CS 4110

Programming Languages & Logics

Lecture 17
Definitional Translation & Continuations

3 October 2016

Announcements

• Wednesday: Prelim I

Syntax

```
e := x
        \lambda x. e
        |e_1e_2|
        |(e_1, e_2)|
        | #1 e
        | #2 e
        | \operatorname{let} x = e_1 \operatorname{in} e_2 |
v := \lambda x. e
           |(v_1, v_2)|
```

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```
E ::= [\cdot]
       | E e
       | v E
      |(E,e)|
      |(v, E)|
      | #1E
      | #2 E
       | \det x = E \text{ in } e_2 |
```

Semantics

$$\frac{e \to e'}{E[e] \to E[e']}$$

$$\overline{(\lambda x. e) \, v \to e\{v/x\}}^{\beta}$$

$$\overline{\#1(v_1, v_2) \to v_1}$$

$$\overline{\#2(v_1, v_2) \to v_2}$$

 $let x = v in e \rightarrow e\{v/x\}$

Translation

$$\mathcal{T}[\![x]\!] = x$$

$$\mathcal{T}[\![\lambda x. e]\!] = \lambda x. \, \mathcal{T}[\![e]\!]$$

$$\mathcal{T}[\![e_1 e_2]\!] = \mathcal{T}[\![e_1]\!] \, \mathcal{T}[\![e_2]\!]$$

$$\mathcal{T}[\![(e_1, e_2)]\!] = (\lambda x. \, \lambda y. \, \lambda f. \, fx \, y) \, \mathcal{T}[\![e_1]\!] \, \mathcal{T}[\![e_2]\!]$$

$$\mathcal{T}[\![\#1 \, e]\!] = \mathcal{T}[\![e]\!] \, (\lambda x. \, \lambda y. \, x)$$

$$\mathcal{T}[\![\#2 \, e]\!] = \mathcal{T}[\![e]\!] \, (\lambda x. \, \lambda y. \, y)$$

$$\mathcal{T}[\![\text{let } x = e_1 \, \text{in } e_2]\!] = (\lambda x. \, \mathcal{T}[\![e_2]\!]) \, \mathcal{T}[\![e_1]\!]$$

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Laziness

Consider the call-by-name λ -calculus...

Syntax

$$e ::= x$$

$$| e_1 e_2$$

$$| \lambda x. e$$

$$v ::= \lambda x. e$$

Semantics

$$\frac{e_1 o e_1'}{e_1 e_2 o e_1' e_2} \qquad \qquad \overline{(\lambda x. e_1) e_2 o e_1 \{e_2/x\}} \ eta$$

Laziness

Translation

```
\mathcal{T}[\![x]\!] = x (\lambda y. y)
\mathcal{T}[\![\lambda x. e]\!] = \lambda x. \mathcal{T}[\![e]\!]
\mathcal{T}[\![e_1 e_2]\!] = \mathcal{T}[\![e_1]\!] (\lambda z. \mathcal{T}[\![e_2]\!]) \quad z \text{ is not a free variable of } e_2
```

Syntax

$$e ::= x$$
$$| \lambda x. e$$
$$| e_0 e_1$$

$$v ::= \lambda x. e$$

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Syntax

$$\begin{array}{c} e ::= x \\ & | \lambda x. e \\ & | e_0 e_1 \\ & | \operatorname{ref} e \end{array}$$

$$v ::= \lambda x. e$$

Syntax

$$\begin{array}{c} e ::= x \\ & | \lambda x. e \\ & | e_0 e_1 \\ & | \operatorname{ref} e \\ & | !e \end{array}$$

$$v ::= \lambda x. e$$

S

Syntax

$$e := x$$
 $| \lambda x. e$
 $| e_0 e_1$
 $| ref e$
 $| !e$
 $| e_1 := e_2$

$$v ::= \lambda x. e$$

S

Syntax

$$e ::= x$$

$$| \lambda x. e$$

$$| e_0 e_1$$

$$| ref e$$

$$| !e$$

$$| e_1 := e_2$$

$$| \ell$$

$$v ::= \lambda x. e$$

S

Syntax

```
e := x
      |\lambda x.e|
      |e_0e_1|
      | ref e
        !e
      | e_1 := e_2
v := \lambda x. e
```

C

Semantics

$$\frac{\langle \sigma, e \rangle \to \langle \sigma', e' \rangle}{\langle \sigma, E[e] \rangle \to \langle \sigma', E[e'] \rangle} \frac{\overline{\langle \sigma, (\lambda x. e) \, v \rangle} \to \langle \sigma, e\{v/x\} \rangle}{\overline{\langle \sigma, (\lambda x. e) \, v \rangle}} \beta$$

$$\frac{\ell \not\in dom(\sigma)}{\overline{\langle \sigma, ref \, v \rangle} \to \overline{\langle \sigma[\ell \mapsto v], \ell \rangle}} \frac{\sigma(\ell) = v}{\overline{\langle \sigma, !\ell \rangle} \to \overline{\langle \sigma, v \rangle}}$$

$$\overline{\langle \sigma, \ell := \mathbf{v} \rangle \to \langle \sigma[\ell \mapsto \mathbf{v}], \mathbf{v} \rangle}$$

Translation

...left as an exercise to the reader. ;-)

Adequacy

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Every target evaluation should represent a source evaluation...

Definition (Soundness)

 $\forall e \in \mathbf{Exp}_{\mathsf{src}}$. if $\mathcal{T}[\![e]\!] \to_{\mathsf{trg}}^* v'$ then $\exists v.\ e \to_{\mathsf{src}}^* v$ and v' equivalent to v

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...and every source evaluation should have a target evaluation:

Definition (Completeness)

 $\forall e \in \mathbf{Exp}_{\mathsf{src}}$. if $e \to_{\mathsf{src}}^* v$ then $\exists v'$. $\mathcal{T}[\![e]\!] \to_{\mathsf{trg}}^* v'$ and v' equivalent to v

Continuations

In the preceding translations, the control structure of the source language was translated directly into the corresponding control structure in the target language.

For example:

$$\begin{split} \mathcal{T}[\![\lambda x.\,e]\!] &= \lambda x.\,\mathcal{T}[\![e]\!] \\ \mathcal{T}[\![e_1\,e_2]\!] &= \mathcal{T}[\![e_1]\!]\,\mathcal{T}[\![e_2]\!] \end{split}$$

What can go wrong with this approach?

Continuations

- A snippet of code that represents "the rest of the program"
- Can be used directly by programmers...
- ...or in program transformations by a compiler
- Make the control flow of the program explicit
- Also useful for defining the meaning of features like exceptions

Consider the following expression:

$$(\lambda x. x)((1+2)+3)+4$$

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$$k_0 = \lambda v. (\lambda x. x) v$$

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 $k_1 = \lambda a. k_0 (a + 4)$
 $k_2 = \lambda b. k_1 (b + 3)$

Consider the following expression:

$$(\lambda x. x) ((1+2)+3)+4$$

$$k_0 = \lambda v. (\lambda x. x) v$$

 $k_1 = \lambda a. k_0 (a + 4)$
 $k_2 = \lambda b. k_1 (b + 3)$
 $k_3 = \lambda c. k_2 (c + 2)$

Consider the following expression:

$$(\lambda x. x) ((1+2)+3)+4$$

If we make all of the continuations explicit, we obtain the following:

$$k_0 = \lambda v. (\lambda x. x) v$$

 $k_1 = \lambda a. k_0 (a + 4)$
 $k_2 = \lambda b. k_1 (b + 3)$
 $k_3 = \lambda c. k_2 (c + 2)$

The original expression is equivalent to k_3 1, or:

$$(\lambda c. (\lambda b. (\lambda a. (\lambda v. (\lambda x. x) v) (a + 4)) (b + 3)) (c + 2)) 1$$

Example (Continued)

Recall that let x = e in e' is syntactic sugar for $(\lambda x. e') e$.

Hence, we can rewrite the expression with continuations more succinctly as

let
$$c = 1$$
 in
let $b = c + 2$ in
let $a = b + 3$ in
let $v = a + 4$ in
 $(\lambda x. x) v$

We write
$$\mathcal{CPS}[e] k = \dots$$
 instead of $\mathcal{CPS}[e] = \lambda k \dots$

$$\mathcal{CPS}[n]k = kn$$

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$$\begin{split} & \mathcal{CPS} \llbracket n \rrbracket \ k = k \ n \\ & \mathcal{CPS} \llbracket e_1 + e_2 \rrbracket \ k = \mathcal{CPS} \llbracket e_1 \rrbracket \left(\lambda n. \ \mathcal{CPS} \llbracket e_2 \rrbracket \left(\lambda m. \ k \left(n + m \right) \right) \right) \end{split}$$

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$$\begin{split} \mathcal{CPS}\llbracket n \rrbracket \ k &= k \, n \\ \mathcal{CPS}\llbracket e_1 + e_2 \rrbracket \ k &= \mathcal{CPS}\llbracket e_1 \rrbracket \left(\lambda n. \, \mathcal{CPS}\llbracket e_2 \rrbracket \left(\lambda m. \, k \, (n+m)\right)\right) \\ \mathcal{CPS}\llbracket (e_1, e_2) \rrbracket \ k &= \mathcal{CPS}\llbracket e_1 \rrbracket \left(\lambda v. \, \mathcal{CPS}\llbracket e_2 \rrbracket \left(\lambda w. \, k \, (v, w)\right)\right) \\ \mathcal{CPS}\llbracket \#1 \, e \rrbracket \ k &= \mathcal{CPS}\llbracket e \rrbracket \left(\lambda v. \, k \, (\#1 \, v)\right) \end{split}$$

We write $\mathcal{CPS}[e] k = \dots$ instead of $\mathcal{CPS}[e] = \lambda k \dots$

$$\begin{split} \mathcal{CPS} \llbracket n \rrbracket \ k &= k \, n \\ \mathcal{CPS} \llbracket e_1 + e_2 \rrbracket \ k &= \mathcal{CPS} \llbracket e_1 \rrbracket \left(\lambda n. \, \mathcal{CPS} \llbracket e_2 \rrbracket \left(\lambda m. \, k \, (n+m) \right) \right) \\ \mathcal{CPS} \llbracket (e_1, e_2) \rrbracket \ k &= \mathcal{CPS} \llbracket e_1 \rrbracket \left(\lambda v. \, \mathcal{CPS} \llbracket e_2 \rrbracket \left(\lambda w. \, k \, (v, w) \right) \right) \\ \mathcal{CPS} \llbracket \#1 \, e \rrbracket \ k &= \mathcal{CPS} \llbracket e \rrbracket \left(\lambda v. \, k \, (\#1 \, v) \right) \\ \mathcal{CPS} \llbracket \#2 \, e \rrbracket \ k &= \mathcal{CPS} \llbracket e \rrbracket \left(\lambda v. \, k \, (\#2 \, v) \right) \end{split}$$

We write $\mathcal{CPS}[e] k = \dots$ instead of $\mathcal{CPS}[e] = \lambda k \dots$

$$\begin{split} \mathcal{CPS} \llbracket n \rrbracket \ k &= k \ n \\ \mathcal{CPS} \llbracket e_1 + e_2 \rrbracket \ k &= \mathcal{CPS} \llbracket e_1 \rrbracket \ (\lambda n. \ \mathcal{CPS} \llbracket e_2 \rrbracket \ (\lambda m. \ k \ (n+m))) \\ \mathcal{CPS} \llbracket (e_1, e_2) \rrbracket \ k &= \mathcal{CPS} \llbracket e_1 \rrbracket \ (\lambda v. \ \mathcal{CPS} \llbracket e_2 \rrbracket \ (\lambda w. \ k \ (v, w))) \\ \mathcal{CPS} \llbracket \#1 \ e \rrbracket \ k &= \mathcal{CPS} \llbracket e \rrbracket \ (\lambda v. \ k \ (\#1 \ v)) \\ \mathcal{CPS} \llbracket \#2 \ e \rrbracket \ k &= \mathcal{CPS} \llbracket e \rrbracket \ (\lambda v. \ k \ (\#2 \ v)) \\ \mathcal{CPS} \llbracket x \rrbracket \ k &= k \ x \end{split}$$

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We write $\mathcal{CPS}[e] k = \dots$ instead of $\mathcal{CPS}[e] = \lambda k \dots$

```
\mathcal{CPS}[n]k = kn
\mathcal{CPS}[e_1 + e_2] k = \mathcal{CPS}[e_1] (\lambda n. \mathcal{CPS}[e_2] (\lambda m. k (n + m)))
\mathcal{CPS}[(e_1, e_2)] k = \mathcal{CPS}[e_1] (\lambda v. \mathcal{CPS}[e_2] (\lambda w. k (v, w)))
    \mathcal{CPS}[\#1\ e] k = \mathcal{CPS}[e] (\lambda v. k (\#1\ v))
    \mathcal{CPS}\llbracket\#2\ e\rrbracket\ k = \mathcal{CPS}\llbracket e\rrbracket\ (\lambda v.\ k\ (\#2\ v))
           \mathcal{CPS}[x] k = kx
    \mathcal{CPS}[\lambda x. e] k = k(\lambda x. \lambda k'. \mathcal{CPS}[e] k')
    \mathcal{CPS}[e_1 e_2] k = \mathcal{CPS}[e_1] (\lambda f. \mathcal{CPS}[e_2] (\lambda v. f v k))
```

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