

# Minimum Spanning Tree

Abhiram Ranade

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Suffices to look for a minimum weight spanning tree..

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**Fact:** (contd) Let  $e'$  be any edge in  $C$ . Then  $T \cup \{e\} - \{e'\}$  is also a spanning tree.



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Can we discover the remaining edges by recursing, i.e. is there optimal substructure?

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$G'$  : obtained by *contracting* a minimum weight edge.

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If  $G' = G/e$ , we will use  $G' * e$  to mean  $G$ .

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**Proof:** Exercise.

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$T/(u, v)$  spans  $G/(u, v)$ , and  $|T/(u, v)| = |T| - 1 = 1$  less than the number of nodes in  $G/(u, v)$ .

**Lemma:** Let  $T'$  be a spanning tree for  $G' = G/(u, v)$ . Then

$T' * (u, v)$  is a spanning tree of  $G$ .

**Proof:** Exercise.

$T' * (u, v)$  = tree induced in  $G$  by the edges of  $T'$  and  $(u, v)$ .

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Classic "union-find" data structure.



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  - ▶ Before considering an edge  $(u, v)$  for contraction, we check that  $\text{Find}(u) \neq \text{Find}(v)$ , i.e. that it is not a self-loop.

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Thus total time spent on vertex  $i$  is  $O(\log |S[i]|)$ .

# Algorithm time analysis



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Algorithm: (Kruskal)

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Rule 3: Minimum weight edge crossing any cut of the graph

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Representing  $T$ :  $v$  = root  $\Rightarrow T(v) = v$ . Else  $T(v)$  = parent of  $v$ .

# Prim's algorithm details

1.  $Q$  = empty min priority queue.
2.  $s$  = any vertex in  $G$ .  $d(s) = 0$ .
3. For all vertices  $v \neq s$ ,  $d(v) = \infty$ .
4. Insert each  $v$  into  $Q$  with key  $d(v)$ .
5. while  $Q$  is not empty
  6.  $u$  = delete-min from  $Q$ .
  7. for each neighbour  $v$  of  $u$ :
    8. if  $d(v) > w(u, v)$ ,
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$m$  decrease key operations,  $n - 1$  delete-min. Time  $O(m \log n)$ .

## Remarks

"Fibonacci heap" can be used to reduce the time to  $O(m + n \log n)$  instead of the present  $O(m \log n)$ .

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**Output:** Partition of vertex set into  $V_1, \dots, V_k$  so as to maximize "spacing" defined as:

$$\text{spacing} = \min_{i \neq j} d(V_i, V_j)$$

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Alternative: Find MST somehow and delete  $k - 1$  max weight edges.

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