

CS 188: Artificial Intelligence

Fall 2011

Lecture 13: Bayes' Nets

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Probabilistic Models

- Models describe how (a portion of) the world works
- Models are always simplifications
 - May not account for every variable
 - May not account for all interactions between variables
 - “All models are wrong; but some are useful.”
 - George E. P. Box
- What do we do with probabilistic models?
 - We (or our agents) need to reason about unknown variables, given evidence
 - Example: explanation (diagnostic reasoning)
 - Example: prediction (causal reasoning)
 - Example: value of information

2

Model for Ghostbusters

- Reminder: ghost is hidden, sensors are noisy

- T: Top sensor is red
B: Bottom sensor is red
G: Ghost is in the top

- Queries:

$$P(+g) = ??$$

$$P(+g \mid +t) = ??$$

$$P(+g \mid +t, -b) = ??$$

- Problem: joint distribution too large / complex



Joint Distribution

T	B	G	P(T,B,G)
+t	+b	+g	0.16
+t	+b	¬g	0.16
+t	¬b	+g	0.24
+t	¬b	¬g	0.04
¬t	+b	+g	0.04
¬t	+b	¬g	0.24
¬t	¬b	+g	0.06
¬t	¬b	¬g	0.06

Independence

- Two variables are *independent* if:

$$\forall x, y : P(x, y) = P(x)P(y)$$

- This says that their joint distribution *factors* into a product two simpler distributions
- Another form:

$$\forall x, y : P(x|y) = P(x)$$

- We write: $X \perp\!\!\!\perp Y$

- Independence is a simplifying *modeling assumption*

- Empirical* joint distributions: at best “close” to independent
- What could we assume for {Weather, Traffic, Cavity, Toothache}?

Conditional Independence

- $P(\text{Toothache}, \text{Cavity}, \text{Catch})$
- If I have a cavity, the probability that the probe catches in it doesn't depend on whether I have a toothache:
 - $P(+catch \mid +toothache, +cavity) = P(+catch \mid +cavity)$
- The same independence holds if I don't have a cavity:
 - $P(+catch \mid +toothache, \neg cavity) = P(+catch \mid \neg cavity)$
- Catch is *conditionally independent* of Toothache given Cavity:
 - $P(\text{Catch} \mid \text{Toothache}, \text{Cavity}) = P(\text{Catch} \mid \text{Cavity})$
- Equivalent statements:
 - $P(\text{Toothache} \mid \text{Catch}, \text{Cavity}) = P(\text{Toothache} \mid \text{Cavity})$
 - $P(\text{Toothache}, \text{Catch} \mid \text{Cavity}) = P(\text{Toothache} \mid \text{Cavity}) P(\text{Catch} \mid \text{Cavity})$
 - One can be derived from the other easily

8

Conditional Independence

- Unconditional (absolute) independence very rare (why?)
- *Conditional independence* is our most basic and robust form of knowledge about uncertain environments:

$$\forall x, y, z : P(x, y|z) = P(x|z)P(y|z)$$

$$\forall x, y, z : P(x|z, y) = P(x|z)$$

$$X \perp\!\!\!\perp Y \mid Z$$

- What about this domain:
 - Traffic
 - Umbrella
 - Raining
- What about fire, smoke, alarm?

9

The Chain Rule

$$P(X_1, X_2, \dots, X_n) = P(X_1)P(X_2|X_1)P(X_3|X_1, X_2) \dots$$

- Trivial decomposition:

$$P(\text{Traffic, Rain, Umbrella}) = P(\text{Rain})P(\text{Traffic}|\text{Rain})P(\text{Umbrella}|\text{Rain, Traffic})$$

- With assumption of conditional independence:

$$P(\text{Traffic, Rain, Umbrella}) = P(\text{Rain})P(\text{Traffic}|\text{Rain})P(\text{Umbrella}|\text{Rain})$$

- Bayes' nets / graphical models help us express conditional independence assumptions

10

Ghostbusters Chain Rule

- Each sensor depends only on where the ghost is

$$P(T, B, G) = P(G) P(T|G) P(B|G)$$

- That means, the two sensors are conditionally independent, given the ghost position

- T: Top square is red
B: Bottom square is red
G: Ghost is in the top

- Givens:

$$\begin{aligned} P(+g) &= 0.5 \\ P(+t \mid +g) &= 0.8 \\ P(+t \mid -g) &= 0.4 \\ P(+b \mid +g) &= 0.4 \\ P(+b \mid -g) &= 0.8 \end{aligned}$$

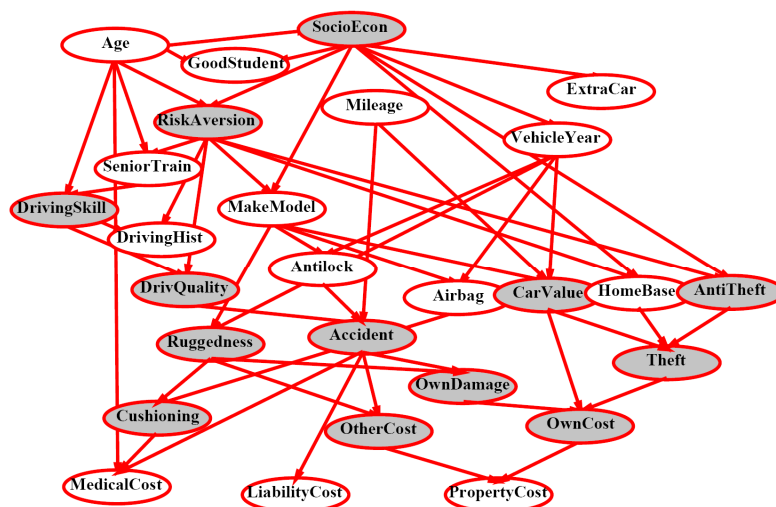
T	B	G	P(T,B,G)
+t	+b	+g	0.16
+t	+b	-g	0.16
+t	-b	+g	0.24
+t	-b	-g	0.04
-t	+b	+g	0.04
-t	+b	-g	0.24
-t	-b	+g	0.06
-t	-b	-g	0.06

Bayes' Nets: Big Picture

- Two problems with using full joint distribution tables as our probabilistic models:
 - Unless there are only a few variables, the joint is WAY too big to represent explicitly
 - Hard to learn (estimate) anything empirically about more than a few variables at a time
- Bayes' nets: a technique for describing complex joint distributions (models) using simple, local distributions (conditional probabilities)
 - More properly called **graphical models**
 - We describe how variables locally interact
 - Local interactions chain together to give global, indirect interactions
 - For about 10 min, we'll be vague about how these interactions are specified

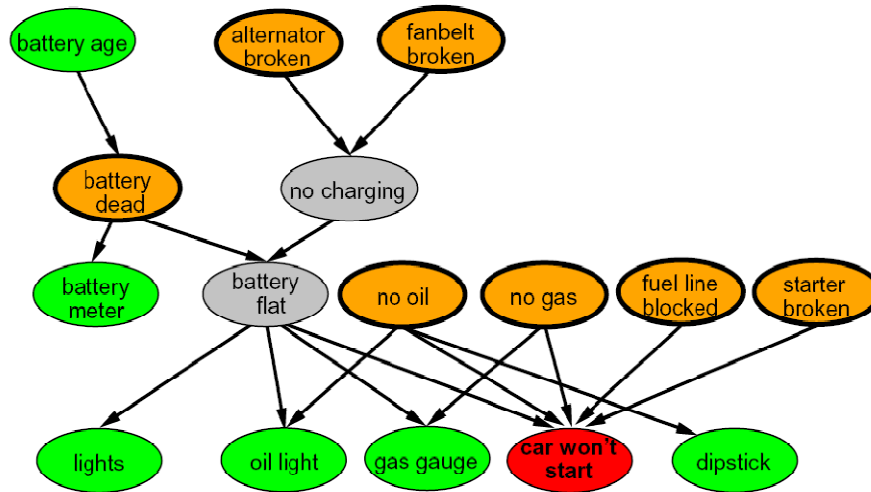
12

Example Bayes' Net: Insurance



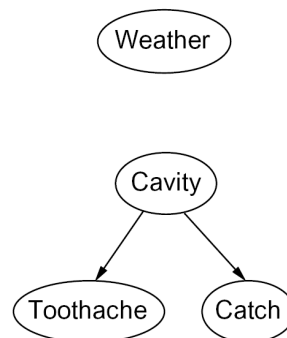
13

Example Bayes' Net: Car



Graphical Model Notation

- **Nodes: variables (with domains)**
 - Can be assigned (observed) or unassigned (unobserved)
- **Arcs: interactions**
 - Similar to CSP constraints
 - Indicate “direct influence” between variables
 - Formally: encode conditional independence (more later)
- **For now: imagine that arrows mean direct causation (in general, they don't!)**



Example: Coin Flips

- N independent coin flips

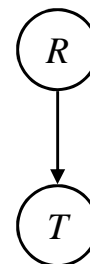


- No interactions between variables:
absolute independence

16

Example: Traffic

- Variables:
 - R: It rains
 - T: There is traffic
- Model 1: independence
- Model 2: rain causes traffic
- Why is an agent using model 2 better?



17

Example: Traffic II

- Let's build a causal graphical model
- Variables
 - T: Traffic
 - R: It rains
 - L: Low pressure
 - D: Roof drips
 - B: Ballgame
 - C: Cavity

18

Example: Alarm Network

- Variables
 - B: Burglary
 - A: Alarm goes off
 - M: Mary calls
 - J: John calls
 - E: Earthquake!

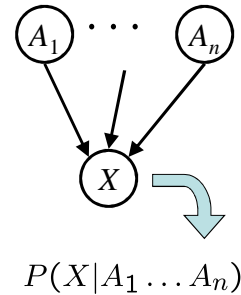
19

Bayes' Net Semantics

- Let's formalize the semantics of a Bayes' net
- A set of nodes, one per variable X
- A directed, acyclic graph
- A conditional distribution for each node
 - A collection of distributions over X , one for each combination of parents' values

$$P(X|a_1 \dots a_n)$$

- CPT: conditional probability table
- Description of a noisy "causal" process



A Bayes net = Topology (graph) + Local Conditional Probabilities

21

Probabilities in BNs

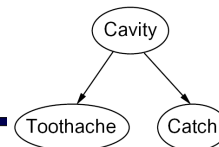
- Bayes' nets **implicitly** encode joint distributions
 - As a product of local conditional distributions
 - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

- Example:

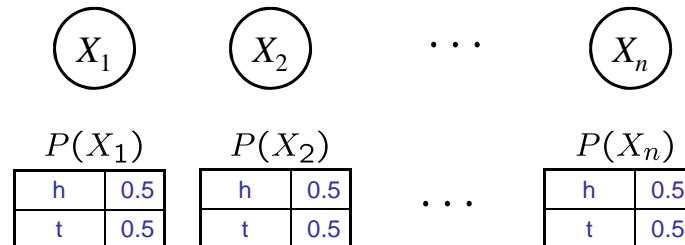
$$P(+cavity, +catch, \neg toothache)$$

- This lets us reconstruct any entry of the full joint
- Not every BN can represent every joint distribution
 - The topology enforces certain conditional independencies



22

Example: Coin Flips

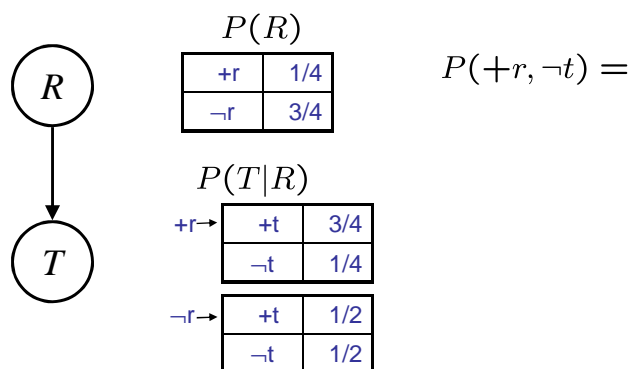


$$P(h, h, t, h) =$$

Only distributions whose variables are absolutely independent can be represented by a Bayes' net with no arcs.

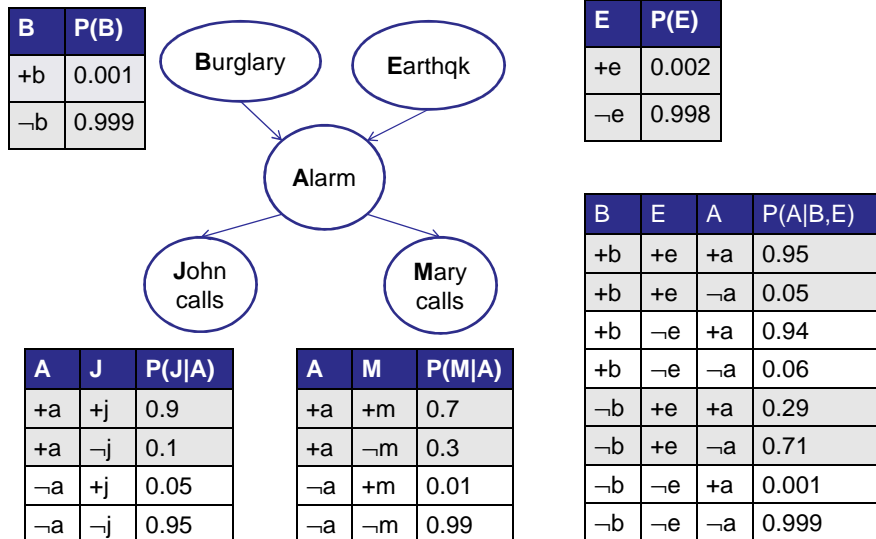
23

Example: Traffic



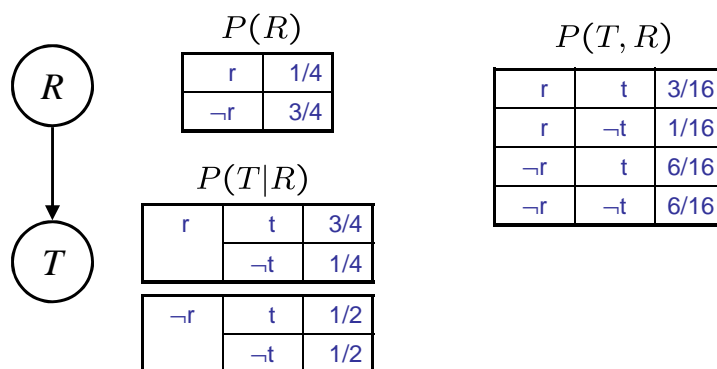
24

Example: Alarm Network



Example: Traffic

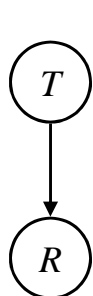
■ Causal direction



26

Example: Reverse Traffic

- Reverse causality?



```

graph TD
    T((T)) --> R((R))
        
```

$P(T)$

t	9/16
¬t	7/16

 $P(R|T)$

t	r	1/3
	¬r	2/3
¬t	r	1/7
	¬r	6/7

$P(T, R)$

r	t	3/16
r	¬t	1/16
¬r	t	6/16
¬r	¬t	6/16

27

Causality?

- When Bayes' nets reflect the true causal patterns:
 - Often simpler (nodes have fewer parents)
 - Often easier to think about
 - Often easier to elicit from experts
- BNs need not actually be causal
 - Sometimes no causal net exists over the domain (especially if variables are missing)
 - E.g. consider the variables *Traffic* and *Drips*
 - End up with arrows that reflect correlation, not causation
- What do the arrows really mean?
 - Topology may happen to encode causal structure
 - Topology really encodes conditional independence

28

Bayes' Nets

- So far: how a Bayes' net encodes a joint distribution
- Next: how to answer queries about that distribution
 - Key idea: conditional independence
 - Today: assembled BNs using an intuitive notion of conditional independence as causality
 - Next: formalize these ideas
 - Main goal: answer queries about conditional independence and influence
- After that: how to answer numerical queries (inference)

29