CS 4110

Programming Languages & Logics

Lecture 17
Definitional Translation & Continuations

We know how to encode Booleans, conditionals, natural numbers, and recursion in λ -calculus.

Can we define a *real* programming language by translating everything in it into the λ -calculus?

We know how to encode Booleans, conditionals, natural numbers, and recursion in λ -calculus.

Can we define a *real* programming language by translating everything in it into the λ -calculus?

In definitional translation, we define a denotational semantics where the target is a simpler programming language instead of mathematical objects.

Multi-Argument λ -calculus

Let's define a version of the λ -calculus that allows functions to take multiple arguments.

$$e ::= x \mid \lambda x_1, \ldots, x_n. e \mid e_0 e_1 \ldots e_n$$

Multi-Argument λ -calculus

We can define a CBV operational semantics:

$$E ::= [\cdot] \mid v_0 \ldots v_{i-1} E e_{i+1} \ldots e_n$$

$$\frac{\mathrm{e} o \mathrm{e}'}{\mathrm{E}[\mathrm{e}] o \mathrm{E}[\mathrm{e}']}$$
 (ontext

$$\overbrace{(\lambda x_1,\ldots,x_n.e_0)\ v_1\ \ldots\ v_n\rightarrow (e_0\{v_1/x_1\})(v_2/x_2)\ldots\{v_n/x_n\}}^{\beta}$$

The evaluation contexts ensure that we evaluate multi-argument applications $e_0 e_1 \dots e_n$ from left to right.

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We can define a translation $\mathcal{T}[\![\cdot]\!]$ that takes an expression in the multi-argument λ -calculus and returns an equivalent expression in the pure λ -calculus.

$$\mathcal{T}[\![x]\!] \stackrel{\triangle}{=} x$$

$$\mathcal{T}[\![\lambda x_1, \dots, x_n, e]\!] \stackrel{\triangle}{=} \lambda x_1, \dots \lambda x_n, \mathcal{T}[\![e]\!]$$

$$\mathcal{T}[\![e_0 e_1 e_2 \dots e_n]\!] \stackrel{\triangle}{=} (\dots ((\mathcal{T}[\![e_0]\!] \mathcal{T}[\![e_1]\!]) \mathcal{T}[\![e_2]\!]) \dots \mathcal{T}[\![e_n]\!])$$

This translation *curries* the multi-argument λ -calculus.



```
e := x
        \lambda x. e
        |e_1 e_2|
       |(e_1, e_2)|
       | #1 e
       | #2 e
        | \operatorname{let} x = e_1 \operatorname{in} e_2 |
v := \lambda x. e
          |(v_1, v_2)|
```

```
E ::= [\cdot]
       | E e
      | v E
      |(E,e)|
      |(v, E)|
      |#1E
      | #2 E
      | \det x = E \text{ in } e_2 |
```

Semantics

$$rac{e
ightarrow e'}{E[e]
ightarrow E[e']}$$
 $\overline{(\lambda x.\,e)\,v
ightarrow e\{v/x\}}^{eta}$ $\overline{\#1\,(v_1,v_2)
ightarrow v_1}$ $\overline{\#2\,(v_1,v_2)
ightarrow v_2}$

$$let x = v in e \rightarrow e\{v/x\}$$

Translation

```
\mathcal{T}[\![x]\!] = x
\mathcal{T}[\![\lambda x. e]\!] = \lambda x. \, \mathcal{T}[\![e]\!]
\mathcal{T}[\![e_1 e_2]\!] = \mathcal{T}[\![e_1]\!] \, \mathcal{T}[\![e_2]\!]
\mathcal{T}[\![(e_1, e_2)]\!] = (\lambda x. \, \lambda y. \, \lambda f. \, fx \, y) \, \mathcal{T}[\![e_1]\!] \, \mathcal{T}[\![e_2]\!]
\mathcal{T}[\![\#1 \, e]\!] = \mathcal{T}[\![e]\!] \, (\lambda x. \, \lambda y. \, x)
\mathcal{T}[\![\#2 \, e]\!] = \mathcal{T}[\![e]\!] \, (\lambda x. \, \lambda y. \, y)
\mathcal{T}[\![\text{let} \, x = e_1 \, \text{in} \, e_2]\!] = (\lambda x. \, \mathcal{T}[\![e_2]\!]) \, \mathcal{T}[\![e_1]\!]
```

S

Laziness

Consider the call-by-name λ -calculus...

Syntax

$$e ::= x$$

$$| e_1 e_2$$

$$| \lambda x. e$$

$$v ::= \lambda x. e$$

Semantics

$$rac{e_1
ightarrow e_1'}{e_1\,e_2
ightarrow e_1'\,e_2} \qquad \qquad \overline{\left(\lambda x.\,e_1
ight)e_2
ightarrow e_1\{e_2/x\}}^{eta}$$

Laziness

Translation

$$\mathcal{T}[\![x]\!] = x(\lambda y.y)$$

$$\mathcal{T}[\![\lambda x.e]\!] = \lambda x. \mathcal{T}[\![e]\!]$$

$$\mathcal{T}[\![e_1 e_2]\!] = \mathcal{T}[\![e_1]\!] (\lambda z. \mathcal{T}[\![e_2]\!]) \quad z \text{ is not a free variable of } e_2$$

$$\mathcal{T}[\![(\lambda x.x))] (\lambda y.y) (\lambda z.z)$$

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$$e ::= x$$
$$| \lambda x. e$$
$$| e_0 e_1$$

$$v ::= \lambda x. e$$

$$e ::= x$$

$$| \lambda x. e$$

$$| e_0 e_1$$

$$| ref e$$

$$v ::= \lambda x. e$$

$$e := x$$

$$|\lambda x. e$$

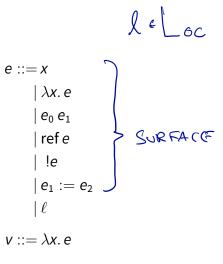
$$|e_0 e_1| \quad \text{#e} = \dots$$

$$|\text{ref } e|$$

$$|e \quad \text{\downarrow} e$$

$$v ::= \lambda x. e$$

```
e := x
     \lambda x. e
     |e_0e_1|
     | ref e
      !e
                           *e, = e2
     | e_1 := e_2
v := \lambda x. e
```



```
e := x
      |\lambda x.e|
      |e_0e_1|
      | ref e
        !e
      | e_1 := e_2
v := \lambda x. e
```

Semantics
$$\langle \sigma, e \rangle \rightarrow \langle \sigma', e' \rangle$$
 $\sigma : \setminus_{GC} \rightarrow \langle \sigma', e' \rangle$ $\overline{\langle \sigma, E[e] \rangle \rightarrow \langle \sigma', E[e'] \rangle}$ $\overline{\langle \sigma, (\lambda x. e) v \rangle \rightarrow \langle \sigma, e\{v/x\} \rangle}^{OLD}$

$$\overline{\langle \sigma, \ell := \mathbf{v} \rangle \to \langle \sigma[\ell \mapsto \mathbf{v}], \mathbf{v} \rangle}$$

 $\frac{\ell \not\in dom(\sigma)}{\langle \sigma, \mathsf{ref} \, \mathsf{v} \rangle \to \langle \sigma[\ell \mapsto \mathsf{v}], \ell \rangle}$

 $\frac{\sigma(\ell) = \mathsf{v}}{\langle \sigma, \ !\ell \rangle \to \langle \sigma, \mathsf{v} \rangle}$

Translation

...left as an exercise to the reader. ;-)

Adequacy

How do we know if a translation is correct?

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Every target evaluation should represent a source evaluation...

Definition (Soundness)

 $\forall e \in \mathbf{Exp}_{\mathsf{src}}$. if $\mathcal{T}[\![e]\!] \to_{\mathsf{trg}}^* v'$ then $\exists v.\ e \to_{\mathsf{src}}^* v$ and v' equivalent to v

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...and every source evaluation should have a target evaluation:

Definition (Completeness)

 $\forall e \in \mathbf{Exp}_{\mathsf{src}}$. if $e \to_{\mathsf{src}}^* v$ then $\exists v'$. $\mathcal{T}[\![e]\!] \to_{\mathsf{trg}}^* v'$ and v' equivalent to v

Continuations

In the preceding translations, the control structure of the source language was translated directly into the corresponding control structure in the target language.

For example:

$$\begin{split} \mathcal{T}[\![\lambda x.\,e]\!] &= \lambda x.\,\mathcal{T}[\![e]\!] \\ \mathcal{T}[\![e_1\,e_2]\!] &= \mathcal{T}[\![e_1]\!]\,\mathcal{T}[\![e_2]\!] \end{split}$$

What can go wrong with this approach?

Continuations

- A snippet of code that represents "the rest of the program"
- Can be used directly by programmers...
- ...or in program transformations by a compiler
- Make the control flow of the program explicit
- Also useful for defining the meaning of features like exceptions

Consider the following expression:

$$(\lambda x. x)((1+2)+3)+4$$

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If we make all of the continuations explicit, we obtain:

$$k_0 = \lambda v. (\lambda x. x) v$$

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$$k_1 = \lambda a. k_0 (a + 4)$$

$$k_2 = \lambda b. k_1 (b + 3)$$

Example

Consider the following expression:

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If we make all of the continuations explicit, we obtain:

$$k_0 = \lambda v. (\lambda x. x) v$$

 $k_1 = \lambda a. k_0 (a + 4)$
 $k_2 = \lambda b. k_1 (b + 3)$
 $k_3 = \lambda c. k_2 (c + 2)$

Example

Consider the following expression:

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If we make all of the continuations explicit, we obtain:

$$k_0 = \lambda v. (\lambda x. x) v$$
 $k_1 = \lambda a. k_0 (a + 4)$
 $k_2 = \lambda b. k_1 (b + 3)$
 $k_3 = \lambda c. k_2 (c + 2)$
 $\lambda x. e_3$

The original expression is equivalent to k_3 1, or:

$$(\lambda c)(\lambda b.(\lambda a.(\lambda v.(\lambda x.x)v)(a+4))(b+3))(c+2))$$

Example (Continued)

Recall that let x = e in e' is syntactic sugar for $(\lambda x. e') e$.

Hence, we can rewrite the expression with continuations more succinctly as

let
$$c = 1$$
 in
let $b = c + 2$ in
let $a = b + 3$ in
let $v = a + 4$ in
 $(\lambda x. x) v$

We write
$$\mathcal{CPS}[e] k = \dots$$
 instead of $\mathcal{CPS}[e] = \lambda k \dots$

$$\mathcal{CPS}[n]k = kn$$

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$$\begin{split} & \mathcal{CPS} \llbracket n \rrbracket \ k = k \ n \\ & \mathcal{CPS} \llbracket e_1 + e_2 \rrbracket \ k = \mathcal{CPS} \llbracket e_1 \rrbracket \left(\lambda n. \ \mathcal{CPS} \llbracket e_2 \rrbracket \left(\lambda m. \ k \left(n + m \right) \right) \right) \end{split}$$

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We write $\mathcal{CPS}[e] k = \dots$ instead of $\mathcal{CPS}[e] = \lambda k \dots$

```
\mathcal{CPS}[n]k = kn
\mathcal{CPS}[e_1 + e_2] k = \mathcal{CPS}[e_1] (\lambda n. \mathcal{CPS}[e_2] (\lambda m. k (n + m)))
\mathcal{CPS}[(e_1, e_2)] k = \mathcal{CPS}[e_1] (\lambda v. \mathcal{CPS}[e_2] (\lambda w. k (v, w)))
    \mathcal{CPS}[\#1\ e] k = \mathcal{CPS}[e] (\lambda v. k (\#1\ v))
    \mathcal{CPS}\llbracket\#2\ e\rrbracket\ k = \mathcal{CPS}\llbracket e\rrbracket\ (\lambda v.\ k\ (\#2\ v))
           \mathcal{CPS}[x] k = kx
    \mathcal{CPS}[\lambda x. e] k = k(\lambda x. \lambda k'. \mathcal{CPS}[e] k')
    \mathcal{CPS}[e_1 e_2] k = \mathcal{CPS}[e_1] (\lambda f. \mathcal{CPS}[e_2] (\lambda v. f v k))
```

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\mathcal{CPS}[n]k = kn
\mathcal{CPS}[e_1 + e_2] k = \mathcal{CPS}[e_1] (\lambda n. \mathcal{CPS}[e_2] (\lambda m. k (n + m)))
\mathcal{CPS}[(e_1, e_2)] k = \mathcal{CPS}[e_1] (\lambda v. \mathcal{CPS}[e_2] (\lambda w. k (v, w)))
    \mathcal{CPS}[\#1\ e] k = \mathcal{CPS}[e] (\lambda v. k (\#1\ v))
    \mathcal{CPS}\llbracket\#2\ e\rrbracket\ k = \mathcal{CPS}\llbracket e\rrbracket\ (\lambda v.\ k\ (\#2\ v))
           \mathcal{CPS}[x] k = kx
    \mathcal{CPS}[\lambda x. e] k = k(\lambda x. \lambda k'. \mathcal{CPS}[e] k')
    \mathcal{CPS}[e_1 e_2] k = \mathcal{CPS}[e_1] (\lambda f. \mathcal{CPS}[e_2] (\lambda v. f v k))
```

We write $\mathcal{CPS}[e] k = \dots$ instead of $\mathcal{CPS}[e] = \lambda k \dots$

 $(PS) (\chi_{K.X}) (((1+2)+3)+4) K =$ CPS[[kx.x]] (\lambda f. CPS[[...]] (\lambda k. CPS[...])
\lambda v. \(\operatorname{\pi} \) (\lambda k. CPS[...] (An CRS[4], CPS[[x]] k') (\lambda m. k (n+m))) JKK X. > K'. (Ak. CAS[[...] (An. (An. K(n+m)) H)) $\lambda k. k. (\lambda x. \lambda k'. k'x) AF$ $(\lambda k. k. (\lambda x. \lambda k'. k'x)) (\lambda k. (PSI...I) (\lambda n. \lambda v. (\lambda m. k. (n+m)) (1)) X$