

# Polymorphism

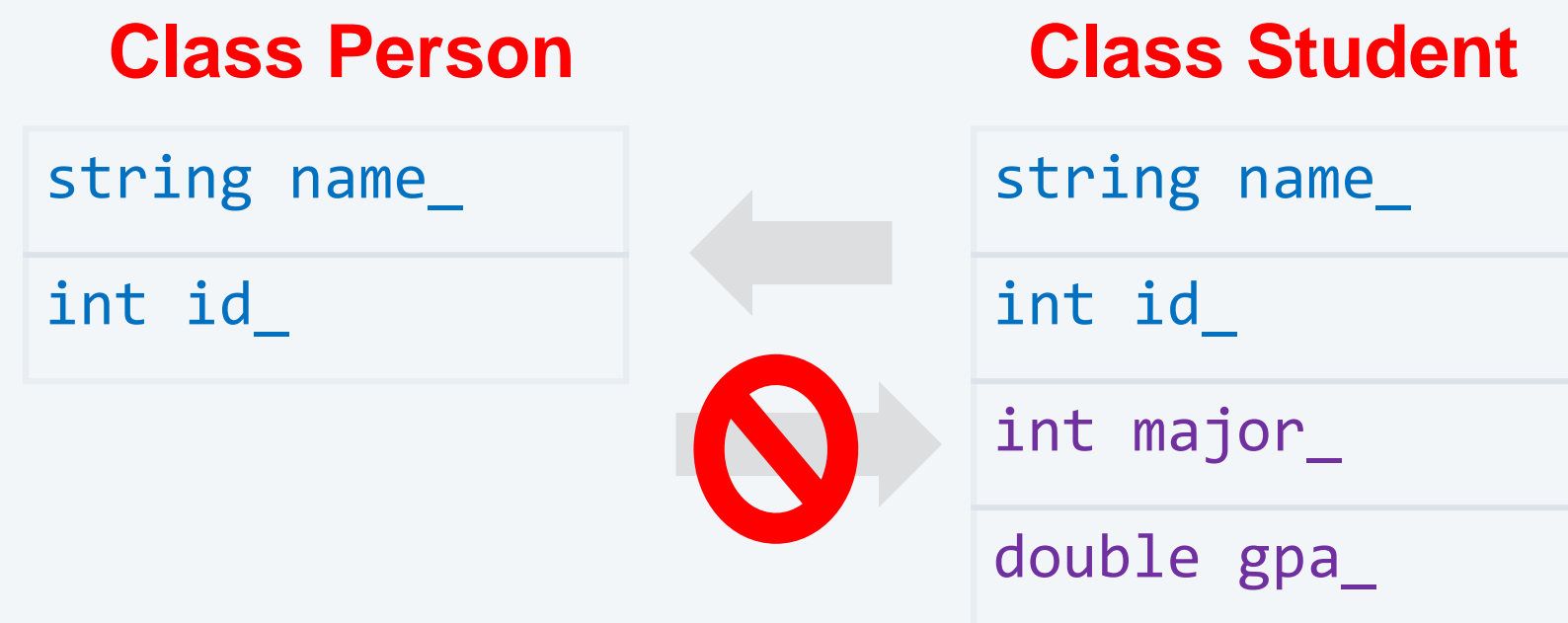
Sandra Batista, Mark Redekopp, and David Kempe

1.1–1.2

# Assignment of Derived Classes to Base cases

A class derived via public inheritance can be assigned to its base class.

- `p = s; // Base = Derived... ?`
- `s = p; // Derived = Base...?`



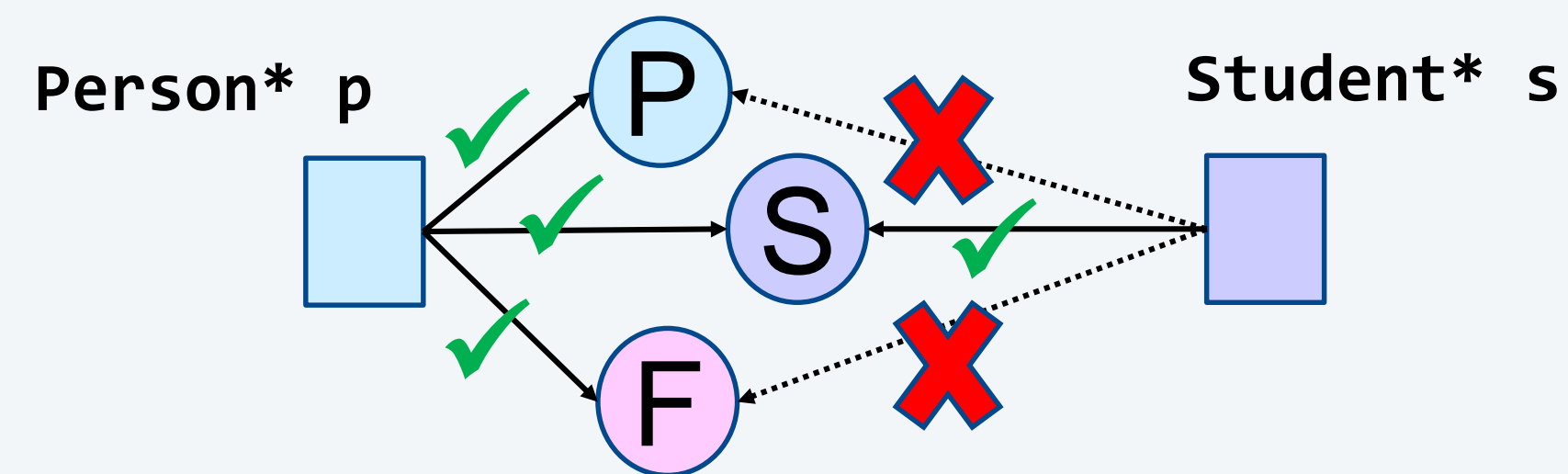
```
class Person {
public:
    Person(string n, int ident): name(), id(ident) {}
    Person():name(""), id(0) {}
    void print_info() { cout << name << " " << id << endl;}
private:
    string name;
    int id;
};

class Student : public Person {
public:
    Student(): mjr(0), gpa(0){}
    Student(string n, int ident, int m): Person(n,ident), mjr(m) {}
    void print_info() {
        Person::print_info();
        cout << mjr << " " << gpa << endl;
    }
private:
    int mjr;
    double gpa;
};

int main(){
    Person p("Bill",1);
    Student s("Joe",2,5);
    p = s;
    //s = p;
}
```

# Inheritance and Type-compatibility

A pointer or reference to a publicly derived class object is **type-compatible** with its base class type.



Base pointer CAN point at any publicly derived object.

Derived pointer CANNOT point at base or "sibling" objects

```
class Faculty : public Person {
    public:
        Faculty(): tenure(false){}
        Faculty(string n, int ident, bool t):
            Person(n,ident), tenure(t) {}
        void print_info() {
            Person::print_info();
            (tenure)? cout << "Tenured" << endl :
                cout << "Not tenured" << endl;
        }
    private:
        bool tenure;
};

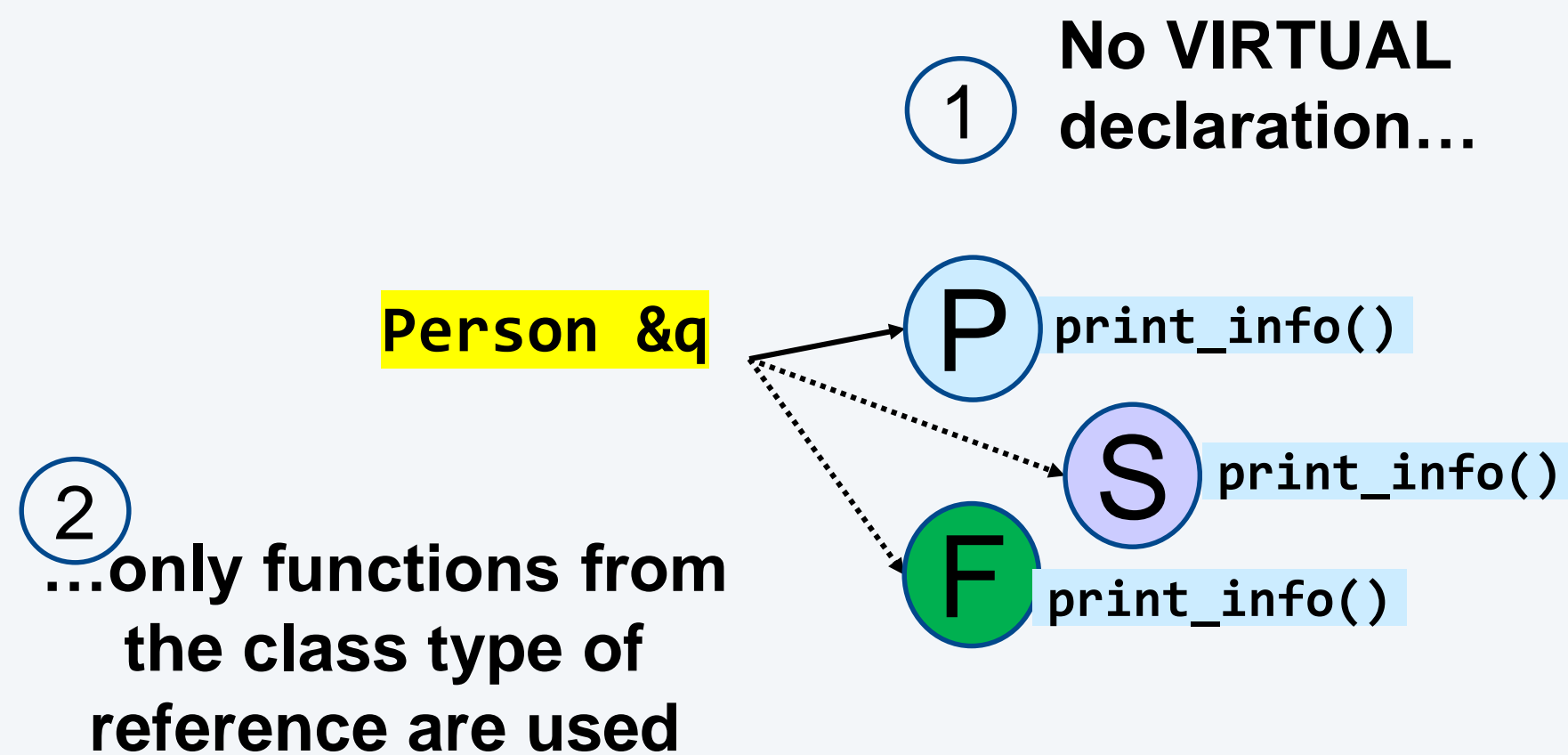
int main(){
    Person p("Bill",1);
    Student s("Joe",2,5);
    Faculty f("Brian", 3, true);
    Person &q = p;
    q = s;
    q = f;
    Student &r = s;
    // r = p;
    // r = f;
    return 0;
}
```

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# **STATIC VS. DYNAMIC BINDING**

# Inheritance and Static Binding

**Static binding** is when the version of the function called is based on the static **type of the pointer or reference used**



```
class Person {
public:
    void print_info() const; // print name, ID
    //string name; int id;
};

class Student : public Person {
public:
    void print_info() const; // print major too
    //int major; double gpa;
};

class Faculty : public Person {
public:
    void print_info() const; // print tenured
    //bool tenure;
};

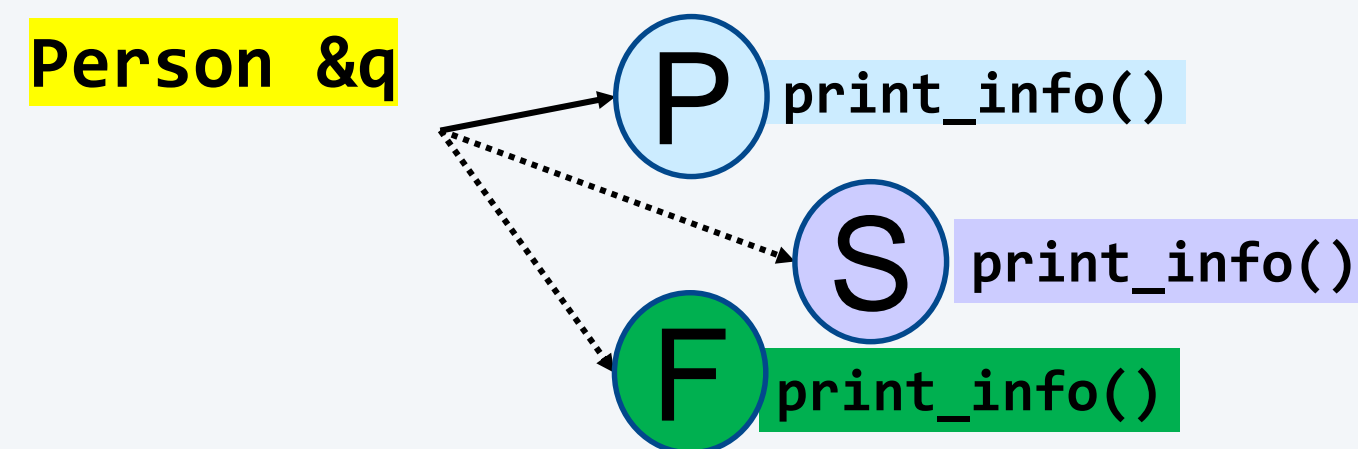
int main(){
    Person p = new Person("Bill",1);
    Student s = new Student("Joe",2,5);
    Faculty f = new Faculty("Brian",3,true);
    Person *q = &p;
    q->print_info();
    q = &s; q->print_info();
    q = &f; q->print_info();
} // calls
```

Bill 1  
Joe 2  
Brian 3

# Virtual Functions and Dynamic Binding

**virtual** keyword specifies that the version of a member function called is determined by the **type of object referenced at runtime**.

This is called **dynamic binding**



```
class Person {
public:
    virtual void print_info() const; // print name, ID
    //string name; int id;
};

class Student : public Person {
public:
    void print_info() const; // print major too
    //int major; double gpa;
};

class Faculty : public Person {
public:
    void print_info() const; // print tenured
    //bool tenure;
};

int main(){
    Person p = new Person("Bill",1);
    Student s = new Student("Joe",2,5);
    Faculty f = new Faculty("Brian",3,true);
    Person *q = &p;
    q->print_info();
    q = &s; q->print_info();
    q = &f; q->print_info();
} // calls
```

Bill 1  
Joe 2  
5 0  
Brian 3  
Tenured

# Polymorphism

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Use base class pointers to point at derived types and use virtual functions for different behaviors for each derived type

**Polymorphism** via virtual functions allows one set of code to operate appropriately on all derived types of objects

```
int main()
{
    unique_ptr<Person> people[3];
    people[0] = make_unique<Person>("Bill",1);
    people[1] = make_unique<Student>("Joe",2,5);
    people[2] = make_unique<Faculty>("Brian", 3, true);
    for (size_t i = 0; i < 3; i++){
        people[i]->print_info();
    }
    return 0;
}
```

Bill 1

Joe 2

5 0

Brian 3

Tenured

# Pointers, References, and Objects

To allow dynamic binding and polymorphism you use a base class

- **Pointer**
- **Reference**

**Copying a derived object** to a base object makes a copy and so no polymorphic behavior is possible

```
void f1(Person* p)
{
    p->print_info();
    // calls Student::print_info()
}

void f2(const Person& p)
{
    p.print_info();
    // calls Student::print_info()
}

void f3(Person p)
{
    p.print_info();
    // calls Person::print_info() on the copy
}

int main(){
    Student s("Joe",2,5);
    f1(&s);
    f2(s);
    f3(s);
    return 0;
}
```

Joe 2

5 0

Joe 2

5 0

Joe 2



# Virtual Destructors: Old School Memory Problems

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```
class Student{
    ~Student() { }
    string major();
    ...
}

class StudentWithGrades : public Student
{
public:
    StudentWithGrades(...)
    { grades = new int[10]; }
    ~StudentWithGrades { delete [] grades; }
    int *grades;
}

int main()
{
    Student *s = new StudentWithGrades(...);
    ...
    delete s; // Which destructor gets called?
    return 0;
}
```

Due to static binding (no virtual decl.)  
~Student() gets called and doesn't delete  
grades array

**Classes that will be used as a base class should have a virtual destructor**

( <http://www.parashift.com/c++-faq-lite/virtual-functions.html#faq-20.7> )

```
class Student{
    virtual ~Student() { }
    string major();
    ...
}

class StudentWithGrades : public Student
{
public:
    StudentWithGrades(...)
    { grades = new int[10]; }
    ~StudentWithGrades { delete [] grades; }
    int *grades;
}

int main()
{
    Student *s = new StudentWithGrades(...);
    ...
    delete s; // Which destructor gets called?
    return 0;
}
```

Due to dynamic binding (virtual decl.)  
~StudentWithGrades() gets called and does  
delete grades array

# Summary

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No virtual declaration:

- Member function that is called is based on the *type of the pointer or reference*
- Static binding

With virtual declaration:

- Member function that is called is based on the *type of the object referenced*
- Dynamic Binding

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# **ABSTRACT CLASSES**

# Abstract Classes & Pure Virtual Functions

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A class with at least one **pure virtual functions** is called an **abstract base class**. They serve as an interface for future derived classes.

- Prototype only
- Make function body  
" = 0; "

Objects of the **abstract class** type **MAY NOT** be instantiated

```
class Shape
{
    public:
        virtual ~Shape() { }
        virtual double getArea() = 0;
        virtual double getPerimeter() = 0;
        virtual string getType() = 0;
};

int main(){
    Shape s; // Cannot instantiate abstract class

    s.getArea(); // WILL NOT COMPILE!!

}
```

# Abstract Classes as Interfaces

- Functions that are not implemented by the abstract base class but **must be implemented by the derived class to be instantiated**
- **Exercise: Can you write a Square class that is publicly derived from the Rectangle class?**

```
class Shape
{
public:
    virtual ~Shape() { }
    virtual double getArea() = 0;
    virtual double getPerimeter() = 0;
    virtual string getType() = 0;
};

class Rectangle :    public Shape
{
public:
    Rectangle(double b, double h)
        : _b(b),_h(h){}
    ~Rectangle() { }
    double getArea() { return _b * _h; }
    double getPerimeter() { return 2*_b+2*_h; }
    string getType() { return "Rectangle"; }
private:
    double _b, _h;
};

int main(){
    Rectangle r(3,4);
    Shape &s = r;

    cout << s.getArea() << endl;

}
```

# Abstract Classes with implementation

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An abstract base class can have functions and data members defined

These data and function members are inherited by derived classes.

```
class Animal {
public:
    Animal(string c): color(c) { }
    virtual ~Animal() {}
    string get_color() { return color; }
    virtual void make_sound() = 0;
protected:
    string color;
};

class Dog : public Animal {
public:
    Dog(string c): Animal(c){}
    void make_sound() { cout << "Bark"; }
};

class Cat : public Animal {
public:
    Cat(string c): Animal(c){}
    void make_sound() { cout << "Meow"; }
};

int main(){
    Animal* a[3];
    //a[0] = new Animal;    // WON'T COMPILE...abstract class
    a[1] = new Dog("brown");
    a[2] = new Cat("calico");
    cout << a[1]->get_color() << endl;
    a[2]->make_sound();
}
```

**Output:**  
brown  
meow

# A Queue Interface

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This abstract Queue class specifies the Queue ADT operations

Any derived implementation must implement these public member functions to be instantiated

```
class IntQueue {  
  
    public:  
        virtual int front() = 0;  
        virtual bool empty() = 0;  
        virtual size_t size() = 0;  
        virtual void push_back(int v) = 0;  
        virtual void pop_front() = 0;  
  
};
```

# A STL List Queue Class

---

This class uses STL List to implement a queue.

It is an example of implementing a queue with a doubly linked list.

It is basically a wrapper class for calls directly to STL List.

```
// This class implements the queue ADT interface using STL list.
// Remember STL list is a doubly linked list implementation.

class ListIntQueue : public IntQueue {
public:
    int front() {
        // Add proper error handling
        if (queue.empty()) return -1;
        return queue.front();
    }
    bool empty() { return queue.empty(); }
    size_t size() { return queue.size(); }
    void push_back(int value) { queue.push_back(value); }
    void pop_front() {
        if (!empty()) {
            queue.pop_front();
        }
    }

private:
    std::list<int> queue;
};
```



# A STL Vector Queue Class

---

This class uses STL Vector to implement a queue.

It is an example of implementing a queue with a dynamically sized array.

It is basically a wrapper class for calls directly to STL Vector.

```
// This class implements the queue ADT interface using STL vector.  
// Remember STL vector is a dynamically sized array
```

```
class VectorIntQueue : public IntQueue {  
  
    public:  
        int front() {  
            // add appropriate error handling  
            if (this->empty()) { return -1;}  
            return queue.front();  
        }  
  
        bool empty() {    return queue.empty();  }  
        size_t size() {    return queue.size();  }  
        void push_back(int value) {    queue.push_back(v);  }  
        void pop_front() {  
            if (!empty()) {  
                queue.erase(queue.begin());  
            }  
        }  
  
    private:  
        std::vector<int> queue;  
};
```

# The Benefits of Polymorphism

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By using references to the abstract class, we can use the same code to test any derived implementation of it.

```
#include "queue.h"
#include "listqueue.h"
#include "vectorqueue.h"

#include <iostream>

#include <chrono>using namespace std;

int main(){

    // Change this for whatever queue you are testing
    list_IntQueue test_queue;
    vector_IntQueue vt_queue;
    // AbstractIntQueue &q = vt_queue;
    AbstractIntQueue &q = test_queue;

    // Is there any difference between the STL List and Queue implementations
    // for adding to the end of the queue? Run tests increasing the size...
    // What measurements can you take? Time for timing experiments.
    for (size_t i = 0; i < 100000; i++){
        q.push_back(i);
    }

    // Can you think of how to test pop_front?
}
```

# Polymorphism & Private Inheritance

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**Warning:** If **private** or **protected** inheritance is used, the **derived class is no longer type-compatible with base class**

```
class Person {
public:
    virtual void print_info();
    //string name; int id;
};
class Student : public Person {
public:
    void print_info(); // print major too
    //int major; double gpa;
};
// if we use private inheritance
// for some reason
class Faculty : private Person {
public:
    void print_info(); // print tenured
    //bool tenure;
};

int main(){
    Person p = new Person("Bill",1);
    Faculty f = new Faculty("Brian",3,true);
    Person *q = &p;
    q->print_info();
    // q = &f; q->print_info(); X No longer works

    f.print_info();
}
```