

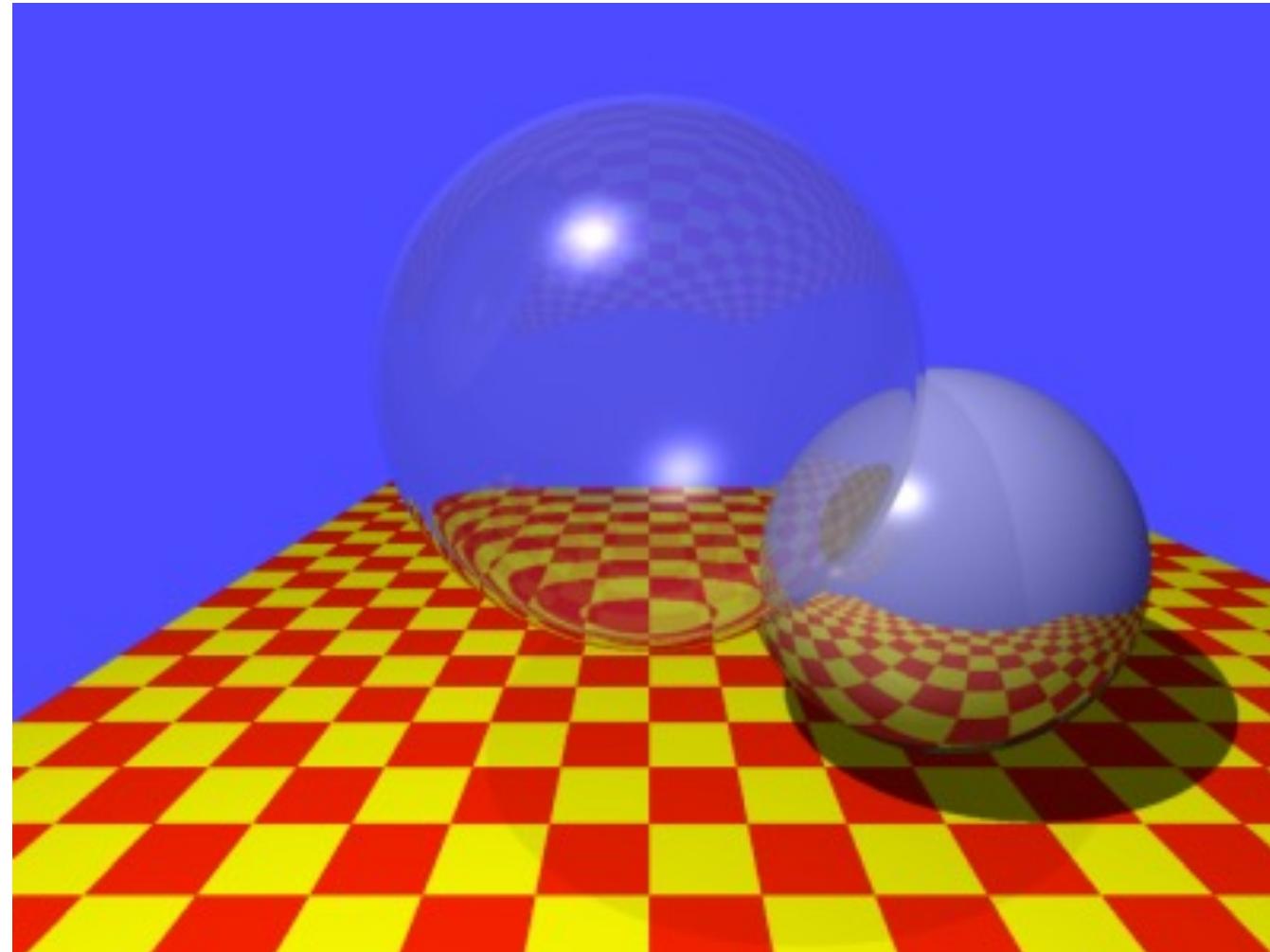
13 – raytracing (1)

3 approaches to graphics

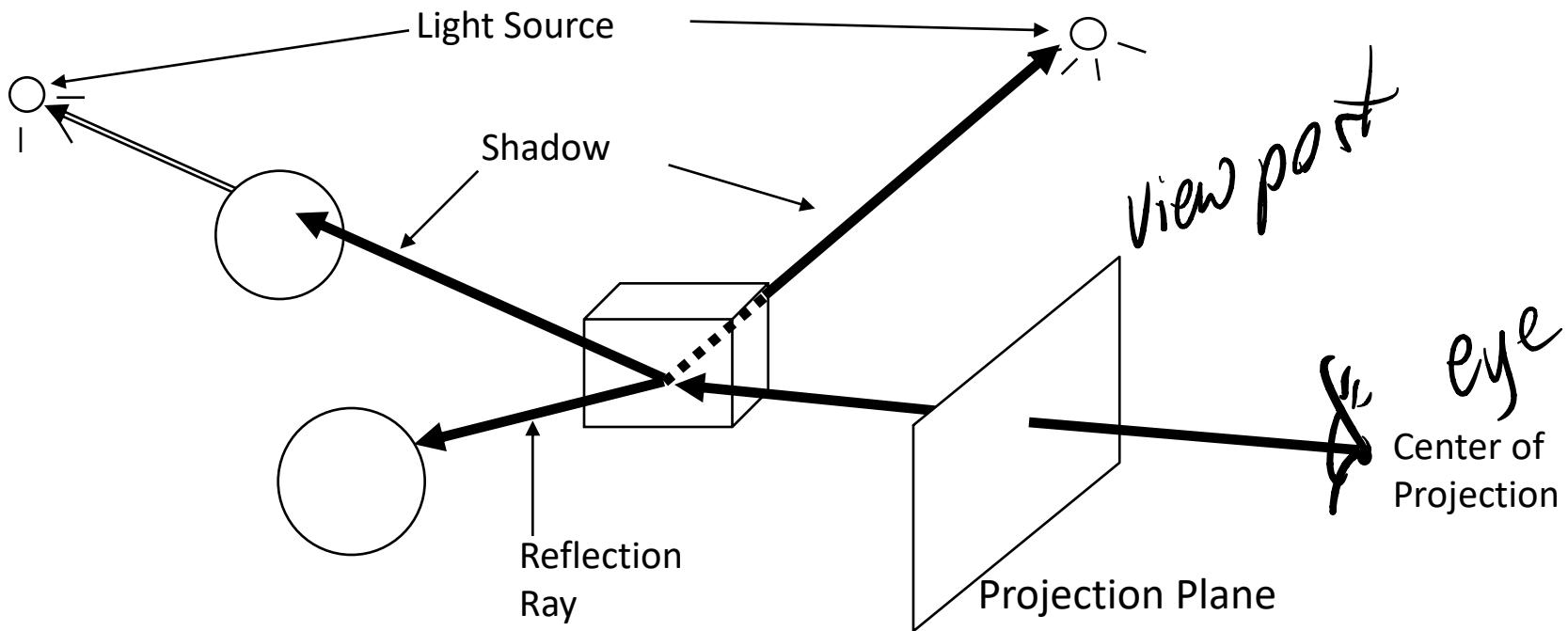
- On-line / “real-time” *WebGL in general*
 - Immediate mode
 - Raw WebGL calls
 - Retained mode / Scene Graphs/etc
- Off-line / batch / “slow”

Ray Tracing 1980's a way to deal with shadows
hidden surfaces

Whitell



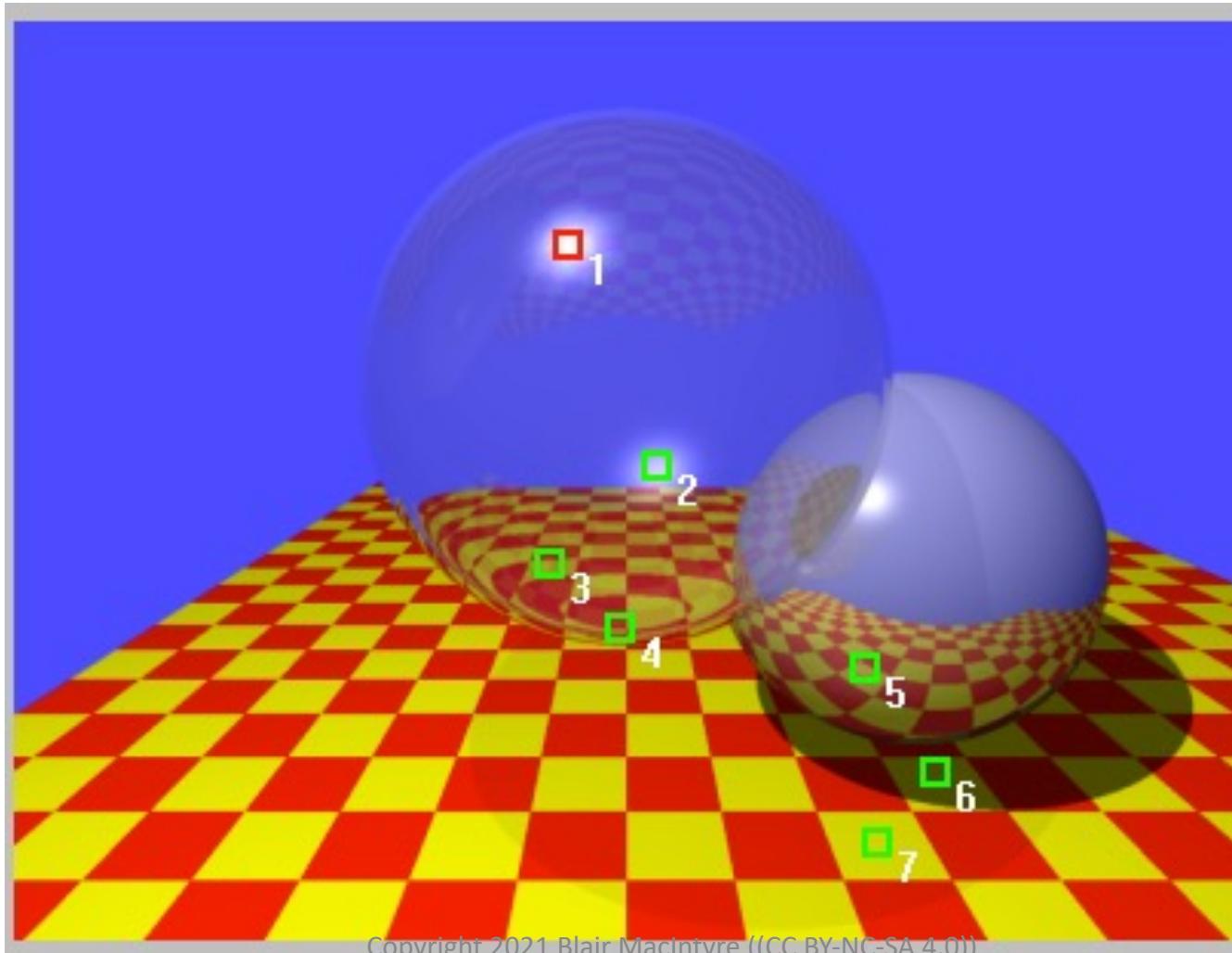
Basic Idea



Basic Algorithm

```
for each pixel  $(x_s, y_s)$ 
    create a ray  $R$  from eye through  $(x_s, y_s)$ 
    for each object  $Q_i$  in scene
        if  $R$  intersects  $Q_i$  & it's the closest
            so far
            record this intersection
    shade pixel based on nearest intersection
        (recursively for ref & transmission)
```

The Adventures of 7 Rays



Basic Algorithm

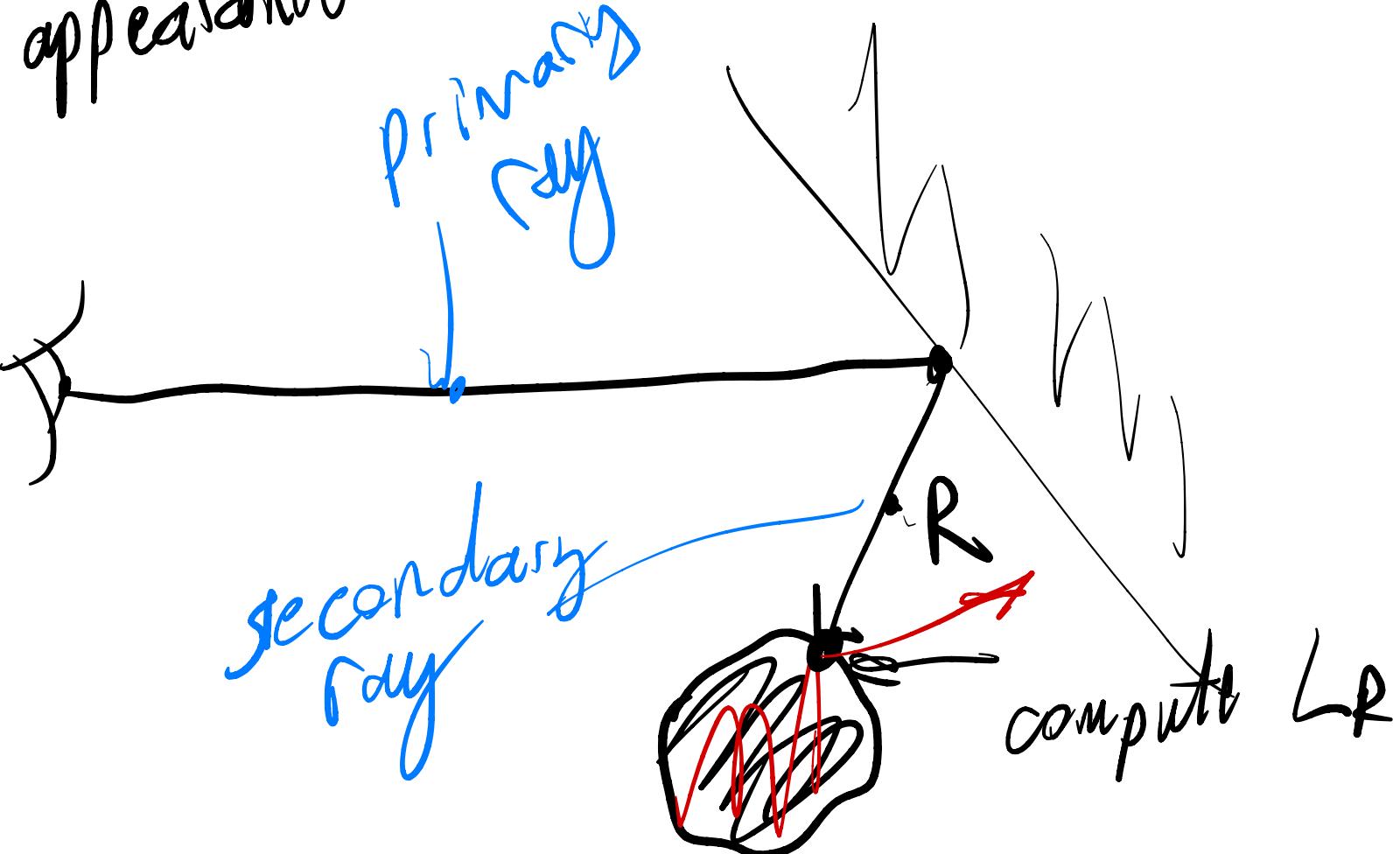
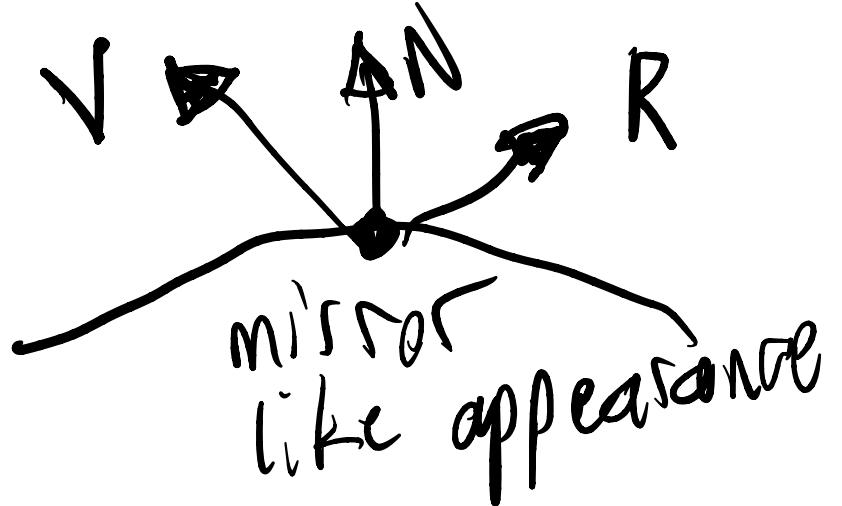
Illumination of a point

$$I = k_a I_a + k_s L_r + k_d L_f + \sum_{1 \leq i \leq N} S_i I_i [k_d (N \cdot L_i) + k_s (R_i \cdot V)^{p_i}]$$

ambient *reflected* *refracted*

previous eq

$$S_i = \begin{cases} 0 & \text{if shadow ray (light ray) is blocked} \\ 1 & \text{if not blocked (creached light)} \end{cases}$$



ambient + diffuse + specular + $k_r L_r + k_f L_t$

how reflective?

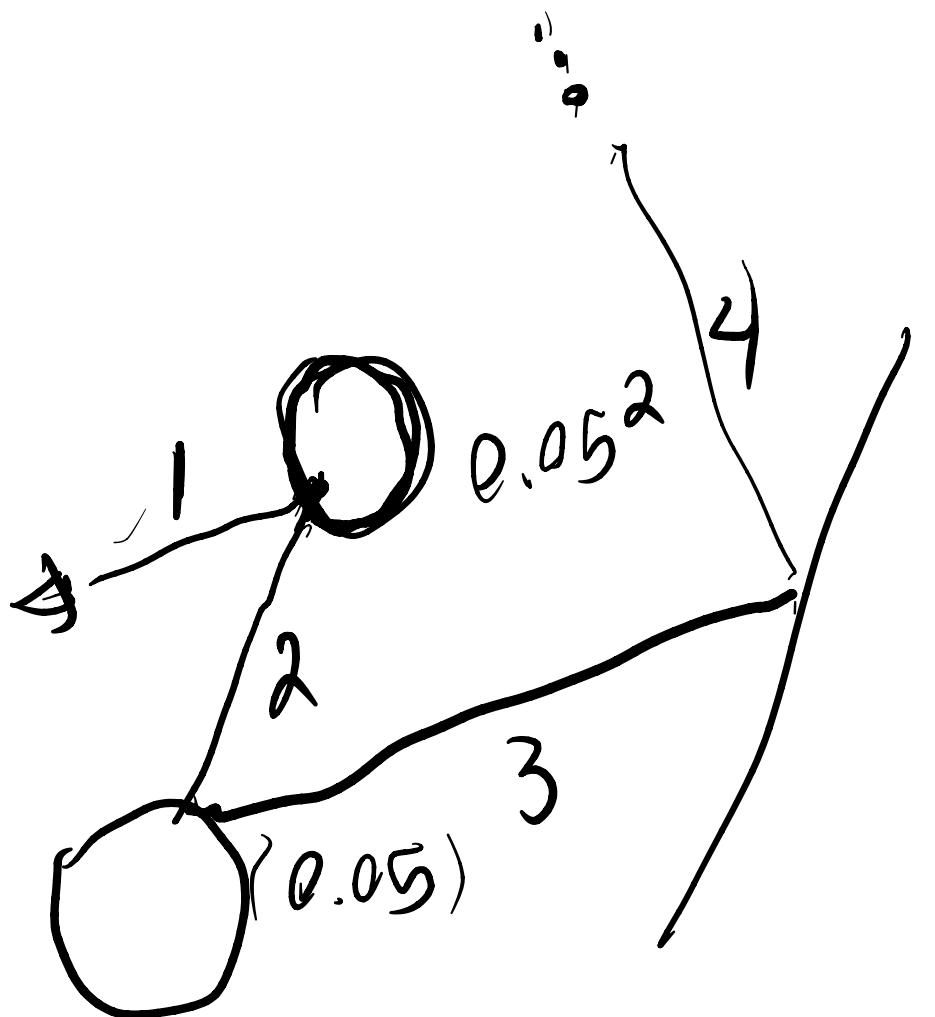
↑

how trans

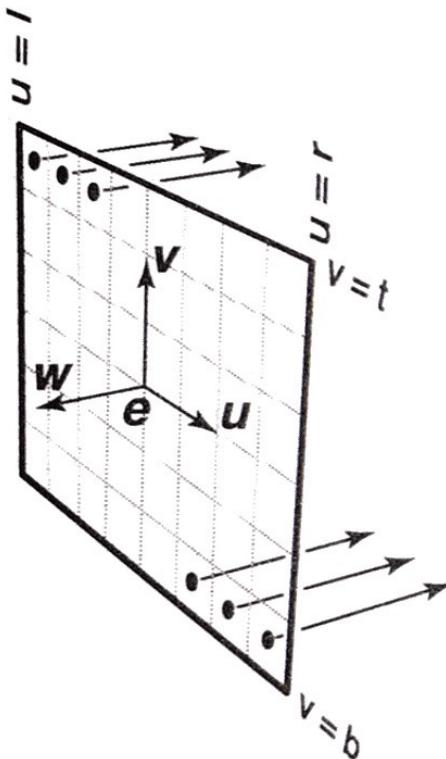
shoot Ray(R) $\rightarrow L$

When to stop?

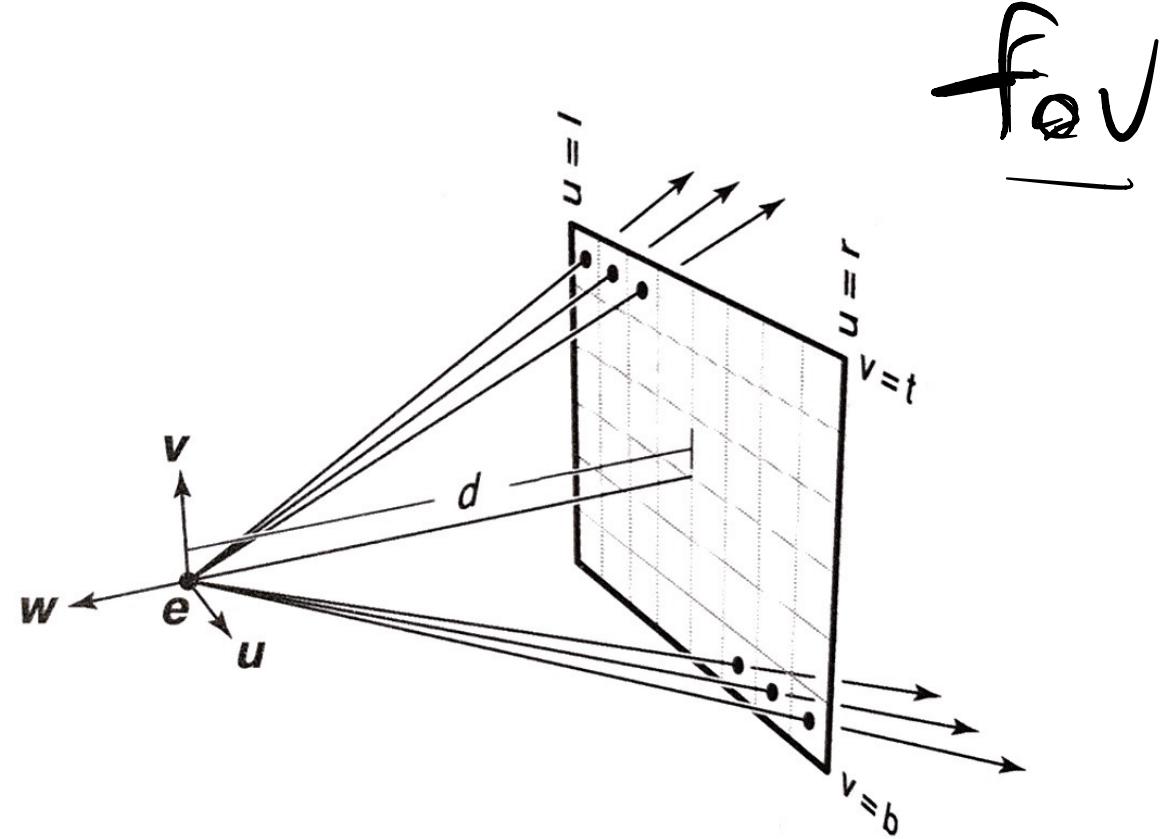
- 1) set max recursive step
- 2) contribution of ray is small



Eye Rays: Depends on Projection (Orthographic, Perspective, Oblique)



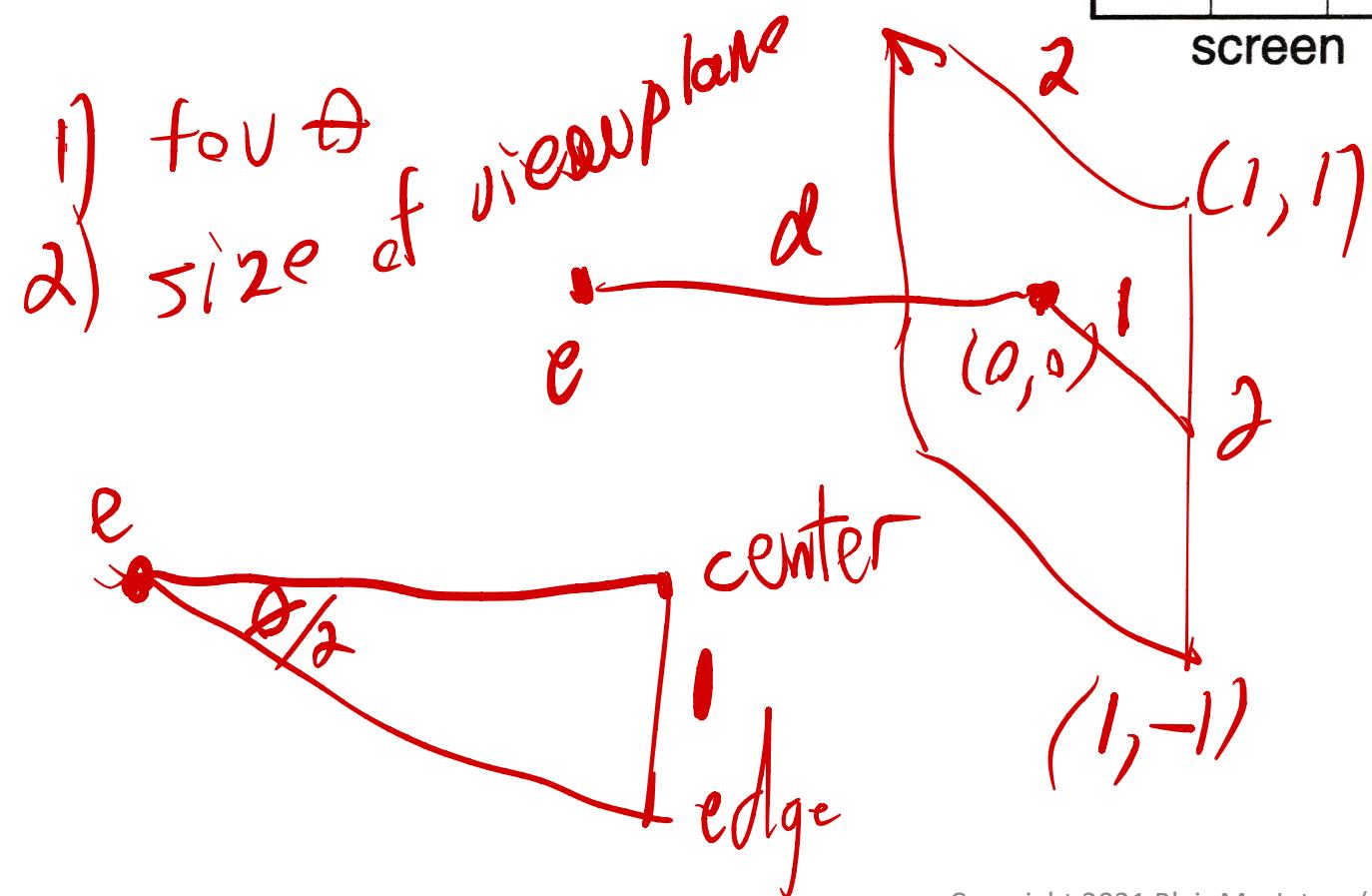
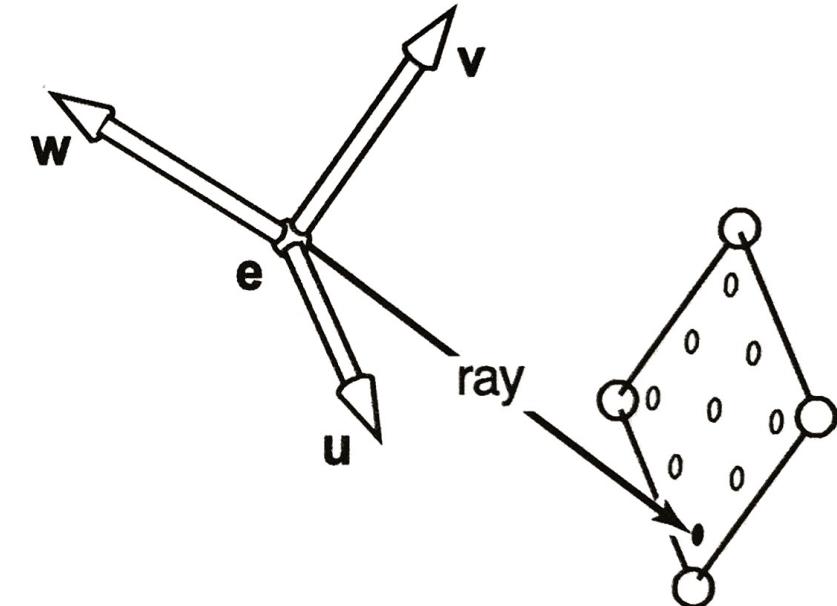
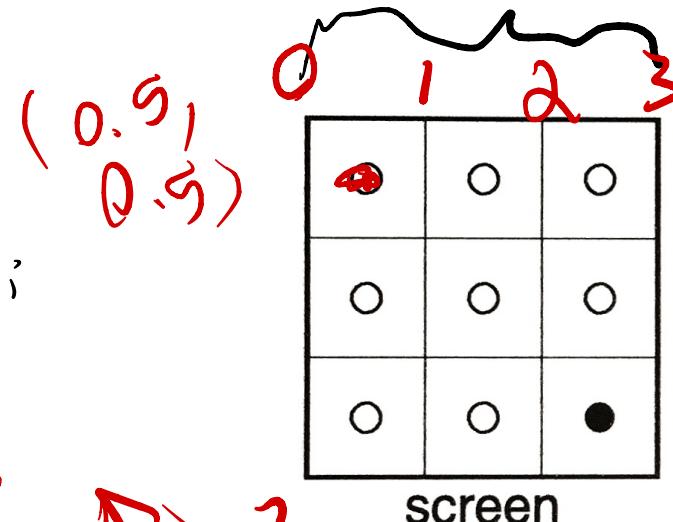
Parallel projection
same direction, different origins



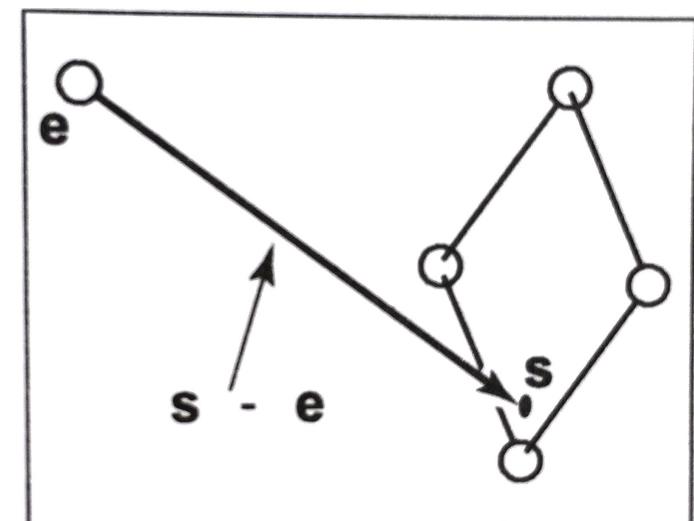
Perspective projection
same origin, different directions

Parametric eq'n:

$$p(t) = e + t(s - e)$$



$$d \Rightarrow \tan\left(\frac{\theta}{2}\right)$$

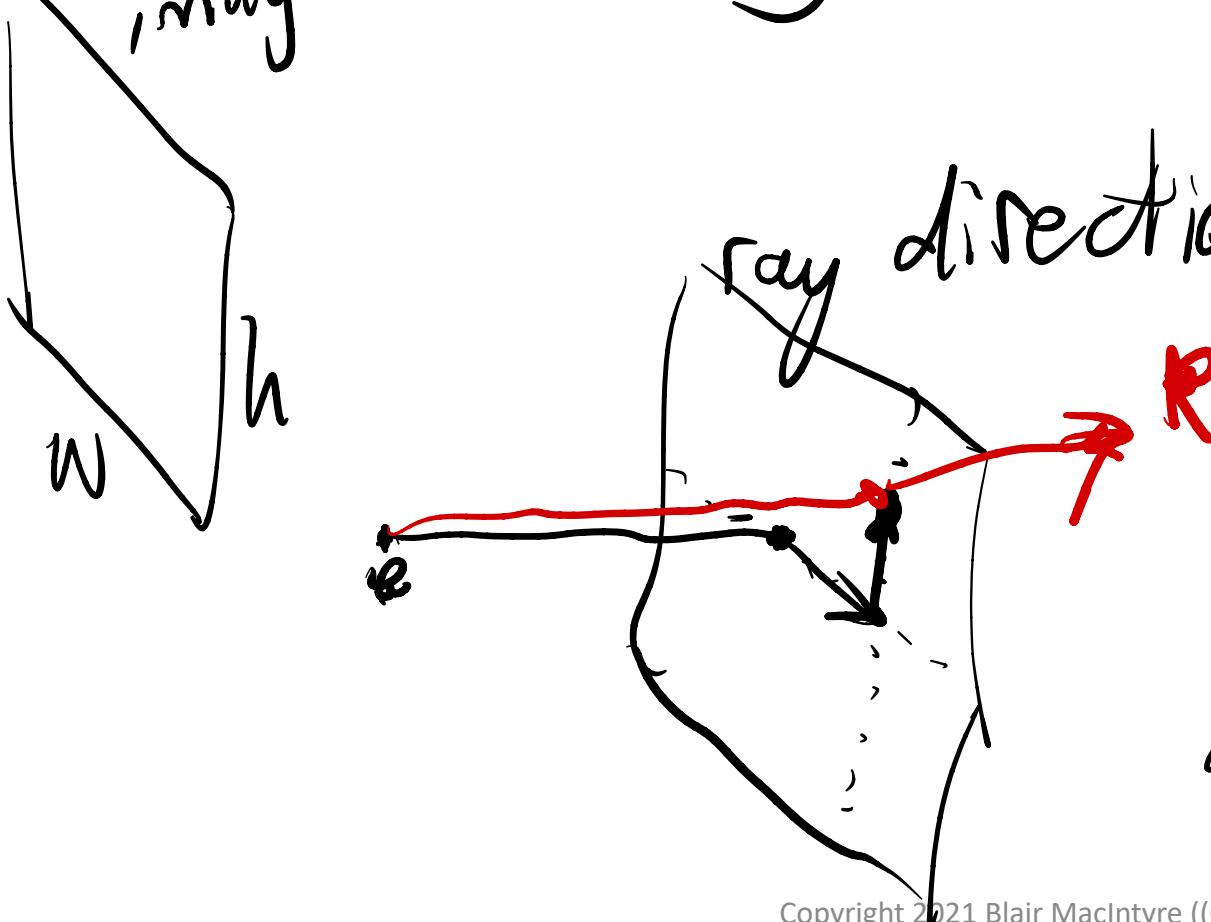


$$u_s = -l + \frac{a_i^w}{h}$$

$$v_s = -l + \frac{a_i^h}{h}$$

for u & v
 $-l \dots i$ range
 u
 v
 w

image



ray direction = $\frac{s - e}{|s - e|}$

= $-dw\hat{u} + u_s\hat{u} + v_s\hat{v}$

origin = e

for $i = 0$ to $w-1$

for $j = 0$ to $h-1$

computeR(u_s, v_s) using (i, j)

shootRay(R)

$j \neq i$

Computing Intersections

different for each object

- sphere is easy
- polygons are easy
- objects mesh (compute per triangle)
- implicit surfaces

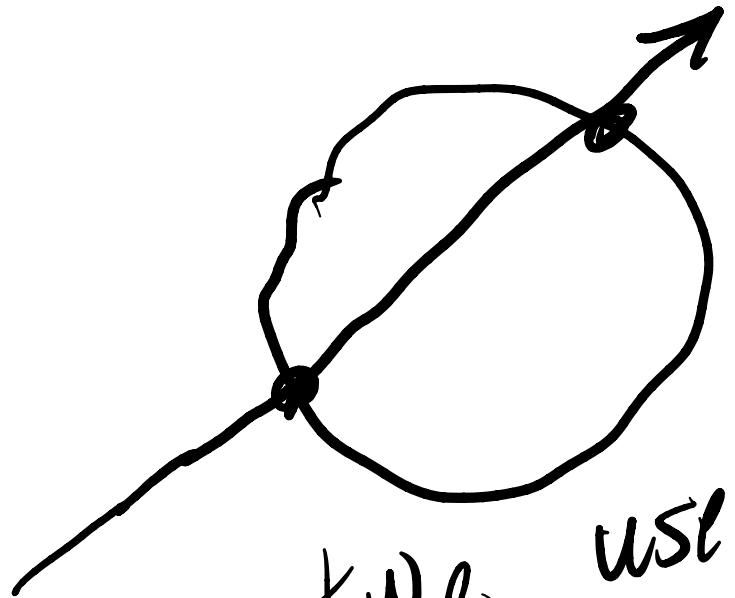
$p(t) = e + td$ $d = 5 - e$ canonical sphere
 Sphere/Ray Intersections center at $(e, 0, 0)$
 radius of 1

$$x^2 + y^2 + z^2 = 1^2$$

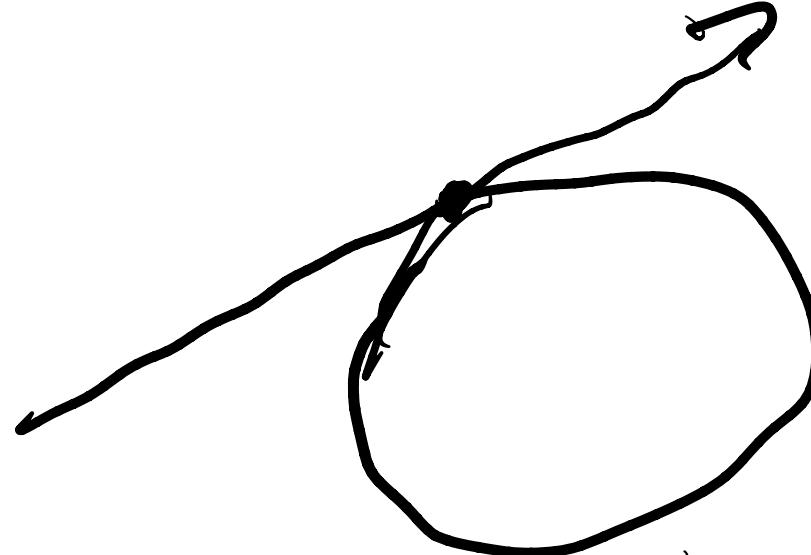
$$(x_e + t dx)^2 + (y_e + t dy)^2 + (z_e + t dz)^2 = 1$$

$$\begin{aligned}
 & t^2(dx^2 + dy^2 + dz^2) + t^2(2(x_e dx + y_e dy + z_e dz) + \\
 & \underbrace{x_e^2 + y_e^2 + z_e^2 - 1}_{c}) = 0
 \end{aligned}$$

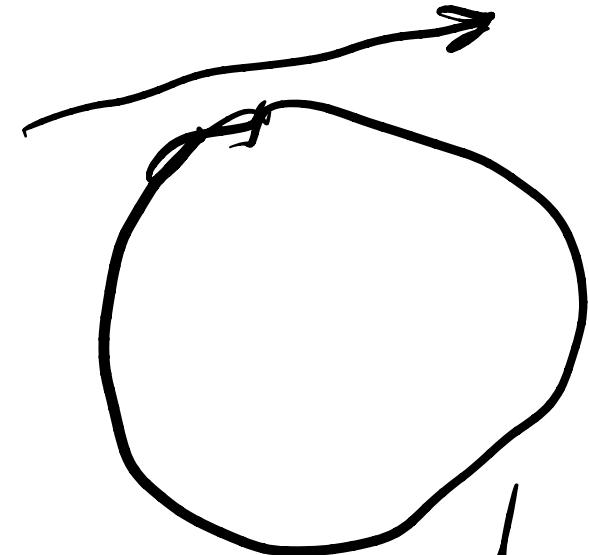
$$t = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$



two, ^{use}
closer



one root



no real
roots

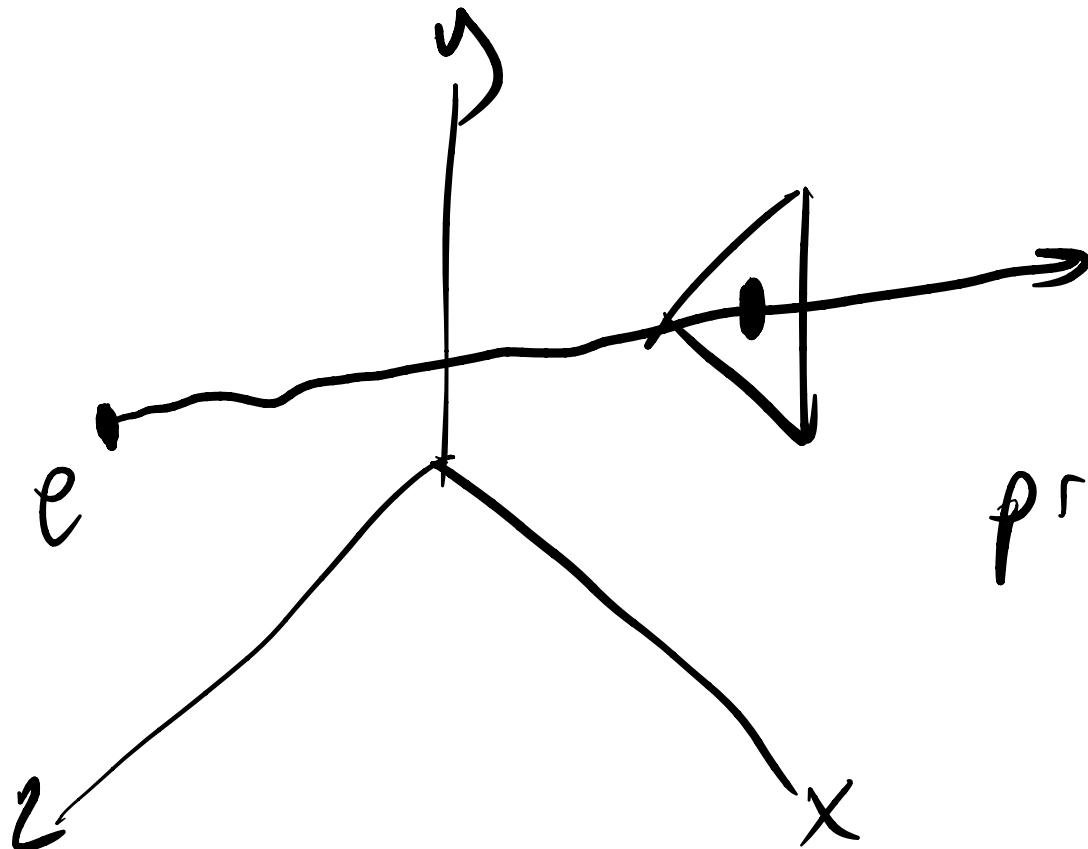
general case

center = (x_c, y_c, z_c)

radius = R

$$(x - x_c)^\alpha + (y - y_c)^\alpha + (z - z_c)^\alpha = R^\alpha$$

Ray/Triangle Intersection

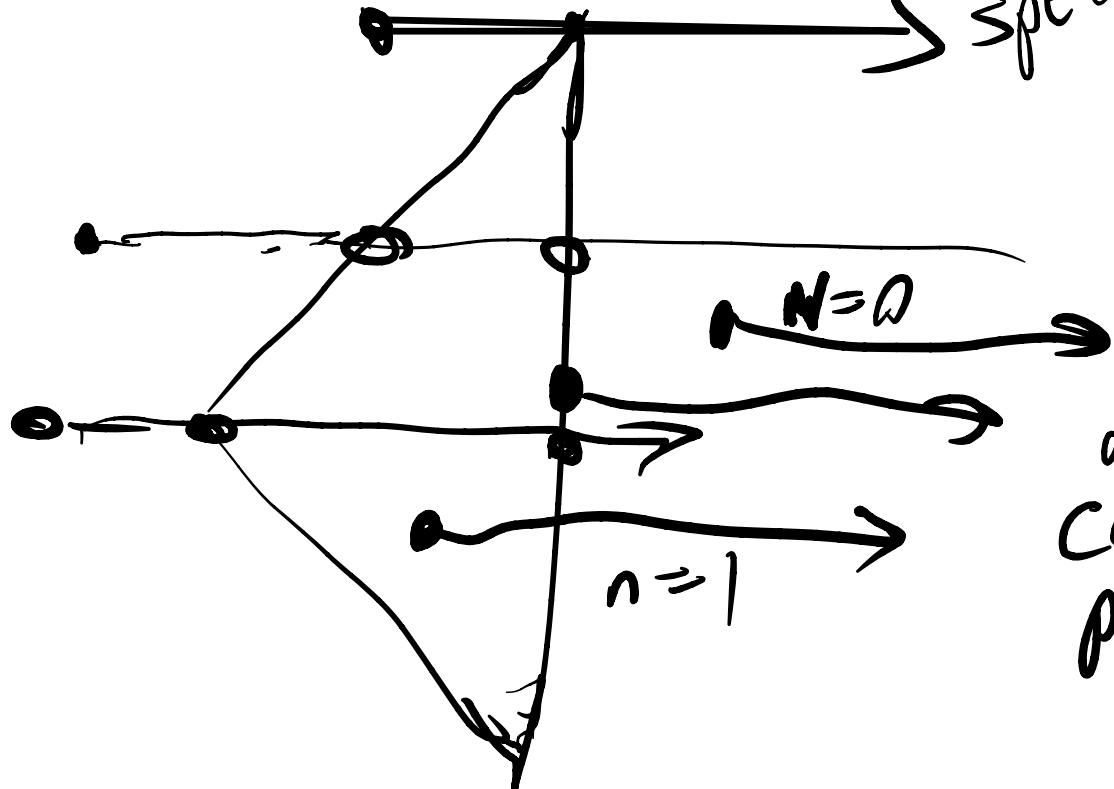


compute intersection
of R with the
plane of the
triangle

project to 2D
 \rightarrow going to xy , xz ,
or yz planes

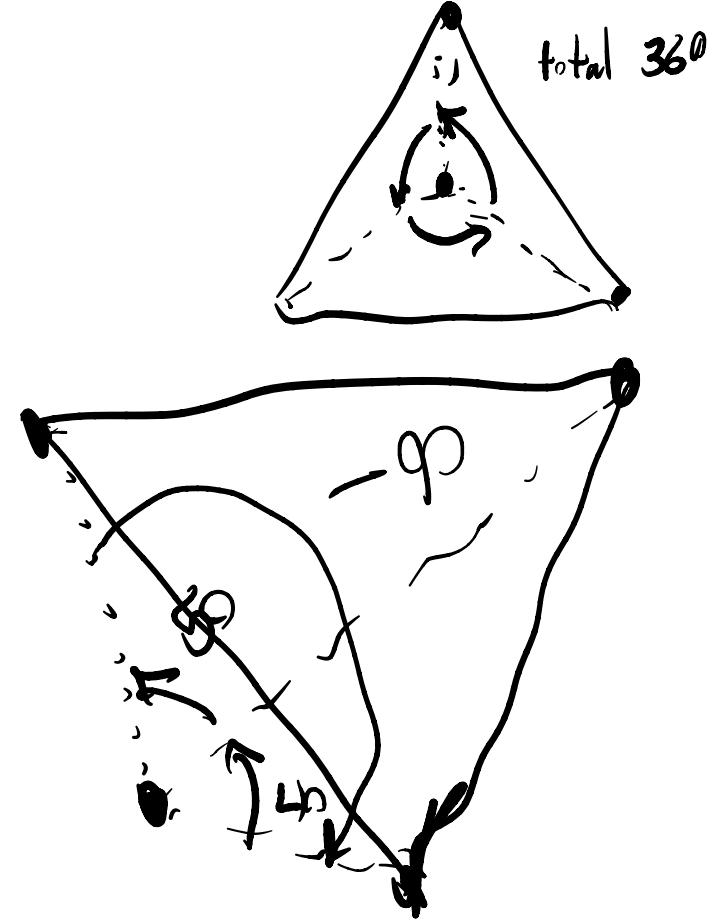
The largest ^{based on} Normal of plane
 (n_x, n_y, n_z)

point in Triangle in 2D
deal with special cases



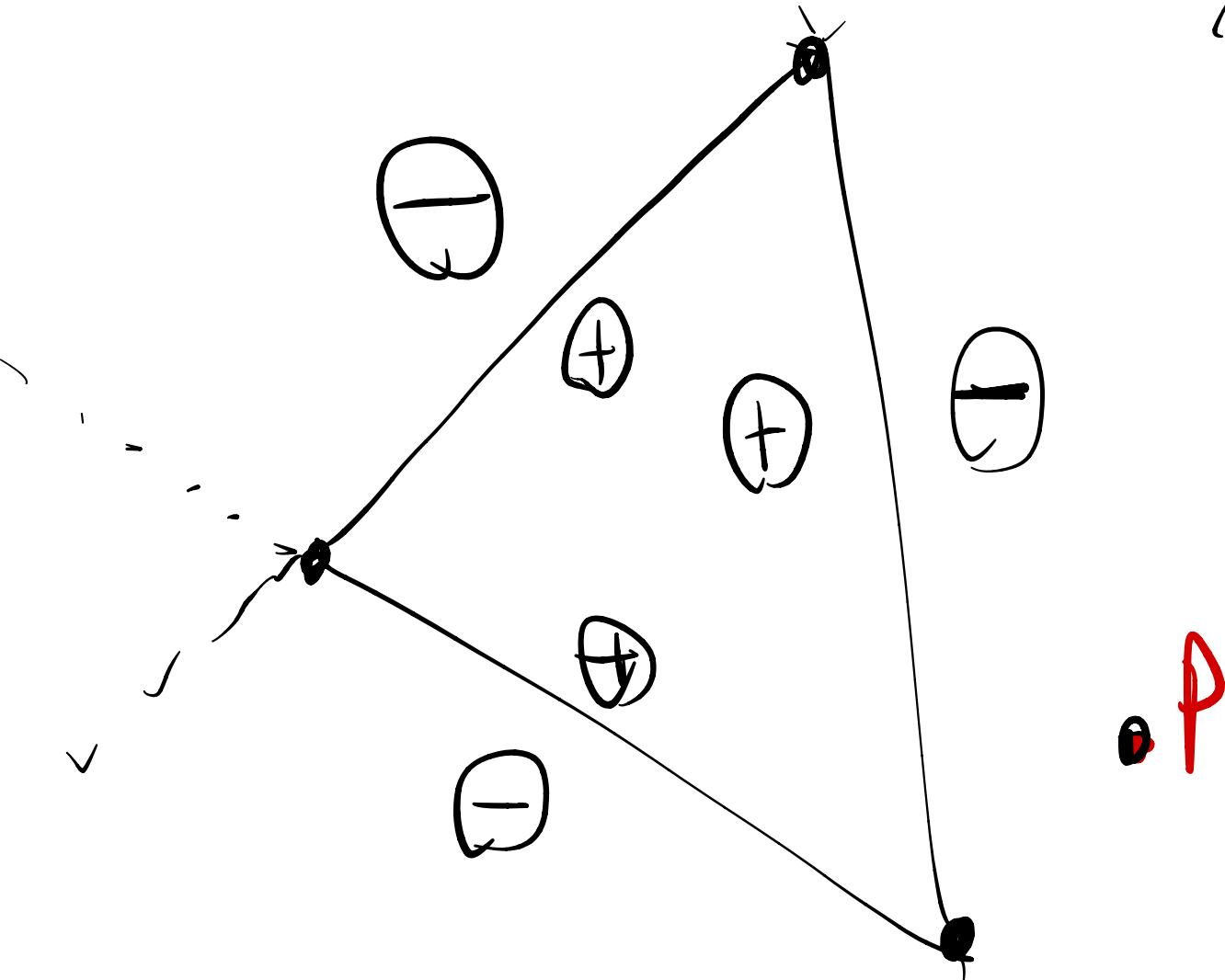
any
convex
polygon too!

even number, outside
odd, inside



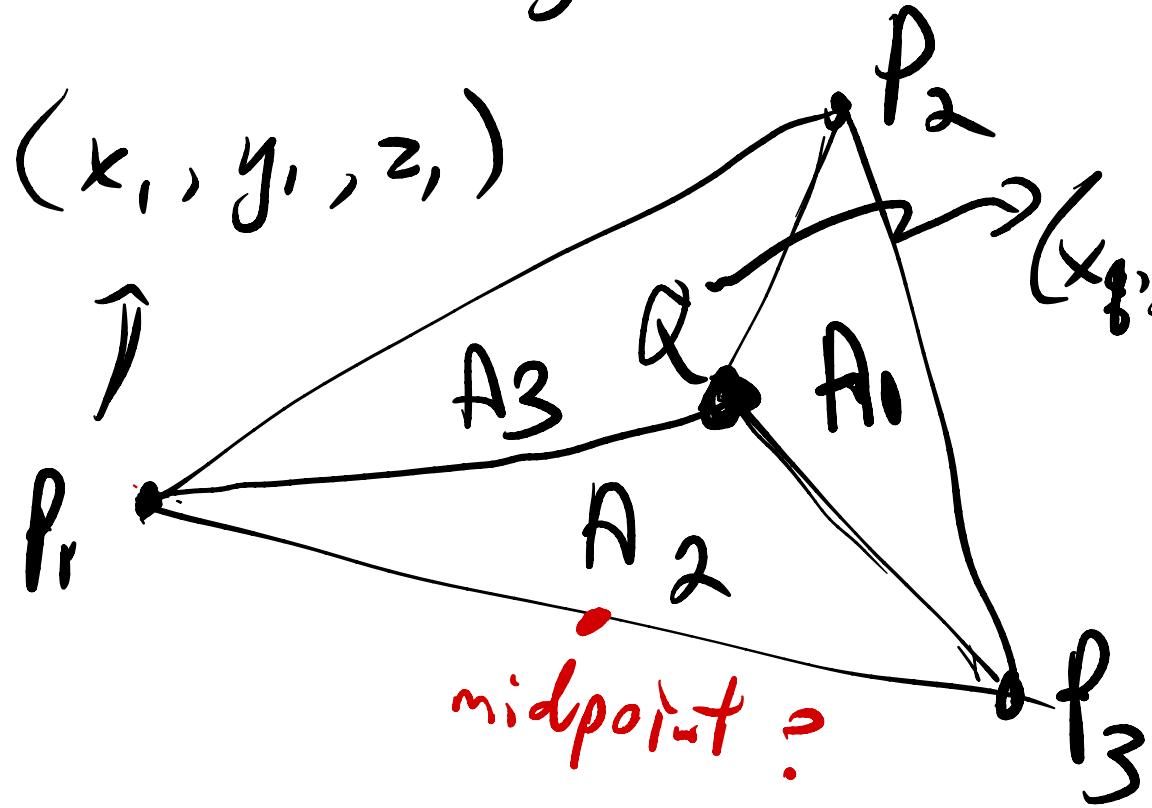
$$40 + 50 - 90 = 0$$

Half-Plane Tests



compute implicit
line equation
for each
line

Barycentric Coordinates



$$Q = \alpha P_1 + \beta P_2 + \gamma P_3$$

A_i = area of sub-triangle opposite f_i
 $(A_2, A_3) \dots$

$$A = A_1 + A_2 + A_3$$

$$\alpha = A_1 / A$$

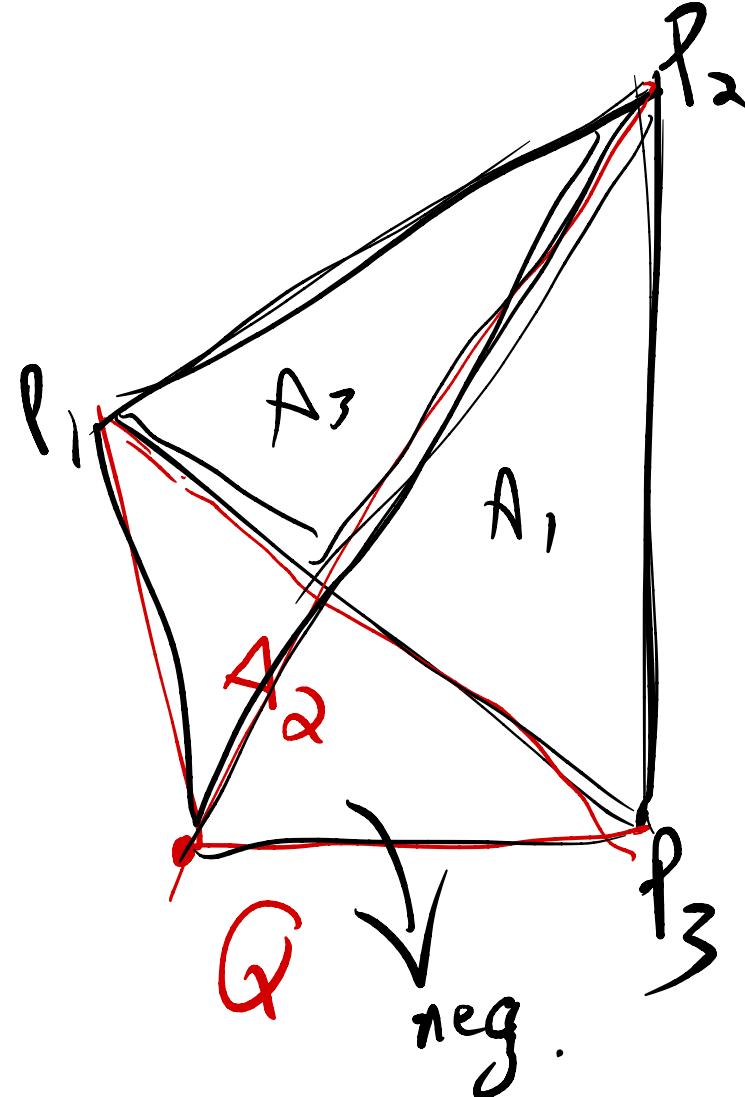
$$\beta = A_2 / A$$

$$\gamma = A_3 / A$$

$$\alpha + \beta + \gamma = 1$$

$$Q = \alpha P_1 + \beta P_2 + \gamma P_3$$

α, β, γ are positive inside tri
one or more negative if point is outside



Computing Plane Intersection: Implicit Line Equation

