Array Iterators

Objective: To manipulate arrays iteratively.

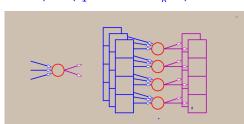
- Given vectors A: intⁿ and B: intⁿ, add them up to give vector
 C: intⁿ. Use map.
- Given array $A : int^n$, find sum of its elements. Use fold. We can also compute $\Sigma(A[i]^2)$ and use this to find standard deviation.
- Mapfold combines the map and the fold.

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 Example: Adding two 3-dimentional vectors a,b:real^3 to get c:real^3.

Method: Use \pm pointwise on every index putting the result in the output array.

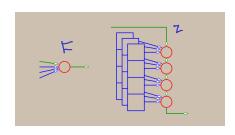
- c = map << 3>> (+) ([1,3,5],[4,3,-2]) gives [5,6,3]
- In general map<<n>>(F) $(x_1,...,x_m)$ returns $(y_1,...,y_k)$ Here $F:(t_1\times...\times t_m)\to (t'_1\times...\times t'_k)$. Also, $x_i:t_i^*$ n for $1\leq i\leq m$ and $y_j:t'_j^*$ n for $1\leq j\leq k$.
- Expression map<<n>>(F) has type $(t_1 \hat{n} \times ... \times t_m \hat{n}) \rightarrow (t'_1 \hat{n} \times ... \times t'_k \hat{n}).$



Here m=3 k=2 n=4

Fold

- Example: Finding sum of array of 4 elements a:int^4 to get c:int.
 Method: Use + pointwise on every index accumulating the sum.
- c = fold << 4>> (+) ([1,3,5,7],0) gives 16
- In general fold<<n>>(F) $(x_1, ..., x_m, z)$ returns y Here $F: (t_1 \times ... \times t_m \times t) \rightarrow \underline{t}$. Also, $x_i: t_i \hat{\ } n$ for $1 \leq i \leq m$ and z, y: t.
- Expression fold<<n>>(F) has type $(t_1 \hat{n} \times ... \times t_m \hat{n} \times t) \rightarrow (t)$.





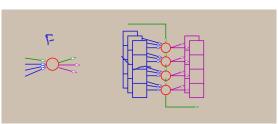
Example

Find dot product of two *n*-dimentional vectors.

```
node dotproduct<<n:int>>(a:real^n; b:real^n) returns (c:real)
var z:real^n
let
   z = map<<n>>(*)(a,b);
   c = fold<<n>>(+)(z,0);
```

Mapfold

- Example: Adding two 3-dimentional vectors a,b:real^3 AND getting their dot-product c:real^3; dot:real
- node F(x,y,accin:real) returns (z,accout:real)
 let z=x+y; accout = accin + (x*y); tel
- c = mapfold<<3>>(F) ([1,3,5],[4,3,-2],0) gives [5,6,3], #3
- In general mapfold<<n>>(F) $(x_1,...,x_m,init)$ returns $(y_1,...,y_k,acc)$ Here $F:(t_1\times...\times t_m\times t)\to t'_1\times...\times t'_k\times t$. Also, $x_i:t_i^n$ for $1\leq i\leq m$ and $y_j:t'_j^n$ for $1\leq j\leq k$ with init,acc:t.



Summary

- Features for writing large and complex programs.
- Records, Arrays, Array slices, Global types and constants, Parameterized nodes.
- Array iterators: map, fold and mapfold.