

Bursting Flow Query on Large Temporal Flow Networks

Abstract

Recently, queries that find bursting patterns in temporal graph data have received increasing research attention. In particular, finding the flow in temporal networks whose flow values are bursting in a time interval has numerous applications, such as detecting the money laundering by the maximum average transfer flow in a transaction graph, and the congestion by the maximum average traffic flow in a road network. Despite its usefulness, there is limited research on querying such a flow pattern. In this paper, we study a novel query of finding a *flow pattern of burstiness* in a temporal flow network. In a nutshell, this query aims to find the *bursting flow* f from a source node to a sink node such that the ratio of f 's flow value to the time interval length of f is maximized. To solve this query, we propose the first solution called BFQ that enumerates all the necessary time intervals and then computes the maximum flow value for each interval. Based on BFQ, we propose an efficient solution called BFQ*, which consists of optimization techniques that incrementally compute the maximum flows without computing the common parts of flows from scratch. The experimental results demonstrate the efficiency of our solutions. A case study on a real world transaction network demonstrates the application of this bursting flow query on detecting abnormal transactions.

1 Introduction

Temporal graphs, such as social networks, blockchain networks and road networks [40, 45, 48, 50], have emerged widely in many applications, including social network analysis, transportation routing and crime detection [15, 23, 26, 29, 30, 38, 52]. In a temporal graph, an edge can be denoted by a triple (u, v, τ) , where u and v are two nodes, and τ represents the timestamp of the interaction between u and v [3, 22]. Moreover, the edges may have their capacities and in such case, the temporal networks are more accurately referred to as *temporal flow networks*. As the interaction patterns in temporal graphs are often known to be *bursty* (i.e., the interaction events of humans often happen in a short time interval), the bursting queries are emerging in temporal graph applications [7, 9, 33, 54].

In this paper, we study a *novel flow problem on temporal flow networks* called δ -bursting flow (δ -BFlow). Given a source node s and a sink node t of a temporal flow network N_T , the δ -BFlow problem is to find in N_T a temporal flow F starting from s at starting timestamp τ_s to t at ending timestamp τ_e , such that i) the length of F 's time interval $[\tau_s, \tau_e]$, i.e., $\tau_e - \tau_s$, is not less than the parameter δ , and ii) the flow density of F , defined by the ratio of F 's flow value (e.g., the total transaction amount from s to t during $[\tau_s, \tau_e]$ in transaction networks) to the length of F 's time interval, is maximized. We illustrate the applications of the δ -BFlow query with an example.

EXAMPLE 1. A digital payment company recently finds two fraud suspects, and wants to trace whether a large volume of money was

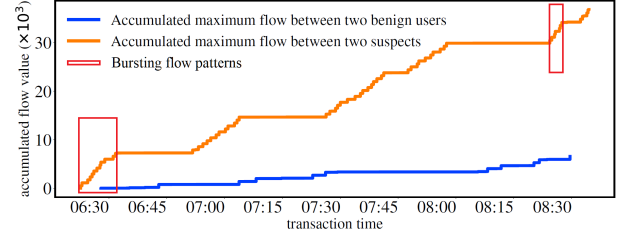


Figure 1: Examples of δ -BFlows on a transaction network

transferred from one to another in a short span of time. The transfers may not be direct transfers but through a large network of people. The company wants to look for a time interval where the density of money transferred was the most, i.e., the amount of money transferred divided by the length of the transfer time interval. They would also like to filter any trivial flows based on one-off transactions, so they would like the transfer time interval having a length at least δ . Figure 1 shows by (red) rectangles some examples of such bursting flow pattern between these two suspects in a transaction network found by a δ -BFlow query, where δ refers to 4 minutes. Note that there are also bursting flow patterns between benign users whose time intervals are relatively short (e.g., 6:48-6:49 and 7:13-7:14), while δ can be used to filter these patterns. Similar scenarios of finding the bursting flow pattern can be found in other applications [4, 10, 31, 41].

There have been works on finding the maximum flow in temporal flow networks [2, 19, 27], which focus on finding the absolute maximization of flow values. However, such maximization on temporal flow may happen during a long time interval, which cannot quantify the speed of temporal flows for finding the δ -BFlow. Hence, in this paper, we take the first step towards querying the temporal flows on temporal flow networks that have the *maximum average flow value during their time intervals*. There are two main challenges.

Challenge 1: To define the bursting flow in temporal flow networks.

To define a novel notion of bursting flow in temporal flow networks, we take as the metrics of the burstiness the average flow value of a flow f from source node s to sink node t during f 's time interval from f 's starting timestamp on s to f 's ending timestamp on t . In particular, we propose a novel concept of a bursting flow in temporal flow networks called δ -bursting flow (δ -BFlow), whose time interval has length not shorter than a parameter δ . The δ value is used to filter trivial bursting flows that happen during extremely short time intervals since the average flow value can be large due to a tiny time interval even when this flow has a small flow value.

Challenge 2: To propose efficient solution for finding δ -BFlow.

To find the novel δ -BFlow in temporal flow networks, existing methods cannot be applied directly since either the solutions for other bursting pattern queries are not compatible with the flow computation, or the solutions for discovering classical flow patterns on flow networks cannot handle the burstiness on temporal flow networks. Therefore, to tackle this challenge, we first propose a practical solution to find δ -BFlow in a temporal flow network N_T by two steps: i) enumerate all possible candidate time intervals of N_T ; and ii) transform N_T into flow networks w.r.t. these candidate intervals and

then find the maximum flows (Maxflows) in these transformed flow networks. To further improve the efficiency of this solution, we propose optimized algorithms that incrementally compute Maxflows for the candidate intervals instead of finding them from scratch.

To the best of our knowledge, this is *the first work to study the bursting flow problem on temporal flow networks*.

Contributions. The contributions of this paper are as follows.

- We propose a novel concept of a bursting flow in the temporal flow network called δ -bursting flow (δ -BFlow) to capture the pattern of temporal flows whose flows burst in a certain time interval. δ -BFlow is a flow from the source node to the sink node that has the maximum flow density, that is the ratio of its flow value to the length l of its time interval where l is not less than a parameter δ . In this work, we study a *novel δ -BFlow query* that is to find the flow density and the time interval of δ -BFlow from a given source node to a given sink node in a temporal flow network. The δ -BFlow query can be answered in polynomial time.
- We propose the first practical solution called BFQ for answering the δ -BFlow query. BFQ has two procedures: i) transforming a temporal flow network N_T into an equivalent flow network for each of the $O(d^2)$ enumerated candidate time intervals instead of all the $O(|T|^2)$ possible time intervals, where d and $|T|$ are the degree of the source node (or the sink node) and the number of timestamps in N_T , respectively, and ii) computing the flow value $|f|$ of Maxflow f in the transformed flow network for each interval $[\tau_s, \tau_e]$ and hence, the flow density $|f|/(\tau_e - \tau_s)$ by using the traditional Maxflow algorithms.
- To further improve the efficiency of BFQ, we propose incremental Maxflow algorithms to avoid the redundant computation on finding the same augmenting paths when computing Maxflows on the transformed flow networks for different time intervals. We also propose pruning strategies to accelerate the Maxflow computation.
- We conduct comprehensive experiments on real world temporal flow networks to evaluate the efficiency of our proposed algorithms. A case study on a real world transaction network is presented to demonstrate the application of δ -BFlow for anomaly detection.

Organization. Section 2 discusses the related work. Section 3 presents the preliminaries and the problem statement. A practical solution is proposed in Section 4. Section 5 presents our efficient optimized solution. Experimental evaluations are presented in Section 6. Section 7 draws the conclusion of this paper.

2 Related Work

There have been a lot of research studying the maximum flow problem on traditional networks [12, 13, 17]. In recent years, analysis on temporal graph query processing has attracted much attention and there comes various temporal query processing [15, 29, 32].

Maximum flow problem (Maxflow problem). Maxflow problem is a classical problem. Various solutions have been proposed over the past few decades. One kind of solutions makes use of the *augmenting path*, which is a path of positive capacity from a source node to a sink node. Ford et al. [13] proposed the first algorithm to answer the Maxflow problem by iteratively finding an augmenting path in the network. As a practical solution which is also used in this work, Dinic [12] proposed to i) construct a layered network from the residual network of the original network

by using the *breadth-first search*, and ii) find an extension of the shortest augmenting path called *block flow* in the layered network. These steps are repeated till no more block flows can be found. Hochbaum [20] proposed the *pseudoflow* algorithm to organize all unsaturated edges in the flow network by using a normalized tree and then accelerate the process of finding augmenting paths by incorporating the dynamic tree [36].

Different from augmenting path based methods, Goldberg et al. [17] proposed a *push-relabel* method to compute the maximum flow, which consists of i) the push operation that move units of flow from an active node to its neighbors, and ii) the relabel operation that updates the labels of the active nodes based on the labels of the neighbor nodes. Both operations are repeatedly performed till no more applicable operations can be performed. There are also works on finding Maxflow on networks of specific topologies with more efficient solutions [5, 21]. Recently, Chen et al. [6] proposed a Maxflow algorithm with a theoretically almost-linear time complexity. However, it has no practical implementation.

As a widely used Maxflow algorithm, Dinic takes $O(|V|^2 \cdot |E|)$ time, where V and E are the set of nodes and the set of edges in a flow network, respectively. In practice, Dinic often has the best overall performance due to many optimized efforts. The time complexities of some other existing Maxflow algorithms are summarized in Appendix A in the technical report [1].

Query processing on the temporal network. There has been a growing interest in query processing on temporal graphs, such as reachability queries [47, 55], path queries [38, 39, 46, 53], subgraph queries [24, 54, 56] and community search queries [29, 32, 51]. Recently, Chen et al. [8] studied the reachability queries on temporal bipartite graphs; Wen et al. [42, 43] studied the span-reachability queries on large temporal graphs by relaxing the time order dependency of paths; Huang et al. [25] studied the minimum path pair query problem of the time-varying network; Qin et al. [33] studied mining bursting core in large temporal graphs; and Xie et al. [49] studied querying connected components in large temporal graphs *without* considering the flow within the components.

Regarding the flow problem on temporal networks, [14, 34, 44] studied the earliest arrival flow problem to determine the earliest time that a flow comes from a source node to a sink node. To solve Maxflow on dynamic networks with an insertion or deletion of an edge, Kumar et al. [28] proposed incremental algorithm based on the push-relabeling algorithm while Greco et al. [18] proposed incremental algorithm based on finding the augmenting paths. However, these methods cannot be adopted directly on finding temporal flows due to the time constraint on the edges of temporal paths. To study Maxflow on temporal networks, Horst et al. [19] assumed that the capacity of each edge changes over time while Akrida et al. [2] characterized the edges in the temporal flow network with specific or random availabilities on time. Kosyfaki et al. [27] studied the Maxflow problem on temporal flow networks with the classical flow transfer model and a greedy flow transfer model that the maximum possible quantity of capacity is transferred on each edge. To the best of our knowledge, the δ -bursting flow problem has not been studied before.

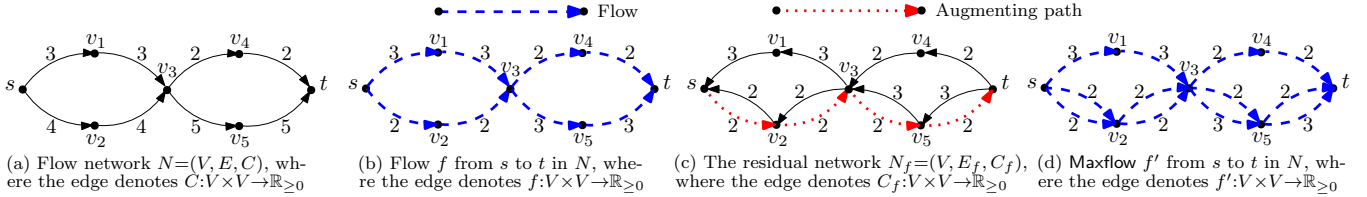


Figure 2: Illustration of the notations in classical flow networks

3 Preliminaries

In this section, we present notations for describing the bursting flow problem on temporal flow networks.

3.1 Background

We first introduce some definitions for classical flow problems.

Flow network. A flow network, denoted by $N = (V, E, C)$, is a directed graph, where i) V and E are the sets of nodes and edges, respectively, and ii) $C: V \times V \rightarrow \mathbb{R}_{\geq 0}$ is a capacity mapping function such that $\forall u, v \in V$, if $(u, v) \in E$, $C(u, v)$ equals a positive value which denotes the capacity of the edge from u to v ; otherwise, $C(u, v) = 0$.

Flow. Given a flow network $N = (V, E, C)$, a flow from a source node s (or simply source) to a sink node t (or simply sink) is denoted by a mapping function $f: V \times V \rightarrow \mathbb{R}_{\geq 0}$ that satisfies the following:

- a) **Capacity constraint.** $\forall u, v \in V$, $0 \leq f(u, v) \leq C(u, v)$; and
- b) **Flow conservation.** $\forall u \in V - \{s, t\}$, $\sum_{v \in V} f(v, u) = \sum_{v \in V} f(u, v)$.

For a flow f from source s to sink t , f 's flow value $|f|$ is,

$$|f| = \sum_{v \in V} f(s, v) = \sum_{v \in V} f(v, t) \quad (1)$$

Then, the maximum flow is defined as follows.

DEFINITION 1. (Maximum flow (Maxflow)) Given a flow network N , a source s , and a sink t , the maximum flow from s to t in N is a flow f from s to t in N such that the flow value $|f|$ is maximized.

To compute Maxflow from a source to a sink in flow networks, the residual network and augmenting path are used in the classical Ford-Fulkerson [13] and Dinic [12] solutions.

Residual network. Given a flow network $N = (V, E, C)$ and a flow f in N , the residual network of N w.r.t. f , denoted by $N_f = (V, E_f, C_f)$, is a directed graph that satisfies the following:

- V is the set of nodes;
- $C_f: V \times V \rightarrow \mathbb{R}_{\geq 0}$ is a capacity mapping function such that if $(u, v) \in E$, $C_f(u, v) = C(u, v) - f(u, v)$ and $C_f(v, u) = f(u, v)$. Otherwise, $C_f(u, v) = 0$; and
- $E_f = \{(u, v) \mid u, v \in V \text{ and } C_f(u, v) > 0\}$ is the set of edges.

Augmenting path. Given a residual network $N_f = (V, E_f, C_f)$ of a flow network N w.r.t. a flow f from source s to sink t in N , an augmenting path is a path from s to t in this residual network N_f . For an augmenting path p in N_f , the value of the flow passes through p (or simply the flow value of p), denoted by $\text{Flow}(p)$, equals to,

$$\text{Flow}(p) = \min_{(u, v) \text{ is an edge of } p} C_f(u, v) \quad (2)$$

According to the definitions of the residual network and the augmenting path, $\text{Flow}(p)$ is non-zero. Note that C_f of a residual network is defined based on an assumption on the flow network $N = (V, E, C)$: if there exists an edge from node u to node v in N ,

there are no edges from v to u in N [17, 37].¹ For simplicity, we apply the same assumption in this paper.

EXAMPLE 2. Figure 2 illustrates the notations with examples.

- Figure 2(a) shows an example of a flow network $N = (V, E, C)$, where i) $V = \{s, v_1, v_2, v_3, v_4, v_5, t\}$, ii) $E = \{(s, v_1), (s, v_2), (v_1, v_3), (v_2, v_3), (v_3, v_4), (v_3, v_5), (v_4, t), (v_5, t)\}$, and iii) $C(s, v_1) = C(v_1, v_3) = 3$, $C(s, v_2) = C(v_2, v_3) = 4$, $C(v_3, v_4) = C(v_4, t) = 2$, $C(v_3, v_5) = C(v_5, t) = 5$, and $C(u, v) = 0$, as $(u, v) \notin E$;
- The (blue) dashed paths in Figure 2(b) show an example of a flow f from source s to sink t in N , where $f(s, v_1) = f(v_1, v_3) = f(v_3, v_5) = f(v_5, t) = 3$, $f(s, v_2) = f(v_2, v_3) = f(v_3, v_4) = f(v_4, t) = 2$, and $f(u, v) = 0$, as $(u, v) \notin E$. The flow value $|f|$ is 5;
- Figure 2(c) shows the residual network N_f of N w.r.t. flow f in Figure 2(b). The (red) dotted path p from s to t in Figure 2(c) shows an augmenting path in N_f having $\text{Flow}(p) = 2$; and
- Figure 2(d) shows Maxflow f' from s to t in N having $|f'| = 7$.

3.2 Temporal Flow and Problem Statement

In this subsection, we extend some definitions above in the temporal network for self-containedness and consistency of symbols, and then define the δ -bursting flow. These symbols are compatible with some existing works [27, 33, 49].

Temporal network. A temporal network, denoted by a 3-ary tuple (V, E_T, T) , is a directed graph, where i) V is the set of nodes, ii) $T = [\tau_1, \dots, \tau_n]$ is a sequence of timestamps such that $\tau_j - \tau_{j-1}, j \in [2, n]$ is a constant (w.l.o.g, the constant is assumed to be 1 unless specified otherwise), and iii) $E_T = \{(u, v, \tau) \mid u, v \in V, \tau \in T\}$ is the set of temporal edges. A temporal edge $e = (u, v, \tau) \in E_T$ denotes a directed edge from node u to node v having timestamp τ .

Temporal flow network. A temporal flow network, denoted by $N_T = (V, E_T, T, C_T)$, is a directed graph, where i) (V, E_T, T) is a temporal network, and ii) $C_T: V \times V \times T \rightarrow \mathbb{R}_{\geq 0}$ is a capacity mapping function such that $\forall u, v \in V, \tau \in T$, if $(u, v, \tau) \in E_T$, $C_T(u, v, \tau)$ equals a positive value which denotes the capacity of the temporal edge from u to v having timestamp τ ; otherwise, $C_T(u, v, \tau) = 0$.

Temporal flow. Given a temporal flow network $N_T = (V, E_T, T, C_T)$, a temporal flow from source s at starting timestamp τ_s to sink t at ending timestamp τ_e ($\tau_e > \tau_s$) is denoted by a mapping function $F: V \times V \times T \rightarrow \mathbb{R}_{\geq 0}$ that satisfies the following:

- a) **Capacity constraint.** $\forall u, v \in V, \tau \in T, 0 \leq F(u, v, \tau) \leq C_T(u, v, \tau)$;
- b) **Flow conservation.** $\forall u \in V - \{s, t\}$,

$$\sum_{v \in V} \sum_{\tau \in [\tau_s, \tau_e]} F(v, u, \tau) = \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau_e]} F(u, v, \tau); \text{ and} \quad (3)$$

¹To handle the case that both of (u, v) and (v, u) exist in E , we can revise the flow network $N = (V, E, C)$ by removing (v, u) and then creating a new node w and two edges (v, w) , (w, u) such that $C(v, w) = C(w, u) = C(v, u)$. In this way, existing Maxflow algorithms by finding augmenting paths in residual networks can be used on the revised network of N to compute Maxflow in N .

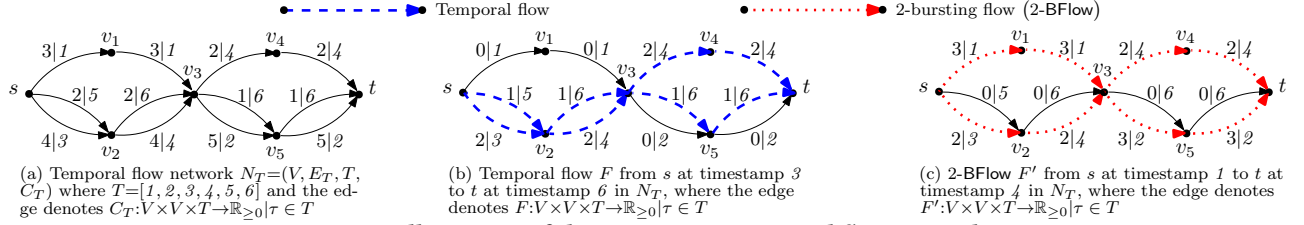


Figure 3: Illustration of the notations in temporal flow networks

Table 1: Frequently used notations

Notation	Description
$s; t$	the source node; the sink node
$\delta; T$	the bursting parameter for δ -BFlow; sequence of timestamps
$N; N_T$	flow network; temporal flow network
$C; C_T$	capacity mapping function of N ; capacity mapping function of N_T
$f; F$	flow; temporal flow
N_f	the residual network of N w.r.t. f
$p; \text{Flow}(p)$	augmenting path; the value of the flow passes through augmenting path p
$\tau_s; \tau_e$	the starting timestamp; the ending timestamp
$[\tau, \tau']$	time interval where $\tau, \tau' \in T$ and $\tau \leq \tau'$
$N_{[\tau, \tau']}$	the transformed flow network of N_T w.r.t. $[\tau, \tau']$
$u; \langle u, \tau \rangle$	node in N or N_T ; node in transformed flow network
$(u, v); \langle u, v, \tau \rangle$	edge from u to v in N ; edge from u to v at timestamp τ in N_T
$(\langle u, \tau \rangle, \langle v, \tau' \rangle)$	edge from $\langle u, \tau \rangle$ to $\langle v, \tau' \rangle$ in transformed flow network
$\text{TiStamp}_{\text{out}}(u)$	set of the timestamps of the out-going edges of u in N_T
$\text{TiStamp}_{\text{in}}(u)$	set of the timestamps of the in-coming edges of u in N_T
$\text{Ti}(u)$	set of the timestamps of the edges of u in N_T that may be part of flows from s to t : $\text{Ti}(s) = \text{TiStamp}_{\text{out}}(s)$, $\text{Ti}(t) = \text{TiStamp}_{\text{in}}(t)$, and $\text{Ti}(u) = \text{TiStamp}_{\text{out}}(u) \cup \text{TiStamp}_{\text{in}}(u)$, $u \neq s, t$
$\text{Seq}(\text{Ti})$	sequence consisting of the elements in Ti in the ascending order
$\text{MF}[\tau_s, \tau_e]$	Maxflow from $\langle s, \tau_s \rangle$ to $\langle t, \tau_e \rangle$ in $N_{[\tau_s, \tau_e]}$ ($\tau_s \geq \tau'_s$ and $\tau_e \leq \tau'_e$)
d_{\max}	the maximum degree of nodes of a temporal flow network
d	$\max\{ \text{Ti}(s) , \text{Ti}(t) \}$
\oplus	binary operator to combine transformed flow networks
\setminus	binary operator to subtract one transformed flow network from another
$\Delta_\tau(N)$	timestamp injection operator on transformed flow network N for τ

(c) **Flow's time constraint.** $\forall u \in V - \{s, t\}, \tau' \in [\tau_s, \tau_e]$,

$$\sum_{v \in V} \sum_{\tau \in [\tau_s, \tau']} F(u, v, \tau) \geq \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau']} F(u, v, \tau) \quad (4)$$

Intuitively, the time constraint of a temporal flow F enforces that, at any node u excluding the source s and the sink t , for all time intervals starting at the starting timestamp and finishing before the ending timestamp, the incoming flow of F to u has a flow value not less than the flow value of the outgoing flow of F from u . Thus, from the starting timestamp to any timestamp, there is no node (excluding s and t) has more outgoing flow than its incoming flow.

For a temporal flow F from source s at starting timestamp τ_s to sink t at ending timestamp τ_e , F 's flow value $|F|$ is,

$$|F| = \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau_e]} F(s, v, \tau) = \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau_e]} F(v, t, \tau) \quad (5)$$

Moreover, the flow density (or simply density) of F is defined by,

$$|F|/(\tau_e - \tau_s) \quad (6)$$

Table 1 lists some frequently used notations. In the following, we define a novel concept of a bursting flow in temporal flow networks called δ -bursting flow and present the problem statement.

DEFINITION 2. (δ -bursting flow (δ -BFlow)) Given a temporal flow network $N_T = (V, E_T, T, C_T)$, a source s , a sink t , a bursting parameter δ for bursting time interval, the δ -bursting flow is a temporal flow F from s at a starting timestamp τ_s to t at an ending timestamp τ_e that satisfies the conditions:

- a) $\tau_e - \tau_s \geq \delta$; and
- b) the flow density of F is maximized.

For a δ -BFlow F , we denote $[\tau_s, \tau_e]$ as F 's bursting interval. To simplify the pseudo code in this work, we define a binary record $(|F|/(\tau_e - \tau_s), [\tau_s, \tau_e])$ of F , where $|F|/(\tau_e - \tau_s)$ and $[\tau_s, \tau_e]$ are F 's density and bursting interval, respectively.

EXAMPLE 3. Figure 3(a) shows an example of a temporal flow network $N_T = (V, E_T, T, C_T)$, where $T = [1, 2, 3, 4, 5, 6]$ and the formatted data on each edge (u, v, τ) denotes $C_T(u, v, \tau) | \tau$; Figure 3(b) shows in (blue) dashed lines a temporal flow F from s at timestamp 3 to t at timestamp 6 in N_T , where $F(s, v_2, 3) = F(v_2, v_3, 4) = F(v_3, v_4, 4) = F(v_4, t, 4) = 2$, $F(s, v_2, 5) = F(v_2, v_3, 6) = F(v_3, v_5, 6) = F(v_5, t, 6) = 1$, and $F(u, v, \tau) = 0$, otherwise. The flow value $|F|$ of F is 3. We can also see an example of the time constraint on F that, for node v_2 and timestamp 5, $\sum_{v \in V} \sum_{\tau \in [1, 5]} F(v, v_2, \tau) = 3 \geq \sum_{v \in V} \sum_{\tau \in [1, 5]} F(v_2, v, \tau) = 2$; and Figure 3(c) shows in (red) dotted lines a 2-BFlow F' from s at 1 to t at 4 in N_T having $|F'| = 5$ and bursting interval $[1, 4]$. F' has a density of $5/3$, which is larger than the densities of any other temporal flows in N_T , e.g., the density $3/3$ of the temporal flow F shown in Figure 3(b). Therefore, F' is a 2-BFlow.

Problem statement. Given a temporal flow network $N_T = (V, E_T, T, C_T)$ and a bursting flow query $Q = (s, t, \delta)$ where $s, t \in V$, the goal is to find the density and bursting interval of the δ -BFlow from s to t in N_T .

4 A Practical Solution for δ -BFlow

In this section, we propose the first practical Bursting Flow Query Solution called BFQ that consists of i) the network transformation procedure (Section 4.1) that converts the problem of finding δ -BFlow on temporal flow network N_T into finding Maxflows on transformed flow networks of N_T w.r.t. all the candidate time intervals; and ii) the candidate interval enumeration procedure (Section 4.2) that reduces the number of candidate time intervals in practice. Section 4.3 illustrates how BFQ computes δ -BFlows in a temporal flow network.

4.1 Network Transformation

In this subsection, we first introduce the network transformation procedure that transforms a temporal flow network N_T into a flow network w.r.t. a time interval. Then, we prove that finding δ -BFlow in N_T is equivalent to finding Maxflows in N_T 's transformed flow networks w.r.t. all possible time intervals.

Consider a temporal flow network $N_T = (V, E_T, T, C_T)$, a source s at the starting timestamp τ_s and a sink t at the ending timestamp τ_e . We first introduce the timestamp inlining operator.

Timestamp inlining. For any node u in V , let $\text{TiStamp}_{\text{out}}(u) = \{\tau \mid (u, v, \tau) \in E\}$ denote the set of the timestamps of the outgoing edges of u in N_T (similarly, $\text{TiStamp}_{\text{in}}(u)$ denotes the case for incoming edges) and let $\text{Seq}(\text{Ti})$ denote a sequence consisting of the

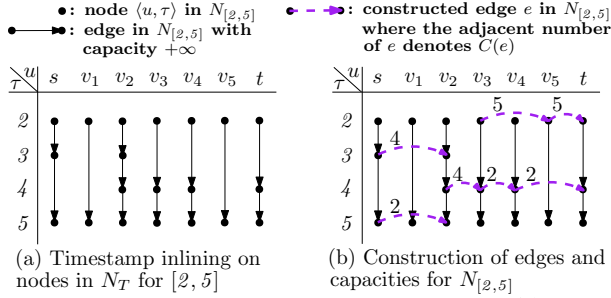


Figure 4: Example of transforming N_T in Figure 3(a) into the transformed flow network $N_{[2,5]}$ of N_T w.r.t. $[2, 5]$

timestamps in set T_i in ascending order. Then, the *timestamp inline operator* on u for time interval $[\tau_s, \tau_e]$ has the following steps:

- 1) initialize set $T_i(u)$ of the timestamps of the edges in N_T that are incident on u and may be part of flows from s to t :
 - $T_i(s) = \text{TiStamp}_{\text{out}}(s)$, $T_i(t) = \text{TiStamp}_{\text{in}}(t)$; and
 - $T_i(u) = \text{TiStamp}_{\text{out}}(u) \cup \text{TiStamp}_{\text{in}}(u)$, $u \in V - \{s, t\}$;
- 2) let $T_i[\tau_s, \tau_e](u) = \{\tau \mid \tau \in T_i(u) \cup \{\tau_s, \tau_e\} \text{ and } \tau_s \leq \tau \leq \tau_e\}$ denote the set of timestamps in $T_i(u)$ within time interval $[\tau_s, \tau_e]$;
- 3) for each timestamp τ in $T_i[\tau_s, \tau_e](u)$, create a node $\langle u, \tau \rangle$; and
- 4) for each timestamp τ and the succeeding timestamp τ' of τ in $\text{Seq}(T_i[\tau_s, \tau_e](u))$, create an edge $(\langle u, \tau \rangle, \langle u, \tau' \rangle)$.

Network transformation procedure. For time interval $[\tau_s, \tau_e]$, the transformed flow network of N_T w.r.t. $[\tau_s, \tau_e]$, denoted by $N_{[\tau_s, \tau_e]} = (V', E, C)$, is a flow network where V' and E are first initialized as empty sets. Then, the *network transformation procedure* constructs $N_{[\tau_s, \tau_e]}$ with the following steps.

- 1) **Timestamp inlining on the source and sink.** Firstly, we conduct the timestamp inlining on the source s and sink t for $[\tau_s, \tau_e]$, and then insert the created nodes and edges into V' and E , respectively.
- 2) **Timestamp inlining on nodes and construction of edges.** Secondly, starting from source s , we perform a depth-first-search on N_T to traverse all the edges in E_T . For each traversed edge (u, v, τ) ,
 - i) if $\langle v, \tau \rangle \notin V'$, conduct the inline operator on v for $[\tau_s, \tau_e]$ and insert the created nodes and edges into V' and E , respectively; and
 - ii) create and insert into E the edge $(\langle u, \tau \rangle, \langle v, \tau \rangle)$.
- 3) **Construction of capacities.** Lastly, we construct the capacity mapping function C of $N_{[\tau_s, \tau_e]}$ as follows:
 - ① for each edge e in $N_{[\tau_s, \tau_e]}$ constructed by the traversed edge e' in N_T in step 2), e has the same capacity as that of e' . That is,

$$\forall \langle u, \tau \rangle, \langle v, \tau \rangle \in V', C(\langle u, \tau \rangle, \langle v, \tau \rangle) = C_T(u, v, \tau);$$
 - ② for the edges created by the inline operator, their capacities are constructed as $+\infty$ since there can always be a flow from a timestamp to the later one on the same node. That is,

$$\forall \langle u, \tau \rangle, \langle u, \tau' \rangle \in V', \text{ if } (\langle u, \tau \rangle, \langle u, \tau' \rangle) \in E, C(\langle u, \tau \rangle, \langle u, \tau' \rangle) = +\infty;$$
 - ③ for the non-existing edges, their capacities are constructed as 0:

$$\forall \langle u, \tau \rangle, \langle v, \tau' \rangle \in V' (u \neq v \text{ and } \tau \neq \tau'), C(\langle u, \tau \rangle, \langle v, \tau' \rangle) = 0; \text{ and}$$

$$\forall \langle u, \tau \rangle, \langle u, \tau' \rangle \in V', \text{ if } (\langle u, \tau \rangle, \langle u, \tau' \rangle) \notin E, C(\langle u, \tau \rangle, \langle u, \tau' \rangle) = 0.$$

EXAMPLE 4. Figure 4 shows an example of transforming the temporal flow network N_T in Figure 3(a) into a transformed flow network w.r.t. $[2, 5]$. For this N_T , we can see that $\text{Seq}(T_i(s)) = [2, 3, 5]$, $\text{Seq}(T_i(v_1)) = \text{Seq}(T_i(v_5)) = [2, 5]$, $\text{Seq}(T_i(v_2)) = [2, 3, 4, 5]$, and $\text{Seq}(T_i(v_3)) = \text{Seq}(T_i(v_4)) = \text{Seq}(T_i(t)) = [2, 4, 5]$. Therefore, the

timestamp inlining on nodes constructs the nodes and edges as shown in Figure 4(a). Figure 4(b) shows in (purple) dashed lines the constructed edges for the edges in N_T having timestamps within the time interval $[2, 5]$, where the adjacent number denotes the capacity.

Given a temporal flow network $N_T = (V, E_T, T, C_T)$, a source s at τ_s , and a sink t at τ_e , the network transformation procedure can transform N_T into a transformed flow network $N_{[\tau_s, \tau_e]}$ in $O(d_{\max} \cdot |V| + |E_T|)$ time, where d_{\max} is the maximum degree of nodes of N_T since $N_{[\tau_s, \tau_e]}$ has $O(d_{\max} \cdot |V|)$ nodes and $O(d_{\max} \cdot |V| + |E_T|)$ edges. Then, we have the following lemma indicating that there exists a temporal flow in N_T and a flow in $N_{[\tau_s, \tau_e]}$ having the same flow value.

LEMMA 1. (Existence of flow of equivalent value) Consider a temporal flow network N_T , a source s at the starting timestamp τ_s , a sink t at the ending timestamp τ_e , and the transformed flow network $N_{[\tau_s, \tau_e]}$ of N_T w.r.t. $[\tau_s, \tau_e]$. For any temporal flow F from s to t in N_T , there exists a flow f from node $\langle s, \tau_s \rangle$ to node $\langle t, \tau_e \rangle$ in $N_{[\tau_s, \tau_e]}$ such that $|f| = |F|$, and vice versa.

Lemma 1 can be proved by constructing an equivalent flow f in $N_{[\tau_s, \tau_e]}$ for F and an equivalent temporal F in N_T for f . The detailed construction is presented in Appendix B [1].

According to Definition 2, the flow densities of temporal flows from source s at τ_s to sink t at τ_e in a temporal flow network N_T during the specific time interval $[\tau_s, \tau_e]$ depends on their flow values. Therefore, finding the temporal flow in N_T during $[\tau_s, \tau_e]$ whose flow density is maximized is *equivalent* to finding the temporal flow F having the maximum flow value during $[\tau_s, \tau_e]$. With Lemma 1, F can be found by finding Maxflow in the transformed flow network $N_{[\tau_s, \tau_e]}$ of N_T w.r.t. $[\tau_s, \tau_e]$. In this way, δ -BFlow from s to t in N_T can be found by finding Maxflows in N_T 's transformed flow networks w.r.t. all possible time intervals. Note that $N_{[\tau_s, \tau_e]}$ is a subgraph of the transformed flow network $N_{[\tau'_s, \tau'_e]}$ of N_T w.r.t. $[\tau'_s, \tau'_e]$, where $\tau_s \geq \tau'_s$ and $\tau_e \leq \tau'_e$. For simplicity, Maxflow from $\langle s, \tau_s \rangle$ to $\langle t, \tau_e \rangle$ in $N_{[\tau'_s, \tau'_e]}$ ($\tau_s \geq \tau'_s$ and $\tau_e \leq \tau'_e$) is called Maxflow w.r.t. $[\tau_s, \tau_e]$, denoted by $\text{MF}[\tau_s, \tau_e]$, when it is clear from the context.

4.2 Candidate Interval Enumeration

In this subsection, we present the procedure for enumerating all the candidate time intervals since δ -BFlow can be found by finding Maxflows in the transformed flow networks w.r.t. these intervals.

A naive method is to enumerate all the possible $O(|T|^2)$ time intervals $[\tau_s, \tau_e]$, $\tau_s, \tau_e \in T$ as *candidate intervals*, where T is the timestamp sequence of a temporal flow network. However, the size of T of a temporal network is usually large. For example, the dataset of the bitcoin transaction network in 2011 (Btc2011) has 59K timestamps that such enumeration is impractical. To reduce the size of the enumeration of candidate intervals, we propose to enumerate the *core intervals* for finding δ -BFlow.

Core interval. Given a temporal flow network $N_T = (V, E_T, T, C_T)$ with source s and sink t , a time interval $[\tau_s, \tau_e]$, $\tau_s, \tau_e \in T$ is a *core interval* if, in $N_{[\tau_s, \tau_e]}$, the flow value $|\text{MF}[\tau_s, \tau_e]|$ of $\text{MF}[\tau_s, \tau_e]$ is larger than the flow values of Maxflows w.r.t. any subintervals $[\tau'_s, \tau'_e]$ of $[\tau_s, \tau_e]$ (i.e., $\tau'_s \geq \tau_s, \tau'_e < \tau_e$ or $\tau'_s > \tau_s, \tau'_e \leq \tau_e$).

For example, $[3, 4]$ is a core interval in the temporal flow network shown in Figure 3(a) since $|\text{MF}[3, 4]| = 2 > |\text{MF}[3, 3]| = |\text{MF}[4, 4]| = 0$. Then, we have the following observation for core intervals.

Algorithm 1: δ -BFlow Query Solution (BFQ)

Input : A temporal flow network $N_T = (V, E_T, T, C_T)$, a source s , a sink t , and a bursting parameter δ

Output: The binary record of δ -BFlow from s to t in N_T

```

1  $r \leftarrow 0$ ; //  $r$ : flow density of current  $\delta$ -BFlow
2  $\tau_{r_s} \leftarrow 0, \tau_{r_e} \leftarrow 0$ ; //  $[\tau_{r_s}, \tau_{r_e}]$ : bursting interval of current  $\delta$ -BFlow
3 foreach  $\tau_s \in \text{Ti}(s)$  do
4   foreach  $\tau_e \in \text{Ti}(t) \cup \{\tau_s + \delta\}$  do // corner case may exist2
5      $N_{[\tau_s, \tau_e]} \leftarrow \text{NetworkTrans}(N_T, s, t, \tau_s, \tau_e)$ ; //Section 4.1
6     conduct Dinic on  $N_{[\tau_s, \tau_e]}$  to compute a Maxflow  $f$  w.r.t.  $[\tau_s, \tau_e]$ ;
7     if  $|f|/(\tau_e - \tau_s) > r$  then
8        $r \leftarrow |f|/(\tau_e - \tau_s), \tau_{r_s} \leftarrow \tau_s, \tau_{r_e} \leftarrow \tau_e$ ; //update of  $\delta$ -BFlow
9 return  $(r, [\tau_{r_s}, \tau_{r_e}])$ ; //output binary record of  $\delta$ -BFlow

```

OBSERVATION 1. (Core interval existence) Given a temporal flow network N_T with source s and sink t , if a time interval $[\tau_s, \tau_e]$ is a core interval, we have $\tau_s \in \text{TiStamp}_{\text{out}}(s)$ and $\tau_e \in \text{TiStamp}_{\text{in}}(t)$.

Observation 1 can be proved as follows. If $\tau_s \notin \text{TiStamp}_{\text{out}}(s)$, there must exist a time interval $[\tau'_s, \tau_e], \tau'_s \geq \tau_s$ such that $|\text{MF}[\tau'_s, \tau_e]| = |\text{MF}[\tau_s, \tau_e]|$. Similar time interval exists if $\tau_e \notin \text{TiStamp}_{\text{in}}(t)$.

With Observation 1, we can know that there exist $O(d^2)$ core intervals for a δ -BFlow query $Q = (s, t, \delta)$ in a temporal flow network $N_T = (V, E_T, T, C_T)$, where $d = \max\{|\text{Ti}(s)|, |\text{Ti}(t)|\}$. Based on the core interval, we present the following lemma to prune the enumeration of all the $O(|T|^2)$ possible time intervals.

LEMMA 2. Given a δ -BFlow query $Q = (s, t, \delta)$ on a temporal flow network N_T , δ -BFlow in N_T for Q can be found by evaluating $\text{MF}[\tau_s, \tau_e]$, where τ_s and τ_e satisfy either i) $\tau_e = \tau_s + \delta, \tau_s \in \text{Ti}(s)$; or ii) $[\tau_s, \tau_e]$ is a core interval such that $\tau_e - \tau_s > \delta$.

Lemma 2 can be proved by showing that δ -BFlows have the same flow density when the bursting intervals of the found δ -BFlows can be used to obtain the bursting intervals of the rest δ -BFlows in a simple method. Based on Lemma 2, we can enumerate at most $O(d^2)$ candidate intervals to find δ -BFlow. As shown in Table 2, d of the three evaluated real world datasets are often smaller than 100.

4.3 Practical δ -BFlow Solution (BFQ)

To find δ -BFlow, we present the procedure of time interval enumeration by our proposed solution BFQ. BFQ contains two procedures:

- **Candidate interval enumeration procedure (Section 4.2).** Given a δ -BFlow query $Q = (s, t, \delta)$ on a temporal flow network, we enumerate $O(d^2)$ core intervals and $|\text{Ti}(s)|$ time intervals $[\tau, \tau + \delta], \tau \in \text{Ti}(s)$ as the candidate intervals, where d equals to $\max\{|\text{Ti}(s)|, |\text{Ti}(t)|\}$.
- **Network transformation procedure (Section 4.1).** We transform the temporal flow network as the transformed flow network w.r.t. each candidate interval. δ -BFlow can be found by computing Maxflows in these transformed flow networks.

In detail, Algorithm 1 shows BFQ for finding the flow density and time interval of δ -BFlow. Taking as inputs a temporal flow network $N_T = (V, E_T, T, C_T)$, a source s , a sink t , and the bursting parameter δ , Algorithm 1 outputs the flow density and the bursting interval of δ -BFlow from s to t in N_T . First, Lines 1-2 initialize the current maximum flow density r and its corresponding bursting

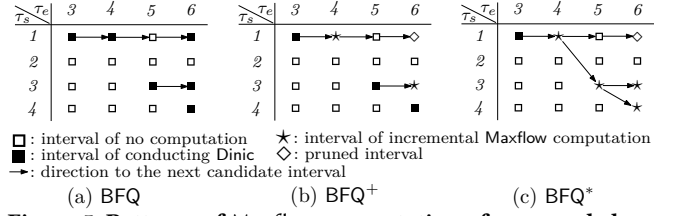


Figure 5: Patterns of Maxflow computation of proposed algorithms on the space of candidate intervals $[\tau_s, \tau_e]$ for computing 2-BFlow from s to t in the N_T shown in Figure 3(a)

interval $[\tau_s, \tau_e]$ as 0 and $[0, 0]$, respectively. Lines 3-4 enumerate candidate intervals with simple corner cases² according to the candidate interval enumeration procedure (Section 4.2). For each candidate interval $[\tau_s, \tau_e]$, Line 5 transforms N_T into a transformed flow network $N_{[\tau_s, \tau_e]}$ w.r.t. $[\tau_s, \tau_e]$ (Section 4.1). Line 6 computes an $\text{MF}[\tau_s, \tau_e]$ from (s, τ_s) to (t, τ_e) in $N_{[\tau_s, \tau_e]}$ by using a practical augmenting path based solution Dinic [12]. Note that other Maxflow solutions can be also used directly. However, as our proposed optimizations are based on the augmenting paths, we make use of Dinic here whereas other augmenting path based solutions also work for our optimizations with minor modifications. f 's flow density is computed in Line 7. Line 8 updates r and $[\tau_{r_s}, \tau_{r_e}]$ by using the current maximum flow density and its corresponding time interval, respectively. Line 9 returns r and $[\tau_{r_s}, \tau_{r_e}]$ as outputs.

EXAMPLE 5. For the temporal flow network N_T in Figure 3(a), BFQ computes 2-BFlow from s to t in N_T by conducting Dinic on the transformed flow networks w.r.t. candidate intervals $[\tau_s, \tau_e]$ as shown in Figure 5(a). Note that the evaluation on candidate interval $[4, 6]$ is a corner case (Line 4 of Algorithm 1) since $5 \in \text{Ti}(s)$ and $5 + \delta = 7 > 6$. BFQ can find one 2-BFlow from s to t having flow density $5/3$ and bursting interval $[1, 4]$ as shown in Figure 3(c).

Analysis. With Lemma 1, BFQ correctly computes the flow density and the bursting interval of δ -BFlow in a temporal flow network $N_T = (V, E_T, T, C_T)$ by computing Maxflows w.r.t. all the $O(d^2)$ candidate intervals. The time complexity of BFQ is $O(d^2 \cdot (d_{\max} \cdot |V|)^2 \cdot (d_{\max} \cdot |V| + |E_T|))$. In the next section, we propose optimizations to avoid some redundant computation to optimize BFQ's efficiency.

5 Efficient δ -BFlow Solution — Incremental Augmenting Path Approach

In Section 4, we propose a δ -BFlow solution BFQ that enumerates $O(d^2)$ candidate intervals (Lines 3-4 of Algorithm 1) for Maxflow evaluations. According to the network transformation procedure of BFQ (Section 4.1), it is apparent that, for any two enumerated intervals $[\tau'_s, \tau'_e]$ and $[\tau_s, \tau_e]$, if $[\tau'_s, \tau'_e]$ is a subinterval of $[\tau_s, \tau_e]$, the transformed flow network $N_{[\tau'_s, \tau'_e]}$ is a subgraph of the transformed flow network $N_{[\tau_s, \tau_e]}$. Therefore, the augmenting paths found in $N_{[\tau'_s, \tau'_e]}$ for $\text{MF}[\tau'_s, \tau'_e]$ also exist in $N_{[\tau_s, \tau_e]}$ as augmenting paths for $\text{MF}[\tau_s, \tau_e]$, which leads an opportunity for incremental Maxflow

²Note that there may exist corner case when the value of τ_e in Line 4 is larger than the maximum timestamp in T . The candidate interval for such case can be replaced by $[\tau_e - \delta, \tau_e]$ according to the analysis in Section 4.2. For simplicity, we omit this corner case in the following sections since it does not affect the analysis and correctness.

computation without computing these paths from scratch. In this section, we propose incremental computation strategies to improve the efficiency of BFQ by maintaining and reusing such augmenting paths.

5.1 BFQ with Incremental Maxflow Computation of the Insertion Case (BFQ⁺)

In this subsection, we propose an optimization to incrementally compute Maxflows w.r.t. the candidate intervals $[\tau_s, \tau_e]$ when increasing the value of τ_e with a fixed τ_s (Lines 4 of Algorithm 1).

5.1.1 Operators for Incremental Maxflow computation. According to the network transformation procedure (Section 4.1), the increase of τ_e leads to only insertion of nodes and edges in the corresponding transformed flow network without the deletion of nodes and edges, and hence the augmenting paths found for Maxflow w.r.t. a given $[\tau_s, \tau_e]$ are also valid augmenting paths for MF $[\tau_s, \tau'_e]$ ($\tau'_e > \tau_e$). For better presentation of the relation between the transformed flow networks w.r.t. time intervals of a fixed τ_s and different τ_e to support the incremental Maxflow computation, we first define two binary operators on transformed flow networks.

Operator \uplus . Given two transformed flow networks $N_a = (V_a, E_a, C_a)$ and $N_b = (V_b, E_b, C_b)$, $N_a \uplus N_b$ denotes a flow network $N = (V_a \cup V_b, E_a \cup E_b, C)$, where $C: (V_a \cup V_b) \times (V_a \cup V_b) \rightarrow \mathbb{R}_{\geq 0}$ satisfies that $\forall \langle u, \tau \rangle, \langle v, \tau' \rangle \in V_a \cup V_b$, $C(\langle u, \tau \rangle, \langle v, \tau' \rangle)$ equals,

$$\begin{cases} C_a(\langle u, \tau \rangle, \langle v, \tau' \rangle) + C_b(\langle u, \tau \rangle, \langle v, \tau' \rangle), & \text{if } (\langle u, \tau \rangle, \langle v, \tau' \rangle) \in E_a \cap E_b; \\ C_a(\langle u, \tau \rangle, \langle v, \tau' \rangle), & \text{if } (\langle u, \tau \rangle, \langle v, \tau' \rangle) \in E_a - E_b; \\ C_b(\langle u, \tau \rangle, \langle v, \tau' \rangle), & \text{if } (\langle u, \tau \rangle, \langle v, \tau' \rangle) \in E_b - E_a; \\ 0, & \text{otherwise.} \end{cases}$$

Operator \setminus . Given two transformed flow networks $N_a = (V_a, E_a, C_a)$ and $N_b = (V_b, E_b, C_b)$, assume that N_a and N_b are the left operand and the right operand of the binary operator \setminus , respectively. Then, $N_a \setminus N_b$ denotes a flow network $N = (V, E, C)$, where i) $E = (E_a - E_b) \cup (E_a \cap E_b)$, ii) $V = \{ \langle u, \tau \rangle \mid (\langle u, \tau \rangle, \langle v, \tau' \rangle) \in E \text{ or } (\langle v, \tau' \rangle, \langle u, \tau \rangle) \in E \}$, and iii) $C: V \times V \rightarrow \mathbb{R}_{\geq 0}$ satisfies that $\forall \langle u, \tau \rangle, \langle v, \tau' \rangle \in V$, $C(\langle u, \tau \rangle, \langle v, \tau' \rangle)$ equals,

$$\begin{cases} C_a(\langle u, \tau \rangle, \langle v, \tau' \rangle) - C_b(\langle u, \tau \rangle, \langle v, \tau' \rangle), & \text{if } (\langle u, \tau \rangle, \langle v, \tau' \rangle) \in E_a \cap E_b; \\ C_a(\langle u, \tau \rangle, \langle v, \tau' \rangle), & \text{if } (\langle u, \tau \rangle, \langle v, \tau' \rangle) \in E_a - E_b; \\ 0, & \text{otherwise.} \end{cases}$$

Operator \uplus generates a union of two flow networks by merging the capacities of their common edges, while operator \setminus generates a flow network of the left operand by reducing the capacities of common edges based on the capacities of the edges of the right operand. (Examples of these two operators will be given together with the examples of the incremental Maxflow). Note that both operators take $O(|E|)$ times, where E is the edge set of the transformed flow networks. Then, we propose the following lemma to incrementally compute MF $[\tau_s, \tau_e]$ when increasing the value of τ_e . We call it the insertion case.

5.1.2 Incremental Maxflow computation (insertion case).

LEMMA 3. (Incremental Maxflow (insertion case)) Consider a temporal flow network N_T with source s and sink t , the transformed flow network $N_{[\tau, \tau_e]}$ of N_T w.r.t. $[\tau, \tau_e]$, and the following notations.

- $f_{[\tau_s, \tau_e]}$ denotes an MF $[\tau_s, \tau_e]$ (where $\tau_s \geq \tau$) in $N_{[\tau, \tau_e]}$ obtained by Dinic by finding augmenting paths; and

Algorithm 2: The Improved δ -BFlow Query Solution (BFQ⁺)

Input : A temporal flow network $N_T = (V, E_T, T, C_T)$, a source s , a sink t , and a bursting parameter δ

Output: The binary record of δ -BFlow from s to t in N_T

```

1  $r \leftarrow 0$ ; //  $r$ : flow density of current  $\delta$ -BFlow
2  $\tau_{rs} \leftarrow 0, \tau_{re} \leftarrow 0$ ; //  $[\tau_{rs}, \tau_{re}]$ : bursting interval of current  $\delta$ -BFlow
3 foreach  $\tau_s \in \text{Ti}(s)$  do
4    $\tau_e \leftarrow \tau_s + \delta$ ;
5    $N_{[\tau_s, \tau_e]} \leftarrow \text{NetworkTrans}(N_T, s, t, \tau_s, \tau_e)$ ; // Section 4.1
6   conduct Dinic on  $N_{[\tau_s, \tau_e]}$  to compute a Maxflow  $f$  w.r.t.  $[\tau_s, \tau_e]$  and the residual network  $N_f$  w.r.t.  $f$ ;
7   if  $|f|/(\tau_e - \tau_s) > r$  then
8      $r \leftarrow |f|/(\tau_e - \tau_s), \tau_{rs} \leftarrow \tau_s, \tau_{re} \leftarrow \tau_e$ ; // update of  $\delta$ -BFlow
9   foreach  $\tau'_e$  in  $\text{Ti}(t)$  that  $\tau'_e > \tau_s + \delta$  do // corner case may exist2
10     $\text{IncrMaxFlow}^+(N_T, f, N_f, \tau_s, \tau_e, \tau'_e, \tau_{rs}, \tau_{re}, r)$ ; // Section 5.1
11     $\tau_e \leftarrow \tau'_e$ ;
12 return  $(r, [\tau_{rs}, \tau_{re}])$ ; // output binary record of  $\delta$ -BFlow

Procedure  $\text{IncrMaxFlow}^+(N_T, f, N_f, \tau_s, \tau_e, \tau'_e, \tau_{rs}, \tau_{re}, r)$ :
13  $N_{[\tau_e, \tau'_e]} \leftarrow \text{NetworkTrans}(N_T, s, t, \tau_e, \tau'_e)$ ; // Section 4.1
14  $N_f \leftarrow N_f \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$ ; // Lemma 3: update  $N_f$ 
15 if  $|f| + \sum_{\tau \in [\tau_e, \tau'_e]} \sum_{u \in V} C_T(u, t, \tau) < r \cdot (\tau'_e - \tau_s)$  then // Observation 2
16   return;
17 conduct Dinic on  $N_f$  to update  $f$  as an MF $[\tau_s, \tau'_e]$  in  $N_{[\tau_s, \tau'_e]}$ ; // Lemma 3
18 if  $|f|/(\tau'_e - \tau_s) > r$  then
19    $r \leftarrow |f|/(\tau'_e - \tau_s), \tau_{rs} \leftarrow \tau_s, \tau_{re} \leftarrow \tau'_e$ ; // update of  $\delta$ -BFlow

```

- τ'_e is a timestamp larger than τ_e .

Then, a Maxflow $f_{[\tau_s, \tau'_e]}$ w.r.t. $[\tau_s, \tau'_e]$ in $N_{[\tau, \tau'_e]}$ can be obtained (by Dinic) by finding augmenting paths $p_{\tau'_e}$ s from $\langle s, \tau_s \rangle$ to $\langle t, \tau'_e \rangle$ on the flow network $N_{f_{[\tau_s, \tau_e]}} \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$ having

$$|f_{[\tau_s, \tau'_e]}| = |f_{[\tau_s, \tau_e]}| + \sum_{p_{\tau'_e}} \text{Flow}(p_{\tau'_e})$$

where $N_{f_{[\tau_s, \tau_e]}}$ is the residual network of $N_{[\tau, \tau_e]}$ w.r.t. $f_{[\tau_s, \tau_e]}$.

Intuitively, Lemma 3 shows that the augmenting paths for finding MF $[\tau_s, \tau_e]$ can be reused for finding MF $[\tau_s, \tau'_e]$ because the transformed flow network w.r.t. $[\tau_e, \tau'_e]$ are inserted into $N_{[\tau, \tau_e]}$ where the inserted edges have no effect on the reused augmenting paths. Therefore, we can incrementally compute MF $[\tau_s, \tau'_e]$, $\tau'_e \in \{\tau_s + \delta\} \cup \text{Ti}(t)$ without computing the common augmenting paths from scratch. The detailed proof of Lemma 3 is presented in Appendix B [1]. Moreover, we propose a *capacity constraint* for pruning the Maxflow computation by the following observation.

OBSERVATION 2. (Capacity constraint) Given a temporal flow network $N_T = (V, E_T, T, C_T)$, and a source s and a sink t in N_T , let f denote an MF $[\tau_s, \tau_e]$ in the transformed flow network $N_{[\tau_s, \tau_e]}$ of N_T and r denote f 's flow density $|f|/(\tau_e - \tau_s)$. For a timestamp τ'_e ($\tau'_e > \tau_e$), if MF $[\tau_s, \tau'_e]$ is a δ -BFlow from s to t , we have,

$$|f| + \sum_{\tau \in [\tau_e, \tau'_e]} \sum_{u \in V} C_T(u, t, \tau) \geq r \cdot (\tau'_e - \tau_s)$$

Observation 2 can be easily proved by contradiction. Assume that all the incoming edges of sink t in N_T having timestamps within $[\tau_e, \tau'_e]$ spend all their capacities for MF $[\tau_s, \tau'_e]$. If such a Maxflow corresponds to a temporal flow having a flow density smaller than r , it cannot be a δ -BFlow.

5.1.3 Improved δ -BFlow solution by using the incremental Maxflow computation of the insertion case. With Lemma 3 and Observation 2, we propose an improved δ -BFlow solution called BFQ⁺. We put a plus sign to BFQ because we compute MF $[\tau_s, \tau_e]$ once for a fixed τ_s , and then increase the value of τ_e for the next iteration of the Maxflow computation as shown in Line 4 of Algorithm 1.

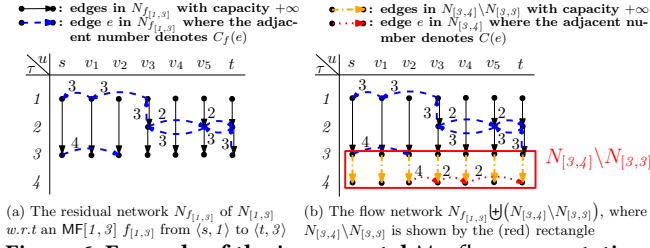


Figure 6: Example of the incremental Maxflow computation (insertion case) in BFQ⁺ from an MF[1, 3] to an MF[1, 4]

As shown in Algorithm 2, BFQ⁺ has the same input and output as those of BFQ. After the initialization of the current δ -BFlow in Lines 1-2, Line 3 enumerates the starting timestamp τ_s for candidate intervals $[\tau_s, \tau_e]$ according to the candidate interval enumeration procedure (Section 4.2). Importantly, for each enumerated τ_s , Lines 4-6 first initialize τ_e as $\tau_s + \delta$ and invoke Dinic on the transformed flow network $N_{[\tau_s, \tau_e]}$ of N_T to compute a Maxflow f w.r.t. $[\tau_s, \tau_e]$. Lines 7-8 record the density r and the time interval $[\tau_s, \tau_e]$ of current δ -BFlow. Then, Lines 9-10 iteratively compute MF[τ_s, τ'_e], $\tau'_e \in \text{Ti}(t)$ by updating f as follows: i) Line 13 transforms N_T into $N_{[\tau_e, \tau'_e]}$; ii) Line 14 computes the flow network $N_f \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$ to update the current residual network N_f ; iii) Lines 15-16 conduct a fast pruning on the Maxflow computation by using the capacity constraint in Observation 2; iv) Line 17 invokes Dinic on the updated N_f to update f as an MF[τ_s, τ'_e]; and v) Lines 18-19 update r and $[\tau_s, \tau_e]$ for recording the current δ -BFlow. After the incremental Maxflow computation in Line 10 finishes, Line 11 updates the value of τ_e by using the value of τ'_e for the next iteration of incremental Maxflow computation for the fixed τ_s . After evaluating Maxflows w.r.t. all the candidate intervals, r and $[\tau_s, \tau_e]$ are returned as outputs in Line 12.

EXAMPLE 6. Consider the computation of BFQ⁺ for 2-BFlow from s to t in Figure 3(a)'s N_T . Figure 5(b) shows the pattern of candidate intervals evaluated by BFQ⁺. According to Lemma 3, BFQ⁺ computes MF[1, 4] in an incremental method (Lines 13-19) as follows. Based on an MF[1, 3] $f_{[1,3]}$ and the residual network $N_{f_{[1,3]}}$ w.r.t. $f_{[1,3]}$, BFQ⁺ computes the flow network $N_{f_{[1,3]}} \uplus (N_{[3,4]} \setminus N_{[3,3]})$. Figure 6(a) shows the residual network of $N_{[1,3]}$ w.r.t. $f_{[1,3]}$ while Figure 6(b) shows the flow network $N_{f_{[1,3]}} \uplus (N_{[3,4]} \setminus N_{[3,3]})$, where there exists an augmenting path $p: \langle s, 1 \rangle \rightarrow \langle s, 3 \rangle \rightarrow \langle v_2, 3 \rangle \rightarrow \langle v_2, 4 \rangle \rightarrow \langle v_3, 4 \rangle \rightarrow \langle v_4, 4 \rangle \rightarrow \langle t, 4 \rangle$. Therefore, Line 17 conducts Dinic to update $f_{[1,3]}$ to obtain an MF[1, 4] whose flow value is $|f_{[1,3]}| + \text{Flow}(p) = 3 + 2 = 5$. An MF[3, 6] can be also computed in such an incremental method. Regarding the Maxflow computation for MF[1, 6], it can be pruned in Lines 15-16 according to Observation 2. This is because an MF[1, 4] f has flow value $|f| = 5$ and density $r = 5/3$, and hence we have $|f| + \sum_{\tau \in [4,6]} \sum_{u \in V} C_T(u, t, \tau) = 5 + 1 < 5/3 \cdot (6 - 1)$.

The following theorem shows the correctness of BFQ⁺.

THEOREM 1. (Correctness of BFQ⁺) Given a temporal flow network N_T with source s and sink t , and a parameter δ , BFQ⁺ returns the flow density and the bursting interval of δ -BFlow from s to t .

Theorem 1 can be proved by showing that BFQ⁺ considers the Maxflow computation for the same candidate intervals enumerated in BFQ. The detailed proof is presented in Appendix B [1].

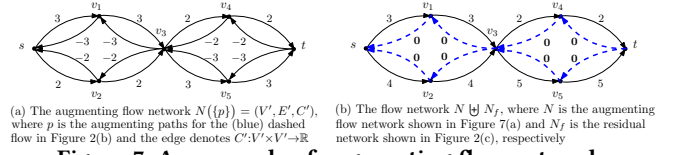


Figure 7: An example of augmenting flow network

Analysis. For a temporal flow network $N_T = (V, E_T, T, C_T)$, Lines 5-8 take $O(d \cdot (d_{\max} \cdot |V|)^2 \cdot (d_{\max} \cdot |V| + |E_T|))$ time for each τ_s . The update of residual network N_f in Lines 13-14 takes $O(d^2 \cdot (d_{\max} \cdot |V| + |E_T|))$ time in total. The update of flow f by conducting Dinic on the updated N_f in Line 17 takes $O(d^2 \cdot (d_{\max} \cdot |V|)^2 \cdot (d_{\max} \cdot |V| + |E_T|))$ time in total. Therefore, the time complexity of BFQ⁺ is $O(d^2 \cdot (d_{\max} \cdot |V|)^2 \cdot (d_{\max} \cdot |V| + |E_T|))$.

5.2 BFQ⁺ with Incremental Maxflow Computation of the Deletion Case (BFQ*)

In this subsection, we further propose an optimization to incrementally compute MF[$\tau_s, \tau_s + \delta$] when increasing the value of τ_s (Lines 3-6 of Algorithm 2). Different from the incremental Maxflow computation introduced in Section 5.1, the case of increasing τ_s may lead to the deletion of nodes and edges in the transformed flow network that such deletion will make some previously found augmenting paths being no longer able to reused for a Maxflow.

To handle this case, we define a new kind of flow network used for withdrawing the flows from such augmenting paths, and then define an important operator to support the incremental Maxflow computation for MF[$\tau_s, \tau_s + \delta$] when increasing the value of τ_s .

5.2.1 Augmenting flow network and timestamp injection operator.

DEFINITION 3. (Augmenting flow network) Consider a set P of augmenting paths in a flow network $N = (V, E, C)$. The augmenting flow network of P , denoted by $N(P) = (V', E', C')$, is a flow network where i) $E' = \{(u, v) \mid (u, v) \text{ or } (v, u) \text{ is an edge in } E \text{ passed through by } p, p \in P\}$, ii) V' consists of the nodes incident to the edges in E' , and iii) $C': V' \times V' \rightarrow \mathbb{R}$ satisfies that:

- $\forall u, v \in V'$, if $(u, v) \notin E'$, $C'(u, v) = 0$; otherwise
- $C'(u, v) = \sum_{p \in \{p' \mid p' \in P \text{ and } p' \text{ passes through } (u, v)\}} \text{Flow}(p) - \sum_{p \in \{p' \mid p' \in P \text{ and } p' \text{ passes through } (v, u)\}} \text{Flow}(p)$.

EXAMPLE 7. Figure 7 shows an example of an augmenting flow network. For the flow f as shown in Figure 2(b), f can be considered as two augmenting paths $p_1: s \rightarrow v_2 \rightarrow v_3 \rightarrow v_4 \rightarrow t$ having $\text{Flow}(p_1) = 2$ and $p_2: s \rightarrow v_1 \rightarrow v_3 \rightarrow v_5 \rightarrow t$ having $\text{Flow}(p_2) = 3$. Figure 7(a) shows the augmenting flow network $N(P)$ of $P = \{p_1, p_2\}$ while Figure 7(b) shows the flow network $N(P) \uplus N_f$, where N_f is the residual network as shown in Figure 2(c). We can see that $N(P) \uplus N_f$ is the same as the flow network N in Figure 2(a) except for some additional edges in (blue) dashed lines having capacities equal to 0.

As Example 7 shows, the augmenting flow network $N(P)$ can be used to withdraw the flows of the augmenting paths in P by conducting operator \uplus between $N(P)$ and the residual network.

Note that the additional edges in (blue) dashed lines have capacities equal to 0, and hence they have no effect on the augmenting path based Maxflow solutions. Then, we further define the timestamp injection operator on transformed flow networks to help enable the incremental Maxflow computation by withdrawing the flow values of the outdated augmenting paths when increasing the value of τ_s .

Timestamp injection. Given the transformed flow network $N_{[\tau_s, \tau_e]} = (V, E, C)$ w.r.t. $[\tau_s, \tau_e]$ and a timestamp τ'_s that $\tau_s < \tau'_s < \tau_e$, the *timestamp injection* on $N_{[\tau_s, \tau_e]}$ for τ'_s , denoted by $\Delta_{\tau'_s}(N_{[\tau_s, \tau_e]})$, is to, for any u in $\{v \mid \langle v, \tau \rangle \in V \text{ and } \langle v, \tau'_s \rangle \notin V\}$, replace the edge $e = (\langle u, \tau_1 \rangle, \langle u, \tau_2 \rangle)$ having $\tau_1 < \tau'_s < \tau_2$ or $\tau_2 < \tau'_s < \tau_1$ by two edges $(\langle u, \tau_1 \rangle, \langle u, \tau'_s \rangle)$ and $(\langle u, \tau'_s \rangle, \langle u, \tau_2 \rangle)$, which have i) the same capacities as that of edge e ; and ii) flows with the same flow value as that of the flow going through edge e .

Figure 8(a) shows an example of $\Delta_3(N_{f[1,4]})$, where $N_{f[1,4]}$ is the residual network w.r.t. Maxflow $f_{[1,4]}$ w.r.t. $[1, 4]$ in the transformed flow network $N_{[1,4]}$. The edges in (blue) dashed lines show the replaced edges after conducting the timestamp injection on $N_{f[1,4]}$ for timestamp 3. It can be easily derived from the definition of timestamp injection that conducting timestamp injection on a flow network N does not change to the flow values of augmenting paths in N .

With the augmenting flow network and timestamp injection operator, we propose the following lemma to incrementally compute $\text{MF}[\tau_s, \tau_e]$ when increasing τ_s 's value. We call it the deletion case.

5.2.2 Incremental Maxflow computation (deletion case).

LEMMA 4. (Incremental Maxflow (deletion case)) Consider a temporal flow network N_T with source s and sink t , the transformed flow network $N_{[\tau_s, \tau_e]}$ of N_T w.r.t. $[\tau_s, \tau_e]$, a timestamp $\tau'_s \in \text{Ti}(s)$ that $\tau_s < \tau'_s < \tau_e$, and the following notations.

- $f_{[\tau_s, \tau_e]}$ denotes an $\text{MF}[\tau_s, \tau_e]$ in $N_{[\tau_s, \tau_e]}$ obtained by Dinic by finding augmenting paths; and
- P denotes the set of the found augmenting paths that do not pass through node $\langle s, \tau'_s \rangle$.

Then, a Maxflow $f_{[\tau'_s, \tau_e]}$ w.r.t. $[\tau'_s, \tau_e]$ in $N_{[\tau'_s, \tau_e]}$ can be obtained by Dinic by finding augmenting paths $p_{\tau'_s}$ from $\langle s, \tau'_s \rangle$ to $\langle t, \tau_e \rangle$ in $(\Delta_{\tau'_s}(N_{f_{[\tau_s, \tau_e]}}) \cup N(P)) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ having,

$$|f_{[\tau'_s, \tau_e]}| = |f_{[\tau_s, \tau_e]}| + \sum_{p_{\tau'_s} \in P} \text{Flow}(p_{\tau'_s}) - \sum_{p \in P} \text{Flow}(p)$$

where $N_{f_{[\tau_s, \tau_e]}}$ is the residual network of $N_{[\tau_s, \tau_e]}$ w.r.t. $f_{[\tau_s, \tau_e]}$.

Intuitively, there exist augmenting paths that are no longer valid after increasing the starting timestamp from τ_s to τ'_s that the transformed flow network w.r.t. $[\tau_s, \tau'_s]$ is removed from $N_{[\tau_s, \tau_e]}$. Lemma 4 shows that we can withdraw the flow of these paths from the residual network of $N_{[\tau_s, \tau_e]}$ as the flow network $N_{f_{[\tau_s, \tau_e]}} \cup N(P)$ and then just compute augmenting paths in the flow network $(\Delta_{\tau'_s}(N_{f_{[\tau_s, \tau_e]}}) \cup N(P)) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ to find an $\text{MF}[\tau'_s, \tau_e]$ without computing all the augmenting paths from scratch. The detailed proof of Lemma 4 is presented in Appendix B [1].

5.2.3 Optimized δ -BFlow solution by using the incremental Maxflow computation of both the insertion case and the deletion case. Based on BFQ^+ and Lemma 4, we further propose an optimized δ -BFlow solution called BFQ^* . We put a "*" to BFQ since BFQ^* makes use of

Algorithm 3: The Optimized δ -BFlow Query Solution (BFQ^*)

Input : A temporal flow network $N_T = (V, E_T, T, C_T)$, a source s , a sink t , and a bursting parameter δ
Output: The binary record of δ -BFlow from s to t in N_T

```

1  $r \leftarrow 0$ ; //  $r$ : flow density of current  $\delta$ -BFlow
2  $\tau_{rs} \leftarrow 0, \tau_{re} \leftarrow 0$ ; //  $[\tau_{rs}, \tau_{re}]$ : bursting interval of current  $\delta$ -BFlow
3  $\tau_s \leftarrow \min_{\tau \in \text{Ti}(s)} \{\tau\}, \tau_e \leftarrow \min_{\tau \in \text{Ti}(t)} \{\tau\} + \delta$ ;
4  $N_{[\tau_s, \tau_e]} \leftarrow \text{NetworkTrans}(N_T, s, t, \tau_s, \tau_e), N_f \leftarrow N_{[\tau_s, \tau_e]}$ ; // Section 4.1
5  $\text{UpdateMaxFlow}(N_f, f, \tau_s, \tau_e, \tau_{rs}, \tau_{re}, r)$ ;
6 foreach  $\tau'_s \in \text{Ti}(s)$  do
7    $\text{flag} \leftarrow \text{true}$ ;
8   foreach  $\tau'_e$  in  $\text{Ti}(t)$  that  $\tau'_e > \tau_s + \delta$  do // corner case may exist2
9     if  $(\tau'_e > \tau'_s + \delta) \&\& \text{flag}$  then
10        $N_{f'} \leftarrow N_f, f' \leftarrow f$ ; // used to record  $f$  and  $N_f$  for next  $\tau'_s$ 
11        $N_{f'} \leftarrow N_{f'} \cup (N_{[\tau_e, \tau'_s + \delta]} \setminus N_{[\tau_e, \tau_e]})$ ; // Lemma 3
12        $\tau_e \leftarrow \tau'_s + \delta, \text{flag} \leftarrow \text{false}$ ;
13        $\text{IncrMaxFlow}^-(f', N_{f'}, \tau_s, \tau'_s, \tau_e, \tau_{rs}, \tau_{re}, r)$ ; // Section 5.2
14        $\text{IncrMaxFlow}^+(N_f, f, N_{f'}, \tau_s, \tau_e, \tau'_e, \tau_{rs}, \tau_{re}, r)$ ;
15        $\tau_e \leftarrow \tau'_e$ ;
16        $\tau_s \leftarrow \tau'_s, N_f \leftarrow N_{f'}, f \leftarrow f'$ ;
17 return  $(r, [\tau_{rs}, \tau_{re}])$ ; // output binary record of  $\delta$ -BFlow

Procedure  $\text{IncrMaxFlow}^-(\&f, \&N_f, \tau_s, \tau'_s, \tau_e, \&\tau_{rs}, \&\tau_{re}, \&r)$ :
18  $N_f \leftarrow \Delta_{\tau'_s}(N_f), P \leftarrow \emptyset, \text{sum} \leftarrow 0$ ;
19 create and insert into  $N_f$  a virtual node  $\langle s', \tau_s \rangle$ ;
20 foreach edge  $(\langle u, \tau \rangle, \langle u, \tau'_s \rangle), u \neq s$  of  $N_f$  do
21   create and insert into  $N_f$  edge  $(\langle u, \tau'_s \rangle, \langle s', \tau_s \rangle)$  with capacity equal to  $f(\langle u, \tau \rangle, \langle u, \tau'_s \rangle)$ ,  $\text{sum} \leftarrow \text{sum} + (f(\langle u, \tau \rangle, \langle u, \tau'_s \rangle))$ ;
22 if  $\text{sum} > 0$  then //  $\text{sum} = 0$ : no paths exist in  $P$  of Lemma 4
23   conduct Dinic on  $N_f$  to compute Maxflow from  $\langle t, \tau_e \rangle$  to  $\langle s', \tau_s \rangle$  and insert the found augmenting paths in set  $P', P \leftarrow \{p \mid p \text{ is the reversed path of } p', p' \in P'\}$ ;
24  $N_f \leftarrow (N_f \cup N(P)) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ ; // Lemma 4
25  $\text{UpdateMaxFlow}(N_f, f, \tau'_s, \tau_e, \tau_{rs}, \tau_{re}, r)$ ;

Procedure  $\text{UpdateMaxFlow}(\&N_f, \&f, \tau_s, \tau_e, \&\tau_{rs}, \&\tau_{re}, \&r)$ :
26 conduct Dinic on  $N_f$  to update  $f$  as an  $\text{MF}[\tau_s, \tau_e]$ ;
27 if  $|f|/(\tau_e - \tau_s) > r$  then
28    $r \leftarrow |f|/(\tau_e - \tau_s), \tau_{rs} \leftarrow \tau_s, \tau_{re} \leftarrow \tau_e$ ; // update of  $\delta$ -BFlow

```

the incremental Maxflow computation of the insertion case in BFQ^+ together with an incremental Maxflow computation of the *deletion case*, which computes $\text{MF}[\tau_s, \tau_s + \delta]$ for the smallest timestamp τ_s in $\text{Ti}(s)$, and then increase the value of τ_s for the next iteration of Maxflow computation (Line 3 of Algorithm 1).

As shown in Algorithm 3, BFQ^* has the same input and output as those of BFQ and BFQ^+ . First, after the initialization of the current δ -BFlow in Lines 1-2, Lines 3-5 first invoke Dinic to compute an $\text{MF}[\min_{\tau \in \text{Ti}(s)} \{\tau\}, \min_{\tau \in \text{Ti}(t)} \{\tau\} + \delta]$ f with residual network N_f and update the current δ -BFlow in $\text{UpdateMaxFlow}()$. Based on the current Maxflow f and the residual network N_f w.r.t. f , Lines 6-8 iteratively compute Maxflows w.r.t. candidate intervals by using the proposed incremental Maxflow computation methods as follows. For each starting timestamp τ_s , Line 14 calls IncrMaxFlow^+ to conduct incremental Maxflow computation of the insertion case (Algorithm 2). Note that Lines 7-13 record a flow f' and the residual network $N_{f'}$ w.r.t. f' used for the Maxflow computation for the next iteration with τ_s in Line 6. Specifically, Lines 10-11 incrementally update $N_{f'}$ by using the \cup and \setminus operators according Lemma 3. Based on current f' and $N_{f'}$, Line 13 calls $\text{IncrMaxFlow}^-()$ to conduct incremental Maxflow computation of the deletion case (Lemma 4) to compute $\text{MF}[\tau'_s, \tau'_s + \delta]$ for the next iteration with τ_s . Finally, after evaluating Maxflows w.r.t. all candidate intervals, r and $[\tau_{rs}, \tau_{re}]$ are returned as outputs in Line 16.

Regarding $\text{IncrMaxFlow}^-()$ for the incremental Maxflow computation of the deletion case, its detailed procedure is as follows. Given an $\text{MF}[\tau_s, \tau_e]$ f , to obtain an $\text{MF}[\tau'_s, \tau_e]$ ($\tau'_s > \tau_s$), Line 18

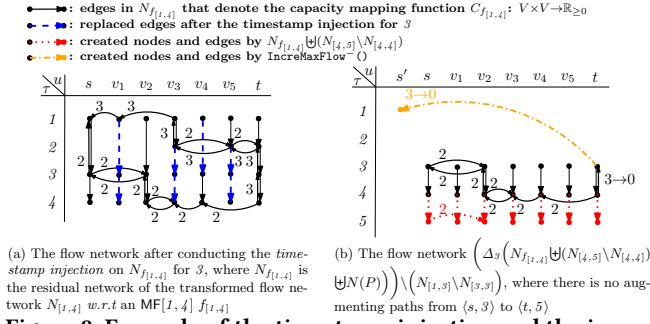


Figure 8: Example of the timestamp injection and the incremental Maxflow computation (deletion case) in BFQ* from an MF[1, 4] to an MF[3, 5]

first conducts the timestamp injection on the residual network N_f w.r.t. f for τ'_s . Then, Lines 19-23 compute the augmenting paths in set P used in Lemma 4 for withdrawing the flow from f during $[\tau_s, \tau'_s]$. In detail, i) Line 19 creates a virtual node $\langle s', \tau_s \rangle$; ii) for each edge $\langle u, \tau \rangle, \langle u, \tau'_s \rangle, u \neq s$ of N_f , Line 21 creates and inserts into N_f edge $\langle u, \tau'_s \rangle, \langle s', \tau_s \rangle$ with capacity equal to $f(\langle u, \tau \rangle, \langle u, \tau'_s \rangle)$; and iii) Line 23 invokes Dinic to compute Maxflow from $\langle t, \tau_e \rangle$ to $\langle s', \tau_s \rangle$ and inserts into set P the reversed paths of the found augmenting paths. According to Lemma 4, Line 24 computes the flow network $(N_f \cup N(P)) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ as the updated residual network N_f , and then Line 25 calls `UpdateMaxFlow()` on N_f to update flow f as an MF $[\tau'_s, \tau_e]$.

EXAMPLE 8. Consider the computation of 2-BFlow from s to t in Figure 3(a)'s N_T . Figure 5(c) shows the pattern of the Maxflow computation for candidate intervals of BFQ*. As shown in Figure 8(b), according to Lemma 4, BFQ* computes an MF[3, 5] $f_{[3,5]}$ in the incremental method (Lines 10-13) based on an MF[1, 4] $f_{[1,4]}$ and the residual network $N_{f_{[1,4]}}$ w.r.t. $f_{[1,4]}$. In detail, Line 11 first computes the flow network $N = N_{f_{[1,4]}} \cup (N_{[4,5]} \setminus N_{[4,4]})$. Then, `IncreMaxFlow()` (Line 13) computes $f_{[3,5]}$ as follows: i) Line 18 computes $N' = \Delta_3(N)$; ii) Lines 19-21 create and insert into N' the virtual node $\langle s', 1 \rangle$ and edge $\langle t, 3 \rangle, \langle s', 1 \rangle$; iii) Line 23 conducts Dinic to find the augmenting path p from $\langle t, 4 \rangle$ to $\langle s', 1 \rangle$: $\langle t, 4 \rangle \rightarrow \langle t, 3 \rangle \rightarrow \langle s', 1 \rangle$; and iv) Line 24 computes the flow network $N' \cup N(\{p\}) \setminus (N_{[1,3]} \setminus N_{[3,3]})$, where no augmenting paths from $\langle s, 3 \rangle$ to $\langle t, 5 \rangle$ can be found in Line 25. Therefore, we have $|f_{[3,5]}| = |f_{[1,4]}| - \text{Flow}(p) = 5 - 3 = 2$. MF[4, 6] can be computed similarly.

BFQ*'s correctness is guaranteed by the following lemma and theorem. The detailed proofs of them are presented in Appendix B [1].

LEMMA 5. `IncreMaxFlow()` computes a set of paths equivalent to set P for the incremental Maxflow computation in Lemma 4.

With Lemmas 4-5, BFQ* can incrementally compute MF $[\tau_s, \tau_e]$ s when increasing τ_s 's value. As BFQ* evaluates Maxflows w.r.t. the same candidate intervals enumerated in BFQ, we have Theorem 2.

THEOREM 2. (Correctness of BFQ*) Given a temporal flow network N_T with source s and sink t , and a parameter δ , BFQ* returns the flow density and the bursting interval of δ -BFlow from s to t .

Analysis. For a temporal flow network $N_T = (V, E_T, T, C_T)$, Lines 4-5 take $O((d_{\max} \cdot |V|)^2 \cdot (d_{\max} \cdot |V| + |E_T|))$ time. The update of transformed flow networks in Lines 18-21 and Line 14 takes $O(d^2 \cdot (d_{\max} \cdot$

Table 2: Statistics of three real world datasets

Dataset	V	E _T	T	Avg. degree	Stddev. degree
Btc2011	1.99M	3.86M	59K	3	7
CTU-13	606K	1.7M	22K	5	1550
Prosper	88K	3.3M	1259	74	141

$|V| + |E_T|)$ time in total. As Lines 6-8 evaluate $O(d^2)$ candidate intervals and Lines 9-16 call $O(1)$ times of Dinic for the incremental Maxflow computation for each candidate interval, the time complexity of Algorithm 3 is $O(d^2 \cdot (d_{\max} \cdot |V|)^2 \cdot (d_{\max} \cdot |V| + |E_T|))$.

6 Experimental Evaluation

We present the experimental settings and then the efficiency evaluation of the proposed δ -BFlow solutions in Section 6.1 and 6.2, respectively. Lastly, we provide a case study in Section 6.3 to demonstrate the application of the proposed δ -BFlow query.

6.1 Experimental Settings

Platform. We implemented in C++ i) some graph data structures for the temporal flow network and the transformed flow network by using the `std::unordered_map` template (an associative container that contains key-value pairs with unique keys, where search, insertion, and removal of elements have average constant-time complexity), which is widely available in graph systems, and then ii) our proposed δ -BFlow solutions by using these structures. The implementation was made memory-resident. All the evaluations were conducted on a machine with an Intel Core i7-7567U 3.5GHz CPU and 16GB RAM running Ubuntu 20.04.5 LTS.

Datasets. We used three real-world datasets, namely the Bitcoin transaction network³, a botnet traffic network in CTU University⁴, and the online peer-to-peer loan service of Prosper Marketplace⁵, which are also used in [16, 27, 35, 45]. These datasets are formatted as temporal flow networks in a similar method as that in [27]. Note that the timestamps of these formatted temporal flow networks are converted into *sequence numbers* in sequence T . Table 2 summarizes some statistics of these datasets.

Queries. We randomly choose 16 pairs of nodes from the datasets as the source s and the sink t such that there exists temporal flow from s to t . As the bursting flow pattern usually happens in a short time, we vary the value of parameter δ for δ -BFlow queries among 3%, 6%, and 9% of $|T|$, where 3% of $|T|$ is set as default.

Solutions. The δ -BFlow solutions to be evaluated are as follows:

- **BFQ.** We use our proposed δ -BFlow solution in Section 4 for finding the flow density and bursting interval of δ -BFlow by i) enumerating all the candidate intervals, and ii) computing Maxflow on the transformed flow network w.r.t. each candidate interval.⁶
- **BFQ⁺.** We use the optimization of the incremental Maxflow computation of the insertion case (Section 5.1)⁷ on BFQ.

³<https://iee-dataport.org/open-access/bitcoin-transactions-data-2011-2013>

⁴<https://www.stratosphereips.org/datasets-ctu13>

⁵<http://konect.cc/networks>

⁶As shown in the experimental section of [27], the linear programming (LP) is hard to handle temporal flow networks with more than 10K temporal edges for computing Maxflows. As the numbers of temporal edges are large when the candidate intervals are of long lengths, we apply Dinic instead of LP to compute Maxflows in BFQ.

⁷We do not apply on BFQ the incremental Maxflow solutions in [28] and [18] since they are designed for dynamic flow networks of inserting or deleting a single general

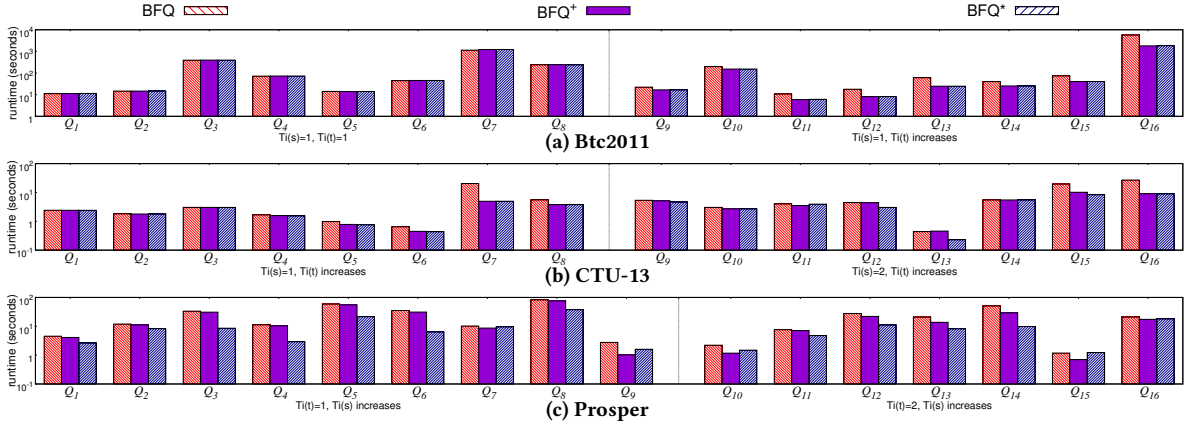


Figure 9: Runtimes of various δ -BFlow solutions on different temporal flow networks (EXP-1)

• BFQ^* . We use the optimizations of the incremental Maxflow computation of both the insertion case (Section 5.1) and the deletion case (Section 5.2)⁷ on BFQ.

Note that there is a technique to prune nodes and temporal edges that do not affect Maxflows on temporal flow networks [27]. This technique is orthogonal to our solutions that it can be applied to further improve the efficiency. We do not include this technique in our solutions to carefully investigate the performance of our proposed solutions. Moreover, we use the augmenting path based Maxflow algorithm, Dinic, in our δ -BFlow solutions for evaluation since it often has the best overall performance.

6.2 Detailed Evaluation on Efficiency

We conducted detailed evaluation to investigate the performance on efficiency of our proposed δ -BFlow solutions. Each query was evaluated 5 times and the average results are reported.

EXP-1. Overall performance. As shown in Table 2, our proposed methods can reduce at least millions of the $|T|^2$ possible time intervals to at most thousands of the $|d|^2$ candidate intervals. In EXP-1, we investigate the efficiency of our proposed δ -BFlow solutions under the default setting. It can be observed in Figure 9(a) that BFQ^+ and BFQ^* has similar runtimes on Btc2011 for Q_1 - Q_8 . The reason is that, for these queries, we have $\text{Ti}(s) = \text{Ti}(t) = 1$ that there is no optimization of the incremental Maxflow computation of both the insertion case and the deletion case. For Q_9 - Q_{16} , both of BFQ^+ and BFQ^* run faster than BFQ due to $\text{Ti}(t) > 1$. There exists incremental Maxflow computation of the insertion case. The experimental results are consistent to an observation on the *Bitcoin* transaction network that most of the addresses has few transactions. The runtimes of the δ -BFlow solutions on CTU-13 are similar to those on Btc2011 as shown in Figure 9(b) since the randomly generated queries for CTU-13 have $1 \leq |\text{Ti}(s)| \leq 2$ and $1 \leq |\text{Ti}(t)| \leq 5$. For Prosper, we can see from Figure 9(c) that BFQ^* is up to 5x and 3x faster than BFQ and BFQ^+ , respectively. This is because the queries' sources have tens of out-going edges that there exists much incremental Maxflow computation of the deletion case.

⁷edge, while our techniques are proposed for handling the insertion and deletion of specific flow networks during the computation in BFQ.

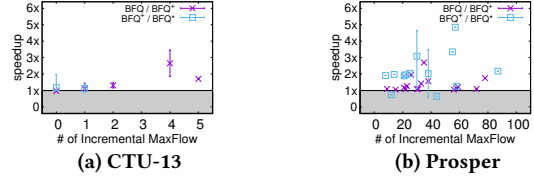


Figure 10: Speedup of BFQ^+ and BFQ^* when varying the number of times of incremental Maxflow computations (EXP-2)

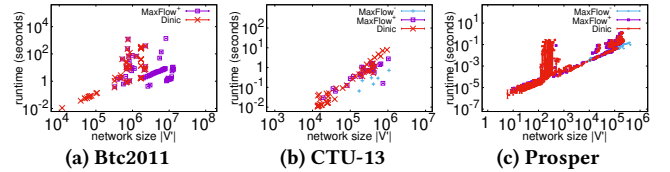


Figure 11: Runtimes of various Maxflow computations when varying the size $|V'|$ of transformed flow network $N = (V', E, C)$ (EXP-3)

EXP-2. Speedup of incremental Maxflow computation. In EXP-2, we investigate the speedup of BFQ^+ and BFQ^* for computing Maxflows by using the ratio of BFQ's runtime to BFQ^+ 's runtime and the ratio of BFQ^+ 's runtime to BFQ^* 's runtime, respectively. To better investigate the incremental Maxflow computation of the proposed solutions, we conducted the speedup evaluation *without* the pruning of Observation 2 on CTU-13 and Prosper, where there exists incremental Maxflow computation of both the insertion case and the deletion case. Figure 10 shows the speedup of BFQ^+ and BFQ^* when varying the number of times of incremental Maxflow computation for finding δ -BFlows for Q_1 - Q_{16} . In Figure 10(a), it can be observed that BFQ^+ always ran faster than BFQ while BFQ^* further ran at most 5x faster than BFQ^+ . Moreover, we can see that the speedup of BFQ^+ and BFQ^* are often not related to the number of times of incremental Maxflow computation. The reason is that, when the size $|V'|$ of the transformed flow network $N = (V', E, C)$ is not large, the runtime of network transformation may sometimes dominate the runtime of Maxflow computation (e.g., the evaluation results for Q_9 , Q_{10} and Q_{15} on Prosper shown in Figure 9(c)).

As our proposed δ -BFlow solutions consist of the network transformation for candidate intervals and the Maxflow computation on transformed flow networks, we report the runtimes of these two parts in the following experiments.

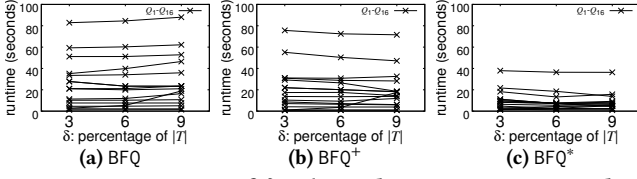


Figure 12: Runtimes of δ -BFlow solutions on Prosper when varying δ (EXP-5)

EXP-3. Runtimes of Maxflow computations when varying the size $|V'|$ of transformed flow network $N = (V', E, C)$. To compute Maxflow f in N w.r.t. a candidate interval, without the network transformation (or the incremental network transformation in Lemmas 3-4), Dinic denotes the computation of f from scratch, while MaxFlow^+ and MaxFlow^- denote the incremental Maxflow computation of the insertion case and the deletion case, respectively. In EXP-3, we conducted BFQ, BFQ^+ , and BFQ^* for Q_1 - Q_{16} on the three datasets to show in Figure 11 the runtimes of Dinic, MaxFlow^+ , and MaxFlow^- on transformed flow networks with different $|V'|$.

It can be observed from Figure 11 that Dinic, MaxFlow^+ , and MaxFlow^- have similar runtimes when $|V'|$ is small that the speedup is not obvious. For Btc2011, we can observe from Figure 11(a) that, there is no cases of MaxFlow^- and the runtime of MaxFlow^+ was not larger than that of Dinic. However, there exist some cases of MaxFlow^+ conducted on transformed flow networks with large $|V'|$. This is because δ -BFlow for Q_{16} ($\text{Ti}(t) = 40$) goes through a dense subgraph of Btc2011, which makes the network transformation of MaxFlow^+ (Lemma 3) duplicate more nodes than the network transformation for specific candidate intervals (Section 4.1). For CTU-13, we can see in Figure 11(b) that the runtimes of Dinic, MaxFlow^+ , and MaxFlow^- increased as $|V'|$ increases while MaxFlow^- is the fastest among the three Maxflow computation on transformed flow networks with the same $|V'|$. For Prosper, Figure 11(c) shows that the runtime of Dinic varies a lot since it's known that the runtime of Dinic for finding Maxflow depends on the topologies of the found augmenting paths, and MaxFlow^- is also the fastest on transformed flow networks having the same $|V'|$.

EXP-4. Runtimes of the network transformations for the proposed δ -BFlow solutions. Let Trans , Trans^+ , and Trans^* denote all the network transformation (from scratch or incrementally) of BFQ, BFQ^+ and BFQ^* , respectively. We observed from the runtimes of the network transformation on the three evaluated datasets that, when compared to Trans , the runtimes of Trans^+ and Trans^* had similar trends of speedup as that of the results in Figure 9. Due to the space limitation, the detailed runtimes are presented in Appendix C [1].

EXP-5. Runtimes of δ -BFlow solutions when varying δ . Figure 12 shows the runtimes of the proposed δ -BFlow solutions on Prosper when varying δ . We obtained similar observations on the experimental results for Btc2011 and CTU-13. It can be seen from Figure 12(a) that the runtimes of BFQ for most queries increase as δ increases. This is because a larger δ will make the transformed flow network $N_{[\tau_s, \tau_s + \delta]}$ w.r.t. $[\tau_s, \tau_s + \delta]$ have a larger $|V'|$ that finding augmenting paths on $N_{[\tau_s, \tau_s + \delta]}$ takes more time. However, we further remark that the runtimes for some queries (Q_{10} and Q_{12}) decrease slightly since a larger δ may invalidate some timestamps in $\text{Ti}(t)$ (i.e., τ_e should be not smaller than $\tau_s + \delta$ according to the definition of δ -BFlow (Definition 2)) that fewer candidate

intervals were evaluated. For BFQ^+ and BFQ^* , we can observe from Figures 12(b) and 12(c) that their runtimes for most queries decrease as δ increases. The reason is that, with the proposed incremental Maxflow computation strategies, the runtimes of BFQ^+ and BFQ^* are not as sensitive to $|V'|$ as the runtime of BFQ, and hence, the runtimes decrease due to the decrease of the number of candidate intervals when δ increases. Due to the space limitation, the detailed results for Btc2011 and Prosper are presented in Appendix C [1].

6.3 Case Study

To demonstrate the application of δ -BFlow on anomaly detection, we applied BFQ^* to find δ -BFlow on the transaction network of a southeast Asia's superapp called *Grab*⁸. The dataset contains 3.5M nodes as users, 28M temporal edges with 2.5M distinct timestamps as transactions. To simplify the exposition, we converted the timestamps (with a translation conducted by *Grab*) into sequence numbers in T and evaluated only the transactions having the largest 1% of timestamps in T . As *Grab* had, in fact, labelled a suspicious user set of 184 nodes, we generated δ -BFlow queries as follows: i) we set $\delta = 0.03$ for filtering the trivial patterns during short time intervals; ii) we inserted into the source set S (resp. the sink set T) all the 14 (resp. 17) suspicious nodes together with 10 randomly chosen nodes having out-going transactions (resp. in-coming transactions); and iii) we generated $24 \times 27 = 648$ δ -BFlow queries $Q = (s, t, 0.03)$, $s \in S$ and $t \in T$. Among these queries, BFQ^* found two interesting queries Q_1 and Q_2 . The densities of the δ -BFlows of Q_1 and Q_2 were significantly larger than the average case. For Q_1 , δ -BFlow f_1 was from node ID 1847843 to node ID 2560590 having a density 26275 during [2000-10-31 19:55:34, 2000-10-31 20:26:01]. For Q_2 , δ -BFlow f_2 was from node ID 2427153 to node ID 806182 having a density 74120 during [2000-10-31 23:59:49, 2000-11-03 02:24:13]. As *Grab* had, in fact, labelled the source and sink nodes of f_1 as suspicious users, the finding of f_1 proved that BFQ^* detected bursting transactions within *half an hour*. For f_2 , the source and the sink were labelled as normal users and the transactions took a long time (3 days), which are common and may not signify an abnormal activity.

7 Conclusion

In this work, we study a new problem of finding a bursting flow pattern on temporal flow networks. We propose a novel concept of a bursting flow in temporal flow networks, called δ -BFlow, to capture the bursting flow patterns. To find δ -BFlow, we first propose a practical solution called BFQ that transforms temporal flow networks into flow networks so that δ -BFlow can be found by computing the maximum flows in these transformed flow networks. To further improve the efficiency of BFQ, we propose to incrementally compute these maximum flows instead of conducting the Maxflow computation from scratch. The experimental results have shown the efficiency of our proposed δ -BFlow solutions. A case study is provided to show the application of δ -BFlow. As for future work, we plan to i) extend the bursting model in temporal graphs to discover bursting graph patterns for subgraph pattern matching semantics, e.g., the subgraph isomorphism [11]; and ii) extend our implementation on existing graph database and analysis applications, such as *Neo4j* and *GraphX*.

⁸<https://www.grab.com/sg/>

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Table 3: Summary of time complexities of some existing Maxflow algorithms on a flow network $N = (V, E, C)$ where V, E , and C are the set of nodes, the set of edges, and the capacity mapping function, respectively. $|f|$ denotes the flow value of the maximum flow f in N .

Algorithm	Network type	Time complexity
Ford-Fulkerson [13]	traditional network	$O(E \cdot f)$
Dinic [12]	traditional network	$O(V ^2 \cdot E)$
Push-relabel [17]	traditional network	$O(V ^3)$ or $O(V \cdot E \cdot \log(V ^2/ E))$
Pseudoflow [20]	traditional network	$O(V \cdot E \cdot \log V)$
Hochstein & Weihe [21]	k -crossings network	$O(k^3 \cdot V \cdot \log V)$
Chambers & Eppstein [5]	one-crossing-minor-free network	$O(V \cdot \log V)$

A Time Complexities of Some Existing Maxflow Algorithms

Table 3 summarizes the time complexities of some existing Maxflow algorithms.

B Proofs

In this appendix, we present the detailed proofs of the lemmas and theorems introduced in this paper.

LEMMA 1. (Existence of flow of equivalent value) Consider a temporal flow network N_T , a source s at the starting timestamp τ_s , a sink t at the ending timestamp τ_e , and the transformed flow network $N_{[\tau_s, \tau_e]}$ of N_T w.r.t. $[\tau_s, \tau_e]$. For any temporal flow F from s to t in N_T , there exists a flow f from node $\langle s, \tau_s \rangle$ to node $\langle t, \tau_e \rangle$ in $N_{[\tau_s, \tau_e]}$ such that $|f| = |F|$, and vice versa.

PROOF. We prove Lemma 1 by constructing the target f and F .

- $F \Rightarrow f$. Given F from s at τ_s to t at τ_e in $N_T = (V, E_T, T, C_T)$, the flow f in $N_{[\tau_s, \tau_e]} = (V', E, C)$ can be constructed as follows:
 - 1) $\forall \langle u, \tau \rangle, \langle v, \tau \rangle \in V'$, if $F(u, v, \tau) > 0$, $f(\langle u, \tau \rangle, \langle v, \tau \rangle) = F(u, v, \tau)$. Otherwise, $f(\langle u, \tau \rangle, \langle v, \tau \rangle) = 0$;
 - 2) let $\text{Ti}_{[\tau_s, \tau_e]}(u)$ denote the set $\{\tau \mid \tau \in \text{Ti}(u), \tau_s \leq \tau \leq \tau_e\}$ and let τ_i denote the i^{th} timestamp in $\text{Seq}(\text{Ti}_{[\tau_s, \tau_e]}(u))$. Then, $\forall \langle u, \tau_i \rangle, \langle u, \tau_{i+1} \rangle \in V'$ such that $u \neq s$,
 - * $f(\langle u, \tau_i \rangle, \langle u, \tau_{i+1} \rangle) = \sum_{v \in V} F(u, v, \tau_i) - \sum_{v \in V} F(u, v, \tau_{i-1})$; and
 - * $f(\langle u, \tau_i \rangle, \langle u, \tau_{i+1} \rangle) = f(\langle u, \tau_{i-1} \rangle, \langle u, \tau_i \rangle) + \sum_{v \in V} F(u, v, \tau_i) - \sum_{v \in V} F(u, v, \tau_{i-1})$, $i \in [2, |\text{Seq}(\text{Ti}_{[\tau_s, \tau_e]}(u))| - 1]$;
 - 3) let $n = |\text{Seq}(\text{Ti}_{[\tau_s, \tau_e]}(s))|$ and let τ_i denote the i^{th} timestamp in $\text{Seq}(\text{Ti}_{[\tau_s, \tau_e]}(s))$. Then, $\forall \langle s, \tau_{i-1} \rangle, \langle s, \tau_i \rangle \in V'$,
 - * $f(\langle s, \tau_{i-1} \rangle, \langle s, \tau_i \rangle) = \sum_{v \in V} F(s, v, \tau_i)$; and
 - * $f(\langle s, \tau_{i-1} \rangle, \langle s, \tau_i \rangle) = f(\langle s, \tau_{i-2} \rangle, \langle s, \tau_{i-1} \rangle) + \sum_{v \in V} F(s, v, \tau_i)$, $i \in [2, n - 1]$;
 - 4) $\forall \langle u, \tau \rangle, \langle v, \tau' \rangle \in V' (\tau \neq \tau')$ such that $(\langle u, \tau \rangle, \langle v, \tau' \rangle) \notin E$, $0 \leq f(\langle u, \tau \rangle, \langle v, \tau' \rangle) \leq C(\langle u, \tau \rangle, \langle v, \tau' \rangle) = 0$
 $\Rightarrow f(\langle u, \tau \rangle, \langle v, \tau' \rangle) = 0$

It can be easily proved that i) f satisfies the capacity constraint and the flow conservation of a flow (Section 3), and ii) $|f| = |F|$.

- $f \Rightarrow F$. Given f from $\langle s, \tau_s \rangle$ to $\langle t, \tau_e \rangle$ in $N_{[\tau_s, \tau_e]} = (V', E, C)$ of $N_T = (V, E_T, T, C_T)$, the temporal flow F in N_T can be constructed by: $\forall u, v \in V, \tau \in [\tau_s, \tau_e]$, if $\langle u, \tau \rangle, \langle v, \tau \rangle \in V'$, $F(u, v, \tau) = f(\langle u, \tau \rangle, \langle v, \tau \rangle)$; otherwise, $F(u, v, \tau) = 0$. F satisfies the following:

- the capacity constraint. $\forall u, v \in V, \tau \in [\tau_s, \tau_e]$, if $\langle u, \tau \rangle, \langle v, \tau \rangle \in V'$, $F(u, v, \tau) = f(\langle u, \tau \rangle, \langle v, \tau \rangle) \leq C(\langle u, \tau \rangle, \langle v, \tau \rangle) = C_T(u, v, \tau)$; otherwise, $F(u, v, \tau) = 0 \leq C_T(u, v, \tau)$.
- the flow conservation (Equation (3)). Given a node u of N_T , let $n = |\text{Seq}(\text{Ti}_{[\tau_s, \tau_e]}(u))|$ and let τ_i denote the i^{th} timestamp in $\text{Seq}(\text{Ti}_{[\tau_s, \tau_e]}(u))$. $\forall u \in V - \{s, t\}$, $i, j \in [2, n]$ ($j > i$), if $j \neq i + 1$, $0 \leq f(\langle u, \tau_i \rangle, \langle u, \tau_j \rangle) \leq C(\langle u, \tau_i \rangle, \langle u, \tau_j \rangle) = 0$. As the flow conservation holds for f , $\forall u \in V - \{s, t\}$, we have,

$$\begin{aligned} & \sum_{i \in [1, n]} \sum_{\langle v, \tau_i \rangle \in V'} f(\langle v, \tau_i \rangle, \langle u, \tau_i \rangle) + \sum_{i \in [2, n]} f(\langle u, \tau_{i-1} \rangle, \langle u, \tau_i \rangle) \\ &= \sum_{i \in [1, n]} \sum_{\langle v, \tau_i \rangle \in V'} f(\langle u, \tau_i \rangle, \langle v, \tau_i \rangle) + \sum_{i \in [1, n-1]} f(\langle u, \tau_i \rangle, \langle u, \tau_{i+1} \rangle) \end{aligned}$$

$$\Rightarrow \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau_e]} F(v, u, \tau) = \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau_e]} F(u, v, \tau)$$

- the time constraint (Equation (4)). $\forall u \in V - \{s, t\}$, $\tau' \in [\tau_s, \tau_e]$, let τ_j denote the j^{th} timestamp in $\text{Seq}(\text{Ti}_{[\tau_s, \tau_e]}(u))$ such that $\tau_j \leq \tau' < \tau_{j+1}$. As the flow conservation holds for f on the nodes $\langle u, \tau_1 \rangle, \dots, \langle u, \tau_j \rangle$ of $N_{[\tau_s, \tau_e]}$, we have,

$$\begin{aligned} & \sum_{i \in [1, j]} \sum_{\langle v, \tau_i \rangle \in V'} f(\langle v, \tau_i \rangle, \langle u, \tau_i \rangle) + \sum_{i \in [2, j]} f(\langle u, \tau_{i-1} \rangle, \langle u, \tau_i \rangle) \\ &= \sum_{i \in [1, j]} \sum_{\langle v, \tau_i \rangle \in V'} f(\langle u, \tau_i \rangle, \langle v, \tau_i \rangle) + \sum_{i \in [1, j]} f(\langle u, \tau_i \rangle, \langle u, \tau_{i+1} \rangle) \end{aligned}$$

$$\begin{aligned} & \Rightarrow \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau']} F(v, u, \tau) = \left(\sum_{v \in V} \sum_{\tau \in [\tau_s, \tau']} F(u, v, \tau) \right) + f(\langle u, \tau_j \rangle, \langle u, \tau_{j+1} \rangle) \\ & \Rightarrow \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau']} F(v, u, \tau) \geq \sum_{v \in V} \sum_{\tau \in [\tau_s, \tau']} F(u, v, \tau) \end{aligned}$$

With the proofs above, F is a temporal flow in N_T that $|F| = |f|$.

With the constructions of f and F , Lemma 1 holds. \square

LEMMA 2. Given a δ -BFlow query $Q = (s, t, \delta)$ on a temporal flow network N_T , δ -BFlow in N_T for Q can be found by evaluating $\text{MF}[\tau_s, \tau_e]$, where τ_s and τ_e satisfy either i) $\tau_e = \tau_s + \delta$, $\tau_s \in \text{Ti}(s)$; or ii) $[\tau_s, \tau_e]$ is a core interval such that $\tau_e - \tau_s > \delta$.

PROOF. For the δ -BFlow query Q , if $[\tau_s, \tau_e]$ is a bursting interval, there are two cases.

Case 1: $[\tau_s, \tau_e]$ is a core interval. For this case, $\text{MF}[\tau_s, \tau_e]$ can be evaluated by enumerating as candidate intervals all the $O(d^2)$ core intervals having interval length larger than δ .

Case 2: $[\tau_s, \tau_e]$ is not a core interval. As $[\tau_s, \tau_e]$ is a bursting interval, there must exist a core interval $[\tau'_s, \tau'_e]$ such that:

- $[\tau'_s, \tau'_e]$ is a subinterval of $[\tau_s, \tau_e]$; and
- $\text{MF}[\tau'_s, \tau'_e]$ and $[\tau_s, \tau_e]$ have the same flow value.

If $[\tau'_s, \tau'_e]$ does not exist, there is no temporal flow during $[\tau_s, \tau_e]$ in N_T , which is *contradictory* to the assumption that $[\tau_s, \tau_e]$ is a bursting interval. Moreover, we have $\tau'_e - \tau'_s < \delta$. The reason is that, if $\tau'_e - \tau'_s \geq \delta$, $[\tau_s, \tau_e]$ cannot a bursting interval since $\text{MF}[\tau'_s, \tau'_e]$ and $[\tau_s, \tau_e]$ have the same flow value while $[\tau'_s, \tau'_e]$ has a smaller interval length. As $N_{[\tau'_s, \tau'_e]}$ is a subgraph of the transformed flow networks $N_{[\tau, \tau + \delta]}$, $\tau'_e - \delta \leq \tau \leq \tau'_s$, we can know that Maxflows w.r.t. all the time intervals $[\tau, \tau + \delta]$ have the same flow value as that of $\text{MF}[\tau_s, \tau_e]$. Therefore, we can only evaluate $\text{MF}[\tau'_s, \tau'_s + \delta]$ and then compute the density $|\text{MF}[\tau'_s, \tau'_s + \delta]|/\delta$ and the bursting

intervals $[\tau, \tau + \delta]$, $\tau'_e - \delta \leq \tau \leq \tau'_e$ as the query results.⁹ Such evaluation can be achieved by enumerating $|\text{Ti}(s)|$ time intervals $[\tau', \tau' + \delta]$, $\tau' \in \text{Ti}(s)$ as candidate intervals.

Based on the above analysis, we can enumerate only $O(d^2)$ candidate intervals to find δ -BFlow and Lemma 2 holds. \square

LEMMA 3. (Incremental Maxflow (insertion case)) Consider a temporal flow network N_T with source s and sink t , the transformed flow network $N_{[\tau, \tau_e]}$ of N_T w.r.t. $[\tau, \tau_e]$, and the following notations.

- $f_{[\tau_s, \tau_e]}$ denotes an MF $[\tau_s, \tau_e]$ (where $\tau_s \geq \tau$) in $N_{[\tau, \tau_e]}$ obtained by Dinic by finding augmenting paths; and
- τ'_e is a timestamp larger than τ_e .

Then, a Maxflow $f_{[\tau_s, \tau'_e]}$ w.r.t. $[\tau_s, \tau'_e]$ in $N_{[\tau, \tau'_e]}$ can be obtained (by Dinic) by finding augmenting paths $p_{\tau'_e}$ s from $\langle s, \tau_s \rangle$ to $\langle t, \tau'_e \rangle$ on the flow network $N_{f_{[\tau_s, \tau_e]}} \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$ having

$$|f_{[\tau_s, \tau'_e]}| = |f_{[\tau_s, \tau_e]}| + \sum_{p_{\tau'_e} \in P} \text{Flow}(p_{\tau'_e})$$

where $N_{f_{[\tau_s, \tau_e]}}$ is the residual network of $N_{[\tau, \tau_e]}$ w.r.t. $f_{[\tau_s, \tau_e]}$.

PROOF. We prove Lemma 3 by showing that the found flow in $N_{f_{[\tau_s, \tau_e]}} \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$ is equivalent to a Maxflow from source $\langle s, \tau_s \rangle$ to sink $\langle t, \tau'_e \rangle$ in $N_{[\tau, \tau'_e]}$. Let's first consider a transformation on flow network $N' = N_{[\tau, \tau_e]} \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$. For any node $\langle u, \tau_e \rangle$ of N' , there exist three exhausted cases:

- **Case 1:** $\langle u, \tau_e \rangle$ has no in-coming edges. For this case, we insert into N' node $\langle u, \tau \rangle$ and edge $(\langle u, \tau \rangle, \langle u, \tau_e \rangle)$ with capacities $+\infty$;
- **Case 2:** $\langle u, \tau_e \rangle$ has only one in-coming edge $(\langle u, \tau' \rangle, \langle u, \tau_e \rangle)$, $\tau' < \tau_e$ and one out-going edge $(\langle u, \tau_e \rangle, \langle u, \tau'' \rangle)$, $\tau'' > \tau_e$. For this case, we remove node $\langle u, \tau_e \rangle$ and these two edges, and then insert into N' an edge $(\langle u, \tau' \rangle, \langle u, \tau'' \rangle)$ with capacities $+\infty$;
- **Case 3.** Case 3 corresponds to the rest cases, where no transformation need to be conducted.

We can easily know that i) such transformation transforms N' into $N_{[\tau, \tau'_e]}$ according to the network transformation procedure (Section 4.1) and operators \uplus and \setminus (Section 5.1); and ii) such transformation has no effect on a Maxflow f' from $\langle s, \tau_s \rangle$ to $\langle t, \tau'_e \rangle$ since f' does not go through the inserted edge in case 1 and f' goes the same flow from $\langle u, \tau' \rangle$ to $\langle u, \tau'' \rangle$ in case 2. Hence, a Maxflow f' from $\langle s, \tau_s \rangle$ to $\langle t, \tau'_e \rangle$ in N' can be transformed into a Maxflow f w.r.t. $[\tau_s, \tau'_e]$ in $N_{[\tau, \tau'_e]}$ according to the above transformation and we have $|f'| = |f|$.

f' can be computed by using existing methods [12, 13] that iteratively finds augmenting paths from residual networks. We first compute the set P of the augmenting paths from $\langle s, \tau_s \rangle$ to $\langle t, \tau_e \rangle$ in $N_{[\tau, \tau_e]}$ to obtain an MF $[\tau_s, \tau_e]$ $f_{[\tau_s, \tau_e]}$ and the corresponding residual network $N_{f_{[\tau_s, \tau_e]}}$. Note that each path p in P can be transformed into an valid augmenting path from $\langle s, \tau_s \rangle$ to $\langle t, \tau'_e \rangle$ in N' with the same flow value $\text{Flow}(p)$ by assigning flow value $\text{Flow}(p)$ on the edges constructed by the timestamp inlining on t for $[\tau_e, \tau'_e]$. Moreover, we have $N_{f_{[\tau_s, \tau_e]}} \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$ equals to the residual network of $N_{[\tau, \tau_e]} \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$ w.r.t. these transformed augmenting paths. The reason is that these augmenting paths go

⁹ τ'_e (resp. τ'_e) can be easily obtained when computing an MF $[\tau'_e, \tau'_e + \delta]$ f by recording the smallest timestamp τ such that $f(\langle s, \tau \rangle, \langle v, \tau \rangle) > 0$, $v \neq s$ (resp. the largest timestamp τ such that $f(\langle v, \tau \rangle, \langle t, \tau \rangle) > 0$, $v \neq t$).

through only the edges of $N_{[\tau, \tau_e]}$ except for the edges constructed by the timestamp inlining on t for $[\tau_e, \tau'_e]$ whose capacities equal to $+\infty$, which do not affect the topology of the residual network w.r.t. the flow of these augmenting paths.

Therefore, we can continue to find augmenting paths $p_{\tau'_e}$ s from $\langle s, \tau_s \rangle$ to $\langle t, \tau'_e \rangle$ in $N_{f_{[\tau_s, \tau_e]}} \uplus (N_{[\tau_e, \tau'_e]} \setminus N_{[\tau_e, \tau_e]})$. The paths in P with a transformation together with the paths $p_{\tau'_e}$ s are valid augmenting paths in N' , and there are no more augmenting paths from $\langle s, \tau_s \rangle$ to $\langle t, \tau'_e \rangle$ in the residual network of N' w.r.t. the flow of these paths. Having the fact that "a flow f from s to t is maximum if and only if there is no augmenting path; that is, t is not reachable from s in the residual graph" [17], we obtain an MF $[\tau_s, \tau'_e]$ f' in N' and hence an MF $[\tau_s, \tau'_e]$ $f_{[\tau_s, \tau'_e]}$ in $N_{[\tau, \tau'_e]}$ having $|f_{[\tau_s, \tau'_e]}| = |f'| = \sum_{p \in P} \text{Flow}(p) + \sum_{p_{\tau'_e} \in P} \text{Flow}(p_{\tau'_e}) = |f_{[\tau_s, \tau_e]}| + \sum_{p_{\tau'_e} \in P} \text{Flow}(p_{\tau'_e})$. Therefore, Lemma 3 holds. \square

THEOREM 1. Given a temporal flow network N_T with source s and sink t , and a parameter δ , BFQ⁺ returns the flow density and the bursting interval of δ -BFlow from s to t .

PROOF. As introduced in Section 4, BFQ computes the flow density and the bursting interval of δ -BFlow by computing Maxflows w.r.t. all the candidate intervals. Therefore, we prove Theorem 1 by showing that BFQ⁺ also computes Maxflows w.r.t. the same candidate intervals enumerated in BFQ.

For the candidate intervals $[\tau_s, \tau_s + \delta]$, $\tau_s \in \text{Ti}(s)$ enumerated in Lines 3-4 of BFQ, BFQ⁺ computes Maxflows w.r.t. these intervals by using Dinic in Lines 3-6. For the rest candidate intervals $[\tau_s, \tau_e]$, $\tau_s \in \text{Ti}(s)$, $\tau_e \in \text{Ti}(t)$ enumerated in Lines 3-4 of BFQ, BFQ⁺ computes Maxflows w.r.t. these intervals by using the incremental method $\text{IncreMaxFlow}^+(\cdot)$ in Lines 9-10. The correctness of $\text{IncreMaxFlow}^+(\cdot)$ is guaranteed by Lemma 3. Therefore, BFQ⁺ and BFQ compute Maxflows w.r.t. the same candidate intervals. Theorem 1 holds. \square

LEMMA 4. (Incremental Maxflow (deletion case)) Consider a temporal flow network N_T with source s and sink t , the transformed flow network $N_{[\tau_s, \tau_e]}$ of N_T w.r.t. $[\tau_s, \tau_e]$, a timestamp $\tau'_s \in \text{Ti}(s)$ that $\tau_s < \tau'_s < \tau_e$, and the following notations.

- $f_{[\tau_s, \tau_e]}$ denotes an MF $[\tau_s, \tau_e]$ in $N_{[\tau_s, \tau_e]}$ obtained by Dinic by finding augmenting paths; and
- P denotes the set of the found augmenting paths that do not pass through node $\langle s, \tau'_s \rangle$.

Then, a Maxflow $f_{[\tau'_s, \tau_e]}$ w.r.t. $[\tau'_s, \tau_e]$ in $N_{[\tau'_s, \tau_e]}$ can be obtained by Dinic by finding augmenting paths $p_{\tau'_s}$ s from $\langle s, \tau'_s \rangle$ to $\langle t, \tau_e \rangle$ in $(\Delta_{\tau'_s}(N_{f_{[\tau_s, \tau_e]}} \uplus N(P))) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ having,

$$|f_{[\tau'_s, \tau_e]}| = |f_{[\tau_s, \tau_e]}| + \sum_{p_{\tau'_s} \in P} \text{Flow}(p_{\tau'_s}) - \sum_{p \in P} \text{Flow}(p)$$

where $N_{f_{[\tau_s, \tau_e]}}$ is the residual network of $N_{[\tau_s, \tau_e]}$ w.r.t. $f_{[\tau_s, \tau_e]}$.

PROOF. We prove Lemma 4 by showing that the found flow in Lemma 4 is equivalent to a Maxflow from source $\langle s, \tau'_s \rangle$ to sink $\langle t, \tau_e \rangle$ in $N_{[\tau'_s, \tau_e]}$. Let's first consider the flow network $N' = (\Delta_{\tau'_s}(N_{[\tau_s, \tau_e]}) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]}))$. According to the definition of timestamp injection (Section 5.2), we can easily know that i) $N' = N_{[\tau'_s, \tau_e]}$; and ii) the timestamp injection and operator \setminus for N' have no effect on a Maxflow f' w.r.t. $[\tau'_s, \tau_e]$ in N' since f' does

not go through the inserted or deleted edges. Hence, f' is also a Maxflow f w.r.t. $[\tau'_s, \tau_e]$ in $N_{[\tau'_s, \tau_e]}$ and we have $|f'| = |f|$.

f' can be computed by using existing methods [12, 13] that iteratively finds augmenting paths from residual networks. Assume that we compute an $\text{MF}[\tau_s, \tau_e]$ $f_{[\tau_s, \tau_e]}$ in $N_{[\tau_s, \tau_e]}$. For $f_{[\tau_s, \tau_e]}$, we insert into set P the found augmenting paths that do not go through $\langle s, \tau'_s \rangle$, and insert the rest found augmenting paths into set P' . Note that the subpaths of the paths in P' starting from $\langle s, \tau'_s \rangle$ to $\langle t, \tau_e \rangle$ can also be augmenting paths for an $\text{MF}[\tau'_s, \tau_e]$ f' in N' having the same flow values on them. We insert these subpaths into set P'' . According to the definitions of residual network (Section 3.1) and augmenting flow network (Section 5.2), it can be deduced that $\left(\Delta_{\tau'_s} (N_{f_{[\tau_s, \tau_e]}} \uplus N(P)) \right) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ equals to the residual network of N' w.r.t. the augmenting paths in P'' since the flow values of augmenting paths in P are withdrawn by conducting operator \uplus between $N_{f_{[\tau_s, \tau_e]}}$ and the augmenting flow network of P . Then, we continue to find augmenting paths $p_{\tau'_s}$ from $\langle s, \tau'_s \rangle$ to $\langle t, \tau_e \rangle$ in $\left(\Delta_{\tau'_s} (N_{f_{[\tau_s, \tau_e]}} \uplus N(P)) \right) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$. The paths $p_{\tau'_s}$ together with the paths in P'' are valid augmenting paths in N' , and there are no more augmenting paths from $\langle s, \tau'_s \rangle$ to $\langle t, \tau_e \rangle$ in the residual network of N' w.r.t. these paths. Having the fact that "a flow f from s to t is maximum if and only if there is no augmenting path; that is, t is not reachable from s in the residual graph" [17], we obtain an $\text{MF}[\tau'_s, \tau_e]$ f' in N' and hence an $\text{MF}[\tau'_s, \tau_e]$ $f_{[\tau'_s, \tau_e]}$ in $N_{[\tau'_s, \tau_e]}$ having $|f_{[\tau'_s, \tau_e]}| = |f'| = \sum_{p \in P''} \text{Flow}(p) + \sum_{p_{\tau'_s}} \text{Flow}(p_{\tau'_s}) = |f_{[\tau_s, \tau_e]}| - \sum_{p \in P} \text{Flow}(p) + \sum_{p_{\tau'_s}} \text{Flow}(p_{\tau'_s})$. Therefore, Lemma 3 holds. \square

LEMMA 5. $\text{IncreMaxFlow}^-()$ computes a set of paths equivalent to set P for the incremental Maxflow computation in Lemma 4.

PROOF. Consider a temporal flow network N_T with source s and sink t . Given a time interval $[\tau_s, \tau_e]$ and a timestamp $\tau'_s \in \text{Ti}(s)$ such that $\tau_s < \tau'_s \leq \tau_e$, assume that Dinic computes an $\text{MF}[\tau_s, \tau_e]$ f in $N_{[\tau_s, \tau_e]}$ with a residual network N_f and finds a set of augmenting paths for f . We divide this set into two subsets P and P' , where P contains the paths that do not pass through node $\langle s, \tau'_s \rangle$ and P' contains the paths that pass through node $\langle s, \tau'_s \rangle$.

Since the edges of $(N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ cannot contribute to $\text{MF}[\tau'_s, \tau_e]$, we prove Lemma 5 by showing that, in $\text{IncreMaxFlow}^-()$, the found augmenting paths from $\langle t, \tau_e \rangle$ to the created virtual node $\langle s', \tau_s \rangle$ can withdraw the same flow value from each edge of $N_f \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ as the paths in P do.

Note that i) an augmenting path in a transformed flow network can be also considered as a transformed flow network, and ii) the timestamp injection does not change the flow values of augmenting paths in a transformed flow network. Therefore, we conduct the timestamp injection on N_f and the augmenting paths in P and P' . Let $P_{f'}$ denote the set of the reversed paths of the augmenting paths for a Maxflow f' from $\langle t, \tau_e \rangle$ to $\langle s', \tau_s \rangle$ found by $\text{IncreMaxFlow}^-()$. Then, the proof idea for Lemma 5 is equivalent to proving that $N(P_{f'}) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]}) = N(P) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$. In the following, we show how this equation holds.

As assumed above, an $\text{MF}[\tau_s, \tau_e]$ f is computed by finding the augmenting paths in P and P' . Then, according to the insertion of

edges in Lines 20-21 of Algorithm 3, we can know that the flow value of f' equals to the sum of the capacities of the incoming edges of the virtual node $\langle s', \tau_s \rangle$, i.e., $\sum_{p \in P} \text{Flow}(p)$. The reason is that there must exist a Maxflow f'' from $\langle t, \tau_e \rangle$ to $\langle s', \tau_s \rangle$ having $|f''| = \sum_{p \in P} \text{Flow}(p)$, which can be obtained by using the reversed paths of the augmenting paths in P with minor modification as follows: i) conduct timestamp injection on these reversed paths for τ'_s ; and ii) for each reversed path, replace this path by its subpath p starting at $\langle t, \tau_e \rangle$ and ending at $\langle u, \tau'_s \rangle$, $u \neq s$ after inserting edge $(\langle u, \tau'_s \rangle, \langle s', \tau_s \rangle)$ into p . Therefore, we have $|f'| = |f''| = \sum_{p \in P} \text{Flow}(p)$. Then, for the set $P_{f'}$ consisting of the reversed paths of the augmenting paths for f' and the set P_Δ consisting of the reversed paths of the modified augmenting paths for f'' , there are two exhausted cases.

- **Case 1:** $P_{f'} = P_\Delta$. For this case, we can easily deduce that $N(P_{f'}) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]}) = N(P_\Delta) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]}) = N(P) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$.
- **Case 2:** $P_{f'} \neq P_\Delta$. For this case, we modify the paths in $P_{f'}$ as follows: i) conduct timestamp injection on the augmenting paths in P for τ'_s ; ii) replace each path in P by its subpath starting at $\langle s, \tau_s \rangle$ and ending at $\langle u, \tau'_s \rangle$, $u \neq s$; and iii) construct augmenting paths from $\langle s, \tau_s \rangle$ to $\langle t, \tau_e \rangle$ by combining paths in P and paths in $P_{f'}$ having the common nodes $\langle u, \tau'_s \rangle$, $u \neq s$. We replace the paths in $P_{f'}$ by these constructed augmenting paths. As the flow conservation holds for the nodes $\langle u, \tau'_s \rangle$, $u \neq s$, the paths in $P_{f'}$ together with the augmenting paths in P' can also find an $\text{MF}[\tau_s, \tau_e]$ in $N_{[\tau_s, \tau_e]}$. Therefore, conducting $\left(\Delta_{\tau'_s} (N_f \uplus N(P_{f'})) \right) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$ is equivalent to withdrawing flow value $\text{Flow}(p)$ from the edges of each path p in $P_{f'}$ on the residual network N_{f_Δ} of $N_{[\tau_s, \tau_e]}$ w.r.t. Maxflow f_Δ . That is, $\left(\Delta_{\tau'_s} (N_f \uplus N(P_{f'})) \right) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]}) = \left(\Delta_{\tau'_s} (N_{f_\Delta} \uplus N(P_{f'})) \right) \setminus (N_{[\tau_s, \tau'_s]} \setminus N_{[\tau'_s, \tau'_s]})$. Hence, Case 2 can be considered as Case 1 for the Maxflow f_Δ .

With the analysis above, Lemma 5 holds. \square

THEOREM 2. (**Correctness of BFQ***) Given a temporal flow network N_T with source s and sink t , and a parameter δ , BFQ^* returns the flow density and the bursting interval of δ -BFlow from s to t .

PROOF. Similar to the proof of Theorem 1, we prove Theorem 2 by showing that BFQ^* also computes Maxflows w.r.t. the same candidate intervals enumerated in BFQ .

Let τ_{\min} denote the timestamp $\min_{\tau \in \text{Ti}(s)} \{\tau\}$. Then, for the candidate interval $[\tau_s, \tau_s + \delta]$, $\tau_s \in \text{Ti}(s)$ enumerated in Lines 3-4 of BFQ , BFQ^* computes $\text{MF}[\tau_{\min}, \tau_{\min} + \delta]$ and $\text{MF}[\tau_s, \tau_s + \delta]$, $\tau_s \in \text{Ti}(s) - \{\tau_{\min}\}$ by using Dinic in Lines 4-5 and the incremental method $\text{IncreMaxFlow}^-()$ in Lines 6-13, respectively. The correctness of $\text{IncreMaxFlow}^-()$ is guaranteed by Lemmas 4-5. For the rest candidate intervals $[\tau_s, \tau_e]$, $\tau_s \in \text{Ti}(s)$, $\tau_e \in \text{Ti}(t)$ enumerated in Lines 3-4 of BFQ , BFQ^* computes Maxflows w.r.t. these intervals by using the incremental method $\text{IncreMaxFlow}^+()$ in Line 14. Therefore, BFQ^* and BFQ compute Maxflows w.r.t. the same candidate intervals. Theorem 2 holds. \square

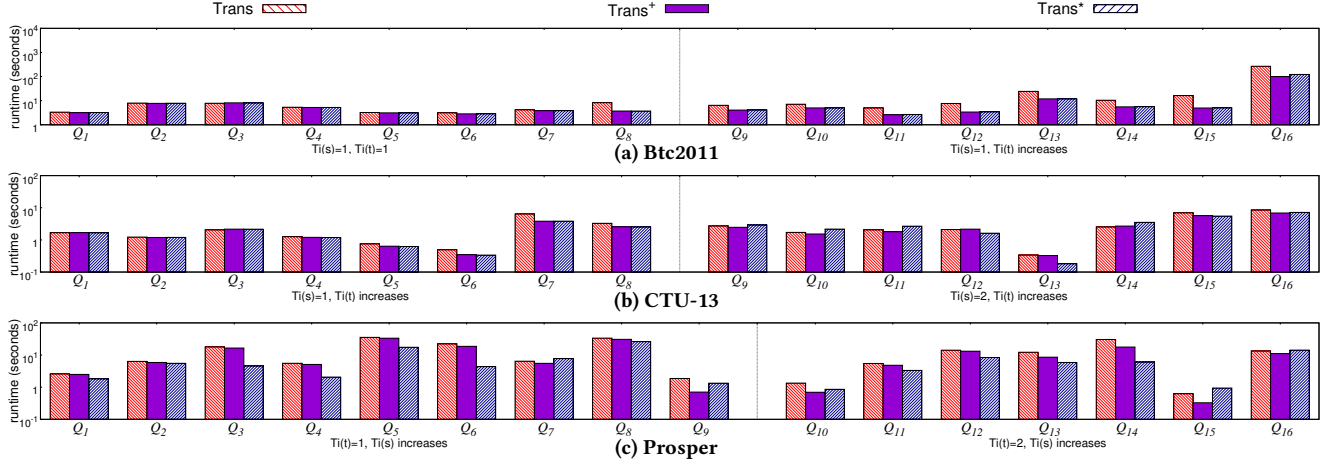
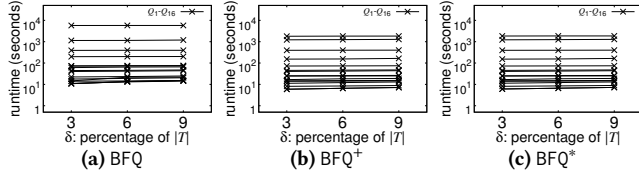
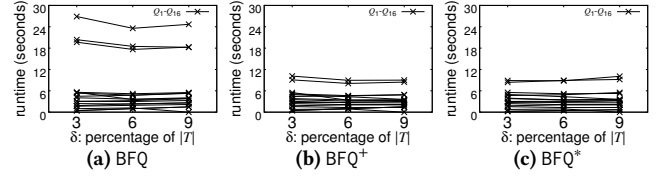


Figure 13: Runtimes of various network transformations on different temporal flow networks

Figure 14: Runtimes of δ -BFlow solutions on the Btc2011 dataset when varying δ Figure 15: Runtimes of δ -BFlow solutions on the CTU-13 dataset when varying δ

C Experimental Results

This section shows some detailed experimental results of Section 6. Firstly, Figure 13 shows the runtimes of Trans, Trans⁺, and Trans⁺ on Btc2011, CTU-13, and Prosper, respectively.

The runtimes of our proposed δ -BFlow solutions on Btc2011 and Prosper when varying δ are presented in Figures 14 and 15.