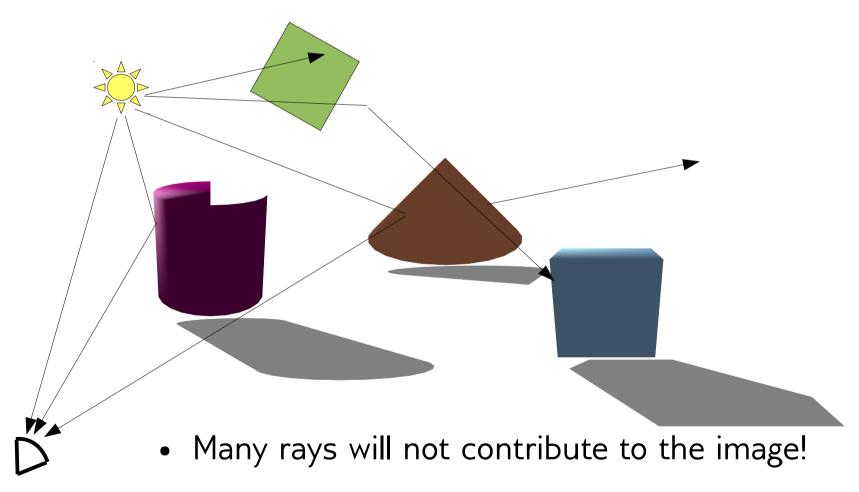
CS475/CS675 Computer Graphics

Rendering

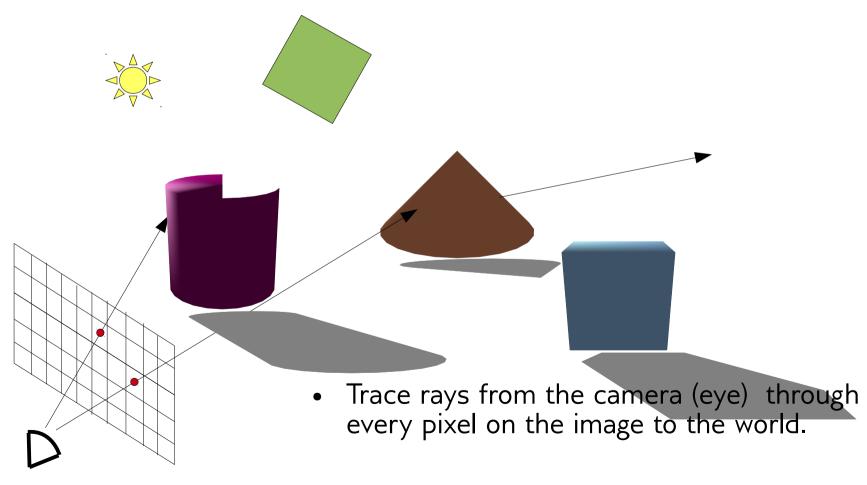
- Drawing images on the computer screen.
- We have seen one rendering method already.
- ssues:
 - Visibility
 - What parts of a scene are visible?
 - Clipping
 - Culling (Backface and Occlusion)
 - Illumination
 - Reflection, Refraction, Shadows, etc.

 Tracing the rays of light to model the interaction of light with objects.



CS 475/CS 675: Lecture 17

Inverse or Backward Ray Tracing

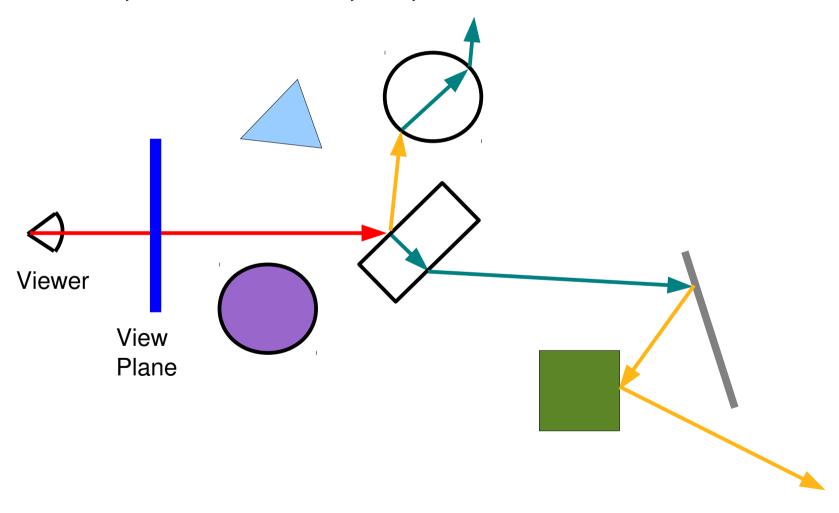


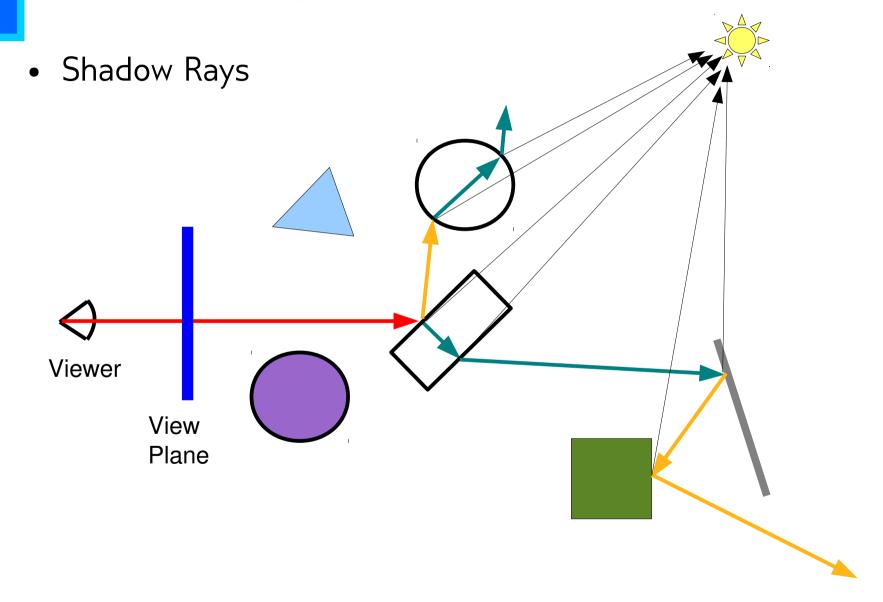
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- Basic Idea
 - For every pixel in the image
 - Shoot a ray
 - Find closest intersection with object
 - Find normal at the point of intersection
 - Compute illumination at point of intersection
 - Assign pixel color

• Primary and Secondary Rays

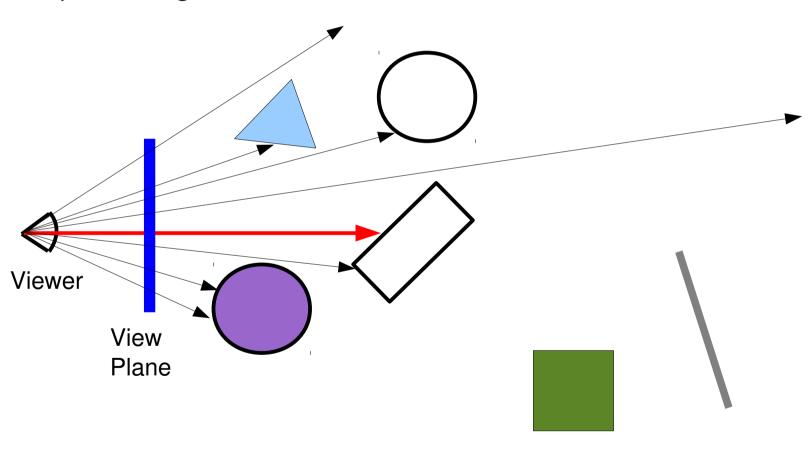






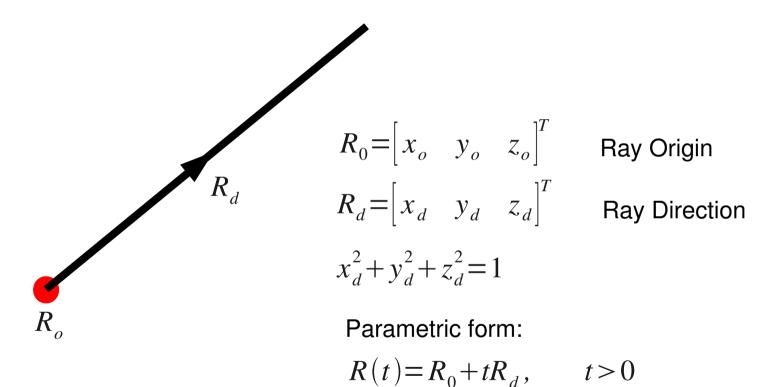
• Ray Casting



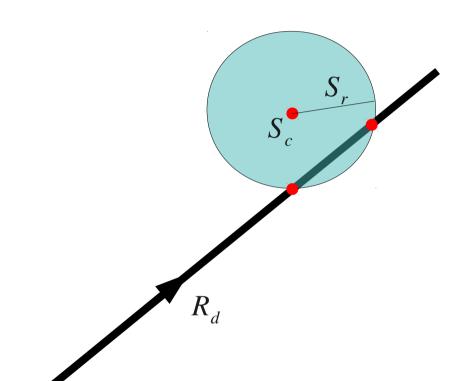


- Visibility
 - Ray Object Intersections
- Illumination
 - Pixel Colour determination (shading)

Ray Representation



• Ray - Sphere Intersection



$$S_c = \begin{bmatrix} x_c & y_c & z_c \end{bmatrix}^T$$
 Center S_r Radius $\begin{bmatrix} x_s & y_s & z_s \end{bmatrix}^T$ Surface Point

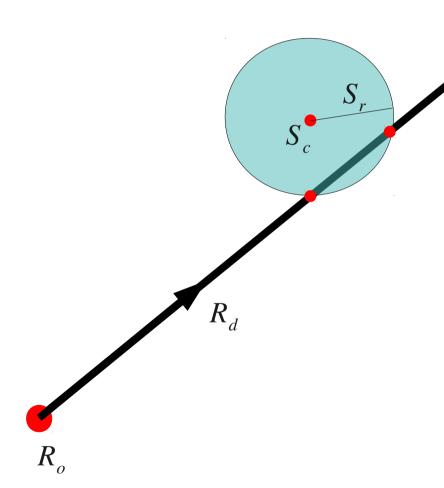
Implicit form of the sphere:

$$(x_s - x_c)^2 + (y_s - y_c)^2 + (z_s - z_c)^2 = S_r^2$$

To solve for the equation we substitute:

$$(x_0 + t x_d - x_c)^2 + (y_0 + t y_d - y_c)^2 + (z_0 + t z_d - z_c)^2 = S_r^2$$

• Ray - Sphere Intersection



We get a quadratic in t

$$At^2 + Bt + C = 0$$

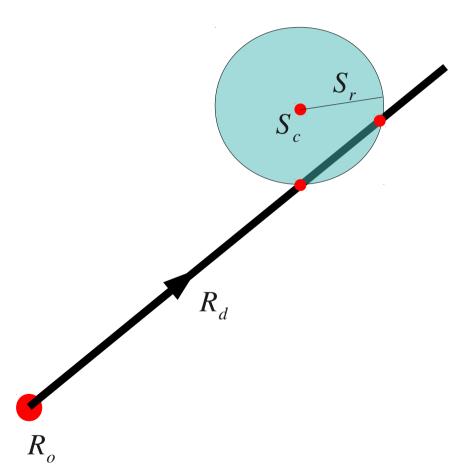
where

$$A = x_d^2 + y_d^2 + z_d^2 = 1$$

$$B = 2x_d(x_o - x_c) + y_d(y_o - y_c) + z_d(z_o - z_c)$$

$$C = (x_o - x_c)^2 + (y_o - y_c)^2 + (z_o - z_c)^2 - S_r^2$$

• Ray - Sphere Intersection



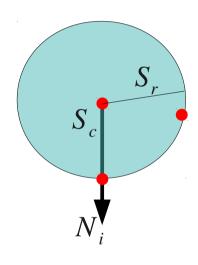
Solving for *t*

$$t_0 = \frac{-B - \sqrt{B^2 - 4AC}}{\frac{2A}{2A}}$$
$$t_1 = \frac{-B + \sqrt{B^2 - 4AC}}{\frac{2A}{2A}}$$

Smallest positive value among these two intersections is the closest intersection point.

$$(x_i, y_i, z_i) = (x_0 + t x_d, y_0 + t y_d, z_0 + t z_d)$$

• Ray - Sphere Intersection



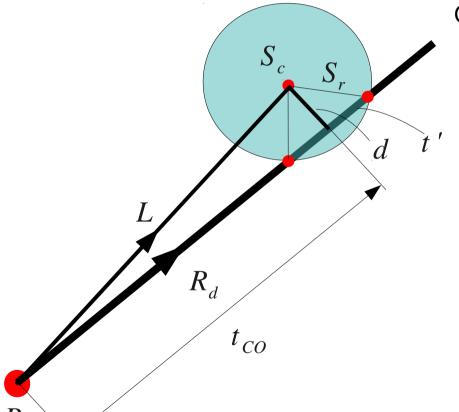
The normal at the point of intersection is given by:

$$N_i = (\frac{(x_i - x_c)}{S_r}, \frac{(y_i - y_c)}{S_r}, \frac{(z_i - z_c)}{S_r})$$

The steps are:

- ·Calculate A, B, C
- ·Compute the discriminant
- ·Calculate minimum t.
- ·Compute intersection point.
- ·Compute the normal.

• Ray - Sphere Intersection



Geometrically:

$$L=S_c-R_o$$

$$t_{CO} = L^T R_d$$

If $t_{CO} < 0$ then no intersection.

$$d^2 = L L^T - t_{CO}^2$$

If $d > S_r$ then no intersection.

$$t' = \sqrt{S_r^2 - d^2}$$

Then the two intersections are given by $t_0 = t_{CO} - t$ and $t_1 = t_{CO} + t$

• Ray - Plane Intersection

Ray
$$R(t) = R_0 + tR_d$$
, $t > 0$

Plane
$$P: Ax + By + Cz + D = 0$$

 $A^2 + B^2 + C^2 = 1$

Plane
$$P_n = (A, B, C)$$

D: Distance from the origin

• Ray - Plane Intersection

Substituing

$$A(x_o + tx_d) + B(y_o + ty_d) + C(z_o + tz_d) + D = 0$$

Solving:

$$t = \frac{-(Ax_o + By_o + Cz_o + D)}{Ax_d + By_d + Cz_d} = \frac{-(P_n \cdot R_o + D)}{P_n \cdot R_d}$$

lf:

$$V_d = Ax_d + By_d + Cz_d = P_n \cdot R_d$$

Now, if $V_d = 0$ then ray is parallel to the plane (i.e., no intersection).

Now, if $V_d > 0$ then normal is pointing away from the ray. Can be used for backface culling.

• Ray - Plane Intersection

Substituing

$$A(x_o + tx_d) + B(y_o + ty_d) + C(z_o + tz_d) + D = 0$$

Solving:

$$t = \frac{-(Ax_o + By_o + Cz_o + D)}{Ax_d + By_d + Cz_d} = \frac{-(P_n \cdot R_o + D)}{P_n \cdot R_d}$$

If:

$$V_{o} = -(Ax_{o} + By_{o} + Cz_{o} + D) = -(P_{n}. R_{o} + D)$$
 then $t = \frac{V_{o}}{V_{d}}$

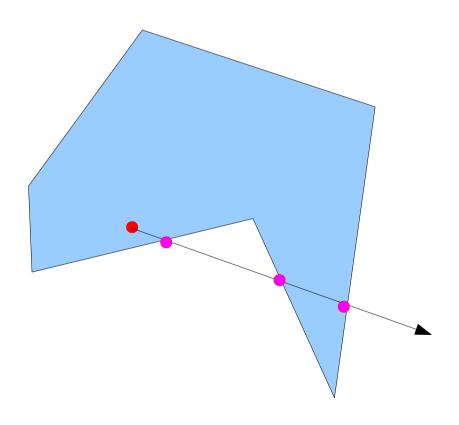
If t < 0 then plane is behind ray's origin, else compute intersection.

$$(x_i, y_i, z_i) = (x_0 + t x_d, y_0 + t y_d, z_0 + t z_d)$$

 $N_i = P_n$

• Ray - Polygon Intersection

Do a Ray-Plane intersection and then check for containment in the polygon.

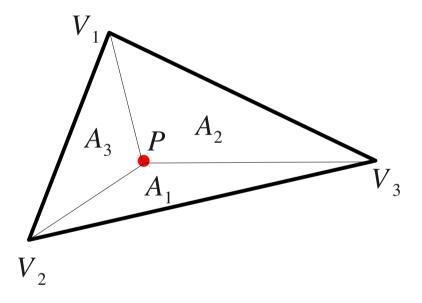


Shoot a ray in any direction from the intersection point in the plane of the polygon.

If number of intersections with the polygon boundary are odd then the point is contained in the polygon

Ray - Triangle Intersection

Do a Ray-Plane intersection and then check for containment in the triangle.



The point of intersection can be written in Barycentric Coordinates as:

$$P = u V_1 + v V_2 + w V_3$$

where

$$u = \frac{A_1}{A}, v = \frac{A_2}{A}, w = \frac{A_3}{A}$$

and

$$A = A_1 + A_2 + A_3$$

The point lies inside the triangle if u+v+w=1 and $u \ge 0, v \ge 0, w \ge 0$

- Ray Quadric Intersection
 - Cylinders, Cones, Sphere, Ellipsoids, Paraboloids

Implicit form of a general quadric is given by:

$$F(x, y, z) = Ax^2 + 2Bxy + 2Cxz + 2Dx + Ey^2 + 2Fyz + 2Gy + Hz^2 + 2Iz + J = 0$$

Ray:
$$R(t) = R_0 + tR_d$$
, $t > 0$

Substitute and solve the quadratic in *t*

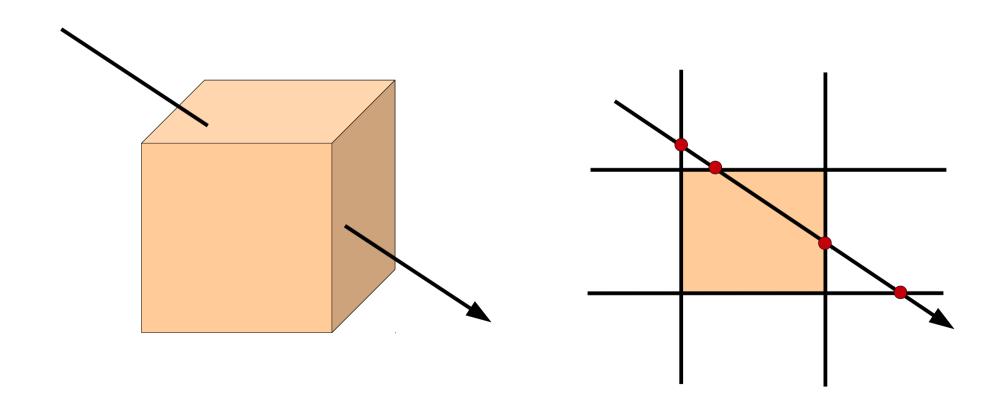
Normal at the point of intersection:

$$N_{i} = \left(\frac{\partial F}{\partial x_{i}}, \frac{\partial F}{\partial y_{i}}, \frac{\partial F}{\partial z_{i}}\right) \Rightarrow N_{ix} = 2\left(Ax_{i} + By_{i} + CZ_{i} + D\right)$$

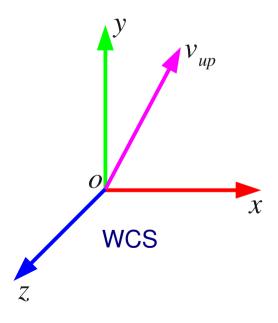
$$N_{iy} = 2\left(Bx_{i} + Ey_{i} + FZ_{i} + G\right)$$

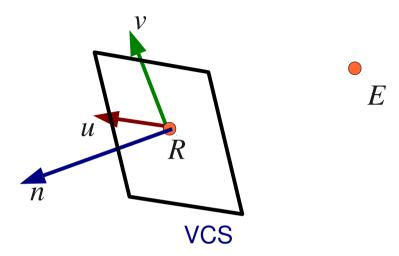
$$N_{iz} = 2\left(Cx_{i} + Fy_{i} + HZ_{i} + I\right)$$

- Ray Box Intersection
 - User Cyrus Beck/Liang Barsky in 3D



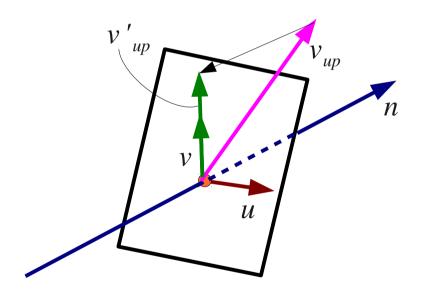
- Setting up
 - Viewing





- In WCS
 - Position of VRP, R
 - Normal to View Plane, n
 - Up Vector, v_{up}
- In VCS
 - Extent of window
 - Position of Eye, E

- Setting up
 - Viewing



If
$$v'_{up} = v_{up} - (v_{up} \cdot n) n$$

then we define $v = \frac{v'_{up}}{\|v'_{up}\|}$ and $u = v \times n$

- Setting up
 - Viewing

If a point *P* has coordinates

(x, y, z) in WCS

(a,b,c) in VCS

then -

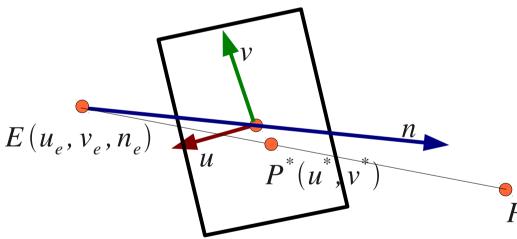
$$\begin{bmatrix} x \\ y \\ z \end{bmatrix} = M \cdot \begin{bmatrix} a \\ b \\ c \end{bmatrix} + R$$

$$E(u_e, v_e, n_e)$$

$$R(r_x, r_y, r_z)$$

where,
$$M = \begin{bmatrix} u_x & v_x & n_x \\ u_y & v_y & n_y \\ u_z & v_z & n_z \end{bmatrix}$$

- Setting up
 - Viewing



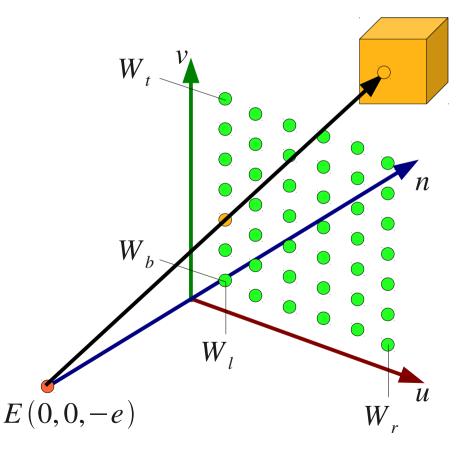
- Define VRP, $R(r_x, r_y, r_z)$
- Compute M from u, v, n
- Define eye in VCS

$$E(u_e, v_e, n_e) = (0, 0, -e)$$

In WCS, the eye becomes $E_{wcs} = M \cdot E + R$

$$P(u_p, v_p, n_p)$$

- Setting up
 - Window



Define window size

$$W_l, W_r, W_t, W_b$$

$$v_{i}^{*} = W_{l} + i\Delta u$$
 for pixel (i, j)
$$v_{i}^{*} = W_{t} - j\Delta v$$

where

$$\Delta u = (W_r - W_t) / \text{MAXCOLS}$$

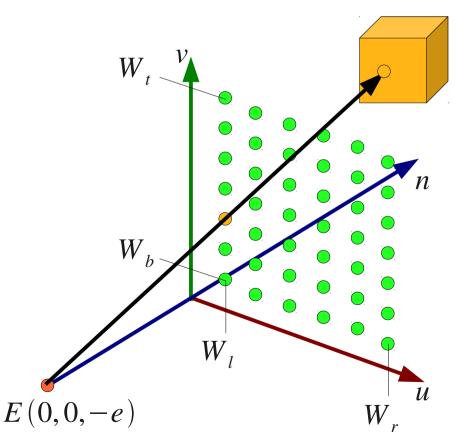
 $\Delta v = (W_t - W_b) / \text{MAXROWS}$

Thus coordinates of pixel (i, j) are

$$P_{ij}^* = (u_i^*, v_j^*, 0)$$

 MAXROWS and MAXCOLS can be used to control the resolution of the image.

- Setting up
 - Ray



•
$$E_{wcs} = M.E + R = M.[0 \ 0 \ -n_e]^T + R$$

 Direction of the ray from the eye through pixel at (i,j) in WCS is given by

$$dir_{ij} = M.P_{ij}^* + R - E_{wcs} = M.(P_{ij}^* - E)$$

$$= M. \begin{bmatrix} u_i^* & v_j^* & n_e \end{bmatrix}^T$$

 Ray is through pixel(i, j) given by

$$R_{ij}(t) = E_{wcs} + dir_{ij}t = R_o + R_d t$$

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- Basic Idea
 - For every pixel in the image
 - Shoot a ray
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 - Compute illumination at point of intersection
 - Assign pixel color

Transforming objects

Ray: s+ct

Objects: Sphere, Cone, Cylinder, Box

We assume the objects to be normalized so that the ray-object intersection is easier:

for e.g., Sphere: $x^2 + y^2 + z^2 = 1$

Transforming objects

Ray: s+ct

Objects: Sphere, Cone, Cylinder, Box

Then we replicate the normalized objects and transform them to create variety in the scene.

Can ray-object intersections be done on the transformed objects?

• Transforming objects

M

World Space

Object Space

A normalized sphere is transformed under an affine transformation, i.e.,

$$q' = M.q \Leftrightarrow q = M^{-1}.q'$$

 Transforming objects MWorld Space **Object Space** s+ct $s+ct=M^{-1}.s'+M^{-1}.c't'$ $\begin{bmatrix} s_{x} \\ s_{y} \\ s_{z} \\ 1 \end{bmatrix} = \begin{bmatrix} a & d & g & l \\ b & e & h & m \\ c & f & i & n \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} s'_{x} \\ s'_{y} \\ s'_{z} \\ 1 \end{bmatrix} = \begin{bmatrix} as'_{x} + ds'_{y} + gs'_{z} + l \\ bs'_{x} + es'_{y} + hs'_{z} + m \\ cs'_{x} + fs'_{y} + is'_{z} + n \\ 1 \end{bmatrix}$

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 Transforming objects MWorld Space **Object Space** s+ct $s+ct=M^{-1}.s'+M^{-1}.c't'$

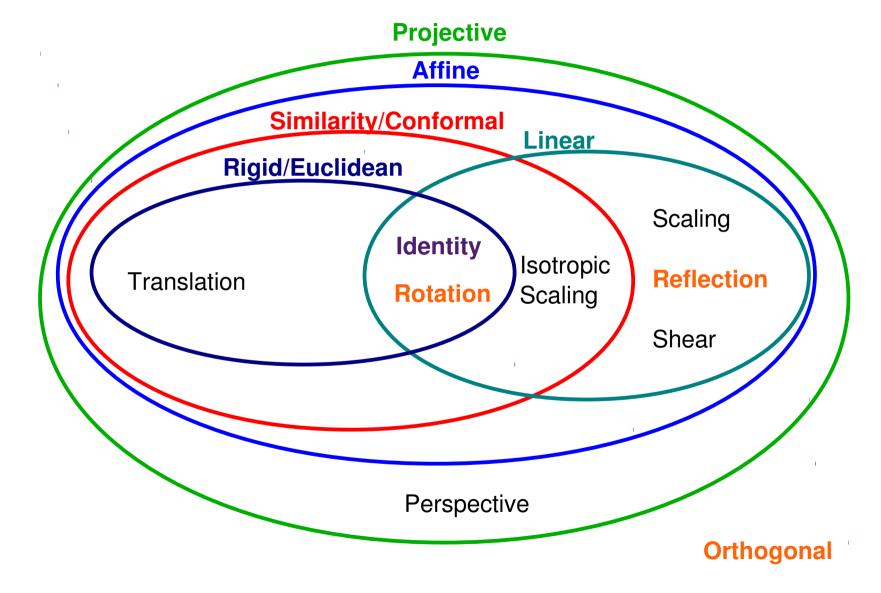
 $\begin{bmatrix} c_{x} \\ c_{y} \\ c_{z} \\ 0 \end{bmatrix} = \begin{bmatrix} a & d & g & l \\ b & e & h & m \\ c & f & i & n \\ 0 & 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} c'_{x} \\ c'_{y} \\ c'_{z} \\ 0 \end{bmatrix} = \begin{bmatrix} ac'_{x} + dc'_{y} + gc'_{z} + l \\ bc'_{x} + ec'_{y} + hc'_{z} + m \\ cc'_{x} + fc'_{y} + ic'_{z} + n \\ 0 \end{bmatrix}$ CS 475/CS 675: Lecture 17

• Transforming objects M World Space S+ct M^{-1}

If M includes a scaling then c is not a unit vector after the transformation. If c is renormalized then scale the t value accordingly.

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A side note on transformations



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• Transforming objects M q' s'+c'tWorld Space

Object Space s+ct

We also need the normal at the point of intersection. How does the normal transform when the object undergoes an affine transformation?

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