

Weekly Review

25/05/21

- **Tasks**

- Run with new action – corner in policy **X** – *Losses still increase*
- Write a stable baselines implementation

- **Problems**

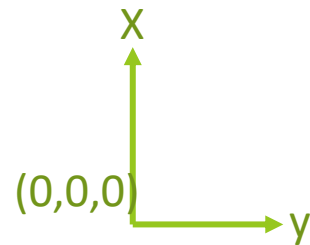
- Learning results unexpected
- Memory gets saturated in Stable Baselines implementation

- **To-Do Items for Next Week**

- Make stable baselines implementation work
- Show code corresponding to learning plots
- Add all hyperparameters used

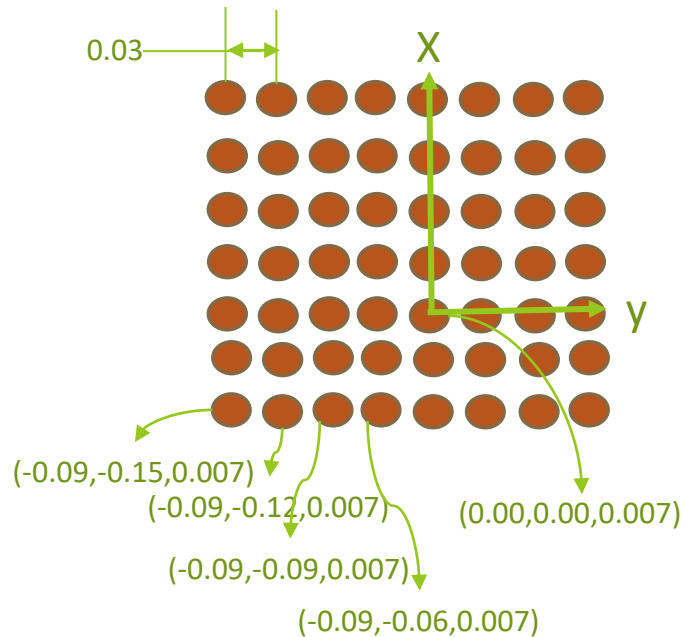
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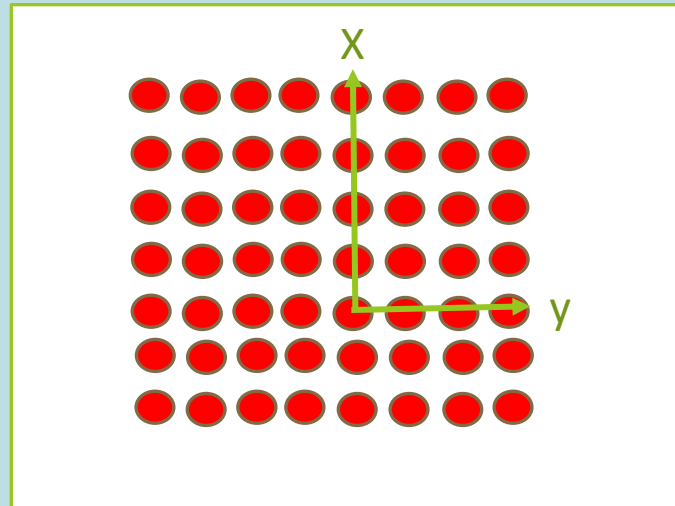
Defined in cloth_corner.xml

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State

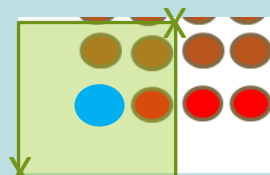
Exp : Cloth_corner.py



Action $[-1, -1, -1]$ to $[1, 1, 1]$ on 1 random corner OR $[X, X, X, X, -1, -1, -1]$ to $[X, X, X, X, 1, 1, 1]$
 Where XXXX is a one hot representation of a corner
 $[1, 0, 0, 0]$ – Corner 1
 $[0, 1, 0, 0]$ – Corner 2
 $[0, 0, 1, 0]$ – Corner 3
 $[0, 0, 0, 1]$ – Corner 4

To environment scale = *0.05
 Force applied =
 proportional to the
 distance to be moved

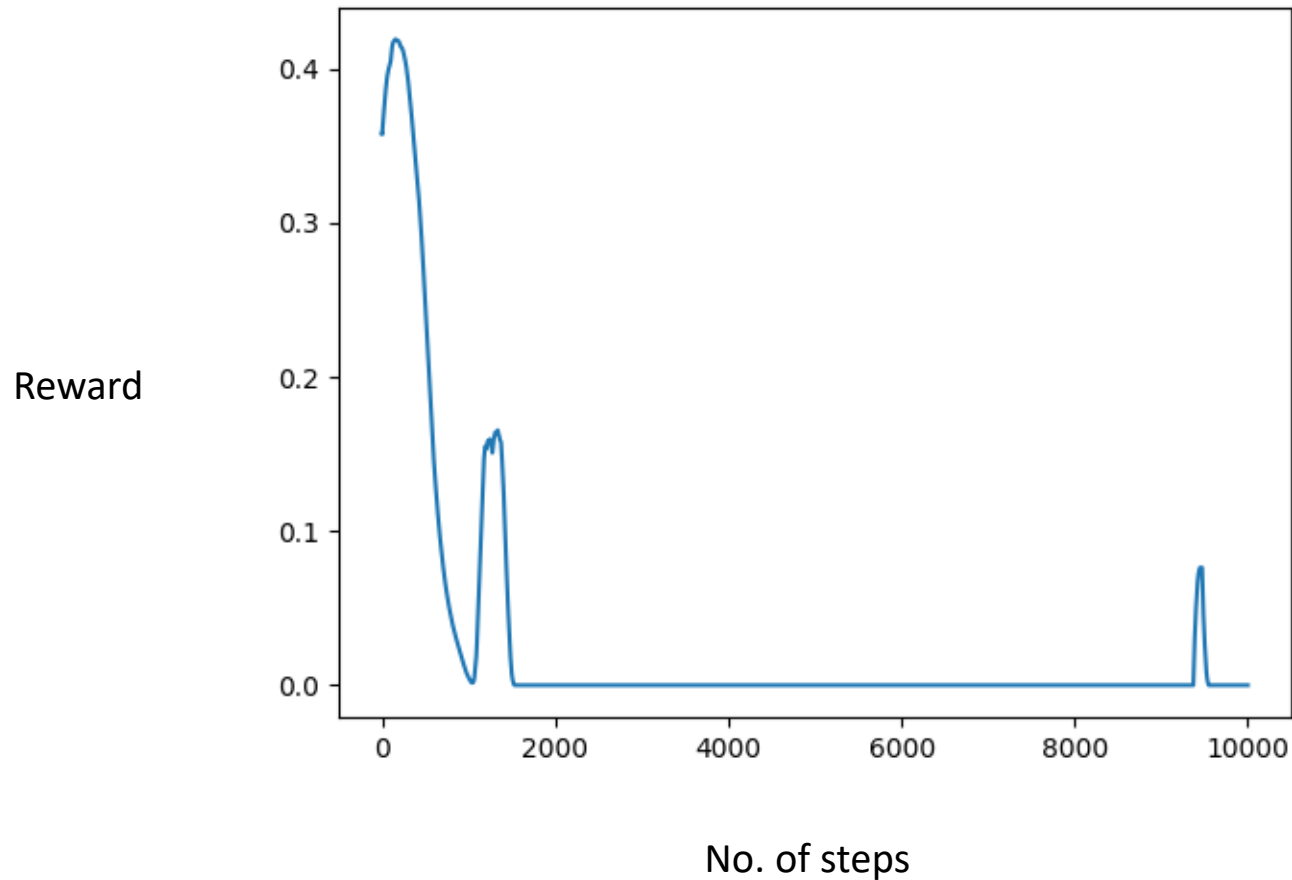
$(-0.05, -0.05)$
 $(0.05, 0.05)$



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1 step = no. of steps in 1 episode / game

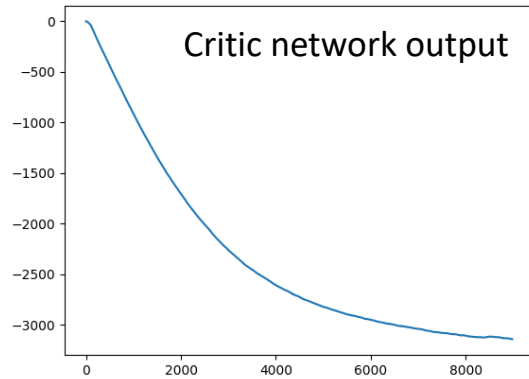
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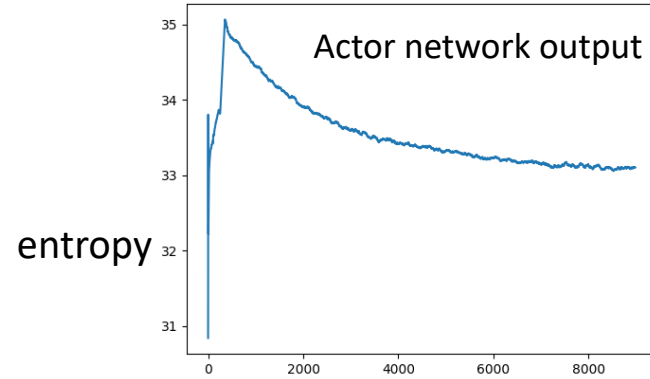
1 step = average value over 1 batch

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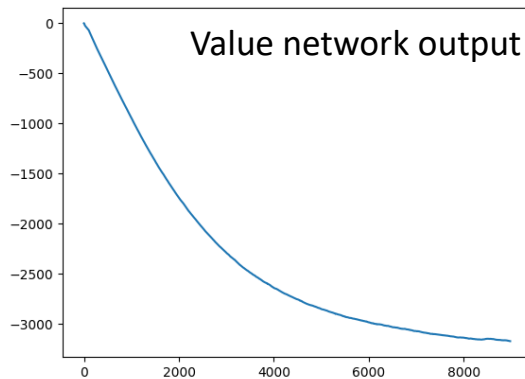
Critic value

No. of steps



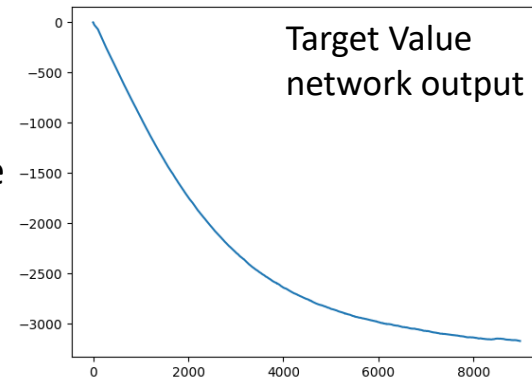
entropy

No. of steps



Value

No. of steps



Target Value

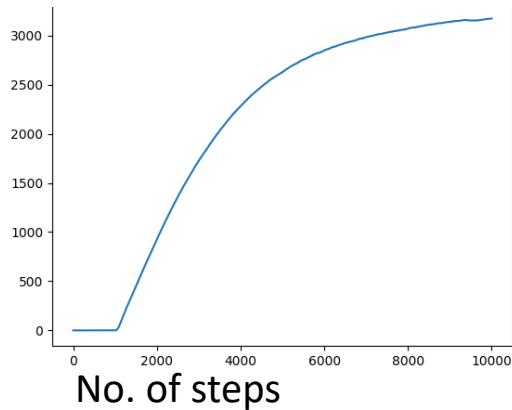
No. of steps

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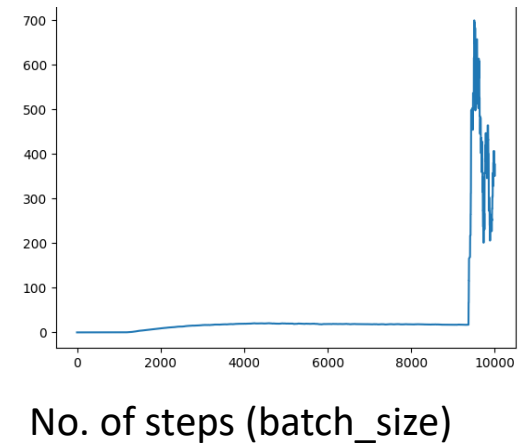
1 step = loss after 1 batch

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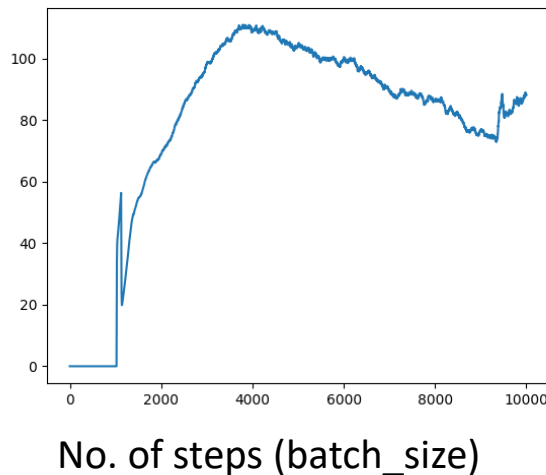
Actor loss



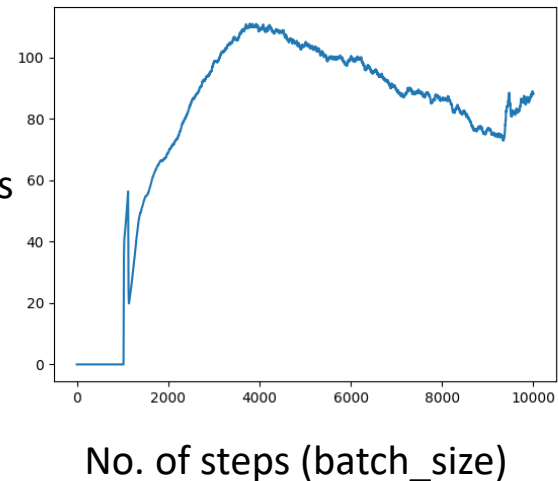
Critic loss



Value loss



Target Value loss

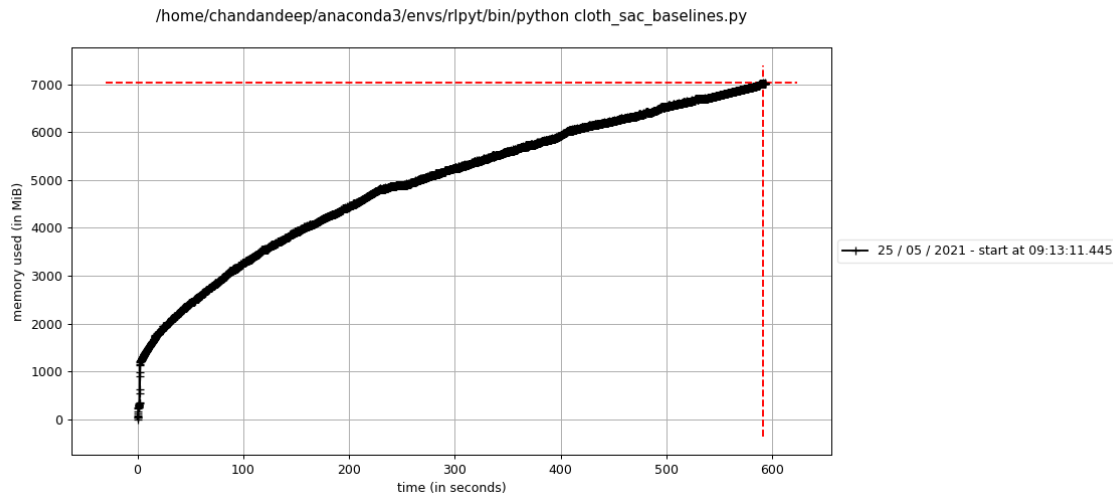


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Stable baselines implementation

- Convert DMControlSuite cloth_corner environment to OpenAI gym environment
- **Memory gets saturated on running**



THANK YOU