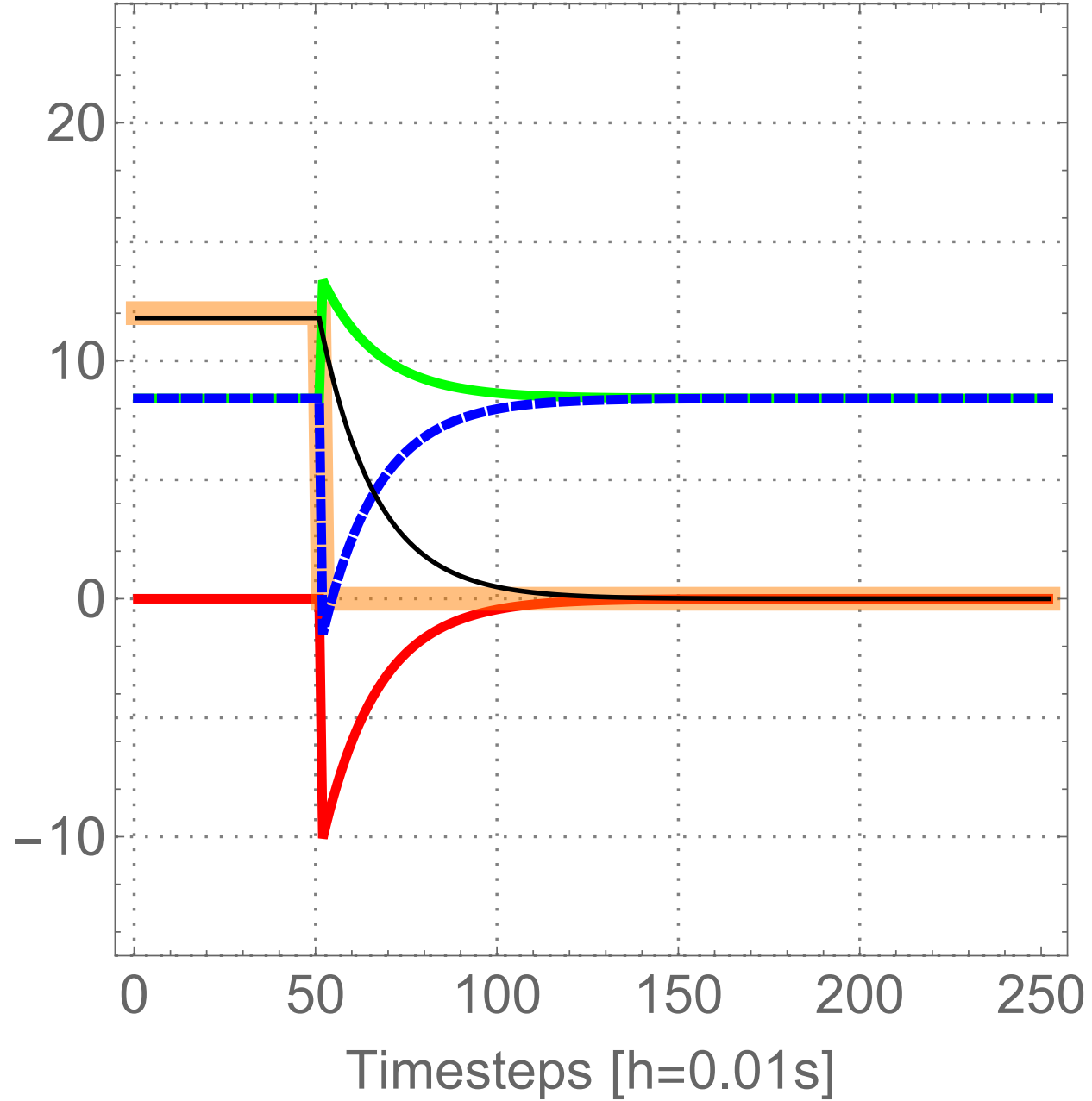


Out[1648]=



- Driven Wheel Torque [Nm × 10<sup>-1</sup>]
- Driven Wheel Voltage [V]
- Contact Force [N]: driven
- Contact Force [N]: passive
- Driven Wheel speed [rad/s]