## CS 4110

## Programming Languages & Logics

Lecture 30
Featherweight Java and Object Encodings

## **Properties**

#### Lemma (Preservation)

If  $\Gamma \vdash e : C$  and  $e \rightarrow e'$  then there exists a type C' such that  $\Gamma \vdash e' : C'$  and C' < C.

## Lemma (Progress)

Let e be an expression such that  $\vdash$  e : C. Then either:

- 1. e is a value,
- **2**. there exists an expression e' such that  $e \rightarrow e'$ , or
- 3.  $e = E[(B) (new A(\overline{v}))]$  with  $A \nleq B$ .

## Lemma (Method Typing)

If  $mtype(m, C) = \overline{D} \rightarrow D$  and  $mbody(m, C) = (\overline{x}, e)$  then there exists types C' and D' such that  $\overline{x} : \overline{D}$ , this :  $C' \vdash e : D'$  and  $D' \leq D$ .

(3)

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#### Lemma (Substitution)

If  $\Gamma, \overline{x} : \overline{B} \vdash e : C$  and  $\Gamma \vdash \overline{u} : \overline{B'}$  with  $\overline{B'} \leq \overline{B}$  then there exists C' such that  $\Gamma \vdash [\overline{x} \mapsto \overline{u}]e : C'$  and  $C' \leq C$ .

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## Lemma (Weakening)

If  $\Gamma \vdash e : C \text{ then } \Gamma, x : B \vdash e : C$ .

## Lemma (Decomposition)

If  $\Gamma \vdash E[e]$ : C then there exists a type B such that  $\Gamma \vdash e$ : B

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#### Lemma (Context)

If  $\Gamma \vdash E[e] : C$  and  $\Gamma \vdash e : B$  and  $\Gamma \vdash e' : B'$  with  $B' \leq B$  then there exists a type C' such that  $\Gamma \vdash E[e'] : C'$  and  $C' \leq C$ .

## **Operational Semantics**

$$E ::= [\cdot] \mid E.f \mid E.m(\overline{e}) \mid v.m(\overline{v}, E, \overline{e}) \mid \text{new } C(\overline{v}, E, \overline{e}) \mid (C) E$$

$$\frac{e \to e'}{E[e] \to E[e']} \text{ E-Context}$$

$$\frac{fields(C) = \overline{C} f}{\text{new } C(\overline{v}).f_i \to v_i} \text{ E-Proj}$$

$$\frac{mbody(m, C) = (\overline{x}, e)}{\text{new } C(\overline{v}).m(\overline{u}) \to [\overline{x} \mapsto \overline{u}, \text{this} \mapsto \text{new } C(\overline{v})]e} \text{ E-Invk}$$

$$\frac{C \leq D}{(D) \text{ new } C(\overline{v}) \to \text{new } C(\overline{v})} \text{ E-Cast}$$

#### Lemma (Canonical Forms)

If  $\vdash v : C \text{ then } v = new C(\overline{v}).$ 

#### Lemma (Inversion)

- **1.** If  $\vdash (newC(\overline{v})).f_i : C_i$  then  $fields(C) = \overline{Cf}$  and  $f_i \in \overline{f}$ .
- 2. If  $\vdash (newC(\overline{v})).m(\overline{u}) : C$  then  $mbody(m,C) = (\overline{x},e)$  and  $|\overline{u}| = |\overline{e}|.$

## Typing Rules

$$\frac{\Gamma(x) = C}{\Gamma \vdash x : C} \text{ T-VAR} \qquad \frac{\Gamma \vdash e : C \qquad \textit{fields}(C) = \overline{Cf}}{\Gamma \vdash e . f_i : C_i} \text{ T-FIELD}$$

$$\frac{\Gamma \vdash e : C \qquad \textit{mtype}(m, C) = \overline{B} \to B \qquad \Gamma \vdash \overline{e} : \overline{A} \qquad \overline{A} \leq \overline{B}}{\Gamma \vdash e . m(\overline{e}) : B} \text{ T-Invk}$$

$$\frac{\textit{fields}(C) = \overline{Cf} \qquad \Gamma \vdash \overline{e} : \overline{B} \qquad \overline{B} \leq \overline{C}}{\Gamma \vdash \text{new} C(\overline{e}) : C} \text{ T-New}$$

$$\frac{\Gamma \vdash e : D \qquad D \leq C}{\Gamma \vdash (C) e : C} \text{ T-UCAST} \qquad \frac{\Gamma \vdash e : D \qquad C \leq D \qquad C \neq D}{\Gamma \vdash (C) e : C} \text{ T-DCAST}$$

$$\frac{\Gamma \vdash e : D \qquad C \nleq D \qquad D \nleq C \qquad \textit{stupid warning}}{\Gamma \vdash (C) e : C} \text{ T-SCAST}$$

# Object Encodings

## **Object-Oriented Features**

- Dynamic dispatch
- Encapsulation
- Subtyping
- Inheritance
- Open recursion

```
type pointRep = { x:int ref; y:int ref }
```

```
type pointRep = { x:int ref; y:int ref }
type point = { movex:int -> unit;
               movey:int -> unit }
```

```
type pointRep = { x:int ref; y:int ref }
type point = { movex:int -> unit;
                 movey:int -> unit }
let pointClass : pointRep -> point =
  (fun (r:pointRep) ->
    { movex = (\text{fun d} \rightarrow r.x := !(r.x) + d);
      movey = (\text{fun d} \rightarrow r.y := !(r.x) + d) }
```

```
type pointRep = { x:int ref; y:int ref }
type point = { movex:int -> unit;
                  movey:int -> unit }
let pointClass : pointRep -> point =
  (fun (r:pointRep) ->
    \{ \text{ movex = } (\text{fun d } \rightarrow \text{r.x := } !(\text{r.x}) + \text{d}); \}
       movey = (\text{fun d} \rightarrow r.y := !(r.x) + d) }
let newPoint : int -> int -> point =
  (fun (x:int) ->
    (fun (y:int) ->
       pointClass { x = ref x; y = ref y }))
```

#### **Inheritance**

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```
type point3DRep = { x:int ref; y:int ref; z:int ref }
type point3D = { movex:int -> unit;
                  movey:int -> unit;
                  movez:int -> unit }
let point3DClass : point3DRep -> point3D =
  (fun (r:point3DRep) ->
    let super = pointClass r in
    { movex = super.movex;
      movey = super.movey;
      movez = (\text{fun d} \rightarrow r.z := !(r.x) + d) }
```

#### Inheritance

```
type point3DRep = { x:int ref; y:int ref; z:int ref }
type point3D = { movex:int -> unit;
                  movey:int -> unit;
                  movez:int -> unit }
let point3DClass : point3DRep -> point3D =
  (fun (r:point3DRep) ->
    let super = pointClass r in
    { movex = super.movex;
      movey = super.movey;
      movez = (\text{fun d} \rightarrow r.z := !(r.x) + d) }
let newPoint3D : int -> int -> int -> point3D =
  (fun (x:int) ->
    (fun (y:int) ->
      (fun (z:int) ->
        point3DClass { x = ref x; y = ref y; z = ref z })))
```

## Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }
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## Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }
type altPoint = { movex:int -> unit;
                 movey:int -> unit;
                 move: int -> int -> unit }
```

## Open Recursion With Self

```
type altPointRep = { x:int ref; y:int ref }
type altPoint = { movex:int -> unit;
                     movey:int -> unit;
                     move: int -> int -> unit }
let altPointClass : altPointRep -> altPoint ref -> altPoint =
  (fun (r:altPointRep) ->
     (fun (self:altPoint ref) ->
       \{ \text{ movex = } (\text{fun d } \rightarrow \text{r.x := } !(\text{r.x}) + \text{d}); \}
         movey = (\text{fun d} \rightarrow \text{r.y} := !(\text{r.y}) + d);
         move = (fun dx dy -> (!self.movex) dx;
                                   (!self.movey) dy) }))
```

## Open Recursion with Self

```
let dummyAltPoint : altPoint =
  \{ movex = (fun d \rightarrow ()); \}
    movey = (fun d \rightarrow ());
    move = (fun dx dy \rightarrow ())}
```

## Open Recursion with Self

```
let dummyAltPoint : altPoint =
  \{ \text{ movex = (fun d -> ())}: 
    movey = (fun d \rightarrow ());
    move = \{\text{fun dx dy -> ()}\}
let newAltPoint : int -> int -> altPoint =
  (fun (x:int) ->
    (fun (y:int) ->
      let r = \{ x = ref x; y = ref y \} in
      let cref = ref dummyAltPoint in
      cref := altPointClass r cref;
      !cref ))
```