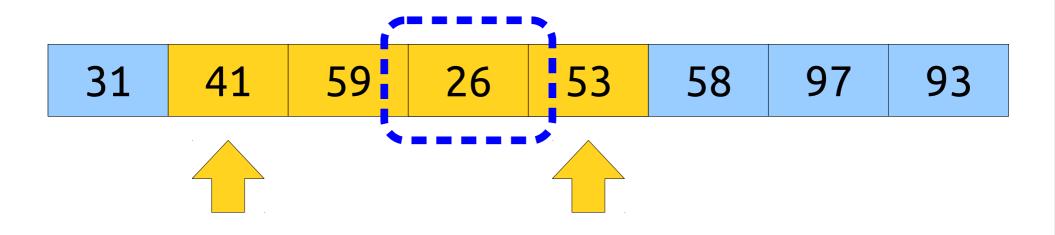
Range Minimum Queries Part Two

Recap from Last Time

The RMQ Problem

• The *Range Minimum Query* (*RMQ*) problem is the following:

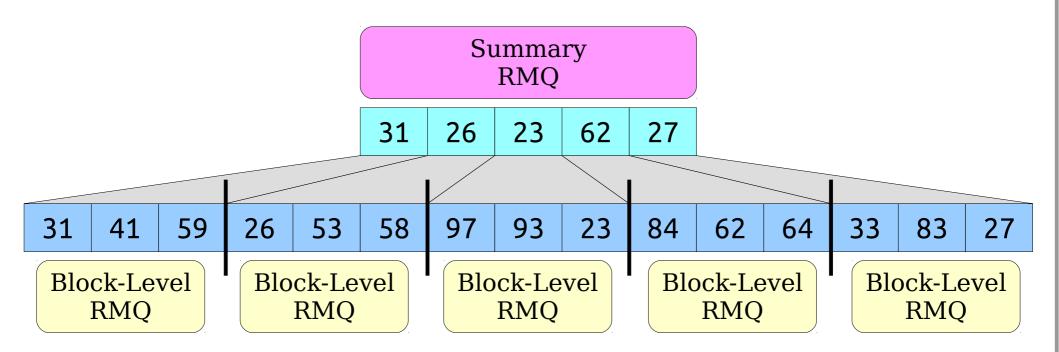
Given a fixed array A and two indices $i \le j$, what is the smallest element out of A[i], A[i+1], ..., A[j-1], A[j]?



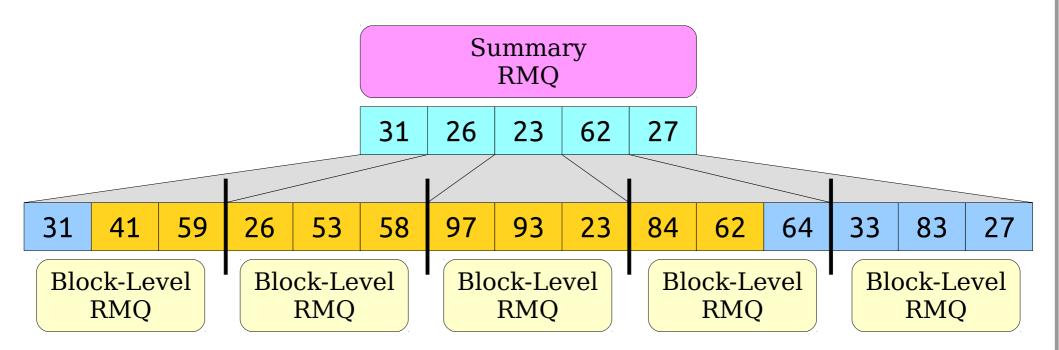
Some Notation

- We'll say that an RMQ data structure has time complexity $\langle p(n), q(n) \rangle$ if
 - preprocessing takes time at most p(n) and
 - queries take time at most q(n).
- Last time, we saw structures with the following runtimes:
 - $\langle O(n^2), O(1) \rangle$ (full preprocessing)
 - $\langle O(n \log n), O(1) \rangle$ (sparse table)
 - $\langle O(n \log \log n), O(1) \rangle$ (hybrid approach)
 - $\langle O(n), O(n^{1/2}) \rangle$ (blocking)
 - $\langle O(n), O(\log n) \rangle$ (hybrid approach)
 - $\langle O(n), O(\log \log n) \rangle$ (hybrid approach)

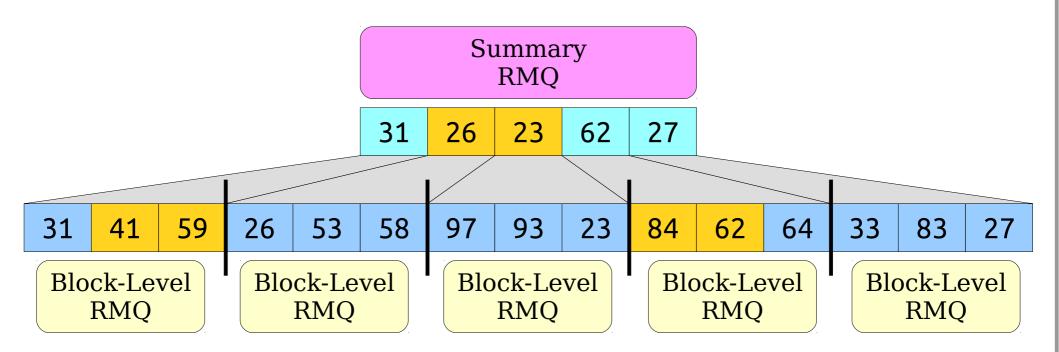
- Split the input into blocks of size *b*.
- Form an array of the block minima.
- Construct a "summary" RMQ structure over the block minima.
- Construct "block" RMQ structures for each block.
- Aggregate the results together.



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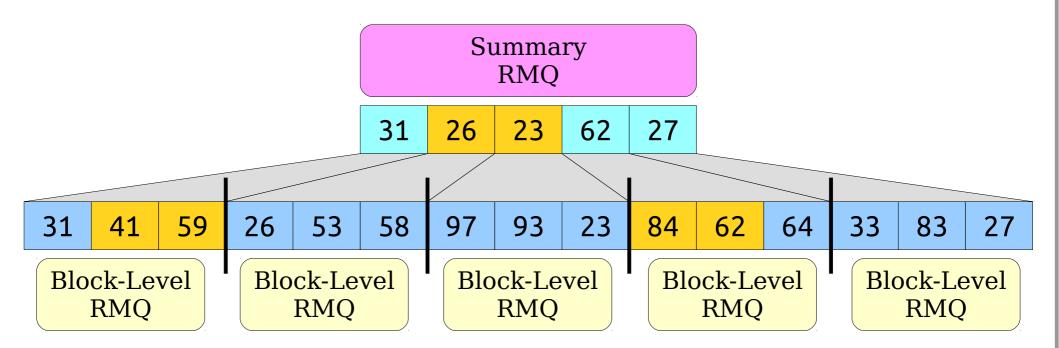


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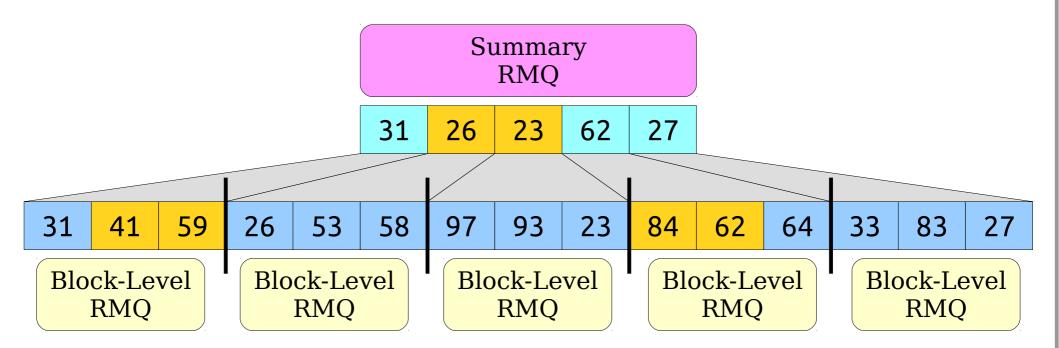
- Suppose we use a $\langle p_1(n), q_1(n) \rangle$ -time RMQ solution for the summary and a $\langle p_2(n), q_2(n) \rangle$ -time RMQ solution within each block. Let the block size be b.
- In the hybrid structure, the preprocessing time is

$$O(n + p_1(n / b) + (n / b) p_2(b))$$



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- In the hybrid structure, the query time is

$$O(q_1(n/b)+q_2(b))$$



Is there an (O(n), O(1)) solution to RMQ?

Yes!

New Stuff!

The Limits of Hybrids

- The preprocessing time on a hybrid structure is $O(n + p_1(n / b) + (n / b) p_2(b)).$
- The query time is

$$O(q_1(n / b) + q_2(b)).$$

• What do $p_2(n)$ and $q_2(n)$ need to be if we want to build a $\langle O(n), O(1) \rangle$ RMQ structure?

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• What do $p_2(n)$ and $q_2(n)$ need to be if we want to build a $\langle O(n), O(1) \rangle$ RMQ structure?

$$p_2(n) = O(n)$$
 $q_2(n) = O(1)$

- **Problem:** We can't build an optimal RMQ structure unless we already have one!
- Or can we?

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What to bu Number of blocks: O(n / b). $p_2(n) = O(n)$ $q_2(n) = O(1)$

Problem: We can't build an optimal RMQ structure unless we already have one!

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A Key Difference

Our original problem is

Solve RMQ on a single array in time (O(n), O(1))

The new problem is

Solve RMQ on a large number of small arrays with O(1) query time and total preprocessing time O(n).

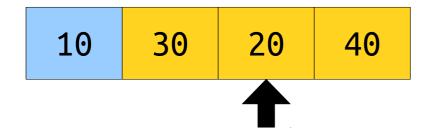
- These are not the same problem.
- *Question:* Why is this second problem any easier than the first?

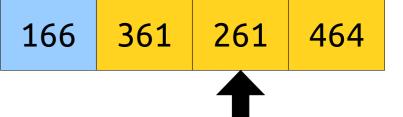
10 30 20 40

166 361 261 464



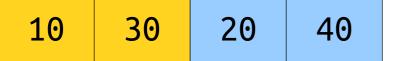
166	361	261	464



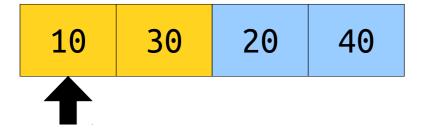


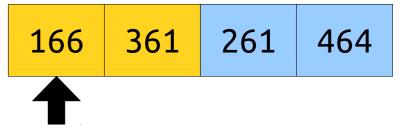
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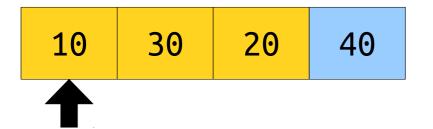


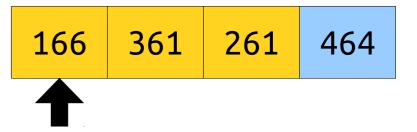
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10 30 20 40

166 361 261 464

Claim: The indices of the answers to any range minimum queries on these two arrays are the same.

Modifying RMQ

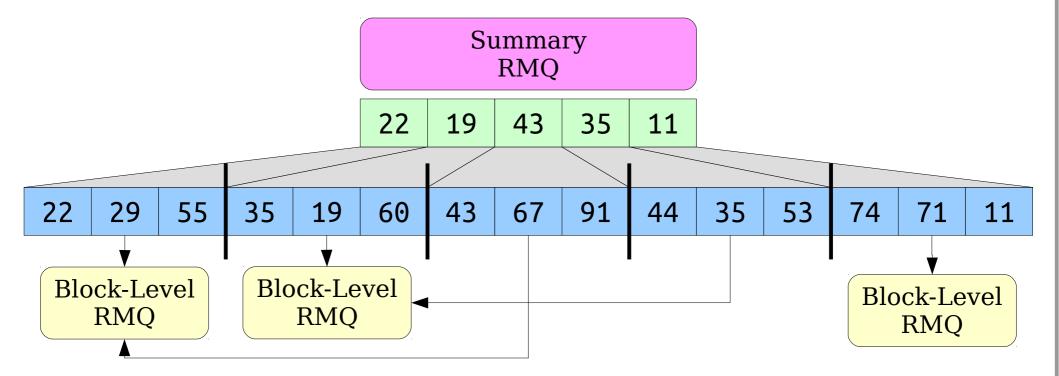
- From this point forward, let's have $RMQ_A(i, j)$ denote the *index* of the minimum value in the range rather than the value itself.
- *Observation:* If RMQ structures return indices rather than values, we can use a single RMQ structure for both of these arrays:

10	30	20	40
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166 361	261	464
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Where We're Going

- Suppose we use an $(O(n \log n), O(1))$ sparse table for the top and the $(O(n^2), O(1))$ precompute-all structures for the blocks.
- However, whenever possible, we share block-level RMQ structures across multiple blocks.
- Assuming there aren't "too many" different types of blocks, and assuming we can find and group blocks efficiently, this overall strategy might let us reach a (O(n), O(1)) solution!



Two Big Questions

How can we tell when two blocks can share RMQ structures?

How many block types are there, as a function of b?

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How many block types are there, as a function of b?

(We need to tune b to ensure that many blocks are shared. What value of b should we pick?)

The Adventure Begins!

Some Notation

- Let B_1 and B_2 be blocks of length b.
- We'll say that B_1 and B_2 have the same block type (denoted $B_1 \sim B_2$) if the following holds:

For all
$$0 \le i \le j < b$$
:
 $RMQ_{B_1}(i, j) = RMQ_{B_2}(i, j)$

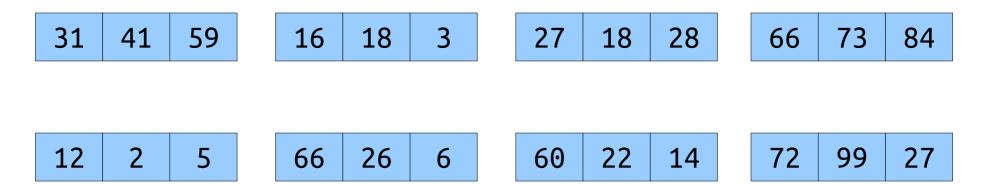
- Intuitively, the RMQ answers for B_1 are always the same as the RMQ answers for B_2 .
- If we build an RMQ to answer queries on some block B_1 , we can reuse that RMQ structure on some other block B_2 iff $B_1 \sim B_2$.

Detecting Block Types

- For this approach to work, we need to be able to check whether two blocks have the same block type.
- **Problem:** Our formal definition of $B_1 \sim B_2$ is defined in terms of RMQ.
 - Not particularly useful *a priori*; we don't want to have to compute RMQ structures on B_1 and B_2 to decide whether they have the same block type!
- Is there a simpler way to determine whether two blocks have the same type?

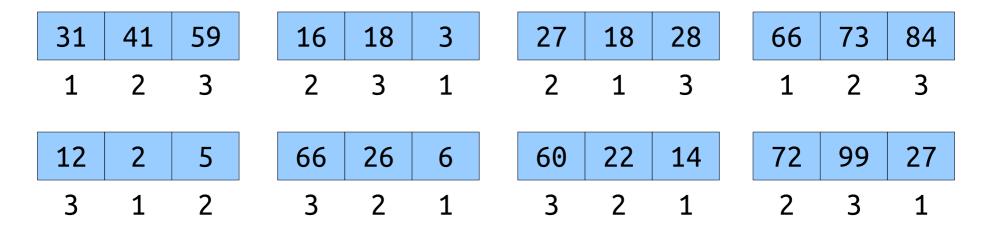
An Initial Idea

• Since the elements of the array are ordered and we're looking for the smallest value in certain ranges, we might look at the permutation types of the blocks.



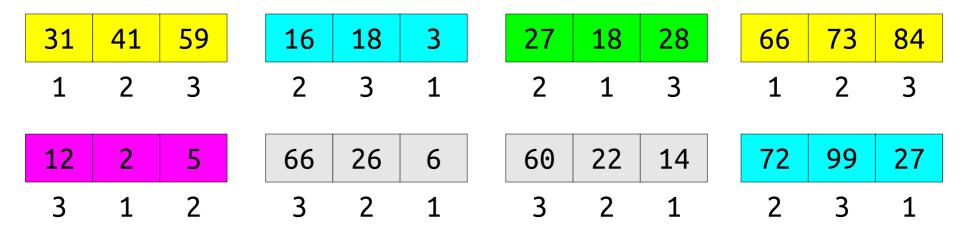
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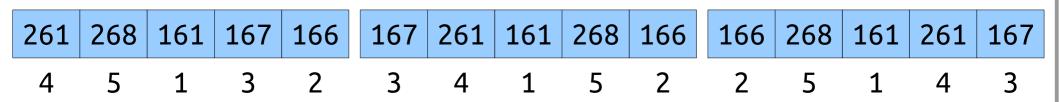
• *Claim:* If B_1 and B_2 have the same permutation on their elements, then $B_1 \sim B_2$.

- There are two main problems with this approach.
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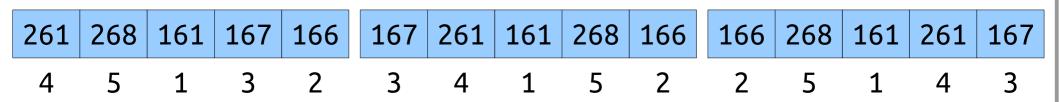
261	268	161	167	166	167	261	161	268	166	166	268	161	261	167
4	5	1	3	2	3	4	1	5	2	2	5	1	4	3

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- **Problem One:** It's possible for two blocks to have different permutations but the same block type.
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- **Problem Two:** The number of possible permutations of a block is b!.
 - *b* has to be absolutely minuscule for *b*! to be small.

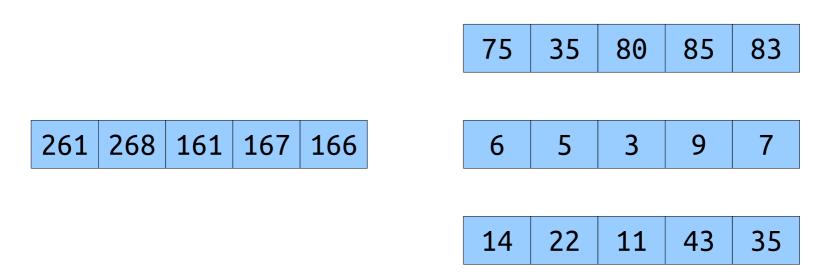
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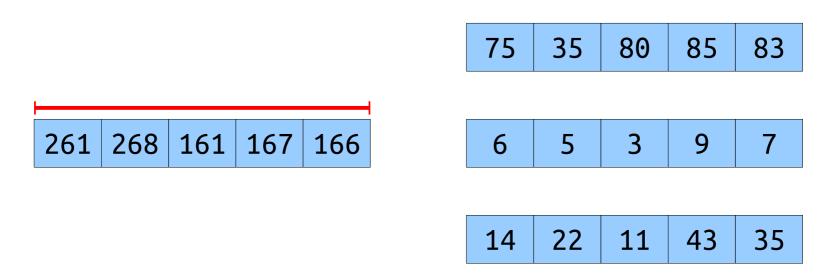


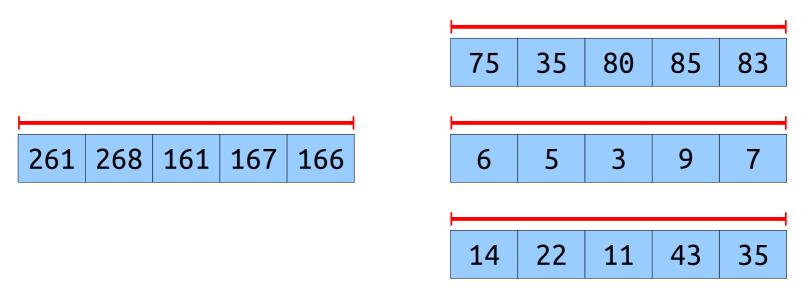
- **Problem Two:** The number of possible permutations of a block is b!.
 - *b* has to be absolutely minuscule for *b*! to be small.
- Is there a better criterion we can use?

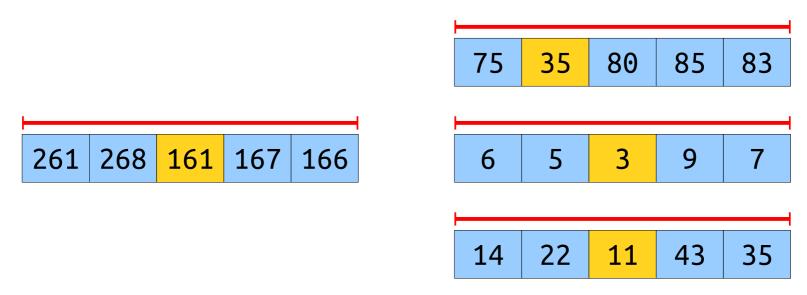
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261 268 161 167 166











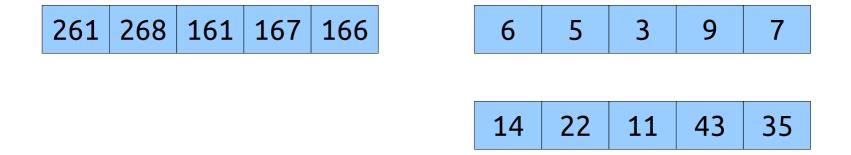




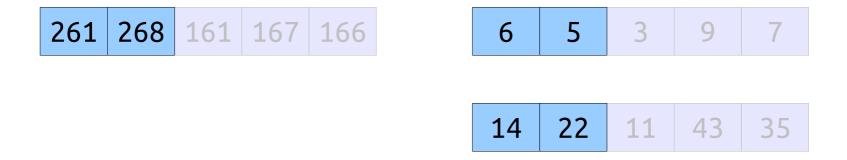


14	22	11	43	35
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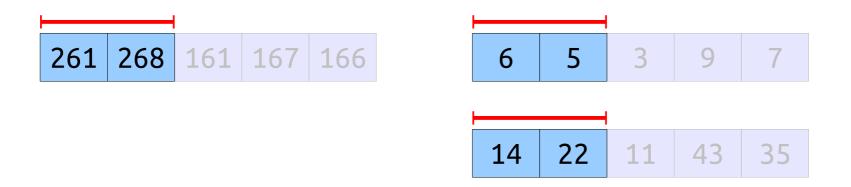
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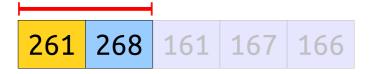
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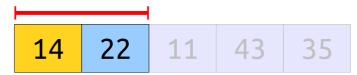


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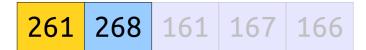


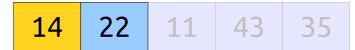
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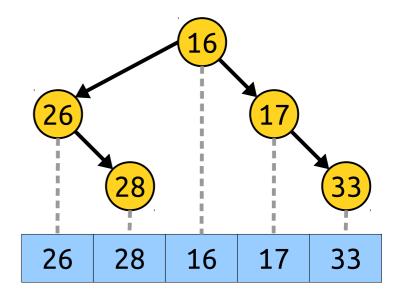
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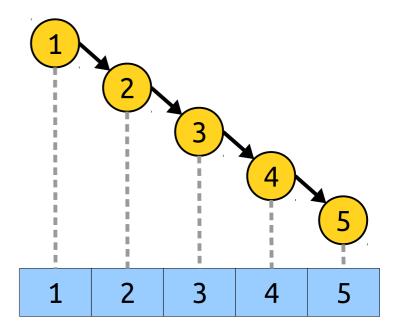
261 268 161 167 166

14 | 22 | 11 | 43 | 35

Cartesian Trees

- A *Cartesian tree* for an array is a binary tree built as follows:
 - The root of the tree is the minimum element of the array.
 - Its left and right subtrees are formed by recursively building Cartesian trees for the subarrays to the left and right of the minimum.
 - (Base case: if the array is empty, the Cartesian tree is empty.)
- This is *mechanical description* of Cartesian trees; it defines Cartesian trees by showing how to make them.



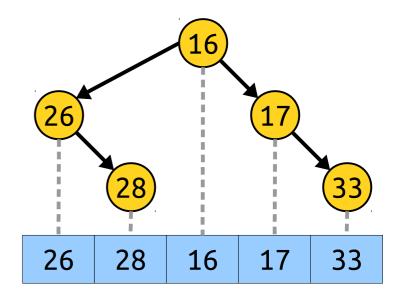


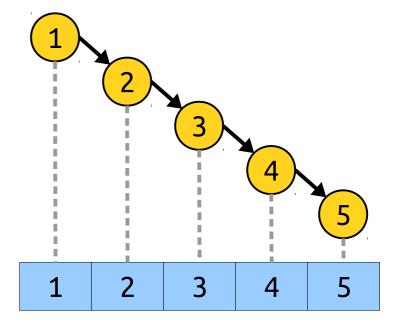
Cartesian Trees

 A Cartesian tree can also be defined as follows:

The Cartesian tree for an array is a binary tree obeying the min-heap property whose inorder traversal gives back the original array.

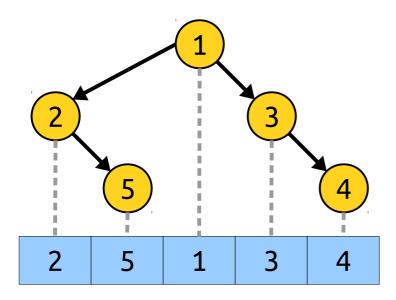
- This is called an operational description; it says what properties the tree has rather than how to find it.
- Having multiple descriptions of the same object is incredibly useful – this will be a recurring theme this quarter!

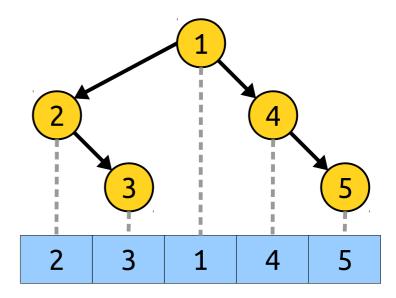




• **Theorem:** Let B_1 and B_2 be blocks of length b. Then $B_1 \sim B_2$ iff B_1 and B_2 have isomorphic Cartesian trees.

"same shape"





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 - (\Rightarrow) Induction. B_1 and B_2 have equal RMQs, so corresponding ranges have minima at the same positions.

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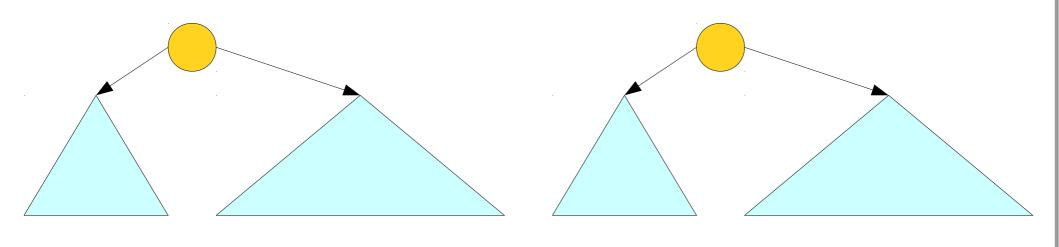
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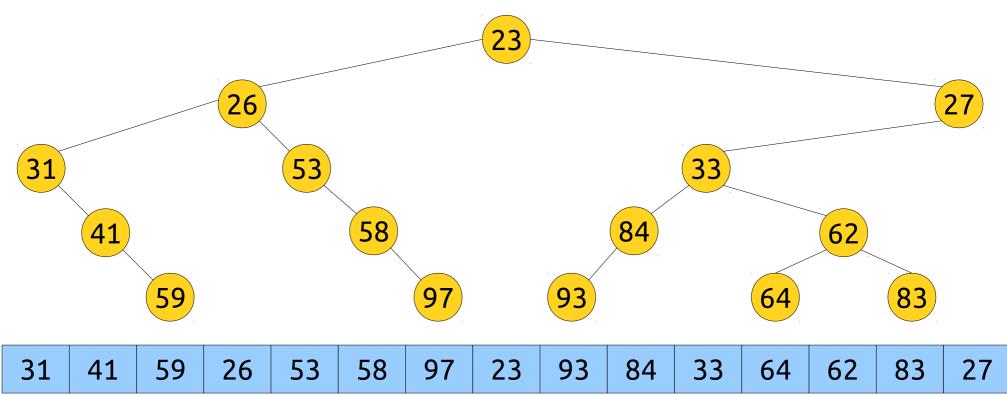
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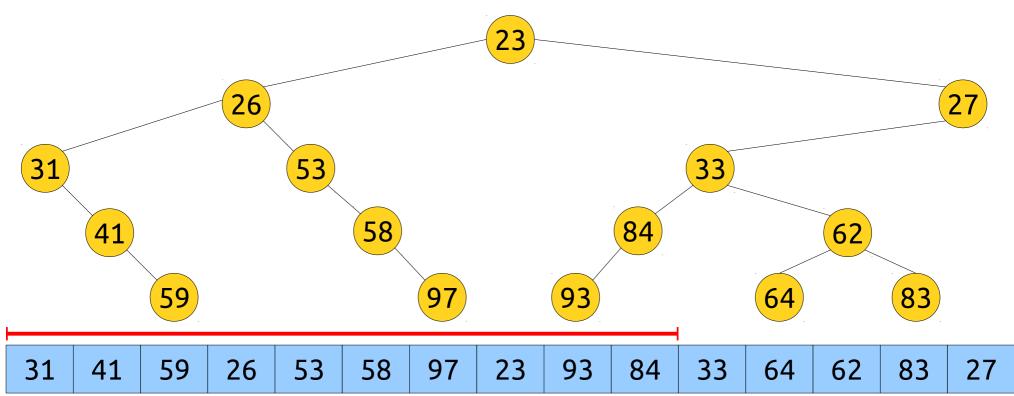
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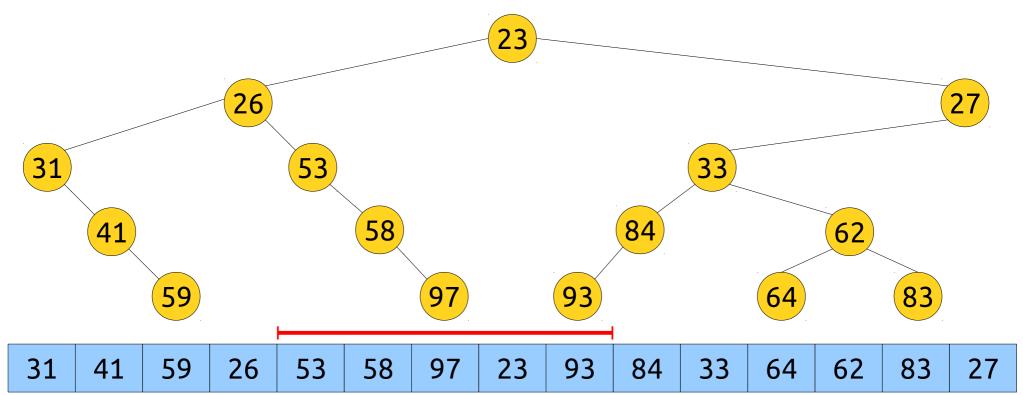
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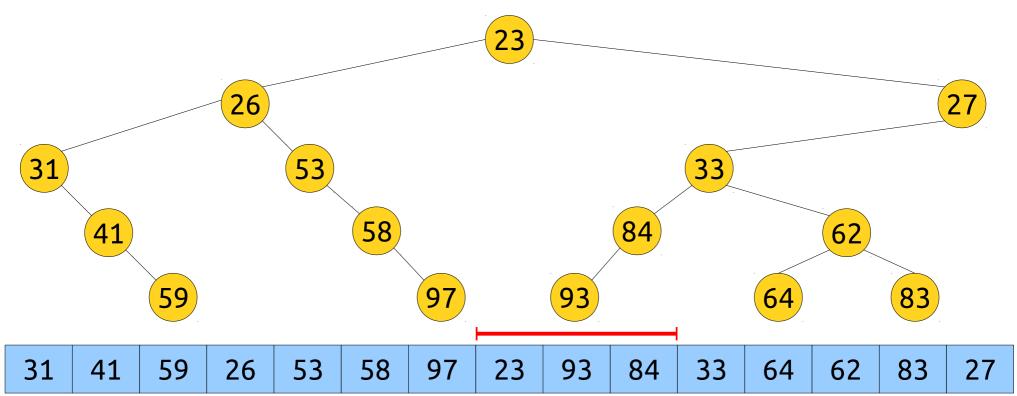
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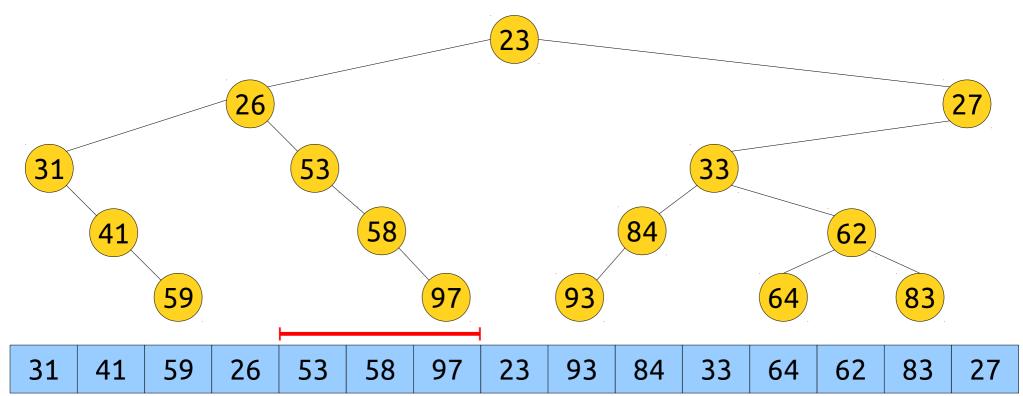
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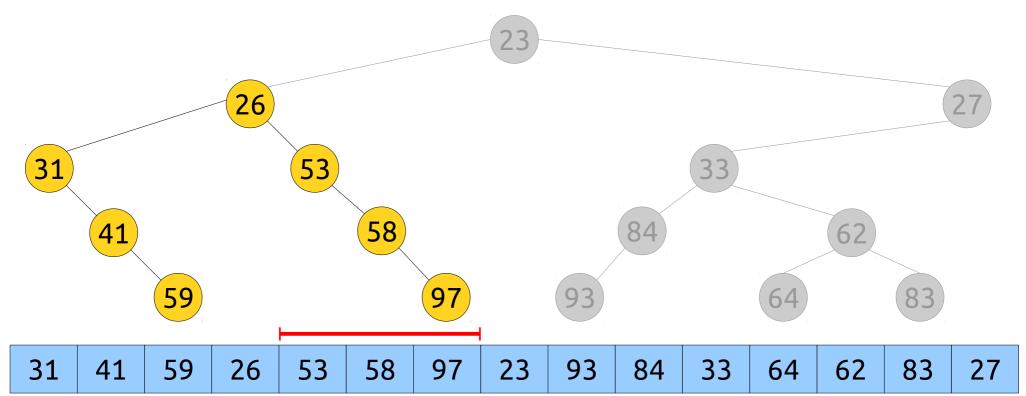
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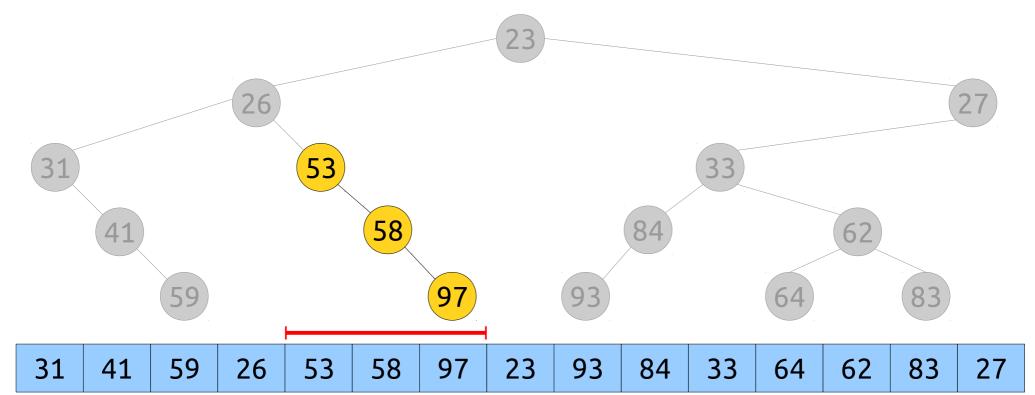
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When those blocks have isomorphic Cartesian trees!

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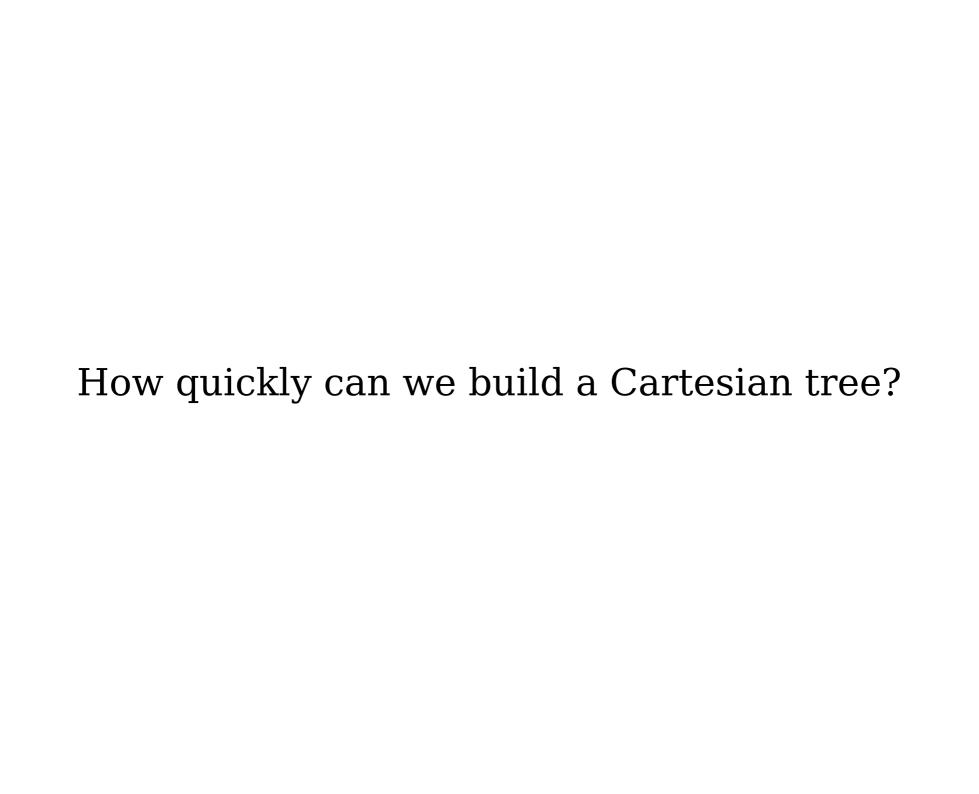
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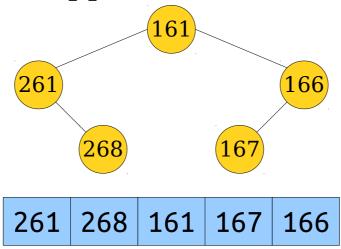
How many block types are there, as a function of b?

「_(ツ)_/「



Building Cartesian Trees

- Here's a naïve algorithm for constructing Cartesian trees:
 - Find the minimum value.
 - Recursively build a Cartesian tree for the array to the left of the minimum.
 - Recursively build a Cartesian tree with the elements to the right of the minimum.
 - Return the overall tree.
- How efficient is this approach?



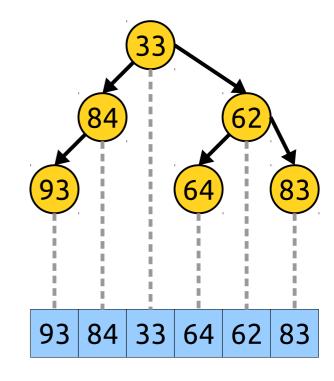
Building Cartesian Trees

- This algorithm works by
 - doing a linear scan over the array to find the minimum value, then
 - recursively processing the left and right halves on the array.
- This is a divide-and-conquer algorithm! Here's a runtime recurrence:

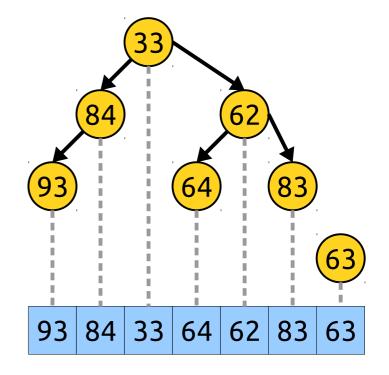
$$T(n) = T(n_{left}) + T(n_{right}) + O(n)$$

- *Question:* What does this recurrence solve to? (Hint: where have you seen this recurrence?)
- This is the same recurrence relation that comes up in the analysis of quicksort!
 - If the min is always in the middle, runtime is $\Theta(n \log n)$.
 - If the min is always all the way to the side, runtime is $\Theta(n^2)$.
- Can we do better?

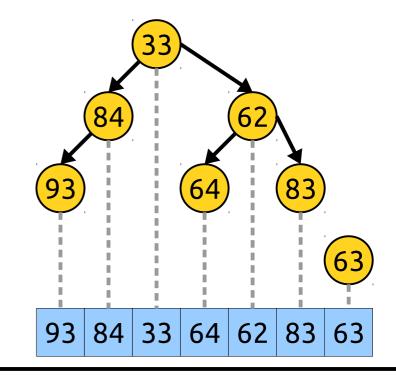
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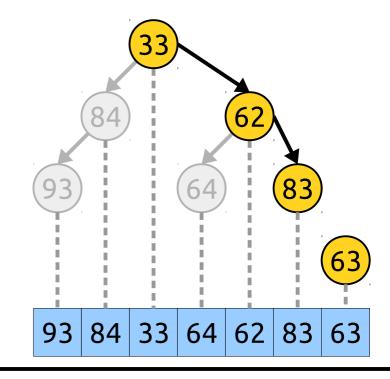


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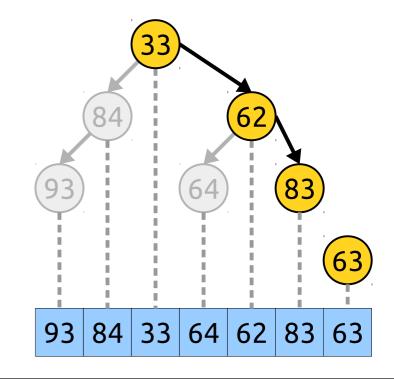
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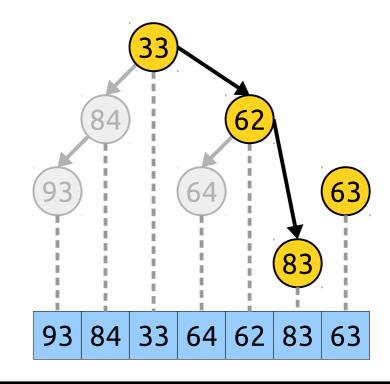


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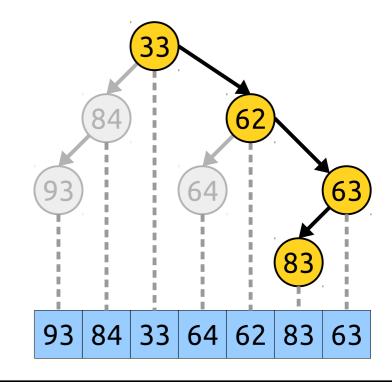
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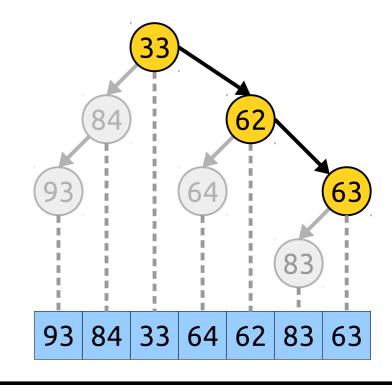
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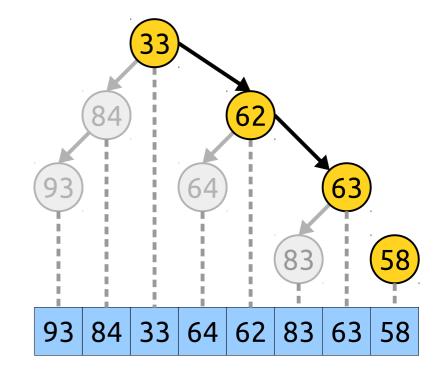
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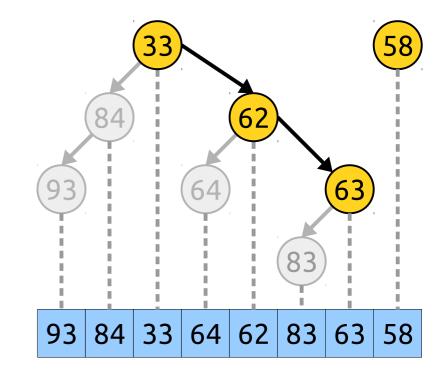
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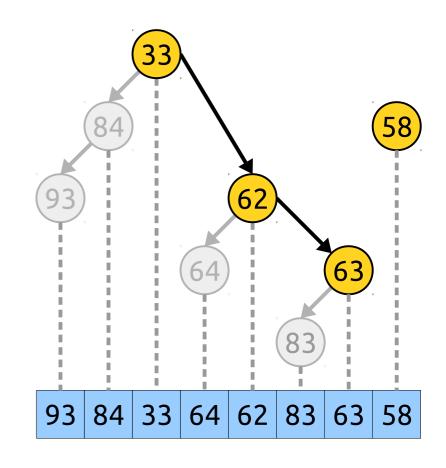
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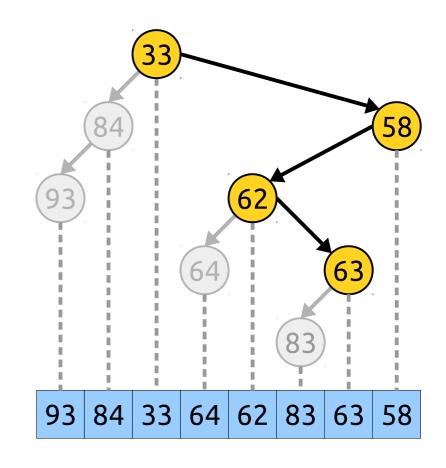
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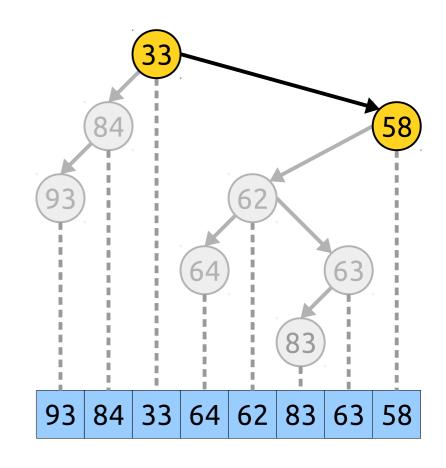
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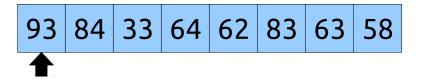
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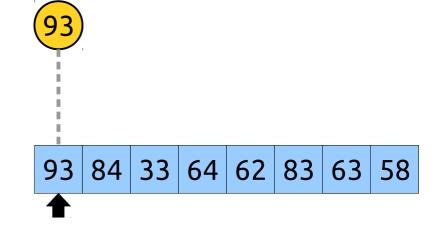


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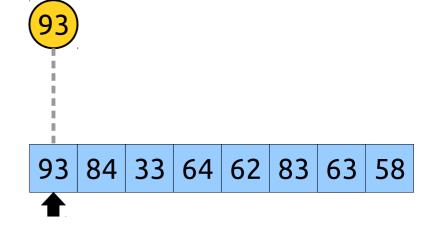
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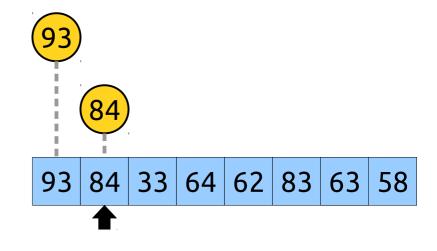
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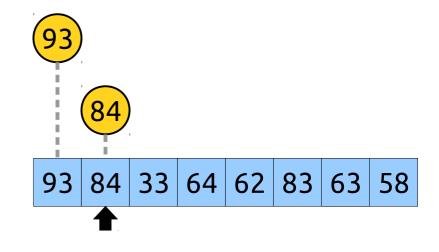




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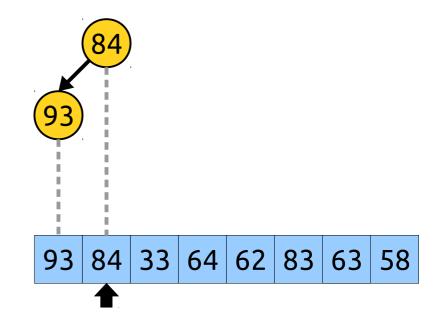


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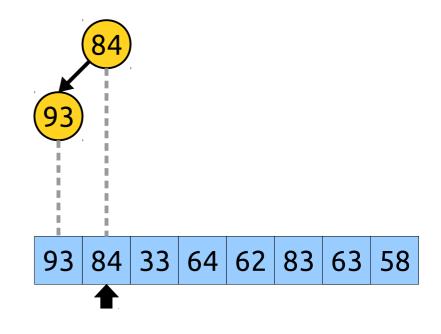


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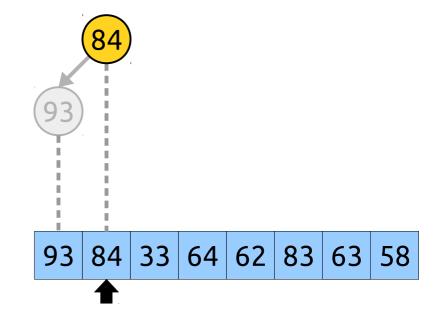


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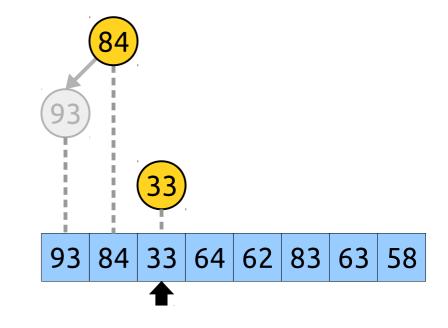


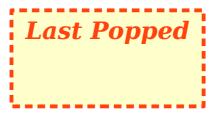


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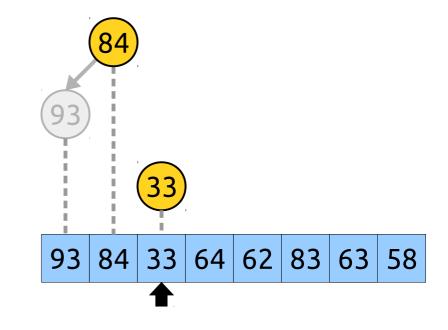


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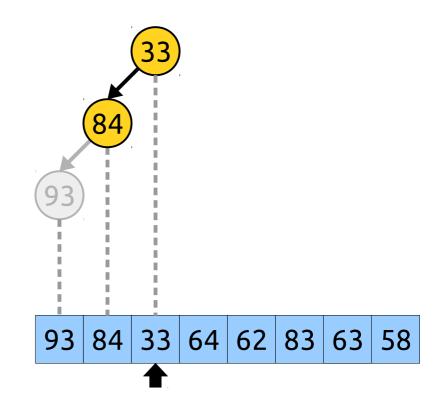


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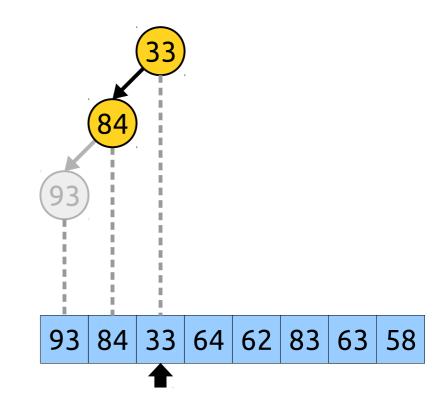


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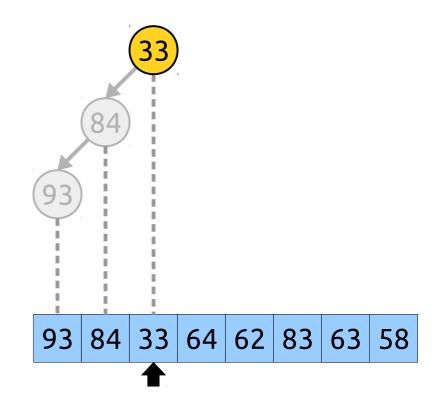


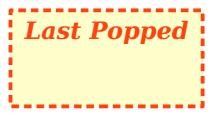
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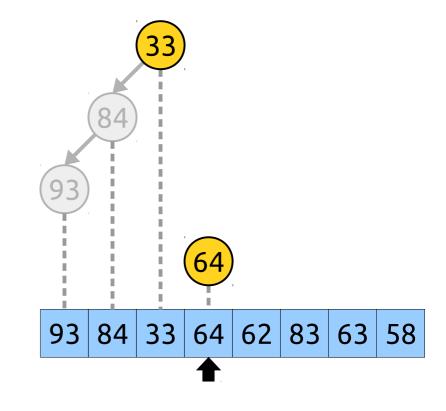


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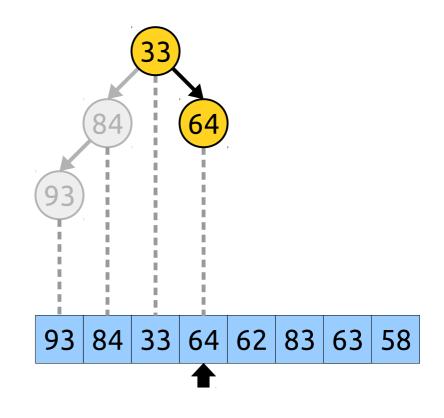


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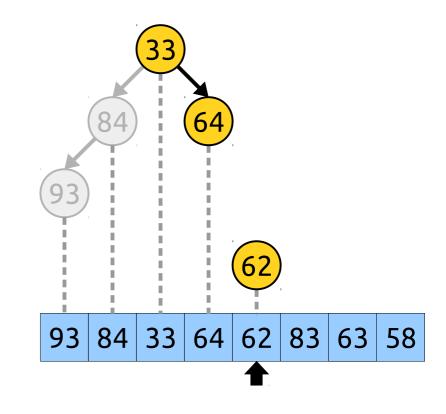


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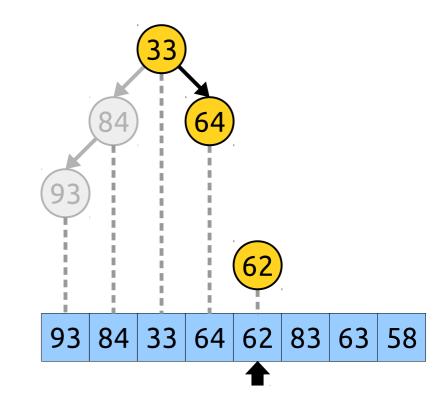


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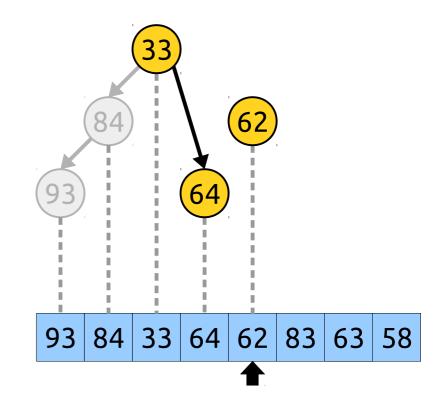


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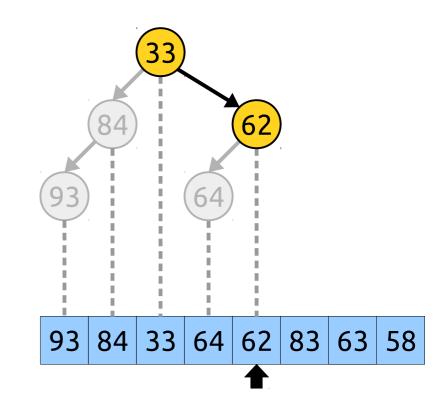


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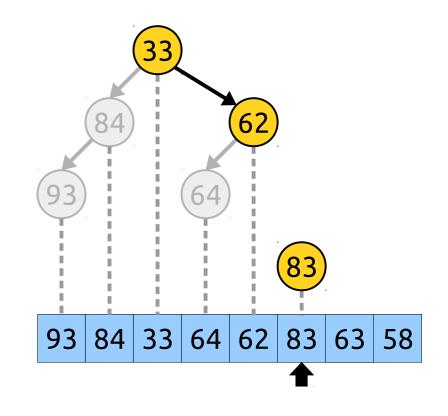


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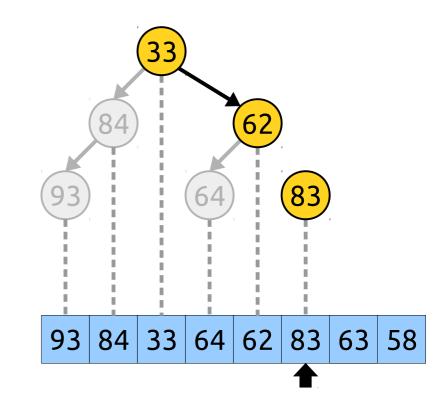


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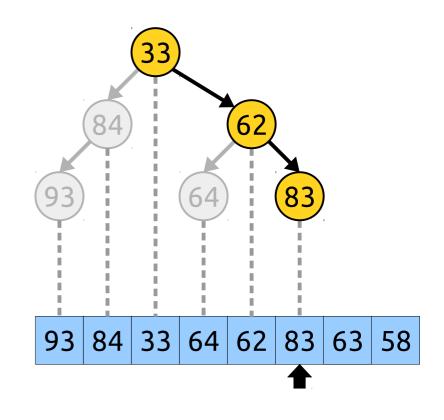


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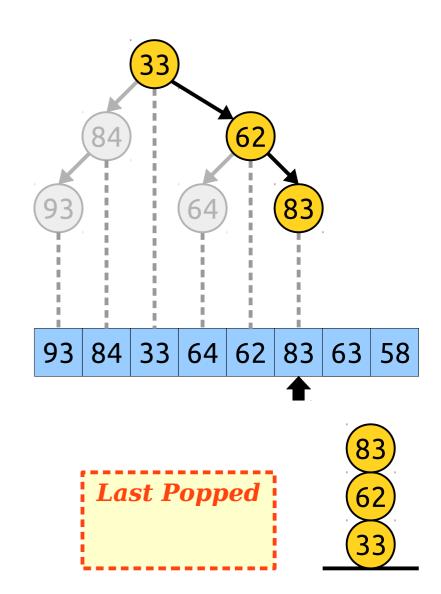


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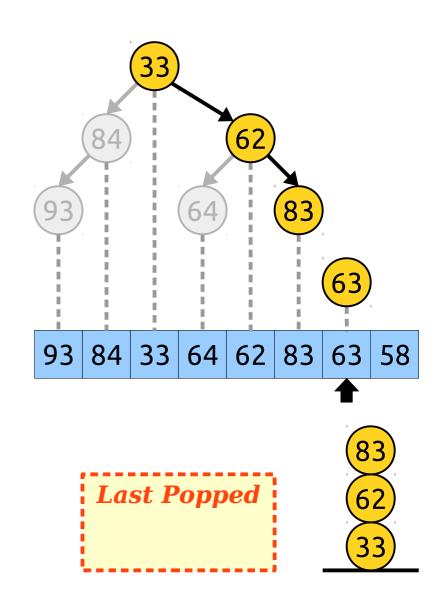




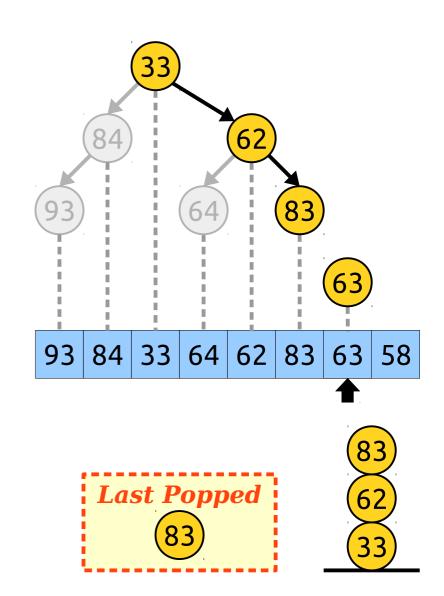
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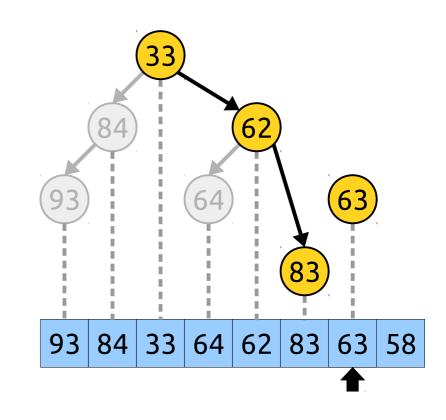
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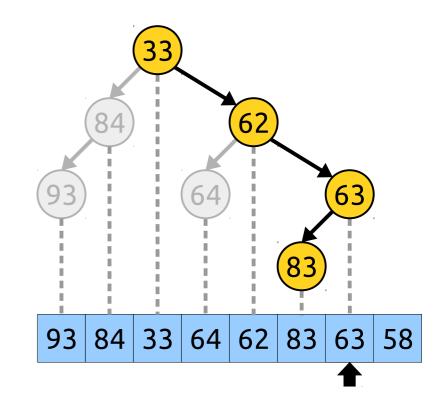


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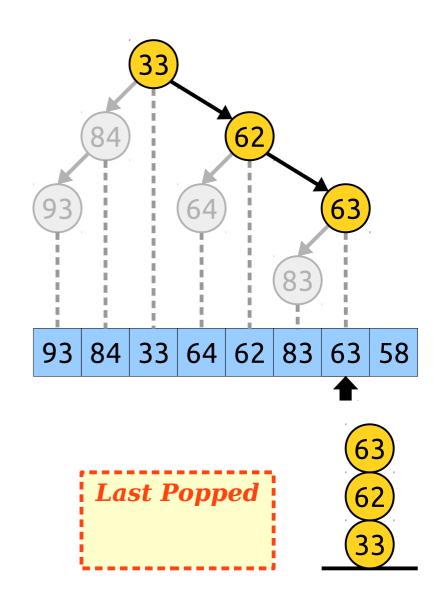


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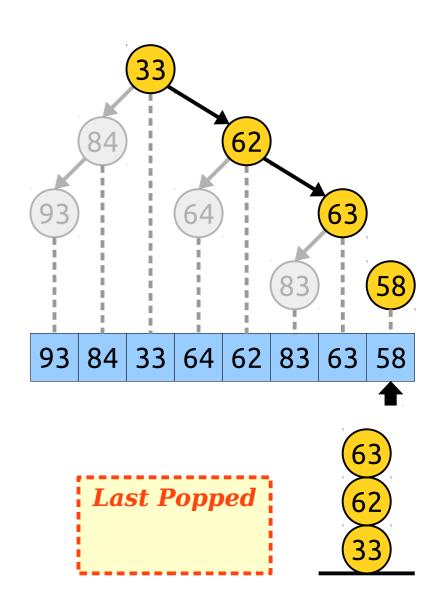




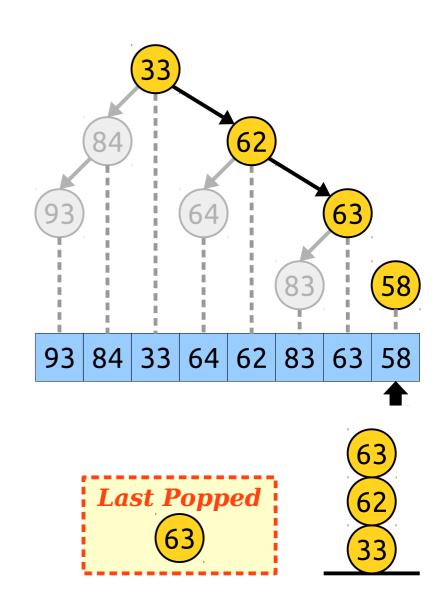
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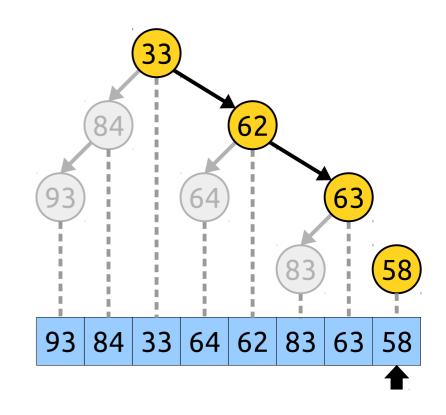
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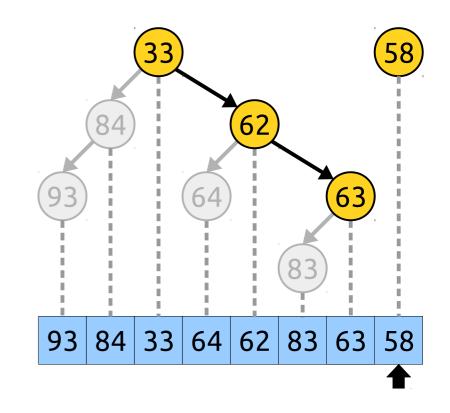


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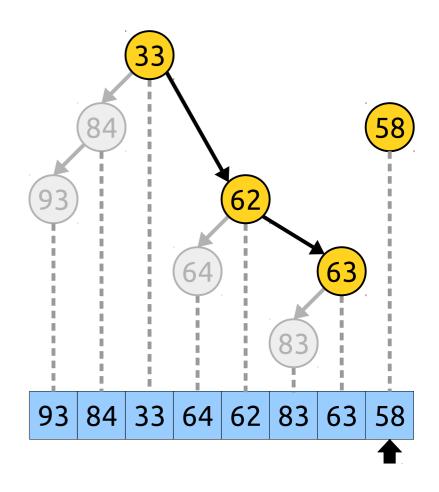


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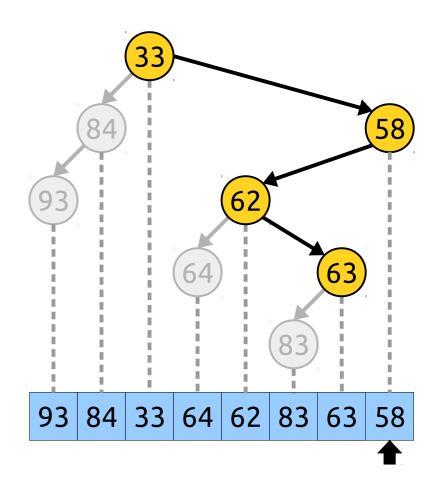


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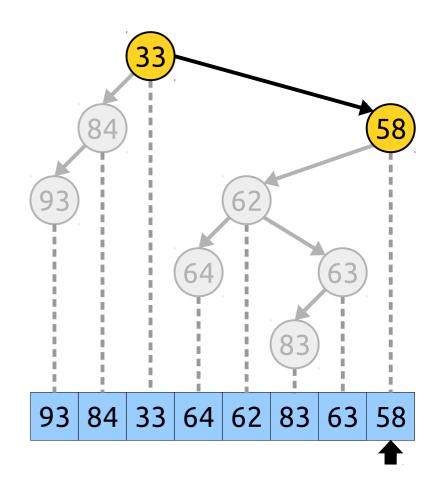


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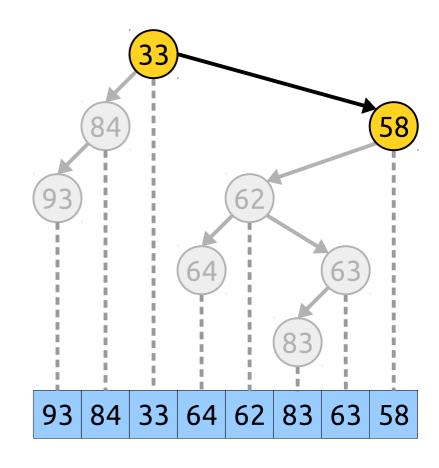


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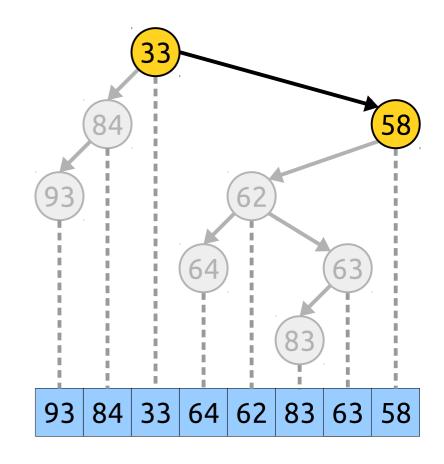


- How fast is this new approach on an array of k elements?
- Adding each element to the tree might take time O(k), since we may have to pop O(k) elements off the stack.
- Since there are k elements, that gives a time bound of $O(k^2)$.
- Question: Is this bound tight?





- Claim: This algorithm takes time O(k) on an array of size k.
- Idea: Each element is pushed onto the stack exactly once, when it's created. Each element can therefore be popped at most once.
- Therefore, there are at O(k) pushes and O(k) pops, so the runtime is O(k).



How can we tell when two blocks can share RMQ structures?

When those blocks have isomorphic Cartesian trees!
And we can check this in time O(b)!
But there are lots of pairs of blocks to check!

How many block types are there, as a function of b?

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Theorem: The number of Cartesian trees for arrays of length b is at most 4^b .

In case you're curious, the actual number is

$$\frac{1}{b+1} \binom{2b}{b}$$
,

which is roughly equal to

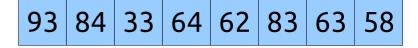
$$rac{4^b}{b^{3/2}\sqrt{\pi}}$$

Look up the **Catalan numbers** for more information!

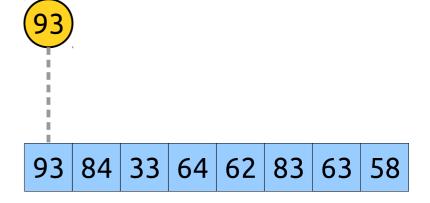
Proof Approach

- Our stack-based algorithm for generating Cartesian trees produces a Cartesian tree for every possible input array.
- Therefore, if we can count the number of possible executions of that algorithm, we can count the number of Cartesian trees.
- Using a simple counting scheme, we can show that there are at most 4^b possible executions.

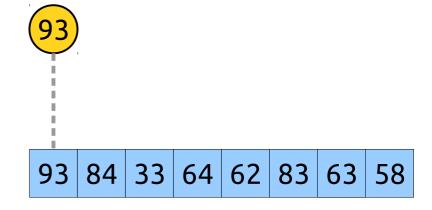
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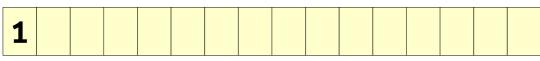


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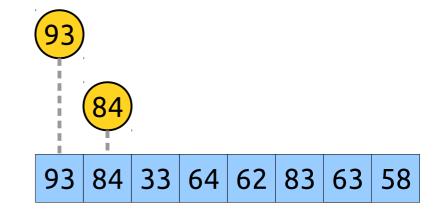


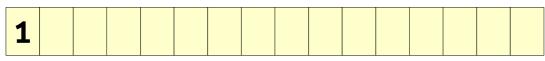
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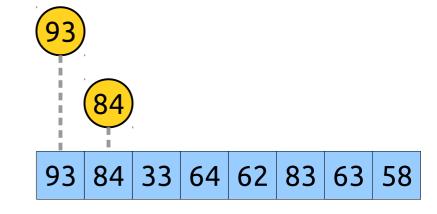


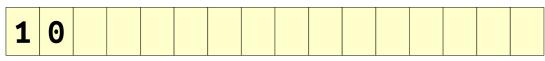
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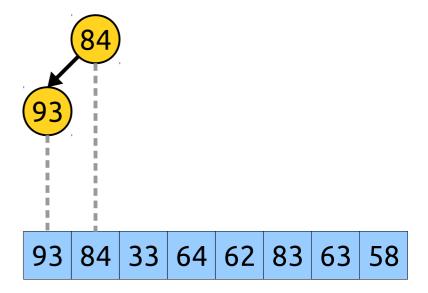


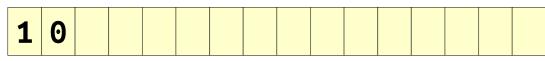
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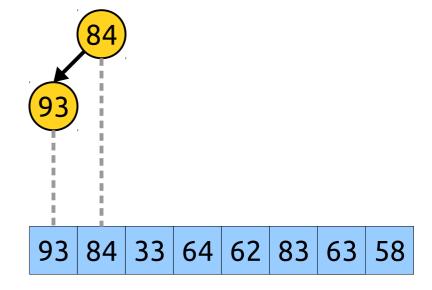


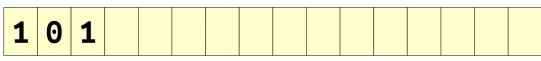
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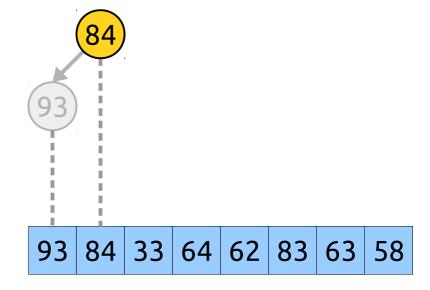


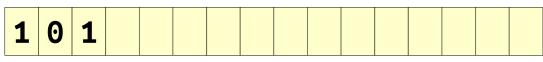
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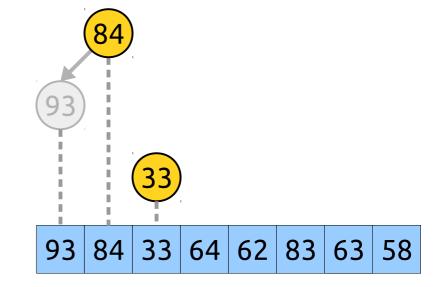


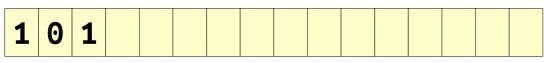
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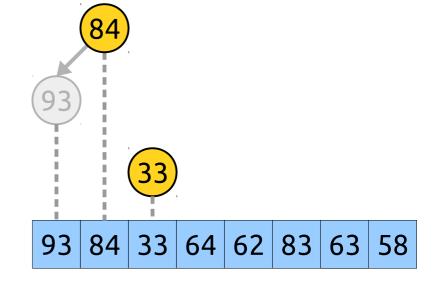


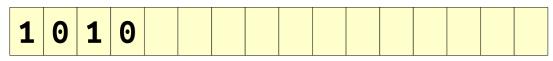
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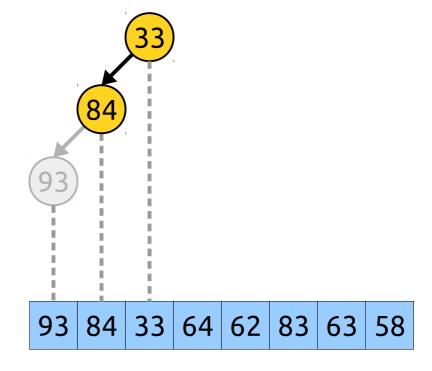


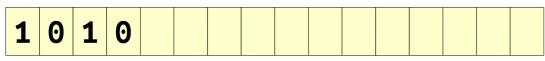
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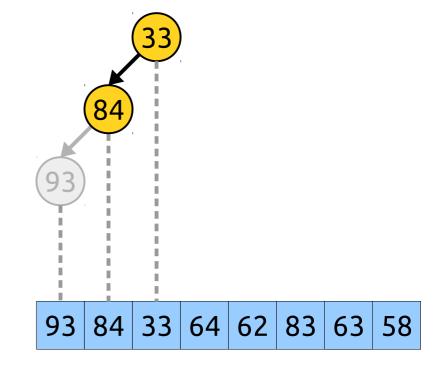


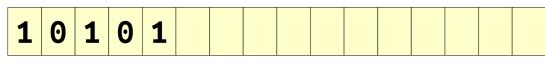
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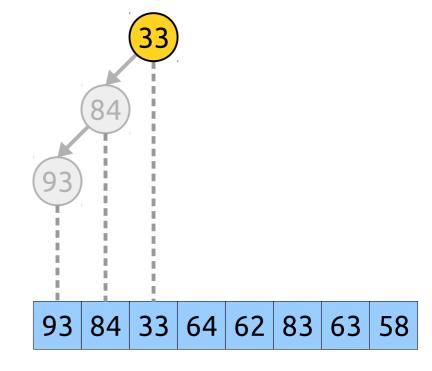


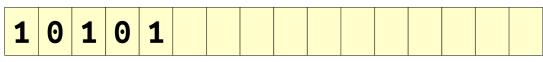
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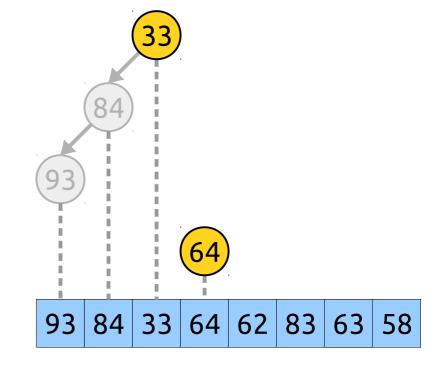


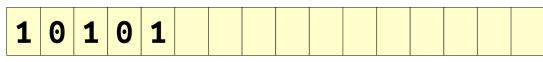
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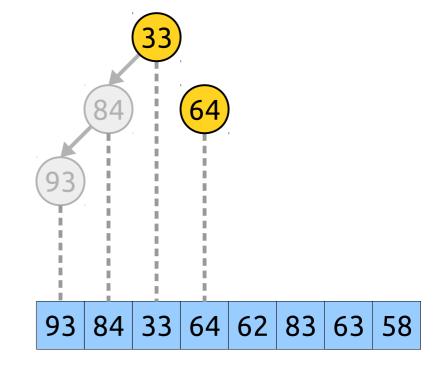


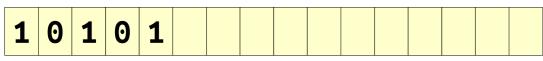
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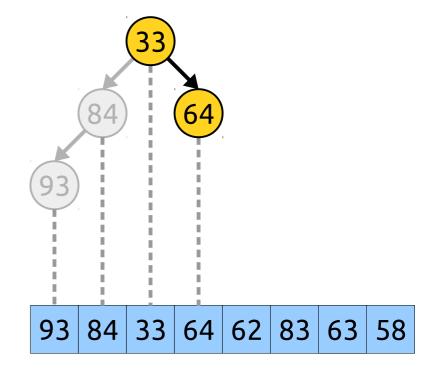


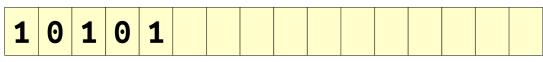
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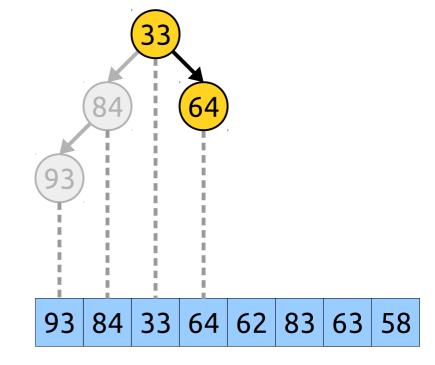


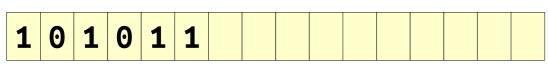
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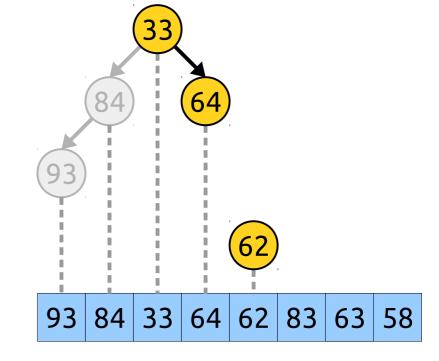
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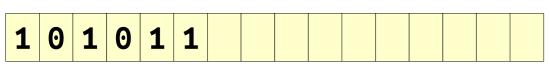






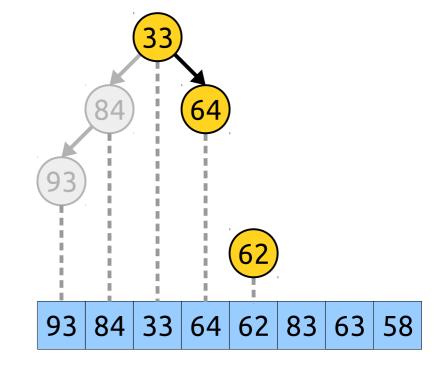
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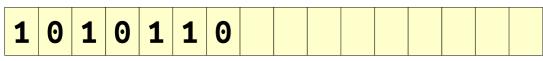




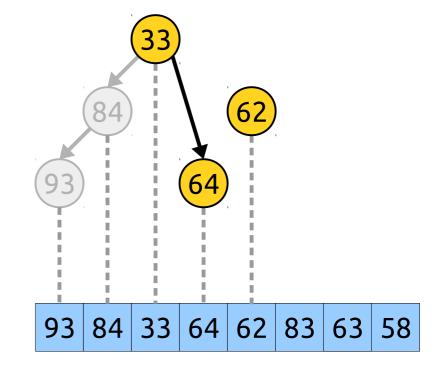


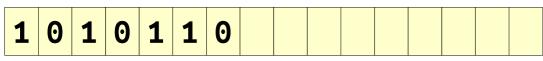
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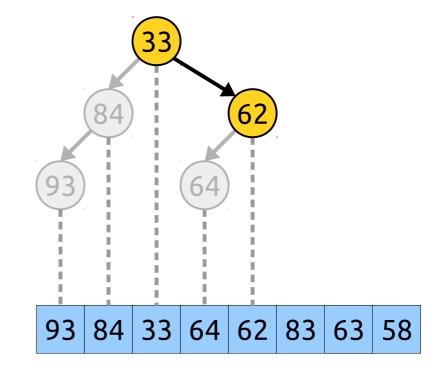


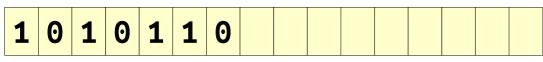
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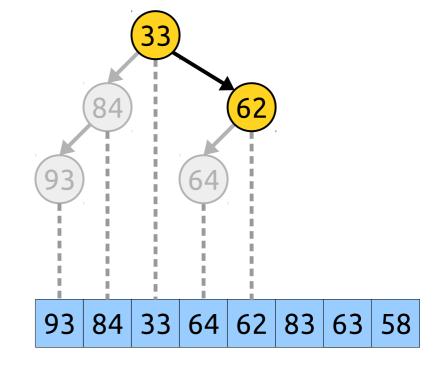


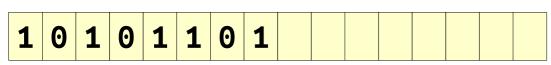
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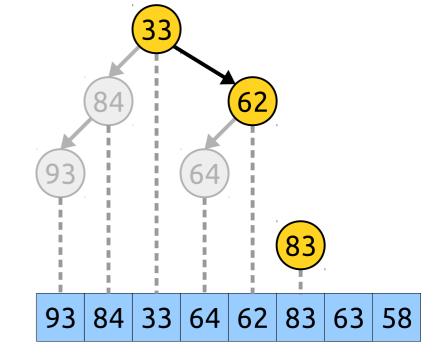
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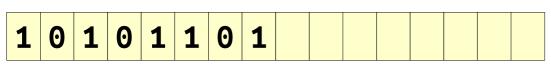






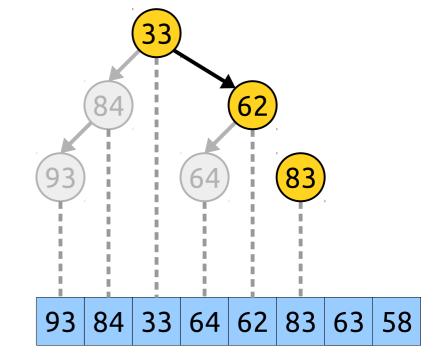
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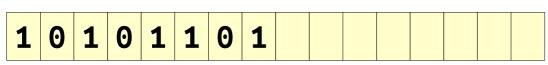






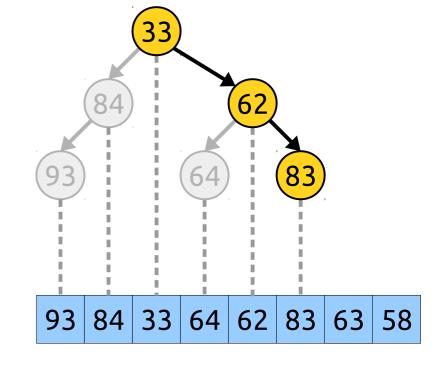
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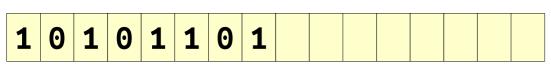






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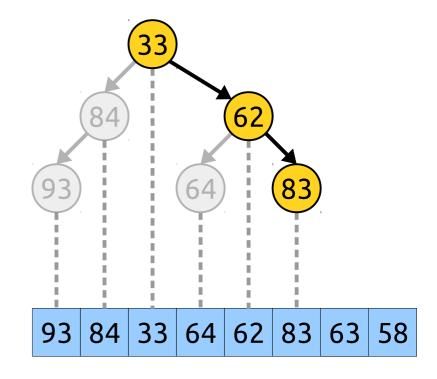




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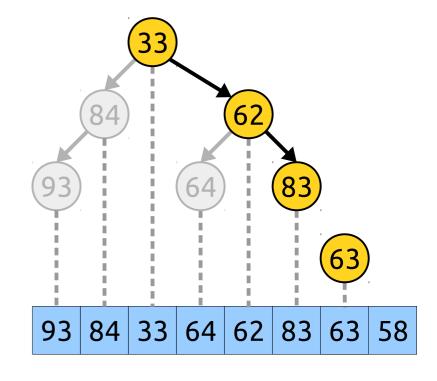
0 means pop; 1 means push

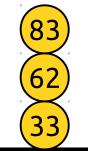


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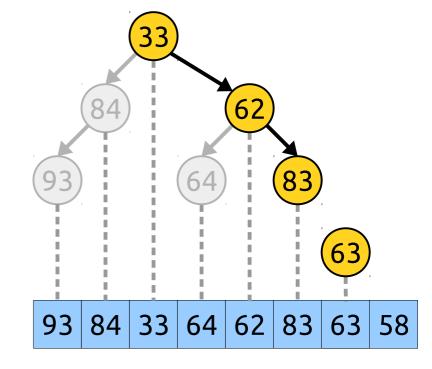
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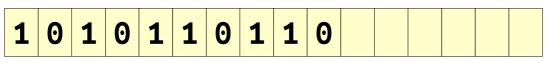






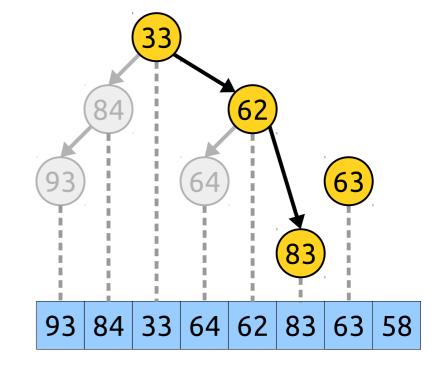
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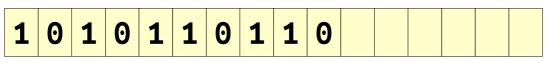






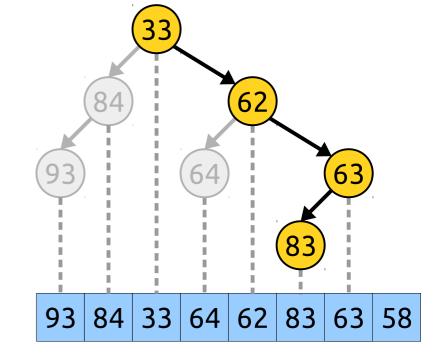
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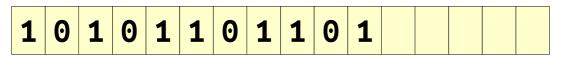
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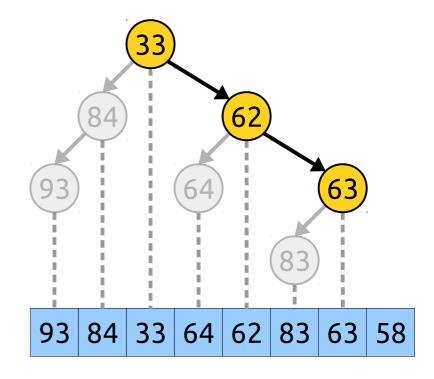


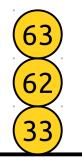




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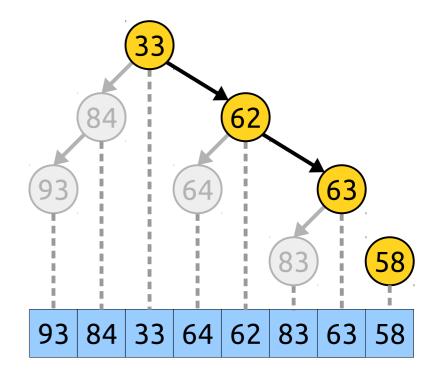


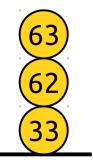




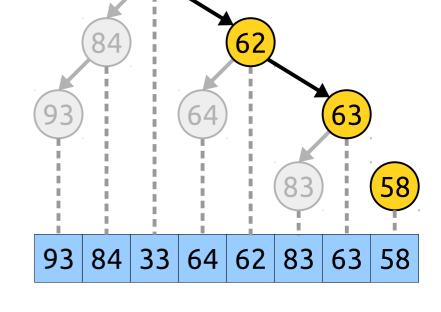
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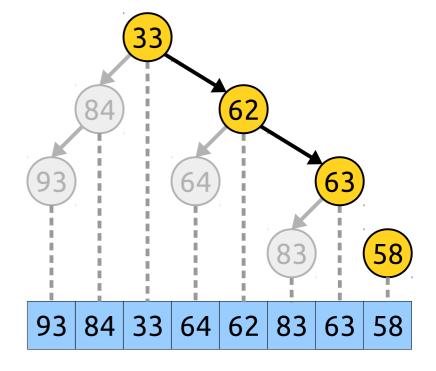
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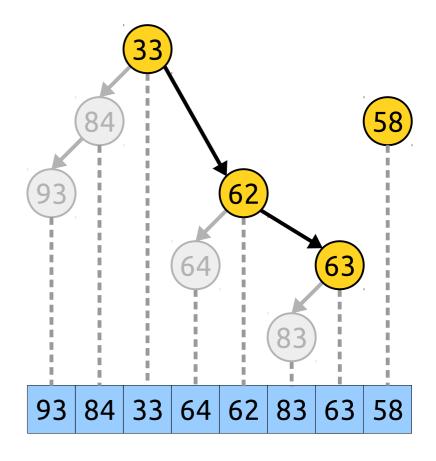


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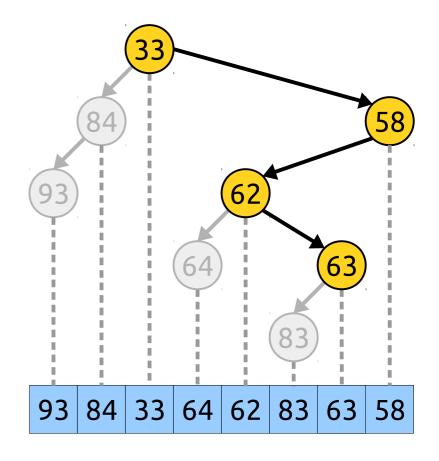


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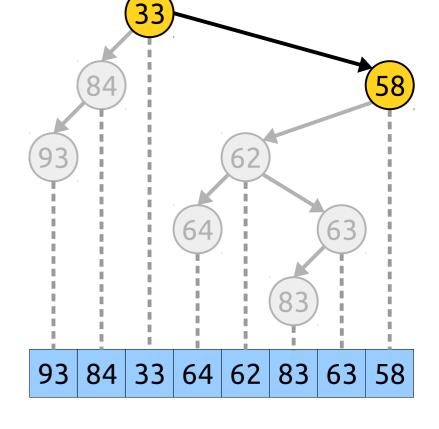


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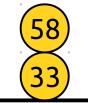


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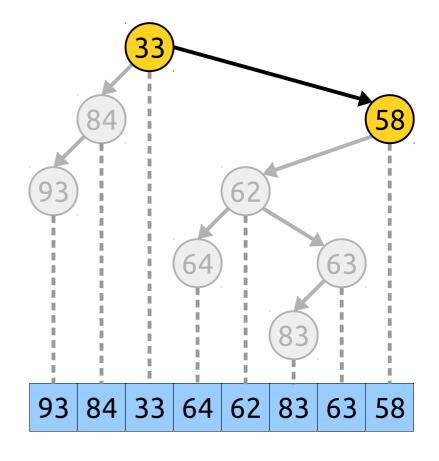
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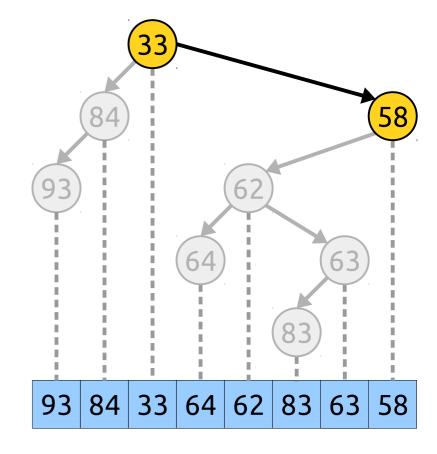


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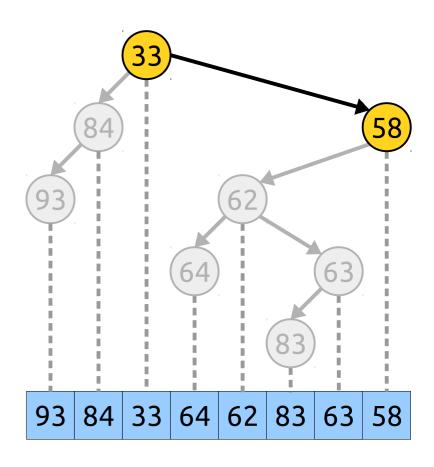
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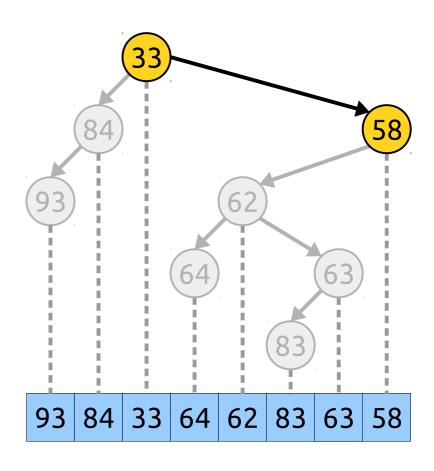
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1 0 1 0 1 1 0 1 1 0 1 0 0 1 0 0

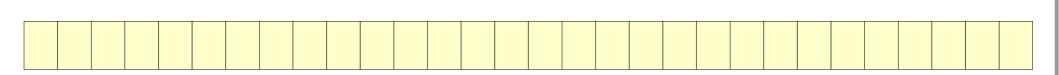
- Two blocks can share an RMQ structure iff they have the same Cartesian tree.
- Observation: If all we care about is finding blocks that can share RMQ structures, we never need to build Cartesian trees! Instead, we can just compute the Cartesian tree number for each block.



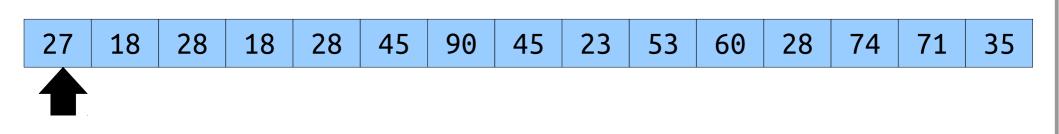
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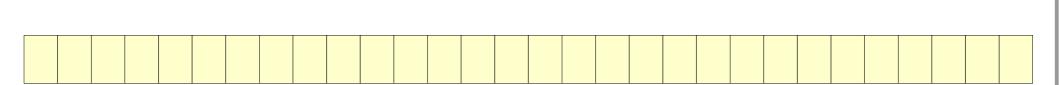
Treeless Tree Numbers





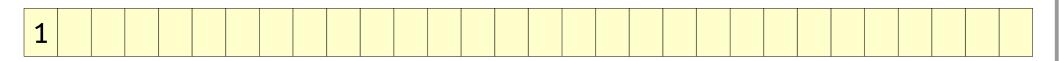
Treeless Tree Numbers



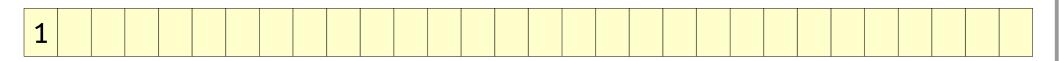


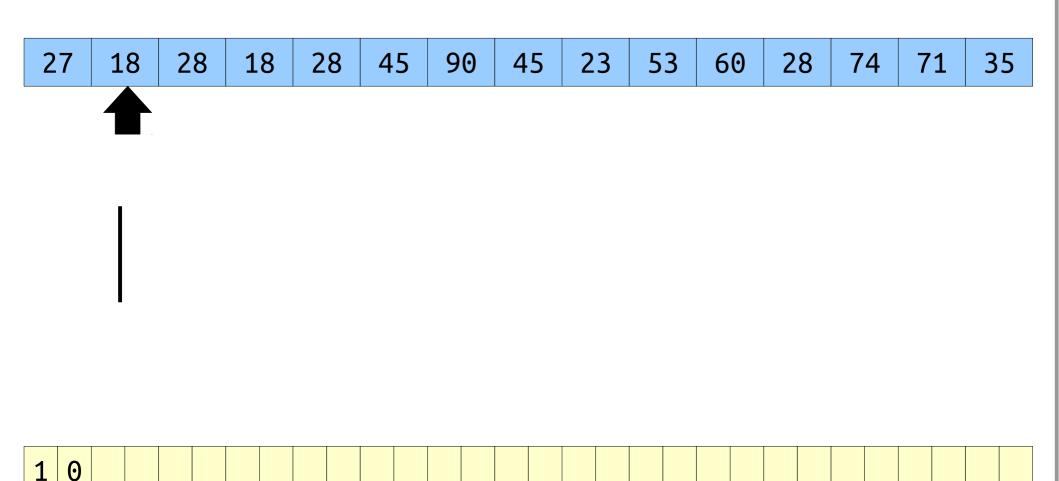


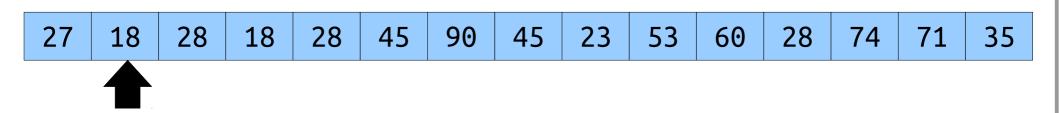


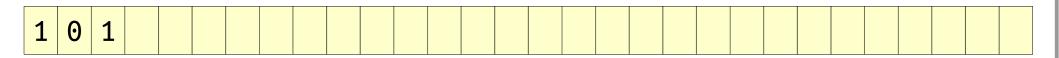


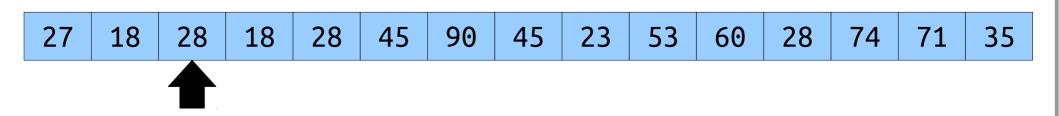


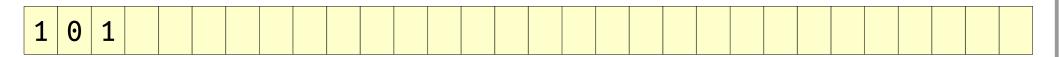


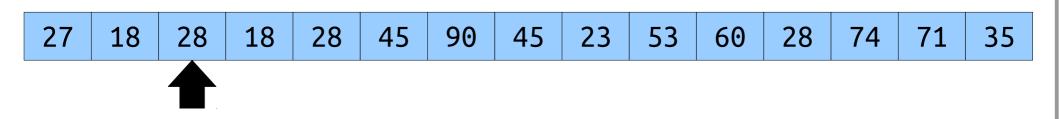


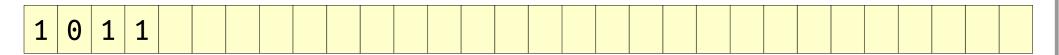


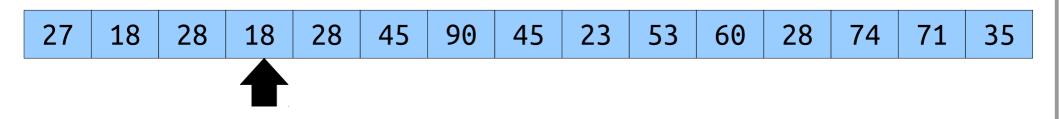


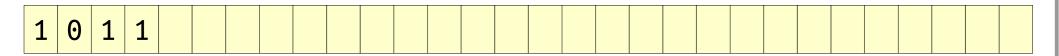


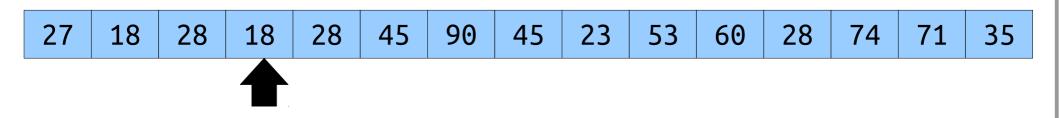


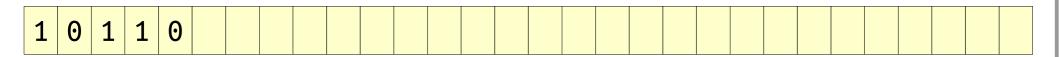


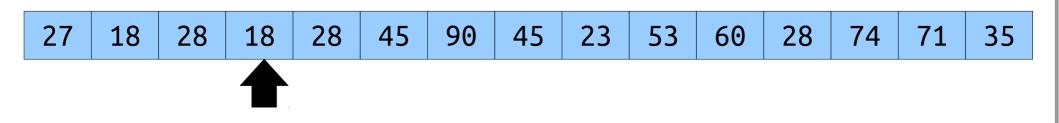


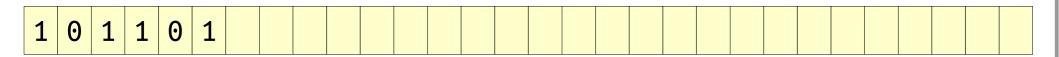


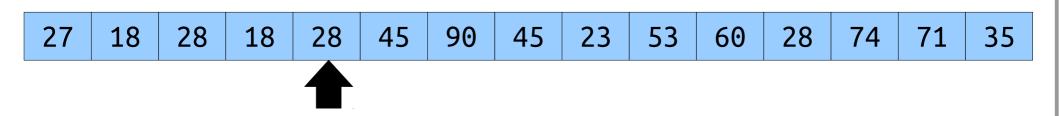


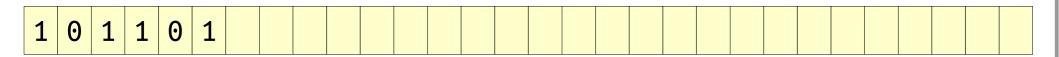


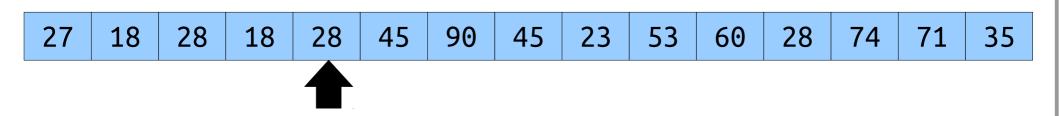


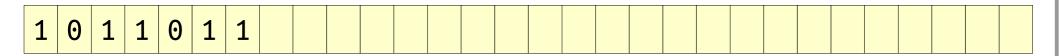


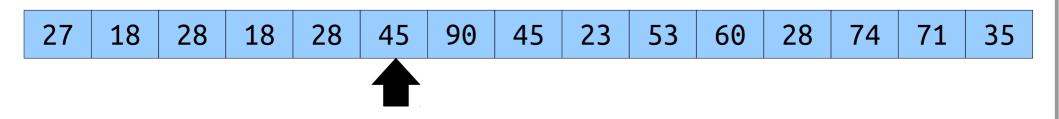


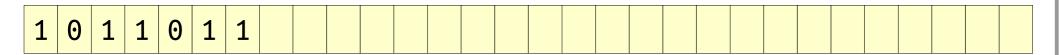


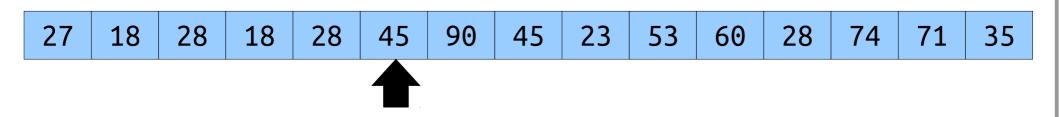




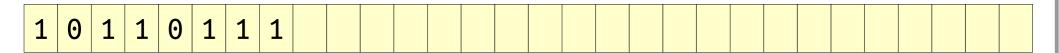


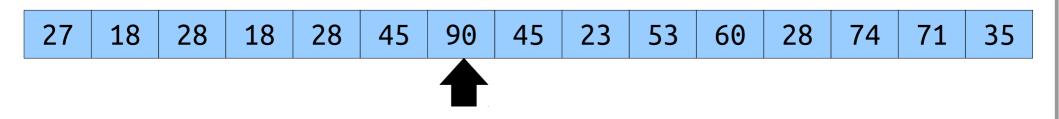




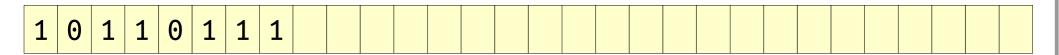


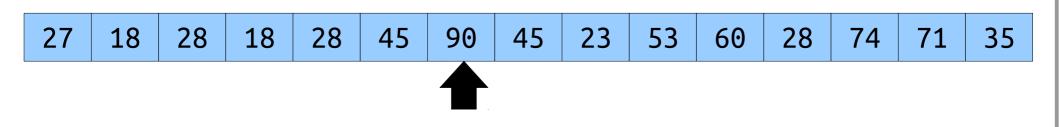
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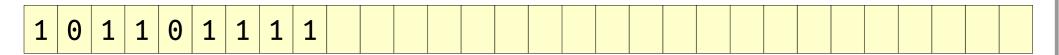


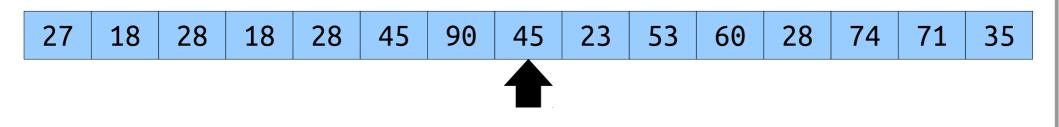
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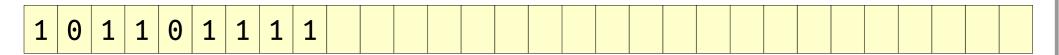


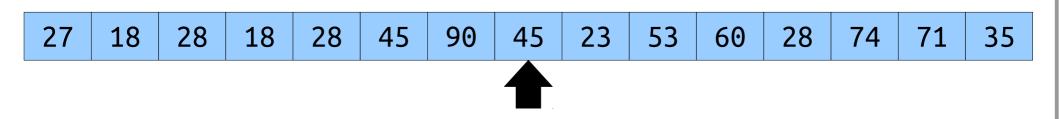
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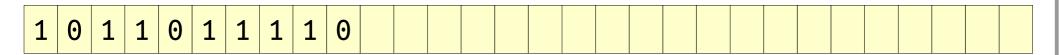


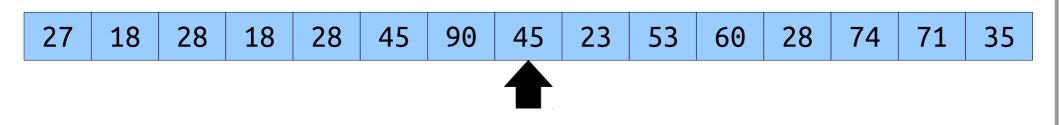
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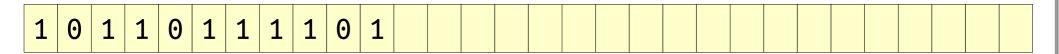


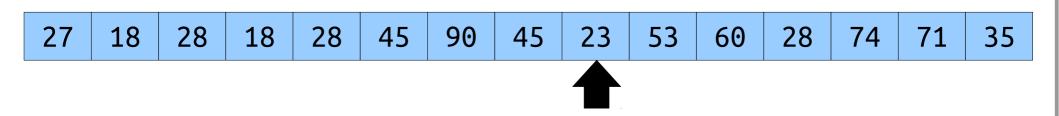
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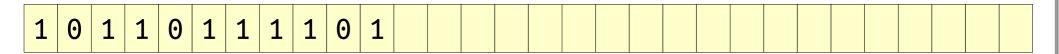


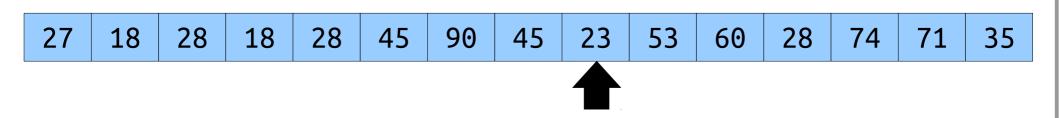
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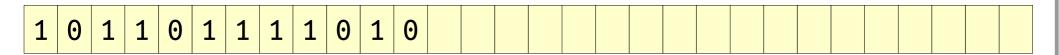


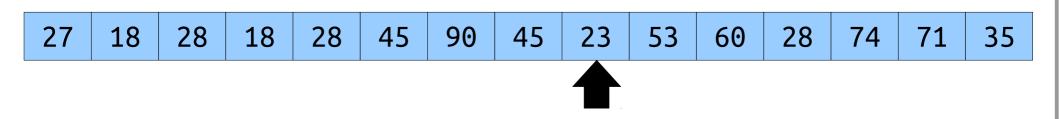




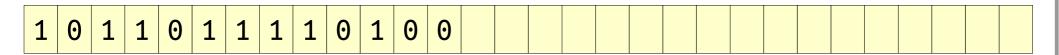


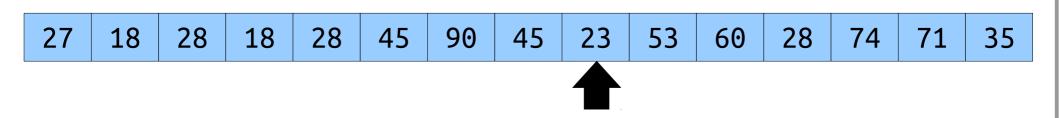
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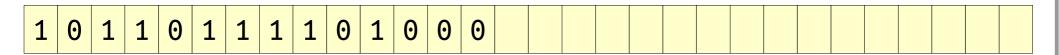


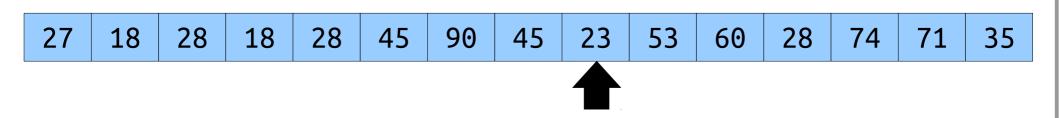


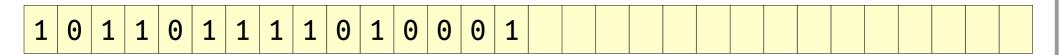


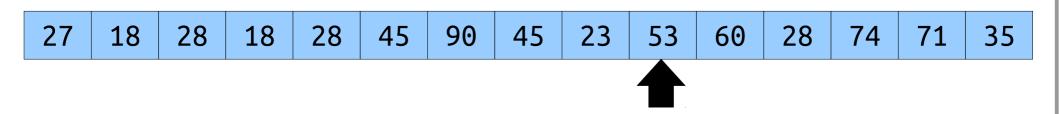


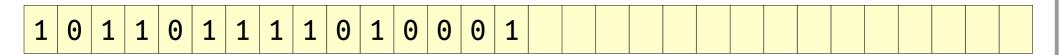


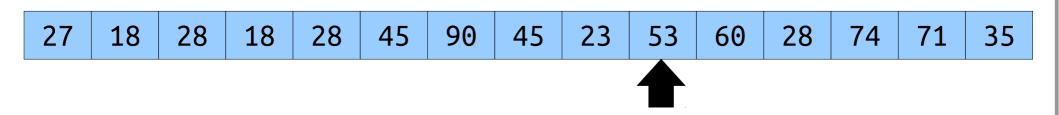






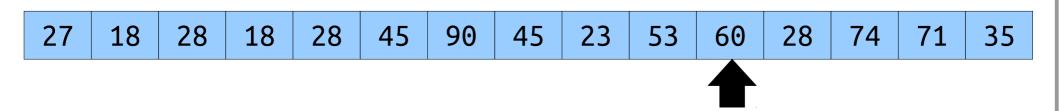






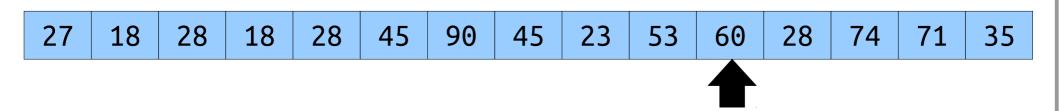
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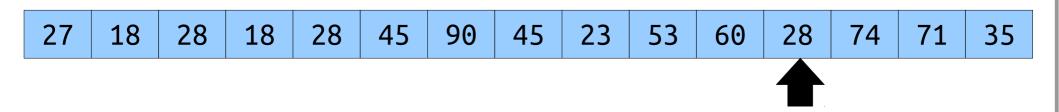
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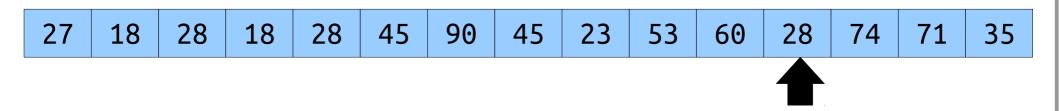
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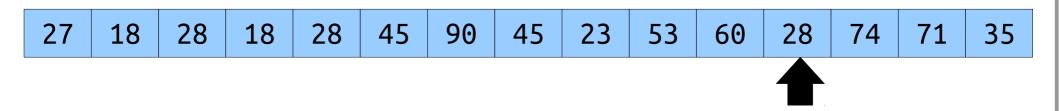
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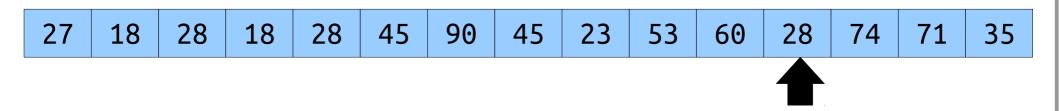


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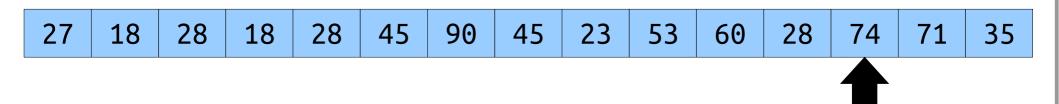






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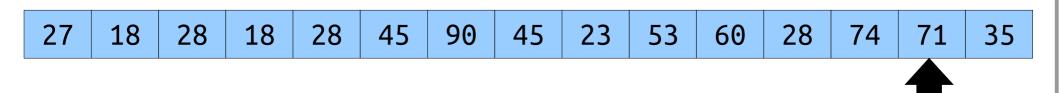
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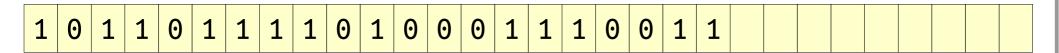


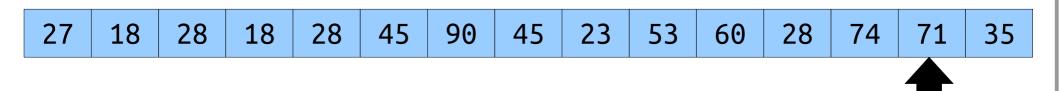
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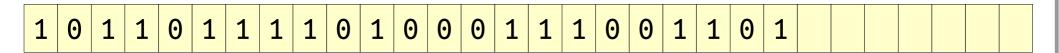
















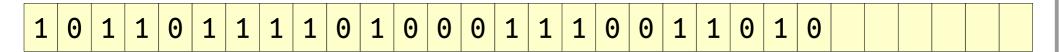
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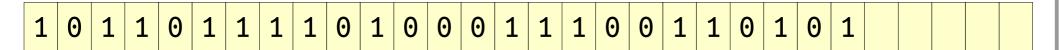


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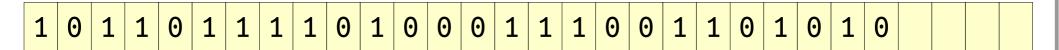


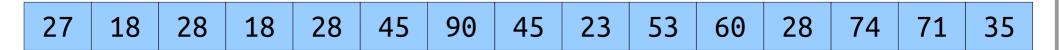
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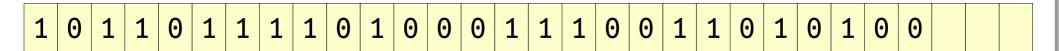




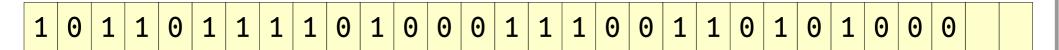
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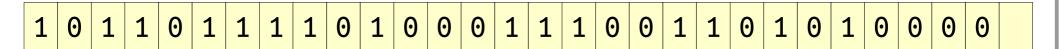


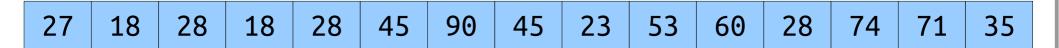


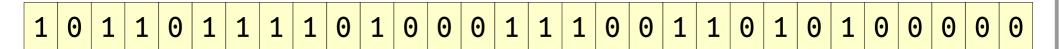




27 18 28 18 28 45 90 45 23 53 60 28 74 71 35









When they have the same Cartesian tree number!

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And we can check this in time O(b)!

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And it's easier to store numbers than trees!

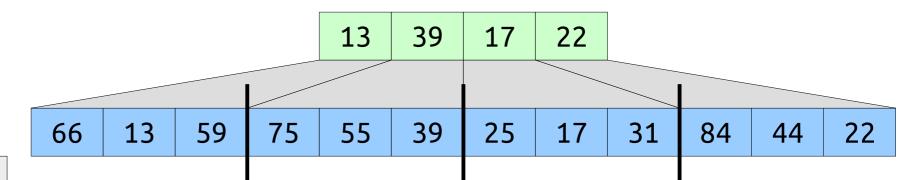
When they have the same Cartesian tree number!
And we can check this in time O(b)!
And it's easier to store numbers than trees!

How many block types are there, as a function of b?

At most 4^b , because of the above algorithm!

Putting it all Together

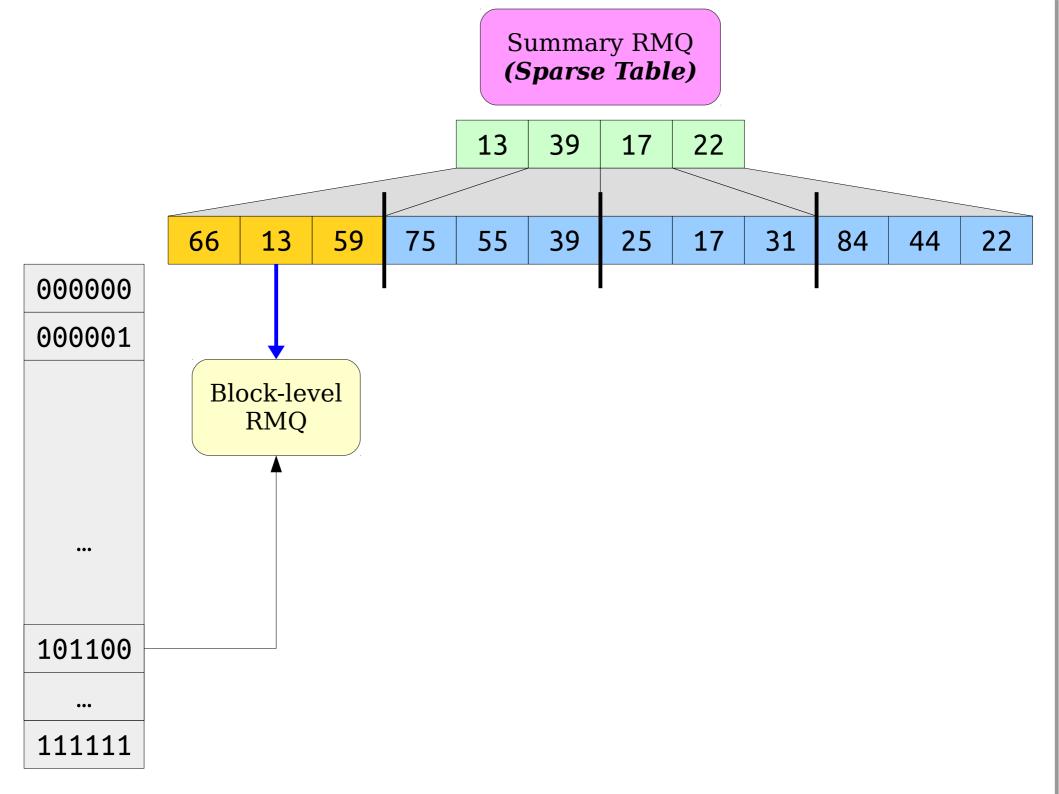
Summary RMQ (Sparse Table)

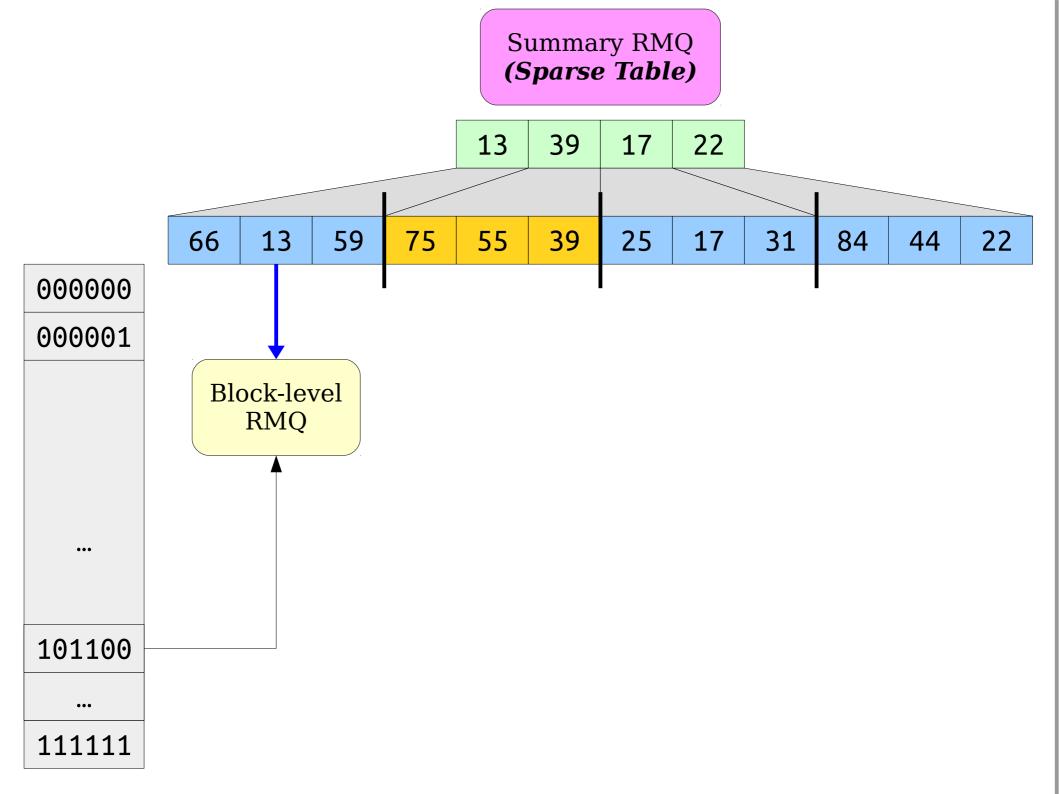


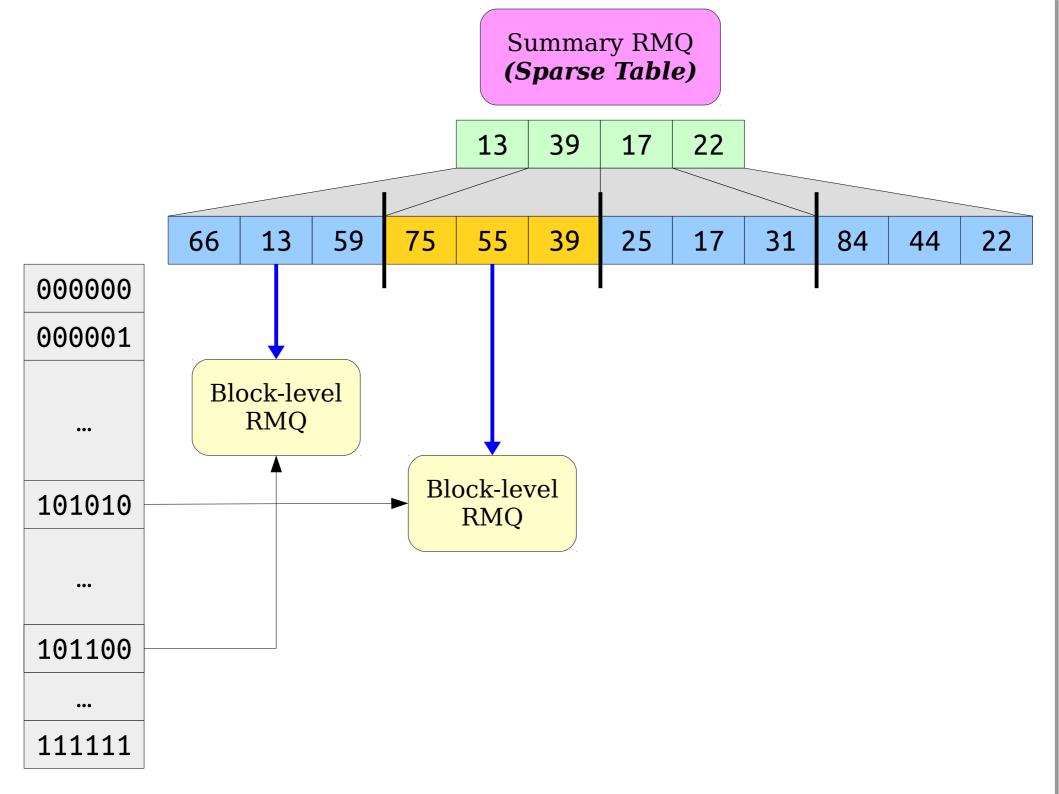
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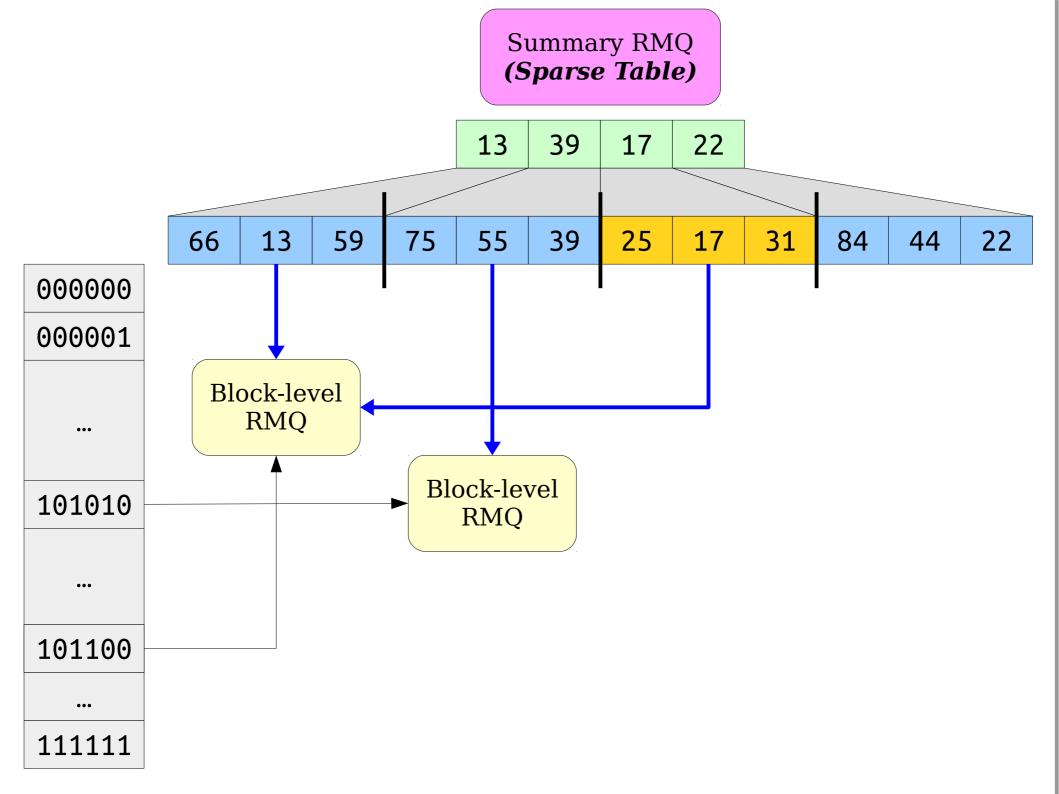
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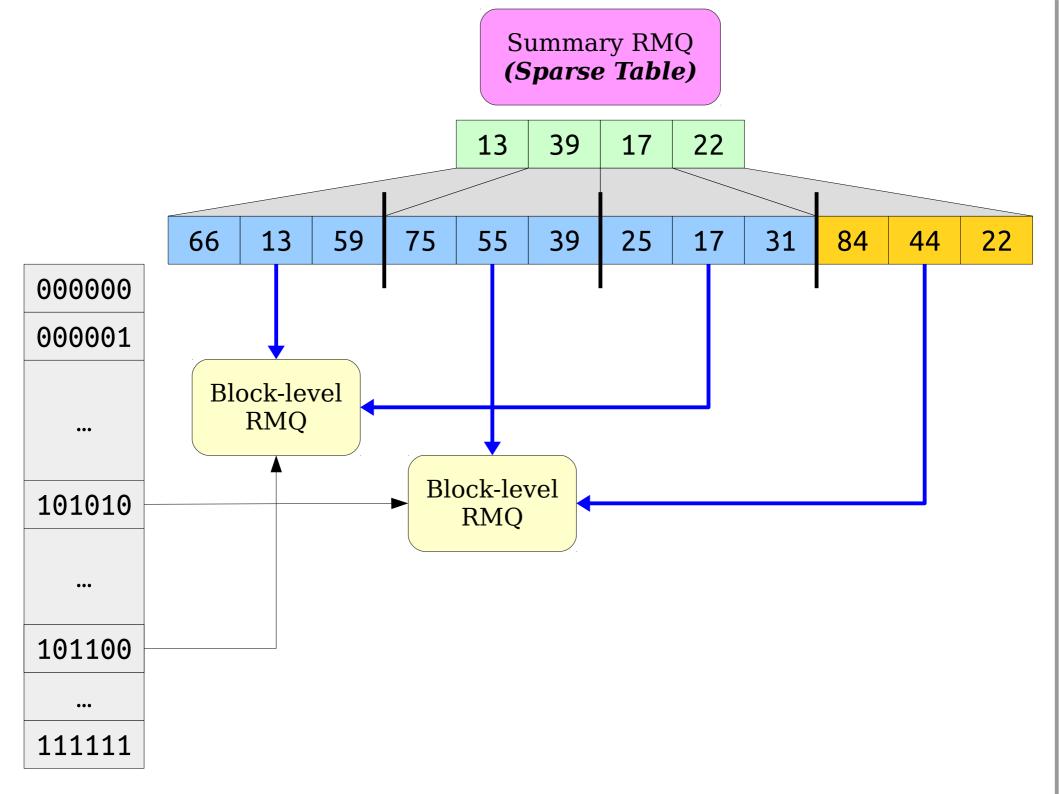
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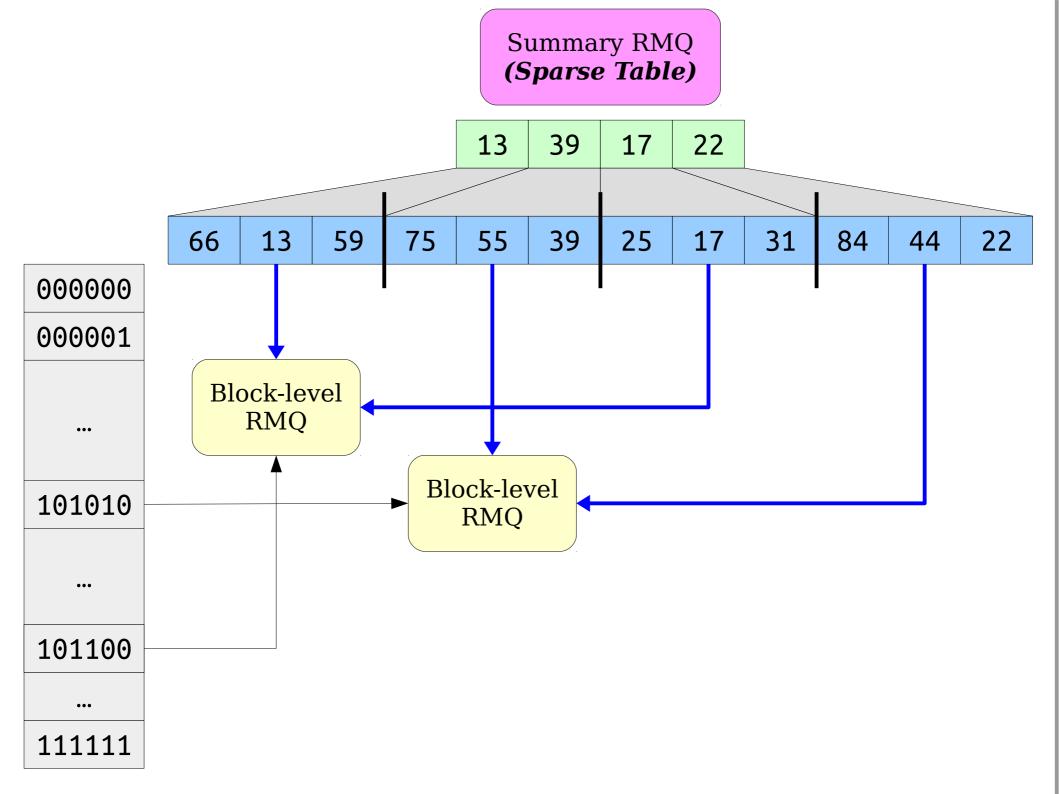


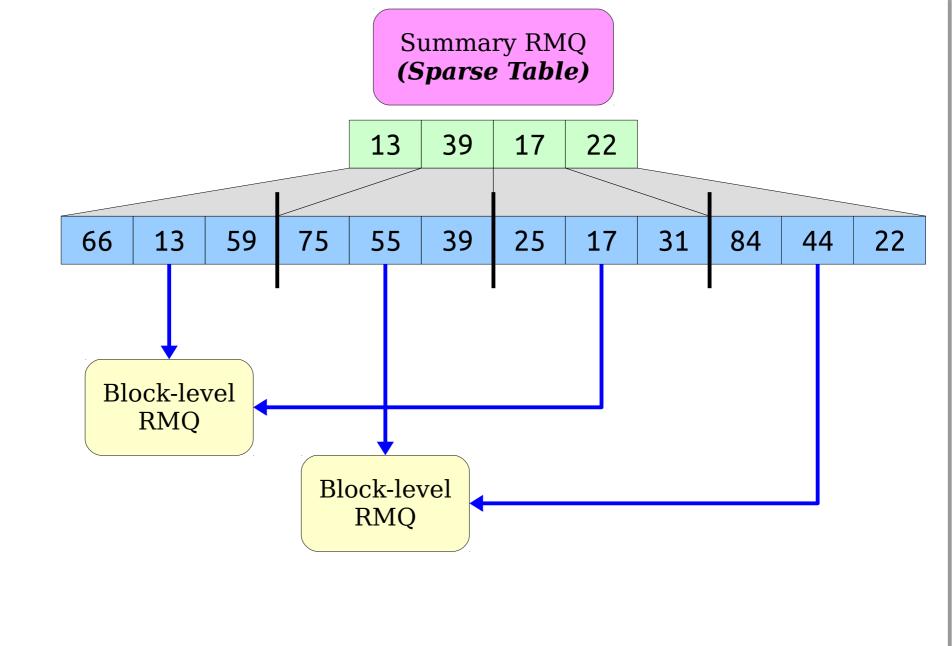












How Efficient is This?

We're using the hybrid approach, and all the types we're using have constant query times.

Query time: O(1)

$$O(n + (n / b) \log (n / b) + b^2 4^b)$$

Compute block minima; compute Cartesian tree numbers of each block.

Construct at most 4^b RMQ structures at a cost of $O(b^2)$ each.

Our preprocessing time is

$$O(n + (n / b) \log (n / b) + b^2 4^b)$$

Build a sparse table on blocks of size n / b.

This term grows exponentially in n unless we pick $b = O(\log n)$.

Our preprocessing time is

$$O(n + (n / b) \log (n / b) + b^2 4^b)$$

This term will be superlinear unless we pick $b = \Omega(\log n)$.

$$O(n + (n / b) \log (n / b) + b^2 4^b)$$

$$O(n + (n / b) \log n + b^2 4^b)$$

$$O(n + (n / b) \log n + b^2 4^b)$$

$$O(n + (n / b) \log n + b^2 4^b)$$

$$O(n + (n / k \log_4 n) \log n + b^2 4^b)$$

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$$O(n + (n / \log n) \log n + b^2 4^b)$$

$$O(n + (n / log n) log n + b^2 4^b)$$

$$O(n + n + b^2 4^b)$$

$$O(n+n+b^2 4^b)$$

$$O(n+n+b^2 4^b)$$

$$O(n+n+b^2 4^{k \log_4 n})$$

$$O(n + n + b^2 4^{\log_4 n^k})$$

$$O(n+n+b^2 4^{\log_4 n^k})$$

$$O(n + n + b^2 n^k)$$

$$O(n + n + (k \log_4 n)^2 n^k)$$

$$O(n + n + (k \log_4 n)^2 n^k)$$

$$O(n + n + (\log n)^2 n^k)$$

$$O(n + n + (\log n)^2 n^k)$$

$$O(n + n + (\log n)^2 n^k)$$

Suppose we pick $b = k \log_4 n$ for some constant k.

$$O(n + n + (\log n)^2 n^{1/2})$$

Suppose we pick $b = k \log_4 n$ for some constant k.

$$O(n + n + n)$$

Suppose we pick $b = k \log_4 n$ for some constant k.

Suppose we pick $b = k \log_4 n$ for some constant k.

The Fischer-Heun Structure

- This data structure is called *Fischer-Heun* structure. It uses a modified version of our hybrid RMQ framework:
 - Set $b = \frac{1}{2} \log_4 n = \frac{1}{4} \log_2 n$.
 - Split the input into blocks of size *b*. Compute an array of minimum values from each block.
 - Build a sparse table on that array of minima.
 - Build per-block RMQ structures for each block, using Cartesian tree numbers to avoid recomputing RMQ structures unnecessarily.
 - Make queries using the standard hybrid solution approach.
- This is an (O(n), O(1)) solution to RMQ!

The Method of Four Russians

- The technique employed here is an example of the *Method of Four Russians*.
 - Break the problem of size n into subproblems of size b, plus some top-level problem of size n / b.
 - This is called a *macro/micro* decomposition.
 - Solve all possible subproblems of size *b*.
 - Here, we only solved the subproblems that actually came up in the original array, but that's just an optimization.
 - Solve the overall problem by combining solutions to the micro and macro problems.
- This is a great way to shave off log factors, which are both theoretical and practical wins!

Why Study RMQ?

- I chose RMQ as our first problem for a few reasons:
 - See different approaches to the same problem.
 Different intuitions produced different runtimes.
 - **Build data structures out of other data structures**. Many modern data structures use other data structures as building blocks, and it's very evident here.
 - **See the Method of Four Russians**. This trick looks like magic the first few times you see it and shows up in lots of places.
 - **Explore modern data structures**. This is relatively recent data structure (2005), and I wanted to show you that the field is still very active!
- So what's next?

Next Time

• String Data Structures

Text, bytes, and genomes are everywhere.
 How do we store them?

• Tries

A canonical string data structure.

Suffix Trees

• Exposing the hidden structures of strings.