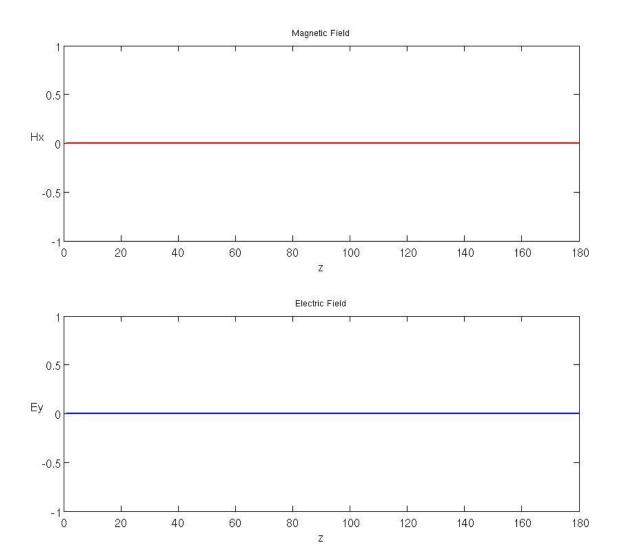
Problem 2



Appendix - P2 Code

%FDTD1D

```
% Initialization
% Initialize MATLAB
close all; clc;
clear all;
%Constants
c0 = 299792458; %m/s
e0 = 8.854187817*10^{-12}; %F/m
u0 = 1.256637061*10^{-6}; %H/m
%Physical Environment
dz = 1.4286*10^{-8}; %meters
dt = 4.7652*10^{17}; %secs
%Simulated Environment
Nz = 180;
STEPS = 1000;
%Material Vectors
ER = ones([1 Nz]);
UR = ones([1 Nz]);
%FDTD Initialization
% Compute Update Coefficients
mER = (c0*dt/dz)./ER;
mHR = (c0*dt/dz)./UR;
% Initialize Feilds
Ey = zeros([1 Nz]);
Hx = zeros([1 Nz]);
% Execute Simulation
```

for t = 1:STEPS

```
for nz = 1:Nz-1
  Hx(nz) = Hx(nz) + mHR(nz)*(Ey(nz+1)-Ey(nz));
 Hx(Nz) = Hx(Nz) + mHR(Nz)*(0 - Ey(Nz));
 % Calculate E
 E_{V}(1) = E_{V}(1) + mE_{R}(1)*(H_{X}(1) - 0);
 for nz = 2:Nz
  Ey(nz) = Ey(nz) + mER(nz)*(Hx(nz)-Hx(nz-1));
 end
end
% Plot Fields
fig = figure;
SetFigure(fig, 'HW#3-P2', [680 274 965 826]);
%Plot Magnetic Field
subplot(211)
h = plot(Hx, '-r', 'LineWidth', 2);
title('Magnetic Field');
h = get(h, 'Parent');
set(h, 'Fontsize', 14);
xlabel('z');
ylabel('Hx', 'Rotation', 0);
set(gca,'YTickLabel',{'-1','-0.5','0', '0.5', '1'})
%Plot Electric Field
subplot(212)
h = plot(Ey, '-b', 'LineWidth', 2);
title('Electric Field');
h = get(h, 'Parent');
set(h, 'Fontsize', 14);
xlabel('z');
ylabel('Ey', 'Rotation', 0);
set(gca,'YTickLabel',{'-1','-0.5','0', '0.5', '1'})
```

% Calculate H