

# CS 423 Operating System Design: Concurrency

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\* Thanks for Prof. Adam Bates for the slides.

## Concurrency vs Parallelism



#### Two tasks

- I. Get a visa
- 2. Prepare slides

- I. Sequential execution
- 2. Concurrent execution
- 3. Parallel execution
- 4. Concurrent but not parallel
- 5. Parallel but not concurrent
- 6. Parallel and concurrent

# Why Concurrency?



- Servers
  - Multiple connections handled simultaneously
- Parallel programs
  - To achieve better performance
- Programs with user interfaces
  - To achieve user responsiveness while doing computation
- Network and disk bound programs
  - To hide network/disk latency

## Definitions



- Thread: A single execution sequence that represents a separately schedulable task.
  - Single execution sequence: intuitive and familiar programming model
  - separately schedulable: OS can run or suspend a thread at any time.
  - Schedulers operate over threads/tasks, both kernel and user threads.
- Does the OS protect all threads from one another?

## The Thread Abstraction



- Infinite number of processors
- Threads execute with variable speed



## Programmer vs. Processor View



#### **Programmer View**

Programmer's View

.

x = x + 1; y = y + x;z = x + 5y;

.

Possible
Execution
#1
...
...
...
x = x + 1;
y = y + x;
z = x + 5y;

Possible
Execution
#2
...
x = x + 1;

Thread is suspended.
Other thread(s) run.

Thread is resumed.

$$y = y + x;$$
  
 $z = x + 5y;$ 

Possible Execution #3

x = x + 1;y = y + x;

Thread is suspended. Other thread(s) run.

Thread is resumed.

z = x + 5y;

Variable Speed: Program must anticipate all of these possible executions

# Possible Executions



#### **Processor View**

One Execution	Another Execution
Thread 1	Thread 1
Thread 2	Thread 2
Thread 3	Thread 3
Another Execution	
Thread 1	
Thread 2	
Thread 3	

Something to look forward to when we discuss scheduling!

# Thread Ops



- thread\_create(thread, func, args)
   Create a new thread to run func(args)
- thread\_yield()
   Relinquish processor voluntarily
- thread\_join(thread)
   In parent, wait for forked thread to exit, then return
- thread\_exit
   Quit thread and clean up, wake up joiner if any

## Ex: threadHello



```
#define NTHREADS 10
thread t threads[NTHREADS];
main() {
    for (i = 0; i < NTHREADS; i++) thread_create(&threads[i], &go, i);</pre>
    for (i = 0; i < NTHREADS; i++) {
        exitValue = thread join(threads[i]);
        printf("Thread %d returned with %ld\n", i, exitValue);
    printf("Main thread done.\n");
}
void go (int n) {
    printf("Hello from thread %d\n", n);
    thread exit(100 + n);
    // REACHED?
```

# Ex: threadHello output



```
bash-3.2$ ./threadHello
Hello from thread 0
Hello from thread 1
Thread 0 returned 100
Hello from thread 3
Hello from thread 4
Thread 1 returned 101
Hello from thread 5
Hello from thread 2
Hello from thread 6
Hello from thread 8
Hello from thread 7
Hello from thread 9
Thread 2 returned 102
Thread 3 returned 103
Thread 4 returned 104
Thread 5 returned 105
Thread 6 returned 106
Thread 7 returned 107
Thread 8 returned 108
Thread 9 returned 109
Main thread done.
```

- Must "thread returned" print in order?
- What is maximum # of threads that exist when thread 5 prints hello?
- Minimum?
- Why aren't any messages interrupted mid-string?

# Create/Join Concurrency



- Threads can create children, and wait for their completion
- Data only shared before fork/after join
- Examples:
  - Web server: fork a new thread for every new connection
    - As long as the threads are completely independent
  - Merge sort
  - Parallel memory copy

## Ex: bzero



```
void blockzero (unsigned char *p, int length) {
    int i, j;
    thread t threads[NTHREADS];
    struct bzeroparams params[NTHREADS];
// For simplicity, assumes length is divisible by NTHREADS.
for (i = 0, j = 0; i < NTHREADS; i++, j += length/NTHREADS) {
        params[i].buffer = p + i * length/NTHREADS;
        params[i].length = length/NTHREADS;
        thread create p(&(threads[i]), &go, &params[i]);
    for (i = 0; i < NTHREADS; i++) {
        thread join(threads[i]);
```

## Thread Data Structures



Shared State

Thread 1's Per–Thread State

Thread 2's Per-Thread State

Code

Global

**Variables** 

Thread Control Block (TCB)

Stack

Information

Saved

Registers

Thread

Metadata

Thread Control Block (TCB)

Stack
Information

Saved

Thread

Registers

Metadata

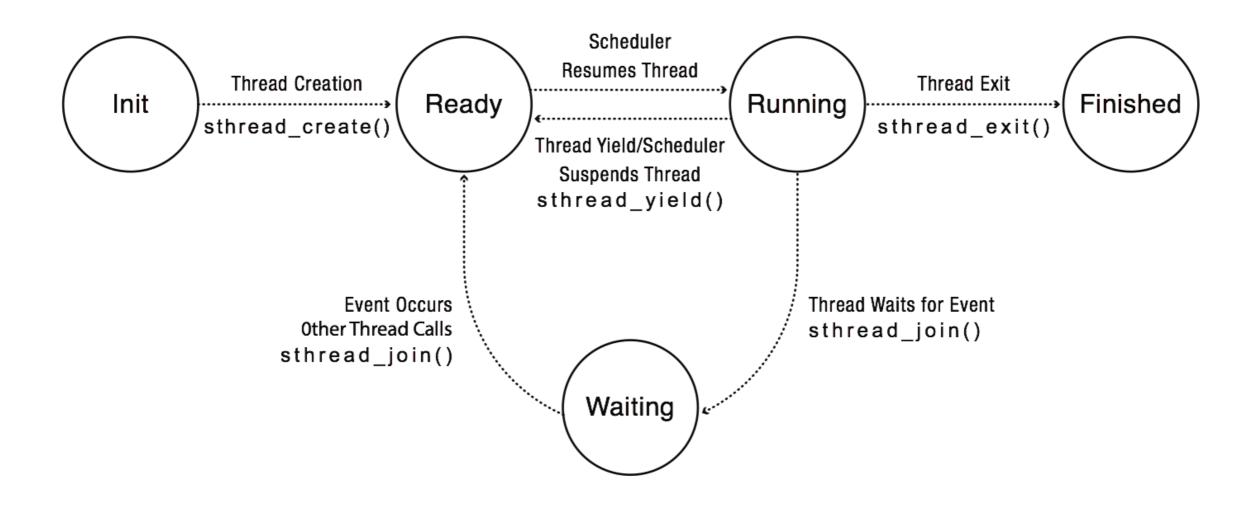
Heap

Stack

Stack

# Thread Lifecycle





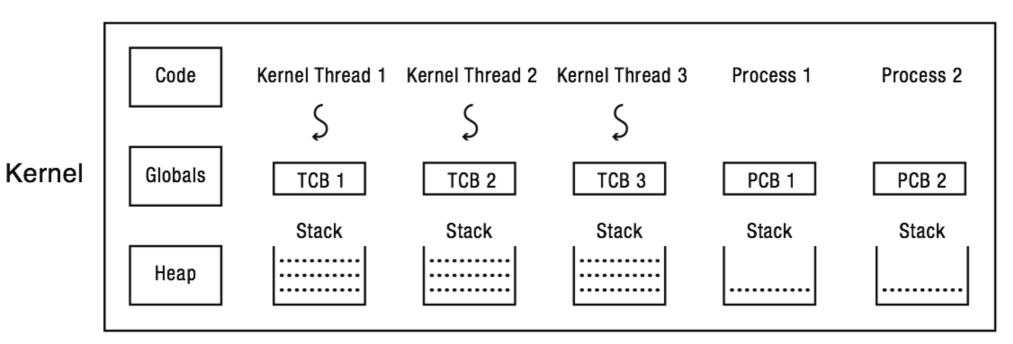
# Thread Implementations



- Kernel threads
  - Thread abstraction only available to kernel
  - To the kernel, a kernel thread and a single threaded user process look quite similar
- Multithreaded processes using kernel threads
  - Kernel thread operations available via syscall
- User-level threads
  - Thread operations without system calls

## Multithreaded OS Kernel





**User-Level Processes** 

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# Implementing Threads



- Thread\_fork(func, args)
  - Allocate thread control block
  - Allocate stack
  - Build stack frame for base of stack (stub)
  - Put func, args on stack
  - Put thread on ready list
  - Will run sometime later (maybe right away!)
- stub(func, args):
  - Call (\*func)(args)
  - If return, call thread\_exit()

# Implementing Threads



- Thread\_Exit
  - Remove thread from the ready list so that it will never run again
  - Free the per-thread state allocated for the thread

## Ex: Two Threads call Yield



#### Thread 1's instructions

"return" from thread\_switch
into stub
call go
call thread\_yield
choose another thread
call thread\_switch
save thread 1 state to TCB
load thread 2 state

#### Thread 2's instructions

"return" from thread\_switch
into stub
call go
call thread\_yield
choose another thread
call thread\_switch
save thread 2 state to TCB
load thread 1 state

#### **Processor's instructions**

"return" from thread switch into stub call go call thread yield choose another thread call thread switch save thread 1 state to TCB load thread 2 state "return" from thread\_switch into stub call go call thread\_yield choose another thread call thread switch save thread 2 state to TCB load thread 1 state return from thread\_switch return from thread\_yield call thread\_yield choose another thread call thread\_switch

return from thread\_switch return from thread\_yield call thread\_yield choose another thread call thread\_switch

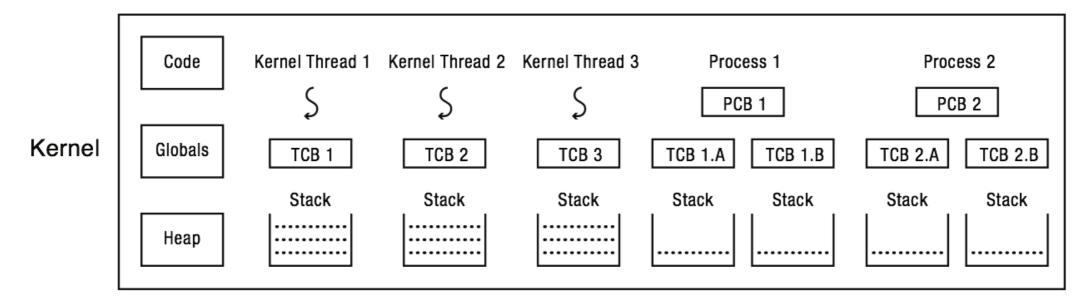


#### Take 1:

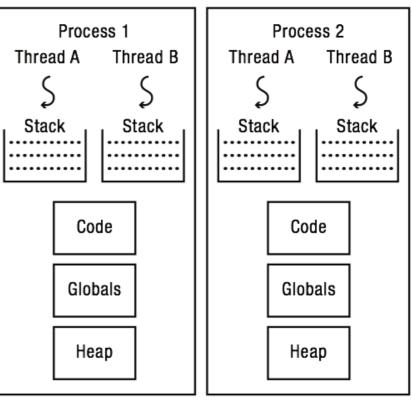
- User thread = kernel thread (Linux, MacOS)
  - System calls for thread fork, join, exit (and lock, unlock,...)
  - Kernel does context switch
  - Simple, but a lot of transitions between user and kernel mode



#### Take 1:



**User-Level Processes** 





#### Take 2:

- Green threads (early Java)
  - User-level library, within a single-threaded process
  - Library does thread context switch
  - Preemption via upcall/UNIX signal on timer interrupt
  - Use multiple processes for parallelism
  - Shared memory region mapped into each process



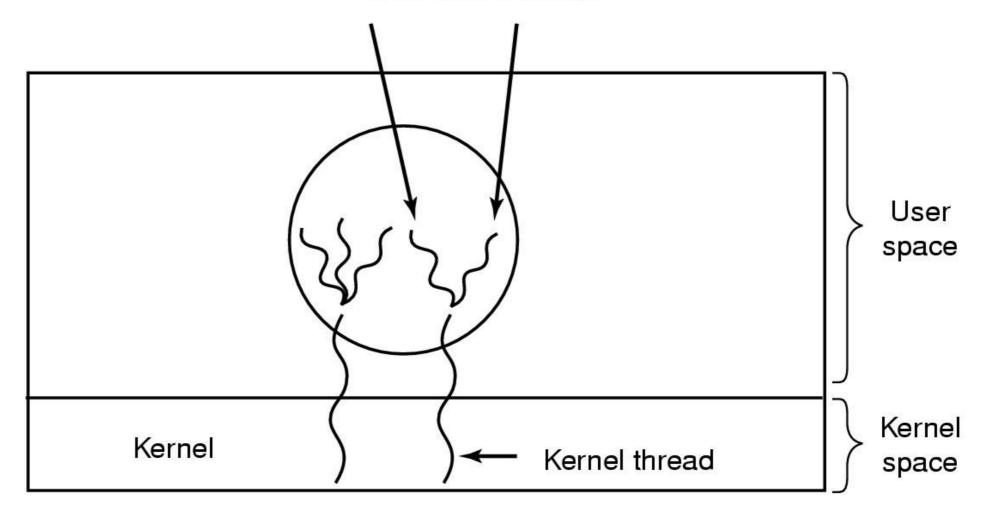
#### Take 3:

- Scheduler activations (Windows 8):
  - Kernel allocates processors to user-level library
  - Thread library implements context switch
  - Thread library decides what thread to run next
- Upcall whenever kernel needs a user-level scheduling decision:
  - Process assigned a new processor
  - Processor removed from process
  - System call blocks in kernel



#### Take 3: (What's old is new again)

Multiple user threads on a kernel thread



M:N model multiplexes N user-level threads onto M kernel-level threads

Good idea? Bad Idea?

# Question



Compare event-driven programming with multithreaded concurrency. Which is better in which circumstances, and why?