

CS 4110

# Programming Languages & Logics

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## Lecture 19 Continuations



# Continuations

In the preceding translations, the control structure of the source language was translated directly into the corresponding control structure in the target language.

For example:

$$\mathcal{T}[\lambda x. e] = \lambda x. \mathcal{T}[e]$$

$$\mathcal{T}[e_1 e_2] = \mathcal{T}[e_1] \mathcal{T}[e_2]$$

What can go wrong with this approach?

# Continuations

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- A snippet of code that represents “the rest of the program”
- Can be used directly by programmers...
- ...or in program transformations by a compiler
- Make the control flow of the program explicit
- Also useful for defining the meaning of features like exceptions

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The original expression is equivalent to  $k_3 \ 1$ , or:

$$(\lambda c. (\lambda b. (\lambda a. (\lambda v. (\lambda x. x) v) (a - 4)) (3 * b)) (c + 2)) \ 1$$

## Example (Continued)

Recall that  $\text{let } x = e \text{ in } e'$  is syntactic sugar for  $(\lambda x. e') e$ .

Hence, we can rewrite the expression with continuations more succinctly as

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let c = 1 in  
let b = c + 2 in  
let a = 3 * b in  
let v = a - 4 in  
( $\lambda x. x$ ) v
```

# CPS Transformation

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We write  $\mathcal{CPS}\llbracket e \rrbracket k = \dots$  instead of  $\mathcal{CPS}\llbracket e \rrbracket = \lambda k. \dots$

We assume that the new variables introduced are “fresh.”

# CPS Transformation

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$$\mathcal{CPS}\llbracket e_1 + e_2 \rrbracket k = \mathcal{CPS}\llbracket e_1 \rrbracket (\lambda n. \mathcal{CPS}\llbracket e_2 \rrbracket (\lambda m. k\ (n + m)))$$

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$$\mathcal{CPS}[(e_1, e_2)] \ k = \mathcal{CPS}[e_1] \ (\lambda v. \mathcal{CPS}[e_2] \ (\lambda w. k \ (v, w)))$$

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