

Desafío 2 - Grupo 4



Trabajando con CNNs o RNNs

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Introducción

En este segundo desafío, deberán elegir un problema en concreto a resolver y proponer un dataset acorde al ejercicio.

Para esto, podrán utilizar algún dataset preexistente o construir uno propio recolectando datos a partir de herramientas de web scraping o consumo de APIs.

Objetivos

- Entrenar y optimizar una red neuronal convolucional que sea capaz de resolver un problema de computer vision, por ejemplo, clasificación de imágenes .
- Entrenar y optimizar una red neuronal recurrente que sea capaz de realizar alguna predicción en base a información secuencial, por ejemplo, pronóstico de series de tiempo o clasificación de textos.

Planteo general de desafío

Dataset

Seleccionar un dataset de imágenes categorizadas.

Modelos

Determinar una lista de modelos de redes convolucionales.

Hacer pruebas con dichos modelos.

Comparativa

Determinar cuál de los modelos probados tiene mejor precisión al momento de clasificar una imagen.

Implementación

Dataset

Stanford Dogs Dataset:

Este conjunto de datos se ha creado utilizando imágenes y anotaciones de ImageNet para la tarea de categorización de imagen detallada.

- Categorías: 120
 - Imágenes: 20,580
 - Anotaciones: etiquetas de clase, cuadros delimitadores
 - 757 MB
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Modelos CNN

- Propio
 - Pre-Entrenado VGG19/RAdam
 - Pre-Entrenado InceptionV3/RAdam
 - Pre-Entrenado InceptionV3
 - Pre-Entrenado InceptionResNetV2
 - Pre-Entrenado NASNet/RAdam
 - Pre-Entrenado Xception
 - Pre-Entrenado VGG19/RAdam/Fine Tunning
 - Pre-Entrenado InceptionV3/RAdam/Fine Tunning
 - Pre-Entrenado NASNet/RAdam/Fine Tunning
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Proceso de pruebas

- Se separa un porcentaje de las imágenes de cada categoría en train, test y validación.

Modelo CNN Propio - Arquitectura

Capa	Activación
Conv2D (32)	relu
MaxPooling2D	
Conv2D (64)	relu
MaxPooling2D	
Conv2D (128)	relu
MaxPooling2D	
Conv2D (128)	relu

Capa	Activación
Flatten	
Dense (512)	relu
Dense (120)	softmax

Kernel	3 x 3
pool_size	2 x 2

Modelo CNN Propio - Compilación

loss	categorical_crossentropy
optimizer	RAdam <ul style="list-style-type: none">• total_steps = 5000• warmup_proportion = 0.1• min_lr = 1e-7
metrics	categorical_accuracy

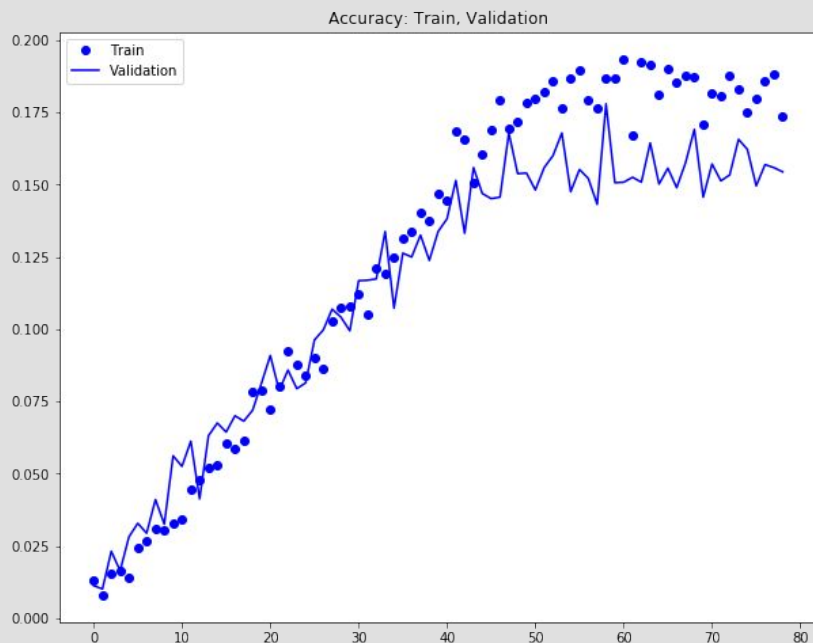
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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Modelo CNN Propio - Entrenamiento

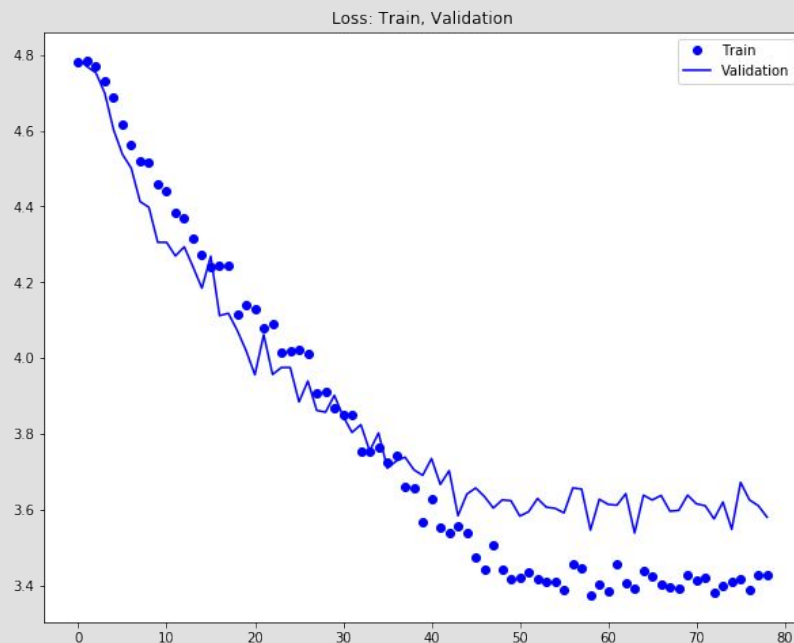
callbacks	<p>EarlyStopping</p> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 500• validation_data = valid_generator• validation_steps = 50

Modelo CNN Propio - Resultados

Precisión



Pérdida



Modelos Pre Entrenados

Modelo Pre Entrenado VGG19 / RAdam

VGG19 / RAdam - Arquitectura

Capa	Activación
conv_base (VGG19)	
Flatten	
Dense (256)	relu
Dense (120)	softmax

VGG19 / RAdam - Compilación

loss	categorical_crossentropy
optimizer	RAdam <ul style="list-style-type: none">• lr=1e-4
metrics	categorical_accuracy

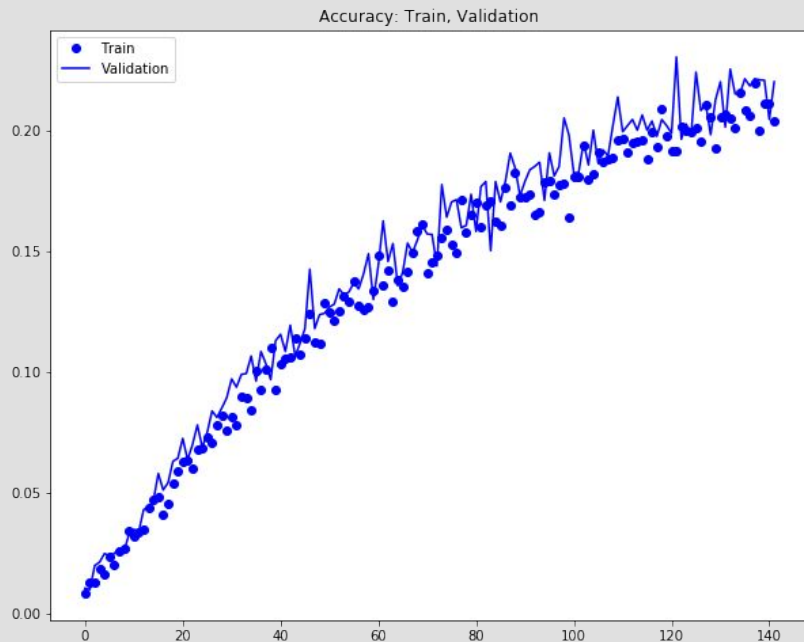
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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VGG19 / RAdam - Entrenamiento

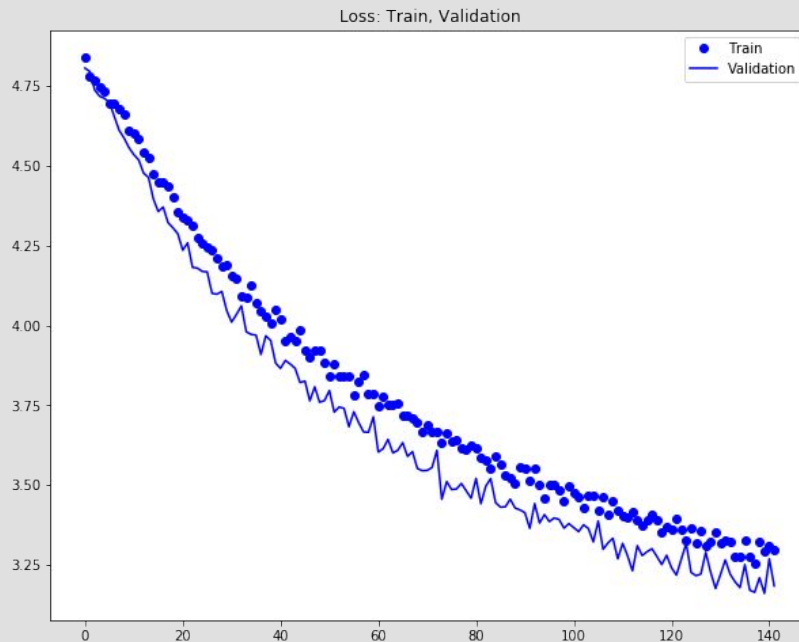
callbacks	<p>EarlyStopping</p> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 500• validation_data = valid_generator• validation_steps = 50

VGG19 / RAdam - Resultados

Precisión



Pérdida



Modelo Pre Entrenado InceptionV3 / RAdam

InceptionV3 / RAdam - Arquitectura

Capa	Activación
conv_base (inception_v3)	
Flatten	
Dense (256)	relu
Dense (120)	softmax

InceptionV3 / RAdam - Compilación

loss	categorical_crossentropy
optimizer	RAdam <ul style="list-style-type: none">• total_steps = 5000• warmup_proportion = 0.1• min_lr = 1e-7
metrics	categorical_accuracy

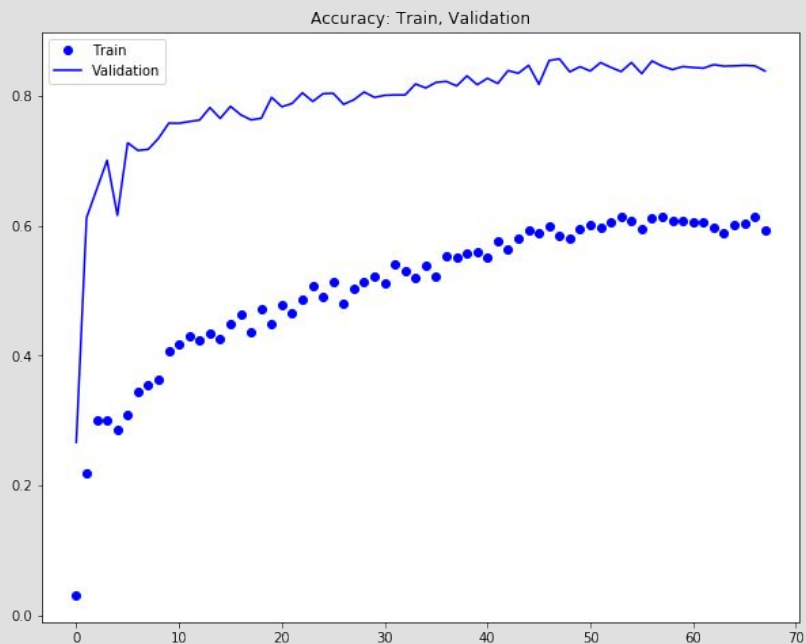
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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InceptionV3 / RAdam - Entrenamiento

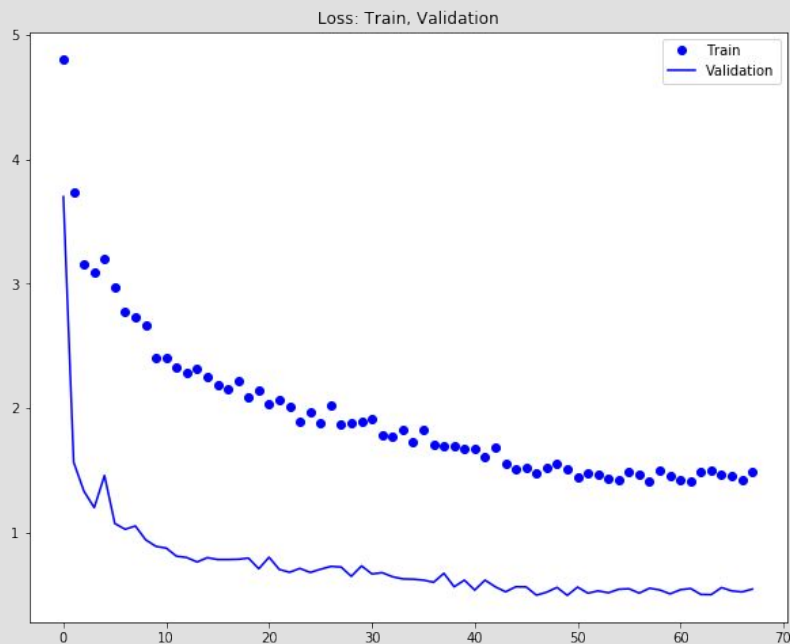
callbacks	<p>EarlyStopping</p> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 500• validation_data = valid_generator• validation_steps = 50

InceptionV3 / RAdam - Resultados

Precisión



Pérdida



Modelo Pre Entrenado InceptionV3

InceptionV3 - Arquitectura

Capa	Activación
conv_base (inception_v3)	
Flatten	
Dense (256)	relu
Dense (120)	softmax

InceptionV3 - Compilación

loss	categorical_crossentropy
optimizer	<div>RMSprop<ul style="list-style-type: none">• Lr = 1e-4</div>
metrics	categorical_accuracy

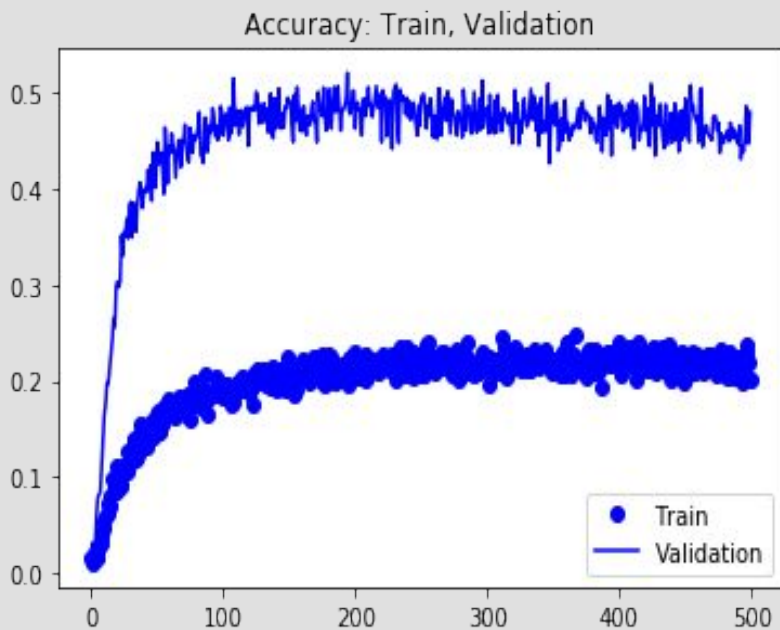
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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InceptionV3 - Entrenamiento

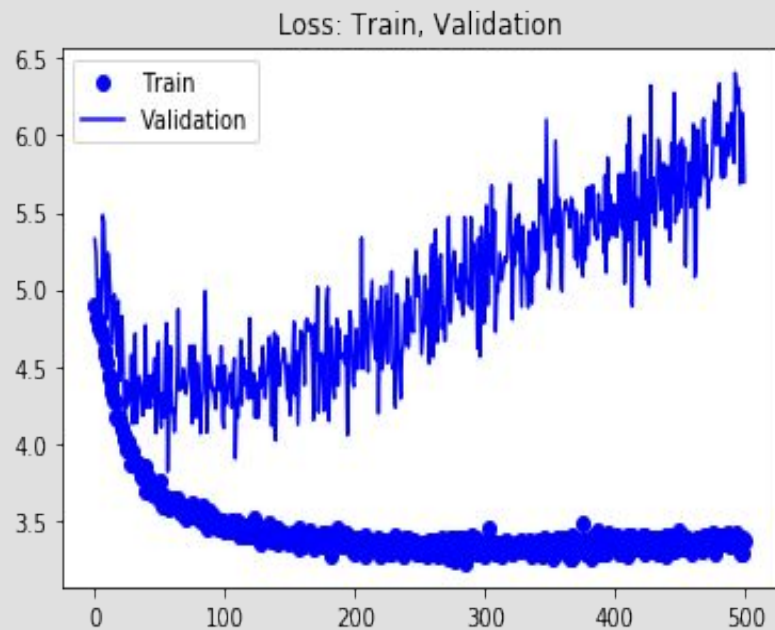
callbacks	<p>EarlyStopping</p> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 500• validation_data = valid_generator• validation_steps = 50

InceptionV3 - Resultados

Precisión



Pérdida



Modelo Pre Entrenado InceptionResNetV2

InceptionResNetV2 - Arquitectura

Capa	Activación
conv_base (inception_resnet_v2)	
Flatten	
Dense (256)	relu
Dense (120)	softmax

InceptionResNetV2 - Compilación

loss	categorical_crossentropy
optimizer	<p>RAdam</p> <ul style="list-style-type: none">• total_steps = 5000• warmup_proportion = 0.1• min_lr = 1e-7
metrics	categorical_accuracy

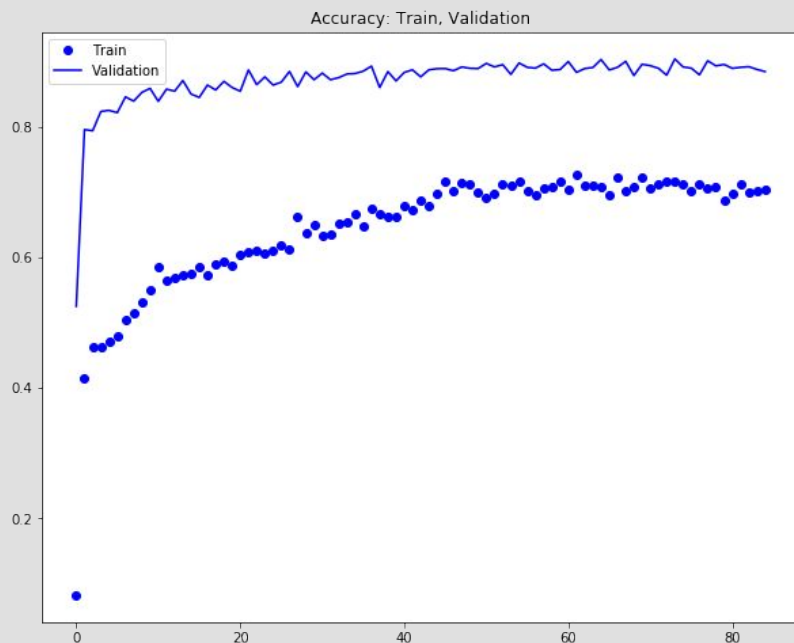
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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InceptionResNetV2 - Entrenamiento

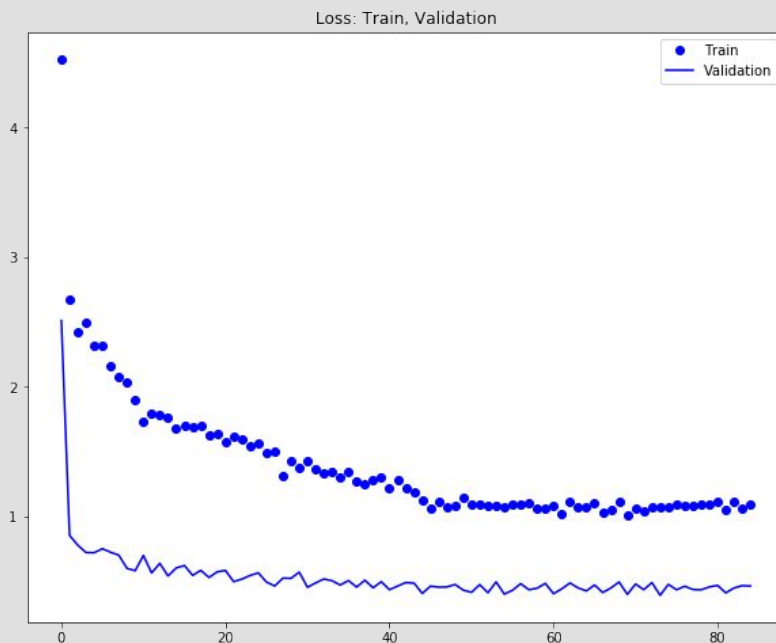
callbacks	<div>EarlyStopping</div> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 500• validation_data = valid_generator• validation_steps = 50

InceptionResNetV2 - Resultados

Precisión



Pérdida



Modelo Pre Entrenado NASNet

NASNet - Arquitectura

Capa	Activación
conv_base (NASNet)	
Flatten	
Dense (256)	relu
Dense (120)	softmax

NASNet - Compilación

loss	categorical_crossentropy
optimizer	<p>RAdam</p> <ul style="list-style-type: none">• total_steps = 5000• warmup_proportion = 0.1• min_lr = 1e-7
metrics	categorical_accuracy

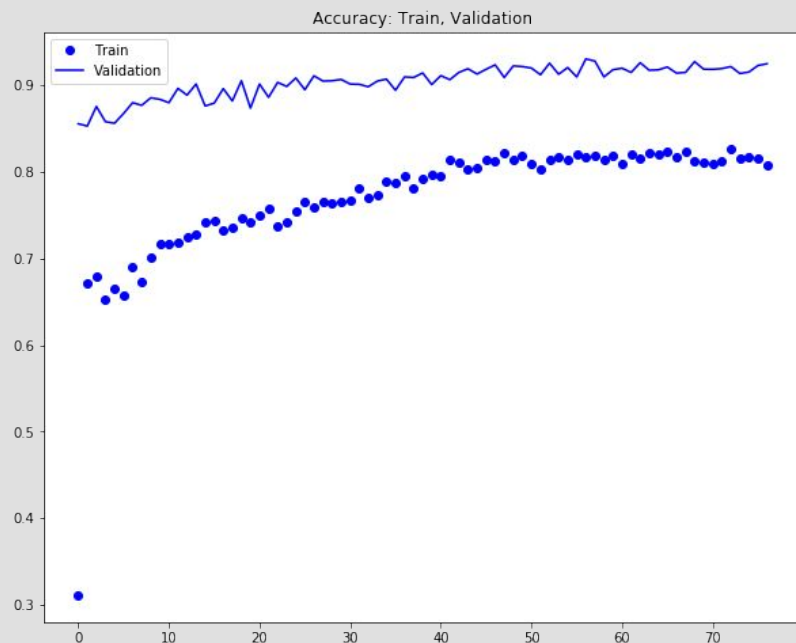
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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NASNet - Entrenamiento

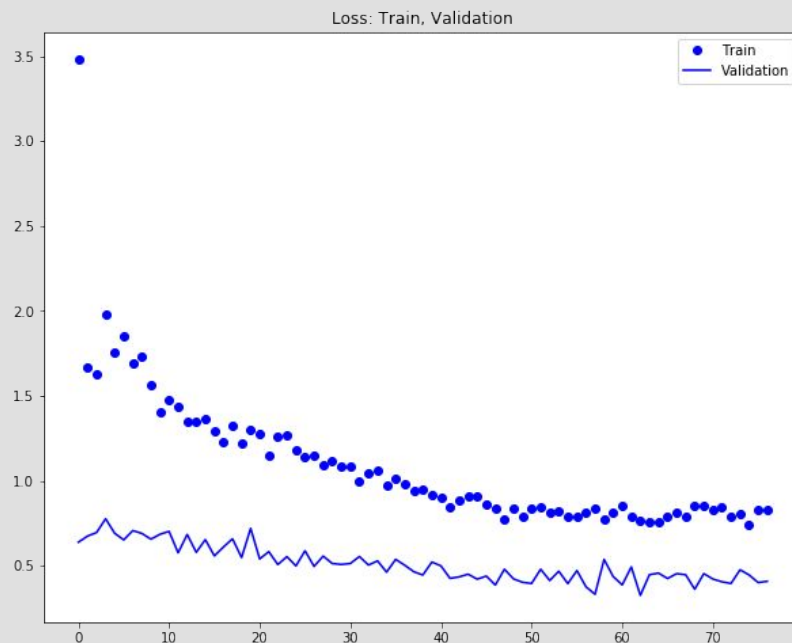
callbacks	<p>EarlyStopping</p> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 500• validation_data = valid_generator• validation_steps = 50

NASNet - Resultados

Precisión



Pérdida



Modelo Pre Entrenado Xception

Xception - Arquitectura

Capa	Activación
conv_base (xception)	
Flatten	
Dense (256)	relu
Dense (120)	softmax

Xception - Compilación

loss	categorical_crossentropy
optimizer	RAdam <ul style="list-style-type: none">• total_steps = 5000• warmup_proportion = 0.1• min_lr = 1e-7
metrics	categorical_accuracy

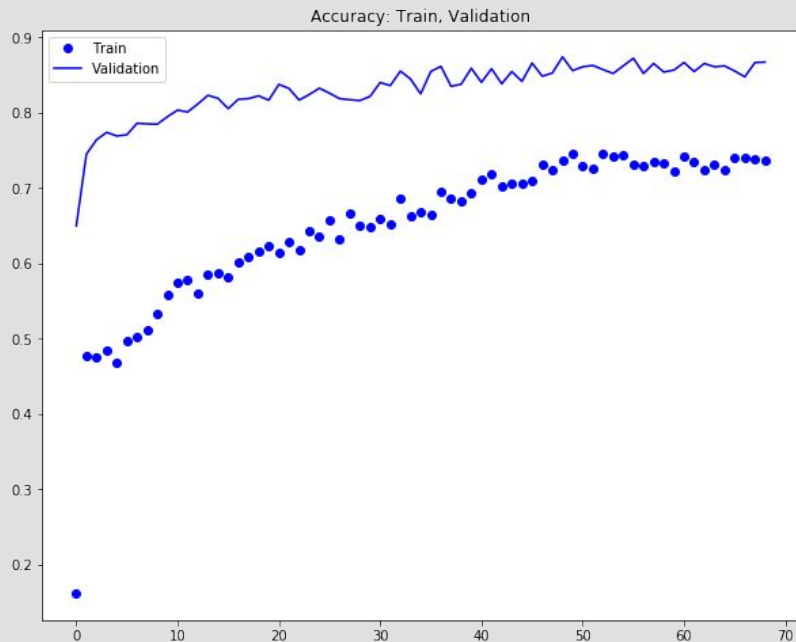
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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Xception - Entrenamiento

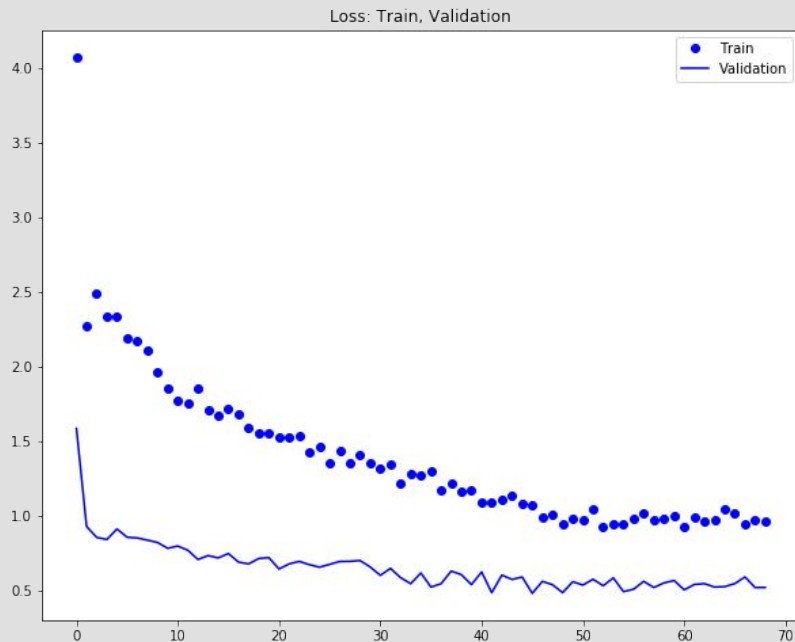
callbacks	<p>EarlyStopping</p> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 500• validation_data = valid_generator• validation_steps = 50

Xception - Resultados

Precisión



Pérdida



Modelo Pre Entrenado VGG19 / Fine Tunning

VGG19/Fine Tunning - Arquitectura

Capa	Activación
conv_base (xception)	
Flatten	
Dense (256)	relu
Dense (120)	softmax

VGG19/Fine Tunning - Compilación

loss	categorical_crossentropy
optimizer	<p>RAdam</p> <ul style="list-style-type: none">• total_steps = 5000• warmup_proportion = 0.1• min_lr = 1e-7
metrics	categorical_accuracy

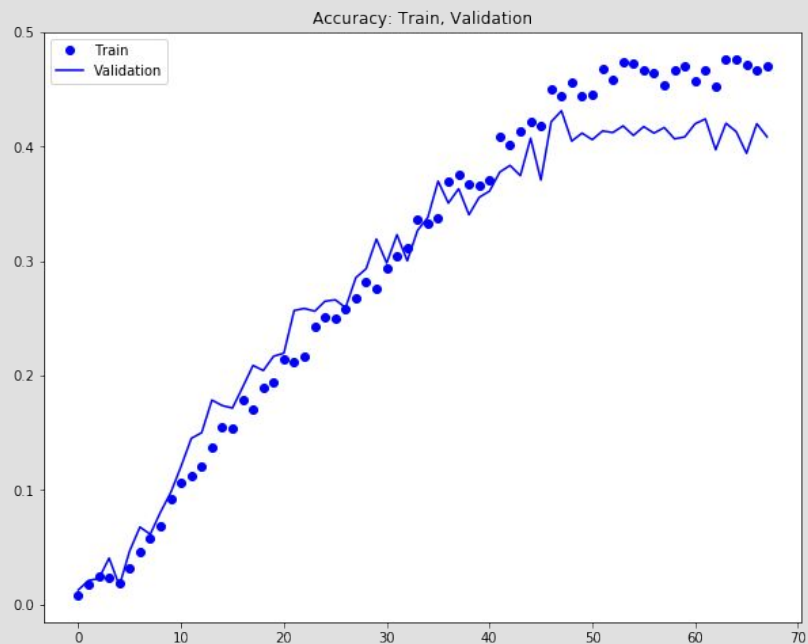
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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VGG19/Fine Tunning - Entrenamiento

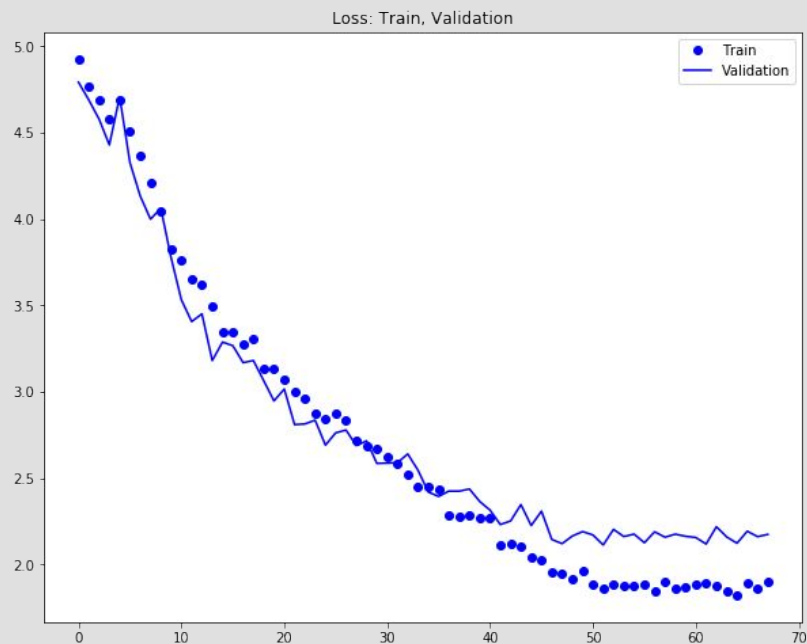
callbacks	<p>EarlyStopping</p> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 2000• validation_data = valid_generator• validation_steps = 50

VGG19/Fine Tuning - Resultados

Precisión



Pérdida



Modelo Pre Entrenado InceptionV3 / Fine Tunning

InceptionV3 / Fine Tunning - Arquitectura

Capa	Activación
conv_base (xception)	
Flatten	
Dense (512)	relu
Dropout (0.1)	
Dense (256)	relu
Dropout (0.5)	
Dense (120)	softmax

InceptionV3 / Fine Tuning - Compilación

loss	categorical_crossentropy
optimizer	<p>RAdam</p> <ul style="list-style-type: none">• total_steps = 5000• warmup_proportion = 0.1• min_lr = 1e-7
metrics	categorical_accuracy

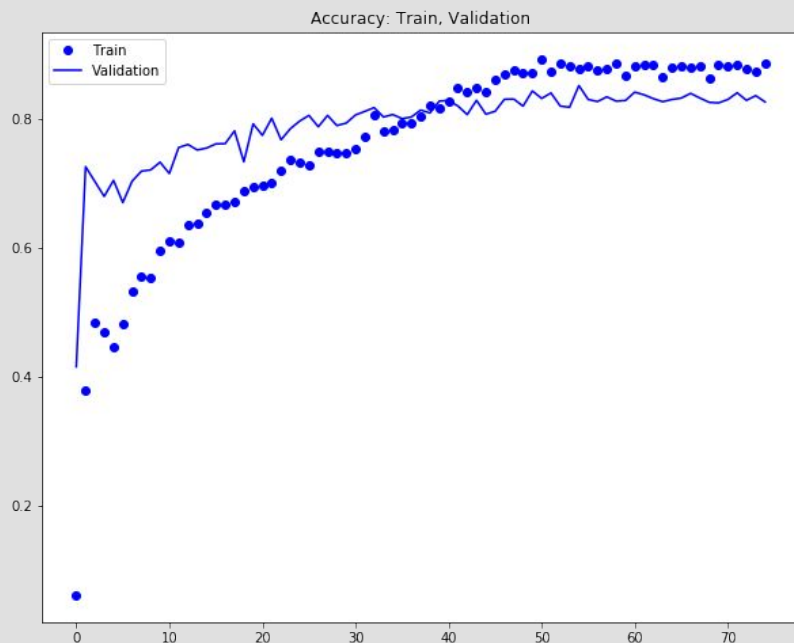
ImageDataGenerator (data augmentation)	<ul style="list-style-type: none">• rescale = 1./255• rotation_range = 40• width_shift_range = 0.2• height_shift_range = 0.2• shear_range = 0.2• zoom_range = 0.2• horizontal_flip = True
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InceptionV3 / Fine Tuning - Entrenamiento

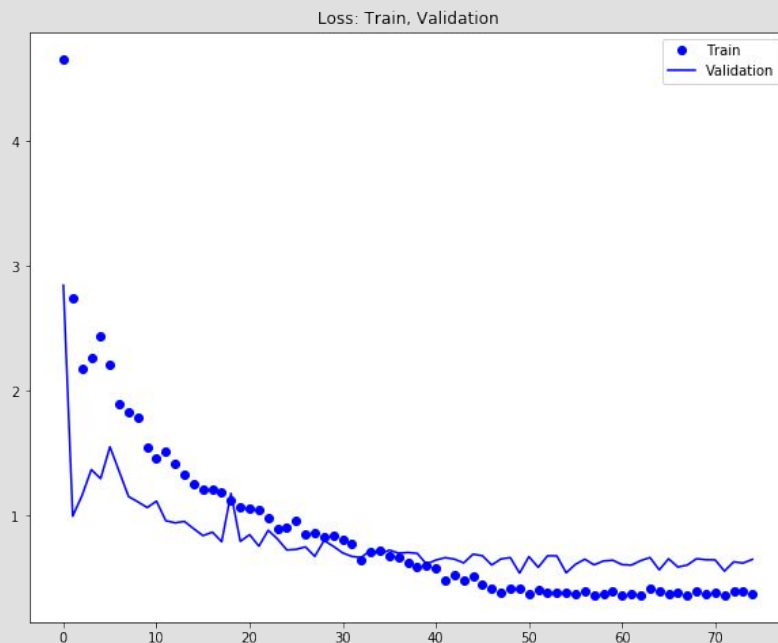
callbacks	<p>EarlyStopping</p> <ul style="list-style-type: none">• monitor = val_categorical_accuracy• min_delta = 0.001• patience = 20• restore_best_weights = True• mode = max
fit_generator	<ul style="list-style-type: none">• steps_per_epoch = 100• epochs = 2000• validation_data = valid_generator• validation_steps = 50

InceptionV3 / Fine Tuning - Resultados

Precisión



Pérdida



Conclusión

General Accuracy

Propio	0.18
InceptionResNetV2	0.90
VGG19	0.21
InceptionV3 - RAdam	0.84
InceptionV3	0.51
NASNetLarge	0.92
Xception	0.86
VGG19-FineTune	0.40
InceptionV3-FineTune	0.83