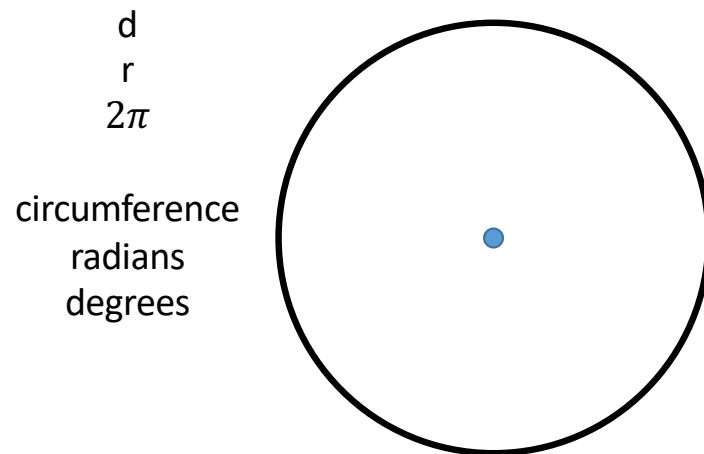


3 - Matrices and Transformations

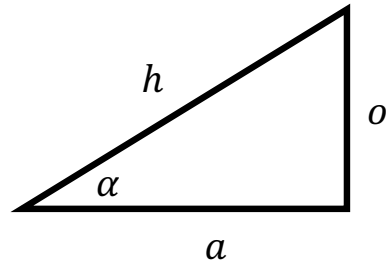
graphics is fun; graphics requires matrix math;
thus, matrix math must be fun

Simple Trig: Angles



Simple Trig: Angles

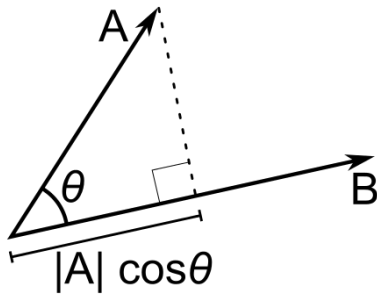
$$a^2 + o^2 = h^2$$



sin, cos, tan,
asin, acos, atan

Dot Product

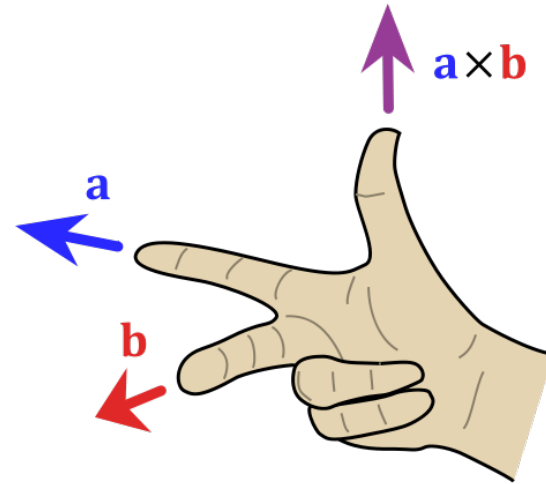
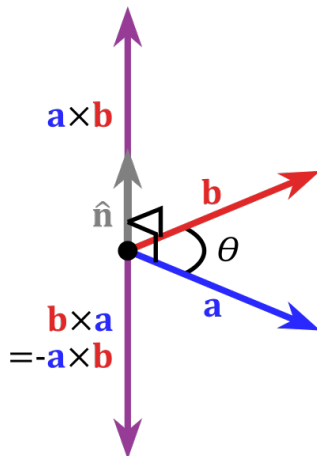
$$\mathbf{A} \cdot \mathbf{B} = \|\mathbf{A}\| \|\mathbf{B}\| \cos \theta,$$



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Some images from https://en.wikipedia.org/wiki/Dot_product

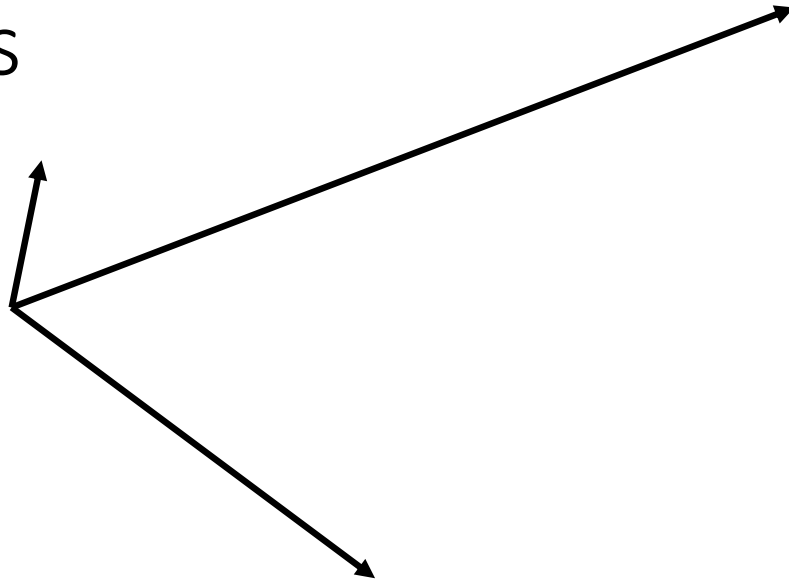
Cross Product



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Some images from https://en.wikipedia.org/wiki/Cross_product

Vectors



add/sub
length
scalar mult

3-D Vectors

Have length and direction

$$\mathbf{V} = [x_v, y_v, z_v]$$

Length is given by the Euclidean Norm

$$||\mathbf{V}|| = \sqrt{x_v^2 + y_v^2 + z_v^2}$$

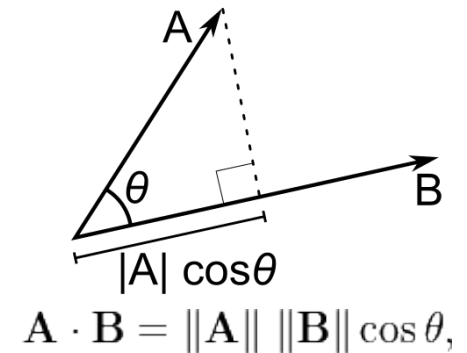
Dot Product $\mathbf{V} \cdot \mathbf{U} = [x_v, y_v, z_v] \cdot [x_u, y_u, z_u]$

$$= x_v x_u + y_v y_u + z_v z_u$$

$$= ||\mathbf{V}|| ||\mathbf{U}|| \cos \beta$$

Cross Product $\mathbf{V} \times \mathbf{U} = [y_v u_z - z_v u_y, -x_v u_z + z_v u_x, x_v u_y - y_v u_x]$

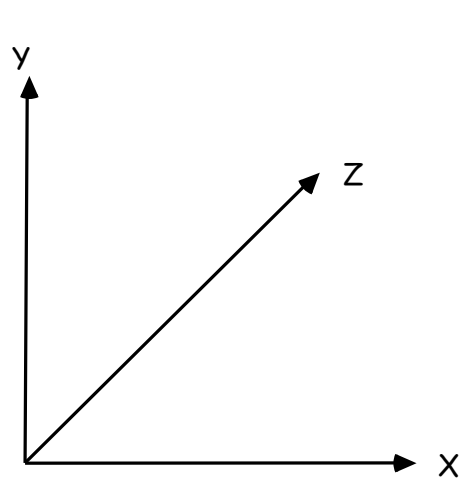
$$\mathbf{V} \times \mathbf{U} = -(\mathbf{U} \times \mathbf{V})$$



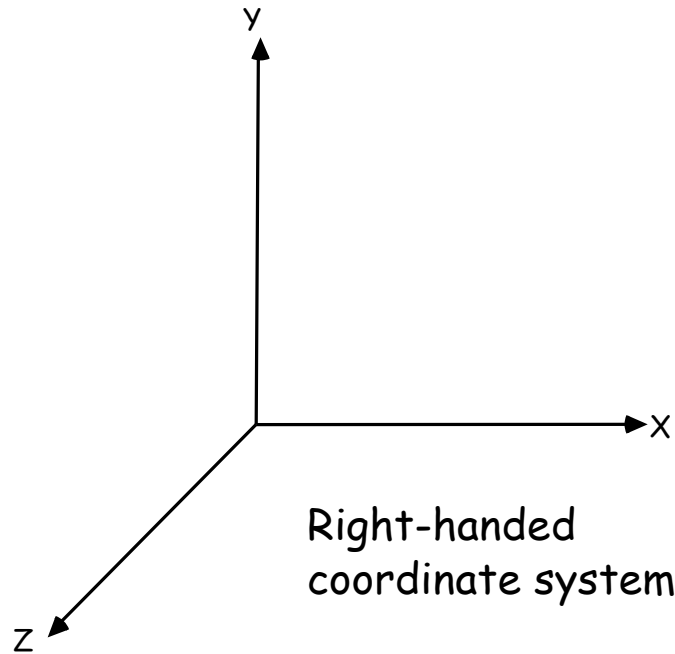
Cartesian Coordinates

- Basis vectors (2D)
- Linear independence
- Coordinates
- Orthogonal
- Orthonormal
 - Cartesian
 - 2D, 3D, 4D,...

3D Coordinate Systems



Left-handed
coordinate system



Right-handed
coordinate system

Matrices: Representation, Operations

Mult, not commutative

Identity

Inverses

Vector Operations with Matrices

Matrices as Transformations on Vectors