

Solutions to Exercises 2

Exercise 1 (Traces).

1. Since there are n variables, which can take two values, there are 2^n possible states.
2. As in class, $\bar{s} = (s_1, \dots, s_n)$ and exponent are used to represent the variables in the different states (i.e. $\bar{s}^k = (s_1^k, \dots, s_n^k)$).

- We note

$$\bar{v}^k = (s_1^k, \dots, s_n^k, a_1^k, \dots, a_m^k, x_1^k, \dots, x_\ell^k)$$

$$F_{(=k)} = \exists \bar{v}^0, \dots, \bar{v}^{k-1}, \bar{s}^k. \text{Init} [\bar{s} := \bar{s}^0] \wedge \left(\bigwedge_{i=0}^{k-1} R_i \right) \wedge (\bar{s}^k = \bar{s})$$

Another solution:

$$\exists \bar{v}^0, \dots, \bar{v}^{k-1}.$$

$$\text{Init} [\bar{s} := \bar{s}^0] \wedge \left(\bigwedge_{i=0}^{k-2} R_i \right) \wedge R \left[(\bar{s}, \bar{a}, \bar{x}, \bar{s}') := (\bar{s}^{k-1}, \bar{a}^{k-1}, \bar{x}^{k-1}, \bar{s}) \right]$$

- $F_{(\leq k)} = \bigvee_{i=0}^k F_{(=i)}$
 - The “intuitive” solution is $F_{(\leq \infty)}$, however this formula is infinite. Using question (1), it can be reduced to $F_{(\text{reachable})} = F_{(\leq 2^n - 1)}$
 - $F_{(=k, \text{Err})} = \exists \bar{v}^0, \dots, \bar{v}^{k-1}, \bar{s}^k. (\bar{s}^0 = \bar{s}) \wedge \left(\bigwedge_{i=0}^{k-1} R_i \right) \wedge E [\bar{s} := \bar{s}^k]$
 - $F_{(\leq k, \text{Err})} = \bigvee_{i=0}^k F_{(=i, \text{Err})}$
 - $F_{(\text{stuck})} = \neg \exists \bar{a}, \bar{x}, \bar{s}'. R$
3. • $\neg \exists \bar{s}. F_{(\text{reachable})} \wedge E$
 - $\neg \exists \bar{s}. F_{(\text{reachable})} \wedge F_{(\text{stuck})}$
 - $\forall \bar{s}. F_{(\leq k)}$
 - Note that we are only allowed to quantify on propositional variables. As such, a formula such as

$$\forall k. \exists \bar{s}. F_{(=k)} \wedge \neg F_{(\text{stuck})}$$

is not allowed, as k ranges (implicitly) over \mathbb{N} .

Consider instead

$$\exists \bar{s}. F_{(=2^n)}$$

if such a state (\bar{s}) exists, the underlying trace contains $2^n + 1$ states (since it is 2^n steps long). By the pigeon hole principle, one of these states must appear twice. This means that there is a part of the trace which can be repeated infinitely (“pumped”), implying the existence of an infinite trace (see the proof of the [pumping lemma](#) for regular languages which relies on the same principle).

Exercise 2 (Tseytin Transformation).

1. Any expression of the type $y_k \leftrightarrow x_i * x_j$ is easily convertible to a CNF.

$$\begin{aligned} y_k \leftrightarrow x_i \vee x_j &\equiv (y_k \rightarrow x_i \vee x_j) \wedge (x_i \vee x_j \rightarrow y_k) \\ &\equiv (\neg y_k \vee x_i \vee x_j) \wedge (\neg x_i \vee y_k) \wedge (\neg x_j \vee y_k) \\ y_k \leftrightarrow x_i \wedge x_j &\equiv (y_k \rightarrow x_i \wedge x_j) \wedge (x_i \wedge x_j \rightarrow y_k) \\ &\equiv (\neg y_k \vee x_i) \wedge (\neg y_k \vee x_j) \wedge (\neg x_i \vee \neg x_j \vee y_k) \\ y_k \leftrightarrow x_i \rightarrow x_j &\equiv y_k \leftrightarrow \neg x_i \vee x_j \\ &\equiv (\neg y_k \vee \neg x_i \vee x_j) \wedge (x_i \vee y_k) \wedge (\neg x_j \vee y_k) \\ y_k \leftrightarrow \neg x_i &\equiv (y_k \rightarrow \neg x_i) \wedge (\neg x_i \rightarrow y_k) \\ &\equiv (\neg y_k \vee \neg x_i) \wedge (x_i \vee y_k) \end{aligned}$$

Let’s first define the mapping between sub formulas and fresh variables:

$$\begin{aligned} y_1 &\leftrightarrow \neg b \\ y_2 &\leftrightarrow a \vee y_1 \\ y_3 &\leftrightarrow b \rightarrow c \\ y_4 &\leftrightarrow \neg y_3 \\ y_5 &\leftrightarrow y_2 \wedge y_4 \\ y_6 &\leftrightarrow y_5 \rightarrow a \end{aligned}$$

The Tseytin transformation of the formula is therefore:

$$\begin{aligned} &(y_1 \leftrightarrow \neg b) \wedge (y_2 \leftrightarrow a \vee y_1) \wedge (y_3 \leftrightarrow b \rightarrow c) \wedge (y_4 \leftrightarrow \neg y_3) \wedge \\ &(y_5 \leftrightarrow y_2 \wedge y_4) \wedge (y_6 \leftrightarrow y_5 \rightarrow a) \wedge y_6 \\ = &(\neg y_1 \vee \neg b) \wedge (b \vee y_1) \wedge (\neg y_2 \vee a \vee y_1) \wedge (\neg a \vee y_2) \wedge (\neg y_1 \vee y_2) \wedge \\ &(\neg y_3 \vee \neg b \vee c) \wedge (b \vee y_3) \wedge (\neg c \vee y_3) \wedge (\neg y_4 \vee \neg y_3) \wedge (y_3 \vee y_4) \wedge \\ &(\neg y_5 \vee y_2) \wedge (\neg y_5 \vee y_4) \wedge (\neg y_2 \vee \neg y_4 \vee y_5) \wedge (\neg y_6 \vee \neg y_5 \vee a) \wedge \\ &(y_5 \vee y_6) \wedge (\neg a \vee y_6) \wedge (\neg y_6 \vee \neg y_7) \wedge (y_6 \vee y_7) \wedge y_7 \end{aligned}$$

2. We first show that they might not be equivalent by providing a small counterexample. As written above, the Tseytin transform of the formula $\neg x$ is $(y \leftrightarrow \neg x) \wedge y$. The value of $\neg x$ when $x = 0$ is 1, whereas the value of its Tseytin transformation when $x = 0, y = 0$, is 0. Therefore the two formulas are not equivalent.

Let's now prove that a formula is satisfiable if and only if its Tseytin transformation is satisfiable as well.

Let φ be a formula and $V = \{x_i \mid x_i \in \text{FV}(\varphi)\}$ its set of variables. One can notice (and prove by induction) that the Tseytin transformation of φ is equivalent to:

$$y_n \wedge \bigwedge_{i=1}^n (y_i \leftrightarrow \psi_i)$$

where $\{\psi_i\}_{0 \leq i \leq n}$ are all the (non-atomic) subformulas of φ ; in particular, $\psi_n = \varphi$. Therefore given an assignment α of V , a clause $(y_i \leftrightarrow \psi_i)$ is true if and only if one assigns the truth value of ψ_i [$V := \alpha$] to y_i . Since these clauses can be true whatever is the value of α , we have that the Tseytin transformation of φ is satisfiable if and only if y_n is satisfiable. Since we have a clause $y_n \leftrightarrow \varphi$ (due to the fact that $\psi_n = \varphi$), y_n is satisfiable if and only if φ is satisfiable. Therefore φ and its Tseytin transformation are equisatisfiable.

3. F is a valid formula if and only if $\neg F$ is false for any variable assignment, i.e. it is unsatisfiable. A formula is unsatisfiable if and only if its Tseytin transformation is unsatisfiable as well (by the previous question). Therefore F is a valid formula if and only if the Tseytin transformation of $\neg F$ is unsatisfiable.

Exercise 3 (SAT solving). By taking the CNF found in the above exercise and applying resolution, we obtain the following derivation trees:

$$\begin{array}{c}
 \frac{\frac{\frac{\neg a \vee y_6}{\neg a} \quad \frac{y_7 \quad \neg y_6 \vee \neg y_7}{\neg y_6}}{\neg a \vee y_6} \quad \frac{\frac{b \vee y_3}{b} \quad \frac{\neg y_3 \vee \neg y_4}{\neg y_3}}{b \vee y_3} \quad \frac{\frac{\frac{y_4 \vee \neg y_5}{y_4} \quad \frac{y_5 \vee y_6}{\neg y_6}}{y_5 \vee \neg y_5} \quad \frac{y_7 \quad \neg y_6 \vee \neg y_7}{\neg y_6}}{y_5 \vee y_6} \\
 \frac{\frac{\neg y_1 \vee \neg b \quad \neg y_2 \vee a \vee y_1}{\neg b \vee a \vee \neg y_2} \quad \frac{\neg y_5 \vee y_2}{y_2} \quad \frac{y_5 \vee y_6}{\neg y_6} \quad \frac{\neg b \vee a \quad \neg a}{b \quad \neg b}}{\neg b \vee a} \quad F
 \end{array}$$

Exercise 4 (First-order structures).

- Let $I = (D, \alpha)$ be an interpretation of \mathcal{L} , for which $\alpha(B) = b$ and $\alpha(T) = t$. For notational convenience we will denote $\alpha(L)$ by L_α

$$\begin{array}{ll}
 \llbracket \text{Min} \rrbracket_I = 1 & \implies L_\alpha(b, b), L_\alpha(b, u) \text{ and } L_\alpha(b, t) \\
 \llbracket \text{Max} \rrbracket_I = 1 & \implies L_\alpha(b, t), L_\alpha(u, t) \text{ and } L_\alpha(t, t) \\
 \llbracket \text{Tot} \rrbracket_I = 1 & \implies L_\alpha(u, u) \text{ (by choosing } x = u \text{ and } y = u) \\
 \llbracket \text{Tra} \rrbracket_I = 1 & \implies (L_\alpha(t, b) \implies L_\alpha(t, u))
 \end{array}$$

This greatly reduce the number of choices, restricting L_α to be either:

a)	L_α	b	u	t
	b	1	1	1
	u	1	1	1
	t	1	1	1
c)	L_α	b	u	t
	b	1	1	1
	u	0	1	1
	t	0	1	1
b)	L_α	b	u	t
	b	1	1	1
	u	1	1	1
	t	0	0	1
d)	L_α	b	u	t
	b	1	1	1
	u	0	1	1
	t	0	0	1

All the options satisfy reflexivity and transitivity as a consequence of the axioms. However, only d) satisfies the anti symmetry property. Therefore only d) is a partial order.

2.

a)	$E_{\alpha'}$	b	u	t
	b	1	1	1
	u	1	1	1
	t	1	1	1
c)	$E_{\alpha'}$	b	u	t
	b	1	0	0
	u	0	1	1
	t	0	1	1
b)	$E_{\alpha'}$	b	u	t
	b	1	1	0
	u	1	1	0
	t	0	0	1
d)	$E_{\alpha'}$	b	u	t
	b	1	0	0
	u	0	1	0
	t	0	0	1

In all the cases, $E_{\alpha'}$ is an equivalence relation.

3. $E_{\alpha'}$ is always an equivalence relation, whatever is the domain.

Let D' be an arbitrary set and $I' = (D', \alpha')$.

- **Reflexivity:** $\llbracket \text{Both} \rrbracket_{I'} = 1 \implies \forall x \in D'. E_{\alpha'}(x, x) \leftrightarrow L_{\alpha'}(x, x)$
(by choosing $y = x$).

We also know that, $\llbracket \text{Tot} \rrbracket_{I'} = 1 \implies \forall x \in D'. L_{\alpha'}(x, x)$

Therefore $\forall x \in D'. E_{\alpha'}(x, x)$

- **Symmetry:**

$$\llbracket \text{Both} \rrbracket_{I'} = 1 \implies \forall x \in D'. \forall y \in D'. E_{\alpha'}(x, y) \leftrightarrow (L_{\alpha'}(x, y) \wedge L_{\alpha'}(y, x))$$

We also know that for $x, y \in D'$ arbitrary $L_{\alpha'}(x, y) \wedge L_{\alpha'}(y, x) \equiv L_{\alpha'}(y, x) \wedge L_{\alpha'}(x, y)$. Therefore we have that for $\forall x \in D'. \forall y \in D'. E_{\alpha'}(x, y) \leftrightarrow E_{\alpha'}(y, x)$ is a tautology.

- **Transitivity:** $\llbracket \text{Both} \rrbracket_{I'} = 1$ implies that for x, y, z arbitrary in D'

$$E_{\alpha'}(x, y) \leftrightarrow (L_{\alpha'}(x, y) \wedge L_{\alpha'}(y, x))$$

and

$$E_{\alpha'}(y, z) \leftrightarrow (L_{\alpha'}(y, z) \wedge L_{\alpha'}(z, y))$$

Therefore

$$E_{\alpha'}(x, y) \wedge E_{\alpha'}(y, z) \leftrightarrow (L_{\alpha'}(x, y) \wedge L_{\alpha'}(y, z) \wedge L_{\alpha'}(z, y) \wedge L_{\alpha'}(y, x))$$

which implies

$$E_{\alpha'}(x, y) \wedge E_{\alpha'}(y, z) \rightarrow (L_{\alpha'}(x, z) \wedge L_{\alpha'}(z, x))$$

and finally

$$E_{\alpha'}(x, y) \wedge E_{\alpha'}(y, z) \rightarrow E_{\alpha'}(x, z)$$

4. One of the solution consists in choosing $D_1 = D' / E_{\alpha'}$, the set of equivalence classes of $E_{\alpha'}$, $\alpha_1 = (B_1, T_1, L_1)$ where $B_1 = [b]_{E_{\alpha'}}$, $T_1 = [t]_{E_{\alpha'}}$ and

$$L_1 := \{([x]_{E_{\alpha'}}, [y]_{E_{\alpha'}}) : L_{\alpha'}(x, y) \text{ where } x, y \in D'\}$$

Reflexivity and transitivity are immediate as they have been proven for $L_{\alpha'}$.

Antisymmetry comes from the fact that for arbitrary $[x]_{E_{\alpha'}}, [y]_{E_{\alpha'}} \in D_1$

$$\begin{aligned} & L_1([x]_{E_{\alpha'}}, [y]_{E_{\alpha'}}) \wedge L_1([y]_{E_{\alpha'}}, [x]_{E_{\alpha'}}) \\ \implies & L_{\alpha'}(x, y) \wedge L_{\alpha'}(y, x) \\ \implies & E_{\alpha'}(x, y) \\ \implies & [x]_{E_{\alpha'}} = [y]_{E_{\alpha'}} \end{aligned}$$

Therefore L_1 is a partial order.