MA-106 Linear Algebra

M.K. Keshari



Department of Mathematics Indian Institute of Technology Bombay Powai, Mumbai - 76

> 8th January, 2015 D1 - Lecture 3

Recall: we have seen matrix multiplication, elementary matrix and permutation matrix.

Let us review their action by 2×2 case.

$$\bullet \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & b \\ c+2a & d+2b \end{pmatrix} \\
(E_{21}(2): R_2 \mapsto R_2 + 2R_1).$$

$$\bullet \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} = \begin{pmatrix} a+2b & b \\ c+2d & d \end{pmatrix} \\
(E_{21}(2): C_1 \mapsto C_1 + 2C_2).$$

$$\bullet \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} c & d \\ a & b \end{pmatrix} \qquad (P_{12}: R_1 \leftrightarrow R_2).$$

$$\bullet \begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} b & d \\ a & c \end{pmatrix} \qquad (P_{12}: C_1 \leftrightarrow C_2).$$

$$E_{21}(2) E_{31}(3) E_{32}(4)$$

$$= E_{21}(2) E_{31}(3) (e_1 e_2 + 4e_3 e_3)$$

$$= E_{21}(2) (e_1 + 3e_3 e_2 + 4e_3 e_3)$$

$$= (e_1 + 3e_3 + 2e_2 e_2 + 4e_3 e_3)$$

$$= \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 4 & 1 \end{pmatrix}$$

There seems to be some doubts about this slide, so I am adding one more slide clarifying this. I should have done it by row operations only which is the next slide.

added after class

Recall $E_{ij}(a)A$ corresponds to row operation $A_i \mapsto A_i + aA_j$.

$$E_{21}(2) E_{31}(3) E_{32}(4) = E_{21}(2) E_{31}(3) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 4 & 1 \end{pmatrix}$$

$$= E_{21}(2) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 3 & 4 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 4 & 1 \end{pmatrix}.$$

$$E_{32}(4) E_{31}(3) E_{21}(2) = E_{32}(4) E_{31}(3) \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$= E_{32}(4) \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 3 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 11 & 4 & 1 \end{pmatrix}$$

Triangular Factors and Row Exchange

Consider
$$\begin{pmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{pmatrix} \begin{pmatrix} u \\ v \\ w \end{pmatrix} = \begin{pmatrix} 5 \\ -2 \\ 9 \end{pmatrix} \quad (Ax = b)$$

In Gauss Elimination, the row operations

$$R_2 \mapsto R_2 - 2R_1, \quad R_3 \mapsto R_3 + R_1, \quad R_3 \mapsto R_3 + R_2$$

changes A to an upper triangular matrix.

$$U := E_{32}(1) E_{31}(1) E_{21}(-2) A =$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} A = \begin{pmatrix} 2 & 1 & 1 \\ 0 & -8 & -2 \\ 0 & 0 & 1 \end{pmatrix},$$

$$b' = E_{32}(1) \ E_{31}(1) \ E_{21}(-2) \ b = \begin{pmatrix} 5 \\ -12 \\ 2 \end{pmatrix},$$

Triangular . . . continued

Previous system Ax = b is equivalent to

Ux = b'.

Example: The row operations

$$R_2 \mapsto R_2 - 2R_1, \quad R_2 \mapsto R_2 + 2R_1$$

leaves the matrix unchanged. Hence they are inverse to each other. In matrix terms,

$$E_{21}(-2) \ E_{21}(2) = \begin{pmatrix} 1 & 0 & 0 \\ -2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Therefore the inverse of $E_{ij}(a)$ is $E_{ij}(-a)$.

Remark: In the previous example,

$$E_{32}(1) E_{31}(1) E_{21}(-2) A = U$$

Hence

$$A = E_{21}(2) E_{31}(-1) E_{32}(-1) U$$

Triangular Factorization

Product of lower triangular matrices is lower triangular. For example

$$L := E_{21}(2) E_{31}(-1) E_{32}(-1) =$$

$$\begin{pmatrix} 1 & 0 & 0 \\ 2 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -1 & 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 \\ \mathbf{2} & 1 & 0 \\ -\mathbf{1} & -\mathbf{1} & 1 \end{pmatrix}$$

- \bullet In the Gaussian elimination of A, if no exchanges of rows are required, then $\overline{A=L\,U}$, where
- ullet L is a lower triangular matrix with diagonal entries 1 and below the diagonals are multipliers (2,-1,-1) in above example)
- ullet U is an upper triangular matrix, which is got after forward elimination, with diagonal entries as pivots.

Example:
$$A = \begin{pmatrix} 0 & 2 \\ 3 & 4 \end{pmatrix}$$
.

A can not be factored as LU (check directly), since the Gaussian elimination of A needs a row exchange.

$$P_{12} A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 2 \\ 3 & 4 \end{pmatrix} = \begin{pmatrix} 3 & 4 \\ 0 & 2 \end{pmatrix} = I U$$

- ullet If A is $n \times n$ non-singular, then there is a matrix P which is a product of permutation matrices (needed to take care of row exchanges in elimination process) such that $\overline{PA=LU}$, where L and U are defined earlier.
- What happens when A is $n \times m$ (rectangular). We will come to this case next week.

added after class

"If A is non-singular then PA = LU, where P is a product of permutation matrices".

To see this, you start with Gaussian elimination on A. If you do not need row exchange then A=LU.

Suppose after eliminating x, (2,2) entry is zero. Then we need to interchange R_2 with R_3 (if (3,2) entry is non-zero).

Now if we replace A by $P_{23}A$ and then start my elimination, then we do not need to interchange R_2 with R_3 . for second pivot.

Proceed. If we need to interchange say R_3 with R_4 , then you start your Gaussian elimination with $P_{34}P_{23}A$. Now you do not need to interchange R_3 with R_3 , and so on.

Inverse of a Matrix

Let A be $n \times n$ matrix. The inverse of A is a $n \times n$ matrix B (denoted by A^{-1}) such that AB = I and BA = I.

- A^{-1} is unique, if it exists. To see this, if B and C are inverse of A, then AB=I and CA=I. Hence B=I.B=(CA).B=C(AB)=C.I=C.
- If A is invertible (i.e. A^{-1} exist), then system Ax = b has a unique solution, namely $x = A^{-1}b$.
- Ax = 0 has a non-zero solution $\implies A$ is not invertible. Note x = 0 is also a solution of Ax = 0, hence solution is not unique.
- ullet A is invertible if and only if A has n pivots.
- ullet An upper triangular matrix A is invertible if and only if its diagonal entries are non-zero.

ullet Assume A and B are invertible. Is AB invertible? Yes

$$(AB)^{-1} = B^{-1}A^{-1}.$$

• Assume A, B are invertible. Is A+B invertible? No (in general).

Example: I + (-I) = (0).

 $\bullet \mbox{ Compute inverse of invertible matrix } A = \begin{pmatrix} 2 & 1 & 1 \\ 4 & -6 & 0 \\ -2 & 7 & 2 \end{pmatrix}.$

If $A^{-1}=\begin{pmatrix} x_1 & x_2 & x_3 \end{pmatrix}$, where x_i is the *i*-th column of A^{-1} , then $AA^{-1}=I$ gives three systems of linear equations

$$Ax_1 = e_1, \quad Ax_2 = e_2, \quad Ax_3 = e_3$$

where e_i is the *i*-th column of I. Since the coefficient matrix A is same, we can solve them simultaneously as follows: