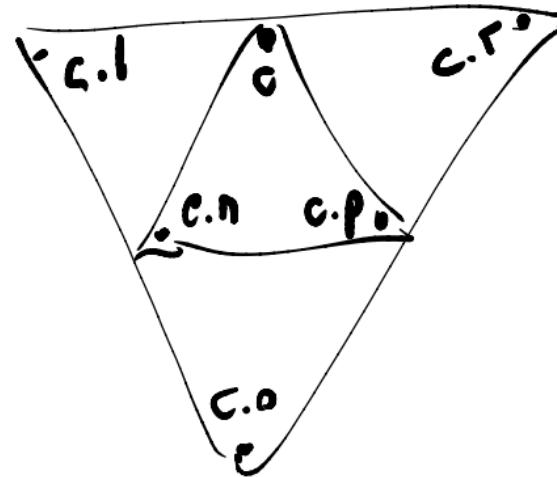
C.O looks
up
opposite

c.o \rightarrow opposite

right neighbor
left neighbor

swing

$$\begin{aligned} c.r &= c.n.o \\ c.l &= c.p.o \\ c.s &= c.n.o.n \end{aligned}$$



Subdivision Surfaces

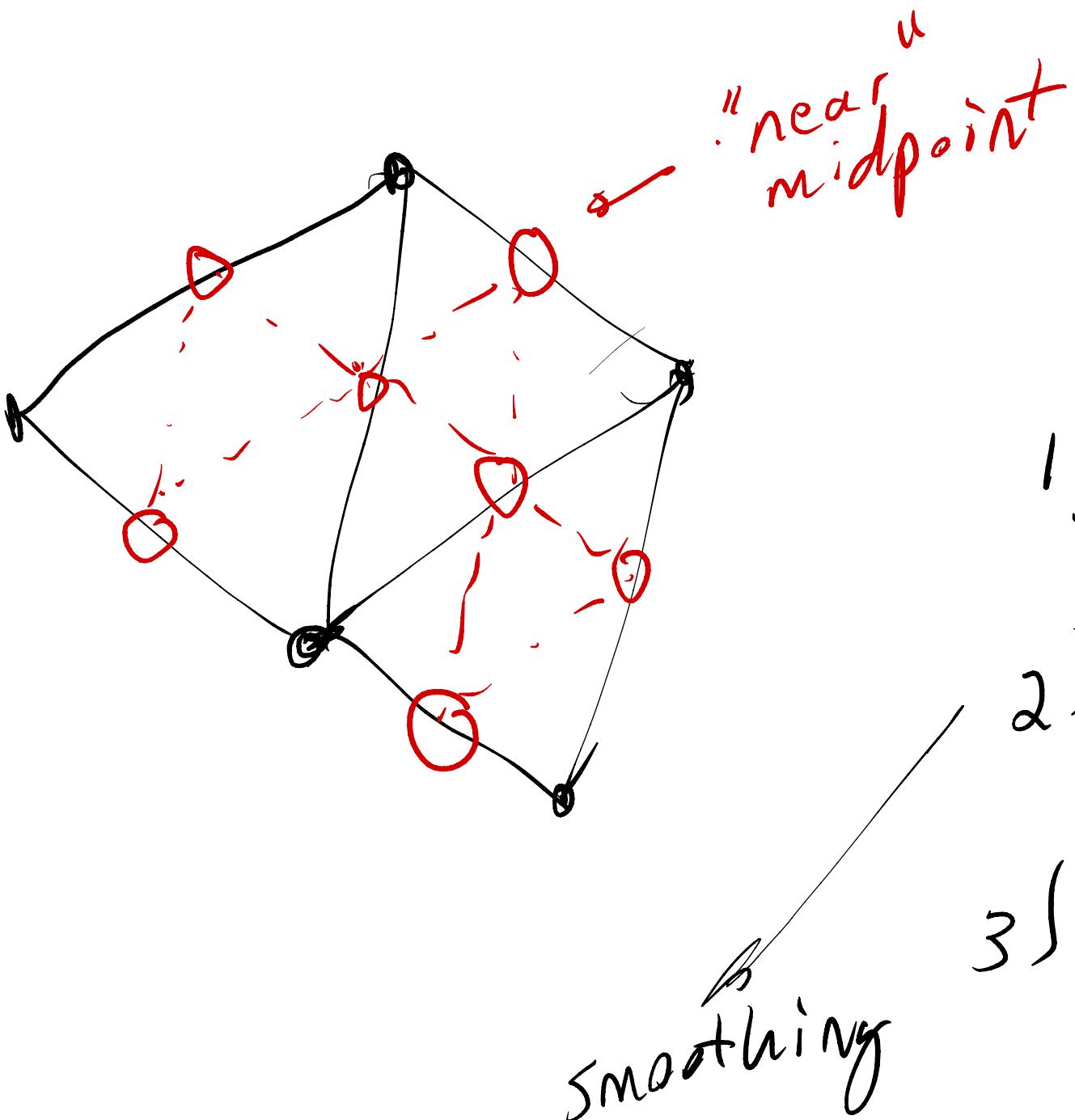
spline / etc (smooth) surfaces have issues

- must subdivide into patches
- continuity between patches

Alternative: Subdivision surfaces

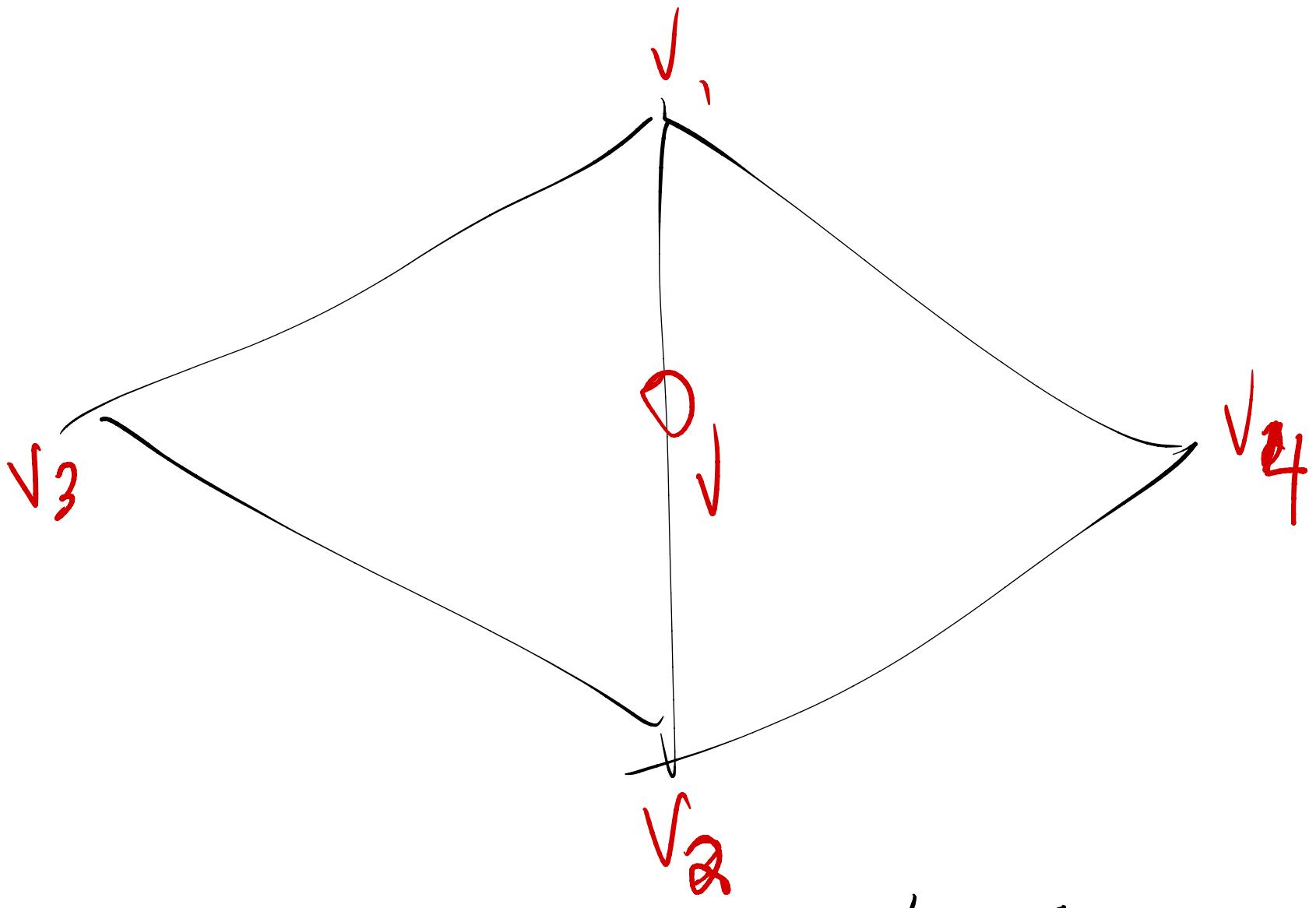
- take triangle (polygon) mesh convert into a smooth
- simple to program

Loop scheme (Triangles) \rightarrow well with corner representation



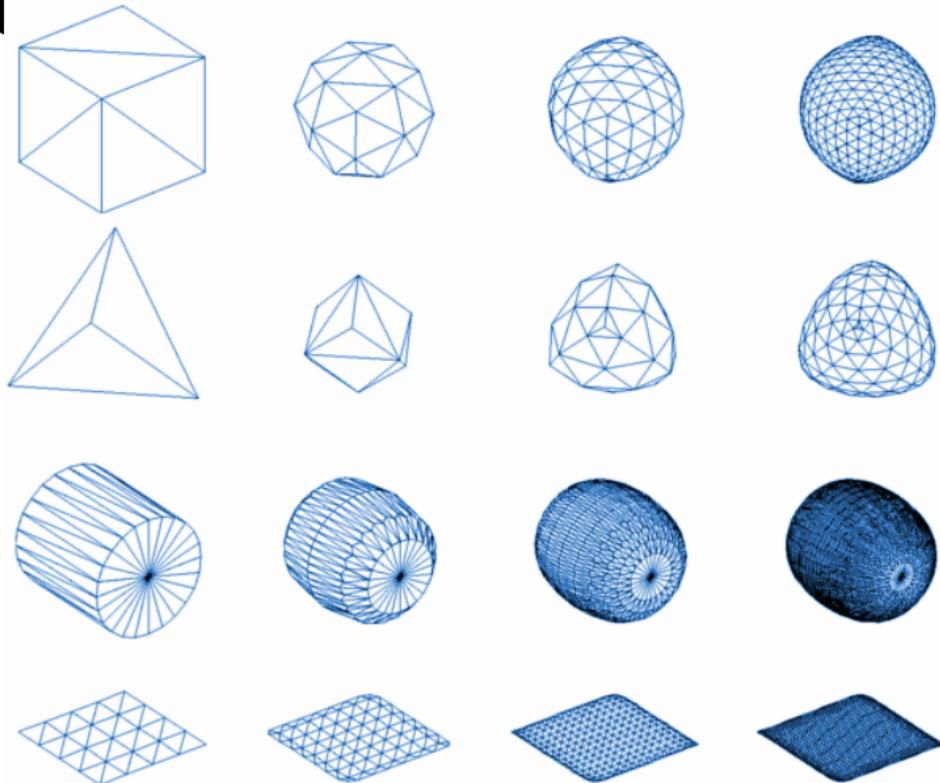
Subdivision:

- 1) compute location new vertices
- 2) move old vertices.
- 3) Make new triangles

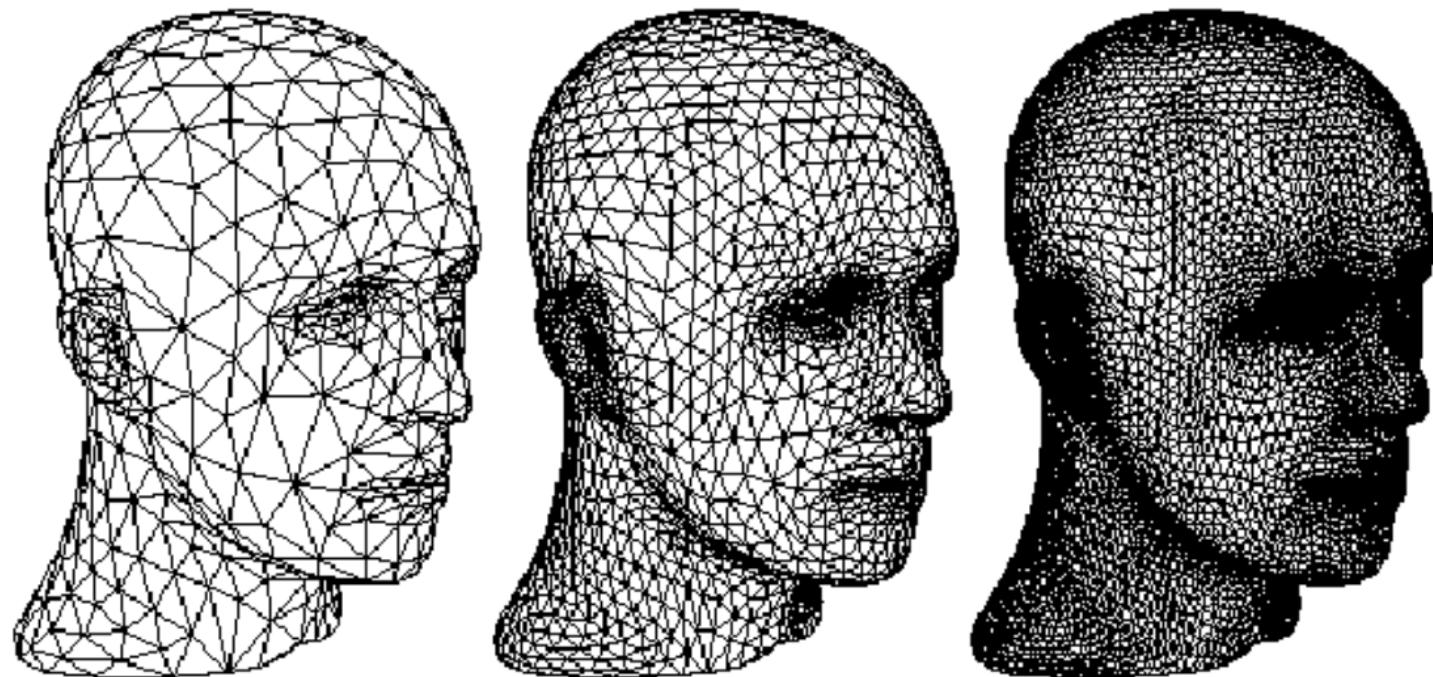


$$v = \frac{3}{8} (v_1 + v_2) + \frac{1}{8} (v_3 + v_4)$$

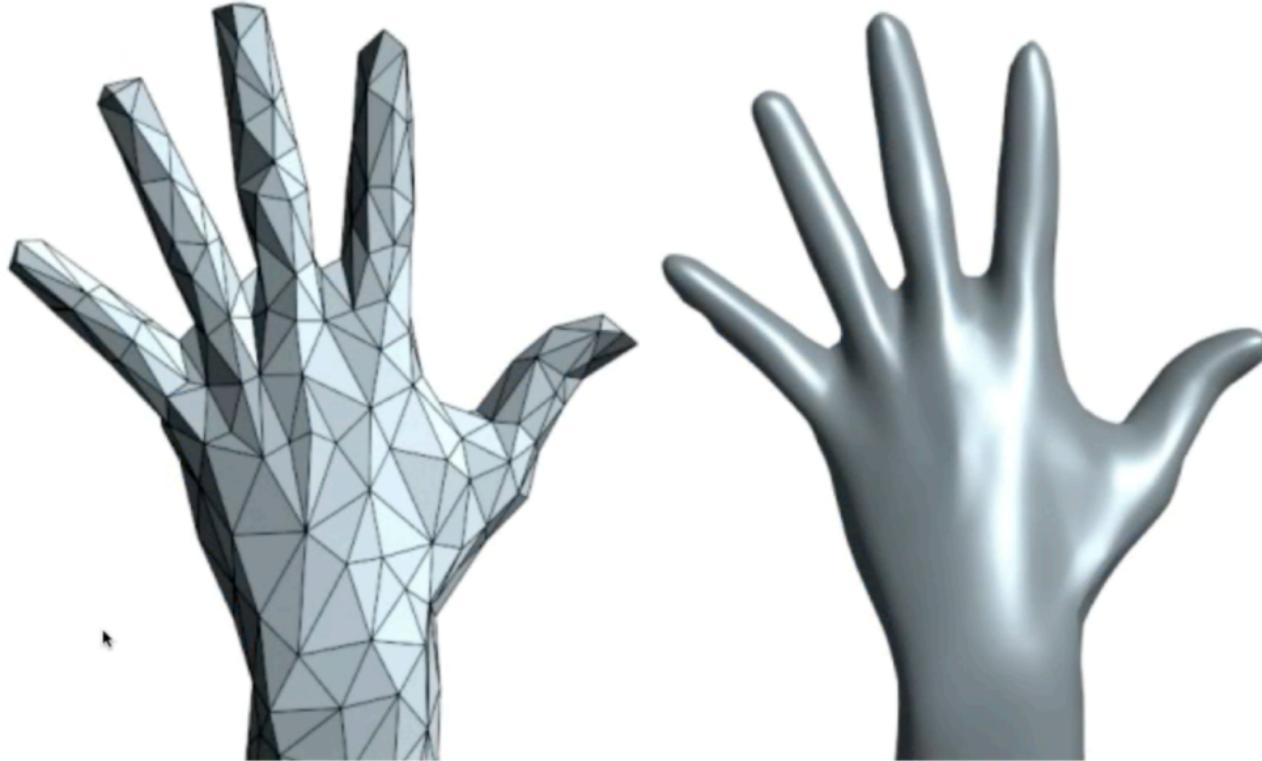
Loop Subdivision



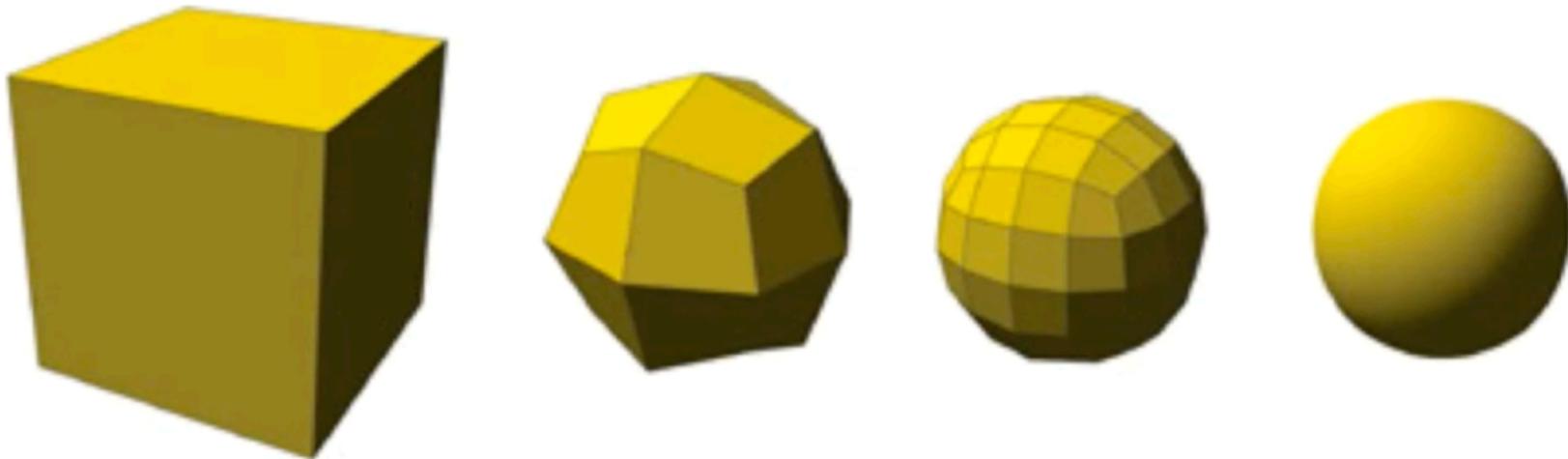
Face Subdivision



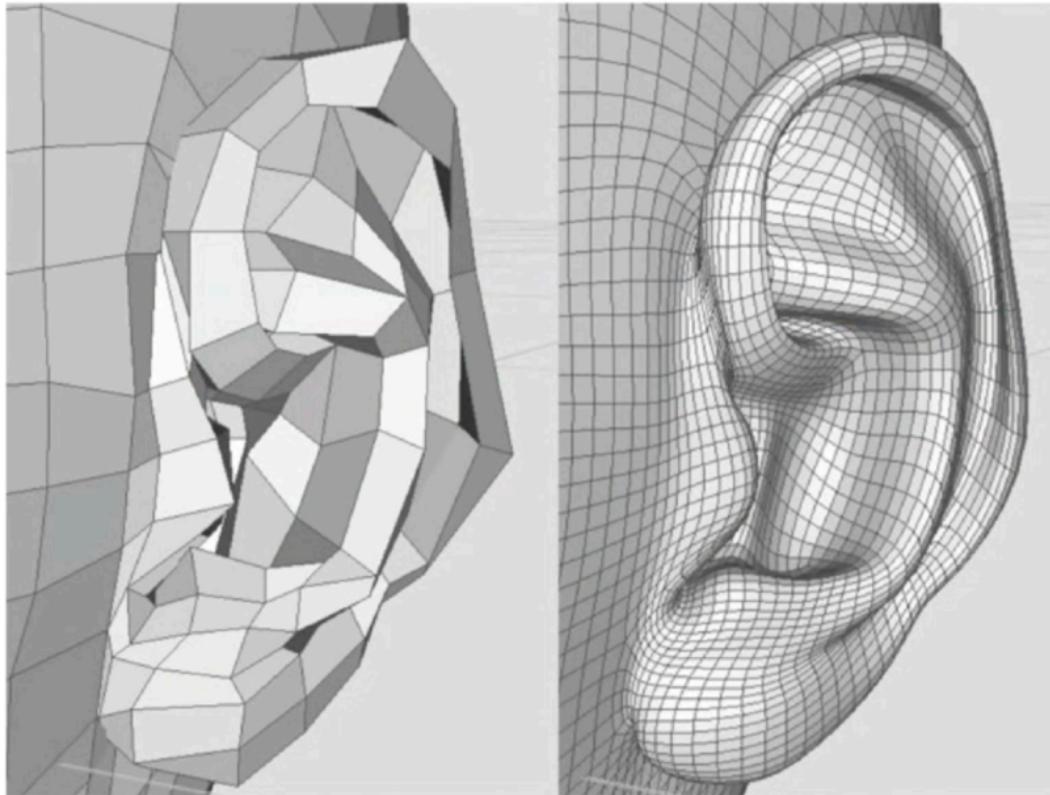
Local Subdivision



Catmull-Clark Subdivision



Catmull-Clark Subdivision



Catmull-Clark Subdivision: Sharp Edges

