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Carmi Merimovich

Tel-Aviv Academic College

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- The process model is determined by both: Hardware and Software.
- The process model is visible directly to Assembly language programmers.
- Higher (and higher) level languages masks the process model from the user.

### Address space

- Address width is hardware dependent. (32-bit on 32 bit Intel's).
- I.e., the address space is 4GB.
- The software can (and does) impose limits on user usage.
- (This required hardware assistance).

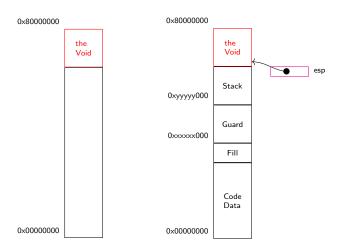
### **Process Memory**

- The memory can be continuous or discountinuous.
- Parts of it can be read-only.
- (Requires hardware assistance).
- The kernel enforces memory separation between processes.
- It does not care for process bugs.
- e.g., byte sized process vs. page size granularity.

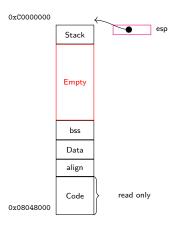
### хv6 process memory

- Program code/data begins at address 0.
- Memory is continuous.
- Memory can be in the range (0-7FFFFFF) (i.e., 2GB).
- In fact only 1MB, but this is easily fixed.
- Stack is above the program.
- There is a guard page between the code/data and the stack
- Note a program can change the above.

### xv6 default process memory layout



### Linux default process memory layout



### xv6 process execution model

- Only non-privileged(!) instructions can be used.
- Integer registers: eax, ecx, edx, ebx, esp, ebp, esi, edi.
- Segment registers: cs, ds, ss, es, fs, gs.
- Of course: eip.

There are MANY MORE unprivileged registers.

- fp0-fp7.
- mmx, xmm, sse 1,2,3,4....
- They are NOT PART of the xv6 process model.
- However: There's no hardware mechanism enforcing this!
- It is the programmers problem if she uses them.

Can a process do anything other than calculations?!?!?!?!

NO. Other stuff can be done ONLY by the kernel.

# System calls or System services

### xv6 process related system calls

Table: Process control

fork() Create process

exit() Terminate current process

wait() Wait for a child process to exit

kill(pid) Terminate process pid

getpid() Return current processs id sleep(n) Sleep for n timer interrupts

Load a file and execute it

exec(filename, \*argv)

Table: Memory control

Grow processs memory by n bytes sbrk(n)

### xv6 file related system calls

Table: file name control

open(filename, flags)
Open a file; flags indicate read/write
pipe(p)
Create a pipe and return fds in p
chdir(dirname)
Change the current directory

mkdir(dirname) Create a new directory mknod(name, major, minor) Create a device file

link(f1, f2) Create another name (f2) for the file f1

unlink(filename)

#### Table: file control

read(fd, buf, n) Read n byes from an open file into buf

write(fd, buf, n) Write n bytes to an open file

close(fd) Release open file fd

dup(fd) Duplicate fd

pipe(p) Create a pipe and return fds in p fstat(fd) Return info about an open file

### system calls?!

- The above looks like a list of C callable routines.
- Which indeed they are!
- But then the code runs in the process model, hence can do nothing...
- First: Recall the C calling convention.
- Second: We see what is really a system call.

### gcc C calling convention: Caller

• Push to the stack arguments from right to left.

```
pushl arg n-1

\vdots \vdots

pushl arg 0
```

Invoke the callee with the call instruction.

- Assumes the callee preserved registers except eax, ecx, edx.
- Removes arguments from stack.

- Integer function return value is in eax.
- (Caller should save register eax, ecx, and edx, if it needs them).

# At&t syntax vs. Intel syntax

#### At&t:

#### Intel:

add esp,4\*n

- 1. Operand size is adjoined to the mnemonic.
- 2. Source and destination order is the opposite of Intel/MS order.
- 3. Immediate operands are preceded by \$.
- 4. Register names are preceded by %.

### Calling a 0-aruments functions

#### Listing 1: source

```
void main(void) {
  extern fork();
  fork();
}
```

#### Listing 2: compiled

```
.globl fork
main::
call fork
ret
}
```

### Calling a 1-argument function

#### Listing 3: source

```
void main(void) {
  extern close();

close(0);
}
```

#### Listing 4: compiled

```
.globl close
main::
pushl $0
call close
addl $4,%esp
ret
}
```

### Calling a 2-arguments function

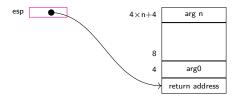
#### Listing 5: source

```
void main(void) {
  extern open();
  open("f",0);
}
```

#### Listing 6: compiled

```
.globl open
 .code
main::
 pushl $0
 pushl $s
 call open
 addl $8,%esp
 ret
 .data
s: .asciz "f"
```

### Stack on entering a routine



### gcc C callee

- Arguments are to be found on the stack above the return address.
- Registers ebx, ebp, esi, edi, and esp, should be preserved.
- (integer) Return value is put in **eax**.
- Returning using the ret instruction.
- Note: accessing the paramters without a frame pointer is error-prone for humans.

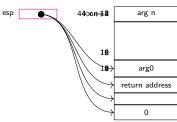
# Arguments offset relative to esp

movl 8(%esp),%eax

subl \$4,%esp
movl 12(%esp),%eax

push1 \$0
movl 16(%esp),%eax

addl \$8,%esp



# Arguments offset relative to ebp

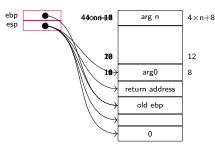
pushl %ebp
movl %esp,%ebp

movl 12(%ebp), %eax

subl \$4,%esp
movl 12(%ebp),%eax

push1 \$0
movl 12(%ebp),%eax

addl \$8,%esp
popl %ebp
ret



### system services

- Each kernel supplies a set of system services.
- These routines run at a privileged (i.e., kernel) state.
- Each routine is identified by a number (which is not very comfortable).
- Each routine might accept arguments.
- Each kenrel/hardware combination has its own system call convention.

# xv6 fork/close/open systrem call

Listing 7: fork

movl \$1,%eax int \$64

Listing 8: close

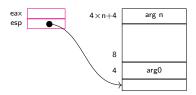
push! \$0
sub! \$4,%esp
mov! \$21,%eax
int \$64
add! \$8.%esp

Listing 9: open

push! \$0
push! \$s
sub! \$4,%esp
mov! \$13,%eax
int \$64
add! \$12,%esp

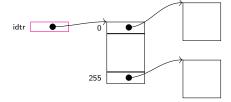
::
 .data
s: .asciz "f"

### State at int \$64 execution



# int \$64 in the xv6 process model

- The **int** instruction is a glorified **call** instruction.
- It has one "side effect": The processor switches to kernel.
- The operand (0–255) is the **number** of the function to run.
- Attempting number other than 64 yields a security violation.
- Outside of the process model:



Demonstrating a different system call convention (Linux)

# Linux system (service) call convention

- The arguments are loaded into registers in the following order: ebx, ecx, edx, esi, edi, ebp.
- System call number is in eax.
- int \$128 is executed.
- Success/failure code returned in eax.
- Except eax, registers (of the process model) are preserved.

# linux/x86-32 fork/close/open system calls

Listing 10: fork

Listing 11: close

Listing 12: open

movl \$2,%eax int \$128

movl \$0,%ebx movl \$6,%eax int \$128 movl \$0,%ecx movl \$s,%ebx movl \$5,%eax int \$128

.data

s: .asciz "f"

Kernel defined xv6 process model

xv6-rev10 The Process model

#### xv6 Process model: files

- File is a general name which can refer to:
  - (disk) file.
  - pipe.
  - · device.
- Mostly, files have names.
- The file names form hierarchy through folders.
- Names(!) can be added/removed to/from existing files.

#### xv6 Process model: files

- The file supporting system calls are divided into:
  - Name only services.
    - Name begining with '/' are considered absolute.
    - Names not begining with '/' are relative to the current working directory.
  - Content services.
- In order to deal with the content of the file it should be "opened".
- Opening a file creates a context for it in the kernel.
- This context is referred to with the **file descriptor**.
- Up to 16 file descriptor can be active in parallel.