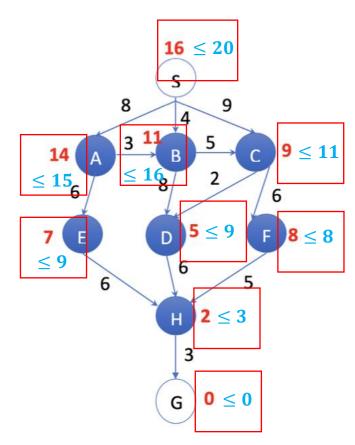
# CS420 ASSIGNMENT 2 SOLUTIONS





(a) Yes, the heuristic is admissible.

## Justification:

- For a heuristic to be admissible, the following must be satisfied:

$$h(n) \le TC^*(n, g)$$

Since all the minimum cost to reach goal state from the current state (shown in light blue) is less than corresponding heuristic value (shown in red) of that state, the heuristic used is said to be admissible.

Node n	Minimum cost to reach goal from $n, TC^*(n, g)$	h(n)
S	20	16
A	15	14
В	16	11
С	11	9
Е	9	7
D	9	5

F	8	8
Н	3	2
G	0	0

(b) No, the heuristic is not consistent.

#### Justification:

- For a heuristic to be consistent, the following must be satisfied:

$$h(n) \le c(n,p) + h(p)$$

- That is, the heuristic value to reach goal state, g from the current state, n is no greater than the step cost of getting to state p plus the heuristic cost of reaching g from p.

Node n	c(n,p) + h(p)	h(n)
S	- c(S,A) + h(A) = 8 + 14 = 22 - c(S,B) + h(B) = 4 + 11 = 15 (<16) 	16

- Since the consistent heuristic must holds for every state and there is a violation, we conclude that the heuristic is not consistent.

## (c) Part 1: DFS Algorithm

- Final Solution Path  $: S \rightarrow A \rightarrow E \rightarrow H \rightarrow G$ - Cost of Solution Path : 8 + 6 + 6 + 3 = 23

- Open list's data structure : **Stack** 

Step#	Open List (Stack)	Pop	Nodes to Add
1	S	S	$C^s, B^s, A^s$
2	$A^s, B^s, C^s$	$A^{S}$	$E^A$
3	$E^A, B^S, C^S$	$E^A$	$H^E$
4	$H^E, B^s, C^s$	$H^E$	$G^H$
5	$G^H, B^S, C^S$	$G^H$	Termination

#### Part 2 : A\* Algorithm

Final Solution Path
 Cost of Solution Path
 Open list's data structure
 S → C → D → H → G
 9 + 2 + 6 + 3 = 20
 Priority Queue

Step#	Open List (Priority Queue)	Dequeue	Nodes to Add
1	$S_{16}$	$S_{16}$	$A_{22}^S, B_{15}^S, C_{18}^S$
2	$B_{15}^S, C_{18}^S, A_{22}^S$	$B_{15}^{S}$	$D_{17}^B, C_{18}^B$
			* Do not replace C in open list
3	$D_{17}^B, C_{18}^S, A_{22}^S$	$D_{17}^{B}$	$H_{20}^D$
4	$C_{18}^S, H_{20}^D, A_{22}^S$	$\mathcal{C}_{18}^{S}$	$D_{16}^{\mathcal{C}}, F_{23}^{\mathcal{C}}$
			* Re-open D in close list
5	$D_{16}^{C}, H_{20}^{D}, A_{22}^{S}, F_{23}^{C}$	$D_{16}^{C}$	$H_{19}^D$
			* Replace H in open list
6	$H_{19}^D, A_{22}^S, F_{23}^C$	$H_{19}^{D}$	$G_{20}^H$
7	$G_{20}^H, A_{22}^S, F_{23}^C$	$G_{20}^H$	Terminated

- The priority of each state, n is based on the f-cost, f(n) which is defined as:

$$f(n) = g(n) + h(n)$$

That is, sum of g(n), cost from start state,  $s_0$  to current state, n, and h(n), heuristic from current state, n to goal state, g.

- Note: Since the heuristic is not consistent, re-opening of closed nodes is possible.

# QUESTION 2

## Clarification of term(s):

- 'First' refers to the integer at the front(leftmost element) of a list.

#### Part 1

## I. State representation

## Describe specifically what is a state in this problem:

- Given N discs, a state could be any legal combination (a bigger disc should never be put on top of a smaller disc) of discs on top of each of the three towers.

# How you would store it in a computer using a data structure, and justify the correctness of your state representation:

One of the possible data structures for this state representation would be using three lists, storing the information of which tower is having which discs (of specific size) being stacked appropriately on it. Since we have N discs of different sizes, each can be assigned with an integer value from 1,2...,N corresponding to smallest to biggest disc. This allows us to represent each tower as an ordered list of integers. For example, the start state,  $s_0$  would be ([1,2...,N], [], []).

#### II. Actions

- Here, an action X<sub>y</sub>, can be defined as **popping** the first integer(i.e., disc) from a list, X (i.e., tower) and **pushing** it to the front of another list, Y.
- An exhausted list of all possible actions for this search problem would be:

Operators, 
$$A = \{A_B, A_C, B_A, B_C, C_A, C_B\}$$

- For an action to be valid at a given state (not all actions are valid at a given each state):
  - The integer value being pushed to the front of another list must be strictly smaller than the integer currently located at the front of the stack be pushed to.
  - Suppose a list has no integer currently, then any of first integer from other lists is allowed to be popped and pushed to it.

#### III. Cost of different actions

- Cost is 1 for all actions,  $X_y \in A$  (uniform cost).

#### IV. Successor State (for each action)

- Suppose that an action,  $X_y$  is valid at a given state, s based on the constraints defined in (2) then the successor state, s' is defined as:
  - Let first integer of list X be k.
  - Then s' would be the state s, with k being popped from the front of list X, and pushed to the front of list Y.

## V. Objective

- Find the least cost path (a **sequence** of **operator** applied on **each intermediate states**) from the start state,  $s_0 = ([1,2...,N],[],[])$  to the goal state,  $s_g = ([],[],[1,2...,N])$ .

#### Part 2

- For a heuristic to be admissible, the following must be satisfied:

$$h(n) \leq TC^*(n, g)$$

- Now, let h(n) = 2 \* (number of discs on tower C that is either smaller than discs on A or B) + (Total number of discs on tower A and B)
- Justification of admissibility:
  - For any state, we have p discs on A, q discs on B, and r discs on C.
  - We also know the goal state is to have all discs being stacked appropriately (increasing size) on C.
  - Before moving any discs from A or B to C, we must first remove those discs with smaller size than those on A and B first (let this be m discs), this takes m actions.
  - Next, we perform relaxation on the original problem:
    - (1) Now we are allowed to remove any disc from any of the towers instead of only the top disc (but ONLY allowed to push to the top of the target tower) at any state.
    - (2) We have one extra tower, T and this tower is allowed hold any discs without considering the size.
  - With this relaxation, now we can remove the m discs on C to T, then always select the next largest discs from any of the A, B and T and place them in correct order on top C, this takes (m + p + q) actions.
  - Hence, total cost of the relaxed problem = m + (m + p + q) = 2 \* m + p + q
  - By the definition of original problem, this heuristic is trivially admissible as the total cost is lower bounded by the heuristic function.

#### Part 3

- The priority of each state, n is based on the f-cost, f(n) which is defined as:

$$f(n) = g(n) + h(n)$$

That is,  $sum ext{ of } g(n)$ , cost from start state,  $s_0$  to current state, n, and h(n), heuristic from current state, n to goal state, g.

- Let the start state,  $S0_3$  be ([1,2,3],[],[]) and f(S0) = 0 + (2\*0 + 3) = 3
- Let the next valid successor states be:
- $-S1_4^{S0}$  (after applying operator A<sub>B</sub> on S0): ([2,3],[1],[]) & f-cost = 1 + (2\*0 + 3) = 4
- $-S2_{50}^{50}$  (after applying operator A<sub>C</sub> on S0): ([2,3],[],[1]) & f-cost = 1 + (2\*1 + 2) = 5
- $-S3_{6}^{S1}$  (after applying operator A<sub>C</sub> on S1): ([3],[1],[2]) & f-cost = 2 + (2\*1 + 2) = 6
- $-S0_5^{S1}$  (after applying operator  $B_A$  on S1): ([1,2,3],[],[]) & f-cost = 2 + (2\*0 + 3) = 5
- $-S2_{6}^{S1}$  (after applying operator B<sub>C</sub> on S1): ([2,3],[],[1]) & f-cost = 2 + (2\*1 + 2) = 6
- $-S4_6^{S2}$  (after applying operator A<sub>B</sub> on S2): ([3],[2],[1]) & f-cost = 2 + (2\*1 + 2) = 6
- $-S0_5^{S2}$  (after applying operator  $C_A$  on S2): ([1,2,3],[],[]) & f-cost = 2 + (2\*0 + 3) = 5
- $-S1_{50}^{S0}$  (after applying operator  $C_B$  on S2): ([2,3],[1],[]) & f-cost = 2 + (2\*0 + 3) = 5

...

First three steps of A\*star search in table representation:

Step #	Open List	Dequeue	Nodes to Add
	(Priority Queue)		
1	S0 <sub>3</sub>	S0 <sub>3</sub>	$S1_4^{S0}, S2_5^{S0}$
2	$S1_4^{S0}, S2_5^{S0}$	$S1_{4}^{S0}$	$S3_{6}^{S1}, S0_{5}^{S1}, S2_{6}^{S1}$
		-	* Do not re-open S0 in the close list
			* Do not replace S2 in the open list
3	$S2_{5}^{S0}, S3_{6}^{S1}$	$S2_{5}^{S0}$	$S4_{6}^{S2}, S0_{5}^{S2}, S1_{5}^{S0}$
			* Do not re-open S0 in the close list
			* Do not re-open S1 in the close list
4	$S4_{6}^{S2}, S3_{6}^{S1}$	S4 <sup>S2</sup>	

## QUESTION 3

## Part (a)

The values for different states  $V^t$  at iteration t are given by:

3	1.564	1.710	1.842	Food
2	1.451	blocked	1.270	Tiger
1	1.327	1.231	1.162	0.844
	1	2	3	4

Computation of values of different states  $V^{t+1}$  using Bellman Optimal Equation:

(1) 
$$Q^{t+1}(s, a) = \sum_{s'} P(s'|s, a) [R(s, a, s') + \gamma V^{t}(s')]$$
  
(2)  $V^{t+1}(s) = \max_{a} Q^{t+1}(s, a)$ 

The available actions at each state are = {N,S,E,W}, each representing N: North, S: South, E: East, W: West

```
For state (1,1):
Q^{t+1}((1,1),N)
= 0.7 * (-0.0025 + 0.95 * 1.451)
  + 0.15 * (-0.0025 + 0.95 * 1.327)
  + 0.15 * (-0.0025 + 0.95 * 1.231)
= 1.3269
Q^{t+1}((1,1),S)
= 0.7 * (-0.0025 + 0.95 * 1.327)
  + 0.15 * (-0.0025 + 0.95 * 1.327)
  + 0.15 * (-0.0025 + 0.95 * 1.231)
= 1.2445
Q^{t+1}((1,1), W)
= 0.7 * (-0.0025 + 0.95 * 1.327)
  + 0.15 * (-0.0025 + 0.95 * 1.451)
  + 0.15 * (-0.0025 + 0.95 * 1.327)
= 1.2758
Q^{t+1}((1,1),E)
= 0.7 * (-0.0025 + 0.95 * 1.231)
  + 0.15 * (-0.0025 + 0.95 * 1.451)
  + 0.15 * (-0.0025 + 0.95 * 1.327)
= 1.2120
V^{t+1}((1,1)) = 1.3269
For state (1,2):
Q^{t+1}((1,2),N)
= 0.7 * (-0.0025 + 0.95 * 1.231)
 + 0.15 * (-0.0025 + 0.95 * 1.327)
  + 0.15 * (-0.0025 + 0.95 * 1.162)
```

= 1.1708

```
Q^{t+1}((1,2),S)
= 0.7 * (-0.0025 + 0.95 * 1.231)
 + 0.15 * (-0.0025 + 0.95 * 1.327)
  + 0.15 * (-0.0025 + 0.95 * 1.162)
= 1.1708
Q^{t+1}((1,2), W)
= 0.7 * (-0.0025 + 0.95 * 1.327)
 + 0.15 * (-0.0025 + 0.95 * 1.231)
  + 0.15 * (-0.0025 + 0.95 * 1.231)
= 1.2308
Q^{t+1}((1,2),E)
= 0.7 * (-0.0025 + 0.95 * 1.162)
 + 0.15 * (-0.0025 + 0.95 * 1.231)
 + 0.15 * (-0.0025 + 0.95 * 1.231)
= 1.1211
V^{t+1}((1,2)) = 1.2308
For state (1,3):
Q^{t+1}((1,3),N)
= 0.7 * (-0.0025 + 0.95 * 1.270)
  + 0.15 * (-0.0025 + 0.95 * 1.231)
  + 0.15 * (-0.0025 + 0.95 * 0.844)
= 1.1377
Q^{t+1}((1,3),S)
= 0.7 * (-0.0025 + 0.95 * 1.162)
  + 0.15 * (-0.0025 + 0.95 * 1.231)
  + 0.15 * (-0.0025 + 0.95 * 0.844)
= 1.0659
Q^{t+1}((1,3),W)
= 0.7 * (-0.0025 + 0.95 * 1.231)
  + 0.15 * (-0.0025 + 0.95 * 1.270)
  + 0.15 * (-0.0025 + 0.95 * 1.162)
= 1.1627
Q^{t+1}((1,3),E)
= 0.7 * (-0.0025 + 0.95 * 0.844)
  + 0.15 * (-0.0025 + 0.95 * 1.270)
  + 0.15 * (-0.0025 + 0.95 * 1.162)
= 0.9053
V^{t+1}((1,3)) = 1.1627
For state (1,4):
Q^{t+1}((1,4),N)
= 0.7 * (-1 + 0)
  + 0.15 * (-0.0025 + 0.95 * 1.162)
  + 0.15 * (-0.0025 + 0.95 * 0.844)
=-0.4149
```

```
Q^{t+1}((1,4),S)
= 0.7 * (-0.0025 + 0.95 * 0.844)
  + 0.15 * (-0.0025 + 0.95 * 1.162)
  + 0.15 * (-0.0025 + 0.95 * 0.844)
= 0.8446
Q^{t+1}((1,4), W)
= 0.7 * (-0.0025 + 0.95 * 1.162)
  +0.15*(-1+0)
  + 0.15 * (-0.0025 + 0.95 * 0.844)
= 0.7409
Q^{t+1}((1,4), E)
= 0.7 * (-0.0025 + 0.95 * 0.844)
 +0.15*(-1+0)
 + 0.15 * (-0.0025 + 0.95 * 0.844)
= 0.5294
V^{t+1}((1,4)) = 0.8466
For state (2,1):
Q^{t+1}((2,1),N)
= 0.7 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.451)
  + 0.15 * (-0.0025 + 0.95 * 1.451)
= 1.4511
Q^{t+1}((2,1),S)
= 0.7 * (-0.0025 + 0.95 * 1.327)
  + 0.15 * (-0.0025 + 0.95 * 1.451)
  + 0.15 * (-0.0025 + 0.95 * 1.451)
= 1.2935
Q^{t+1}((2,1), W)
= 0.7 * (-0.0025 + 0.95 * 1.451)
  + 0.15 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.327)
= 1.3744
Q^{t+1}((2,1),E)
= 0.7 * (-0.0025 + 0.95 * 1.451)
  + 0.15 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.327)
= 1.3744
V^{t+1}((2,1)) = 1.4511
For state (2,3):
Q^{t+1}((2,3),N)
= 0.7 * (-0.0025 + 0.95 * 1.842)
  + 0.15 * (-0.0025 + 0.95 * 1.270)
  +0.15*(-1+0)
= 1.2538
```

```
Q^{t+1}((2,3),S)
= 0.7 * (-0.0025 + 0.95 * 1.162)
 + 0.15 * (-0.0025 + 0.95 * 1.270)
  +0.15*(-1+0)
= 0.8016
Q^{t+1}((2,3), W)
= 0.7 * (-0.0025 + 0.95 * 1.270)
 + 0.15 * (-0.0025 + 0.95 * 1.842)
  + 0.15 * (-0.0025 + 0.95 * 1.162)
= 1.2701
Q^{t+1}((2,3),E)
= 0.7 * (-1 + 0)
 + 0.15 * (-0.0025 + 0.95 * 1.842)
 + 0.15 * (-0.0025 + 0.95 * 1.162)
=-0.2727
V^{t+1}((2,3)) = 1.2701
For state (3,1):
Q^{t+1}((3,1),N)
= 0.7 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.710)
= 1.5041
Q^{t+1}((3,1),S)
= 0.7 * (-0.0025 + 0.95 * 1.451)
  + 0.15 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.710)
= 1.4290
Q^{t+1}((3,1), W)
= 0.7 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.451)
= 1.4672
Q^{t+1}((3,1), E)
= 0.7 * (-0.0025 + 0.95 * 1.710)
  + 0.15 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.451)
= 1.5643
V^{t+1}((3,1)) = 1.5643
For state (3,2):
Q^{t+1}((3,2),N)
= 0.7 * (-0.0025 + 0.95 * 1.710)
 + 0.15 * (-0.0025 + 0.95 * 1.564)
  + 0.15 * (-0.0025 + 0.95 * 1.842)
```

= 1.6200

$$\begin{split} &Q^{t+1}((3,2),S) \\ &= 0.7*(-0.0025 + 0.95*1.710) \\ &+ 0.15*(-0.0025 + 0.95*1.564) \\ &+ 0.15*(-0.0025 + 0.95*1.842) \\ &= 1.6200 \\ &Q^{t+1}((3,2),W) \\ &= 0.7*(-0.0025 + 0.95*1.564) \\ &+ 0.15*(-0.0025 + 0.95*1.710) \\ &+ 0.15*(-0.0025 + 0.95*1.710) \\ &+ 0.15*(-0.0025 + 0.95*1.710) \\ &= 1.5249 \\ &Q^{t+1}((3,2),E) \\ &= 0.7*(-0.0025 + 0.95*1.710) \\ &+ 0.15*(-0.0025 + 0.95*1.710) \\ &+ 0.15*(-0.0025 + 0.95*1.710) \\ &= 1.7098 \\ &V^{t+1}((3,2)) = 1.7098 \\ &\textbf{For state (3,3):} \\ &Q^{t+1}((3,3),N) \\ &= 0.7*(-0.0025 + 0.95*1.842) \\ &+ 0.15*(-0.0025 + 0.95*1.710) \\ &+ 0.15*(2+0) \\ &= 1.7665 \\ &Q^{t+1}((3,3),S) \\ &= 0.7*(-0.0025 + 0.95*1.270) \\ &+ 0.15*(2+0) \\ &= 1.3861 \\ &Q^{t+1}((3,3),W) \\ &= 0.7*(-0.0025 + 0.95*1.710) \\ &+ 0.15*(-0.0025 + 0.95*1.710) \\ &+ 0.15*(-0.0025 + 0.95*1.270) \\ &= 1.5781 \\ &Q^{t+1}((3,3),E) \\ &= 0.7*(2+0) \\ &+ 0.15*(-0.0025 + 0.95*1.270) \\ &= 1.8427 \\ &V^{t+1}((3,3)) = 1.8427 \\ \end{split}$$

Hence, the numerical answer for each state of  $V^{t+1}$  is summarized as below:

3	1.5643	1.7098	1.8427	Food
2	1.4511	blocked	1.2701	Tiger
1	1.3269	1.2308	1.1627	0.8446
	1	2	3	4

## Part (b)

Optimal policy is chosen by:

 $\pi^{t+1}(s) = \arg\max_{a \in \{N,S,W,S\}} Q^{t+1}(s,a)$ , which gives the best action (of that state) that maximize the expected utility over all states.

## For state (1,1):

$$\pi^{t+1}((1,1)) = \arg \max_{a \in \{N,S,W,S\}} Q^{t+1}((1,1),a)$$

According to computation of  $Q^{t+1}((1,1), a)$ ,  $\forall a \in \{N, S, W, S\}$  in part (a), the action to be chosen for (1,1) should be N (North), corresponding to  $V^{t+1}((1,1)) = 1.3269$ .

## For state (1,2):

$$\pi^{t+1}((1,2)) = \arg\max_{a \in \{N,S,W,S\}} Q^{t+1}((1,2),a)$$

According to computation of  $Q^{t+1}((1,2), a)$ ,  $\forall a \in \{N, S, W, S\}$  in part (a), the action to be chosen for (1,2) should be W(West), corresponding to  $V^{t+1}((1,2)) = 1$ . 2308.

## For state (1,3):

$$\pi^{t+1}((1,3)) = \arg \max_{\alpha \in \{N,S,W,S\}} Q^{t+1}((1,3),\alpha)$$

According to computation of  $Q^{t+1}((1,3), a)$ ,  $\forall a \in \{N, S, W, S\}$  in part (a), the action to be chosen for (1,3) should be W (West), corresponding to  $V^{t+1}((1,3)) = 1.1627$ .

# For state (1,4):

$$\pi^{t+1}((1,4)) = \arg \max_{a \in \{N,S,W,S\}} Q^{t+1}((1,4),a)$$

According to computation of  $Q^{t+1}((1,4), a)$ ,  $\forall a \in \{N, S, W, S\}$  in part (a), the action to be chosen for (1,4) should be S (South), corresponding to  $V^{t+1}((1,4)) = 0.8466$ .

#### For state (2,1):

$$\pi^{t+1}((2,1)) = \arg\max_{a \in \{N,S,W,S\}} Q^{t+1}((2,1),a)$$

According to computation of  $Q^{t+1}((2,1),a)$ ,  $\forall a \in \{N,S,W,S\}$  in part (a), the action to be chosen for (2,1) should be N (North), corresponding to  $V^{t+1}((2,1)) = 1.4511$ .

## For state (2,3):

$$\pi^{t+1}((2,3)) = \arg \max_{a \in \{N,S,W,S\}} Q^{t+1}((2,3),a)$$

According to computation of  $Q^{t+1}((2,3),a)$ ,  $\forall a \in \{N,S,W,S\}$  in part (a), the action to be chosen for (2,3) should be W (West), corresponding to  $V^{t+1}((2,3)) = 1.2701$ .

## For state (3,1):

$$\pi^{t+1}((3,1)) = \arg \max_{\alpha \in \{N,S,W,S\}} Q^{t+1}((3,1),\alpha)$$

According to computation of  $Q^{t+1}((3,1),a), \forall a \in \{N,S,W,S\}$  in part (a), the action to be chosen for (3,1) should be E (East), corresponding to  $V^{t+1}((3,1)) = 1.5643$ .

#### For state (3,2):

$$\pi^{t+1}((3,2)) = \arg \max_{a \in \{N,S,W,S\}} Q^{t+1}((3,2), a)$$

According to computation of  $Q^{t+1}((3,2), a)$ ,  $\forall a \in \{N, S, W, S\}$  in part (a), the action to be chosen for (3,2) should be E(East), corresponding to  $V^{t+1}((3,2)) = 1.7098$ .

#### For state (3,3):

(9) 
$$\pi^{t+1}((3,3)) = \arg \max_{a \in \{N,S,W,S\}} Q^{t+1}((3,3),a)$$

According to computation of  $Q^{t+1}((3,3), a), \forall a \in \{N, S, W, S\}$  in part (a), the action to be chosen for (3,3) should be E(East), corresponding to  $V^{t+1}((3,3)) = 1.8427$ .

Hence, the final policy is summarized as follows:

3	East	East	East	Food
2	North	blocked	West	Tiger
1	North	West	West	South
	1	2	3	4

# QUESTION 4

## Part (a)

```
[8] # Import packages
import numpy as np
import gym
import random
import matplotlib.pyplot as plt
import seaborn as an
wmatplotlib inline
 [10] # Create the Frozen Lake Environmer
env = gym.make("FrozenLake%x8-v0")
env.render()
[11] # Determine state space
   action_size = env.action_space.n
   print("Action size: ", action_size)
             # Create Q-table
qtable = np.zeros((state_size, action_size))
qtable_history = (]
score_history = (]
print("Table shape: ", qtable.shape)
```

- Shows the size of the state space, action space
- Shows the appropriate data structure Q-Table

```
[12] # Hyperparameters
          gamma = 0.9  # Discount factor
total episodes = 250000  # Total episodes
learning_rate = 0.8  # Learning rate
max_steps = 400  # Max steps per episode = action_size * state_size * 2
          # Exploration parameters
epslion = 1.0  # Exploration rate
max_epslion = 1.0  # Exploration probability at start
min_epslion = 0.001  # Minimum exploration probability
decay_rate = 0.00005  # Exponential decay rate for exploration prob
```

Set the hyperparameters for Q-learning, and discount factor to 0.9

```
[13] # List of rewards
rewards = []
           Run the Q-Learning with pre-defined number of episodes
or episode in range(total_episodes);
for episode in range(10000);
              # Reset the environment in a new episode state = env.reset()
              step = 0
              done = False
              total_rewards = 0
                    # Choose an action, a in the current world state
# Get a randomized number
exp_exp_tradeoff = random.uniform(0, 1)
                    # If this number > greater than epsilon : exploitation (taking the biggest 0 value for this state)
if exp_exp_tradeoff > epsilon:
    action = np.argmax(qtable[state,:])
                        Else doing a random choice : exploration
                     else:
    action = env.action_space.sample()
                     # Take the action (a) and observe the outcome sta
new_state, reward, done, info = env.step(action)
                                                                                               state(s') and reward (r)
                    # Update Q(s,a):= Q(s,a) + lr [R(s,a) + gamma * max Q(s',a') - Q(s,a)]
qtable[state, action] = qtable[state, action] + learning_rate * (reward + gamma * np.max(qtable[new_state, :]) - qtable[state, action])
                     # Add the reward to total_rewards of this episode
total_rewards += reward
                    # If done (we're dead) : finish episode
if done == True:
break
              # Reduce epsilon after each iteration : exploitation over exploration
epsilon = min_epsilon + (max_epsilon - min_epsilon)*np.exp(-decay_rate*episode)
               # Append the reward of this eposide to reward list
rewards.append(total_rewards)
```

- Code that implements Q-learning
- (For Part b) Keep track of total accumulated reward for each episode (episode return), assigned to a list, rewards

#### Part (b)

Above shows the total accumulated reward for each episode

```
rint (Theoard Over time: " + str(sum(rewards)/total_episodes))
print(gtable)

Reward over time: 0.33144

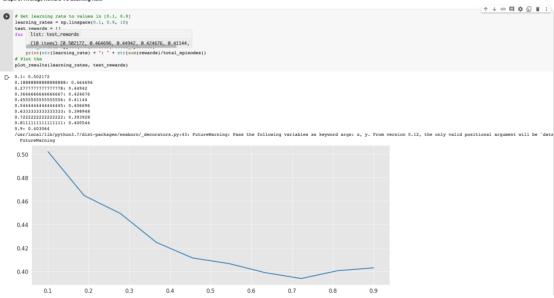
[(1.32522220-04 4.31842840-23 1.32473346-04 7.97357168-05)]
[(1.32522220-04 4.31842840-23 1.32473346-04 7.97357168-05)]
[(1.3252220-04 4.31842840-23 1.32473346-04 7.97357168-05)]
[(1.3252220-04 4.31842840-23 1.32473346-04 7.797357168-05)]
[(1.3252220-04 4.31842840-23 1.3245590020-04 3.7716705-04)]
[(1.3252220-03 1.32477106-03 1.325516-02 3.77428136-05)]
[(1.3593646-03 1.646260-04 8.130102346-03 1.32918790-03)]
[(1.3593746-03 1.3646090-04 1.39137810-02 1.45798746-03)]
[(1.3593746-03 7.71324660-03 2.0256016-02 1.59188660-03)]
[(1.35937460-03 7.71324660-03 2.0256016-02 1.59188660-03)]
[(1.35937460-03 7.71324660-03 2.0256016-02 1.59188660-03)]
[(1.35937460-03 7.71324660-03 2.0256016-02 1.59188660-03)]
[(1.35937460-03 7.71324660-03 1.02256020-03 4.162653516-02)]
[(1.35937460-03 1.042605000-04 1.2793157740-04 1.32536020-03 4.162653516-02)]
[(1.35937460-03 1.042605000-04 1.279315704-04 1.779028626-02)]
[(1.35937460-03 1.82938070-04 1.2793578740-04 1.27938020-03)]
[(1.35947400-03 1.82938070-04 1.279315704-04 1.779028626-02)]
[(1.35947400-03 1.82938070-03 1.279478070-03 2.410781520-03)]
[(1.35947912-03 2.02774170-03 4.04647740-02 2.41388220-03)]
[(1.35947912-03 2.02774170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.02774170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44261780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44264780-03 2.410741520-03)]
[(1.36947912-03 2.03754170-03 2.44264780-03 2.4284780-03 2.4284780-03 2.4284780-03 2.4284780-03 2.4284780-03 2.4284780-03 2.4284780-03 2.4284780-03 2.4284780-03 2.4284780-03 2.
```

- Each of the values above is the Average Reward (Sum of Rewards of All Episodes / Total Number of Episodes)



- Plot the graph average return (over the last 100 episodes while the agent is learning) on y-axis and episode number on x-axis
- The number of episodes is sufficient to ensure convergence as shown above

## Part (c)



- Plot the graph Average Reward (Sum of Rewards of All Episodes / Total Number of Episodes) on y-axis and Learning Rate on x-axis
- As shown above, the Average Reward (as a metric to measure performance) drops when the Learning Rate increases
- According to <u>wikipedia</u>, 'A too high learning rate will make the learning jump over minima but a too low learning rate will either take too long to converge or get stuck in an undesirable local minimum'
- In conclusion, after testing learning rates with 10 different values in [0.1,0.9], I believe 0.45556 is a decent learning rate to use, after considering both factors mentioned above
- As the average reward between using learning rate of 0.81111 and 0.45556 differ only approximately 0.01, and due to limitation of computation power of machine, I used **0.8** for this Q-Learning

# QUESTION 5

## Part (a)

```
[] import talks
# import the stop words
# import the revers deposed
# import deposed
# import the revers deposed
# import deposed
# import deposed
# import the revers deposed
# import depos
```

- Process words into the lowercase
  - Perform stop words removal

#### Part (b)

- Number of unique words (size of vocabulary): 7157

```
[] def compute_co_cocurence_matrix(corps, vindow_misow_misow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow_disow
```

Set the window size to 7 on either size of the word

## Part (c)

- Apply SVD and obtain word embedding of size 75

## Part (d)

- Generate word embedding of size 75 using Word2Vec.pynb on the same Reuters dataset

```
from aklearn.metrics.pairvise import cosine_similarity

def svd_most_similar(query_word, n=18):

""" return 'n' most similar words of a query word using the SVD word embeddings similar to word?veo's most_smilar

Params:
    query_word (strings): a query word

Neturn:
    most_similar (list of strings): the list of 'n' most similar words

""" cosine_sim = cosine_similarity(word_embedding_75dim, np.array([word_embedding_75dim[word2Ind[query_word]]]))

cosine_sim = cosine_sim.latten()

indices = (-cosine_sim).argsort()[lin*1]

most_similar = []

for i in indices:
    most_similar.append((words[i), cosine_sim[i]))

for val in most_similar:
    print(val)
```

- To compare and determine which method (Word2Vec OR SVD) works better, a few examples are shown below:

- Based on the observation above, on overall, Word2Vec approach works better for this reuters\_corpus:
  - For the word 'money', 5 out of 10 of the returned results of SVD approach are numerical values, which is relatively less meaningful for this case as compared to Word2Vec approach.

- For the word 'bank', we can see that one of the top 3 returned results of Word2Vec approach is 'market', which by meaning, could be related.
   However, for SVD approach, almost all returned results have no direct meaning with the word 'bank'.
- One possible reason for this observation is that the dataset provided is not huge enough to capture the actual 'meaning' of each word
- Furthermore, for this specific example, we are required to set the hyperparameter values based on Q5 instructions, e.g., the window size is set to 7, which could be adjusted to larger size to better capture the relationship between words.



- Another possible reason is the corpus contains relative high number of non-English words. Although these special characters may be meaningful to certain extend, but with word counts approaching 10% of the entire corpus may affects, and possibly reduce the accuracy of SVD computation approach.

- Finish -