xv6©-rev10 (Copyright Frans Kaashoek, Robert Morris, and Russ Cox.) xv6 Interrupt Servicing

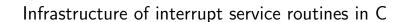
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Interrupt Serivce routines

- In xv6 the C-routine **trap()** is the basis for interrupt servicing.
- Interrupt service routines are necessarily hardware depedent, thus
 - ISRs cannot be written totally in C.
 - (as usual) We aim to write whatever is possible in C.
- In the following we look at what the hardware forces us to do.



Using trap0() issues

- Assume **trap0** is a C routine to handle interrupt request 0.
- Issues we need to deal with:
 - Can IDT[0] point directly to **trap0**? Yes, but returing will crash.
 - What about the interrupted code registers? Proably will be destroyed.
 - What about our segment registers? Unexpected if was at user mode.

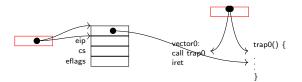
We solve these issues one by one.

IDT[0] pointing to a good place

- trap0() ends with ret, no way around it.
- So we wrap **trap0** inside a routine ending with **iret**:

```
vector0:
call trap0
iret
```

• Then we let IDT[0] point to vector0.



Saving interrupted code GPRs

- Registers destroyed by the interrupt service routine should be saved.
- eip, eflags, and possibly esp where already saved.
- The registers destroyed by trap0() are not known, thus save them all:

```
vector0:

pushal

call trap0

popal

iret
```

Our segment registers?

- cs was saved and then loaded from the IDT.
- SS:
 - User mode interrupted: ss was saved and then loaded from the TSS.
 - Kernel mode interrupted: ss already contains the correct value (SEG_KDATA).
- ds, es, fs, gs: Code needed:

```
movw $SEG_KDATA<<3,%ax
movw %ax,%ds
movw %ax,%es
movw $0,%ax
movw %ax,%fs
movw %ax,%gs
```

Infrastructure (1) for trap0()

```
vector0:
  pushal
movw $SEG_KDATA<<3,%ax
movw %ax,%ds
movw %ax,%es
movw $0,%ax
movw %ax,%fs
movw %ax,%fs
movw %ax,%gs</pre>
```

```
call trapO
popal
iret
```

• We might have just destroyed user mode registers!

Infrastructure (2) for trap0()

```
vector0:
 pushl %ds
 pushl %es
 pushl %fs
 pushl %gs
 pushal
movw $SEG_KDATA<<3.%ax
movw %ax,%ds
movw %ax.%es
movw $0,%ax
movw %ax,%fs
movw %ax,%gs
```

```
call trap0
popal
popl %gs
popl %fs
popl %es
popl %ds
iret
```

Interrupted code registers content

- ISRs might be interested in accessing the interrupted code registers.
- (This is reasonable only for internal interrupt requests!)
- The register values where pushed onto the stack.
- A slight addition allows easy access to them from C.
- (elective) The values are accessible also without the change.

Infrastructure (3) for trap0()

```
vector0:
 pushl %ds
 pushl %es
 pushl %fs
 pushl %gs
 pushal
movw $SEG_KDATA<<3.%ax
movw %ax.%ds
movw %ax.%es
movw $0,%ax
movw %ax,%fs
movw %ax,%gs
```

```
pushl %esp
call trap0
addl $4,%esp
popal
popl %gs
popl %fs
popl %es
popl %ds
iret
```

frame struct

```
struct frame {
 long edi;
 long esi;
 long ebp;
 long esp_irrelevant;
 long ebx;
 long edx;
 long ecx;
 long eax;
short gs;
 short padding1;
 short fs:
 short padding2;
 short es:
```

```
short ds:
short padding4;
long eip;
short cs:
short padding5;
long eflags;
long esp;
short ss:
short padding6;
```

Accessing interrupted code registers

Possible declaration of trap0():

```
void trap0(struct frame *f) {
f->eax = someValue(f);
:
}
```

• Note: The **esp** and **ss** fields exist only if user mode was interrupted.

Infrastructure for trap8() (serving IRQ 8)

- IRQ8 leaves error code below eip.
- Hence:
 - The **frame** struct does not give the correct picture.
 - There is a superfulous word before the **iret** instruction.
- So:
 - A new structure replacing frame struct is needed.
 - Revmoing a word from the stack is needed.

Infrastructure (1) for trap8()

```
vector8:
 pushl %ds
 pushl %es
 pushl %fs
 pushl %gs
 pushal
movw $SEG_KDATA<<3.%ax
movw %ax.%ds
movw %ax.%es
movw $0,%ax
movw %ax,%fs
movw %ax,%gs
```

```
pushl %esp
call trap8
addl $4,%esp
popal
popl %gs
popl %fs
popl %es
popl %ds
addl $4,%esp
iret
```

eframe struct

```
struct eframe {
 long edi;
 long esi;
 long ebp;
 long esp_irrelevant;
 long ebx;
 long edx;
 long ecx;
 long eax;
short gs;
 short padding1;
 short fs:
 short padding2;
 short es:
```

```
short ds:
short padding4;
long err;
long eip;
short cs:
short padding5;
long eflags;
long esp;
short ss:
short padding6;
```

Accessing error code

• Possible declaration of trap8():

```
void trap8(struct eframe *f) {
  if (f->err)
  f->eax = someValue(f);
  else
  f->eax = someOtherValue(f);
  :
}
```

Uniform behaviour would be useful

- The above solution is feasible.
- However, if one uniform routine trap() is asked for, we tinker.
- How?

Infrastructure (4) for trap0()

```
vector0:
 pushl $0
 pushl %ds
 pushl %es
 pushl %fs
 pushl %gs
 pushal
movw $SEG_KDATA<<3.%ax
movw %ax.%ds
movw %ax, %es
movw $0,%ax
movw %ax,%fs
movw %ax,%gs
```

```
pushl %esp
call trap0
addl $4,%esp
popal
popl %gs
popl %fs
popl %es
popl %ds
addl $4,%esp
iret
```

The **trapframe** struct (1)

```
struct trapframe {
 long edi;
 long esi;
 long ebp;
 long esp_irrelevant;
 long ebx;
 long edx;
 long ecx;
 long eax;
short gs;
 short padding1;
 short fs:
 short padding2;
 short es:
```

```
short ds:
short padding4;
long err;
long eip;
short cs;
short padding5;
long eflags;
long esp;
short ss:
short padding6;
```

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All isr's can use the **trapframe** struct

```
void trap0(struct trapframe *f) {
    :
}

void trap8(struct trapframe *f) {
    :
}
```

• Let us reorganize the entry code.

Infrastructure (5) for **trap0()**

```
vector0:
pushl $0
imp alltraps
alltraps:
 pushl %ds
 pushl %es
 pushl %fs
 pushl %gs
 pushal
movw $SEG_KDATA<<3,%ax
movw %ax.%ds
movw %ax,%es
movw $0.%ax
movw %ax,%fs
```

```
pushl %esp
call trap0
addl $4,%esp
popal
popl %gs
popl %fs
popl %es
popl %ds
addl $4,%esp
iret
```

Infrastructure (5) for trap8()

```
vector8:
imp alltraps
alltraps:
 pushl %ds
 pushl %es
 pushl %fs
 pushl %gs
 pushal
movw $SEG_KDATA<<3,%ax
movw %ax.%ds
movw %ax,%es
movw $0.%ax
movw %ax,%fs
```

```
pushl %esp
call trap8
addl $4,%esp
popal
popl %gs
popl %fs
popl %es
popl %ds
addl $4,%esp
iret
```

Infrastructure (1) for trap(), IRQ0

```
vector0:
 pushl $0
imp alltraps
vector8:
imp alltraps
alltraps:
 pushl %ds
 pushl %es
 pushl %fs
 pushl %gs
 pushal
movw $SEG_KDATA<<3.%ax
```

What is lost??

```
movw %ax.%ds
movw %ax.%es
movw $0,%ax
movw %ax.%fs
movw %ax,%gs
pushl %esp
call trap
addl $4,%esp
popal
popl %gs
popl %fs
popl %es
popl %ds
addl $4.%esp
iret
```

Infrastructure (2) for trap()

```
vector0:
 pushl $0
 pushl $0
imp alltraps
vector8:
 pushl $8
imp alltraps
alltraps:
 pushl %ds
 pushl %es
 pushl %fs
 pushl %gs
 pushal
movw $SEG_KDATA<<3.%ax
```

```
movw %ax,%ds
movw %ax.%es
movw $0,%ax
movw %ax.%fs
movw %ax,%gs
pushl %esp
call trap
addl $4,%esp
popal
popl %gs
popl %fs
popl %es
popl %ds
addl $8.%esp
iret
```

The **trapframe** struct (2)

```
struct trapframe {
 long edi;
 long esi;
 long ebp;
 long esp_irrelevant;
 long ebx;
 long edx;
 long ecx;
 long eax;
short gs;
 short padding1;
 short fs:
 short padding2;
 short es:
```

```
short ds:
short padding4;
long trapno;
long err;
long eip;
short cs;
short padding5;
long eflags;
long esp;
short ss:
short padding6;
```

trap()

```
void trap(struct trapframe *tf) {
switch (tf->trapno) {
 case 0:
  trap0(tf);
  break:
 case 8:
 trap8(tf);
  break:
```

Retro groking on process creation

- Note the trapframe structure and recall userinit().
- Now we can understand why things are as they are:
 - There are always interrupts.
 - User mode code is always going to be interrupted.
 - So there must be a framework for:
 - switching from user mode to kernel mode.
 - Return safely from kernel mode to user mode.
 - Running new user code builds on this framework.
 - New user code has no history (It is new!).
 - So a fake history is build for it.
 - And then the kenel 'returns' to the code entry point.

• The xv6 code.

Kernel entry points

We combine the previous techniques to get:

- Kernel entry points vector0 upto vector255 follows on the next slide.
- Each entry will contains one or two push instructions followed by jmp alltraps
- Use some scripting language to generate the .S file with the above code.
- (elective) (or by a smart.s and some fancy assembly directives).

all vectors

```
vector0:
 pushl $0
 pushl $0
imp alltraps
vector7:
 pushl $0
 pushl $7
imp alltraps
vector8:
 pushl $8
imp alltraps
vector9:
 pushl $0
 pushl $9
imp alltraps
```

```
vector10:
pushl $10
imp alltraps
vector14:
pushl $14
imp alltraps
vector15:
pushl $0
pushl $15
jmp alltraps
vector16:
pushl $0
pushl $16
jmp alltraps
```

```
vector17:
 pushl $17
imp alltraps
vector18:
 pushl $0
 pushl $18
imp alltraps
vector255:
 pushl $0
 pushl $255
imp alltraps
```

Tedious!

alltraps

alltraps:: pushl %ds pushl %es pushl %fs pushl %gs pushal movw \$SEG_KDATA<<3.%ax movw %ax.%ds movw %ax.%es movw \$0,%ax movw %ax,%fs movw %ax,%gs

```
pushl %esp
 call trap
 addl $4,%esp
trapret:
 popal
 popl %gs
 popl %fs
 popl %es
 popl %ds
 addl $8,%esp
 iret
```

vectors[]

- How do we loop on vector0 through vector255 to initialize IDT?
 - We cannot.
- So, we build a vector of addresses:

```
vectors::
.long vector0
.long vector1
:
.long vector255
```

• Writing this is also TEDIOUS.

vectors.pl

```
for (my i = 0; i < 256; i++) {
 print "vector$i:\n";
 if (!(\$i == 8 ||
    (\$i >= 10 \&\& \$i <= 14) \mid |\$i == 17)) 
  print "_pushl_\$$i\n";
 print "_jmp_alltraps\n";
print ".data\n";
print "vectors::\n";
for (my i = 0; i < 256; i++) {
 print "_.long_vector$i\n";
```

(elective) a direct vectors.S

```
.globl alltraps, vectors
 . data
vectors:
v = 0
.rept 256
 . text
0 :
 | (v = 8 | (10 \le v \& v \le 14) | v = 17) |
   pushl $0
 . endif
 pushl $v
imp alltraps
 . data
 .long 0b
v = v + 1
. endr
```

IDT initializing

Gate descriptor

```
31
                                        16 15 14 13 12 11
 Trap/Interrupt
                                         |1| 00 |0|111 <mark>1/0</mark>|
                      Offset (high)
                                                          00000000
 gate:
              31
                                       16 15
                                                  Offset (low)
                        Selector
    struct gatedesc {
901
     uint off_15_0 : 16; // low 16 bits of offset in segment
     uint cs : 16; // code segment selector
     uint args : 5; // # args, 0 for interrupt/trap gates
     uint rsv1 : 3; // reserved(should be zero I guess)
     uint type : 4; // type(STS_{TG, IG32, TG32})
     uint s : 1; // must be 0 (system)
     uint dpl : 2; // descriptor(meaning new) privilege level
     uint p : 1; // Present
     uint off_31_16 : 16; // high bits of offset in segment
    };
```

SETGATE macro

```
#define SETGATE(gate, istrap, sel, off, d) \ { \
 (gate). off_15_0 = (uint)(off) & 0 \times ffff;
 (gate).cs = (sel);
 (gate).args = 0; \
 (gate).rsv1 = 0; \setminus
 ((gate).type = (istrap) ? STS_TG32 : STS_IG32; 
 (gate).s = 0; \
 (gate).dpl = (d);
 (gate).p = 1;
 (gate).off_31_16 = (uint)(off) >> 16;
```

IDT construction

```
#define T_SYSCALL 64
3361 struct gatedesc idt[256];
   extern uint vectors[]; // in vectors.S: array of 256
   tvinit(void) {
    for (int i = 0; i < 256; i++)
     SETGATE(idt[i], 0, SEG_KCODE<<3, vectors[i], 0);</pre>
    SETGATE(idt[T_SYSCALL], 1, SEG_KCODE<<3,
                 vectors[T_SYSCALL], DPL_USER);
3378 void idtinit(void) {
    lidt(idt, sizeof(idt));
```

xv6-rev10 Interrupt Servicing

Finaly, we can investigate trap().

trap()

The code of **trap()** is composed of three parts:

- 1. Handle **killed** and dispatch to **syscall()** if invoked by **int \$64**.
- 2. Dispatch to code handling other IRQ's.
- 3. Code handling killed and yield().

Note about killed:

- killed set means the process should terminate.
- The killed field should be checked at the following locations:
 - Entering the kernel.
 - Leaving the kernel.
 - Whenever the process might enter SLEEPING for a long time.

trap() part 1

```
void trap(struct trapframe *tf) {
  if (tf->trapno == T_SYSCALL) {
    if (myproc()->killed)
      exit();
  myproc()->tf = tf;
  syscall();
  if (myproc()->killed)
      exit();
  return;
}
```

 User mode might be loooong, hence the check on myproc()->killed before returing.

trap() part 2, controller interrupts

```
switch (tf->trapno) {
case T_IRQ0+IRQ_TIMER:
 if (cpuid() = 0) {
  acquire(&tickslock);
  ticks++:
  wakeup(&ticks);
  release(&tickslock);
 lapiceoi();
break:
case T_IRQ0+IRQ_IDE:
 ideintr();
 lapiceoi();
break:
case T_IRQ0+IRQ_IDE+1:
break:
```

```
case T_IRQ0+IRQ_KBD:
  kbdintr();
  lapiceoi();
  break:
 case T_IRQ0+IRQ_COM1:
  uartintr();
  lapiceoi();
  break:
 case T_IRQ0+7:
 case T_IRQ0+IRQ_SPURIOUS:
  cprintf("cpu%d:_spurious_\
____interrupt_at_%x:%x\n"
   cpuid(), tf \rightarrow cs, tf \rightarrow eip);
  lapiceoi();
  break:
```

trap() part 2, unexpected interrupt

```
default:
               if (myproc() = 0 \mid | (tf->cs\&3) = 0)  {
                     cprintf("unexpected_trap_%d_from_cpu_%d_\
color = colo
                                                       tf \rightarrow trapno, mycpu() \rightarrow id, tf \rightarrow eip, rcr2());
                     panic("trap");
               cprintf("pid_%d_%s:_trap_%d_err_%d_on_cpu_%d_"
                                        "eip_0x\%x_addr_0x\%x kill_proc\n".
             myproc()->pid, myproc()->name, tf->trapno, tf->err
                                                       cpuid(), tf \rightarrow eip,
               rcr2());
             myproc()->killed = 1;
```

trap() part 3

```
if (myproc() && myproc()-> killed &&
         (tf \rightarrow cs \& 3) = DPL_USER)
 exit();
if (myproc() && myproc()->state == RUNNING &&
        tf->trapno == T_IRQ0+IRQ_TIMER)
 yield();
if (myproc() && myproc()-> killed &&
         (tf \rightarrow cs \& 3) = DPL_USER)
 exit();
```