Part-2: Refine init

Q = {boot_hw, senchk, tchk, psichk, ready}

q₀ : boot_hw

Σ1 = {hw_ok, sen_ok, t_ok, psi_ok}

Σ2 = {check_sensors, check_t_sensor, check_psi_sensor}

V = { }

Λ = {

$\longrightarrow$ *boot_hw*

boot_hw $\xrightarrow{\text{hw\_ok / check\_sensors}}$ *senchk*

senchk $\xrightarrow{\text{sen\_ok / check\_t\_sensor}}$ *tchk*

tchk $\xrightarrow{\text{t\_ok / check\_psi\_sensor}}$ *psichk*

psichk $\xrightarrow{\text{psi\_ok}}$ *ready*

ready $\longrightarrow$ *end*

}