CSc 179 – Graph Coverage for Source Code

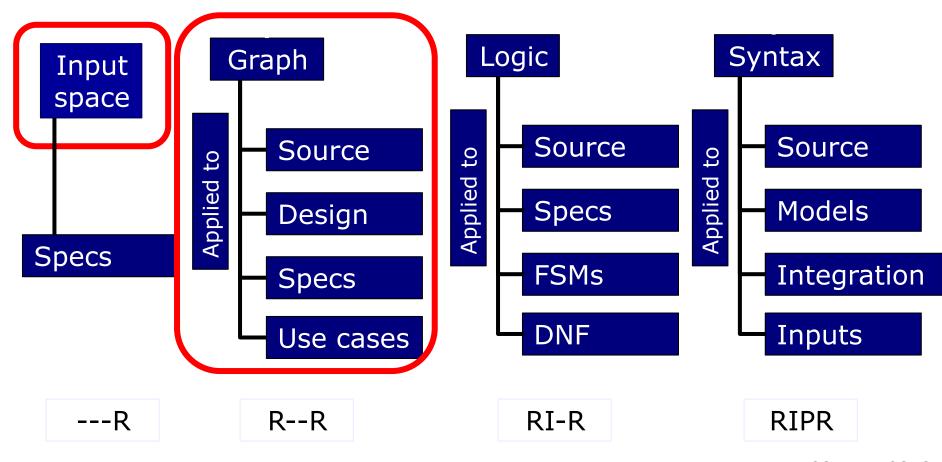
Credits:

AO – Ammann and Offutt, "Introduction to Software Testing," Ch. 7

University of Virginia (CS 4501 / 6501)

Structures for Criteria-Based Testing

Four structures for modeling software





Overview

- Graph coverage criteria are widely used on source code
- Define graph, then apply coverage criterion
- Control flow graph (CFG): the most common graph for source code
- Node coverage: execute every statement
- Edge coverage: execute every branch
- Data flow coverage: augment the CFG with
 - defs: statements that assign values to variables
 - uses: statements that use variables



Control Flow Graph (CFG)

- Represent the control flow of a piece of source code
 - Nodes represent basic blocks
 - Basic blocks represent sequences of instructions / statements that always execute together in sequence
 - Edges represent control flow (branch) between basic blocks
 - Transfer of control
 - Initial nodes correspond to a method's entry points
 - Final nodes correspond to a method's exit points
 - Return or throw in Java
 - Decision nodes represent choices in control flow
 - if or switch-case blocks or condition for loops in Java
- Can be annotated with extra information such as branch predicates, defs, and uses



Example: CFG for if-else

```
if (x < y)
{
    y = 0;
    x = x+1;
}
else
{
    x = y;
}</pre>
```

Basic blocks (nodes)

- Entry node1
- Decision nodes1
- Junction nodes4
- Exit nodes

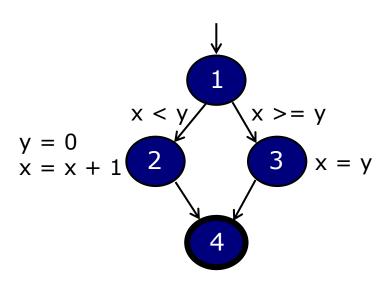
Control flow (edges)

$$1 \rightarrow 2$$

$$1 \rightarrow 3$$

$$2 \rightarrow 4$$

$$3 \rightarrow 4$$





Example: CFG for If without else

```
if (x < y)
{
    y = 0;
    x = x+1;
}</pre>
```

Basic blocks (nodes)

1: if
$$(x < y)$$

2:
$$y=0$$
; $x = x+1$;

Entry node

1

Decision nodes

Junction nodes

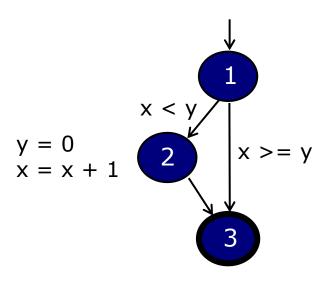
Exit nodes

Control flow (edges)

$$1 \rightarrow 2$$

$$1 \rightarrow 3$$

$$2 \rightarrow 3$$





Example: CFG for If with return

```
if (x < y)
{
    return;
}
print(x);
return;</pre>
```

Basic blocks (nodes)

1: if (x < y)

2: return;

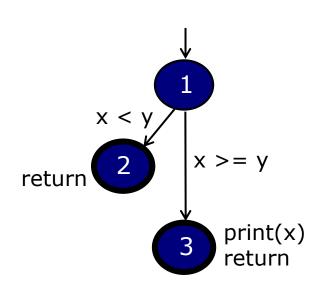
3: print(x); return;

- Entry node
 - 1
- Decision nodes
- Junction nodes
- Exit nodes2, 3

Control flow (edges)

 $1 \rightarrow 2$

 $1 \rightarrow 3$





Loops

- Loops require extra nodes ("dummy" node)
 - Not directly derived from program statements
- Looping structures: while loop, for loop, do-while loop
- Common mistake
 - Try to have the edge go to the entry node



Basic blocks (nodes)

1:
$$x = 0$$
;

2: while(
$$x < y$$
)

3:
$$y = f(x,y)$$
; $x = x+1$;

Control flow (edges)

$$1 \rightarrow 2$$

$$2 \rightarrow 3$$

$$2 \rightarrow 4$$

$$3 \rightarrow 2$$

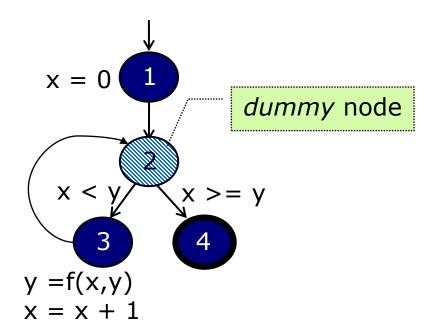
Entry node

Decision nodes

Junction nodes

_

Exit nodes
4





Example: CFG for a for loop

```
for (x=0; x<y; x++)
    y = f(x,y);
Basic blocks (nodes)
    1: x = 0;
    2: x < y
    3: y = f(x,y);
    4: x++;
  Entry node
  Decision nodes
  Junction nodes
  Exit nodes
```

5

Control flow (edges) $1 \to 2, 2 \to 3, 2 \to 5, 3 \to 4, 4 \to 2$ implicitly x = 0initializes loop x < yx >= yy = f(x, y)X++implicitly

increments loop



Example: CFG for a do-while loop

```
x = 0;
do
{
    y = f(x,y);
    x = x + 1;
} while (x < y)
println(y);</pre>
```

Basic blocks (nodes)

Control flow (edges)

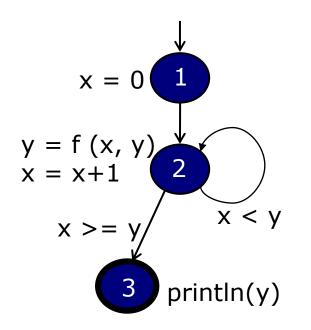
$$\begin{array}{c}
1 \rightarrow 2 \\
2 \rightarrow 2 \\
2 \rightarrow 3
\end{array}$$

Entry node

1
Decision nodes
2

Junction nodes

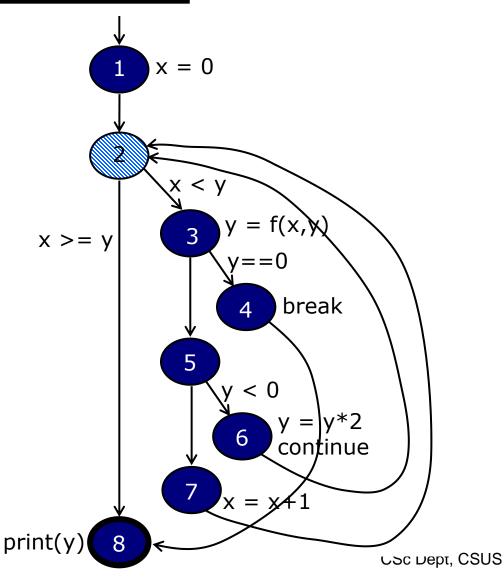
Exit nodes 3





Example: CFG for a loop with break and continue

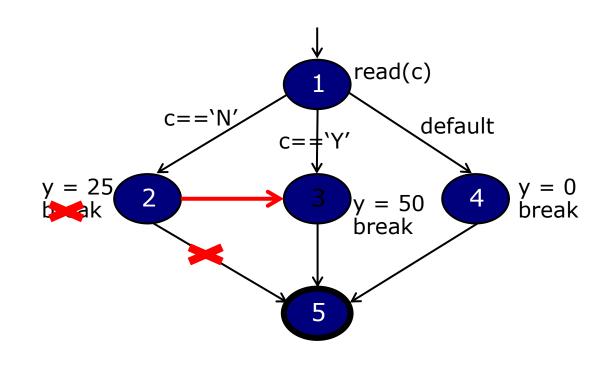
```
x = 0;
while (x < y)
{
    y = f(x,y);
    if (y==0)
        break;
    else if (y < 0)
        y = y*2;
        continue;
    x = x + 1;
print(x);
```





Example: CFG for (switch) case

```
read(c);
switch(c)
case 'N':
    y = 25;
    break;
case 'Y':
    y = 50;
    break;
default:
    y = 0;
    break;
}
```

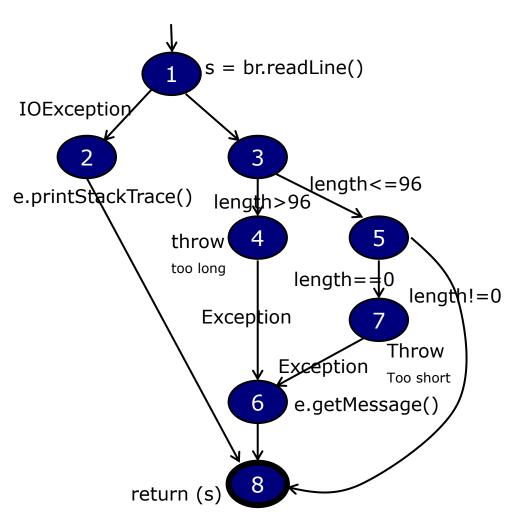


Cases without break?

Fall through to the next case

Example: CFG for Exceptions (try-catch)

```
try
{
    s = br.readLine();
    if (s.length() > 96)
        throw new Exception("too long");
    if (s.length() ==0)
        throw new Exception("too short");
} catch (IOException e) {
    e.printStackTrace();
} catch (Exception e) {
    e.getMessage();
}
return(s);
```





Exercise

```
public static int numberOccurrences(char □ v, char c)
    if (v == null)
        throw new NullPointerException();
    int n = 0;
    for (int i=0; i<v.length; i++)</pre>
    {
        if (v[i] == c)
            n++;
    return n;
}
                Entry node
                Exit nodes
                   2, 8
```

```
Basic blocks (nodes)

1: if (v == null)

2: throw .. NPE;

3: n=0; i=0;

4: i < v.length;

5: if (v[i] == c)

6: n++;

7: i++;
```

Control flow (edges)

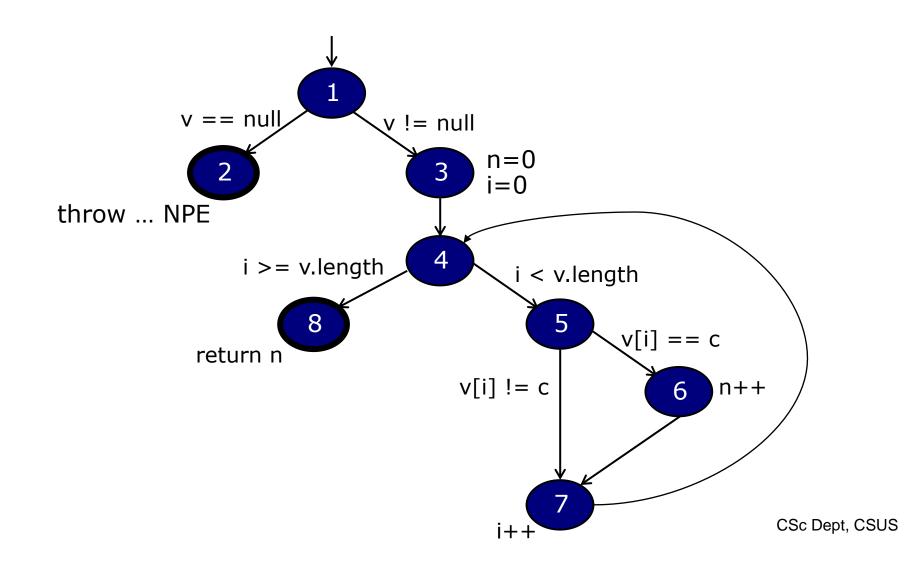
8: return n;

$$1 \rightarrow 2, 1 \rightarrow 3$$

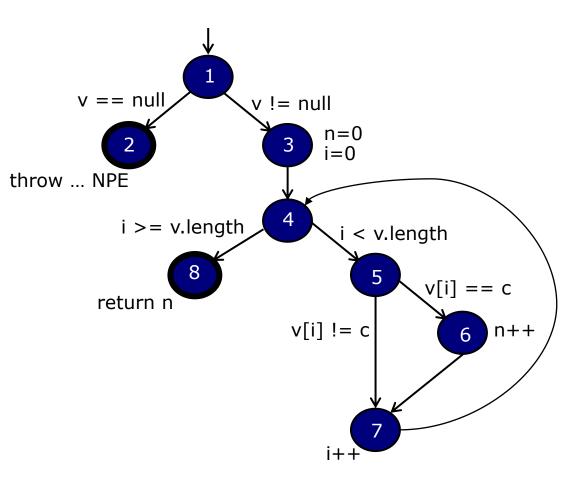
 $3 \rightarrow 4$
 $4 \rightarrow 5, 4 \rightarrow 8$
 $5 \rightarrow 6, 5 \rightarrow 7$
 $6 \rightarrow 7$
 $7 \rightarrow 4$



CFG for numberOccurrences()







Test requirements

$$TR = \{1,2,3,4,5,6,7,8\}$$

Test paths

$$t1 = [1,2]$$

$$t2 = [1,3,4,5,6,7,4,8]$$

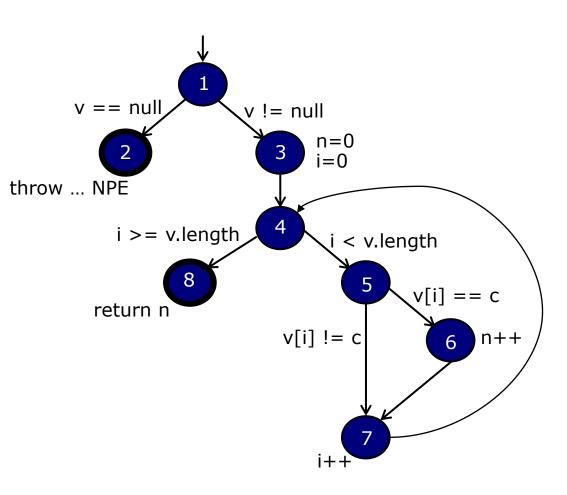
NC satisfied by {t1, t2}

Test case values (v,c)

$$t2 = (\{'a'\}, 'a'\}, expected 1$$



Applying Edge Coverage (EC)



Test requirements

TR =
$$\{(1,2), (1,3), (3,4), (4,5), (4,8), (5,6), (5,7), (6,7), (7,4)\}$$

Test paths

$$t1 = [1,2]$$

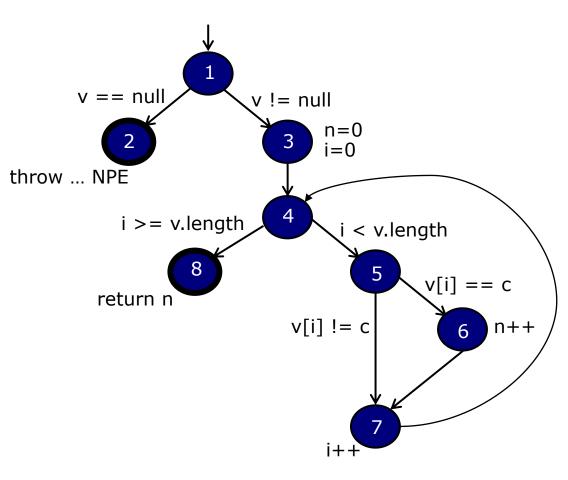
$$t2 = [1,3,4,5,6,7,4,8]$$

$$t3 = [1,3,4,5,7,4,8]$$

Test case values (v,c)



Applying Edge-Pair Coverage (EPC)



Test requirements

TR =
$$\{(1,2), (1,3,4), (3,4,8), (3,4,5), (4,5,6), (4,5,7), (5,6,7), (5,7,4), (6,7,4), (7,4,5), (7,4,8)\}$$

Test paths

$$t1 = [1,2]$$

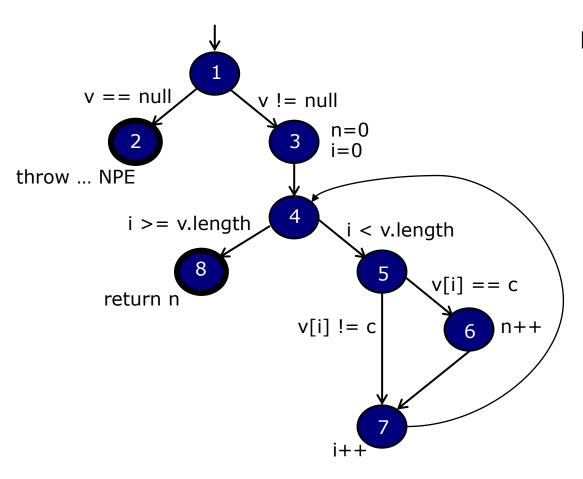
 $t2 = [1,3,4,8]$
 $t3 = [1,3,4,5,7,4,5,6,7,4,8]$

EPC satisfied by {t1, t2, t3}

Test case values (v,c)



Applying Prime Path Coverage



Deriving prime paths

- Enumerate all simple paths of length 0, 1, 2, 3, ... until no more simple paths are found
- Pick the prime paths among all derived simple paths
- Notes:(1) Simple path: Path from node n_i to n_j that is no internal loops. (2) Prime Path is simple path that is not subpath of any other simple path



Recap: Simple Paths

Path from node n_i to n_i that is **no internal loops**

• A path from ni to nj is simple if no node appears more than once in the path (first and last nodes may be identical) List simple paths: 31 simple paths

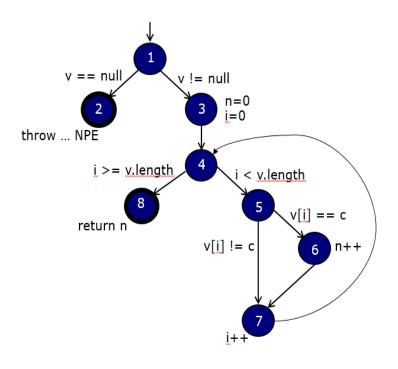
A loop is a simple path

3

Subpaths of other simple paths → avoid these

```
[1,2,3,4,7], [1,2,3,5,7], [1,2,3,5,6],
[1,2,3,4], [1,2,3,5],
[1,3,4,7], [1,3,5,7], [1,3,5,6],
[2,3,4,7], [2,3,5,7], [2,3,5,6],
[1,2,3], [1,3,4], [1,3,5],
[2,3,4], [2,3,5],
[3,4,7], [3,5,7], [3,5,6],
[5,6,5],
[6,5,6], [6,5,7],
[1,2], [1,3], [2,3], [3,4], [3,5],
[4,7], [5,7], [5,6], [6,5]
```

Applying Prime Path Coverage



[1] [2]! [3] [4] [5] [6] [7] [8]!

[1,2]! [1,3] [3,4] [4,5] [4,8]! [5,6] [5,7] [6,7] [7,4]

[1,3,4] [3,4,5] [3,4,8]! [4,5,6] [4,5,7] [5,6,7] [5,7,4] [6,7,4] [7,4,5] [7,4,8]! [1,3,4,5] [1,3,4,8]! [3,4,5,6] [3,4,5,7]! [4,5,6,7] [4,5,7,4]* [5,6,7,4] [5,7,4,5]* [5,7,4,8]! [6,7,4,8]! [7,4,5,6] [7,4,5,6]

[1,3,4,5,6] [1,3,4,5,7]! [3,4,5,6,7]! [4,5,6,7,4]* [5,6,7,4,5]* [5,6,7,4,8]! [6,7,4,5,6]* [7,4,5,6,7]*

! - cannot be extended

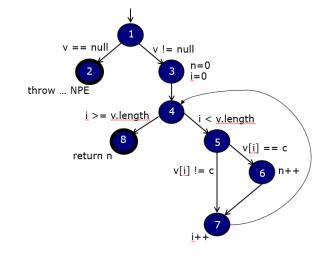
* - is a cycle

[1,3,4,5,6,7]!

Applying Prime Path

Coverage

Prime path	Covered by
[1,2]	t1
[1,3,4,8]	t2
[1,3,4,5,6,7]	t4, t5
[1,3,4,5,7]	t3
[4,5,7,4]	t3, t4
[4,5,6,7,4]	t3, t4, t5
[5,7,4,5]	t3
[5,7,4,8]	t4
[5,6,7,4,5]	t4, t5
[5,6,7,4,8]	t3, t5
[6,7,4,5,6]	t5
[7,4,5,7]	t4
[7,4,5,6,7]	t3, t5

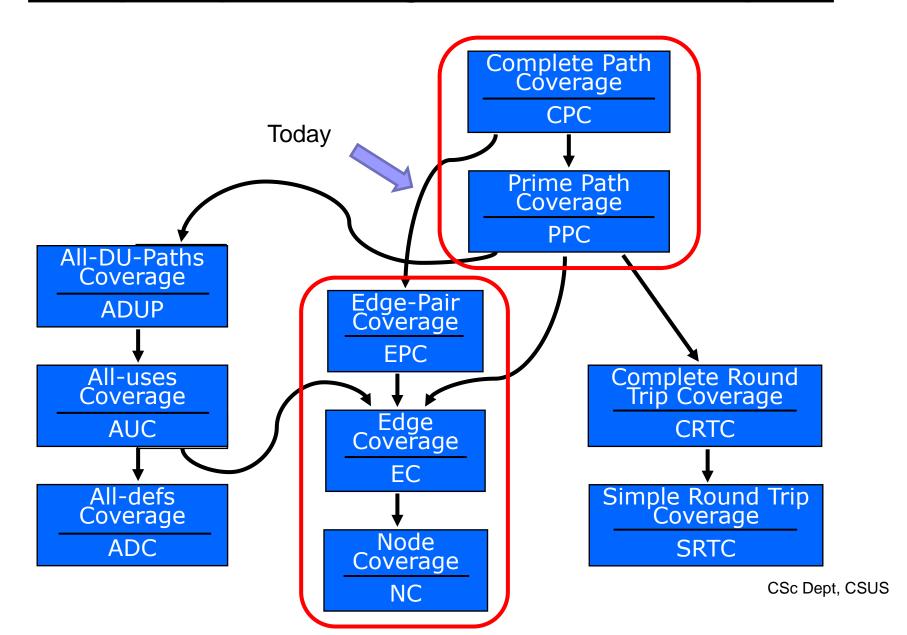


	Test paths	Test case values (v,c)	Expected values
t1	[1,2]	(null, 'a')	NPE
t2	[1 ,3,4, 8]	({}, 'a')	0
t3	[1 ,3,4,5,7,4,5,6,7,4, 8]	({`x', `a'}, `a')	1
t4	[1 ,3,4,5,6,7,4,5,7,4, 8]	({`a', `x'}, `a')	1
t5	[1 ,3,4,5,6,7,4,5,6,7,4, 8]	({`a', `a'}, `a')	2

PPC satisfied by {t1, t2, t3, t4, t5}

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Recap: Graph Coverage Criteria Subsumption





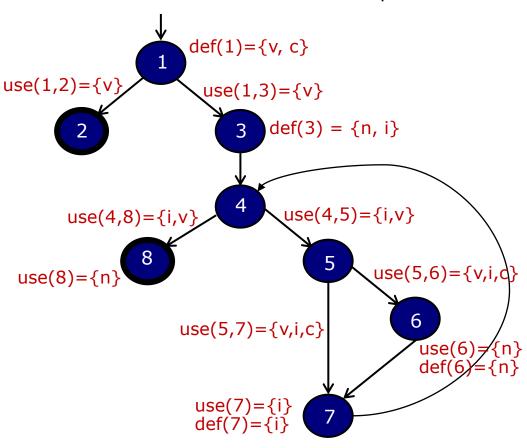
Recap: Handling Loops in Graphs

Attempts to deal with loops:

- 1970s: Execute cycles once ([5, 6, 5] in previous example)
- 1980s: Execute each loop, exactly once
- 1990s: Execute loops 0 times, once, more than once
- 2000s: Prime paths (touring, sidetrips, and detours)

Applying Data Flow Coverage

v and c are forwarded parameters



Deriving test requirements

- List all du-pairs
- Based on du-pairs, derive dupaths
- Must be def-clear paths
- All Defs Coverage (ADC)
 - For each def, at least one use must be reached
- All Uses Coverage (AUC)
 - For each def, all uses must be reached
- All DU-Paths Coverage (ADUPC)
 - For each def-use pair, all paths between defs and uses must be covered

DU-Pairs → DU-Paths

Ī		DU Pairs			1
	[1,(1,2)]				
	[1, (1, 3)]				
	[1, (4, 8)]				
	[1, (4, 5)]				
	[1, (5, 6)]	\/o.	: _	بر مام	
	[1, (5, 7)]	var	d	ıble v	
	[1, (5, 7)]	Variable c			
	[1, (5, 6)]				
	[3,8]				
	[3,6]	Var	ia	ıble n	
	ILC 01				
	[6,8]				
	[6,6]			defs <u>a</u>	after
	[6,6] [3.7]		1	defs <u>a</u> uses, th	
	[6,6] [3,7] [7,7]				<mark>ese are</mark>
	[6,6] [3,7] [7,7] [3, (4,8)]			uses, th	<mark>ese are</mark>
	[6,6] [3,7] [7,7] [3, (4,8)] [3, (4,5)]			uses, th	<mark>ese are</mark>
	[6,6] [3,7] [7,7] [3, (4,8)] [3, (4,5)] [3, (5,6)]	Var	ia	uses, th	<mark>ese are</mark>
	[6,6] [3,7] [7,7] [3, (4,8)] [3, (4,5)] [3, (5,6)] [3, (5,7)]	Var	ia	uses, th valid Du	<mark>ese are</mark>
	[6,6] [3,7] [7,7] [3, (4,8)] [3, (4,5)] [3, (5,6)] [3, (5,7)] [7, (4,8)]	Var	ia	uses, th valid Du	<mark>ese are</mark>
	[6,6] [3,7] [7,7] [3, (4,8)] [3, (4,5)] [3, (5,6)] [3, (5,7)] [7, (4,8)] [7, (4,5)]	Var	ia	uses, th valid Du	<mark>ese are</mark>
	[6,6] [3,7] [7,7] [3, (4,8)] [3, (4,5)] [3, (5,6)] [3, (5,7)] [7, (4,8)]	Var	ia	uses, th valid Du	<mark>ese are</mark>

DU Paths			
[1,3]			
[1,2]			
[1,3,4,8]			
[1,3,4,5]			
[1,3,4,5,7]	Variable v		
[1,3,4,5,6]	Variable v		
[1,3,4,5,6]	Variable c		
[1,3,4,5,7]			
[3,4,8]			
[3,4,5,6]	Variable n		
[6,7,4,8]			
[6,7,4,5,6]			
[3,4,5]			
[3,4,8]			
[3,4,5,6]			
[3,4,5,7]			
[3,4,5,6,7]	Variable i		
[7,4,5]			
[7,4,8]			
[7,4,5,6]			
[7,4,5,7]		t, CSUS	
[7,4,5,6,7]		1, 0000	



ADC: DU-Paths → Test Paths

DU Paths		
[1,3]		
[1,2]		
[1,3,4,8]		
[1,3,4,5]		
[1,3,4,5,7]	V / a vi a la la	
[1,3,4,5,6]	Variable v	
[1,3,4,5,6]	Variable c	
[1,3,4,5,7]		
[3,4,8]		
[3,4,5,6]	Variable n	
[6,7,4,8]		
[6,7,4,5,6]		
[3,4,5]		
[3,4,8]		
[3,4,5,6]		
[3,4,5,7]		
[3,4,5,6,7]	Variable i	
[7,4,5]		
[7,4,8]		
[7,4,5,6]		
[7,4,5,7]		
[7,4,5,6,7]		

Test paths that satisfy All Defs Coverage

Variable	All Def Coverage
V	[1,3,4,8]
c	[1,3,4,5,6,7,4,8]
n	[1,3,4,8]
	[1,3,4,5,6,7,4,8]
1	[1,3,4,5,7,4,8]
1	[1,3,4,5,7,4,5,7,4,8]



AUC: DU-Paths → Test Paths

	DU Paths
[1,3]	
[1,2]	
[1,3,4,8]	
[1,3,4,5]	
[1,3,4,5,7]	Va via la la
[1,3,4,5,6]	Variable v
[1,3,4,5,6]	Variable c
[1,3,4,5,7]	
[3,4,8]	
[3,4,5,6]	Variable n
[6,7,4,8]	
[6,7,4,5,6]	
[3,4,5]	
[3,4,8]	
[3,4,5,6]	
[3,4,5,7]	
[3,4,5,6,7]	Variable i
[7,4,5]	
[7,4,8]	
[7,4,5,6]	
[7,4,5,7]	
[7,4,5,6,7]	

Test paths that satisfy All Uses Coverage

Variable	All Use Coverage
	[1,2] [1,3,4,8]
v	[1,3,4,5,7,4,8]
	[1,3,4,5,6,7,4,8]
C	[1,3,4,5,7,4,8]
	[1,3,4,5,6,7,4,8]
	[1,3,4,8]
n	[1,3,4,5,6,7,4,8]
	[1,3,4,5,6,7,4,5,6,7,4,8]
	[1,3,4,5,7,4,8]
	[1,3,4,5,7,4,5,7,4,8]
i	[1,3,4,8]
1	[1,3,4,5,6,7,4,8]
	[1,3,4,5,7,4,8]
	[1,3,4,5,7,4,5,6,7,4,8]



ADUPC: DU-Paths → Test Paths

DU Paths		
[1,3]		
[1,2]		
[1,3,4,8]		
[1,3,4,5]		
[1,3,4,5,7]	Mawia la la	
[1,3,4,5,6]	Variable v	
[1,3,4,5,6]	Variable c	
[1,3,4,5,7]		
[3,4,8]		
[3,4,5,6]	Variable n	
[6,7,4,8]		
[6,7,4,5,6]		
[3,4,5]		
[3,4,8]		
[3,4,5,6]		
[3,4,5,7]		
[3,4,5,6,7]	Variable i	
[7,4,5]		
[7,4,8]		
[7,4,5,6]		
[7,4,5,7]		
[7,4,5,6,7]		

Test paths that satisfy All DU-Paths Coverage

Variable	All DU Path Coverage
	[1,3,4,8]
v	[1,2]
v	[1,3,4,5,7,4,8]
	[1,3,4,5,6,7,4,8]
	[1,3,4,5,6,7,4,8]
	[1,3,4,5,7,4,8]
	[1,3,4,8]
n	[1,3,4,5,6,7,4,8]
	[1,3,4,5,6,7,4,5,6,7,4,8]
	[1,3,4,5,7,4,8]
	[1,3,4,8]
	[1,3,4,5,6,7,4,8]
<u> </u>	[1,3,4,5,7,4,5,7,4,8]
	[1,3,4,5,7,4,8]
	[1,3,4,5,7,4,5,6,7,4,8]



Summary

- A common application of graph coverage criteria is to program source – control flow graph (CFG)
- Applying graph coverage criteria to control flow graphs is relatively straightforward
- A few decisions must be made to translate control structures into the graph
- We use basic blocks when assigning program statements to nodes while some tools assign each statement to a unique node.
 - Coverage is the same, although the bookkeeping will differ



McCabe's Cyclomatic Complexity & Code Coverage



McCabe's Cyclomatic Complexity

Cyclomatic complexity is a <u>software metric</u> used to indicate the complexity of a program. It is a quantitative measure of the number of linearly independent paths through a program's <u>source code</u>.

Source: https://en.wikipedia.org/wiki/Cyclomatic_complexity



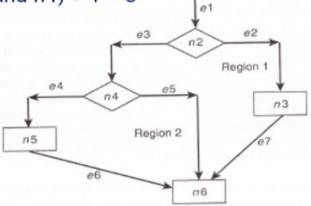
McCabe's Cyclomatic Complexity

- Basic idea: program quality is directly related to the complexity of the control flow (branching)
- Computed from a control flow diagram
 - Cyclomatic complexity = E N + 2p
 - E = number of edges of the graph
 - N = number of nodes of the graph
 - p = number of connected components (usually 1)
- Alternate computations:
 - number of binary decision + 1
 - number of closed regions +1



McCabe's Cyclomatic Complexity Example

- Using the different computations:
 - 7 edges 6 nodes + 2*1 = 3
 - 2 regions + 1 = 3
 - 2 binary decisions (n2 and n4) + 1 = 3





McCabe's Cyclomatic Complexity

- What does the number mean?
- Lower the Program's cyclomatic complexity, lower the risk to modify and easier to understand
- It's the maximum number of linearly independent paths through the flow diagram - used to determine the number of test cases needed to cover each path through the system
- The higher the number, the more risk exists (and more testing is needed)
- 1-10 is considered low risk
- greater than 50 is considered high risk

Structural Analysis

Structural Analysis ... Providing Actionable Metrics

The higher the complexity the more bugs. The more bugs the more security flaws

Cyclomatic Complexity & Reliability Risk

• 1 – 10 Simple procedure, little risk

11- 20 More Complex, moderate risk

• 21 – 50 Complex , high risk

>50 Untestable, VERY HIGH RISK

Cyclomatic Complexity & Bad Fix Probability

· 1 – 10 5%

• 20 **–**30 20%

• > 50 40%

• Approaching 100 60%

Essential Complexity (Unstructuredness) &

Maintainability (future Reliability) Risk

• 1 – 4 Structured, little risk

> 4 Unstructured, High Risk





Code Coverage

- Code coverage is a measure to describe the degree to which the source code of a program is executed when a particular test suite runs
- Code Coverage is classified as a White box testing



Benefits

- Identify untested part of codebase
- Identify testing gaps or missing tests
- Identify the redundant/dead Code



Types of Coverage

Method coverage

```
public void method(a, b, c) {

Branch coverage

                       Statement coverage
    call();
               call()){
        call();
                 Path coverage
```



ECLEmmea Code Coverage offers covered instruction and missed instructions

