	Adedayo Akinade	Daniel Barros	Eyerusalem Birhan	Muhammed Danso	Birhanu Shimelis Girma	Yohannes Haile	Ibrahim Jimoh	Clifford Onyonka	Muhirwa Richard	Tsegazeab Tefferi	David Vernon	Status
D1.2 Rwandan Cultural Knowledge			R						R		R	N.A.
D2.1 Use Case Scenario Definition											R	N.A.
D2.2 Robot Behavior Specification											R	N.A.
D2.3 Visitor Behavior Specification											R	N.A.
D3.1 System Architecture,											R	N.A.
D3.2 Software Engineering Standards Manual											R	N.A.
D3.3 Software Installation Manual				R								N.A.
D3.4 System Integration and Quality Assurance Manual											R	N.A.
D3.5 System Integration and Quality Assurance								R				N.A.
D4.1 Sensor Tests						R						Accepted
D4.2.1 Person Detection and Localization						R						Accepted
D4.2.2 Face and Eye Detection and Localization						R						Accepted
D4.2.3 Sound Detection and Localization						R						Accepted
D4.2.4 Robot Localization							R					Accepted
D4.3.2 Speech Event								R				Accepted
D5.1 Actuator Tests						R						Accepted
D5.2 Animate Behavior Subsystem			R									Accepted
D5.3 Attention Subsystem				R								Accepted
D5.4.1 Cultural Knowledge Ontology & Knowledge Base											R	N.A.
D5.4.2 Robot Mission Language										R		N.A.
D5.4.3 Robot Mission Interpreter										R		Accepted
D5.5.1.1 Gesture Execution										R		Accepted
D5.5.1.2 Programming by Demonstration		R										Submitted
D5.5.2.1 English Text to Speech Conversion									R			N.A.
D5.5.2.3 Kinyarwanda Text to Speech Conversion									R			N.A.
D5.5.2.4 Integrated Text to Speech Conversion									R			Accepted
D5.5.3 Environment Map Generation				R								Accepted
D5.5.4 Robot Navigation				R								Accepted
D6.1 Use Case Implementation										R		N.A.
D6.2 Use Case Evaluation												N.A.
D7.1 Online Presence											R	N.A.
D7.3 Open-Source Software Repository	R											N.A.
D8.1 Progress Report											R	N.A.
D8.2 Expenditure Report											R	N.A.
Interim Demo: emulate Choreograph welcome												Demonstrated
Final Demo: Lab Tour												Initial Demonstration

R: Responsible