Section	Visual Description	Narration
1: Introduce the Problem our Bot will Address	Show a shoe store setting with a staff and customer. The customer tells the staff what shoes + sizes he/she wants and then the staff will go retrieve the shoes. Then show a customer 2 who tries to talk to staff but the staff is too busy retrieving shoes for customer 1 who has been waiting for a long time for his shoes.	Narrator: "Imagine you are at a shoe store and you want new to complement your summer beach bod. Has this ever happened to you?"  Queue the scene showing customers waiting on the staff.
	Optional: Show staff handling lots of boxes, dropping boxes, taking a long time to find the boxes, maybe finding that some shoes are not available.	
2: How Shuguru tackles the Problem	Show the same setting but now with the customer interacting with a tablet with the Shuguru frontend telling the robot which shoes he wants while the staff that was previously busy is interacting with customer 2 and providing recommendations on which shoe to get.	Narrator: "Well now with our revolutionary Shuguru robot, this could be you" Queue next scene Have some cheesy music
	Now show the robot getting the request for the shoes and then going to the shoe shelf to pick up the requested shoe, bringing the shoe to the customer and dropping it off at the designated place where the customer who ordered the shoe is sitting.	
3: Explanation of the Shuguru robot + Team Member Introductions	Show snapshots of robot doing different things: <ul> <li>a close up of the website and a user clicking on a specific shoe.</li> <li>The robot getting the command and responding to the order</li> <li>Picking up a specific shoe box</li> </ul>	Kousuke (Backend engineer), Jackson(Frontend engineer), Rio (Hardware planner), Artem(product enthusiast) Talking Heads to introduce team  Artem: "Our product Shuguru has revolutionized the shoe store industry by assisting staff in the retrieval of shoes thereby freeing and allowing staff to have more time
	<ul> <li>from shoe shelf</li> <li>Carrying the shoe box and making its way to the location where the customer is sitting</li> <li>Dropping the shoe gently on the flow.</li> </ul>	to interact with customers"  Jackson: "With the easy to use website, the customer has to specify a which shoe and also the station they are currently at. Shuguru keeps inventory of the available shoes and will only display shoes in stock on the website,

	Repeat until end of narration.	saving the staff from going to the storage to check which shoes are available" Kousuke: "Shuguru robot waits for request from customers and once it gets a request, it goes to the storage shelf and picks the specific shoe. Once it retrieves the shoe, it will move to the station that the customer is sitting at and will drop it off at that location" Rio: (Talk about shoe box picker)
4: Testimonials from Customers and Staff	Show the following:  Interview with potential shoe customers talking about how the robot allows for more interaction with the staff since staff are free + easy to use UI  Interview with potential shoe store worker about how the robot would ease the workload put on the staff and how it would allow for more valuable interaction with the customer	Display important quotes made by the customer on the screen  Display key quotes made by the staff on the screen
5: Wrap Up	<ul> <li>Another video shot of the shuguru robot moving around and delivering shoes blurred with the Shuguru logo on top.</li> <li>Talking head of Artem</li> </ul>	Narrator: "Preorder your Shuguru robot for your shoe store today and make your shoe store today a more interactive and fun place to shop!"  Product Evangelist: "By buying our product, you are guaranteed to a lifelong access to our continually improving service,

## Demo + Video Setup:

- Shoe box with 5 shoe boxes, 3 on top, 2 on bottom if shoe boxes hanging slightly from the edge so it is easier for the robot to grab the shoe boxes.
- Areas defined clearly by tape indicating Area 1 and Area 2 for the robot to go to
- Robot with the shoe gripper on.
- Reset the robot:
  - o Arm: neutral starting position
  - o Head: look at ar tags once we get to shelf
  - o Torso: Move to lowest possible position