

Linear Causal Disentanglement via Interventions

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IDENTIFIABLE REPRESENTATION LEARNING

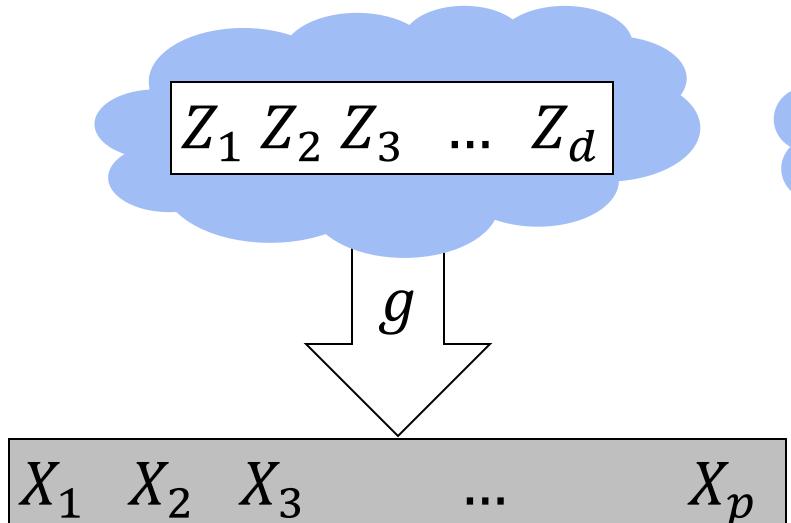
Identifiability: Does a unique generative model (theory)

explain the observed data?

(Latent) Macro-variables (Unknown)

(Observed)

Mixing function Micro-variables



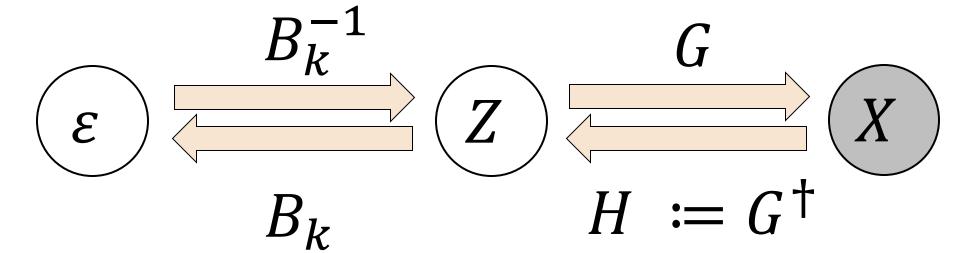
Cell State Biological & optical processes Cell image

Example

Causal representation learning/causal disentanglement: We assume $\mathbb{P}(Z)$ is Markov to a DAG G (w.l.o.g., assume (1, 2, ..., d) is a topological order of G).

ASSUMPTIONS IN OUR WORK

- (a) Linear latent model: For context k, we have $Z = A_k Z + \Omega_k^{1/2} \varepsilon$. Here, the support of A_k is consistent with \mathcal{G} , Ω_k is diagonal, and $\text{Cov}(\varepsilon) = I$. Define $B_k = \Omega_k^{1/2} (I - A_k)$.
- (b) Single-node interventions: For context k, there exists an intervention target i_k such that only the i_k -th row of B_k changes.
- (c) Linear mixing: In each context, X = GZ for $G \in \mathbb{R}^{p \times d}$ full rank.

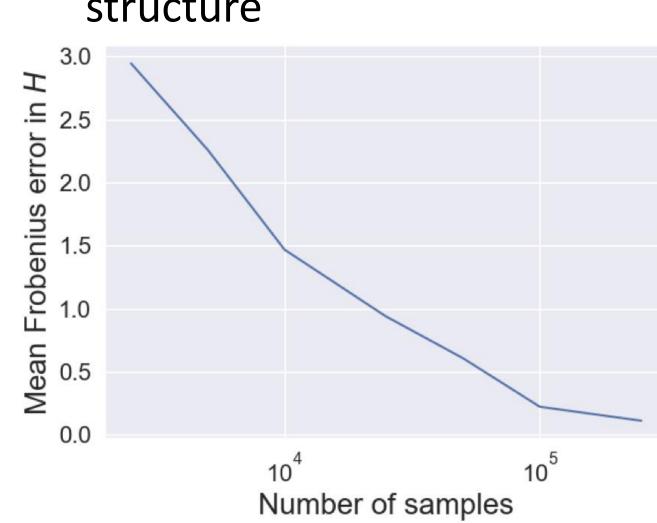


Under these assumptions: $\Theta_k := \operatorname{Cov}_k(X)^{\dagger} = H^{\mathsf{T}} B_k^{\mathsf{T}} B_k H$

EMPIRICAL RESULTS

Synthetic data

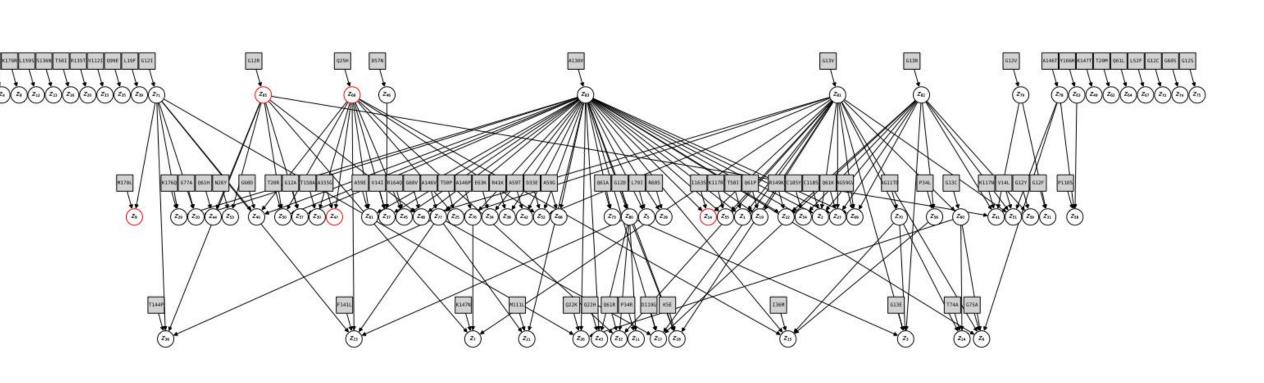
- d = K = 5
- p = 10
- 500 random models, Erdős-Rényi structure



Lung cancer scRNA-seq data [7]:

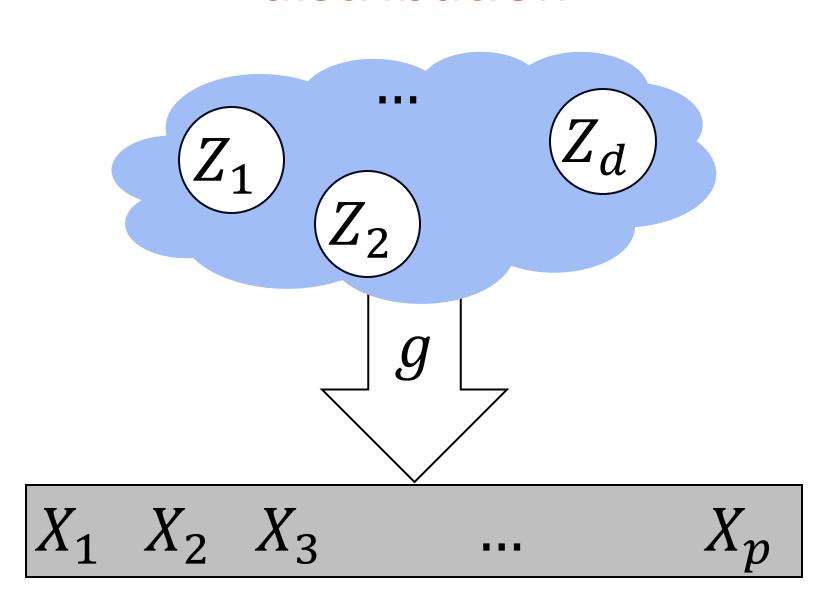
- K = 83 (mutations of the KRAS oncogene)
- p = 83 (most variable genes)

Qualitative findings: Mutations of G12 and G13 are predicted to have widespread effects; these are key functional residues, and their mutations are known drivers of cancer.



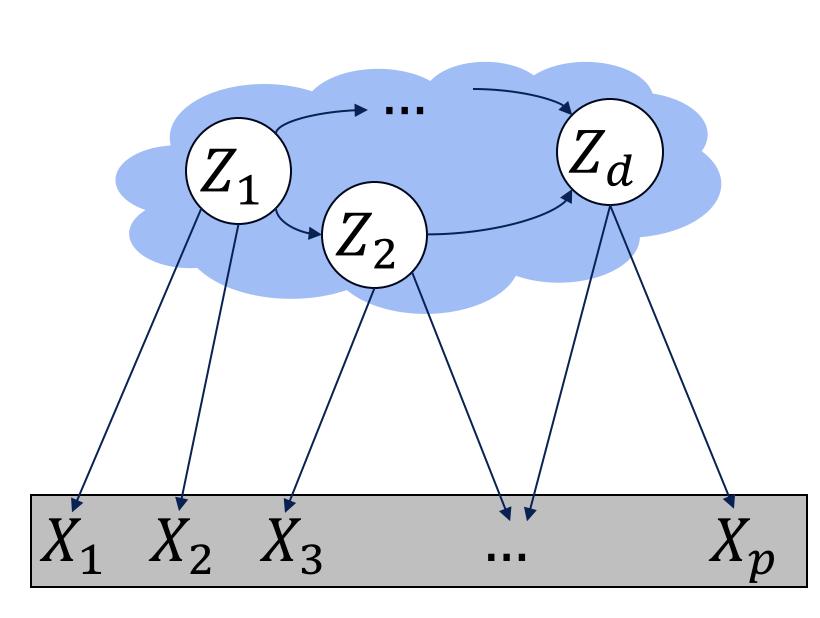
COMMON APPROACHES TO ESTABLISHING IDENTIFIABILITY

Restrict the latent distribution



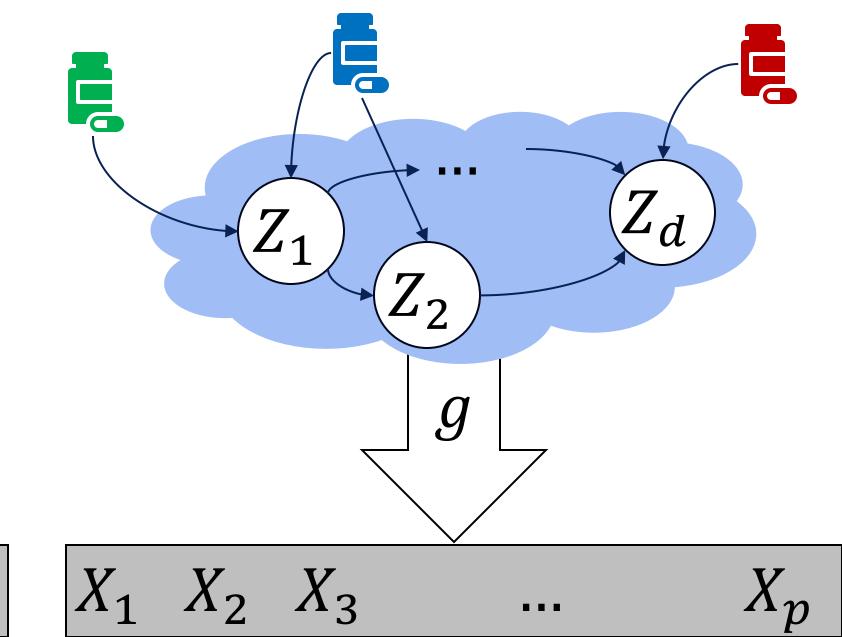
Independent component analysis [4, 5]

Restrict the mixing function



Most prior work on latent DAG recovery [3,6]

Incorporate multiple contexts



This work and other recent works [1,2,8,9,10]

OUR IDENTIFIABILITY GUARANTEES

One **perfect** intervention per variable is sufficient, and in the worst case necessary to identify \mathcal{G} and $(B_0, B_1, ..., B_K, G)$.

One **soft** intervention per variable is sufficient, and in the worst case necessary to identify \mathcal{G} up to transitive closure.

Proof components

Key Identity: $\Theta_k - \Theta_0 = (H^{\mathsf{T}} B_k^{\mathsf{T}} \boldsymbol{e}_{i_k})^{\otimes 2} - (H^{\mathsf{T}} B_0^{\mathsf{T}} \boldsymbol{e}_{i_k})^{\otimes 2}$

Rank one if i_k is a source node, rank two otherwise. Used to find $m{h}_{i
u}$ when i_k is a source node.

General principle: rowspan $(\Theta_k - \Theta_0) \subseteq \{h_i : i \in \mathcal{I}\}$ if and only if $\mathcal{I} = pa(i_k) \cup \{i_k\}$.

This lets us iteratively recover (1) the partial order over i_k 's and (2) the corresponding rows of H.

EXTENSIONS AND FUTURE WORK

- 1) Multi-node interventions: For each context k, allow a set I_k of intervention targets.
- 2) Soft interventions: See poster [10] at the Workshop on Spurious Correlations, Invariance, and Stability.
- 3) Non-parametric models: Latent model [1,8,10]. Mixing function [2]. Both (when d=2) [9].
- 4) Partial identifiability: What is identifiable when full identifiability is not achievable? Is this sufficient for downstream tasks?
- 5) Statistically/computationally efficient algorithms.

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