# Comp 363 - Design and Analysis of Computer Algorithms

# Spring Semester 2020 - Week 7 Dr Nick Hayward

## Video - Algorithms and Data Structures

# Recursion & Divide and Conquer - part 3



Efficiency of Recursion and Divide and Conquer - UP TO 13:59

Source - Divide and Conquer - YouTube

#### sorting - quicksort - part 1

- a brief segue into a consideration of a sorting algorithm, quicksort
- faster search option than selection sort
- a common option for many real-world uses...
- e.g. implementations of a qsort funtion in the C standard library.
- Quicksort also uses a pattern of divide and conquer
- e.g. use quicksort to sort our previous array of data
  - [6, 9, 13, 5, 11, 16]
- consider our last example of divide and conquer
  - identified base case as simplest array we could sum
- same may initially be considered relative to sorting
- i.e. clearly identify some arrays that do not need sorting
- may define base case for such sorting as follows
- [] empty array
- [16] array with one element
- empty arrays and arrays with one element
  - become base case for this sorting
  - i.e. return arrays as is without need to sort

#### sorting - quicksort - part 2

- then consider an array with three elements
- again, use divide and conquer...
- want to break this array down until we reach base case
- i.e. define quicksort as follows
- 1. choose an element in array
  - element is pivot
- 2. partition the array
- find elements less than pivot
- find elements greater than pivot
- now have two sub-arrays
  - · sub-array of all elements less than the pivot
  - · sub-array of all elements greater than the pivot
- these arrays will not initially be sorted
- just partitioned
- when sub-arrays have been sorted
- combine them with pivot to return required sorted array
- i.e.

sub\_array[less\_than] + pivot + sub\_array[greater\_than]

#### sorting - quicksort - part 3

- need a way to sort the sub-arrays
  - where base case is useful again
- i.e. Quicksort already knows how to sort arrays of two elements
- if we use quicksort with two sub-arrays
  - then combine results
  - we now have a sorted array
- e.g.

```
quicksort([less_than]) + [pivot] + quicksort([greater_than])
```

- this approach will work with any chosen pivot
- now define quicksort for an array of three elements
  - choose a pivot
  - partition array into two sub-arrays
  - o elements less than pivot
  - elements greater than pivot
  - recursively call quicksort on the two sub-arrays

# Video - Algorithms and Data Structures

## quicksort - part 1



Quicksort - UP TO 3:25

Source - Quicksort - Java - YouTube

#### sorting - quicksort - part 4

- what happens if we now need to sort an array of four elements...
- use a similar, known pattern
- e.g. for an array of [37, 12, 17, 9] follow expected steps
  - · choose a pivot
  - o e.g. 37
- select elements less than pivot
  - o e.g. [12, 17, 9]
- · select elements greater than pivot
  - ∘ e.g. []
- we know how to sort an array of three elements
- may call quicksort recursively for this array
- simply combine results to return sorted array
- we may now sort an array of four elements
- if we can sort an array of four elements
  - may also sort an array of five elements
  - then six elements
  - & seven elements
  - ...

#### sorting - quicksort - part 5

- i.e. if we consider an array of five elements
  - [6, 10, 4, 2, 8]
- we may partition this array as follows
  - then call quicksort for sub-arrays
- e.g.

```
[] 2 [6, 10, 4, 8]

[2] 4 [6, 10, 8]

[2, 4] 6 [10, 8]

[2, 6, 4] 8 [10]

[2, 6, 4, 8] 10 []
```

- clearly see how each sub-array has between zero and four elements
- · already know how to sort arrays of these sizes using quicksort
- regardless of chosen pivot
- recursively call quicksort on two sub-arrays
- continue this logic for six elements, &c.

#### sorting - quicksort - part 6

example implementation in Python is as follows

```
def quicksort(data):
    if len(data) < 2:
        # base case - 0 or 1 elements already sorted...
        return data
    else:
        # recursive case
        pivot = data[0]
        # sub-array of elements less than pivot
        less_than = [i for i in data[1:] if i <= pivot]
        # sub-array of elements greater than pivot
        greater_than = [i for i in data[1:] if i > pivot]
        # return sorted data
        return quicksort(less_than) + [pivot] + quicksort(greater_than)
```

# Video - Algorithms and Data Structures

## sorting algorithms



Algorithms and Sorting - UP TO 22:03

Source - Algorithms - YouTube

#### inductive proofs - part 1

- just seen an example of inductive proofs
- use such proofs to show an algorithm will work in theory
- each inductive proof has two familiar steps
  - a base case
  - an inductive case
- e.g. we want to prove that a test robot can climb steps
- inductive case may define the following
- if robot's legs are on a step
- it may put its legs on the next step...
- o e.g. if it's on the second step, it may now move to the third step, and so on...
- base case will define the following
  - robots legs are on first step
  - it can now climb all of the steps
  - o i.e. progressing one step at a time...

#### inductive proofs - part 2

- we may see a similar logic for our earlier quicksort algorithm
- base case shown to work as expected for arrays of size 0 and 1
- inductive case proved that if quicksort worked with an array of size 1
  - it would also work with an array of size 2
- if it works for an array of size 2
  - it will also work for an array of size 3...
- by inductive reasoning
  - the algorithm for quicksort will work with an array of any size
- for real-world usage
  - obviously making assumptions regarding memory usage, scale, &c.
  - · but inductive proofs still remain true

- briefly return to a consideration of Big O notation
- comparison of runtimes for various search and sort algorithms
  - may help provide some context for quicksort &c...
  - *e.g.*

| binary search | simple search | quicksort    | selection sort | traveling salesman |
|---------------|---------------|--------------|----------------|--------------------|
| O(log n)      | O(n)          | O(n log n)   | O(n²)          | O(n!)              |
| logarithmic   | linear        | linearithmic | quadratic      | factorial          |

# Video - Algorithms and Data Structures

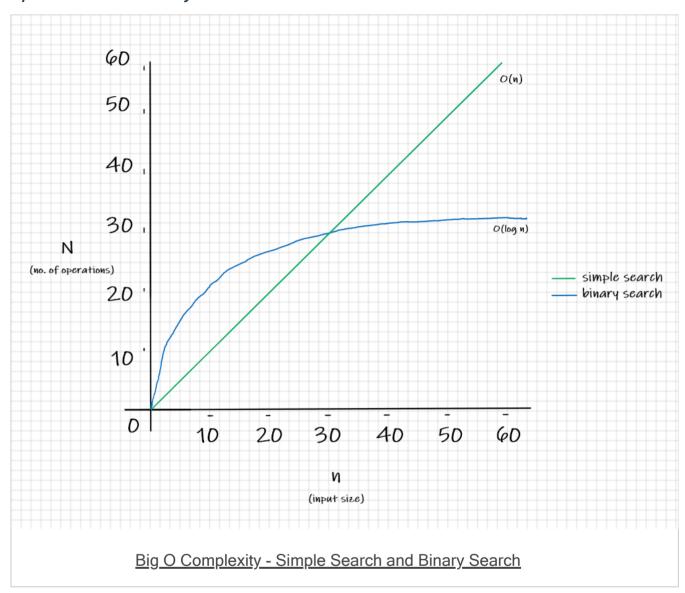
## quicksort - part 2



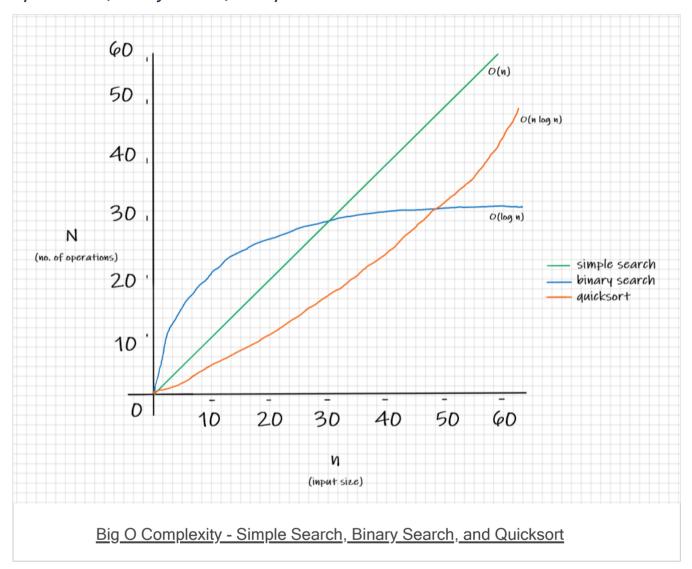
Quicksort - UP TO 4:40

Source - Quicksort - Java - YouTube

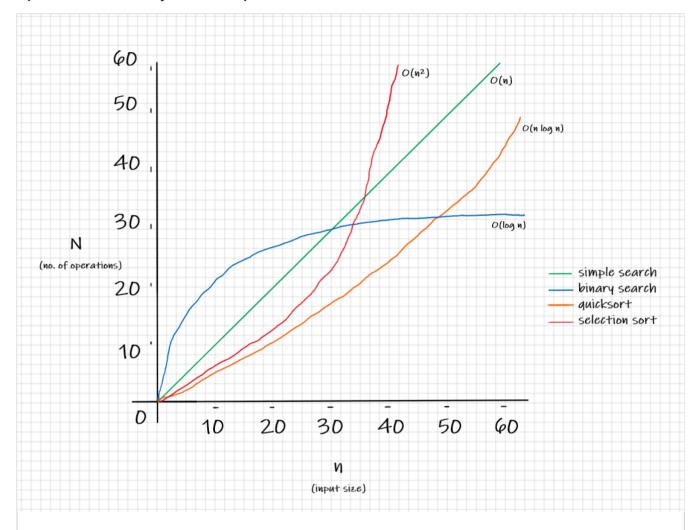
## simple search and binary search



## simple search, binary search, and quicksort

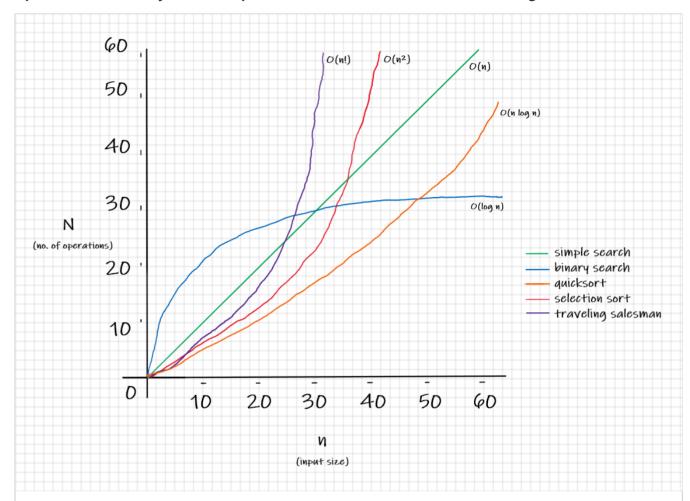


## simple search, binary search, quicksort, and selection sort



Big O Complexity - Simple Search, Binary Search, Quicksort, and Selection Sort

## simple search, binary search, quicksort, selection sort, and traveling salesman



<u>Big O Complexity - Simple Search, Binary Search, Quicksort, Selection Sort, and Traveling Salesman</u>

- consider the following comparative run times
- computer capable of a basic 10 operations per second
- (such a slow computer helps visualise the comparative performance)

| data size  | quicksort    | selection sort | traveling salesman              |  |
|------------|--------------|----------------|---------------------------------|--|
| 10 items   | 3.3 seconds  | 10 seconds     | 4.2 days                        |  |
| 100 items  | 66.4 seconds | 16.6 minutes   | 2.9 x 10 <sup>149</sup> years   |  |
| 1000 items | 996 seconds  | 27.7 hours     | 1.27 x 10 <sup>2559</sup> years |  |

- previous graphs indicative of expected performance
  - not accurate reflections of performance times
- show difference in expected performance for each algorithm
- relative to scale...
- e.g quickly see that selection sort, O(n²), is a slow algorithm
- in particular compared with quicksort...

- compare with another sorting algorithm
  - e.g merge sort a time of O(n log n)
  - much faster than selection sort
- current algorithm *quicksort* is a tad harder to pin down
- for worst case
  - *time is*  $0(n^2)$
  - potentially as slow as selection sort
- for average case
  - define a time of O(n Log n)
  - comparable with faster algorithm merge sort
- if merge sort is considered faster with a time of O(n log n)
  - why not use this algorithm all the time instead of quicksort?

- consider a comparison of quicksort and merge sort
  - should helps choose a preferred algorithm to use...
- start with the following simple usage
  - a Python function to iterate a list

```
def print_list(data):
   for val in list:
    print val
```

- as this iteration loops the whole list
- runs with a time of O(n)
- what happens if we need to introduce a pause per iteration...
  - e.g. perhaps to check an external data store, API &c.
  - · add a test pause of one second per iteration
- both use cases need to loop through data
  - each may be defined with a time of O(n)
- even though both functions return same time using Big O notation
- first iteration without pause will return faster real-world performance and time...

#### Big O revisited - part 5

- consider apparent contradiction for a moment
  - start to understand actual meaning of Big O notation
- consider a time of O(n) as follows

```
`constant` x `n`
```

or

`c` x `n`

```
c is a fixed amount of time algorithm will take
```

- or the constant
- comparative times for basic iteration and iteration with a pause
- e.g. 10ms \* n vs1 sec \* n

- usually ignore such constants
  - if comparative algorithms have different Big O time
  - i.e. for most instances constant doesn't matter
- e.g. compare simple search to binary search for previous usage

```
simple search = 10ms * n
binary search = 1 sec * log n
```

- simple search initially seems faster
- if we scale query to four billion elements
  - disparity in performance becomes clear...

```
simple search = 10ms * 4 billion = 463 days
binary search = 1sec * 32 = 32 seconds
```

- clear improvement in times with binary search
- the constant did not make a difference

- still exceptions to this rule
- i.e. constant may sometimes make a difference
- Quicksort versus merge sort is one example where this holds true
- Quicksort has a smaller constant than merge sort
- if they're both O(n log n) time
  - quicksort is faster...
- quicksort is faster in practice
  - it hits average case more frequently than worst case

- average case and worst case
- performance for *quicksort* predicated on chosen *pivot*
- e.g. if we choose a pivot and array is already sorted
  - quicksort does not check if input array is already sorted
  - i.e. it will try to sort the passed array
- if we compared two possible scenarios for an array
  - 1. first element is always chosen as the pivot
  - •2. middle element is always chosen as the pivot
- starting at middle element
  - will not need to make as many recursive calls for this example
- i.e. hits the base case more quickly, and required call stack will also be shorter...

- first example, choosing first element, is worst case
- second example, middle element selection, is best case
- for worst case
- stack size is O(n)
- best case has a stack size of O(log n)
- e.g. we may see how best case is partitioning the array

```
[1, 2, 3, 4, 5, 6, 7, 8]
[1, 2, 3] 4 [5, 6, 7, 8]
[1] 2 [3] [5] 6 [7, 8]
[] 7 [8]
```

- for worst case
  - checking each element in array
  - e.g. eight in this example
- first operation takes O(n)
  - we actually check O(n) elements on every level of call stack
- even if we partition array in a different manner
  - e.g. with a different pivot
- still checking O(n) elements every time
- i.e. each level of the stack currently takes O(n) time to complete

- difference between worst case and best case
  - · seen when we consider height of call stack
- e.g. best case will check O(log n) levels
  - height of its call stack
- each level takes O(n) time
- algorithm will take O(n) \* O(Log n)
- i.e. O(n Log n) time
- · best case for this algorithm
- see difference when we calculate comparative worst case
  - a time of O(n) for each level
  - but also O(n) levels
  - algorithm will take O(n) \* O(n)
  - i.e. O(n²) time
- also define best case as average case
  - if we always choose a random element in array as defined pivot
  - quicksort algorithm will have average time of O(n Log n)

# Video - Algorithms and Data Structures

## quicksort - part 3



Quicksort - UP TO 8:42

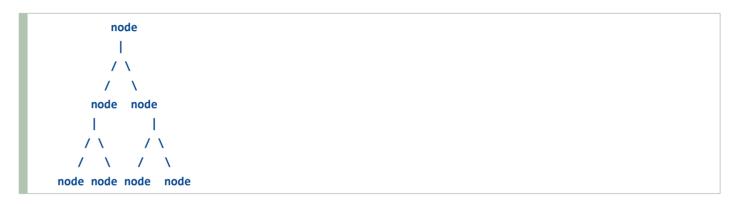
Source - Quicksort - Java - YouTube

#### binary search tree - intro - part 1

- binary search tree (BST) is a binary tree
- each node has a Comparable key (and an associated value)
- satisfies a defined restriction
- e.g. key in any node is
- larger than the keys in all nodes in that node's left subtree
- smaller than the keys in all nodes in that node's right subtree
- comparison is context specific relative to the current node
- binary search need to work with sorted data sets
- when we add or update the data
  - need to re-sort list before using binary search
- if we're working with sorted lists of data
- e.g. an array of books
- quickly encounter a problem
  - list may need to be updated item in the array is deleted
  - then need to add a value to index where last deleted item stored...

## binary search tree - intro - part 2

- may now update list to meet specific criteria
  - removing need to repeatedly sort dataset
- binary search tree data structure
  - basic tree data structure



#### Video

#### Trees and parsing - part 1



How the browser renders a website - UP TO 7:40

Source - So how does the browser actually render a website - YouTube

#### binary search tree - intro - part 3

sample binary search tree may be structured as follows

- for every node in this tree
- nodes to left of current node are smaller
- nodes to right of current node are larger
- e.g. search for violet begin at root then use following path
  - V is after D traverse right side of tree
    - current node = emma
  - V is after E continue down right side
  - ∘ current node = rose
  - V is before Y continue down left side
    - violet node found...
- searching for a node in a binary search tree takes O(log n) on average
  - O(n) for worst cases
- sorted array, by contrast, takes O(log n) in worst case scenarios
- might initially consider arrays as preferable option
- sorted binary search tree is, on average, faster for insertions and deletions...

## binary search tree - issues

- binary search trees do not provide random access
- performance times are averages
- rely on a balanced tree
- specialist trees may provide self-balancing mechanisms
- e.g. might use a *red-black* tree

# Video - Algorithms and Data Structures

#### binary search trees - part 1



Binary Search Trees - UP TO 1:36

Source - Trees - Java - YouTube

### binary search tree - basic logic implementation - part 1

- symbol-table API for a binary search tree
- common option for implementing this type of traversal and search
- symbol-table is also known as a map, dictionary, associative array &c.
  - may vary by programming language
- general concept is as follows
  - abstraction of key/value pairs
    - o e.g. insert a value with a specified key
  - o given key, search for corresponding value
- sample usage may include the following

| application | search                                            | key              | value                                      |
|-------------|---------------------------------------------------|------------------|--------------------------------------------|
| dictionary  | search for a definition                           | word             | definition                                 |
| index       | search for a given<br>reference, e.g book<br>page | term             | e.g. list of page<br>numbers for a<br>book |
| compiler    | search for props of variables                     | variable<br>name | type and value                             |

- for binary search tree logic may begin with custom function to define nodes
- function includes props required for a node, e.g.
  - key
  - value
  - left link
  - right link
  - node count

### Video

### Trees and rendering - part 2



A common working example - How the browser renders a website - UP TO 17:17

Source - So how does the browser actually render a website - YouTube

### binary search tree - order-based methods - part 1

- common reason for working with binary search trees (BST)
  - they keep the keys in order
- may use BSTs in many disparate API contexts
  - ensure consistent I/O structure
- e.g. might consider a custom symbol-table API
- some sample methods and usage
  - min & max
    - if left link of root is null
    - smallest key in BST must be root node
    - if left link is not null
    - smallest key is in subtree referenced by left link
    - repeats for each left link in each subtree...
  - floor
    - if a given key is less than key at root of BST
    - floor of key must now be added to left subtree...
    - o if key is greater than root
    - o floor can be in right link but only if there is a smaller or equal existing key
    - · if not, floor of key is root...
  - ceiling
  - same pattern as floor
  - · except check relative to right link
  - selection
  - o e.g. seek key of rank k
  - · key such that precisely k other keys in BST are smaller
  - if number of keys t in left subtree is larger than k
  - · look (recursively) for key of rank k in left subtree
  - if t is equal to k
  - · return key at root
  - if t is smaller than k
  - look (recursively) for key of rank k t 1 in right subtree

### binary search tree - order-based methods - part 2

- range search
- to implement keys () method returns all keys in a given range
- begin with basic recursive BST traversal method known as inorder traversal
- e.g. to show this order traversal
- o first print all keys in left side of BST all less than root
- then print root key
- o then print all keys in right side of BST
- keys() method
- o define code to add each key that is in range to a Queue
- o skip recursive calls for subtrees that cannot contain keys in range

#### rank

- if given key is equal to key at root
- o return number of keys t in left subtree
- if given key is less than key at root
  - o return rank of key in left subtree
- if given key is larger than key at root
- o return t plus one (to count key at root) plus rank of key in right subtree

### binary search tree - order-based methods - part 3

- delete min & max
  - delete minimum
  - go left until finding a node that has a null left link
  - then replace link to that node by its right link
  - symmetric method works for delete maximum
- delete
- proceed in a similar manner to delete a node with one or null childrem
- for two or more start by replacing current node with its successor
- successor is node with smallest key in its right subtree
- accomplish task of replacing x by its successor in four easy steps
  - 1. save a link to node to be deleted in t
  - •2. set x to point to its successormin(t.right)
  - 3. set right link of x
    - $\circ$  supposed to point to BST containing all keys larger than x.key
    - ∘ to deleteMin(t.right)
    - the link to BST containing all keys that are larger than x.key after deletion
  - •4. set left link of x to t. Left
  - all keys that are less than both deleted key and its successor...

### Video

### symbol table API



Symbol table API - UP TO 5:40

Source - Symbol Table API - YouTube

### binary search tree - usage - intro

- binary search tree (BST) has a non-linear insertion algorithm
- BST is similar in nature to a doubly-linked list
- a linked data structure
- includes set of sequentially linked records, commonly known as nodes
- each node defines three fields,
  - link field previous node in sequence of nodes
  - link field next node in sequence of nodes
  - one data field
- link fields may be represented using a common example of a convoy, a train &c.
  - e.g. linked ships sailing in a convoy...

### binary search tree - usage - links and usage - part 1

- binary search tree defines its pointers as left and right to help indicate any duplication of logic &c.
- algorithm may be detected
- providing support for left and right traversal
- binary search tree node's pointers are typically called *left* and *right* 
  - indicate subtrees of values relating to current value
- simple JavaScript implementation of such a node is as follows

```
const node = {
    value: 123,
    left: null,
    right: null
}
```

 BST is a unique tree due to its inherent ordering of nodes based on value

### binary search tree - usage - links and usage - part 2

- any child nodes in a left subtree are always less than parent node's value
- converse holds for a right subtree
  - · values in subtree will always be greater
- e.g.

```
7
/\
5 9
/\
2 11
/\\
1 3 12
\
14
/\
13
```

- traverse the tree and check key of current node
- if search key is less than current node's value
  - follow left link
  - otherwise, follow right link
- position of node values is based on a few factors
  - value of node
  - value of root
  - order of insertion
- e.g.
  - root is set to 7
  - 5 is less than root insert as left link
  - 9 is greater than root insert as right link
  - 2 is less than root follow left link
  - 2 is less than 5 left link is null insert as left link
  - ...
- repeat for additional inserts...

# Video - Algorithms and Data Structures

### binary search trees - part 2



Binary Search Trees - Insert - UP TO 3:00

Source - Trees - Java - YouTube

### Resources

#### **Various**

- Algorithms YouTube
- Divide and Conquer YouTube
- Memoisation YouTube
- Quicksort Java YouTube
- Recursion & Fibonacci YouTube
- Recursion and Fun JavaScript YouTube
- Recursion and the Call Stack Java YouTube
- So how does the browser actually render a website YouTube
- Symbol Table API YouTube
- Trees Java YouTube