

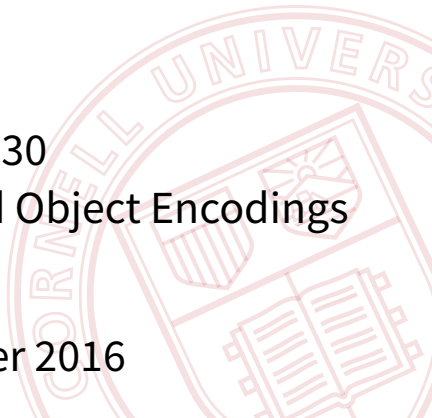
CS 4110

Programming Languages & Logics

Lecture 30

Featherweight Java and Object Encodings

11 November 2016



Properties

Lemma (Preservation)

If $\Gamma \vdash e : C$ and $e \rightarrow e'$ then there exists a type C' such that $\Gamma \vdash e' : C'$ and $C' \leq C$.

Lemma (Progress)

Let e be an expression such that $\vdash e : C$. Then either:

- 1. e is a value,*
- 2. there exists an expression e' such that $e \rightarrow e'$, or*
- 3. $e = E[(B) (\text{new } A(\bar{v}))]$ with $A \not\leq B$.*

Lemmas

Lemma (Method Typing)

If $mtype(m, C) = \bar{D} \rightarrow D$ and $mbody(m, C) = (\bar{x}, e)$ then there exists types C' and D' such that $\bar{x} : \bar{D}$, $this : C' \vdash e : D'$ and $D' \leq D$.

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Lemma (Substitution)

If $\Gamma, \bar{x} : \bar{B} \vdash e : C$ and $\Gamma \vdash \bar{u} : \bar{B}'$ with $\bar{B}' \leq \bar{B}$ then there exists C' such that $\Gamma \vdash [\bar{x} \mapsto \bar{u}]e : C'$ and $C' \leq C$.

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Lemma (Weakening)

If $\Gamma \vdash e : C$ then $\Gamma, x : B \vdash e : C$.

Lemmas

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If $\Gamma \vdash E[e] : C$ then there exists a type B such that $\Gamma \vdash e : B$

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Lemma (Context)

If $\Gamma \vdash E[e] : C$ and $\Gamma \vdash e : B$ and $\Gamma \vdash e' : B'$ with $B' \leq B$ then there exists a type C' such that $\Gamma \vdash E[e'] : C'$ and $C' \leq C$.

Operational Semantics

$$E ::= [\cdot] \mid E.f \mid E.m(\bar{e}) \mid v.m(\bar{v}, E, \bar{e}) \mid \text{new } C(\bar{v}, E, \bar{e}) \mid (C) E$$

Operational Semantics

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$$\frac{e \rightarrow e'}{E[e] \rightarrow E[e']} \text{ E-CONTEXT}$$

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$$\frac{\text{mbody}(m, C) = (\bar{x}, e)}{\text{new } C(\bar{v}).m(\bar{u}) \rightarrow [\bar{x} \mapsto \bar{u}, \text{this} \mapsto \text{new } C(\bar{v})]e} \text{ E-INVK}$$

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$$\frac{C \leq D}{(D) \text{new } C(\bar{v}) \rightarrow \text{new } C(\bar{v})} \text{ E-CAST}$$

Lemmas

Lemma (Canonical Forms)

If $\vdash v : C$ then $v = \text{new } C(\bar{v})$.

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Lemma (Inversion)

- If $\vdash (\text{new } C(\bar{v})).f_i : C_i$ then $\text{fields}(C) = \overline{C}f$ and $f_i \in \bar{f}$.*
- If $\vdash (\text{new } C(\bar{v})).m(\bar{u}) : C$ then $\text{mbody}(m, C) = (\bar{x}, e)$ and $|\bar{u}| = |\bar{e}|$.*

Typing Rules

$$\frac{\Gamma(x) = C}{\Gamma \vdash x : C} \text{ T-VAR}$$

$$\frac{\Gamma \vdash e : C \quad \text{fields}(C) = \overline{C}f}{\Gamma \vdash e.f_i : C_i} \text{ T-FIELD}$$

$$\frac{\Gamma \vdash e : C \quad \text{mtype}(m, C) = \overline{B} \rightarrow B \quad \Gamma \vdash \bar{e} : \overline{A} \quad \overline{A} \leq \overline{B}}{\Gamma \vdash e.m(\bar{e}) : B} \text{ T-INVK}$$

$$\frac{\text{fields}(C) = \overline{C}f \quad \Gamma \vdash \bar{e} : \overline{B} \quad \overline{B} \leq \overline{C}}{\Gamma \vdash \text{new } C(\bar{e}) : C} \text{ T-NEW}$$

$$\frac{\Gamma \vdash e : D \quad D \leq C}{\Gamma \vdash (C)e : C} \text{ T-UCAST}$$

$$\frac{\Gamma \vdash e : D \quad C \leq D \quad C \neq D}{\Gamma \vdash (C)e : C} \text{ T-DCAST}$$

$$\frac{\Gamma \vdash e : D \quad C \not\leq D \quad D \not\leq C \quad \text{stupid warning}}{\Gamma \vdash (C)e : C} \text{ T-SCAST}$$

Object Encodings

Object-Oriented Features

- Dynamic dispatch
- Encapsulation
- Subtyping
- Inheritance
- Open recursion

Dynamic Dispatch

```
interface Shape {  
    ...  
    void draw() { ... }  
}  
  
class Circle extends Shape {  
    ...  
    void draw() { ... }  
}  
  
class Square extends Shape {  
    ...  
    void draw() { ... }  
}  
  
/*could be a circle, square, or something else */  
Shape s = ...;  
s.draw();
```

Encapsulation

```
class Circle extends Shape {  
    private Point center;  
    private int radius;  
    ...  
    public Point getX() { return center.x }  
    public Point getY() { return center.y }  
}
```

Subtyping

Subtyping fits naturally with object-oriented languages because (ignoring languages such as Java that allow certain objects to manipulate instance variables directly) the only way to interact with an object is to invoke a method

As a result, an object that supports the same methods as another object can be used wherever the second is expected

Example: a method that takes an object of type `Shape` can be passed a `Circle`, `Square`, or any other subtype of `Shape`, because they each support the methods listed in the `Shape` interface

Inheritance

```
class A {  
    public int f(...) { ... g(...) ... }  
    public bool g(...) { ... }  
}  
  
class B extends A {  
    public bool g(...) { ... }  
}  
  
...  
new B.f(...)
```

Open Recursion

Many object-oriented languages allow objects to invoke their own methods using the special keyword `this` (or `self`)

Implementing `this` in the presence of inheritance requires deferring the binding of `this` until the object is actually created

We will see an example of this next...

Record Encoding

```
type pointRep = { x:int ref; y:int ref }
```

Record Encoding

```
type pointRep = { x:int ref; y:int ref }  
type point = { movex:int -> unit;  
               movey:int -> unit }
```


Record Encoding

```
type pointRep = { x:int ref; y:int ref }  
type point = { movex:int -> unit;  
               movey:int -> unit }  
  
let pointClass : pointRep -> point =  
  (fun (r:pointRep) ->  
    { movex = (fun d -> r.x := !(r.x) + d);  
      movey = (fun d -> r.y := !(r.y) + d) })
```

Record Encoding

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  (fun (r:pointRep) ->  
    { movex = (fun d -> r.x := !(r.x) + d);  
      movey = (fun d -> r.y := !(r.x) + d) })  
  
let newPoint : int -> int -> point =  
  (fun (x:int) ->  
    (fun (y:int) ->  
      pointClass { x=ref x; y = ref y })))
```

Inheritance

```
type point3D = { movex:int -> unit;  
                 movey:int -> unit;  
                 movez:int -> unit }
```

Inheritance

```
type point3D = { movex:int -> unit;  
                 movey:int -> unit;  
                 movez:int -> unit }  
  
let point3DClass : point3DRep -> point3D =  
  (fun (r:point3DRep) ->  
    let super = pointClass r in  
    { movex = super.movex;  
      movey = super.movey;  
      movez = (fun d -> r.z := !(r.x) + d) } )
```

Inheritance

```
type point3D = { movex:int -> unit;  
                movey:int -> unit;  
                movez:int -> unit }  
  
let point3DClass : point3DRep -> point3D =  
  (fun (r:point3DRep) ->  
    let super = pointClass r in  
    { movex = super.movex;  
      movey = super.movey;  
      movez = (fun d -> r.z := !(r.x) + d) } )  
  
let newPoint3D : int -> int -> int -> point3D =  
  (fun (x:int) ->  
    (fun (y:int) ->  
      (fun (z:int) ->  
        point3DClass { x=ref x; y = ref y; z = ref z }))))
```

Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }
```

Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }  
type altPoint = { movex:int -> unit;  
                  movey:int -> unit;  
                  move: int -> int -> unit }
```

Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }  
type altPoint = { movex:int -> unit;  
                  movey:int -> unit;  
                  move: int -> int -> unit }  
  
let altPointClass : altPointRep -> altPoint ref -> altPoint =  
  (fun (r:altPointRep) ->  
    (fun (self:altPoint ref) ->  
      { movex = (fun d -> r.x := !(r.x) + d);  
        movey = (fun d -> r.y := !(r.y) + d);  
        move = (fun dx dy -> (!self.movex) dx;  
                  (!self.movey) dy) })))
```


Open Recursion with Self

```
let dummyAltPoint : altPoint =  
  { movex = (fun d -> ());  
    movey = (fun d -> ());  
    move = (fun dx dy -> ()) }
```

Open Recursion with Self

```
let dummyAltPoint : altPoint =  
  { movex = (fun d -> ());  
    movey = (fun d -> ());  
    move = (fun dx dy -> ()) }  
  
let newAltPoint : int -> int -> altPoint =  
  (fun (x:int) ->  
    (fun (y:int) ->  
      let r = { x=ref x; y = ref y } in  
      let cref = ref dummyAltPoint in  
      cref := altPointClass r cref;  
      !cref ))
```