

CS310 Automata Theory – 2016-2017

Nutan Limaye

Indian Institute of Technology, Bombay

nutan@cse.iitb.ac.in

Lecture 24: Turing machines, computability

March 16, 2017

Last three classes

Introduction to Turing machines

What are Turing machines? Informal and formal definitions and examples.

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Turing recognizable and Turing decidable languages.

k -tape TMs equivalent to 1-tape TMs.

Existence of unrecognizable languages.

Proof that A_{TM} is recognizable but not decidable.

Variants of Turing machines

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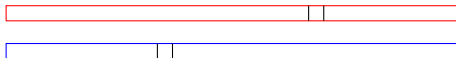


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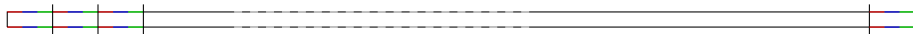


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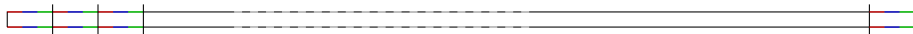


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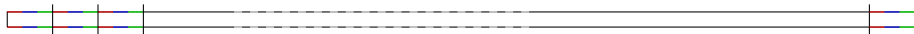
Let $M = (Q, \Sigma, \Gamma, \delta, q_0, q_{acc}, q_{rej},)$ be the k -tape Turing machine.

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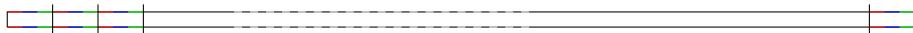
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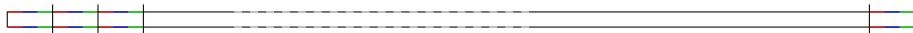
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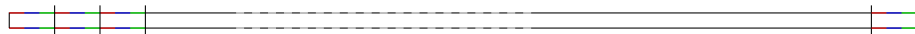
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$\bar{\Gamma}$ symbols used to denote tape head positions.

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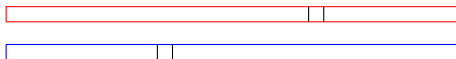


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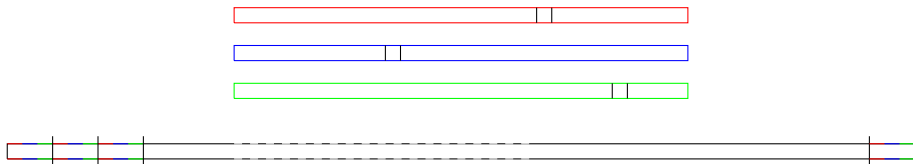


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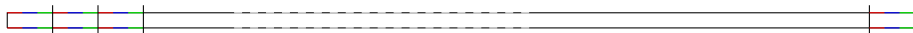


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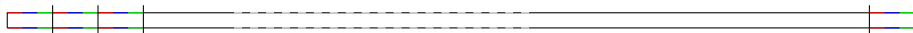
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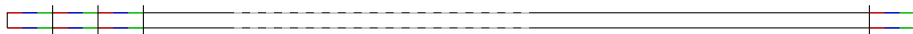
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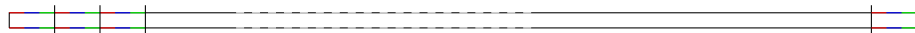
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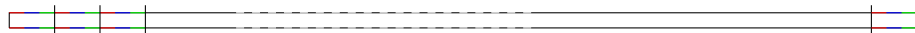
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A language L is Turing decidable if and only if L and \bar{L} are both Turing recognizable.

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Else M_2 will reach the accepting configuraion. In that case, reject.

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Is A_{TM} decidable?

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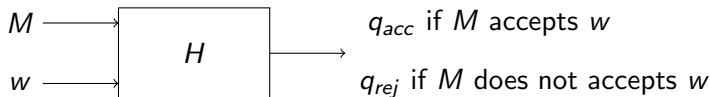
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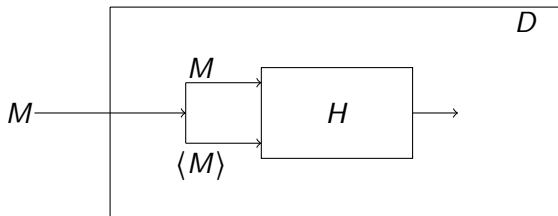
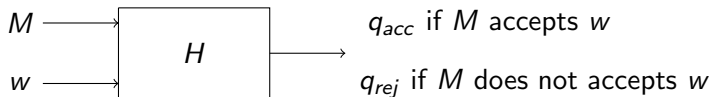


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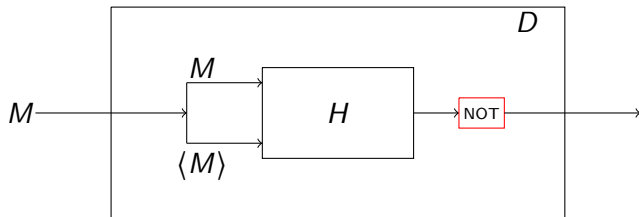
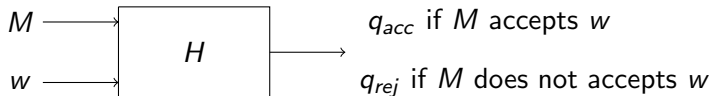


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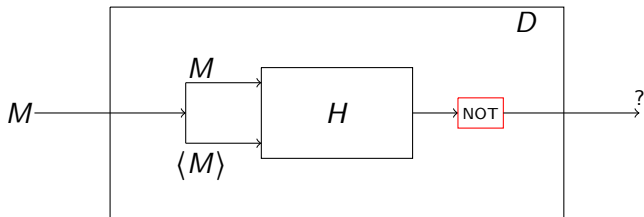
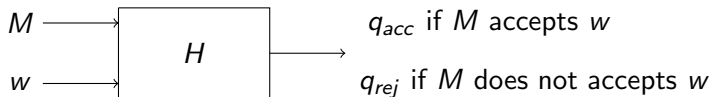


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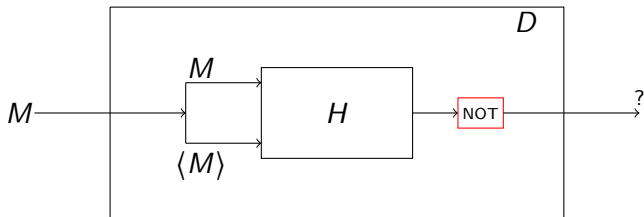
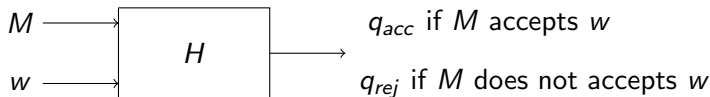


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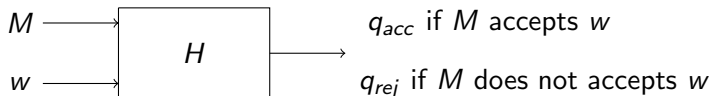


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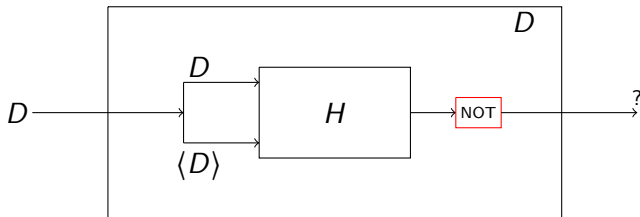
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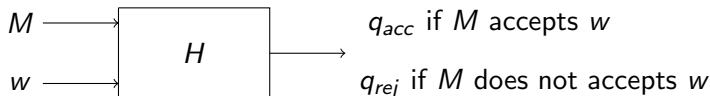


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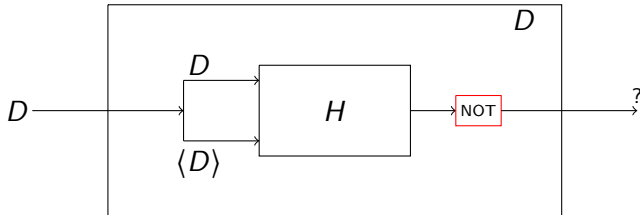
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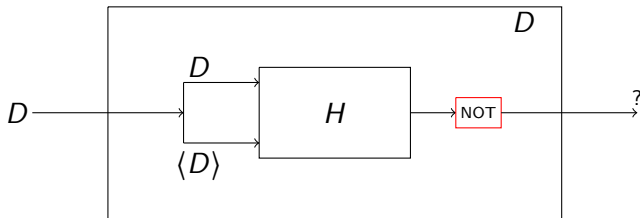
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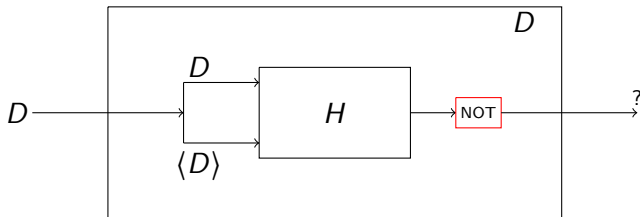
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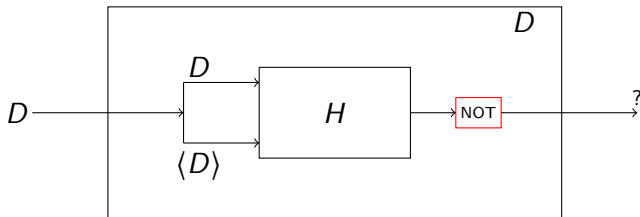


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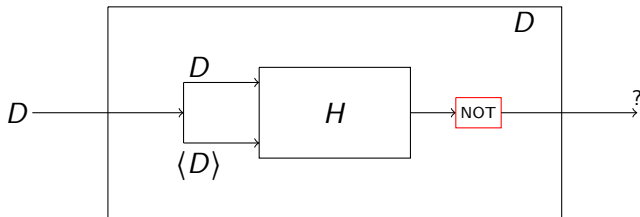


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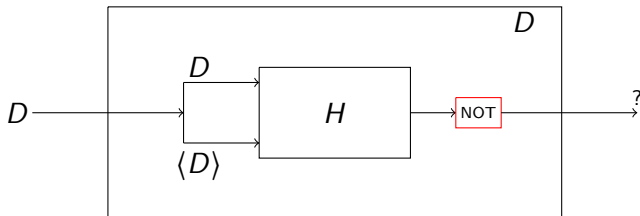
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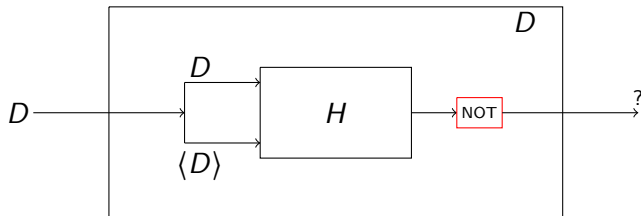
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$A_{\text{DFA}} = \{ \langle M, w \rangle \mid \text{DFA } M \text{ accepts } w \}$ is decidable.

Similarly, $A_{\text{PDA}} = \{ \langle M, w \rangle \mid \text{PDA } M \text{ accepts } w \}$ is also decidable.

Diagonalization inside the proof

Behaviour of the machines.

	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$
M_1	✓		✓	✓...

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M_3	×	×	✓	... ×	✓
⋮					
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Diagonalization inside the proof

Behaviour of H .

	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$
M_1	✓	×	✓	✓
M_2	✓	×	×	×	... ✓ ... × ✓ ...
M_3	×	×	✓	... ×	✓
⋮					
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Diagonalization inside the proof

Behaviour of H .

	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$
M_1	✓	×	✓	✓
M_2	✓	×	×	×	... ✓ ... × ✓ ...
M_3	×	×	✓	... ×	✓
⋮					
⋮					

Diagonalization inside the proof

Behaviour of D .

	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$
M_1	✓ ✓ ✓ ×	×	✓	✓
M_2	✓	× ✓	×	×	... ✓ ... × ✓ ...
M_3	×	×	✓ ✓ ✓ ×	... ×	✓
⋮					
⋮					

Diagonalization inside the proof

Behaviour of D on itself.

	$\langle M_1 \rangle$	$\langle M_2 \rangle$	$\langle M_3 \rangle$	$\dots \langle D \rangle \dots$	\dots
M_1	✓ ×	×	✓	✓ ...	\dots
M_2	✓	× ✓	×	×	✓ ... × ✓ ...
M_3	×	×	✓ ×	... ×	✓ \dots
\vdots					
\vdots					
D				... ? ...	\dots

Other undecidable problems and reducibility

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\mathcal{H} decides Halt if and only if \mathcal{A} decides A_{TM} .

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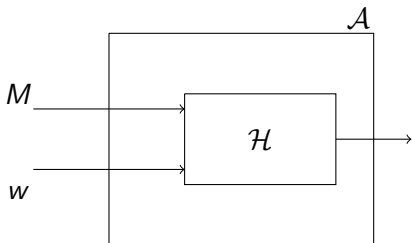
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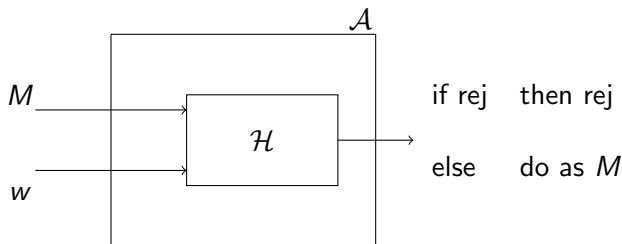


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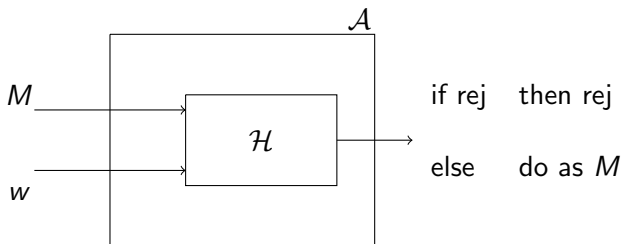


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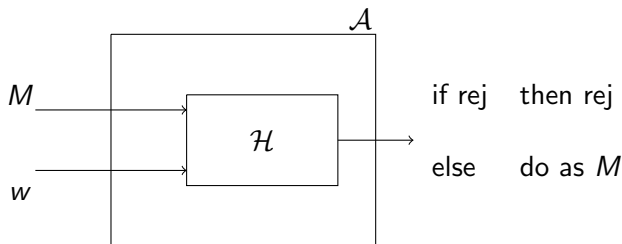
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Another way to describe the same proof.



If Halt is decidable then \mathcal{A} decides A_{TM} , which is a contradiction.