

Lecture 7

Air Quality:

Air Pollution Control

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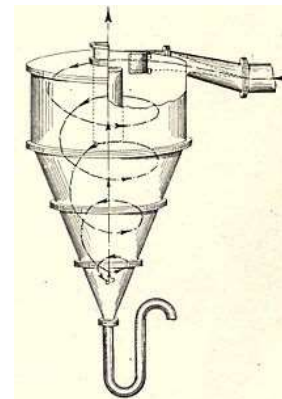
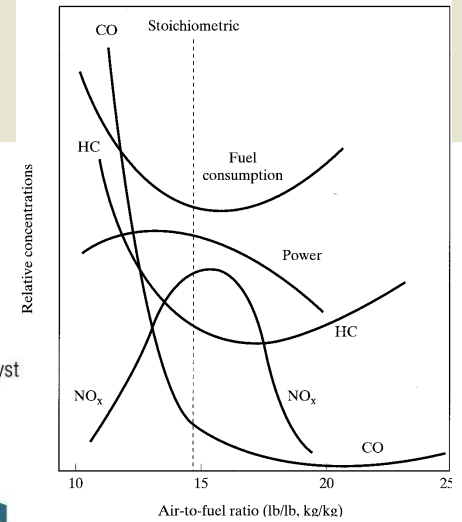
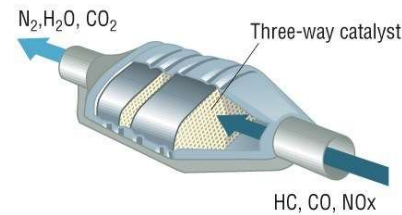
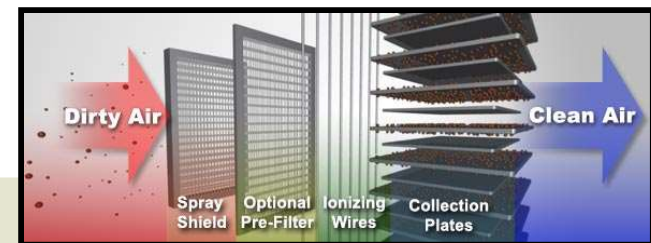
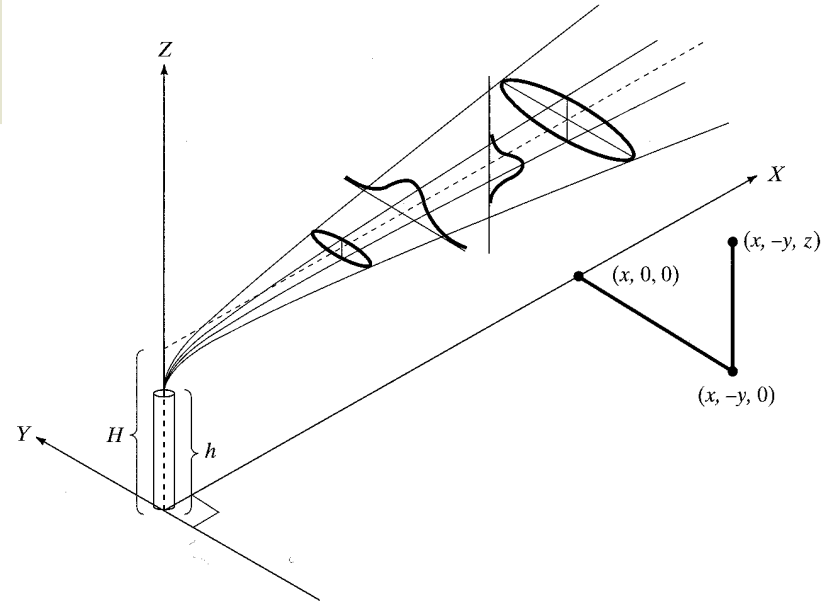


FIG. 201.—COLMAN'S "CYCLOSE" TAB EXTRACTOR.



Recap 1

- Air pollution monitoring is crucial for true understanding of the state of the environment but impossible to have wide spatial coverage, hence air quality modeling is needed
- **Gaussian Plume (Dispersion) Model (GPM)** is used to estimate the ground level concentrations for pollutants coming from a chimney/point source
- Inputs to GPM are: height of chimney; source emission strength; wind rose data; atmospheric stability of the region



$$\chi(x, y, 0, H) = \left[\frac{Q}{\pi s_y s_z u} \right] \left[\exp \left[-\frac{1}{2} \left(\frac{y}{s_y} \right)^2 \right] \right] \left[\exp \left[-\frac{1}{2} \left(\frac{H}{s_z} \right)^2 \right] \right]$$

Recap 2

- Assumptions in GPM
 - pollutants released from a “virtual point source”
 - advective transport by wind
 - dispersive transport (spreading) follows normal (Gaussian) distribution away from trajectory
 - constant source emission rate
 - wind speed constant with time and elevation
 - pollutant is conservative (no reaction)
 - terrain is flat and unobstructed
 - uniform atmospheric stability
- Effective stack height

$$H = h + \Delta H$$

$$\Delta H = \frac{v_s d}{u} \left[1.5 + \left(2.68 \times 10^{-3} (P) \left(\frac{T_s - T_a}{T_s} \right) d \right) \right]$$

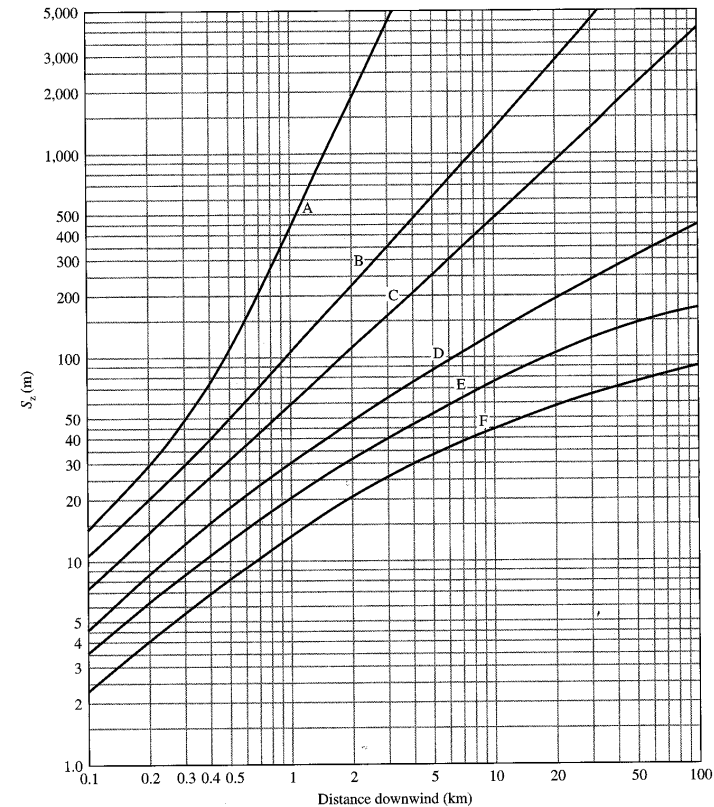
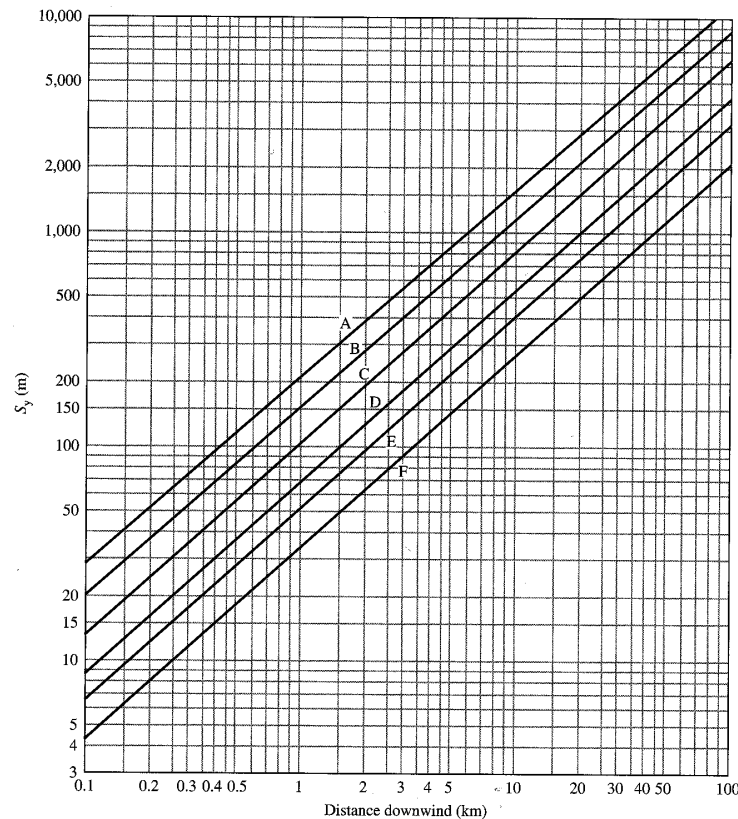
Holland's formula

Recap 3

- Estimation of horizontal dispersion (s_y and s_z)

$$\sigma_y = a x^{0.894}$$

$$\sigma_z = cx^d + f$$



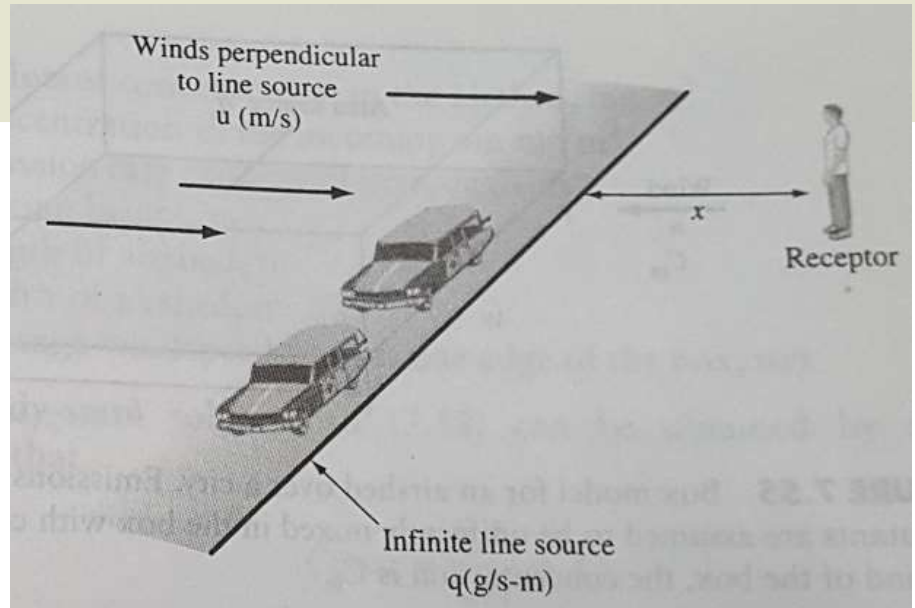
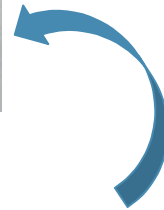
- Estimation of wind speed at stack height
- Model uncertainty could be up to 50%

$$u_2 = u_1 \left(\frac{z_2}{z_1} \right)^p$$

Recap 4

- When source is distributed along a line with continuous emissions, similar approach can be used
- Ground level conc. of pollutants at a perpendicular distance x can be obtained by:

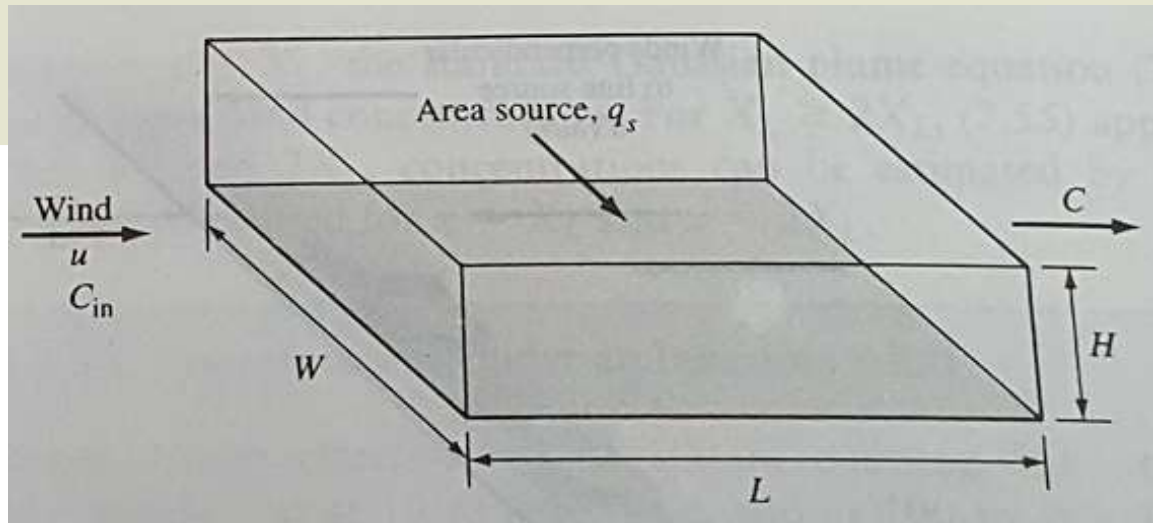
$$C(x) = \frac{2q}{\sqrt{2\pi} \sigma_z u}$$



$$\chi(x, y, 0, H) = \left[\frac{Q}{\pi s_y s_z u} \right] \left[\exp \left[-\frac{1}{2} \left(\frac{y}{s_y} \right)^2 \right] \right] \left[\exp \left[-\frac{1}{2} \left(\frac{H}{s_z} \right)^2 \right] \right]$$

Recap 5

- For distributed sources spread over an area, **box model** can be used



- Assuming uniform mixing in the box, and a conservative pollutants, rate of change of pollutants in the box:

$$\left(\text{Rate of change of} \right) = \left(\text{Rate of pollution} \right) - \left(\text{Rate of pollution} \right)$$

pollution in the box entering the box leaving the box

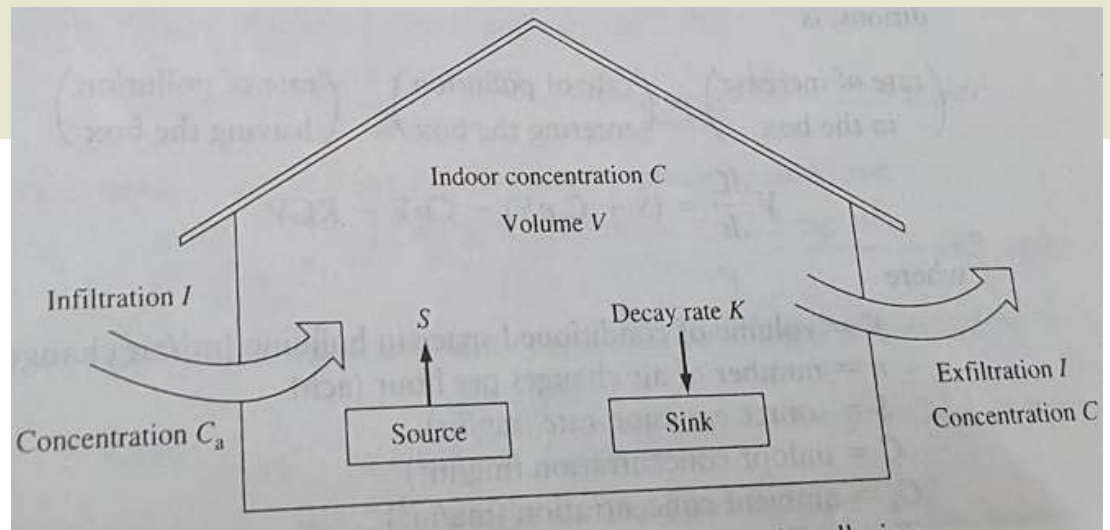
$$LWH \frac{dC}{dt} = q_s L W + WHu C_{in} - WHu C$$

$$C(\infty) = \frac{q_s L}{uH} + C_{in}$$

$$C(t) = \left(\frac{q_s L}{uH} + C_{in} \right) (1 - e^{-ut/L}) + C(0) e^{-ut/L}$$

Recap 6

- Similar to urban airshed, an **indoor box model** can be built
- e.g. a basic mass balance for pollution in the building/ room, assuming well-mixed conditions:



$$\left(\begin{array}{c} \text{rate of increase} \\ \text{in the box} \end{array} \right) = \left(\begin{array}{c} \text{rate of pollution} \\ \text{entering the box} \end{array} \right) - \left(\begin{array}{c} \text{rate of pollution} \\ \text{leaving the box} \end{array} \right) - \left(\begin{array}{c} \text{rate of decay} \\ \text{in the box} \end{array} \right)$$

$$V \frac{dC}{dt} = (S + C_a n V) - C n V - K C V$$

where, n is number of air changes per hour

$$C(t) = \left[\frac{(S/V) + C_a n}{n + K} \right] [1 - e^{-(n+K)t}] + C(0) e^{-(n+K)t}$$

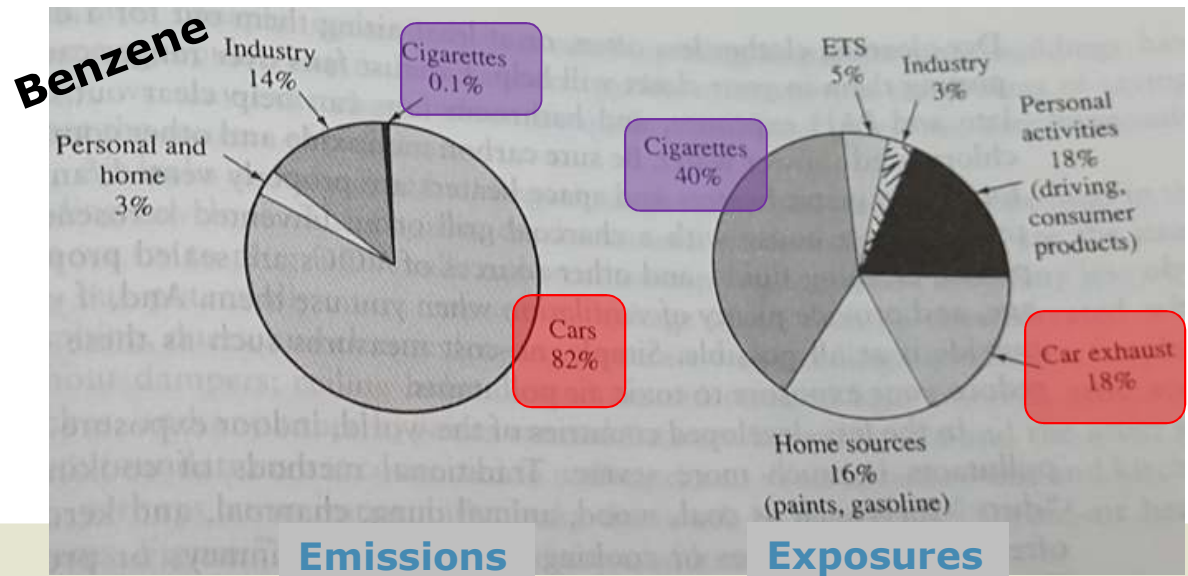
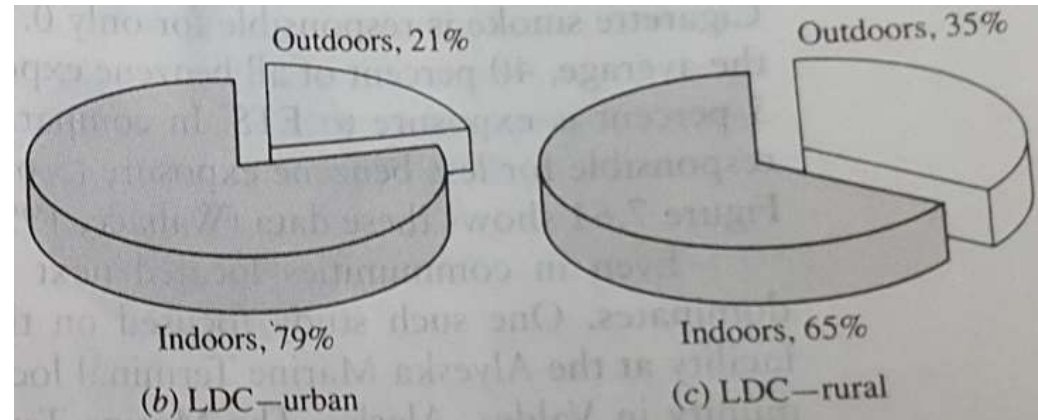
$$C(\infty) = \frac{(S/V) + C_a n}{n + K}$$

$$C(t) = \left(\frac{S}{nV} \right) (1 - e^{-nt})$$

Recap 6

Exposure = concentration x duration of time in contact

- Contact duration depends on where people spend their time
- Some of the largest emissions may have lowest exposures and vice-versa



Today's Learning Objective !

- To learn about air pollution control methods from mobile and stationary sources

Air Pollution Control: Mobile Sources

India Emission Standards

Standard	Reference	Date	Region
India 2000	Euro 1	2000	Nationwide
Bharat Stage II	Euro 2	2001	NCR*, Mumbai, Kolkata, Chennai
		2003.04	NCR*, 11 cities†
		2005.04	Nationwide
Bharat Stage III	Euro 3	2005.04	NCR*, 11 cities†
		2010.04	Nationwide
Bharat Stage IV	Euro 4	2010.04	NCR*, 13 cities‡
		2015.07	Above plus 29 cities mainly in the states of Haryana, Uttar Pradesh, Rajasthan and Maharastra [3231]
		2015.10	North India plus bordering districts of Rajasthan (9 States) [3232]
		2016.04	Western India plus parts of South and East India (10 States and Territories) [3232]
		2017.04	Nationwide [3232]
Bharat Stage V	Euro 5	n/a ^a	
Bharat Stage VI	Euro 6	2020.04	Nationwide [3349]

* National Capital Region (Delhi)

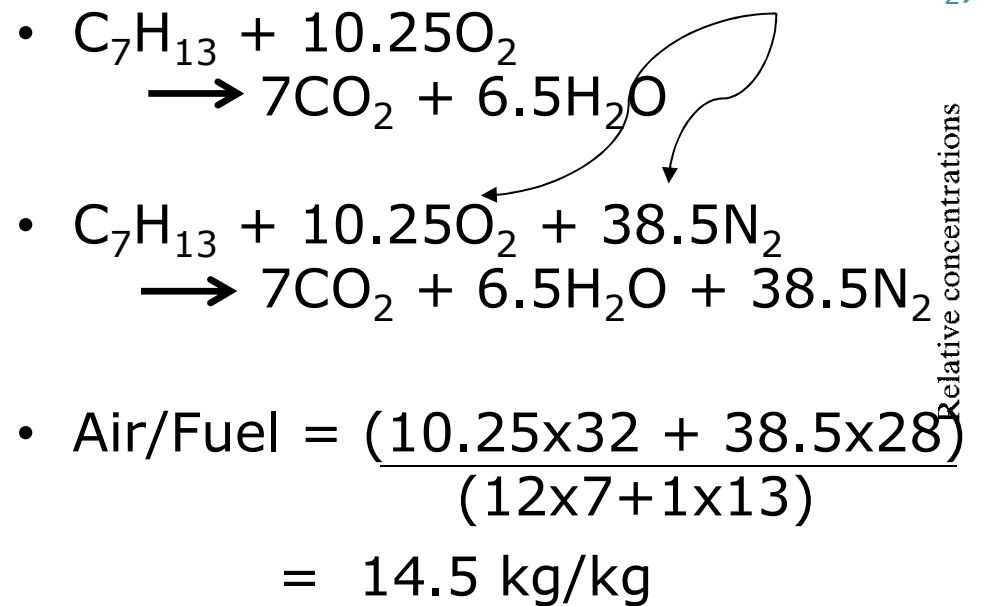
† Mumbai, Kolkata, Chennai, Bangalore, Hyderabad, Secunderabad, Ahmedabad, Pune, Surat, Kanpur and Agra

‡ Above cities plus Solapur and Lucknow. The program was later expanded with the aim of including 50 additional cities by March 2015

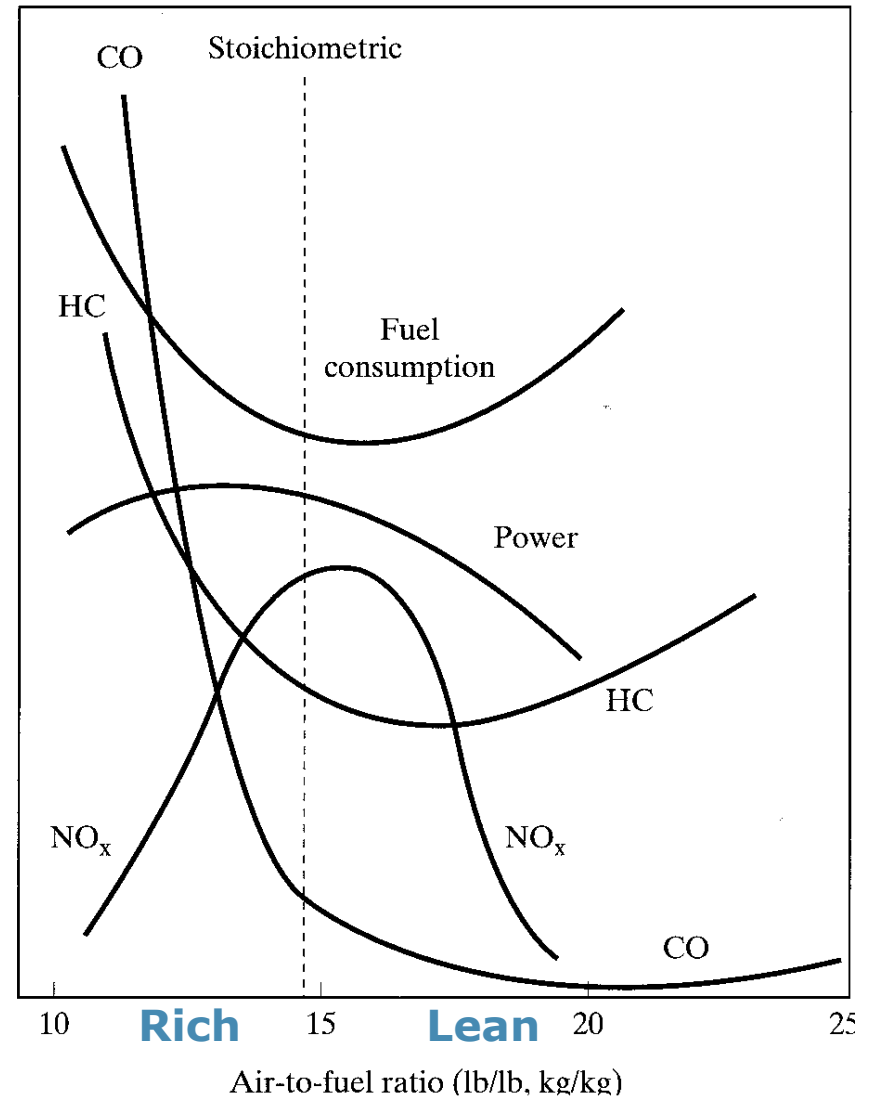
^a Initially proposed in 2015.11 [3297][3298] but removed from a 2016.02 proposal [3349]

Emission control of IC engines

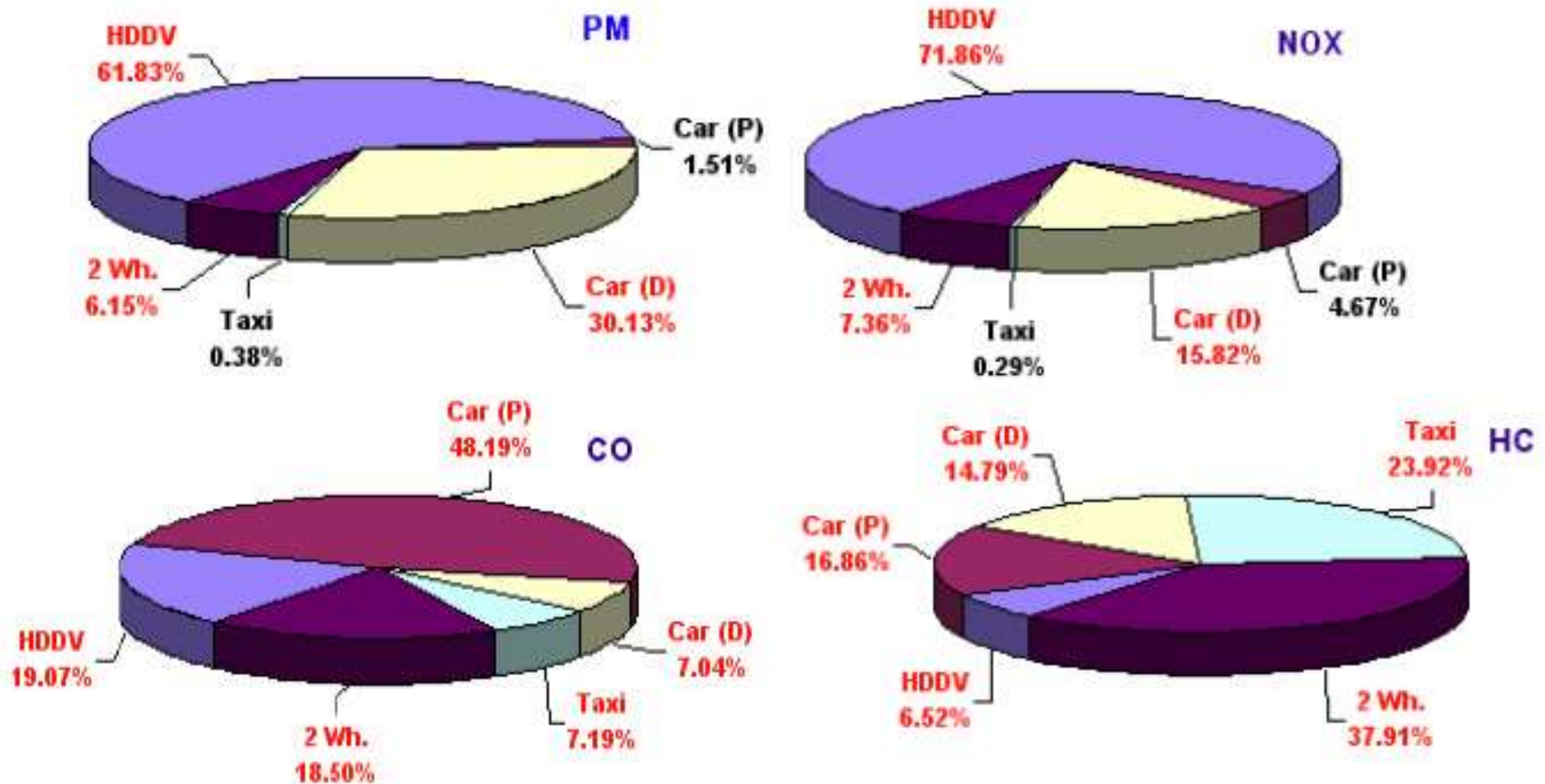
- Maintaining a **stoichiometric air/fuel ratio**



- Petrol vs. Diesel emissions

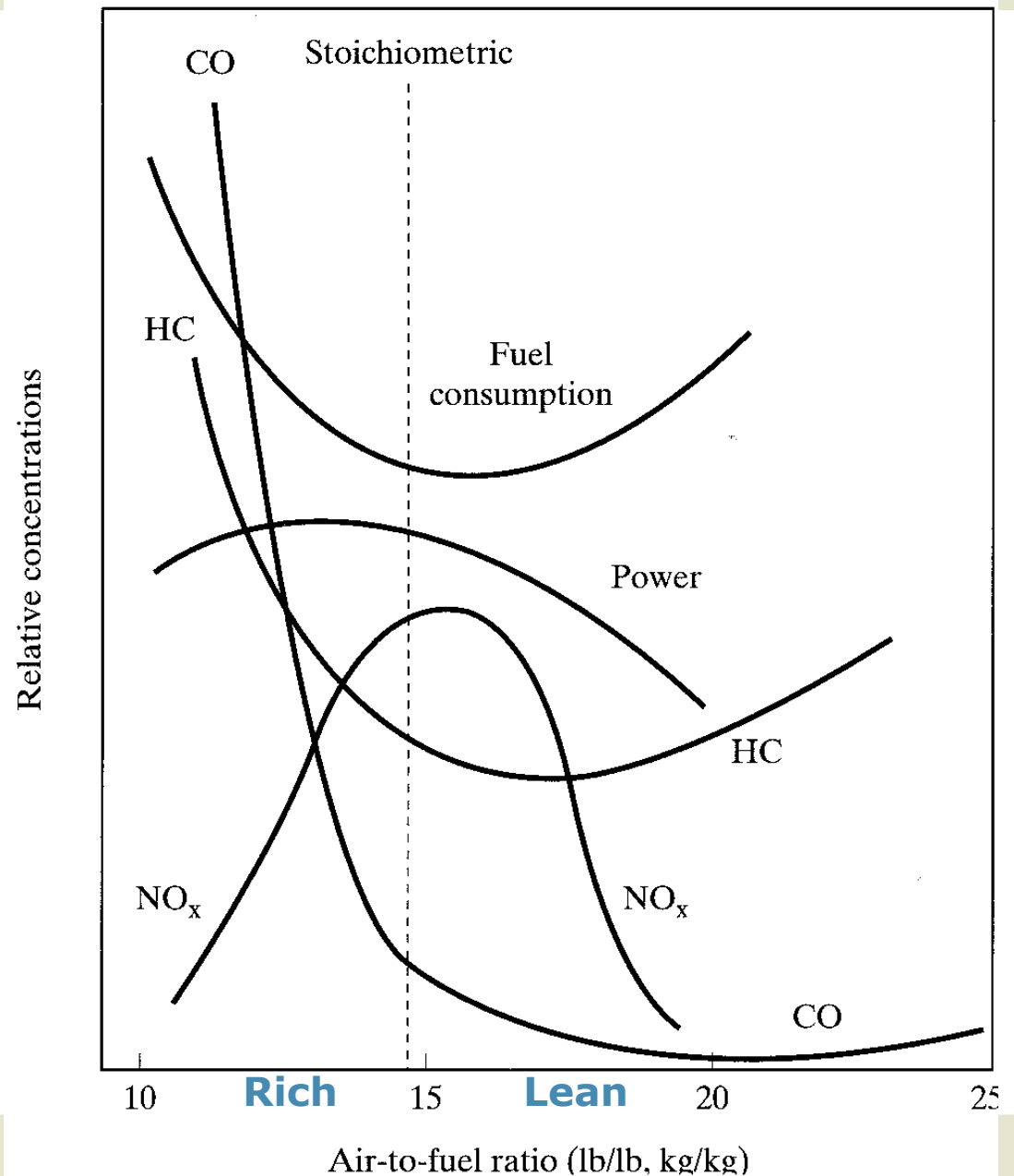


Total emissions from IC engines: Petrol vs. Diesel



Emission control of IC engines

- Maintaining a stoichiometric air/fuel ratio



Three-way Catalytic converter

A three-way catalytic converter has three simultaneous tasks:

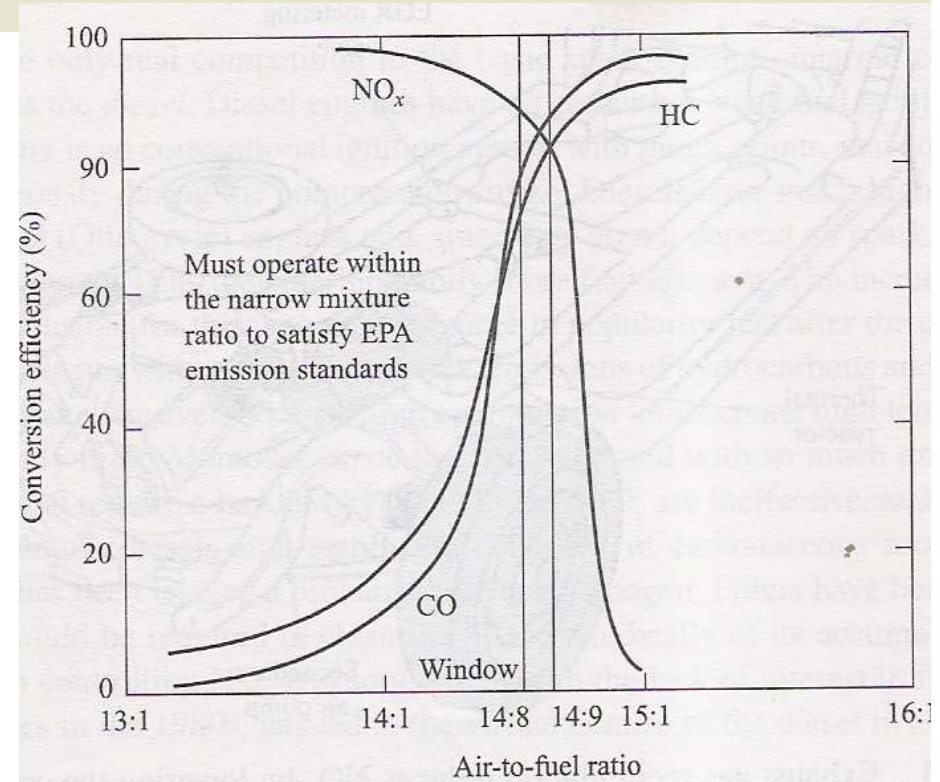
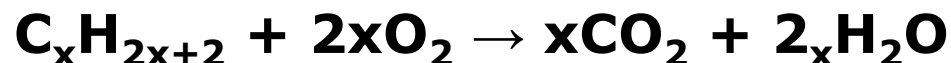
- Reduction of **nitrogen oxides** to nitrogen and oxygen:



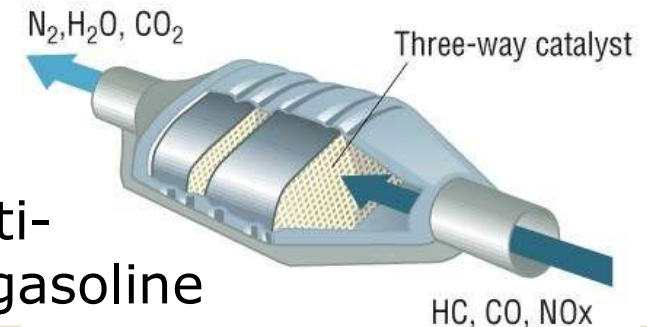
- Oxidation of **carbon monoxide** to carbon dioxide:



- Oxidation of unburnt **hydrocarbons (HC)** to carbon dioxide and water:



➔ Elimination of tetraethyl lead as an anti-knocking agent/ octane booster from gasoline



Cleaner/Alternative fuel

- Vaporization of gasoline should be reduced
- Oxygen containing additives reduce air requirement., e.g. ethanol, MTBE (Hazardous)
 - **Methanol**: Less photochemically reactive VOC, but emits HCHO (eye irritant), difficult to start in winters: can be overcome by M85 (85% methanol, 15% gasoline)
 - **Ethanol**: E10 (10% ethanol & 90% gasoline; used as an oxygenate to reduce CO emissions
 - **Biodiesel**: produced from animal fats, vegetable oils; generally blended with diesel e.g. B2, B5 and B20 are common
 - **CNG**: Low HC, high NO_x, inconvenient refueling, leakage hazard
 - **LPG**: Propane, high NO_x
 - **Electric /hybrid** vehicles

Landmarks dates in Delhi NCR clean up !

- April 1995: Mandatory fitting of catalytic convertors
- April 1996: Low sulphur diesel introduced
- April 1998: Introduction of CNG buses in Delhi
- Sept 1998: Complete removal of lead in petrol
- Dec 1998: Restrict plying of goods vehicles during the day
- Sept 1999: Amendment of Motor Vehicles Act to include CNG
- April 2000: Private vehicles to be registered only if they conform to Euro II standards
- April 2000: Eight-year-old commercial vehicles phased out
- Nov 2002: Conversion of all public transport buses to CNG

Air Pollution Control: Stationary Sources

- Pre-combustion Control
 - Switching to less S and less N fuel
- Combustion Control
 - Improving the combustion process
 - New burners to reduce NO_x
 - Integrated Gasification combined cycle
- Post-Combustion Control
 - Particulate collection devices
 - Flue gas desulfurization

Air Pollution Control: PM

Device selection depends on

- Particle size
- Concentration
- Corrosivity
- Volumetric flow rate
- Required collection efficiency
- Cost

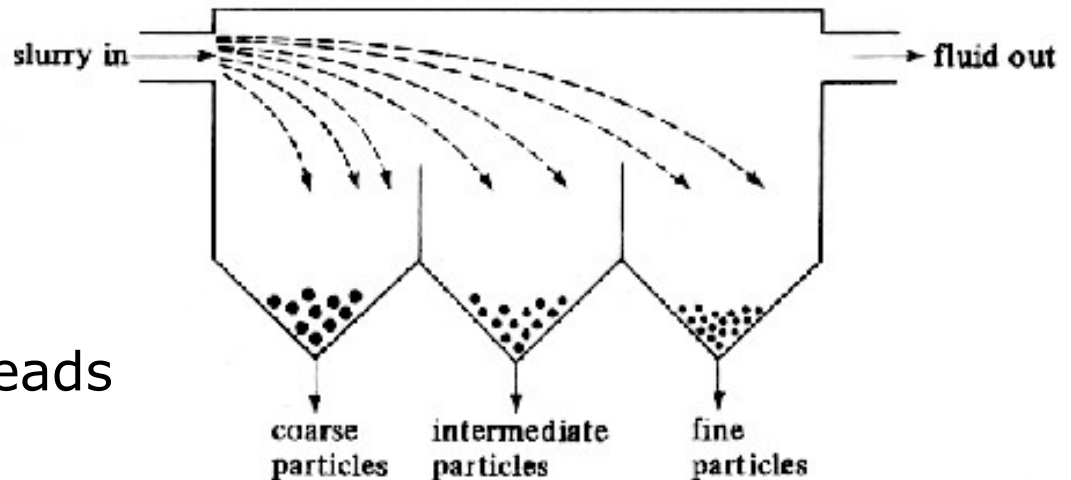
Air Pollution Control: PM

- Mechanical
 - Gravity based: Settling Chambers > 20 μm
 - Inertia based: Cyclones > 10 μm
 - Diffusion based: Filters > 0.1 μm
- Electrical
 - Electrostatic Precipitators > 0.1 μm

Mechanical - Gravity

Gravitational Settlers

- Particle settling:
Gravitational forces are balanced by drag and buoyancy forces. This leads to **Stokes law** - settling velocity of particles.



$$m_p g = \rho_p \frac{\pi}{6} d^3 g$$
$$F_d = 3 \pi \mu d v$$

When $F_d = F_g$, settling velocity is given by

$$v_t = g d^2 \frac{\rho_p}{18 \mu}$$

**V_t (1 μ m particle)
= 0.006 cm/s**

where,

g - gravity acceleration 9.8 m/s²

d - particle diameter (m)

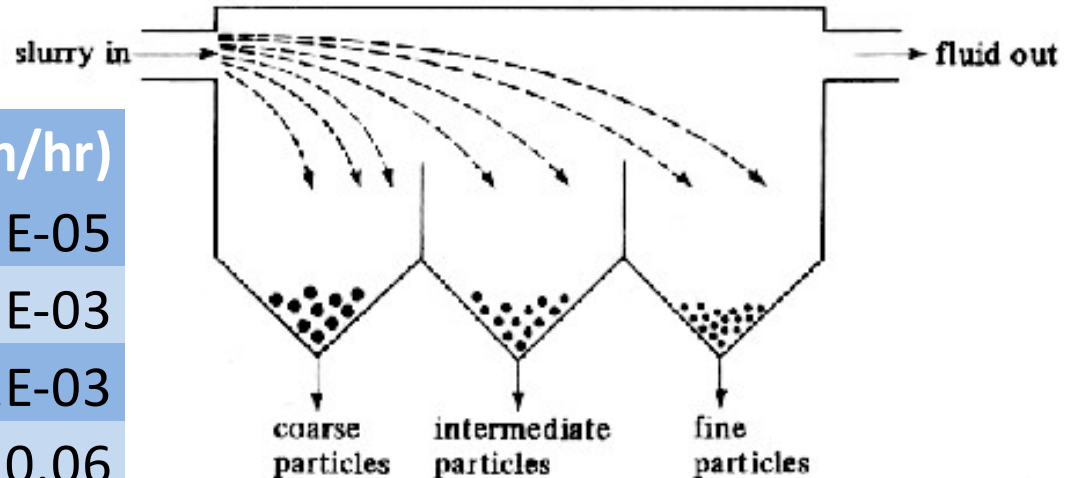
ρ_p - particle density (g/m³) = 2×10^6 g/m³

μ - air viscosity = 0.0172 g/m.s

Mechanical - Gravity

Gravitational Settlers

D_p (μm)	V_t (m/s)	V_t (m/hr)
0.01	6.3E-09	2.3E-05
0.1	6.3E-07	2.3E-03
0.2	2.5E-06	9.1E-03
0.5	1.6E-05	0.06
1	6.3E-05	0.23
2	2.5E-04	0.91
5	0.0016	5.70
10	0.0063	22.79
20	0.0253	91.16
50	0.1583	569.77
100	0.6331	2279.07
200	2.5323	9116.28
500	15.8269	56976.74
1000	63.3075	227906.98

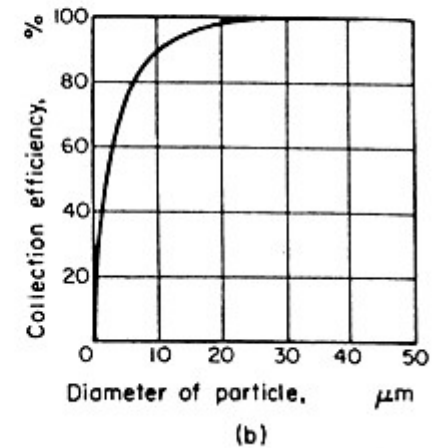
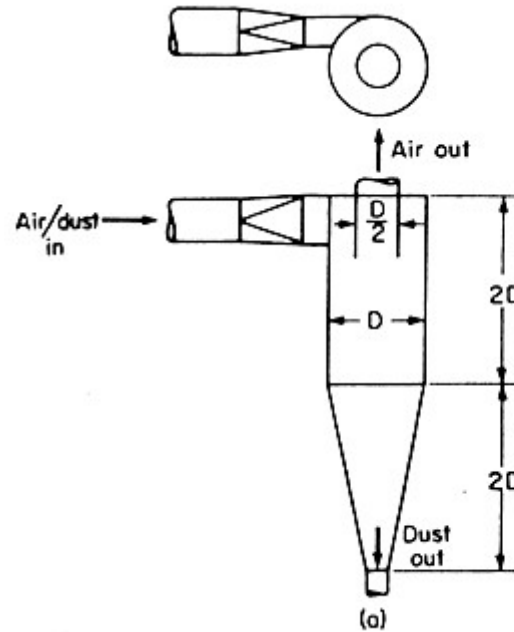
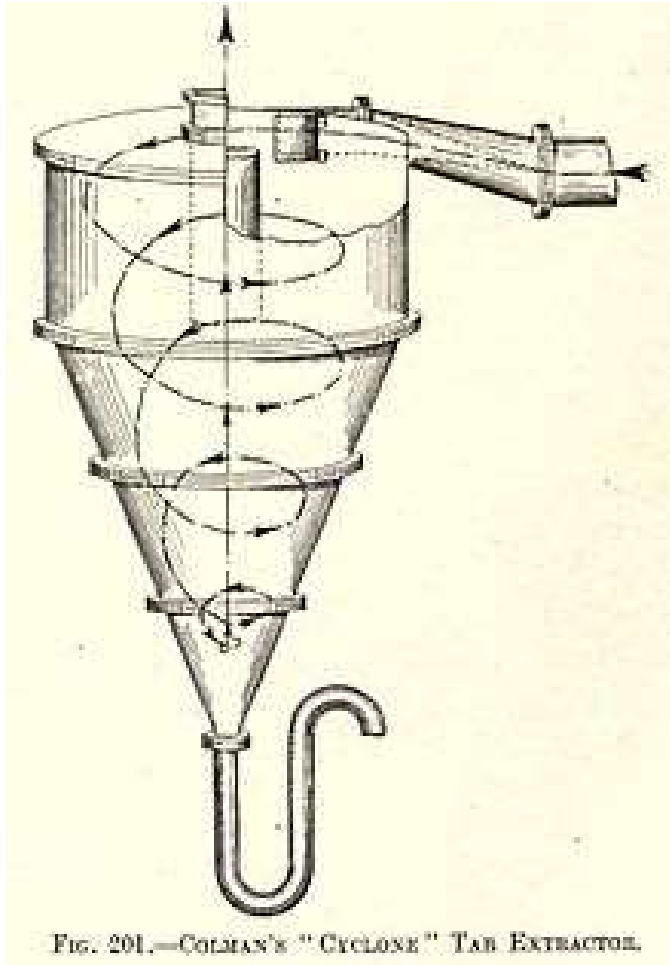


**V_t ($1\mu\text{m}$ particle)
= 0.006 cm/s**

$$v_t = g d^2 \frac{\rho_p}{18 \mu}$$

Mechanical - Inertia

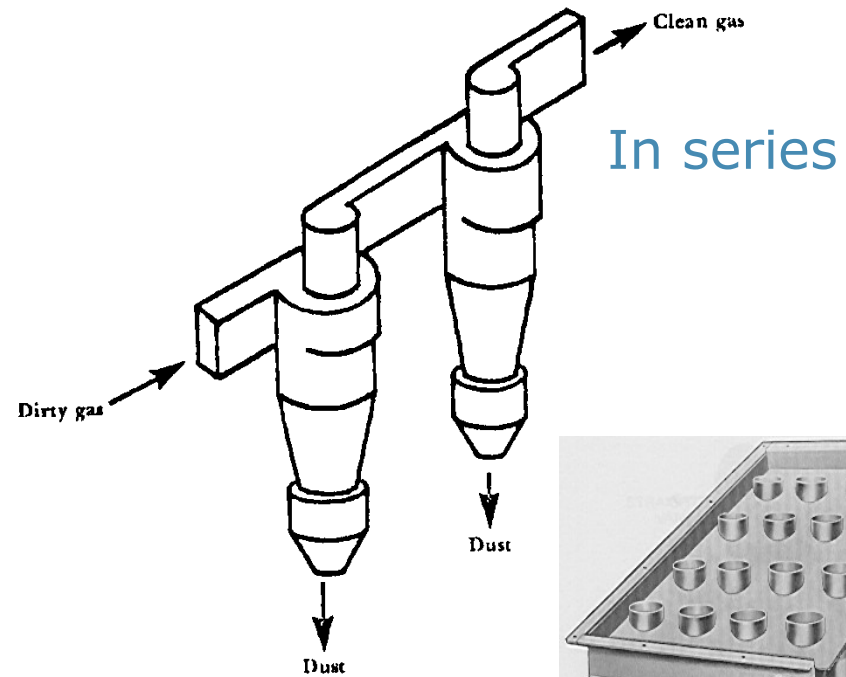
Cyclones



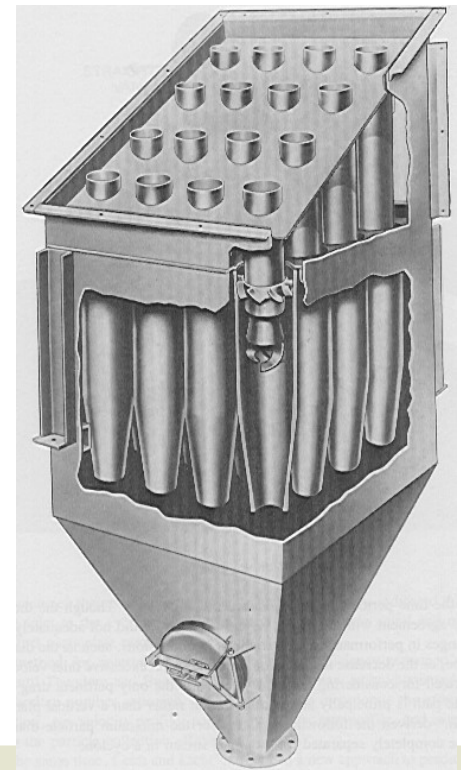
- For PM > 5 μm
- Efficiency > 90%
- Maintenance-free
- Low-cost

Mechanical - Inertia

Cyclones

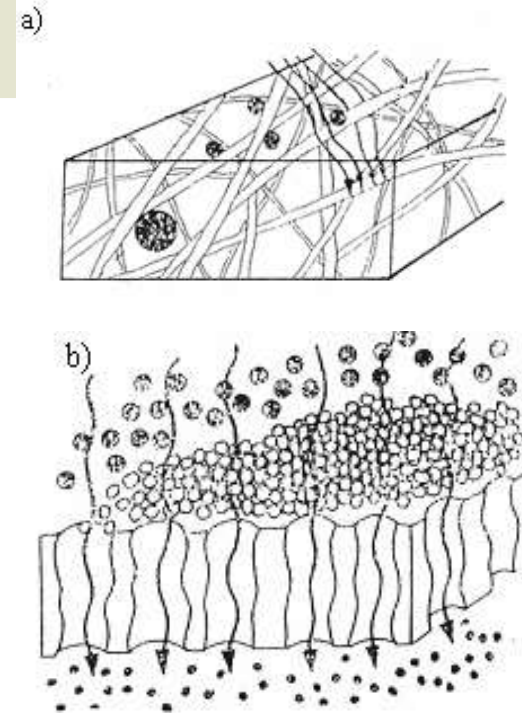
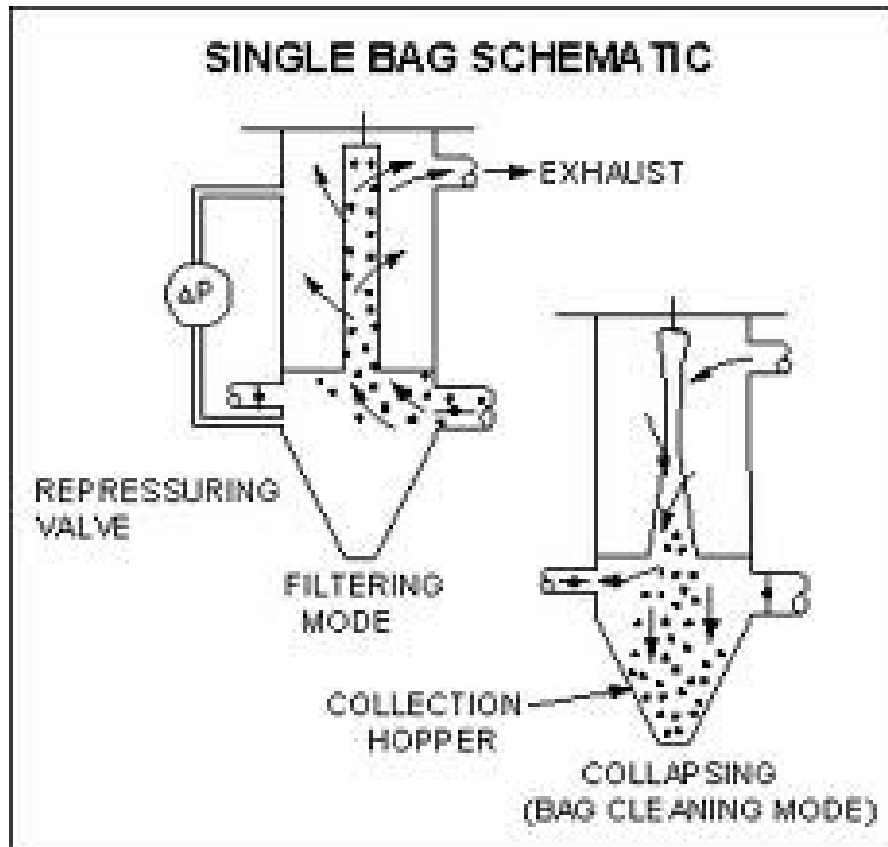


In parallel



Mechanical - Filtration

Bag filters

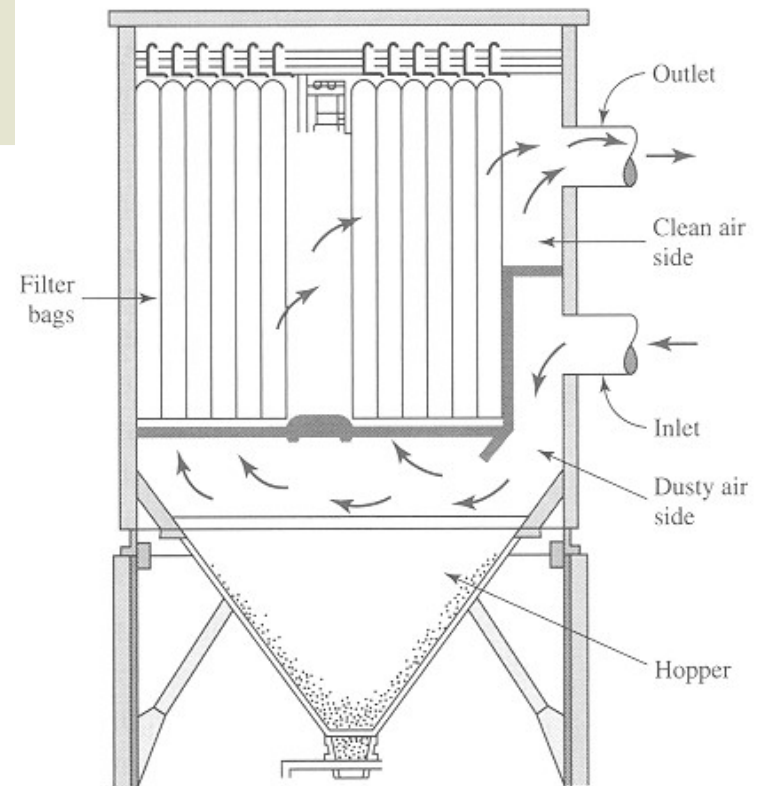


Filtration through fibrous material via:

- Diffusion
- Impaction
- Interception
- (NOT SIEVING)

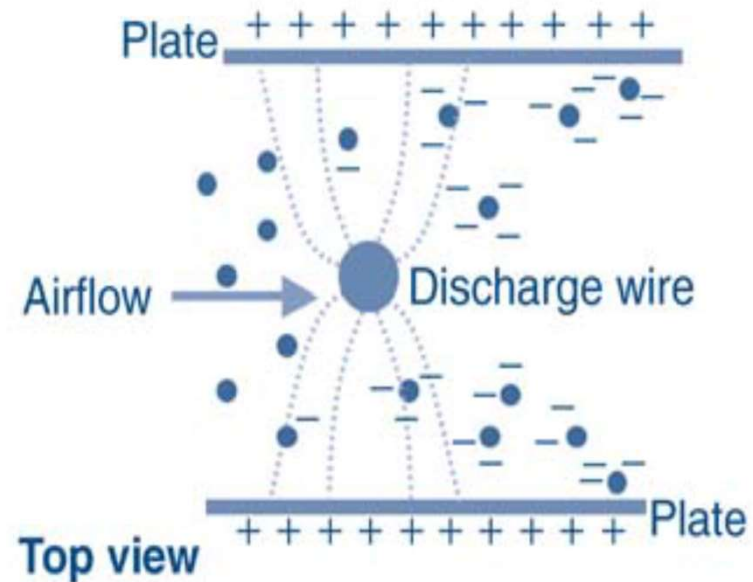
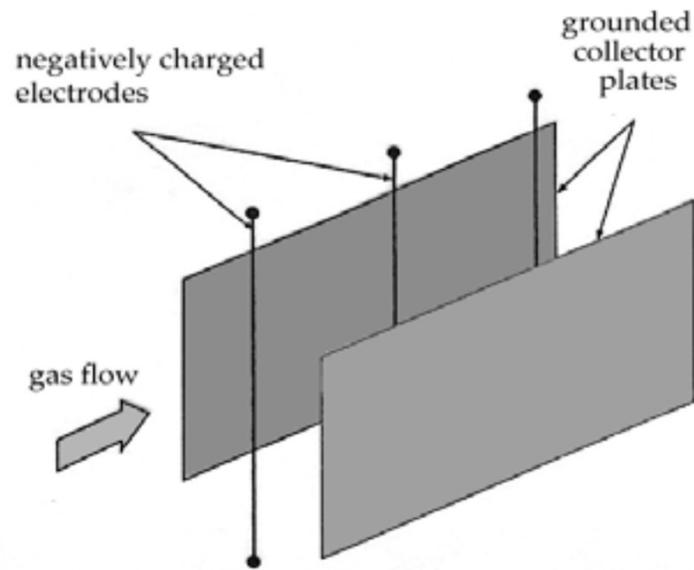
Mechanical - Filtration

Bag filters



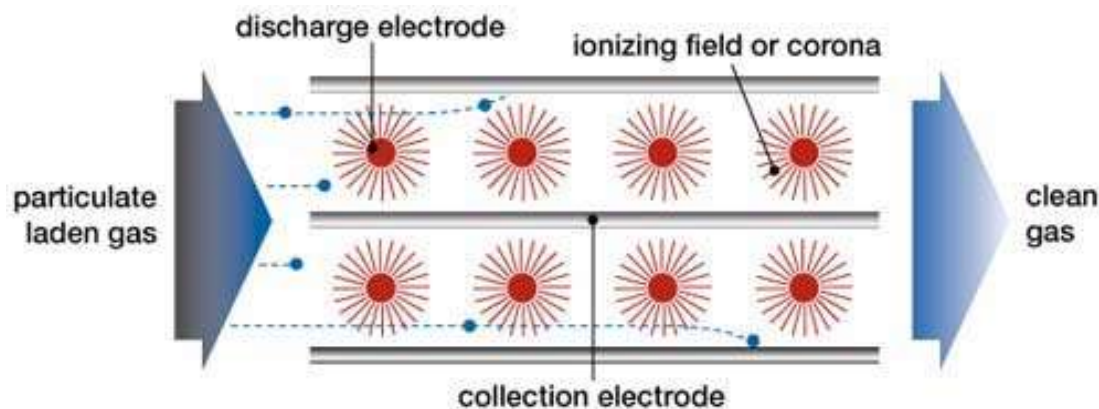
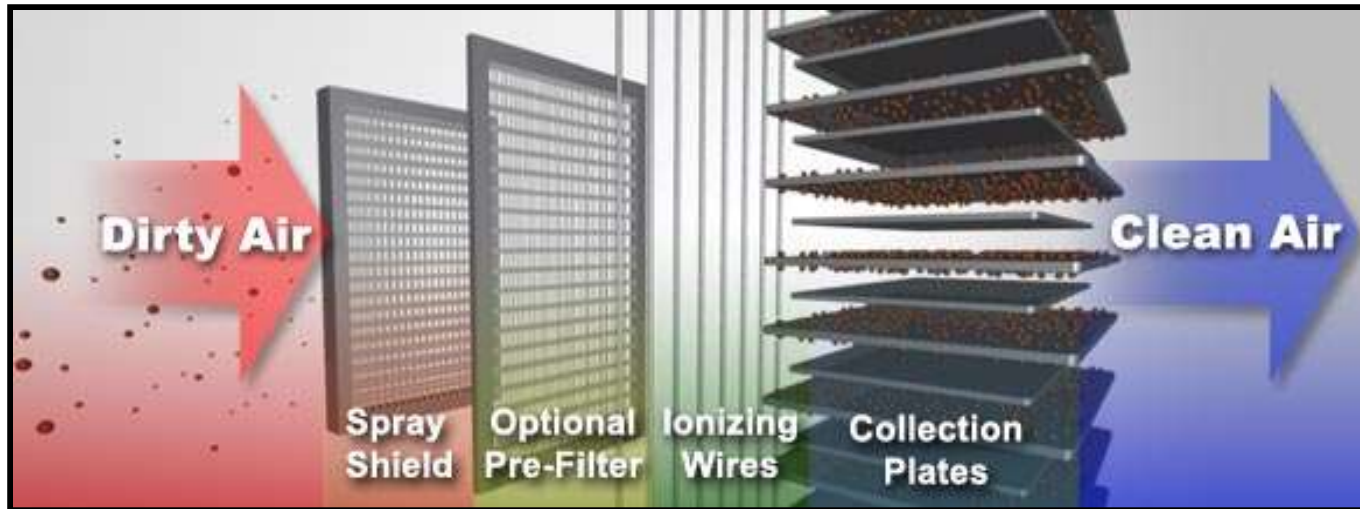
- Efficiency – 100% for particles $>0.01\text{-}1\ \mu\text{m}$
- Cannot operate in moist environment
- Large & expensive
- Competitive with ESP

Electrostatic Precipitators (ESP)



- *Principle:* Electrodes at high voltage create a corona effect (ionized atmosphere) surrounding them
- This charges the passing particles
- Once charged, particles are subject to a transverse electrostatic force that pulls them toward the collecting plates
- Plates are periodically "rapped" (vibrated) to make the collected particles fall down into a receiver basket

Electrostatic Precipitators (ESP)



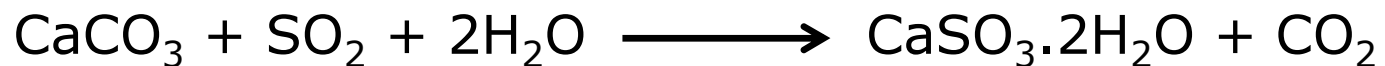
- Removal > 98%, all sizes
- Little pressure drop, low O&M cost, but expensive
- Occupy large space
- Plate area requirement depends on required efficiency

Air Pollution Control - Gases

- Absorption/ Adsorption
- Incineration
- Chemical Reactions
 - Catalysts: e.g. **selective catalytic reduction (SCR)** for NO_x control; NH_3 is injected into boiler flue gas and the mix is passed through a catalyst bed where NO_x is reduced to N_2 :

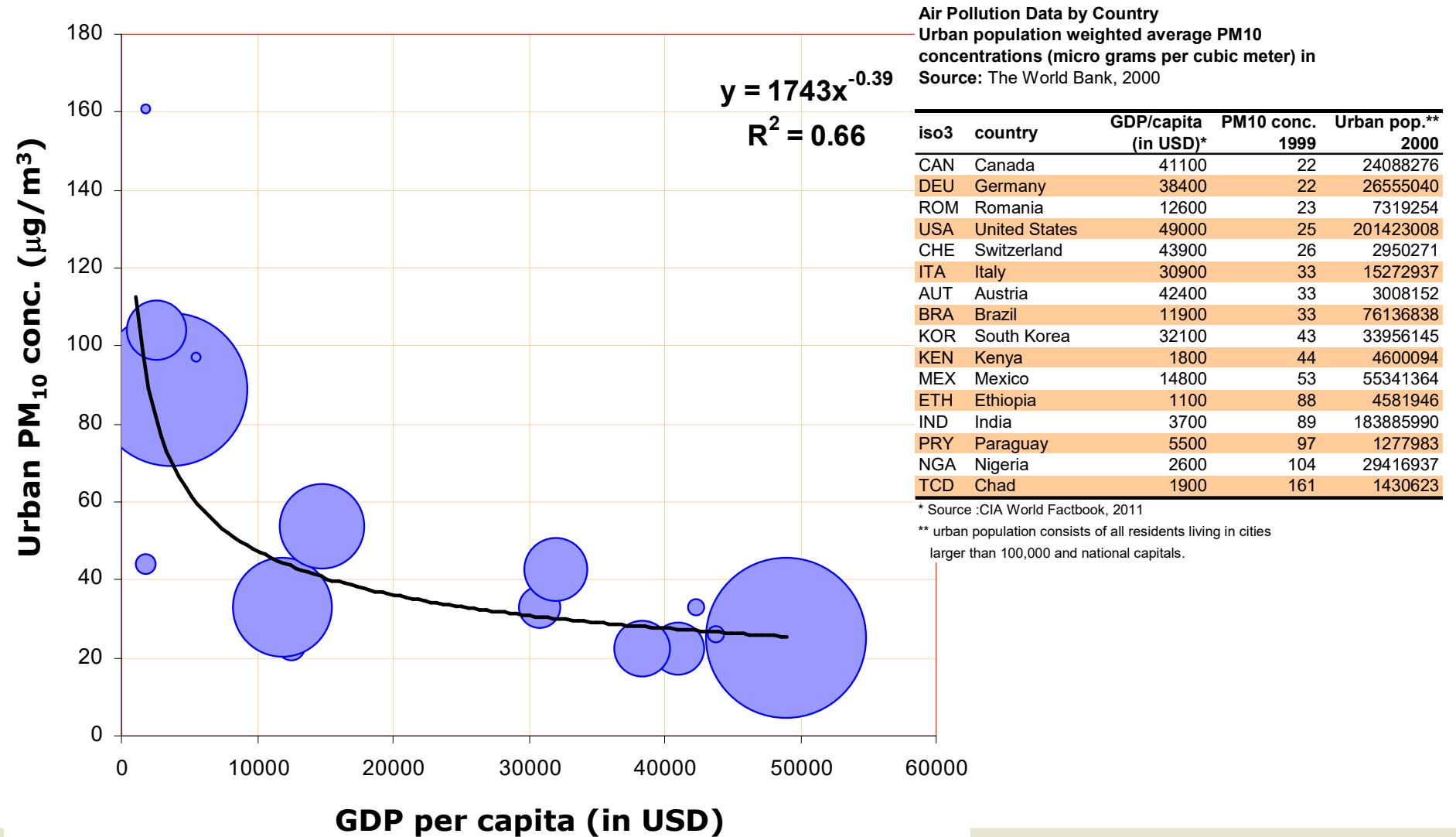


- **Flue gas desulfurisation**: Finely pulverized limestone (CaCO_3) is mixed with water to create a slurry that is sprayed into the flue gas; about 90% SO_2 can be captured:

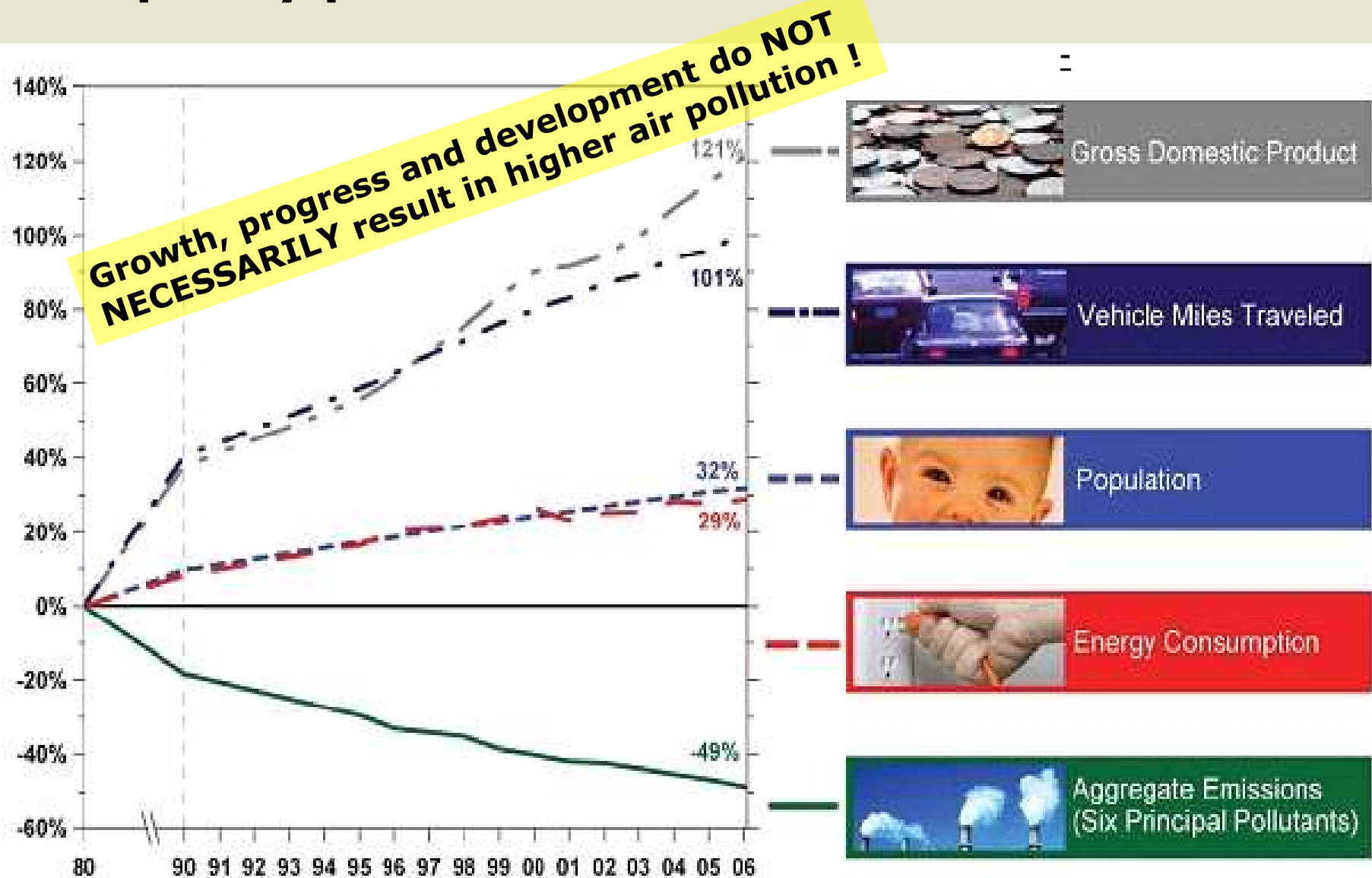


...a food for thought on air pollution problems!

The two 'E's – Economics & Environment



Air quality policies do matter !



**Good luck for
ES 200 end-sem exam !!!**

Thu, 16.Nov, 14:00-17:00
LA101, LA102, LA301

**For ONLY those who missed quiz,
...for a genuine reason**

Re-Quiz !

**Today, 12:45-13:10
CESE, Seminar Hall, 1st Floor**