# **Christopher Choi**

541-243-2950 | 
 □ chrischoi1014@gmail.com | 
 in linkedin.com/in/chrisschoi

#### **Education**

#### **Honors Bachelor of Science in Mechanical Engineering**

**Expected June 2028** 

Oregon State University, Corvallis, GPA 3.88

**Relevant Courses**: Mechanics and Strength of Materials, Dynamics, Engineering Graphics & 3D Modeling, Statics, Linear Algebra, Applied Differential Equations, Physics with Calculus, Electrical Fundamentals

## **Experience**

## Soft Robotics Research Intern | Oregon State University

Dec 2024 - Present

- Tested 5+ prototypes for a new type of omnidirectional isovolumetric joint, resulting in negligible force required to configure bend of soft robot
- Developed a high-performance electroadhesive clutch mechanism using acetone and dimethylformamide to integrate isovolumetric joints with electroadhesive clutches for versatility in soft robotics
- Presented research at a Spring Poster Symposium with over 400 attendees, inspiring future soft robotics ideas

## Design/CAD Lead | FIRST Robotics Competition Team 955

Sep 2021 - June 2024

- Designed a robot using Onshape to collect and place cones and purple cubes onto slim poles and boxes using a vision system, awarded World Championship Qualification - 3rd out of 50 teams in Pacific Northwest
- Collaborated with team leads, winning Excellence in Engineering Award 1st out of 34 teams, demonstrating a
  professional approach to the design process
- Managed and delegated tasks to a team of 10+ designers, integration of prototypes, and timely achievement of project deadlines utilizing CAD/3D Modeling in 2 and 1/2 weeks

# **Primary Designer | FIRST Robotics Competition Team 955**

Sep 2021 – June 2024

- Researched and modeled an offseason project to enhance circular-shaped object manipulation, increasing design speed execution by 200% - Ball Indexer: <a href="https://tinyurl.com/BallIndexer">https://tinyurl.com/BallIndexer</a>
- Created a custom drivetrain chassis to overcome potential terrain challenges allowing for adjustable bumper mounting and flexibility - West Coast Drivebase: <a href="https://tinyurl.com/955WCD">https://tinyurl.com/955WCD</a>

# **Projects**

## Robotics Multidirectional Drivetrain | Research Project | Fusion 360/3DPrinting/Prototyping/Arduino

- Primary designer for custom drivetrain allowing for multidirectional, swerve movement, increasing maneuverability
- Connected the Board of Business and VEXU for specific alterations to marketing and design

## Design Workshop & Greenhouse Gutter | Personal Project | Onshape/Prototyping/Solidworks

- Organized and presented 2, 3 hour CAD/Design workshops involving Introduction to Onshape and a Design Principles Workshop for community teams
- Administered a team of 20+ for USDA: Greenhouse Gutter Project to develop a solution for stabilizing greenhouse tarps, eliminating need for manual adjustments by personnel

## Mechanical Greeting Cards | Research Project | Onshape/3DPrinting/Mechanical Design

- Designed and fabricated mechanical greeting cards for K-5 students, inspiring K-5 to engineering/STEM fields
- Inspired 100+ kids in STEM through manipulatives, improving student learning in STEM through hands-on engagement in Corvallis, Greater Albany, and Beaverton school districts

# Robotics Mentoring & Outreach | Personal Project | SolidWorks/3DPrinting/Outreach

- Directed robot demonstrations at 3+ local Corvallis elementary schools, high schools, and community events
- Mentored FTC adopting technical expertise to inspire and benefit robotics community

# **Skills**

CAD: Onshape, Fusion360 (CAD), NX Siemens, SolidWorks

Technical: Manual machining (mill, lathe, etc.), 3D Printing, Prototyping, Mechanical Design

Clubs: Engineering Student Council | Leadership Empowerment & Purpose | VEXU Research | SASE | APASU