

# CS 188: Artificial Intelligence

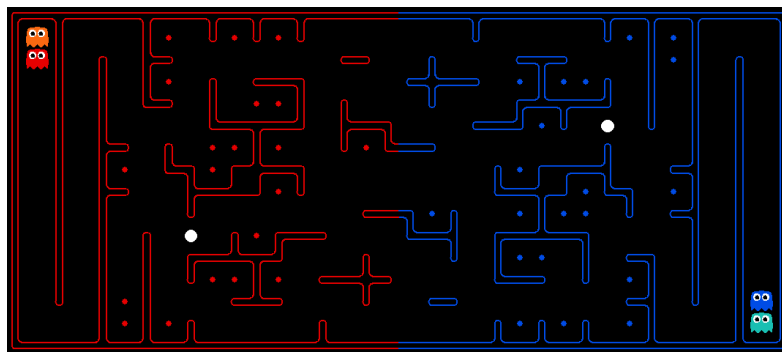
## Fall 2011

### Lecture 25: Conclusion

12/1/2011

Dan Klein – UC Berkeley

## Pacman Contest



- **Challenges:**

- Long term strategy
- Multiple agents
- Adversarial utilities
- Uncertainty about other agents' positions, plans, etc.

## CONTEST SLIDES HIDDEN

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## ...and Congratulations to All!

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- Amazing work by everyone
- You should all be proud of what you've accomplished!

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## Example: Starcraft



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## What is Starcraft?

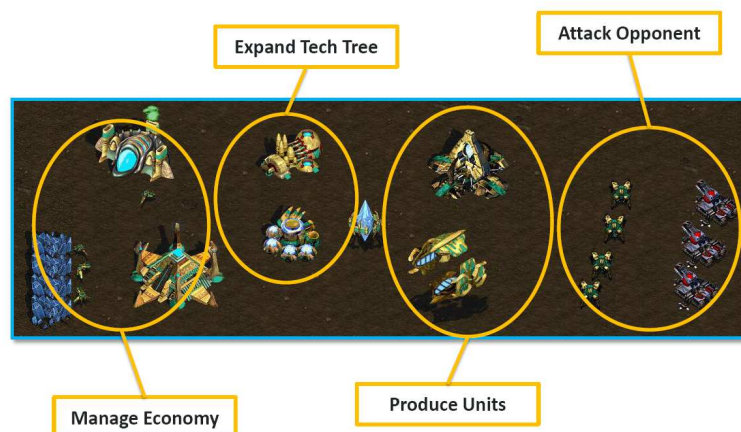


Image from Ben Weber

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## Why is Starcraft Hard?

- Starcraft is:
  - Adversarial
  - Long Horizon
  - Partially Observable
  - Realtime
  - Concurrent
  - ...
- No single algorithm (e.g. minimax) will solve it off-the-shelf



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## The Berkeley Overmind



Search: path planning  
Minimax: targeting  
Learning: micro control  
Inference: tracking units  
Scheduling: resource management  
Hierarchical control

<http://overmind.eecs.berkeley.edu>

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## Search for Pathing



[Pathing]

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## Minimax for Targeting



[Targeting]

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## RL for Micro Control

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[RL, Potential Fields]

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## Inference / VPI / Scouting

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[Scouting, Cloaking]

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# Starcraft Als: AIIDE 2010



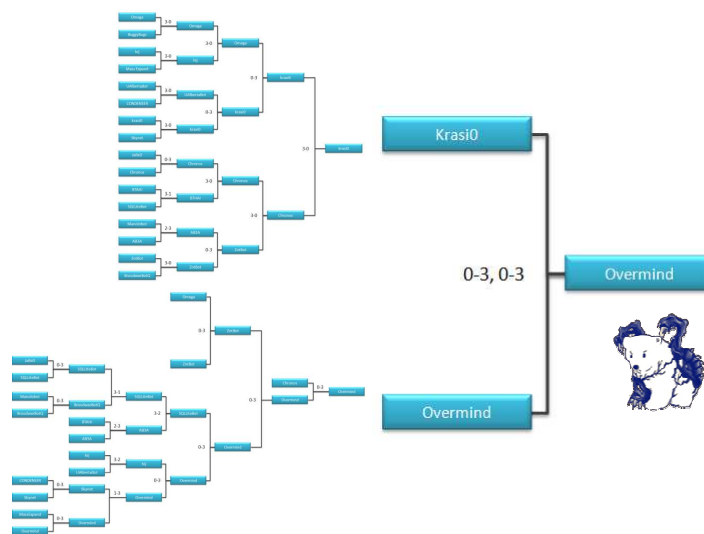
```
onFrame() {
  units = Broodwar->getAllUnits();
  unit->attackUnit(enemyUnit);
}
```

```
onFrame() {
  units = Broodwar->getAllUnits();
  unit->attackUnit(enemyUnit);
}
```

- 28 Teams: international entrants, universities, research labs...

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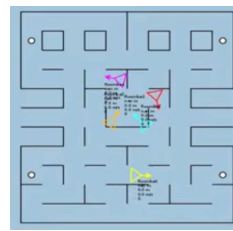
# AIIDE 2010 Competition



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# Pacman: Beyond Simulation?

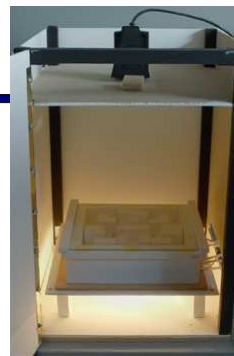


[DEMO]

Students at Colorado University: <http://pacman.elstonj.com>

# Bugman?

- AI = Animal Intelligence?
  - Wim van Eck at Leiden University
  - Pacman controlled by a human
  - Ghosts controlled by crickets
  - Vibrations drive crickets toward or away from Pacman's location



[DEMO]

<http://pong.hku.nl/~wim/bugman.htm>

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## Where to go next?

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- Congratulations, you've seen the basics of modern AI
  - ... and done some amazing work putting it to use!
- How to continue:
  - Machine learning: cs281a / cs281b (also a 194)
  - Cognitive modeling: cog sci 131
  - Vision: cs280
  - Robotics: cs287
  - NLP: cs288
  - Decision making: cs289
  - ... and more; ask if you're interested
- Next term:
  - cs280 (vision)
  - cs281b (classification)

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## That's It!

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- Help us out with some course evaluations
- Have a good break, and always maximize your expected utilities!

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