

# CS 423 Operating System Design: Midterm Review

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# Midterm Details



- In-Class, Oct 18<sup>th</sup> (75 minutes).
- Close book: No textbooks, no paper notes, no printed sheets. No Internet!
  - I will be the "Internet" ask me questions if you don't remember something.
- Content: All lecture and text material covered prior to before the exam (including memory memory I&II).

# Midterm Details



- No need to memorize terms.
- Ask me during the exam, if you forget some names or abbreviation.
  - Demo: "What is MLFQ"?
- Mostly short answers + small coding questions
  - Review MP1!
- If you really want to have a sample problem, here is one:
  - In x86-64 virtual memory design, the huge pages are 2MB and 1GB (the regular page is 4KB). Can we support other sizes like 4MB and 16MB? Why or why not?

# More Q&A





### Remainder of these slides

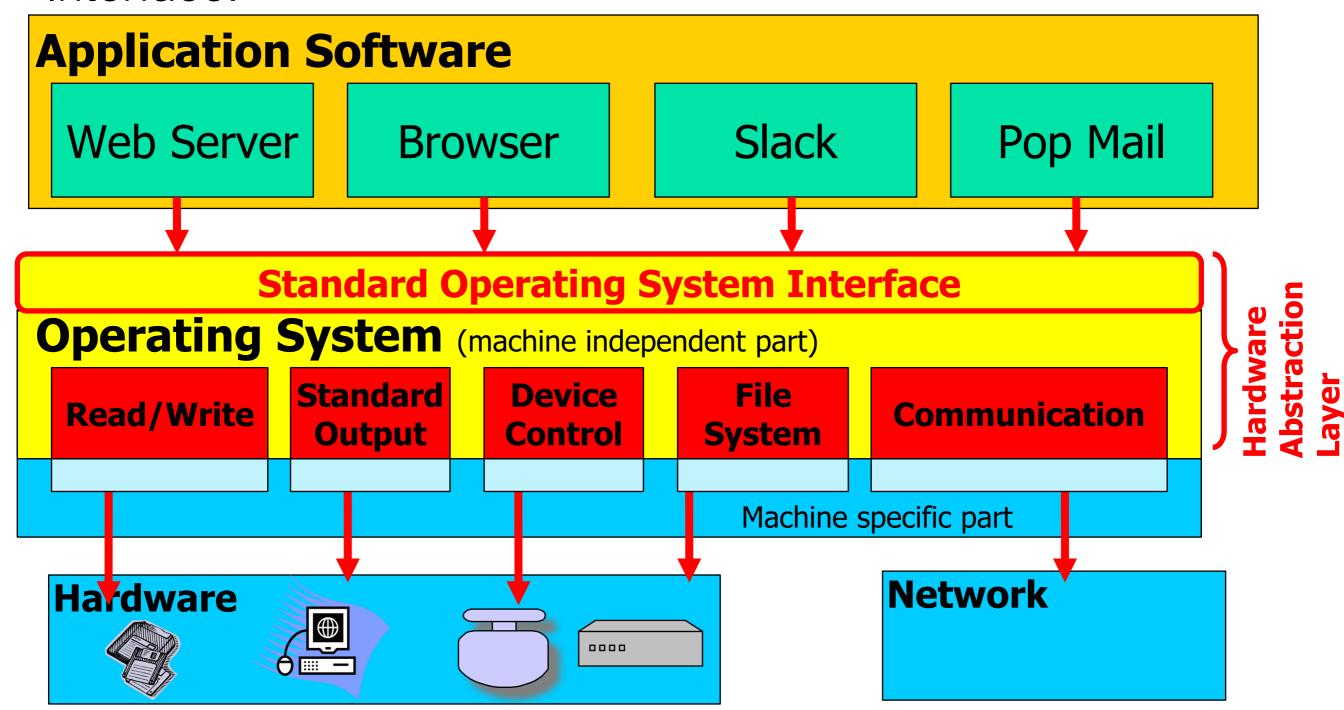


- This is not a study guide
- I prepared these by walking the lecture slides from start to finish and sampling important concepts
- Slides intended to prompt discussion and questions
- Test is written at this point, but this deck leaks minimal information; don't try to read into which slides I did/didn't copy over to here.
- There are no memory slides since we just covered it, but obviously there will be questions about memory on the exam.

# Overview: OS Stack



OS Runs on Multiple Platforms while presenting the same Interface:



### Overview: OS Roles



#### Role #1: Referee

- Manage resource allocation between users and applications
- Isolate different users and applications from one another
- Facilitate and mediate communication between different users and applications

#### Role #2: Illusionist

- Allow each application to believe it has the entire machine to itself
- Create the appearance of an Infinite number of processors, (near) infinite memory
- Abstract away complexity of reliability, storage, network communication...

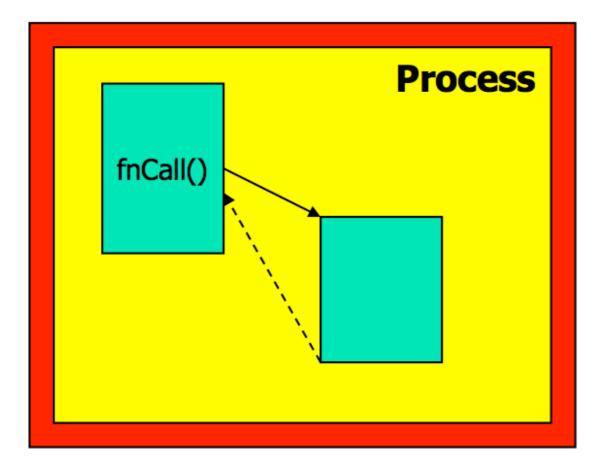
#### Role #3: Glue

- Manage hardware so applications can be machine-agnostic
- Provide a set of common services that facilitate sharing among applications
- Examples of "Glue" OS Services?

# Review: System Calls



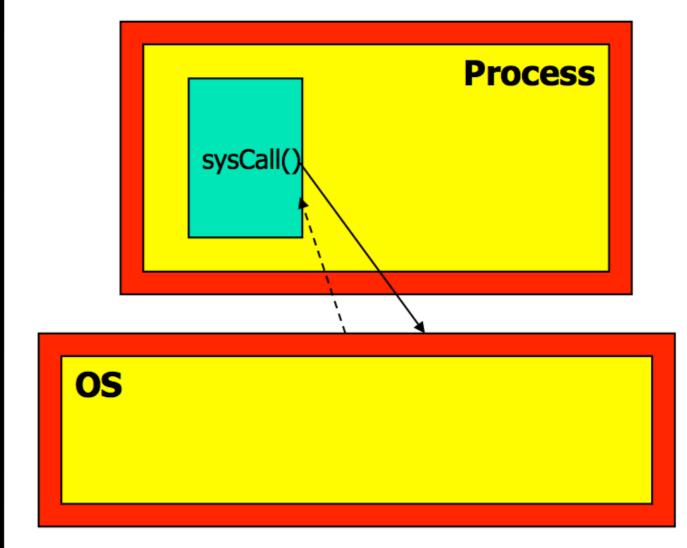
### **Function Calls**



Caller and callee are in the same Process

- Same user
- Same "domain of trust"

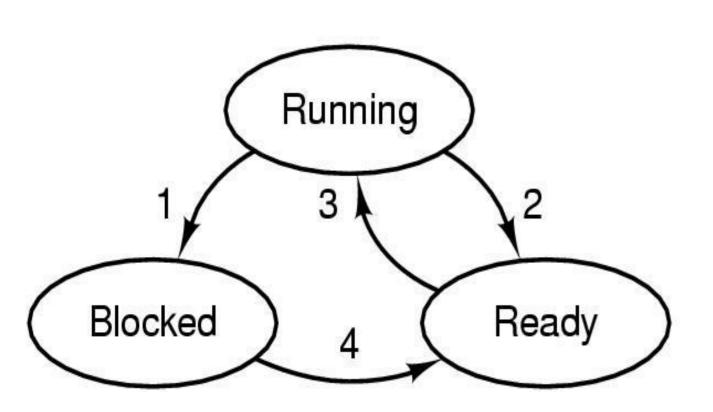
### System Calls



- OS is trusted; user is not.
- OS has super-privileges; user does not
- Must take measures to prevent abuse

### Review: Process Abstraction





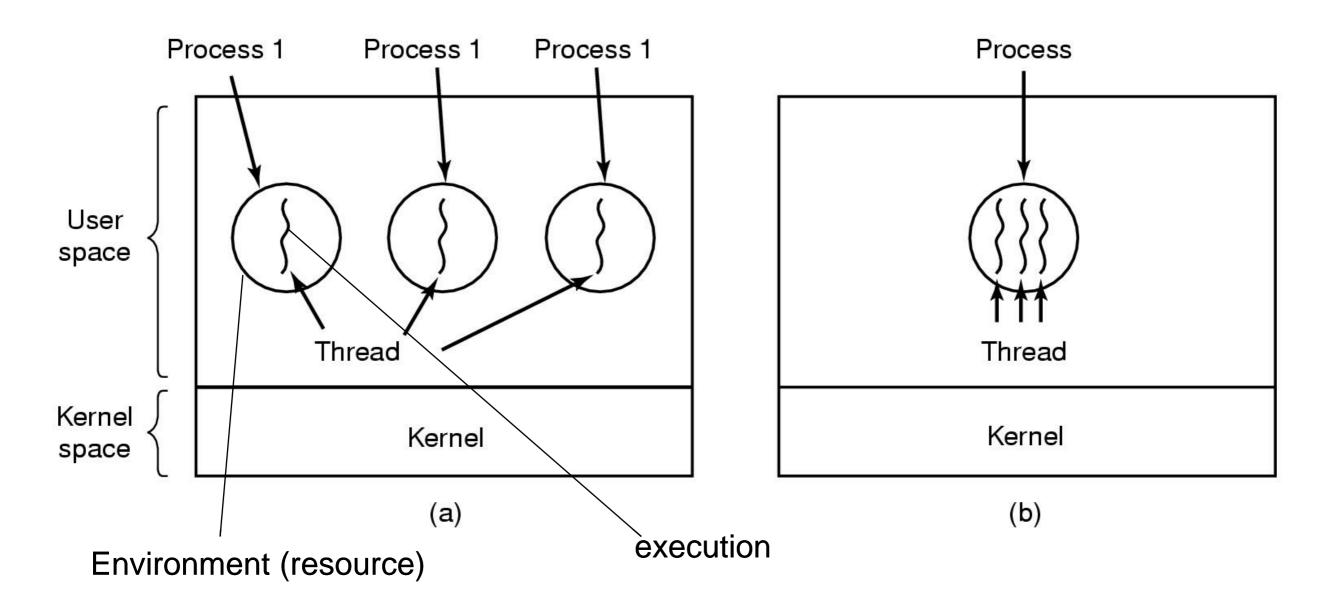
- 1. Process blocks for input
- 2. Scheduler picks another process
- 3. Scheduler picks this process
- 4. Input becomes available

- Possible process states
  - Running (occupy CPU)
  - Blocked
  - Ready (does not occupy CPU)
  - Other states: suspended, terminated

Question: in a single processor machine, how many process can be in running state?

### Review: Threads



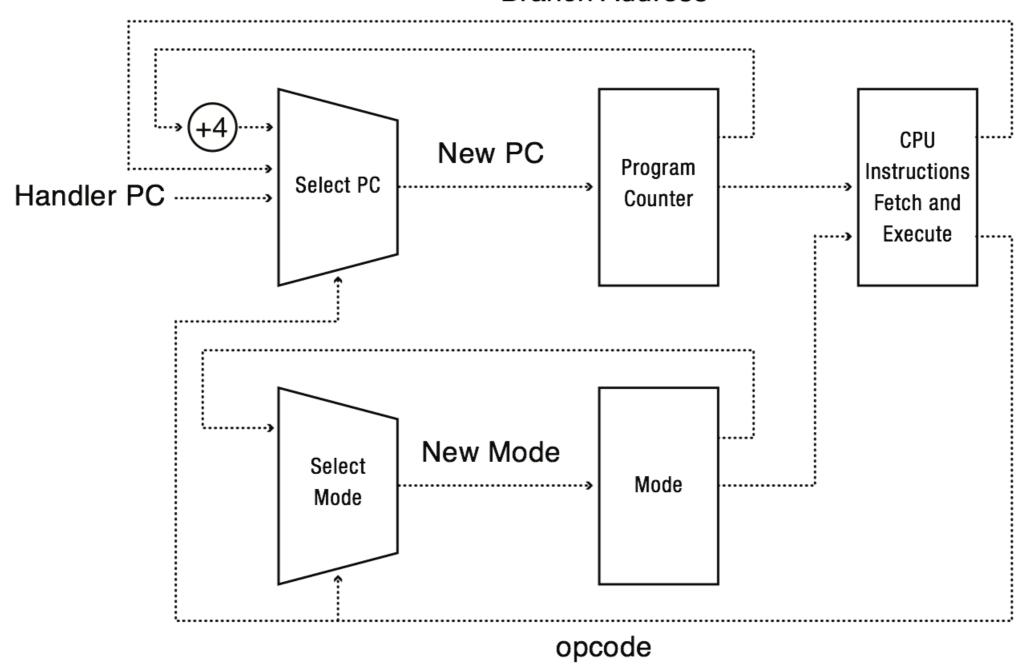


- (a) Three processes each with one thread
- (b) One process with three threads

# Kernel Abstraction: HW Support

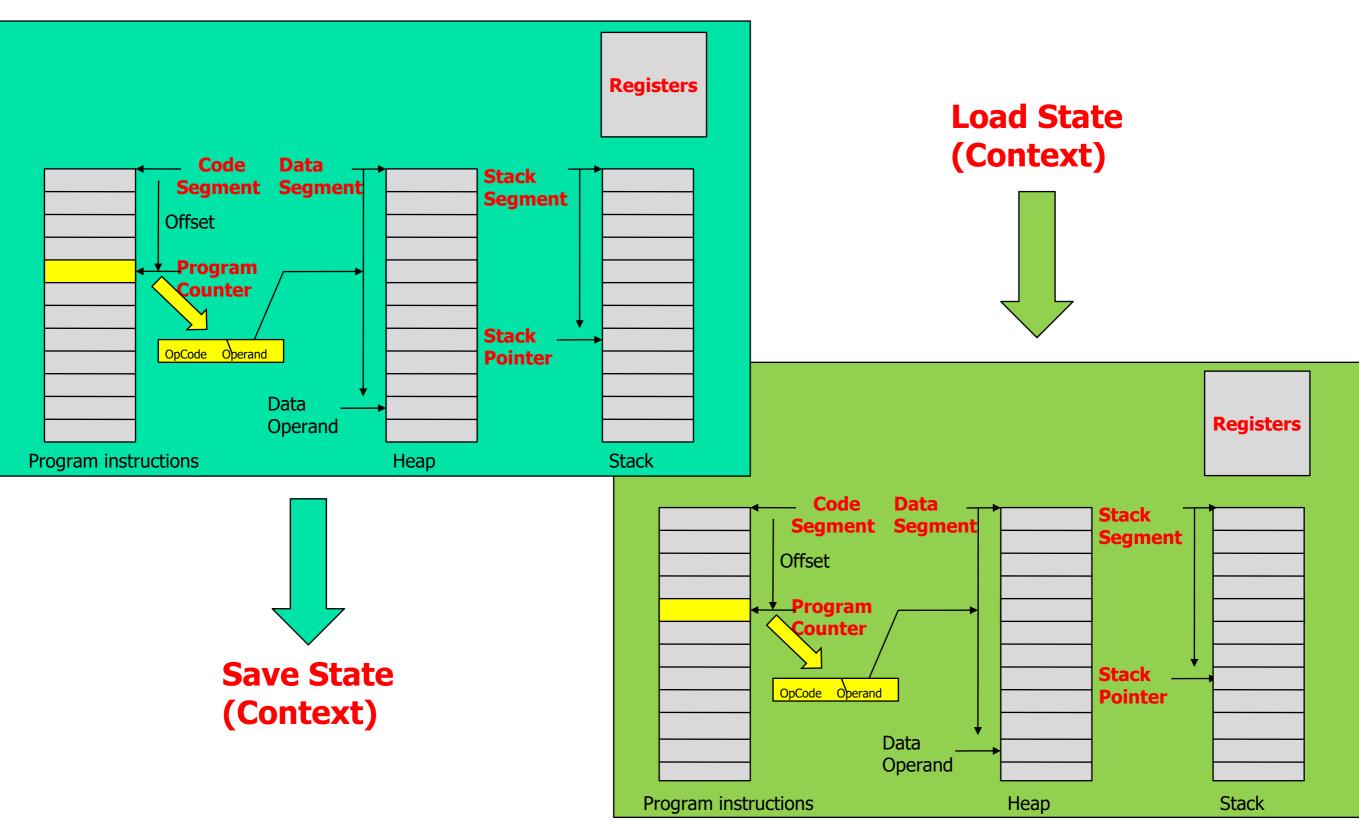


### **Branch Address**



### Kernel Abstraction: CTX Switch

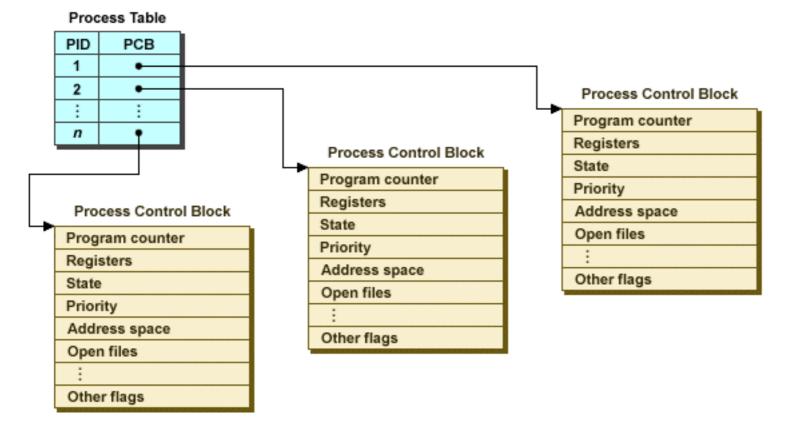


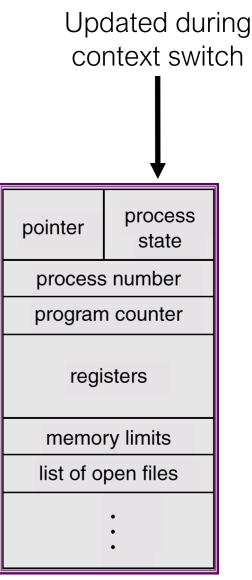


### Kernel Abstraction: PCBs



The state for processes that are not running on the CPU are maintained in the Process Control Block (PCB) data structure





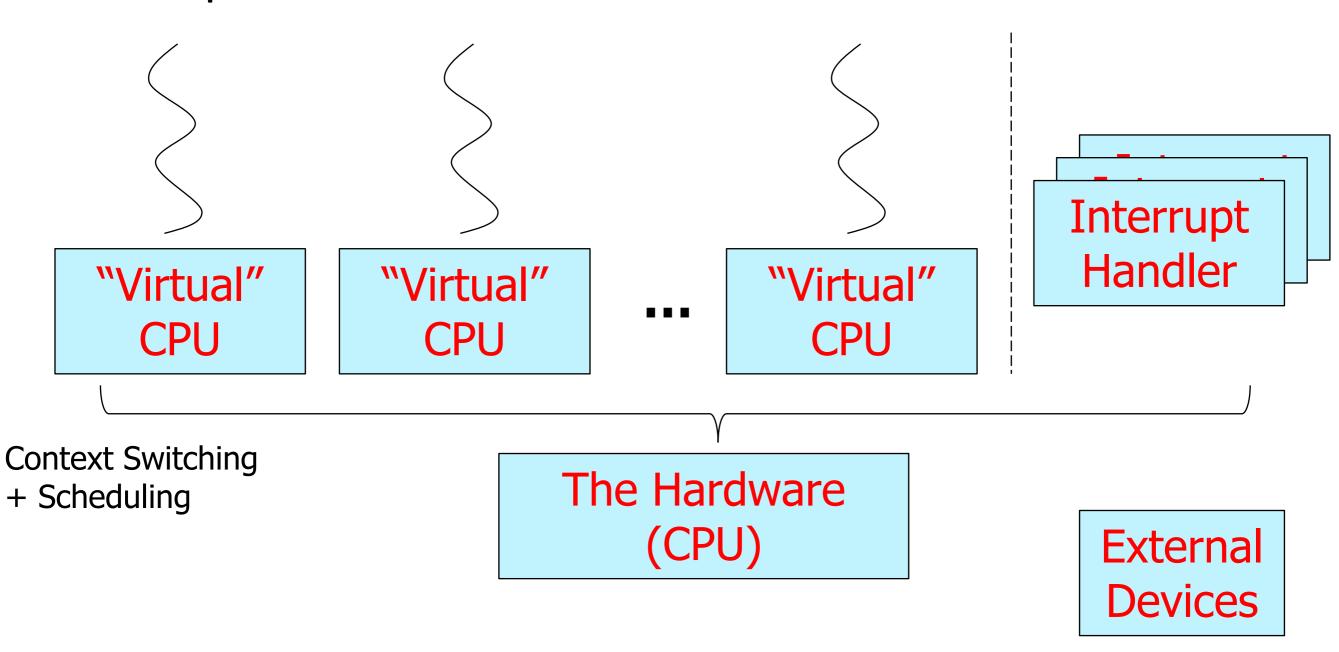
An alternate PCB diagram

# Interrupts: Model



Interrupts to drive scheduling decisions!

Interrupt handlers are also tasks that share the CPU.

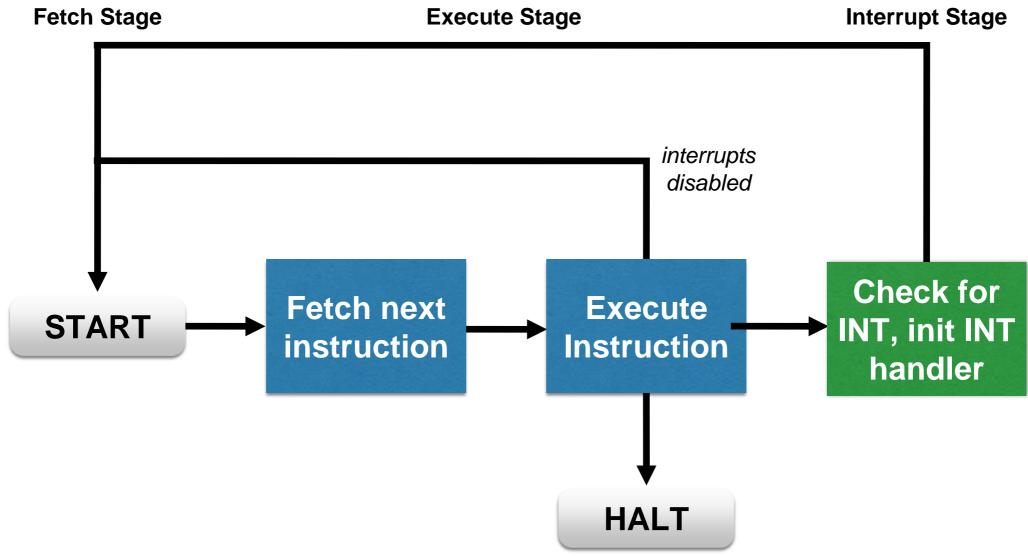


# Interrupts: Handling



How does interrupt handling change the instruction

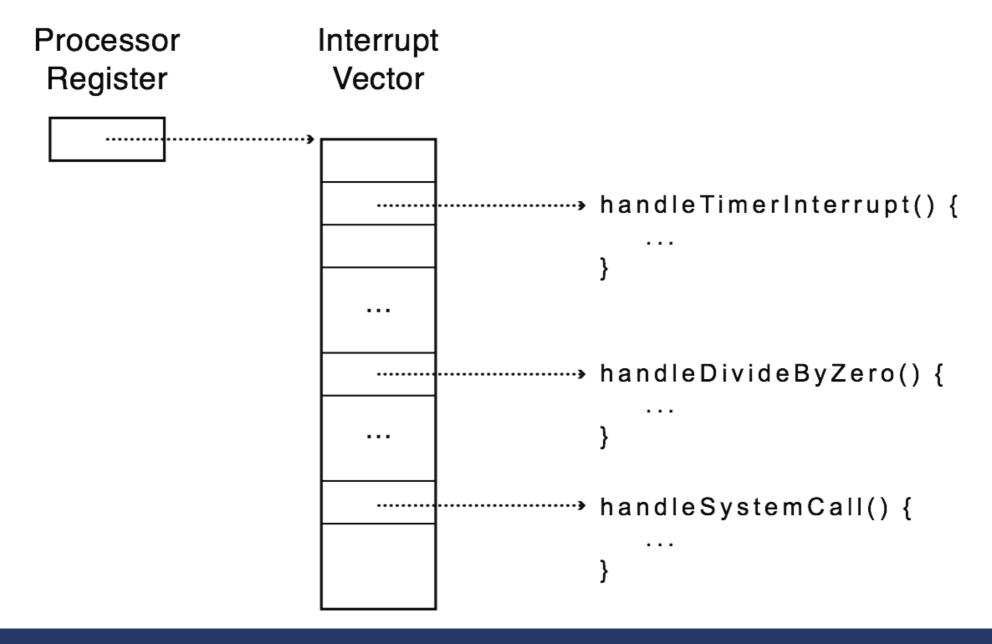
cycle?



# Interrupts: Handling



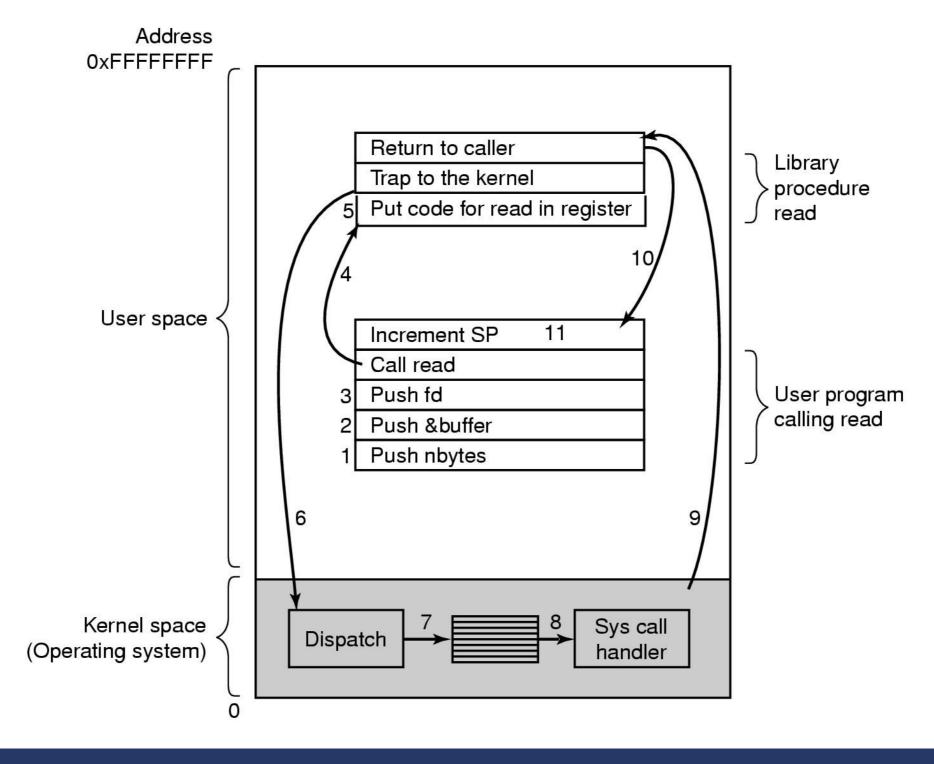
Table set up by OS kernel; pointers to code to run on different events



### System Calls: Under the Hood

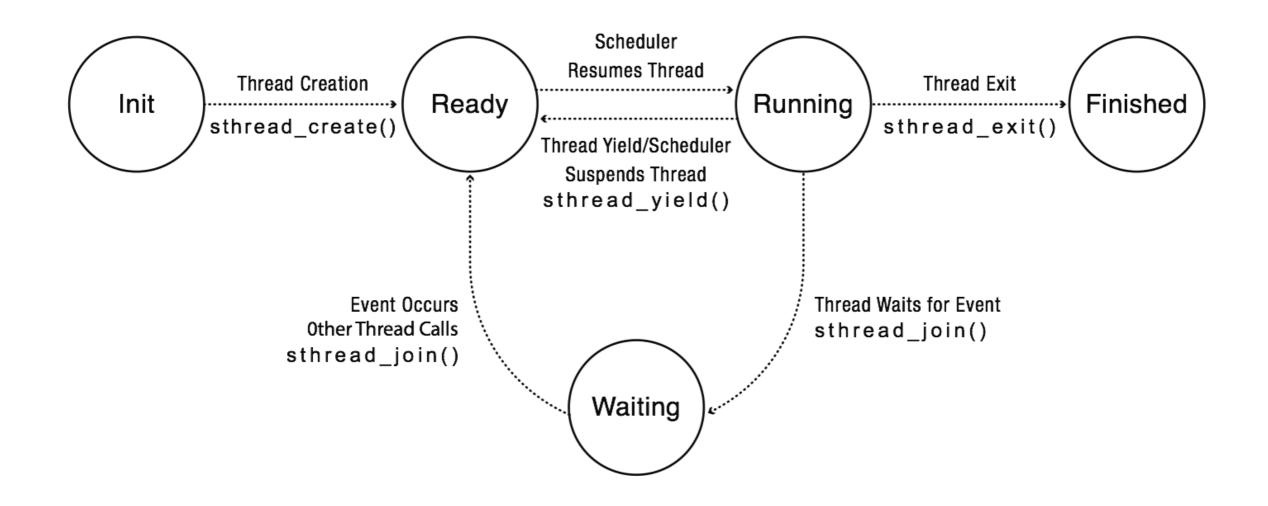


### read (fd, buffer, nbytes)



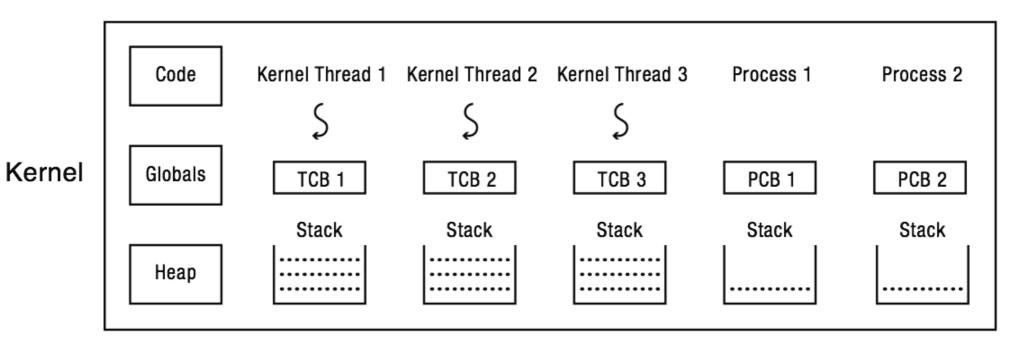
# Concurrency: Thread Lifecycle





# Concurrency: Thread State





**User-Level Processes** 

Process 1 Thread	Process 2 Thread
Stack	Stack
Code	Code
Globals	Globals
Неар	Неар

# Synchronization: Principals



**Concurrent Applications** 

**Shared Objects** 

**Bounded Buffer** 

**Barrier** 

Synchronization Variables

Semaphores Locks

**Condition Variables** 

Atomic Instructions

Interrupt Disable Test-and-Set

Hardware

Multiple Processors

Hardware Interrupts

# Queueing Lock Implementation (1 Proc)



```
Lock::acquire() {
                                     Lock::release() {
    disableInterrupts();
                                         disableInterrupts();
                                         if (!waiting.Empty()) {
    if (value == BUSY) {
        waiting.add(myTCB);
                                             next = waiting.remove();
        myTCB->state = WAITING;
                                             next->state = READY;
        next = readyList.remove();
                                             readyList.add(next);
        switch (myTCB, next);
                                         } else {
        myTCB->state = RUNNING;
                                          value = FREE;
    } else {
        value = BUSY;
                                         enableInterrupts();
    enableInterrupts();
```

# Multiprocessor Sync Tool!



- Read-modify-write (RMW) instructions
  - Atomically read a value from memory, operate on it, and then write it back to memory
  - Intervening instructions prevented in hardware
- Examples
  - Test and set
  - Intel: xchgb, lock prefix
  - Compare and swap
- Any of these can be used for implementing locks and condition variables!

### Test-and-set



- The **test-and-set** instruction is an instruction used to write 1 (set) to a memory location and return its old value as a single **atomic** (i.e., non-interruptible) operation. If multiple processes may access the same memory location, and if a process is currently performing a test-and-set, no other process may begin another test-and-set until the first process's test-and-set is finished.
- Please implement a lock using test-and-set (5 minutes)

```
lock:acquire() {
}
lock:release() {
}
```

# Synchronization: Locks



- Lock::acquire
  - wait until lock is free, then take it
- Lock::release
  - release lock, waking up anyone waiting for it
- 1. At most one lock holder at a time (safety)
- 2. If no one holding, acquire gets lock (progress)
- If all lock holders finish and no higher priority waiters, waiter eventually gets lock (progress)

# Synchronization: Condition Variables



- Waiting inside a critical section
  - Called only when holding a lock
- <u>CV::Wait</u> atomically release lock and relinquish processor
  - Reacquire the lock when wakened
- CV::Signal wake up a waiter, if any
- CV::Broadcast wake up all waiters, if any

# Synchronization: Spinlocks



- A spinlock is a lock where the processor waits in a loop for the lock to become free
  - Assumes lock will be held for a short time
  - Used to protect the CPU scheduler and to implement locks

```
Spinlock::acquire() {
    while (testAndSet(&lockValue) == BUSY)
    ;
}
Spinlock::release() {
    lockValue = FREE;
    memorybarrier();
}
```

# Semaphores



- Semaphore has a non-negative integer value
  - P() atomically waits for value to become > 0, then decrements
  - V() atomically increments value (waking up waiter if needed)
- Semaphores are like integers except:
  - Only operations are P and V
  - Operations are atomic
    - If value is 1, two P's will result in value 0 and one waiter

# Scheduling: Principals

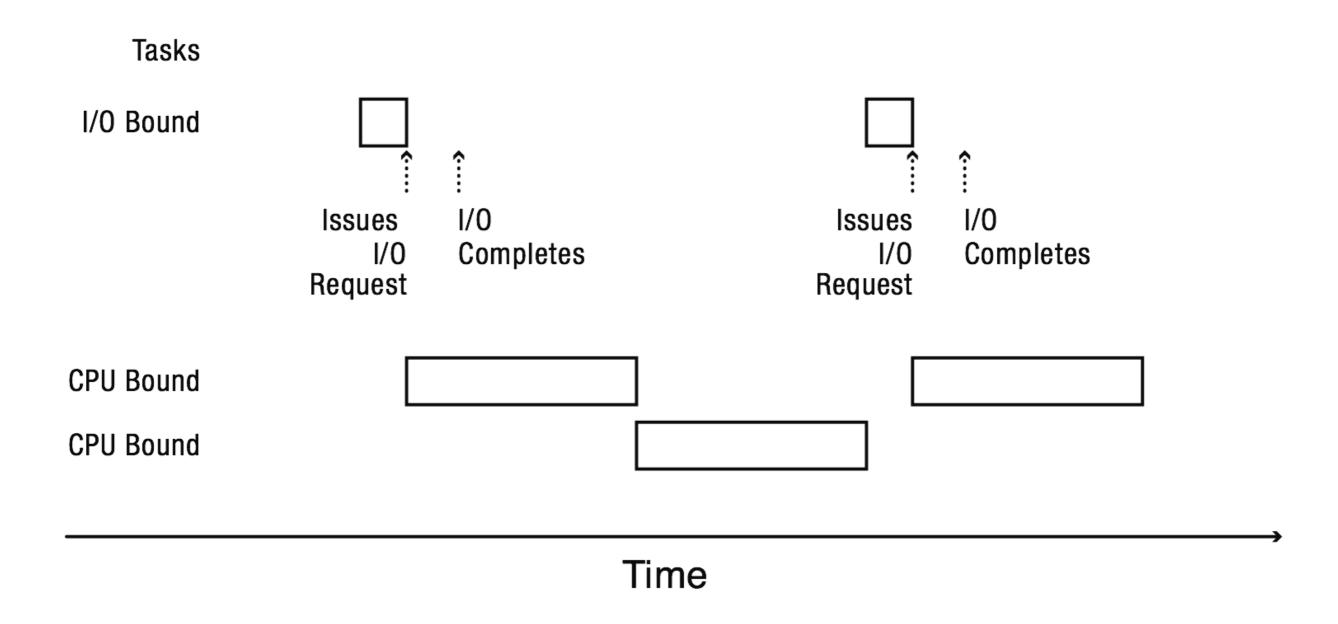


- Basic scheduling algorithms
  - FIFO (FCFS)
  - Shortest job first
  - Round Robin

• What is an optimal algorithm in the sense of maximizing the number of jobs finished (i.e., minimizing average response time)?

# Scheduling: Mixed Workloads??





# Scheduling: MFQ



Priority Time Slice (ms)

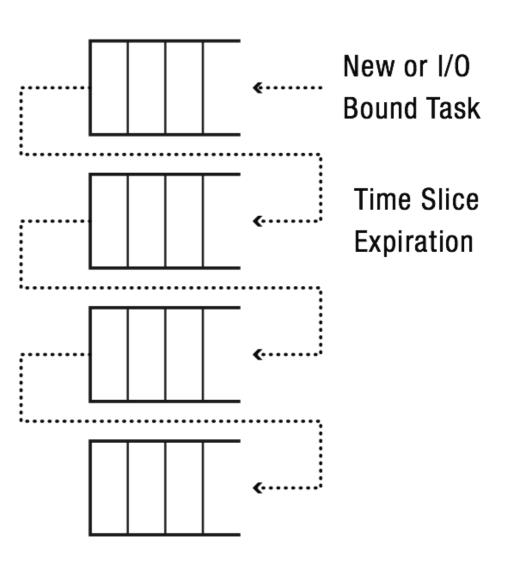
10

2 20

3 40

4 80

### **Round Robin Queues**



# Scheduling: Early Linux



- Linux 1.2: circular queue w/ round-robin policy.
  - Simple and minimal.
  - Did not meet many of the aforementioned goals

 Linux 2.2: introduced scheduling classes (realtime, non-real-time).

```
/* Scheduling Policies
*/
#define SCHED_OTHER 0 // Normal user tasks (default)
#define SCHED_FIFO 1 // RT: Will almost never be preempted
#define SCHED_RR 2 // RT: Prioritized RR queues
```

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# Scheduling: CFS

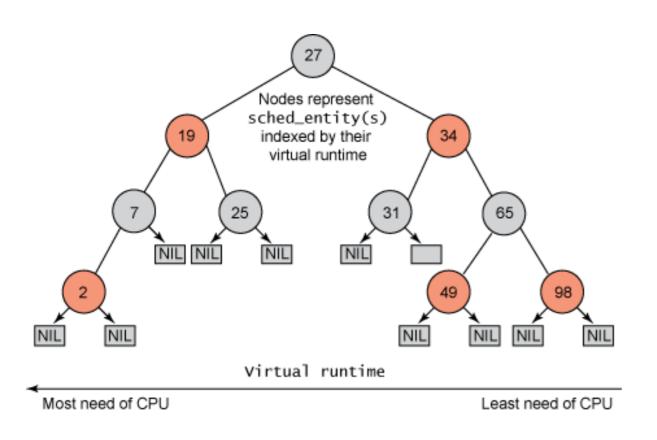


- Merged into the 2.6.23 release of the Linux kernel and is the default scheduler.
- Scheduler maintains a red-black tree where nodes are ordered according to received virtual execution time
- Node with smallest virtual received execution time is picked next
- Priorities determine accumulation rate of virtual execution time
  - Higher priority → slower accumulation rate

# Scheduling: Red-Black Trees



CFS dispenses with a run queue and instead maintains a time-ordered red-black tree. Why?



An RB tree is a BST w/ the constraints:

- 1. Each node is red or black
- 2. Root node is black
- 3. All leaves (NIL) are black
- 4. If node is red, both children are black
- 5. Every path from a given node to its descendent NIL leaves contains the same number of black nodes

Takeaway: In an RB Tree, the path from the root to the farthest leaf is no more than twice as long as the path from the root to the nearest leaf.

# Scheduling: Multi-Processor



- CPU affinity would seem to necessitate a <u>multi-queue</u> approach to scheduling... but how?
- Asymmetric Multiprocessing (AMP): One processor (e.g., CPU 0) handles all scheduling decisions and I/O processing, other processes execute only user code.
- <u>Symmetric Multiprocessing (SMP)</u>: Each processor is self-scheduling. Could work with a single queue, but also works with private queues.
  - Potential problems?

# Virtual Memory



- Provide user with virtual memory that is as big as user needs
- Store virtual memory on disk
- Cache parts of virtual memory being used in real memory
- Load and store cached virtual memory without user program intervention



### virtual iviemory

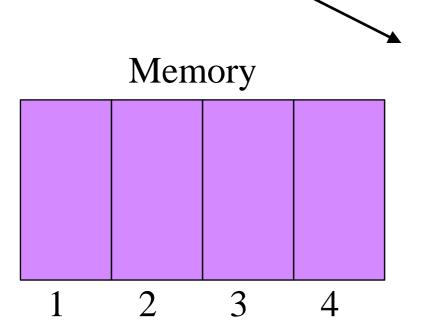


Cyctome



- Fixed partitions
  - Internal fragmentation
- Segmentation (variable partition)
  - External fragmentation



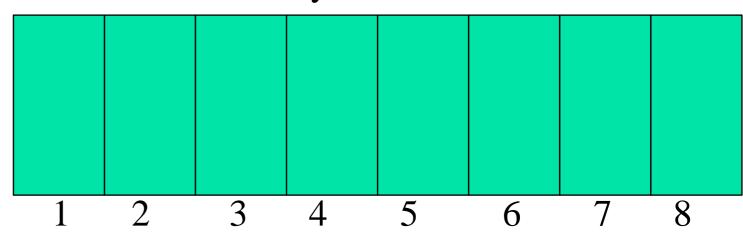




Page Table

1
2
3
4

Virtual Memory Stored on Disk

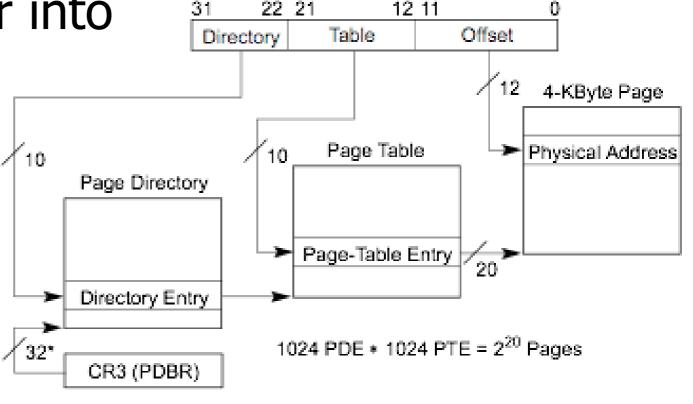


# Multi-level Page Tables



### Example: Addressing in a Multi-level Page Table system.

- A logical address (on 32-bit x86 with 4k page size) is divided into
  - A page number consisting of 20 bits
  - A page offset consisting of 12 bits
- Divide the page number into
  - A 10-bit page directory
  - A 10-bit page number



Linear Address

<sup>\*32</sup> bits aligned onto a 4-KByte boundary.

# Page Faults



- Occur when we access a virtual page that is not mapped into any physical page
  - A fault is triggered by hardware
- Page fault handler (in OS's VM subsystem)
  - Find if there is any free physical page available
    - If no, evict some resident page to disk (swapping space)
  - Allocate a free physical page
  - Load the faulted virtual page to the prepared physical page
  - Modify the page table