

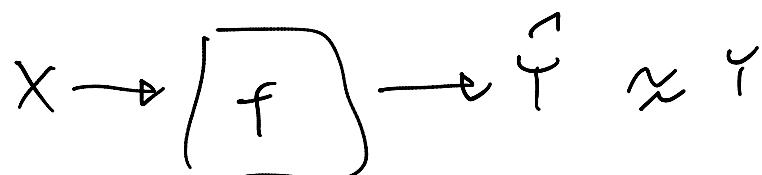
Supervised learning:

Given examples $x_1, y_1, \dots, x_n, y_n$

Want to learn a prediction rule f

s.t. for any new unseen example

$$y \approx f(x) = ?$$



The output \hat{Y} takes values in G

We classify the cases as:

- $G = \{a, b\}$ binary classification

where a, b can be anything

e.g.:

- $G = \{0, 1\}$

- $G = \{\text{red}, \text{blue}\}$

- $G = \{\text{high risk}, \text{low risk}\}$

- $G = \{a, b, c, \dots\}$ multi-class classification

- $G = \mathbb{R}$ regression

Our first classification algo: KNN

Given a new query point X :

- find k "closest" x -values in

- Given a new x'
- find the k "closest" x -values in the examples x_1, \dots, x_n
 - Note their indices $i_1, \dots, i_k \in \{1, \dots, n\}$
 - classify the example as the most common label in the corresponding set of training labels

$$\hat{y} = \text{mode}\{y_{i_1}, \dots, y_{i_k}\}$$

What does "closest" mean?

Need a distance measure.

Suppose X is a vector of features

$$x_i = \begin{pmatrix} x_{i1} \\ \vdots \\ x_{ip} \end{pmatrix} \in \mathbb{R}^p$$

Can we use Euclidean distance

$$\|x - x'\|_2 = \sqrt{\sum_j (x_j - x'_j)^2}$$

Or can we use any other ^{vector} distance

$$\text{e.g. } \|x - x'\|_\infty = \max_j |x_j - x'_j|$$

Constructing feature vectors

1 If using these vector distances, mean

o

1. If using these vector distances, may want to first standardize the later:

$$x_{ij} \leftarrow \frac{(x_{ij} - \hat{\mu}_j)}{\hat{\sigma}_j}$$

mean & std dev
of x_{1j}, \dots, x_{nj}

2. If some of the features are categorical

e.g. Which of {Yale, Columbia, Cornell}
did you attend

often we encode this using

one-hot encoding:

use three ^{binary} variables to encode

Yale as $(1, 0, 0)$ Columbia $(0, 1, 0)$ Cornell $(0, 0, 1)$

3. Later in class, we'll also talk about more abstract ways to measure similarity.

E.g. $X =$ Content of an email
 $\quad \quad \quad$ in words

$Y =$ Whether spam

Out-of-sample evaluation

KNN tries to make \hat{Y} equal Y

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 To evaluate how well it — or
 any other supervised learning
 algo — does is to ask how
 often is that true.

If X, Y are r.v.s representing
 new random examples drawn from
 the population of examples, then
 we want low risk

$$R(f) = \mathbb{E}[\ell(Y, f(X))]$$

Where ℓ is a loss fn

$$\text{For now: } \ell(y, \hat{y}) = \mathbb{I}[y \neq \hat{y}] = \begin{cases} 1 & y \neq \hat{y} \\ 0 & y = \hat{y} \end{cases}$$

To estimate $R(f)$ we can take
 a test set of examples $x_1^{\text{test}}, y_1^{\text{test}}, \dots, x_{n_{\text{test}}}^{\text{test}}, y_{n_{\text{test}}}^{\text{test}}$
 drawn at random from the population
 of examples & compute an empirical avg

$$\hat{R}_{n_{\text{test}}}(f) = \frac{1}{n_{\text{test}}} \sum_{i=1}^{n_{\text{test}}} \ell(y_i^{\text{test}}, f(x_i^{\text{test}}))$$

This is a consistent & unbiased

estimate of $R(f)$.

Often, we get the test set by splitting off from the training data.

Bayes classifier & Bayes (Error) Rate

So kNN is just one classifier.

But: What is the BEST classifier?

The one that minimizes $R(f)$

$$\begin{aligned} R(f) &= \mathbb{E}[l(Y, f(x))] \\ &= \mathbb{E}[\mathbb{I}[Y \neq f(x)]] \\ &= \mathbb{E}[1 - \mathbb{I}[Y = f(x)]] \\ &= \mathbb{E}[\mathbb{E}[-\mathbb{I}[Y=f(x)]|X]] \quad (\text{total expectation}) \\ &= \mathbb{E}\left[\sum_{y \in G_2} P(Y=y|X)(1 - \mathbb{I}[y=f(x)])\right] \\ &= 1 - \mathbb{E}\left[\sum_{y \in G_2} P(Y=y|X) \mathbb{I}[y=f(x)]\right] \end{aligned}$$

For each x , we can choose one $y \in G_2$
so that $f(x) = y$

Which y to choose to minimize $R(f)$?

Maximize the 2nd term

for each x , choose $f(x)$ to maximize

$$\sum_{y \in G} P(Y=y | X=x) \prod [y = f(x)]$$

\Rightarrow choose $f(x)$ to be the maximizer
of $P(Y=y | X=x)$

$$f^*(x) = \underset{y \in G}{\operatorname{argmax}} P(Y=y | X=x) = \operatorname{mode}(P(Y|X=x))$$

f^* is known as the Bayes classifier

$R(f^*)$ is known as the Bayes (error) rate

R the best possible risk

f^* gets at the fundamental limit
of the predictability of Y from X

KNN as a probabilistic classifier

Can modify the output of KNN as
a probability estimate:

$$\hat{P}(Y=y | X) = \frac{1}{K} \sum_{j=1}^K \prod [Y_{i_j} = y]$$

fraction of K nearest
neighbors that have

fraction or
neighbors that have
label y

Our kNN prediction can be written

$$\hat{y} = \arg \max_{y \in G_k} \hat{P}(Y=y | X)$$

Mimics Bayes classifier w/ an estimated conditional prob

For $G_k = \{0, 1\}$ (binary classification),

this translates to

$$\begin{aligned}\hat{y} &= \begin{cases} 0 & \hat{P}(Y=1|X) \leq \frac{1}{2} \\ 1 & \hat{P}(Y=1|X) > \frac{1}{2} \end{cases} \\ &= \mathbb{I}[\hat{P}(Y=1|X) > \frac{1}{2}]\end{aligned}$$

Can modify this and use other thresholds

$$\hat{y} = \mathbb{I}[\hat{P}(Y=1|X) > \theta] \quad \theta \in \mathbb{R}$$

What this does is change the
classification rates.

Classification rates: binary case

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Exhaustively categorize all cases of prediction:

- $y=1, \hat{y}=1$ TP }
 - $y=0, \hat{y}=1$ FP }
 - $y=0, \hat{y}=0$ TN }
 - $y=1, \hat{y}=0$ FN }
- $T = \text{true}$
 $F = \text{false}$
 $P = \text{positive}$
 $N = \text{negative}$

$$\# \text{TP} = \sum_{i=1}^{n_{\text{test}}} \mathbb{I}[y_i^{\text{test}} = 1, f(x_i^{\text{test}}) = 1]$$

$$\# \text{FP} = \dots$$

...

Confusion matrix:

y	1	0
1	#TP	#FD
0	#FN	#TN

Sometimes raw numbers

Sometimes divide everything by n_{test}

Rates:

True positive rate = $\text{TPR} = \frac{\# \text{TP}}{\# P} = \frac{\# \text{TP}}{\# \text{TP} + \# \text{FN}}$
 aka Recall

$$\text{TNR} = \frac{\# \text{TN}}{\# N} = \frac{\# \text{TN}}{\# \text{TN} + \# \text{FP}}$$

$$TNR = \frac{\# TN}{\# TN + \# FP}$$

$$FPR = 1 - TNR$$

$$= \frac{\# FP}{\# TN + \# FP}$$

$$FNR = 1 - TPR = \frac{\# FN}{\# TP + \# FN}$$

$$\text{Accuracy} \quad Acc = 1 - (\text{Any 0-1 loss})$$
$$= \frac{\# TP + \# TN}{\# TP + \# TN + \# FP + \# FN}$$