

1 Certifying Differential Invariants of Neural Networks using 2 Abstract Duals 3

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6 Neural networks are increasingly used in safety-critical domains, necessitating formal guarantees about
7 their properties under perturbations to inputs. Existing robust verification techniques, typified by DeepPoly,
8 primarily focus on the Forward Pass Verification Problem—certifying output stability where $f(I) \subseteq [y_L, y_R]$
9 for an L_∞ -constrained input set $I = \{x \mid \|x - x_0\|_\infty \leq \epsilon\}$. While methods like DeepPoly employ a sophisticated
10 polyhedral abstract domain (combining intervals and affine forms) to generate sound, tight bounds, this entire
11 class of analysis still fails to provide sound guarantees over the network’s derivative behavior. This oversight
12 creates a critical verification gap for gradient-dependent systems—such as scientific machine learning models
13 and feedback control loops—where the core challenge shifts to the Backward Pass Verification Problem:
14 formally bounding the Jacobian $J(x) = \nabla_x f(x)$ such that $J(x) \subseteq [J_L, J_R]$ for all $x \in I$. This new capability is
essential for certifying crucial differential invariants.

15 **1 Introduction**
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17 **2 Overview**

18 **3 [Contribution 1]**

19 **4 [Contribution 2]**

20 **5 Evaluation**

21 **6 Related Work**

22 **7 Conclusion**

23 **Acknowledgments**

24 TBD
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26 **References**
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