

# CSCI 104L Lecture 18: Collision Resolution

## Collision Resolution

Apart from *chaining*, another way to handle collisions is *probing*, wherein we just have an array of either key/value pairs (no linked lists). There are many variants.

In *linear probing*, if  $h(k) = i$  and  $A[i]$  is taken, we try  $A[i + 1]$  and then  $A[i + 2]$  and so on. If you reach the end of the array, you loop back to the beginning.

That is,  $h(k, i) = (h(k) + i) \% m$ , where  $i$  is the number of failed inserts, and  $m$  is the size of our hash table.

**Question 1** *What problems can you see arising when using linear probing?*

## Quadratic Probing

$$h(k, i) = (h(k) + i^2) \% m$$

**Question 2** *Using the hash function  $h(k) = k \% 10$ , determine the contents of the hash table after inserting 1, 11, 2, 21, 12, 31, 41.*

If your load factor is above 0.5, you cannot guarantee that quadratic probing will find an empty bucket, even if the hash table size is prime.

**Question 3** *Using the hash function  $h(k) = k \% 7$ , determine what happens after inserting 14, 8, 21, 2, 7.*

If the table size is not prime, the problem is even worse.

**Question 4** *Using the hash function  $h(k) = k \% 9$ , determine what happens after inserting 36, 27, 18, 9, 0.*

If your hash table has a prime size, then the first  $\frac{m}{2}$  probes are guaranteed to go to distinct locations, meaning that you will find a location if the load factor is no more than 0.5.

## Double Hashing

This avoids both primary and secondary clumping. You have a second hash function  $h'(k)$ .

If  $h(k) = i$  is taken, then try, in order,  $i + h'(k)$ ,  $i + 2h'(k)$ ,  $i + 3h'(k)$ , ...

That is,  $h(k, i) = (h(k) + i \cdot h'(k)) \% m$ .

This is better because even amongst all the items mapped to  $i$ , they will follow very different paths.

A good choice of secondary hash function can ensure you always find a free slot as long as the load factor is smaller than 1 (but you still want to keep the load factor below 0.5 for performance issues).

An example of a good secondary hash functions is  $h'(k) = p - (k \% p)$ , where  $p$  is a prime smaller than  $m$ .

## Bloom Filters

**Question 5** *Could we use a hashtable to implement a set?*

**Question 6** *What kind of issues would arise with such an implementation?*

Bloom Filters are a way to avoid requiring the storage of keys. They come with a tradeoff: Bloom Filters are Monte Carlo Randomized Algorithms. That is, there is a small chance you will get the wrong answer.

When implementing a set, we generally have three functions: add, remove, contains.

When using a Bloom Filter, we will not implement remove (it's generally not worth it).

Your set merely needs to save which items are inside. You can add an item, and you can check whether an item is contained within it.

All we really need is an array of bits. If we want to store item  $k$  inside our set, then pass  $k$  into our hash function  $h(k)$ , and set  $a[h(k)] = 1$ .

**Question 7** *What's the problem with this proposed implementation?*

A false positive occurs when we say something is in the set, but it actually isn't. We will try to minimize the probability of this occurring.

**Question 8** *Is a false negative possible?*

To reduce the probability of a false positive, we can use multiple hash functions  $h_1, h_2, \dots, h_j$ . When we add an item  $k$  to the array, we set  $h_1(k), h_2(k), \dots, h_j(k)$  to true.

When we check whether an item is in the array, we make sure ALL of the bits  $h_1(k), h_2(k), \dots, h_j(k)$  are set.

**Question 9** *Can a false negative occur in this new implementation?*

The probability of a false positive should have vastly decreased, because we have  $j$  independent tests as to whether the item is being stored in the set. The tradeoff is that we must increase the size of our bloom filter to compensate for the additional number of inserted bits.

If you want a false positive rate of 1%, you would want 7 hash functions, and 9.2 bits in the bloom filter for each item you plan to have inside.

If you want a false positive rate of .1%, you would want 10 hash functions, and 14 bits per key.

Most Bloom Filters will have between 2-20 hash functions.

Pre-filter Bloom Filters have become quite popular for applications that expect the majority of queries to return "no". You do a very cheap Bloom Filter operation to check whether the item is in the set or not. If the answer is "yes", we then verify it via a more expensive operation.

Suppose we have the following hash functions:

- $h_1 = (7x + 4) \% 10$
- $h_2 = (2x + 1) \% 10$
- $h_3 = (5x + 3) \% 10$

**Question 10** *What happens after inserting 0, 1, 2, 8, then looking up 2, 3, 4, 9?*