

MA-106 Linear Algebra

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17th February, 2015
D1 - Lecture 19

Recall:

- A square matrix A is diagonalizable if and only if A has a basis consisting of eigenvectors.
- For an invertible matrix S , $S^{-1}AS$ is a diagonal matrix if and only columns of S are eigenvectors of A .
- If x_1, \dots, x_r are eigenvectors of A associated to distinct eigenvalues $\lambda_1, \dots, \lambda_r$, then x_1, \dots, x_r are linearly independent.
- If A has n distinct eigenvalues, then A is diagonalizable.
- A triangular matrix need not be diagonalizable.
- Assume A and B are diagonalizable . Then A and B have same set of eigenvectors if and only if $AB = BA$.

Eigenvalues of A^k

- If $Ax = \lambda x$, then $A^2x = A(Ax) = A(\lambda x) = \lambda(Ax) = \lambda^2x$.

Similarly $A^kx = \lambda^kx$ for any $k \geq 0$.

Thus if λ is an eigenvalue of A with associated eigenvector x , then

λ^k is an eigenvalue for A^k , with the same associated eigenvector x

for $k \geq 0$. If A is invertible, then $\lambda \neq 0$. Hence, the same also holds for $k < 0$ since $A^{-1}x = \lambda^{-1}x$.

- Assume A is diagonalizable. Then $S^{-1}AS = \Lambda$ is diagonal where columns of S are eigenvectors of A .

Now $(S^{-1}AS)(S^{-1}AS) = S^{-1}A^2S = \Lambda^2$, which is diagonal. Hence eigenvectors of A^2 are same as eigenvectors of A . Similarly

$(S^{-1}AS)^k = S^{-1}A^kS = \Lambda^k$. For $k \geq 0$, A^k is diagonalizable

and the same also holds for $k < 0$ if A is invertible.

Application: Fibonacci Numbers

Let $F_0 = 0$, $F_1 = 1$ and $F_k = F_{k-1} + F_{k-2}$ for $k \geq 2$ define the Fibonacci sequence. What is the k th term?

$$\text{If } u_k = \begin{bmatrix} F_{k+1} \\ F_k \end{bmatrix}, \text{ then } \begin{bmatrix} F_{k+1} \\ F_k \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} F_k \\ F_{k-1} \end{bmatrix}, \text{ i.e.,}$$

$$u_k = Au_{k-1} \text{ for } k \geq 1, \text{ where } A = \begin{bmatrix} 1 & 1 \\ 1 & 0 \end{bmatrix} \Rightarrow u_k = A^k u_0 \text{ for } k \geq 1.$$

Characteristic polynomial of A : $(1 - \lambda)(-\lambda) - 1 = \lambda^2 - \lambda - 1$.

$$\text{Eigenvalues: } \lambda_1 = \frac{1 + \sqrt{5}}{2}, \lambda_2 = \frac{1 - \sqrt{5}}{2}.$$

The eigenvalues are distinct \Rightarrow the associated eigenvectors x_1 and x_2 are linearly independent $\Rightarrow \{x_1, x_2\}$ is a basis for \mathbb{R}^2 .

$$\begin{aligned} \text{Write } u_0 &= c_1 x_1 + c_2 x_2. \text{ Then } u_k = A^k u_0 = A^k (c_1 x_1 + c_2 x_2) \\ &= c_1 A^k x_1 + c_2 A^k x_2 = c_1 \left(\frac{1 + \sqrt{5}}{2} \right)^k x_1 + c_2 \left(\frac{1 - \sqrt{5}}{2} \right)^k x_2. \end{aligned}$$

Q: Find x_1 , x_2 , c_1 and c_2 and get the exact formula for F_k .

An Application: Steady State

Suppose we have a system where the current state depends linearly on the previous one, i.e., $u_k = Au_{k-1}$. Then observe that $u_k = A^k u_0$.

The **steady state** of the system is $u_\infty = \lim_{k \rightarrow \infty} (u_k)$.

Q. How do we find the steady state?

- If u_0 is an eigenvector of A associated to λ , then $u_k = \lambda^k u_0$.
- If x_1, \dots, x_r are eigenvectors of A associated to $\lambda_1, \dots, \lambda_r$ resp. and $u_0 \in \text{Span}\{x_1, \dots, x_r\}$, i.e., $u_0 = c_1 x_1 + \dots + c_r x_r$ for scalars c_1, \dots, c_r , then
$$u_k = A^k u_0 = c_1 A^k x_1 + \dots + c_r A^k x_r = c_1 \lambda_1^k x_1 + \dots + c_r \lambda_r^k x_r.$$
- If A is diagonalizable, then there is a basis of \mathbb{R}^n consisting of eigenvectors of A . Hence, the previous remark holds for all $u_0 \in \mathbb{R}^n$.
- Let A be diagonalizable and u_k represent population of some species. Under what conditions will there be a population explosion? What conditions will force the population to become extinct? When does the population stabilise to a non-zero value?

Hint: Answer depends on eigenvalues λ_i of A .

An Application: Predator - Prey Model

Let us study the dynamics of spotted owl and wood rat population. Assume owls diet are mostly rats and likewise rats are mostly preyed by owls. Let O_k and R_k denote population of owls and rats in month k . Let us model the population dynamics as follows

$$O_{k+1} = 0.5O_k + 0.4R_k$$

$$R_{k+1} = -pO_k + 1.1R_k$$

Here pO_k is the no. of rats consumed per month per owl.

1.1 is growth rate of rats in the absence of owls, (10% increase monthly)

$0.5O_k$ means 50% decrease in owls population if there are no rats.

$0.4R_k$ means growth rate of owl population if rats are present.

Write the system as $u_{k+1} = Au_k$, where $u_k = \begin{pmatrix} O_k \\ R_k \end{pmatrix}$, $A = \begin{pmatrix} 0.5 & 0.4 \\ -p & 1.1 \end{pmatrix}$.

Assume $u_0 = (100 \ 100)^T$ and $p = 0.2$. Then $u_k = A^k u_0$.

Find whether the populations grow, decline or approach a steady state.

Complex Eigenvalues

Ex: Rotation by 90° , $K = \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$, $|K - \lambda I| = \lambda^2 + 1$.

It has no eigenvector, since rotation by 90° changes the direction.

K has eigenvalues, but they are **not real**. They are imaginary numbers i and $-i$, where $i^2 = -1$.

The associated eigenvectors are also not real. Let us compute them.

$$(K - iI)x_1 = \begin{bmatrix} -i & -1 \\ 1 & -i \end{bmatrix} x_1 = 0 \Rightarrow x_1 = \begin{bmatrix} 1 \\ -i \end{bmatrix},$$

$$(K + iI)x_2 = \begin{bmatrix} i & -1 \\ 1 & i \end{bmatrix} x_2 = 0 \Rightarrow x_2 = \begin{bmatrix} 1 \\ i \end{bmatrix}.$$

The eigenvalues are distinct (though imaginary), hence eigenvectors are linearly independent.

$$\text{If } S = \begin{bmatrix} x_1 & x_2 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ -i & i \end{bmatrix}, \text{ then } S^{-1}KS = \begin{bmatrix} i & 0 \\ 0 & -i \end{bmatrix}.$$

Complex Numbers

Conclusion: We need complex numbers \mathbb{C} even if we are working with real matrices. Over \mathbb{C} , an $n \times n$ matrix A always has n eigenvalues.

Reason: Fundamental theorem of Algebra

Every polynomial over \mathbb{C} of degree n has n roots in \mathbb{C} .

For a complex number $x = a + ib$, its conjugate is $\bar{x} = a - ib$.

Note that $\bar{x} \cdot x = a^2 + b^2$.

If $x = (x_1, \dots, x_n)$, $y = (y_1, \dots, y_n) \in \mathbb{C}^n$ are complex vectors,

define $x \cdot y = \bar{x}_1 y_1 + \dots + \bar{x}_n y_n \in \mathbb{C}$. Then

- $x \cdot x = |x_1|^2 + \dots + |x_n|^2 \in \mathbb{R}$ and is ≥ 0 .
- $x \cdot x = 0 \Leftrightarrow x = 0$.
- For $c \in \mathbb{C}$, $x \cdot cx = \bar{x}_1 c x_1 + \dots + \bar{x}_n c x_n = (x \cdot x)c$.
- Observe $cx \cdot x = \bar{c}(x \cdot x)$

(In fact, this defines a complex inner product on \mathbb{C}^n).

Real Symmetric $n \times n$ Matrix A :

- For every $x \in \mathbb{C}^n$, $x \cdot Ax \in \mathbb{R}$. Let us do it for $n = 2$.

$$\text{If } x = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \in \mathbb{C}^2, A = \begin{bmatrix} a & b \\ b & d \end{bmatrix}, \text{ then } Ax = \begin{pmatrix} az_1 + bz_2 \\ bz_1 + dz_2 \end{pmatrix}.$$

$$\begin{aligned} \text{Now } x \cdot Ax &= \bar{z}_1(az_1 + bz_2) + \bar{z}_2(bz_1 + dz_2) \\ &= (a|z_1|^2 + d|z_2|^2) + b(\bar{z}_1z_2 + \bar{z}_2z_1) \in \mathbb{R}. \end{aligned}$$

- Every eigenvalue of A is real.

Let $\lambda \in \mathbb{C}$ be an eigenvalue of A , with associated eigenvector $x \in \mathbb{C}^n$.
Then $Ax = \lambda x \Rightarrow x \cdot Ax = x \cdot \lambda x = (x \cdot x)\lambda$.

Since $x \neq 0 \Rightarrow x \cdot x$ is a positive real number $\Rightarrow \lambda = \frac{x \cdot Ax}{x \cdot x} \in \mathbb{R}$.

- A has real eigenvector associated to (real) eigenvalue λ .

This follows from the fact that $\dim N(A - \lambda I) \geq 1$.

We can also find it from complex eigenvector $x \in \mathbb{C}^n$.

Write $x = u + iv$, where $u, v \in \mathbb{R}^n$. Then $Ax = \lambda x \Rightarrow Au + iAv = \lambda(u + iv) \Rightarrow Au = \lambda u$ and $Av = \lambda v$.

Therefore u and v are eigenvector of A associated to λ .

Real Symmetric $n \times n$ Matrix A :

- If $\lambda_1 \neq \lambda_2$ are distinct eigenvalues of A with eigenvectors $x_1, x_2 \in \mathbb{R}^n$, then x_1 and x_2 are orthogonal, i.e., $x_1^T x_2 = 0$.

$$\begin{aligned}\text{Now } \lambda_1(x_1^T x_2) &= (\lambda_1 x_1)^T x_2 = (Ax_1)^T x_2 = (x_1^T A^T) x_2 \\ &= x_1^T (Ax_2) = x_1^T (\lambda_2 x_2) = \lambda_2 (x_1^T x_2).\end{aligned}$$

Since $\lambda_1 \neq \lambda_2$, we get $x_1^T x_2 = 0$.

- If A has n distinct eigenvalues, then there is an orthogonal matrix Q and a diagonal matrix Λ such that $A = Q\Lambda Q^T$.

A has n distinct eigenvalues $\Rightarrow A$ is diagonalizable $\Rightarrow S^{-1}AS = \Lambda$, where S is (real) invertible and Λ is diagonal.

If $S = [x_1 \ \dots \ x_n]$ with $x_i \in \mathbb{R}^n$, then x_i 's are eigenvectors of A .

$$\text{Since } x_i^T x_j = 0 \text{ for } i \neq j, \quad Q = \begin{bmatrix} \frac{x_1}{\|x_1\|} & \dots & \frac{x_n}{\|x_n\|} \end{bmatrix}$$

is an orthogonal matrix, i.e., $Q^{-1} = Q^T$.

Note $Q = SD$, where D is a diagonal matrix with diagonal entries $1/\|x_1\|, \dots, 1/\|x_n\|$.

$$\text{Therefore } Q^{-1}AQ = D^{-1}S^{-1}ASD = D^{-1}\Lambda D = \Lambda \Rightarrow \boxed{A = Q\Lambda Q^T}.$$

Spectral Theorem for a Real Symmetric Matrix

Theorem Every real symmetric matrix A can be diagonalised.

Further there is an orthogonal matrix Q and a diagonal matrix Λ such that

$$A = Q\Lambda Q^T.$$

Once you know that A can be diagonalised, $A = Q\Lambda Q^T$ follows from the previous slide + Gram-Schmidt process applied to each eigenspace of A .
(Without Proof)

Ex: Let $A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$. Then $A - \lambda I = \begin{bmatrix} 1 - \lambda & 0 & 0 \\ 0 & -\lambda & 1 \\ 0 & 1 & -\lambda \end{bmatrix}$ and

$\det(A - \lambda I) = (1 - \lambda)(\lambda^2 - 1)$. Eigenvalues: $\lambda_1 = 1, \lambda_2 = 1, \lambda_3 = -1$.
Eigenvectors: $x_1 = (1, 0, 0)^T$, $x_2 = (0, 1, 1)^T$ and $x_3 = (0, 1, -1)^T$. Observe $x_1^T x_3 = 0 = x_2^T x_3$.

Gram-Schmidt gives an orthonormal basis $\{u_1, u_2\}$ for $N(A - I)$, and let $u_3 = x_3 / \|x_3\|$. Then $Q = [u_1 \ u_2 \ u_3]$ is an orthogonal matrix.

Further, $A = Q\Lambda Q^T$, where Λ is a diagonal matrix with entries 1, 1, -1 on the diagonal.

For extra reading: Sketch of proof of Spectral Theorem

Since A is real symmetric, it has a real eigenvalue, say λ_1 . Let x_1 be a real eigenvector of A associated to λ_1 .

Let W_1 be the orthogonal complement of $\text{Span}(x_1)$. Then $A : \mathbb{R}^n \rightarrow \mathbb{R}^n$ takes W_1 to W_1 , i.e. $A|_{W_1} : W_1 \rightarrow W_1$. (Needs checking)

Since W_1 is $n - 1$ -dimensional, the matrix associated to $A|_{W_1}$ with respect to some basis B of W_1 , i.e. $[A|_{W_1}]_B^B$, is square of size $n - 1$ and symmetric.

Using induction on n , we get a basis x_2, \dots, x_n of W_1 consisting of eigenvectors of $A|_{W_1}$. Then x_1, \dots, x_n is a basis of \mathbb{R}^n consisting of eigenvectors of A . This proves that A is diagonalizable.

Let $\lambda_1, \dots, \lambda_r$ be distinct eigenvalues of A with U_1, \dots, U_r as their eigenspaces. Then U_i is orthogonal to U_j for $i \neq j$, since their elements are eigenvectors corresponding to different eigenvalues.

$\dim(U_i)$ = the number of times λ_i is repeating as eigenvalue of A .

Gram-Schmidt gives an orthonormal basis B_i of U_i .

For extra reading

Let $B = \cup_{i=1}^r B_i = \{y_1, \dots, y_n\}$ be an orthonormal basis of \mathbb{R}^n . Each y_i is an eigenvector of A .

Let $Q = [y_1 \ y_2 \ \dots \ y_n]$ be an orthogonal matrix. Then $Q^{-1}AQ = \Lambda$ will be diagonal matrix. Hence $A = Q\Lambda Q^{-1}$, and $Q^{-1} = Q^T$. This completes the proof. \square

- Let A be symmetric, and $A = Q\Lambda Q^T$.

If $Q = [x_1 \ \dots \ x_n]$ then

$$\begin{aligned} A &= Q\Lambda Q^T = [x_1 \ \dots \ x_n] \begin{bmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{bmatrix} [x_1 \ \dots \ x_n]^T \\ &= [\lambda_1 x_1 \ \dots \ \lambda_n x_n] [x_1 \ \dots \ x_n]^T = \lambda_1 x_1 x_1^T + \dots + \lambda_n x_n x_n^T. \end{aligned}$$

Each matrix $\lambda_i x_i x_i^T$ is a projection matrix (check!) projecting a vector on the line spanned by x_i . Hence every symmetric matrix

A can be decomposed as sum of n projection matrices.