Web-based Supplementary Materials for Analysis of Capture-Recapture Models with Individual Covariates Using Data Augmentation by J.A. Royle

Web Appendix A: WinBUGS model specifications for Microtus examples.

This appendix contains the WinBUGS model specifications for both the Microtus data (Fig. 1) and the waterfowl survey data (Fig. 2). These model specifications were executed from ${\bf R}$ using the R2WinBUGS library. In some instances, WinBUGS does not appear to update latent continuous random effects in some classes of capture-recapture models. This can be diagnosed by inspecting the MCMC history of the variance component of the random effect, which will show little or no movement from its initial value and chains that do not mix. In such cases, modification of the prior by truncation, according to

wt[i] ~ dnorm(mu.wt,tau.wt)I(-6,6)

appears to resolve the problem.

```
model {
   {\it \# Prior \ distributions \ for \ model \ parameters}
   psi \sim dunif(0,1)
   mu.wt~dnorm(0,.001)
   tau.wt \sim dgamma(.001,.001)
   sigma~sqrt(1/tau.wt)
   a0 \sim dnorm(0,.001)
   a1\sim dnorm(0,.001)
   a2\sim dnorm(0,.001)
   beta \sim dnorm(0,.001)
   for(i in 1:(nind+nz)){
     wt[i]~dnorm(mu.wt,tau.wt)
     z[i] \sim dbin(psi,1)
     ff[i] <-z[i]+1
     for(t in 1:T){
       logit(p[i,t])<- a0*(1-prevcap[i,t]) + a1*prevcap[i,t] + beta*wt[i]</pre>
+a2*lagY[i,t]
       P[i,t,1]<-0
       P[i,t,2] < -p[i,t]
       mu[i,t]<-P[i,t,ff[i]]</pre>
       Y[i,t] \sim dbern(mu[i,t])
   N<-sum(z[1:(nind+nz)])</pre>
}
```

Figure 1: WinBUGS model specification for the Microtus data with behavioral effects and body mass as a covariate on detection probability.

```
model {
   psi\sim dunif(0,1)
   logmu.gs~dnorm(0,.001)
   lambda<-exp(logmu.gs)</pre>
   alpha1\sim dnorm(0,.001)
   alpha2\sim dnorm(0,.001)
   beta \sim dnorm(0,.001)
   for(i in 1:(nind+nzeroes)){
     z[i] \sim dbin(psi,1)
     gs[i]~dpois(lambda)
     logit(p1[i])<- alpha1 + beta*(1+gs[i])</pre>
     logit(p2[i])<- alpha2 + beta*(1+gs[i])</pre>
     mu[i,1]<- z[i]*(1-p1[i])*p2[i]</pre>
     mu[i,2] \leftarrow z[i]*p1[i]*(1-p2[i])
     mu[i,3]<- z[i]*p1[i]*p2[i]</pre>
     mu[i,4] \leftarrow z[i]*(1-p1[i])*(1-p2[i]) + (1-z[i])
     ncap[i,1:4] \sim dmulti(mu[i,1:4],1)
   Nc<-sum(z[1:(nind+nzeroes)])</pre>
}
```

Figure 2: WinBUGS model specification of the double-observer waterfowl survey data where group size is the detection probability covariate.