CS 775: Advanced Computer Graphics

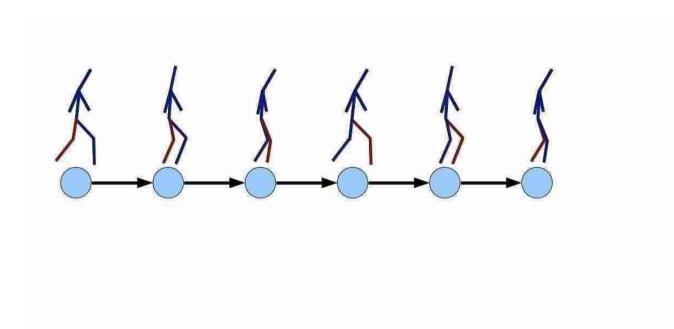
Lecture 21 : Motion Graphs

Motion Graphs

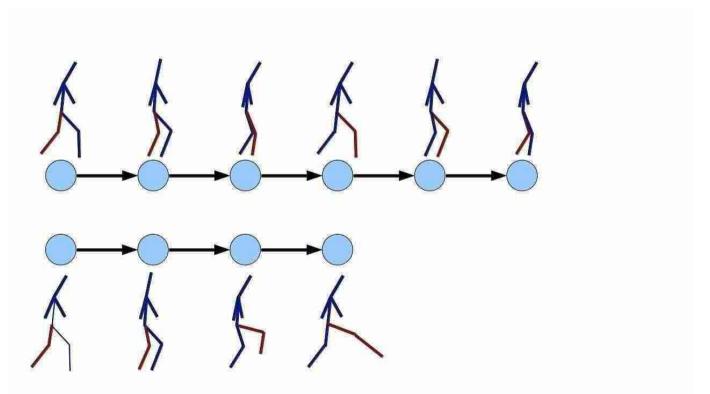
- Given
 - Database of Motion Clips
 - Constraints or a Query
- Problem
 - No single motion in the database will satisfy all the constraints or the query
- Solution
 - Join motions together, to synthesize a new motion and try to satisfy the constraints

Every motion clip is a graph.

Vertex ~ pose, Edge ~ transition frames.

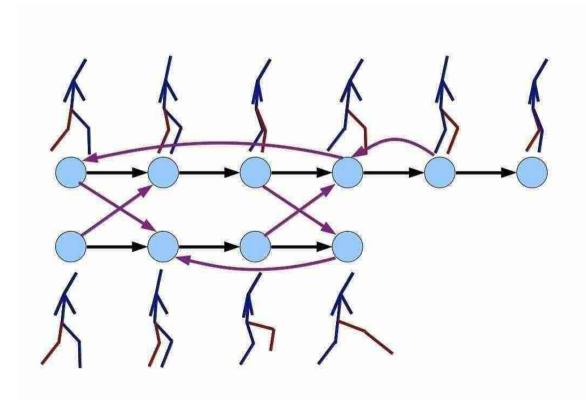


There are many such clips in a motion database.



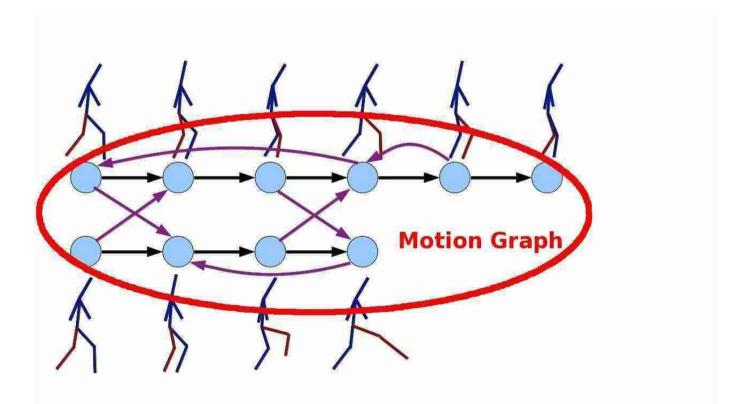
Find similar poses between clips.

Add transitions between them.

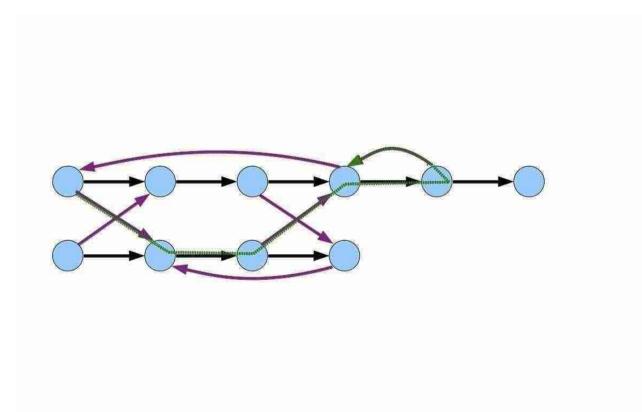


Find similar poses between clips.

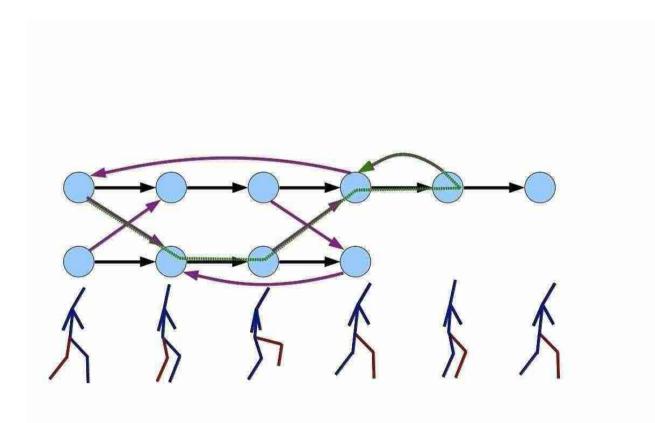
Add transitions between them.



Now any walk on this graph...

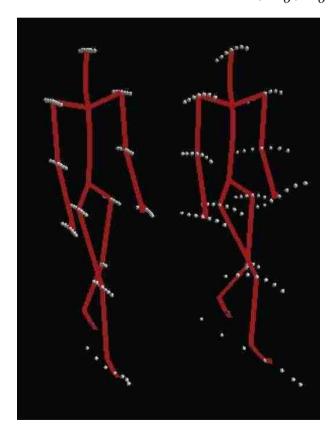


...generates a new motion.



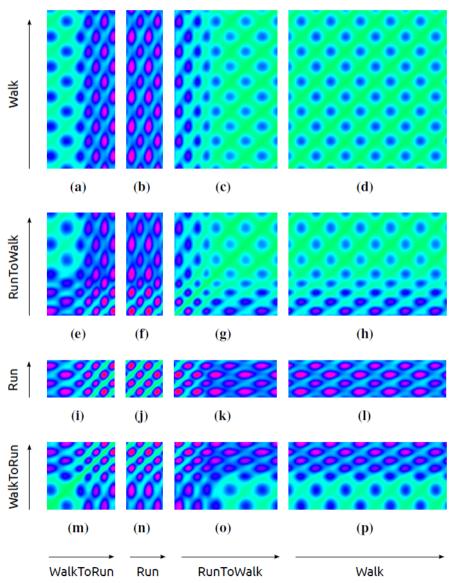
- Similarity between poses across clips
 - Identify compatible coordinate systems.
 - Account for changes in body pose.
 - Account for changes in joint-velocity and acceleration.
 - Relative importance of joints.

$$D(P_{i}, P_{j}) = \min_{\theta, x_{o}, z_{o}} \sum_{k=1}^{n} \omega_{k} \|p_{i}^{k} - T_{\theta, x_{o}, z_{o}} p_{j}^{k}\|^{2}$$



Compute distance over a window of 2L+1 frames centered at P_i and P_j

Constructing Good Quality Motion Graphs for Realistic Human Animation, Limin Zhaog, PhD Thesis, University of Pennsylvania, 2009.



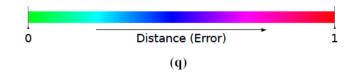


Fig.	Y-axis clip *	X-axis clip*
(a)	Walk	WalkToRun
(b)	Walk	Run
(c)	Walk	RunToWalk
(d)	Walk	Walk
(e)	RunToWalk	WalkToRun
(f)	RunToWalk	Run
(g)	RunToWalk	RunToWalk
(h)	RunToWalk	Walk
(i)	Run	WalkToRun
(j)	Run	Run
(k)	Run	RunToWalk
(1)	Run	Walk
(m)	WalkToRun	WalkToRun
(n)	WalkToRun	Run
(o)	WalkToRun	RunToWalk
(p)	WalkToRun	Walk

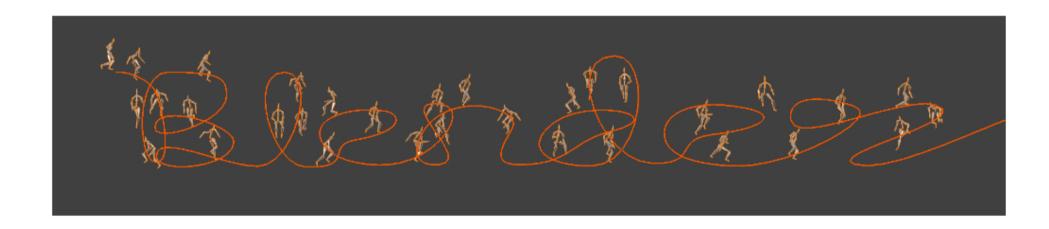
^{*}Note: The lower left corner represents beginning of both clips in each figure.

- Create transitions between similar frames.
- Retain the largest strongly connected component.
- Linear interpolation of translations, SLERP for rotations.



Motion Graphs – Generating Motion

 Follow a path – minimize a "path follow" function during the graph walk.



Motion Graphs – Generating Motion

 Follow a path – minimize a "path follow" function during the graph walk.

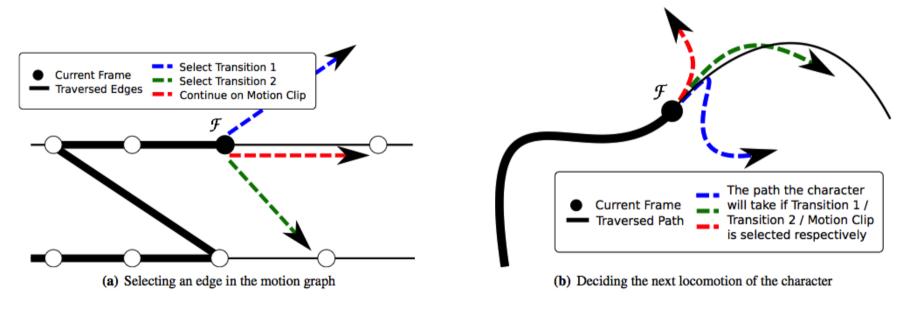


Figure 1: Selecting an edge in the motion graph is equivalent to deciding next locomotion of the character

Motion Graphs – Generating Motion

 Follow a path – minimize a "path follow" function during the graph walk.

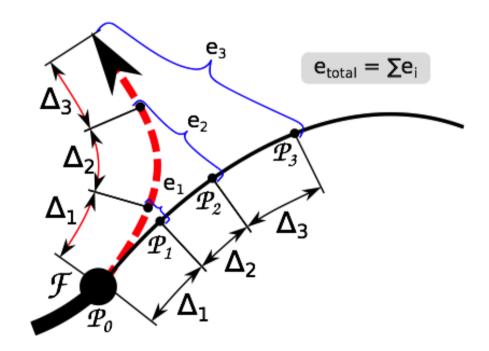
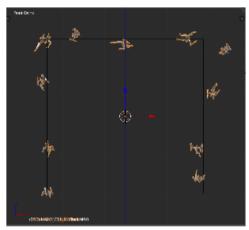
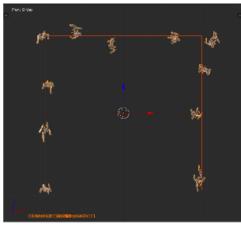


Figure 5: Finding the deviation of motion from path segment

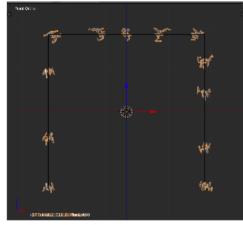
Motion Graphs – Generating Motion



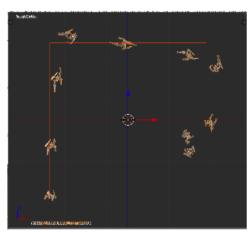
(a) Threshold = 50%, Prediction = 0 frames, No Grouping



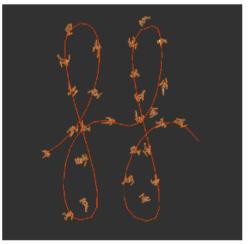
(b) Threshold = 50%, Prediction = 5 frames, No Grouping



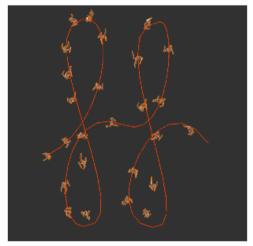
(c) Threshold = 50%, Prediction = 15 frames, No Grouping



(d) Threshold = 50%, Prediction = 15 frames, Inbound and Outbound Grouping

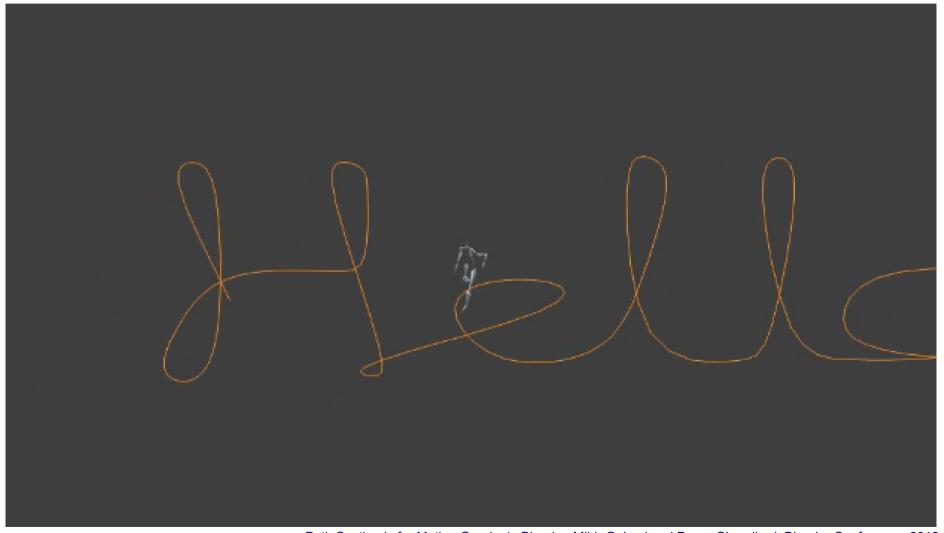


(e) Threshold = 50%, Prediction = 0 frames, Inbound and Outbound Grouping

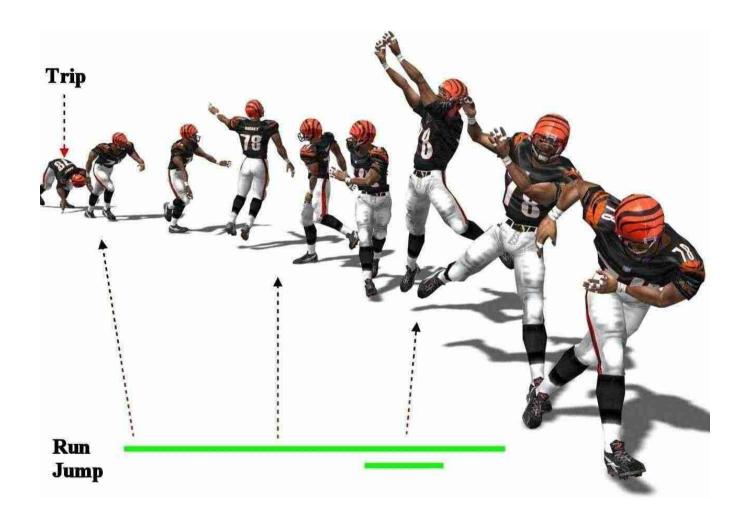


(f) Threshold = 50%, Prediction = 15 frames, Inbound and Outbound Grouping

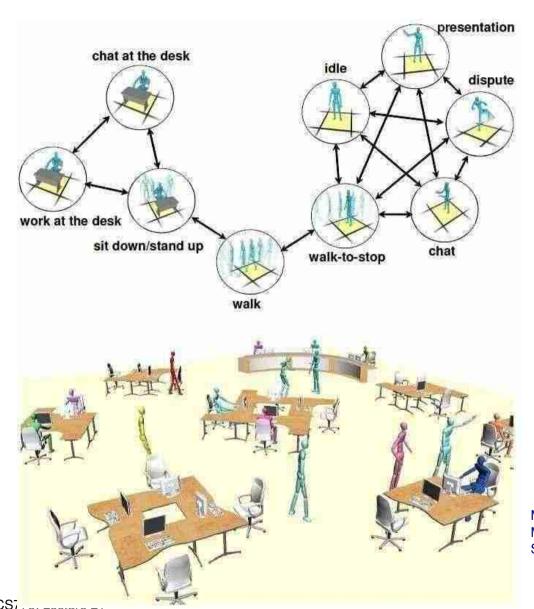
Motion Graphs – Generating Motion



Path Synthesis for Motion Graphs in Blender, Mihir Gokani and Parag Chaudhuri, Blender Conference, 2012 Parag Chaudhuri

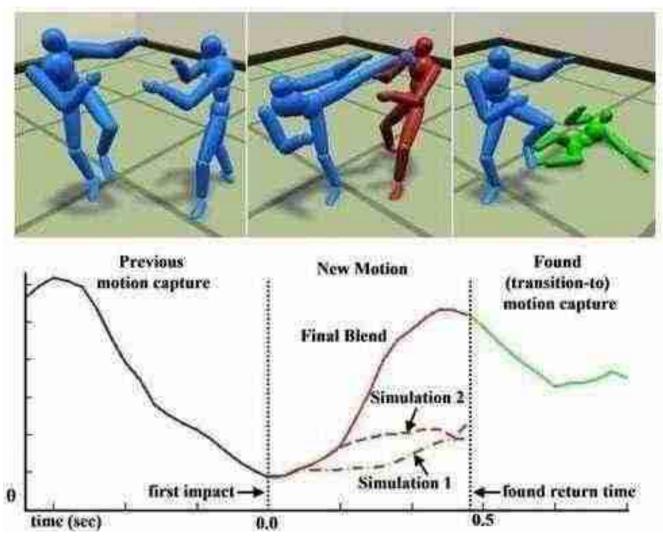


Motion Synthesis from Annotations, Okan Arikan, David Forsyth, James O'Brien, SIGGRAPH 2003

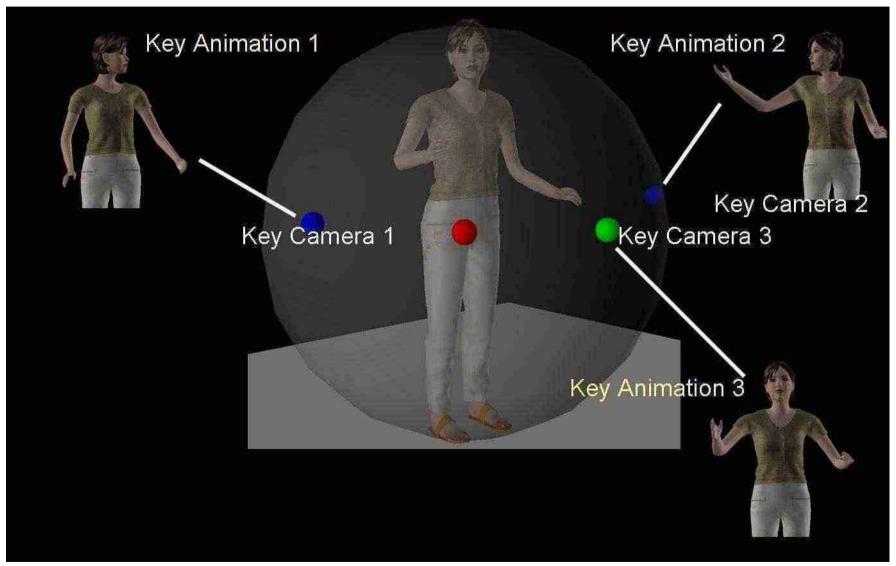


Motion Patches: Building Blocks for Virtual Environments Annotated with Motion Data, Kang Hoon Lee, Myung Geol Choi and Jehee Lee, SIGGRAPH 2006

Parag Chaudhuri



Dynamic Response for Motion Capture Animation, Victor Zordan, Anna Majkowska, Bill Chiu and Matthew Fast, SIGGRAPH 2005



Self Adaptive Animation based on User Perspective, Parag Chaudhuri, George Papagiannakis, Nadia Magnenat-Thalmann, CGI 2008
Parag Chaudhuri