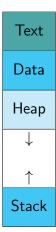
Virtual Memory

Operating Systems
Based on: Three Easy Pieces by Arpaci-Dusseaux

Moshe Sulamy

Tel-Aviv Academic College

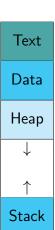
- Each process has its own address space
 - 4GB (32-bit)
 - Not really. Linux takes top 1GB. Windows top 2GB.
 - Heap, Stack, Data, Code (Text)



- Each process has its own address space
 - 4GB (32-bit)
 - Not really. Linux takes top 1GB. Windows top 2GB.
 - Heap, Stack, Data, Code (Text)
- Heap
 - Dynamic memory allocation
- Stack
 - Automatic memory allocation



- Each process has its own address space
 - 4GB (32-bit)
 - Not really. Linux takes top 1GB. Windows top 2GB.
 - Heap, Stack, Data, Code (Text)
- Heap
 - Dynamic memory allocation
- Stack
 - Automatic memory allocation
- Data
 - Static (Global/Local) values and variables
- Code
 - Program instructions



- Each process has its own address space
 - 4GB (32-bit)
- Ten processes: 40GB of RAM!
 - Typically we have much less physical memory
 - And many more processes

How can the OS provide a private, potentially large address space for multiple running processes?

Virtualizing Memory

- OS virtualizes physical memory
- Goals:
 - Transparency:
 - Invisible to the running program
 - A process "thinks" it has a continuous address space
 - Efficiency:
 - Not making programs run much more slowly
 - Not using too much memory to support virtualization
 - Protection:
 - Protect processes from one another, and the OS from processes
 - Isolation among processes

Address Translation

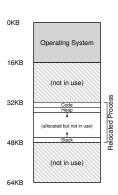
- Hardware-based address translation
 - On every memory reference, address translation is performed
 - Hardware redirects memory references to physical locations
- OS manages memory locations
 - Which are free and which are in use
- Hardware support
 - e.g., registers, TLBs, page-table

Assumptions

- Address space must be placed contiguously
- 2 The size is less than the physical memory size
- Each address space is the same size

Dynamic Relocation

- Also called: base and bounds
 - Hardware registers: base and bounds
 - OS decides where in physical memory a process is loaded
 - Sets base register to that value
 - Memory references are translated by base
 - physical address =
 virtual address + base
 - Processor checks reference is within **bounds** of base



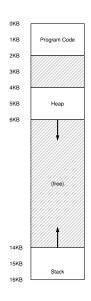
Hardware Support

- Two (or more) CPU modes:
 - OS runs in privileged mode (or kernel mode)
 - Applications run in user mode
- Base and bounds registers
 - Hardware is called memory management unit (MMU)
- Generate exceptions on illegal access
 - Execute OS exception handler

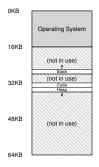
Issues

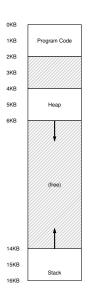
- A process starts running:
 - Find space for address space in physical memory
 - Maintain a free list of free address spaces
- A process is terminated:
 - Reclaim the memory for use
 - Add it back to the free list
- Context switch:
 - Save and restore the base and bounds registers
 - In the process structure (PCB)

- Base and bounds is problematic
 - Big chunk of free space
 - Still taking up physical memory
- Solution?



- Base and bounds is problematic
 - Big chunk of free space
 - Still taking up physical memory
- Solution? segmentation
 - Base and bounds pair for each segment





- A contiguous portion of the address space
 - Logical segments: code, stack, heap
- Each can be placed in a different part of the physical memory
- physical address = offset + base
 - Not virtual address + base!
 - e.g., offset of virtual address 100 is 100
 - Offset of virtual address 4200 can be 104
 - Since it is 104 in the heap segment

- Ever encountered a **segmentation fault**?
- If an **illegal address** beyond the segment is referenced:
 - Hardware detects out of bounds access
 - OS event: segmentation fault

Support for Sharing

- Segment can be shared between address spaces (processes)
 - Code sharing is common
 - Same program, no need to load the code twice
- Extra hardware support: protection bits
 - Code segment is read-only
 - Can be shared without harming isolation

Segment	Base	Size	Grows Positive?	Protection
Code	32K	2K	1	Read-Execute
Неар	34K	3K	1	Read-Write
Stack	28K	2K	0	Read-Write

Fine-Grained vs. Coarse-Grained

- Thus far: just a few segments
 - Code, stack, heap
 - Coarse-grained
- Fine-grained
 - Large number of smaller segments
 - Segment table stored in memory
 - More flexible

OS Support

- On context switch: segment registers saved and restored
- On memory allocation/free: update segment size

OS Support

- On context switch: segment registers saved and restored
- On memory allocation/free: update segment size

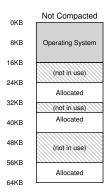
External fragmentation

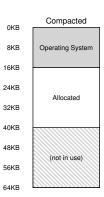
- Physical memory becomes full of little holes of free space
- Difficult to allocate new segments, or grow existing ones

Compaction

Compaction

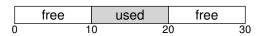
- Stop running processes
- Copy data to contiguous region
- Change segment registers accordingly
- Compaction is expensive!





External Fragmentation

- Detour to discuss free-space management
- Also applies to user-level memory allocation
 - e.g., malloc() and free()
- Not a problem with fixed-size chunks
 - Can use a free-list

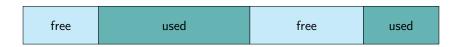


20 free bytes fragmented into chunks of 10

External Fragmentation

Assume:

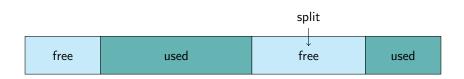
- A basic heap interface:
 - malloc(size_t size) allocates size or more bytes
 - free (void *ptr) frees corresponding chunk
 - Note that no size is provided
- Only external fragmentation
 - Allocators also have internal fragmentation
 - Unused space in chunks bigger than requested
- No memory relocation
 - No compaction of free space



malloc(2048)

free used	free	used
-----------	------	------

malloc(2048)



$$malloc(2048) = 15KB$$

free used	used	free	used
-----------	------	------	------

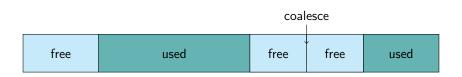


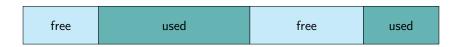
free (15KB)

free used	l used	free	used
-----------	--------	------	------

free (15KB)

free used	free	free	used
-----------	------	------	------





- Find a free chunk to satisfy request and split it into two
 - Assume the following 30-byte heap:

	free	used	f	ree
0	1	0	20	30

• Its free list is:



• After a 1-byte request:

- Find a free chunk to satisfy request and split it into two
 - Assume the following 30-byte heap:

	free	used	free	
ō	1	0	20	30

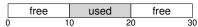
• Its free list is:



• After a 1-byte request:



- Coalesce free space when memory is freed
 - i.e., merge contiguous free chunk
 - Consider our previous heap:



• After a call to free (10):



With coalescing:

- Coalesce free space when memory is freed
 - i.e., merge contiguous free chunk
 - Consider our previous heap:



• After a call to free (10):



With coalescing:



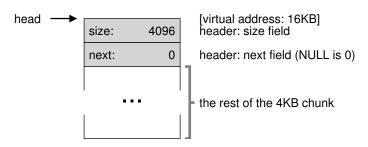
Tracking The Size

- Interface to free (void *ptr) does not provide size
- Store extra information in a header block
 - Usually just before chunk of memory
 - Magic number for integrity checking

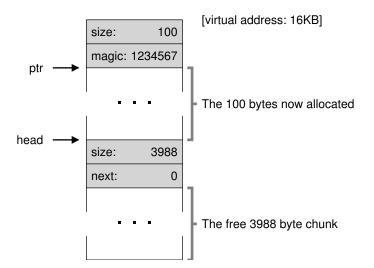


- Need to implement the free list itself
 - Can't call malloc() we are implementing it!
 - Need to embed the list inside the free space itself

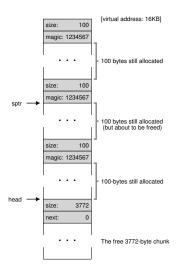
- Need to implement the free list itself
 - Can't call malloc() we are implementing it!
 - Need to embed the list inside the free space itself
- Example: manage 4096-byte chunk
 - Maintain size and next for each node:



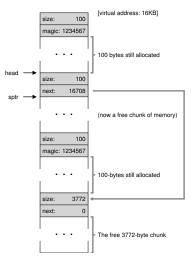
• 100 bytes are requested: **split** chunk



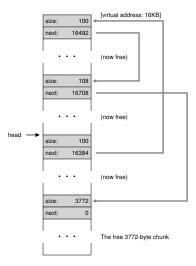
• Three allocated regions of 100 bytes:



- After free (16500):
 - Region start: 16384, previous chunk: 108, current header: 8



- Free last two chunks: fragmentation!
 - Need to coalesce the list



Managing Free Space

Best Fit

- Return smallest chunk that's as big or bigger than requested size
- Exhaustive search: heavy performance penalty

Worst Fit

- Opposite of best fit: return largest chunk
- Still requires full search, bad performance, excess fragmentation

Managing Free Space

First Fit

- Return first block that is big enough
- Speed advantage, but pollutes beginning of list

Next Fit

- As first fit, but start where stopped previously
- Spreads the searches throughout the list

Managing Free Space

• Examples: allocation request size 15



Best-fit:



Worst-fit:

head
$$\longrightarrow$$
 10 \longrightarrow 15 \longrightarrow 20 \longrightarrow NULL

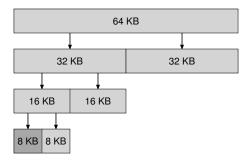
• First-fit: same as worst-fit, but faster

Segregated Lists

- Keep lists for fixed-size objects
- General memory allocator for the rest
- Slab allocator allocates object caches
 - For common kernel objects (locks, file-system inodes, etc.)
 - When a cache is running low: request slab of memory from general allocator

Buddy Allocation

- Make coalescing simple: binary buddy allocator
- Divide free space by two until a block is found
 - Further split into two is too small
 - Suffers from internal fragmentation
 - Easy to coalesce:
 - Recursively up the the tree
 - Buddy address differs by a single bit



Summary

- Virtualize RAM into process address space
- Address translation:
 - Dynamic relocation (base and bounds)
 - Segmentation
 - Coarse-grained: just a few segments
 - Fine-grained: large number of smaller segments
- External fragmentation
 - Free memory fragments into small parts
 - Splitting & coalescing
- Compaction
 - Stop processes, copy data to contiguous region