## Lecture 1

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## 1 2/21/23 lecture

- 1. V = 0 everywhere (trivial)
- 2. more meaningful solutions agree with the boundary conditions (b.c.) and vary in some region as V(x,y,z).

Dirichlet b.c.:

1. 
$$V(x = 5m) = 0 = m(5) + b = -5m$$

2. 
$$V(x=1) = 4 = m(1) + (-5m) = -4m = -m = -1$$

Hence,

$$V(x) = (5 - x)$$
 Volts  $E_x = -1$  V/m

- Solution is generally a linear function
  - consider V(x+a) = mx + b + ma
  - and V(x-a) = mx + b ma

V(x) is the average of these expressions (explicitly shown below).

$$V(x) = \frac{1}{2}(V(x+a) + V(x-a))$$

Laplace's equations is like an averageing instruction (1D, 2D, 3D).

$$\nabla^2 V = 0$$

 $\implies$  No maxium or minimum inside of the volume of the space. And the only extrema exists at the boundary

i.e. 
$$\left(\frac{dV}{dn} = \frac{-\sigma}{\epsilon_0}\right)$$

There are two types of b.c.'s:

- 1. Dirichlet b.c. : V is fixed by some external means at the surface dV (e.g. grounded)
- 2. Neumann b.c. : The value of  $\vec{\nabla}V.\hat{n}$  at the surface AV is fixed ( the normal derivate is fixed, i.e.  $\frac{dV}{dn}=$  is fixed

There are actually two uniqueness theorems but we will only be using the first one in this class.

1. Theorem 1: With either b.c. (1) or (2) chosen, at surface dV, there is a unique solution V(x,y,z) to Laplace's equation in a region of space.

Proof:

Suppose we have a function  $f = V_1 - V_2$ , where  $V_1$  and  $V_2$  satisfy  $\nabla^2 V_i = 0$ .

$$\begin{split} \int_{V} \vec{\nabla} \cdot \left( f \vec{\nabla} f \right) d^{3}x &= \int_{V} \left( \vec{\nabla} f \cdot \vec{\nabla} f \right) + f \left( \nabla^{2} f \right) \right) d^{3}x \\ &= \int_{V} \left( \vec{\nabla} f \cdot \vec{\nabla} f \right) d^{3}x \text{ Div. Thm} \\ &= \int_{dV} f \vec{\nabla} f \cdot d\vec{a} \end{split}$$

 $\nabla^2 f$  becomes zero, hence the simplification

A) Suppose we pick a situation where Dirichlet b.c. conditions are used. Then,  $V_1$  and  $V_2$  are both solutions to Laplace's equation. Hence, they have the same value at the boundary  $(dV (V_1 = V_2 = V_{fixed}))$ 

f=0 in volume V too, or else on extrema would occur inside region.

Suppose f > 0 inside V, in order to go to zero at dV or f would have some max inside V ( $\nabla^2 f \neq 0$ ): contradiction.

$$\implies f = 0 \text{ or } V_1 = V_2 \text{ is unique.}$$

B) Suppose we pick a situation where Neumann b.c. conditions are used. Then,  $\vec{\nabla} f = 0$  at dV (since  $\vec{\nabla} V_1.\hat{n}_= \vec{\nabla} V_2.\hat{n}$ )

Within Volume 
$$V$$
  $\vec{\nabla} f = 0$  too since, 
$$\oint_{aV} f \vec{\nabla} f \cdot d\vec{a} = 0 \implies \int_{V} |\vec{\nabla} f|^2 d^3x$$
 since  $\vec{\nabla} f = 0$  everywhere

Here, we have a gauge freedom. This can be seen because  $V_1 = V_2 + V_0$  for some  $V_0$  (constant).

• Physics only cares about how the V changes (  $\vec{E} = -\vec{\nabla}V$ ))

e.g. of B) Parallel Plates

Say, 
$$|\vec{B}| = |\frac{\nabla V}{d}| = 1000 \text{ V/m}$$

 $ec{E}$  will always be in direction of lower potential. Separation of variables

Goal: Find V(x, y, z) such that  $\nabla^2 V = 0$ 

In 3D we have 6 total b.c.'s.

Working under assumption of  $V(x,y,z)=f(x^1)g(x^2)h(x^3)$  s.t. superscripts represent different x's

The solutions depend on coordinate system:

- 1. Cartesian: x,y,z or  $x^1, x^2, x^3 \implies \text{sines/cosines}$ , exponentials
- 2. Cylindrical:  $s, \rho, z \implies \text{Bessel functions: } J^n, K^n$
- 3. Spherical: r,  $\theta$ ,  $\phi \implies$  Legendre Polynomials (i.e. new trancendental functions)
- 1. Cartesian
- $c < 0, c < -k^2 \implies$  f''  $\overline{f = -k^2}$  s.t. k is constant e.g. 2D)