## A Fully Adaptive Block-Structured Multiresolution Scheme for Reactive Flows

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#### Introduction

Many engineering applications depend on numerically solving systems of conservation laws of the form

$$\begin{cases} u_t + f(u)_x = s(u) \\ u(x,0) = u_0(x), \end{cases}$$
 (1)

where  $x \in \Omega$  and  $t \in [t_0, t_f]$ . Volume averages are defined for each cell  $I_i = [x_{i-1/2}, x_{i+1/2}]$ ,

$$\overline{u}_{i}(t) = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} u(\xi, t) d\xi, \tag{2}$$

#### Discretization

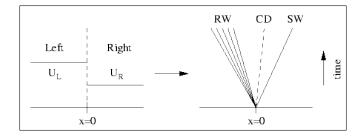
The governing equations are cast into the semi-discrete conservative form,

$$\frac{d\overline{u}_{i}(t)}{dt} = L(\overline{\mathbf{u}}) = -\frac{1}{\Delta x} \left( \hat{f}_{i+1/2} - \hat{f}_{i-1/2} \right) + \overline{s}_{i}, \tag{3}$$

where  $\overline{s} = \frac{1}{\Delta x} \int_{x_{i-1/2}}^{x_{i+1/2}} s(u) d\xi$ , and the numerical flux is evaluated as

$$\hat{f}_{i\pm 1/2} = \hat{f}(\overline{u}_{i\pm 1/2}^-, \overline{u}_{i\pm 1/2}^+).$$
 (4)

# Riemann problem



### Time integration

This system of ODEs is evolved forward in time

$$\overline{\mathbf{u}}^{n+1} = \overline{\mathbf{u}}^n + \Delta t \sum_{j=1}^s b_j \mathbf{k}_j, \tag{5}$$

where the stages  $k_j$  are solved either implicitly or explicitly.

These equations are typically solved on non-uniform mesh spacing:

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- blocks introduce inherent "overresolution" in some regions of the mesh

## Mesh hierarchy

Define multiple levels of representation of the discrete data

$$\mathcal{G}_I = \left\{ x_i^I \right\}_{i=0}^{N_I}, \quad x_i^I = i \cdot \Delta x_I, \quad \Delta x_I = 2^{L-I} \cdot \Delta x_L, \quad N_I = N_L/2^{L-I},$$

where  $\Delta x_I$  and  $N_I$  denote the cell width and number of cells, respectively, on level I. The index space of cells on each level of the hierarchy is denoted by  $\mathcal{I}^I = \{1, \dots, N_I\}$ .

### Decomposition

*Project:* The cells at level l+1 are projected by means of averaging, onto the coarser grid level l. The projection is defined by a linear operator which performs the mapping  $\mathbf{P}_{l+1}^{l}: \overline{\mathbf{u}}^{l+1} \mapsto \overline{\mathbf{u}}^{l}$ .

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*Predict*: Cell averages at level l+1 are predicted by an average-interpolating polynomial constructed of cells on level l. The prediction operator performs the mapping  $\mathbf{P}_l^{l+1}: \overline{\mathbf{u}}^l \mapsto \widetilde{\mathbf{u}}^{l+1}.$ 

#### **Project**

Coarsening/projection is done via

$$\overline{u}_i^l = \left(\mathbf{P}_{l+1}^l \overline{\mathbf{u}}^{l+1}\right)_i = \frac{1}{2} (\overline{u}_{2i-1}^{l+1} + \overline{u}_{2i}^{l+1}), \quad \forall i \in \mathcal{I}^l.$$
 (6)

#### **Predict**

Prediction is done using average-interpolating polynomials, with  $m \in \{0,1\}$ ,

$$\tilde{u}_{2i-m}^{l+1} = \overline{u}_i^l - (-1)^m \sum_{p=1}^s \gamma_p \left( \overline{u}_{i+p}^l - \overline{u}_{i-p}^l \right), \quad \forall i \in \mathcal{I}^l.$$

### Difference information and thresholding

We compute a difference between the true value at the higher resolution l+1, and its prediction,

$$d_i^l = \overline{u}_{2i}^{l+1} - \tilde{u}_{2i}^{l+1}, \quad \forall i \in \mathcal{I}^l.$$
 (7)

Then we can eliminate small detail coefficients (where solution is smooth enough),

$$\tilde{d}_{i}^{I} = \begin{cases} d_{i}^{I}, & \text{if } |d_{i}^{I}| > \varepsilon \\ 0, & \text{if } |d_{i}^{I}| \le \varepsilon. \end{cases}$$
 (8)

Then reconstructing field is done by

$$\overline{u}_{2i}^{l+1} = \tilde{u}_{2i}^{l+1} + \tilde{d}_i^l.$$

# Grid adaptation

(MOVIE)

#### Adaptive flux and source computations on blocks

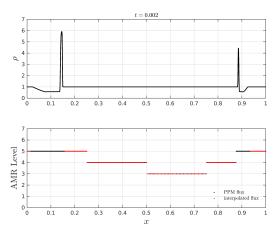
Where the mask is not active (solution is smooth enough), we can also replace redundant flux calculations with interpolation,

$$\hat{f}_{2i+1}^{l+1} \approx \sum_{p=1}^{s+1} \beta_p \left( \hat{f}_{i-p+1}^l + \hat{f}_{i+p}^l \right). \tag{9}$$

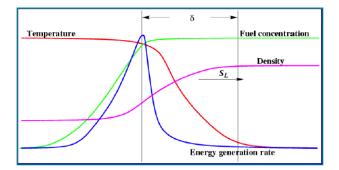
We can do the same for the source terms,

$$\overline{s}_{2i-m}^{l+1} \approx \overline{s}_i^l - (-1)^m \sum_{p=1}^k \gamma_p \left( \overline{s}_{i+p}^l - \overline{s}_{i-p}^l \right). \tag{10}$$

## Two interacting blast waves



#### Laminar flame



## Nuclear burning

